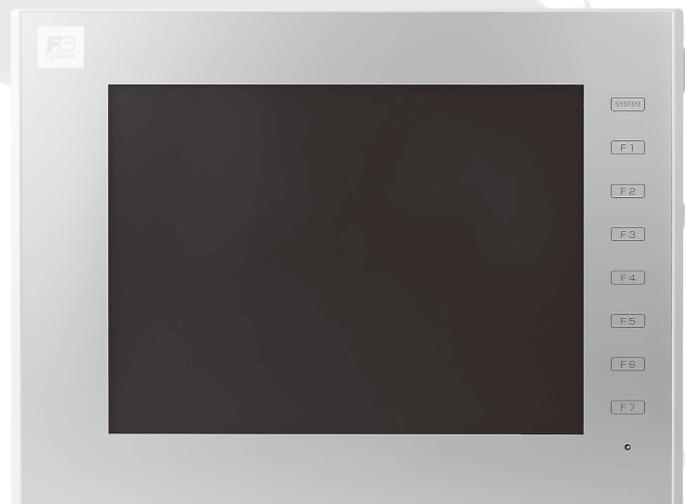


MONITOUCH

Connection Manual [1]

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V9 series

Record of Revisions

Reference numbers are shown at the bottom left corner on the back cover of each manual.

| Printing Date | Reference No. | Revised Contents |
|---------------|---------------|------------------|
| May, 2014 | 2210NE0 | First edition |
| | | |

Preface

Thank you for selecting the MONITOUCH V9 series.

For correct set-up of the V9 series, you are requested to read through this manual to understand more about the product.

For more information about the V9 series, refer to the following related manuals.

| Manual Name | Contents | Reference No. |
|--|--|---------------|
| V9 Series Connection Manual [1] | The connection and communication parameters for the V9 series and controllers are explained in detail. Included Makers ALLEN BRADLEY, Automationdirect, Azbil, Baumuller, BECKHOFF, CHINO, CIMON, DELTA, DELTA TAU DATA SYSTEMS, EATON Cutler-Hammer, EMERSON, FANUC, Fatek Automation, FUFENG, Fuji Electric, Gammaflux, GE Fanuc, Hitachi, Hitachi Industrial Equipment Systems | 2210NE |
| V9 Series Connection Manual [2] | The connection and communication parameters for the V9 series and controllers are explained in detail. Included Makers IAI, IDEC, JTEKT, KEYENCE, KOGANEI, KOYO ELECTRONICS, LS, MITSUBISHI ELECTRIC, MODICON, MOELLER, M-SYSTEM, OMRON, Oriental Motor, Panasonic, RKC, RS Automation | 2211NE |
| V9 Series Connection Manual [3] | The connection and communication parameters for the V9 series and controllers are explained in detail. Included Makers SAIA, SAMSUNG, SanRex, SANMEI, SHARP, SHIMADEN, SHINKO TECHNOS, Siemens, SINFONIA TECHNOLOGY, TECO, Telemecanique, TOHO, TOSHIBA, TOSHIBA MACHINE, TURCK, UNIPULSE, UNITRONICS, VIGOR, WAGO, XINJE, YAMAHA, Yaskawa Electric, Yokogawa Electric, MODBUS, Barcode Reader, Slave Communication Function, Universal Serial Communication | 2212NE |
| V9 Series Reference Manual [1] | The functions and instructions of the V9 series are explained. | 1065NE |
| V9 Series Reference Manual [2] | | 1066NE |
| V9 Series Troubleshooting/Maintenance Manual | Errors and operation procedures of the V9 series are explained. | 1068NE |
| V9 Series Hardware Specifications | Notes on usage and hardware specifications for the V9 series are explained. | 2023NE |
| V9 Series Macro Reference | An overview of macros of V-SFT version 6 as well as macro editor operations and macro command descriptions are explained. | 1071NE |

For further details about PLCs, inverters, or temperature controllers, refer to the manual attached to each controller.

Notes:

1. This manual may not, in whole or in part, be printed or reproduced without the prior written consent of Hakko Electronics Co., Ltd.
2. The information in this manual is subject to change without prior notice.
3. Windows and Excel are registered trademarks of Microsoft Corporation in the United States and other countries.
4. All other company names or product names are trademarks or registered trademarks of their respective holders.
5. This manual is intended to give accurate information about MONITOUCH hardware. If you have any questions, please contact your local distributor.

