

# **APPLICATION NOTE**

# FECA-AN-145

### RS-485 Data Format 12 Procedure

Inverter type

Software version Required options Related documentation FRENIC-Mini/Eco/Multi/MEGA series All versions None RS-485 User's Manual MEH448c Shane Spencer 4/05/2012

#### Introduction:

Author

Revision

Date

This application note will diagram how to correctly enter data to register addresses with data format 12 in the **RS-485 User's Manual** (**MEH448c**, page 5-50) over RS-485 communications.

#### Format:

Data format 12 has the following specification as displayed in the **RS-485 User's Manual**, page 5-50:

Data format [12] Floating point data (accel./decal. time, PID display coefficient)

|            | 15       | 14 | 13 | 12 | 11   | 10    | 9 | 8 | 7 | 6 | 5   | 4     | 3 | 2 | 1 | 0 |
|------------|----------|----|----|----|------|-------|---|---|---|---|-----|-------|---|---|---|---|
|            |          |    |    |    |      |       |   |   |   |   |     |       |   |   |   |   |
|            | Polarity | 0  | 0  | 0  | Expo | onent |   |   |   |   | Man | tissa |   |   |   |   |
| L Unused J |          |    |    |    |      |       |   |   |   |   |     |       |   |   |   |   |

Polarity: 0 → Positive (+), 1 → Negative (-) Exponent: 0 to 3 Mantissa: 1 to 999

Value expressed in this form = (polarity) Mantissa x (Exponent - 2) power of 10

| Value        | Mantissa   | Exponent | (Exponent - 2)<br>power of 10 |
|--------------|------------|----------|-------------------------------|
| 0.01 to 9.99 | 1 to 999   | 0        | 0.01                          |
| 10.0 to 99.9 | 100 to 999 | 1        | 0.1                           |
| 100 to 999   | 100 to 999 | 2        | 1                             |
| 1000 to 9990 | 100 to 999 | 3        | 10                            |

(Example) When F07 (acceleration time 1) = 20.0 seconds

 $20.0 = 200 \times 0.1 \Rightarrow 0000 \ 0100 \ 1100 \ 1000_{b} = 04C8_{H} \Rightarrow 04_{H} C8_{H}$ 

### Procedure:

To ensure you send the correct data to the inverter corresponding to the desired value, follow the procedure outlined below.



**STEP 1:** Determine the decimal value you want to send to the register address with data format 12.

For example, let's say you want to set the acceleration time (F07) to 5 seconds. The decimal number 5 falls into the first group of values (0.01 to 9.99).



**STEP 2**: Find the "(Exponent - 2) power of 10" value your decimal number corresponds to. Our example of setting acceleration time to 5 corresponds to 0.01.

Value expressed in this form = (polarity) Mantissa x (Exponent - 2) power of 10

| Value        | Mantissa   | Exponent | (Exponent - 2)<br>power of 10 |
|--------------|------------|----------|-------------------------------|
| 0.01 to 9.99 | 1 to 999   | 0        | 0.01                          |
| 10.0 to 99.9 | 100 to 999 | 1        | 0.1                           |
| 100 to 999   | 100 to 999 | 2        |                               |
| 1000 to 9990 | 100 to 999 | 3        | 10                            |

**STEP 3:** Take your decimal value from STEP 1 and divide it by the "(Exponent – 2) power of 10" value from STEP 2.

For our example, take 5 and divide it by 0.01 to get 500.

**STEP 4:** Take your value found in STEP 3 and convert it to binary. This is the value you will enter in the Mantissa, bits 0 to 9.

Our example: 500 decimal = 0111110100 binary.

**STEP 5:** Find the Exponent that your decimal number from STEP 1 corresponds to and convert it to binary. This value will go in bits 11 and 10 Our example: 5 corresponds to Exponent 0.

**STEP 6:** Find the Polarity of your value from STEP 1. If the value from STEP 1 is positive, the polarity is 0. If the value from STEP 1 is negative, the polarity is 1. This value will go in bit 15.

**STEP 7:** Plug your binary values into their corresponding bits. This may need to be converted to hexadecimal to be communicated to drive. For our example, the binary number is:



000000011111110100 binary = 01F4 hex