Notes on Safe Usage of MONITOUCH

In this manual, you will find various notes categorized under the following two levels with the signal words "Danger" and "Caution."



DANGER

Indicates an imminently hazardous situation which, if not avoided, will result in death or serious injury.



CAUTION

Indicates a potentially hazardous situation which, if not avoided, may result in minor or moderate injury and could cause property damage.

Note that there is a possibility that an item listed under  **CAUTION** may have serious ramifications.

DANGER

- Never use the output signal of the V9 series for operations that may threaten human life or damage the system, such as signals used in case of emergency. Please design the system so that it can cope with the malfunctions of a touch switch. A malfunction of a touch switch may result in machine accident or damage.
- Turn off the power supply when you set up the unit, connect new cables, or perform maintenance or inspections. Otherwise, electrical shock or damage may occur.
- Never touch any terminals while the power is on. Otherwise, electric shock may occur.
- Put a cover on the terminals on the unit before turning the power on starting operation. Otherwise, electric shock may occur.
- The liquid crystal in the LCD panel is a hazardous substance. If the LCD panel is damaged, do not ingest the leaked liquid crystal. If the liquid crystal contacts skin or clothing, use soap and wash off thoroughly.
- Never disassemble, recharge, deform by pressure, short-circuit, reverse the polarity of the lithium battery, nor dispose of the lithium battery in fire. Failure to follow these conditions will lead to explosion or fire.
- Never use a lithium battery that is deformed, leaks, or shows any other signs of abnormality. Failure to follow these conditions may lead to explosion or fire.
- The power lamp flashes when the backlight is at the end of life or is faulty. However, the switches on the screen are operable at this time. Do not touch the screen when the screen becomes dark and the power lamp flashes. Otherwise, a malfunction may occur and result in machine accident or damage.

CAUTION

- Check the appearance of MONITOUCH when unpacked. Do not use it if any damage or deformation is found. Failure to do so may lead to fire, damage or malfunction.
- For use in a facility or for a system related to nuclear energy, aerospace, medical, traffic equipment, or mobile installations, please consult your local distributor.
- Operate (or store) the V9 series under the conditions indicated in this manual and related manuals. Failure to do so could cause fire, malfunction, physical damage or deterioration.
- Understand the following environmental limits for use and storage of MONITOUCH. Otherwise, fire or damage to the unit may result.
 - Avoid locations where there is a possibility that water, corrosive gas, flammable gas, solvents, grinding fluids or cutting oil can come into contact with the unit.
 - Avoid high temperature, condensation, and outside weather conditions, such as wind, rain or direct sunlight.
 - Avoid locations where excessive dust, salt, and metallic particles are present.
 - Avoid installing the unit in a location where vibration or physical shock may be transmitted.
- Equipment must be correctly mounted so that the main terminal of the V9 series will not be touched inadvertently. Otherwise, an accident or electric shock may occur.
- Tighten the fixtures of the V9 series evenly to a torque of 0.6 N·m.
Excessive tightening may distort the panel surface. Loose tightening may cause MONITOUCH to come off, malfunction or be short-circuited.
- Check periodically that terminal screws on the power supply terminal block and fixtures are firmly tightened. Loosened screws may result in fire or malfunction.
- Tighten terminal screws on the power supply terminal block equally to a torque of 7.1 to 8.8 inch-lbf (0.8 to 1.0 N·m). Improper tightening of screws may result in fire, malfunction, or other trouble.
- The V9 series has a glass screen. Do not drop or give physical shock to the unit. Otherwise, the screen may be damaged.
- Connect the cables correctly to the terminals of the V9 series in accordance with the specified voltage and wattage. Over-voltage, over-wattage, or incorrect cable connection could cause fire, malfunction or damage to the unit.
- Be sure to establish a ground of the V9 series. The FG terminal must be used exclusively for the unit with the level of grounding resistance less than 100 Ω. Otherwise, electric shock or fire may occur.
- Prevent any conductive particles from entering into the V9 series. Failure to do so may lead to fire, damage, or malfunction.
- After wiring is finished, remove the paper used as a dust cover before starting to operate the V9 series. Operation with the cover attached may result in an accident, fire, malfunction, or trouble.
- Do not attempt to repair the V9 series at your site. Ask Hakko Electronics or the designated contractor for repairs.

 **CAUTION**

- Do not repair, disassemble or modify the V9 series. Hakko Electronics Co., Ltd. is not responsible for any damages resulting from repair, disassembly or modification of a unit that was performed by an unauthorized person.
- Do not use a sharp-pointed tool when pressing a touch switch. Doing so may damage the screen.
- Only experts are authorized to set up the unit, connect the cables or perform maintenance and inspection.
- Lithium batteries contain combustible material such as lithium or organic solvents. Mishandling may cause heat, explosion or ignition resulting in fire or injury. Read related manuals carefully and handle the lithium battery correctly as instructed.
- Do not press two or more positions on the screen at the same time. If two or more positions are pressed at the same time, the switch located between the pressed positions activates.
- Take safety precautions during operations such as changing settings during running, forced output, start, and stop. Any misoperation may cause unexpected machine motions, resulting in machine accident or damage.
- In facilities where a failure of the V9 series could lead to accidents threatening human life or other serious damage, be sure that the facilities are equipped with adequate safeguards.
- At the time of disposal, the V9 series must be treated as industrial waste.
- Before touching the V9 series, discharge static electricity from your body by touching grounded metal. Excessive static electricity may cause malfunction or trouble.
- Insert an SD card into the unit in the same orientation as pictured on the unit. Failure to do so may damage the SD card or the slot on the unit.
- The SD card access LED flashes red when the SD card is being accessed. Never remove the SD card or turn off power to the unit while the LED is flashing. Doing so may destroy the data on the SD card. Check that the LED has turned off before removing the SD card or turning off the power to the unit.

[General Notes]

- Never bundle control cables or input/output cables with high-voltage and large-current carrying cables such as power supply cables. Keep these cables at least 200 mm away from the high-voltage and large-current carrying cables. Otherwise, malfunction may occur due to noise.
- When using the V9 series in an environment where a source of high-frequency noise is present, it is recommended that the FG shielded cable (communication cable) be grounded at each end. However, when communication is unstable, select between grounding one or both ends, as permitted by the usage environment.
- Be sure to plug connectors or sockets of the V9 series in the correct orientation. Failure to do so may lead to damage or malfunction.
- If a LAN cable is inserted into the MJ1 or MJ2 connector on the V9 series, the counterpart device may be damaged. Check the indication on the unit and insert a cable into the correct position.
- Do not use thinners for cleaning because they may discolor the V9 series surface. Use commercially available alcohol.
- If a data receive error occurs when the V9 series and the counterpart (PLC, temperature controller, etc.) are started at the same time, read the manual for the counterpart unit and remove the error correctly.
- Avoid discharging static electricity on the mounting panel of the V9 series. Discharging static electricity on the mounting panel may cause malfunction due to noise.
- Avoid prolonged display of any fixed pattern. Due to the characteristic of liquid crystal displays, an afterimage may occur. If prolonged display of a fixed pattern is expected, use the backlight's auto OFF function.
- The V9 series is identified as a class-A product in industrial environments. In the case of use in a domestic environment, the unit is likely to cause electromagnetic interference. Preventive measures should thereby be taken appropriately.

[Notes on the LCD]

Note that the following conditions may occur under normal circumstances.

- The response time, brightness and colors of the V9 series may be affected by the ambient temperature.
- Tiny spots (dark or luminescent) may appear on the display due to the characteristics of liquid crystal.
- There are variations in brightness and colors between units.

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20. Hitachi Industrial Equipment Systems

| | | |
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Connection Compatibility List

1. Overview

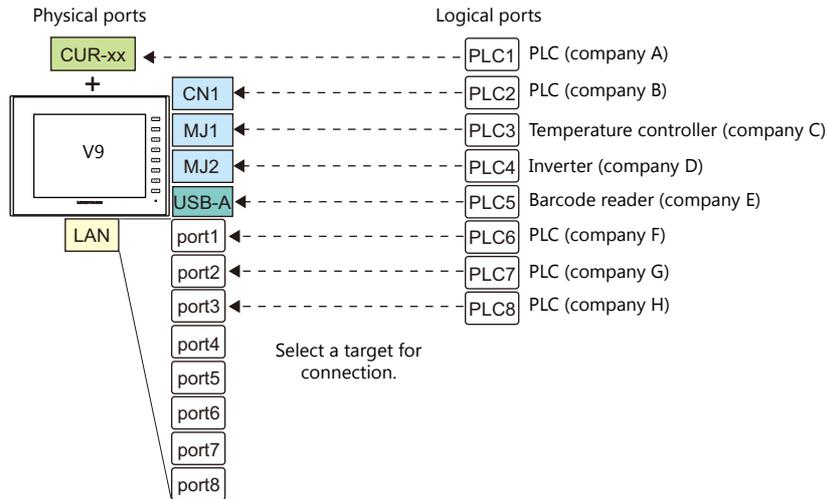
- 1.1 System Configuration
- 1.2 Physical Ports
- 1.3 Connection Methods
- 1.4 Hardware Settings
- 1.5 System Device Memory for Communication Confirmation

1.1 System Configuration

1.1.1 Overview

The V9 series is equipped with seven physical ports consisting of three serial ports, one LAN port, one USB-A port, one USB mini-B port, and one network communication port ^{*1}. The LAN port can open eight ports simultaneously. You can use the physical ports to connect a maximum of eight different models of devices and allow the V9 series to communicate with them at the same time. This is called 8-way communication.

*1 A communication interface unit (CUR-xx, under development) is required to enable network communication.



| Physical Ports | | No. of Ports | Applicable Devices | | |
|----------------|---|----------------------------|--|--|---|
| | | | 8-way Communication | Other than 8-way | |
| Serial | CN1 (RS-232C/RS-422/485) | 1 | PLC, temperature controller, servo, inverter, barcode reader | - | |
| | MJ1 (RS-232C/RS-485, 2-wire connection) | 1 | PLC, temperature controller, servo, inverter, barcode reader, V-Link, slave communication (Modbus RTU) | Computer (screen program transfer, MJ1) | |
| | MJ2 (RS-232C/RS-485, 2-wire connection) | 1 | | Serial printer | |
| Ethernet | LAN | 8 | PLC, slave communication (Modbus TCP/IP) | Computer (screen program transfer) | |
| USB | USB-A | 1 | Barcode reader | Printer (EPSON ESC/P-R compatible), USB flash drive, USB-CFREC-2 (under development), keyboard, mouse, USB hub | |
| | USB mini-B | 1 | - | Printer (PictBridge), computer (screen program transfer) | |
| Network | OPCN-1 | CUR-00 (under development) | 1 | PLC | - |
| | T-Link | CUR-01 (under development) | | | |
| | CC-LINK | CUR-02 (under development) | | | |
| | Ethernet | CUR-03 (under development) | | | |
| | PROFIBUS-DP | CUR-04 (under development) | | | |
| | SX BUS | CUR-06 (under development) | | | |
| | DeviceNet | CUR-07 (under development) | | | |
| | FL-Net | CUR-08 (under development) | | | |

- Only the logical port PLC1 can be selected for the following devices and functions. Thus, they cannot be connected at the same time.
 - Devices
Network connection (CUR-xx, under development), without PLC connection, Mitsubishi Electric A-Link + Net10, AB Control Logix, Siemens S7-200PPI, Siemens S7-300/400 MPI connection
 - Functions
Multi-link2, Multi-link, ladder transfer, ladder monitor, MICREX SX variable name cooperation function

1.1.2 System Composition

Serial Communication

- 1 : 1 Connection

A communication port is selectable from CN1, MJ1, and MJ2.

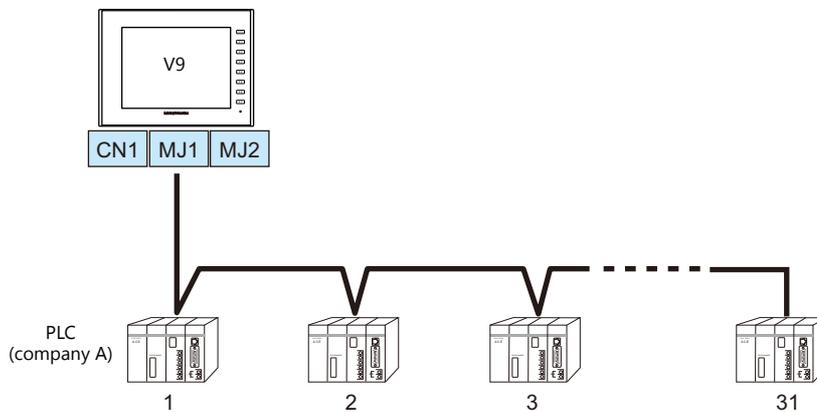
For more information, refer to "1 : 1 Connection" (page 1-8) in "1.3 Connection Methods".



- 1 : n Connection

A communication port is selectable from CN1, MJ1, and MJ2. A maximum of 31 units of the same model can be connected to each port.

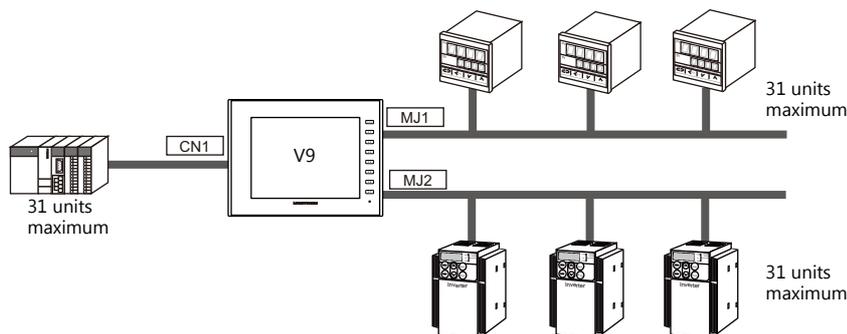
For more information, refer to "1 : n Connection (Multi-drop)" (page 1-14) in "1.3 Connection Methods".



- 3-way Connection

The V9 series is allowed to communicate with three different models of devices at the same time via three serial ports. A maximum of 31 units of the same model can be connected to each port.

The connection method is the same as those for 1 : 1 and 1 : n.



- n : 1 Connection (Under development)

Multiple V9 units can be connected to one PLC or temperature controller.

For more information, refer to "n : 1 Connection (Multi-link2) (Under Development)" (page 1-17), "n : 1 Connection (Multi-link2 (Ethernet)) (Under Development)" (page 1-25), "n : 1 Connection (Multi-link) (Under Development)" (page 1-31) in "1.3 Connection Methods".

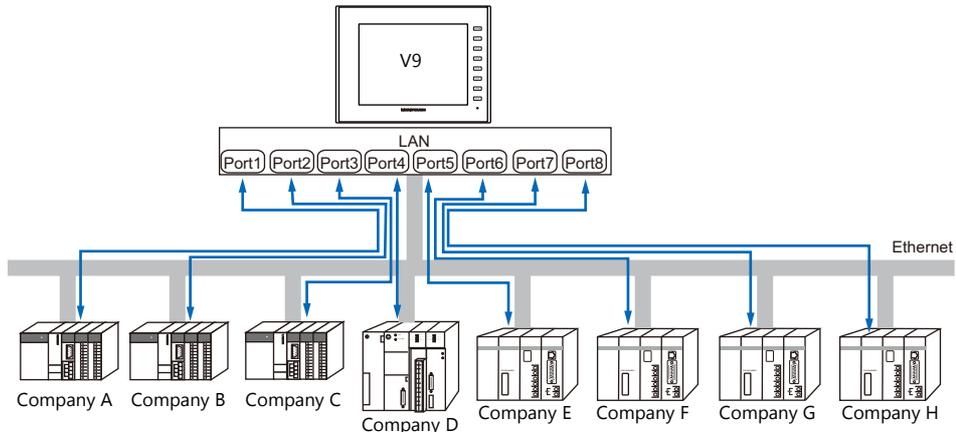
- n : n Connection (Under development)

Multiple V9 units can be connected to multiple PLCs.

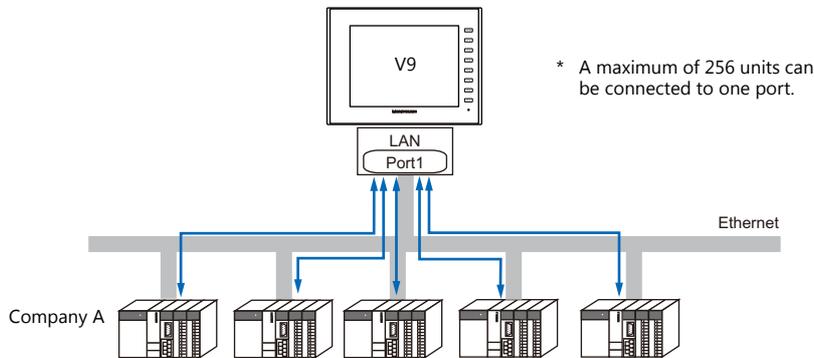
For more information, refer to "n : n Connection (1: n Multi-link2 (Ethernet)) (Under Development)" (page 1-28) in "1.3 Connection Methods".

Ethernet Communication

Because eight communication ports can be opened, the V9series is allowed to communicate with eight models of PLCs at the same time.



When there are two or more PLCs of the same model, the V9 series is allowed to carry out 1 : n communication via one port.



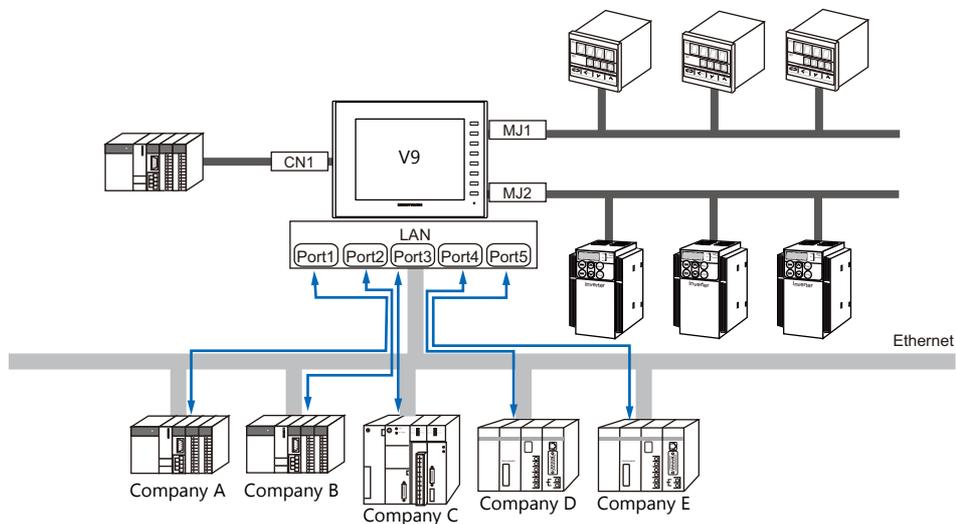
* A maximum of 256 units can be connected to one port.

* For more information, refer to "1.3.2 Ethernet Communication" (page 1-36) in "1.3 Connection Methods".

Mixed Serial-Ethernet Communication

In the case of mixed serial-Ethernet communication, the V9 series is allowed to communicate with eight different models of devices at the same time.

- Connection of 3 models for serial communication and 5 models for Ethernet communication



* For the connection method, refer to "1.3.1 Serial Communication" and "1.3.2 Ethernet Communication".

1.2 Physical Ports

1.2.1 CN1

The CN1 port supports communication via RS-232C, RS-422 (4-wire system), and RS-485 (2-wire system). The signal level can be changed between RS-232C and RS-422/485 under [Communication Setting] of the editor.

* The signal level can be changed between RS-232C and RS-422/485 in the Local mode on the V9 unit as well. For details, refer to the separate V9 Series Hardware Specifications manual.



CAUTION

When executing communication via RS-232C, set the DIP switches 5 and 7 to OFF. For more information on the DIP switch, refer to "1.2.6 DIP Switch (DIPSW) Settings" (page 1-7).

Pin Arrangement

| CN1 Dsub 9pin, Female | No. | RS-232C | | RS-422/RS-485 | |
|--------------------------|-----|---------|--------------------|---------------|------------------------|
| | | Name | Contents | Name | Contents |
| | 1 | NC | Not used | +RD | Receive data (+) |
| | 2 | RD | Receive data | -RD | Receive data (-) |
| | 3 | SD | Send data | -SD | Send data (-) |
| | 4 | NC | Not used | +SD | Send data (+) |
| | 5 | 0V | Signal ground | 0V | Signal ground |
| | 6 | NC | Not used | +RS | RS send data (+) |
| | 7 | RS | RS request to send | -RS | RS send data (-) |
| | 8 | CS | CS clear to send | NC | Not used |
| | 9 | NC | Not used | +5V | Terminating resistance |

Recommended Connector for Communication Cable

| Recommended Connector | |
|-----------------------------|---|
| DDK's 17JE-23090-02(D8C)-CG | D-sub 9-pin, male, inch screw thread, with hood, RoHS compliant |

Applicable Devices

| Applicable Devices |
|--|
| PLC, temperature controller, inverter, servo, barcode reader |

1.2.2 MJ1/MJ2

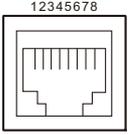
The MJ1 and MJ2 ports support communication via RS-232C and RS-485 (2-wire system). MJ1 is also usable as a screen program transfer port.

CAUTION

- MJ1 and MJ2 use the same type RJ-45 connector as the LAN connector. To prevent damage to the device from an external power supply of the MJ, check the indication on the unit and insert a cable in the correct position.
- MJ1 and MJ2 are not usable for connection via RS-422 (4-wire system). Use the CN1 port instead or a commercially available RS-232C-to-RS-422 converter.

Pin Arrangement

MJ1/MJ2

| MJ1/MJ2 RJ-45 8pin | No. | Signal | Contents |
|---|-----|--------|---------------------------------------|
|  | 1 | +SD/RD | RS-485 + data |
| | 2 | -SD/RD | RS-485 - data |
| | 3 | +5V | Externally supplied +5 V [*] |
| | 4 | | |
| | 5 | SG | Signal ground |
| | 6 | | |
| | 7 | RD | RS-232C receive data |
| | 8 | SD | RS-232C send data |

* For MJ1, MJ2 and USB A, the maximum allowable current is 150 mA in total (only when the installation angle of MONITOUCH is within 60° to 120°).

Recommended Cable

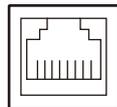
| Recommended Cable |
|--|
| Hakko Electronics' cable "V6-TMP" 3, 5, 10 m |

Notes on Configuring a Cable

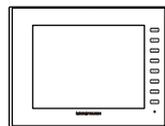
CAUTION

Pins No. 3 and 4 are provided for external power supply. To prevent damage to the device due to wrong connection, check the pin numbers and connect wires correctly.

Pin arrangement
on MONITOUCH



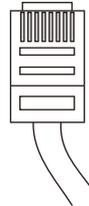
87654321



Pin arrangement
on the cable



12345678



Applicable Devices

| Port | Applicable Devices |
|------|--|
| MJ1 | Computer (screen program transfer) |
| | PLC, temperature controller, inverter, servo, barcode reader, V-Link, slave communication (Modbus RTU), serial printer |
| MJ2 | PLC, temperature controller, inverter, servo, barcode reader, V-Link, slave communication (Modbus RTU), serial printer |

1.2.3 LAN



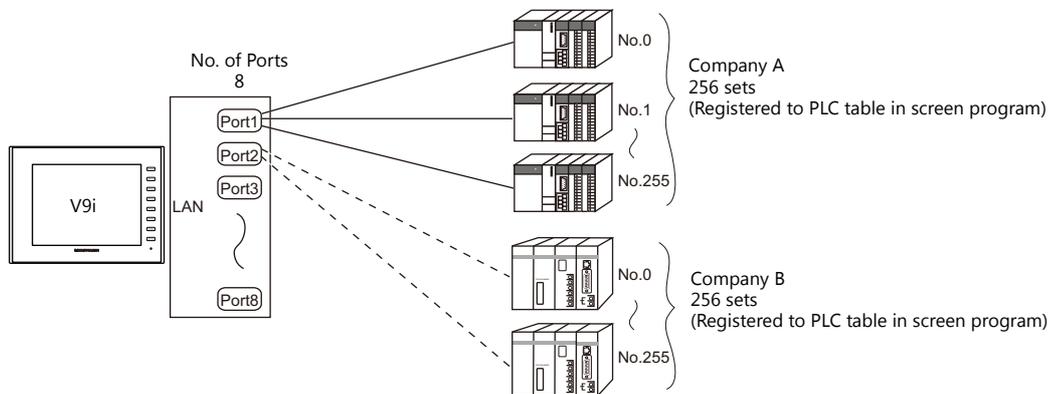
CAUTION

The LAN connector uses the same type RJ-45 connector as MJ1 and MJ2. Check the indication on the unit and insert a cable into the correct position.

LAN Port Specifications

| Item | Specifications | |
|---------------------------------------|--|----------------------|
| | 100BASE-TX (IEEE802.3u) | 10BASE-T (IEEE802.3) |
| Baud Rate | 100 Mbps | 10 Mbps |
| Transmission method | Base band | |
| Maximum segment length | 100 m (between the node and the hub) | |
| Connecting cable | 100 Ω, UTP cable, category 5 | |
| Protocol | UDP/IP, TCP/IP | |
| Port | Auto-MDIX, Auto-Negotiation functions compatible | |
| Number of concurrently opened ports | 8 ports | |
| Maximum number of connectable devices | 256 sets each via one single port PLC1 - PLC8 | |

Maximum number of connectable devices



Pin Arrangement

| LAN RJ-45 | No. | Name | Contents |
|-----------|-----|------|------------------|
| | 1 | TX+ | Send signal + |
| | 2 | TX- | Send signal - |
| | 3 | RX+ | Receive signal + |
| | 4 | NC | Not used |
| | 5 | | |
| | 6 | RX- | Receive signal - |
| | 7 | NC | Not used |
| | 8 | | |

Applicable Devices

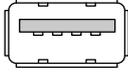
| Applicable Devices |
|--|
| PLC, slave communication (Modbus TCP/IP), computer (screen program transfer, V-Server, etc.) |

1.2.4 Network Communication Port (Under Development)

An optional communication interface unit "CUR-xx" (under development) is required to perform network communication. For more information, refer to the specifications for each unit.

1.2.5 USB

USB Port Specifications

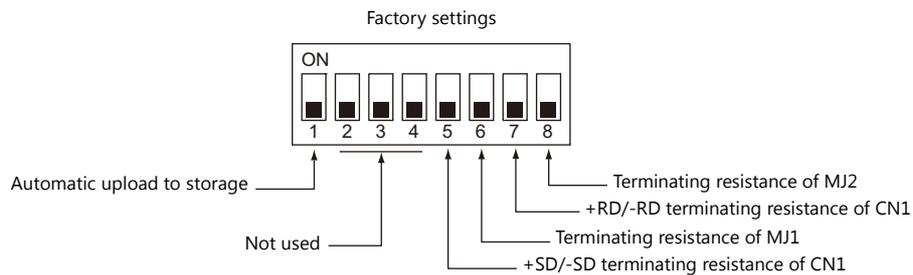
| Item | Specifications |
|---|--|
| USB-A  | Applicable standards USB versions 2.0 |
| USB mini-B  | Baud Rate High-speed 480 Mbps |

Applicable Devices

| Port | Applicable Devices |
|------------|--|
| USB-A | Printer (EPSON ESC/P-R compatible), barcode reader, USB flash drive, USB-CFREC-2 (under development), numeric keypad, keyboard, mouse, USB hub |
| USB mini-B | Printer (PictBridge), computer (screen program transfer) |

1.2.6 DIP Switch (DIPSW) Settings

The V9 series is equipped with DIP switches 1 to 8. When setting the DIP switch, turn the power off.



DIPSW1* (Automatic upload to storage)

Set the DIPSW1 to ON when automatically uploading screen programs from storage such as an SD card or USB flash drive. For details, refer to the separate V9 Series Hardware Specifications manual.

* Be sure to set the DIPSW1 to OFF when automatic upload is not performed.

DIPSW5, 6, 7, 8 (Terminating resistance setting)

- When connecting a controller to CN1 via RS-422/485 (2-wire connection), set the DIPSW7 to ON.
- When connecting a controller to CN1 via RS-422/485 (4-wire connection), set the DIPSW5 and DIPSW7 to ON.
- When connecting a controller at MJ1 via RS-422/485 (2-wire connection), set the DIPSW6 to ON.
- When connecting a controller at MJ2 via RS-422/485 (2-wire connection), set the DIPSW8 to ON.



CAUTION

When executing communication via RS-232C at CN1, set the DIP switches 5 and 7 to OFF.

1.3 Connection Methods

1.3.1 Serial Communication

1 : 1 Connection

Overview

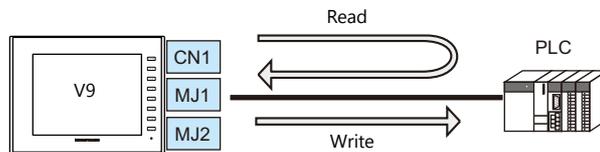
- One set of the V9 is connected to one PLC (1 : 1 connection).
- You can make settings for 1 : 1 communication in [Communication Setting] for the logical ports PLC1 - PLC8. A communication port is selectable from CN1, MJ1, and MJ2.



RS-232C or RS-422 (RS-485) connection
 Maximum length of wiring
 RS-232C connection: 15 m
 RS-422/RS-485 connection: 500 m

* The maximum length of wiring varies depending on the connected device.
 Check the specifications for each device.

- The V9 (master station) communicates with a PLC under the PLC's protocol. Therefore, there is no need to prepare a communication program for the PLC (slave station).
- The V9 reads from the PLC device memory for screen display. It is also possible to write switch data or numerical data entered through the keypad directly to the PLC device memory.

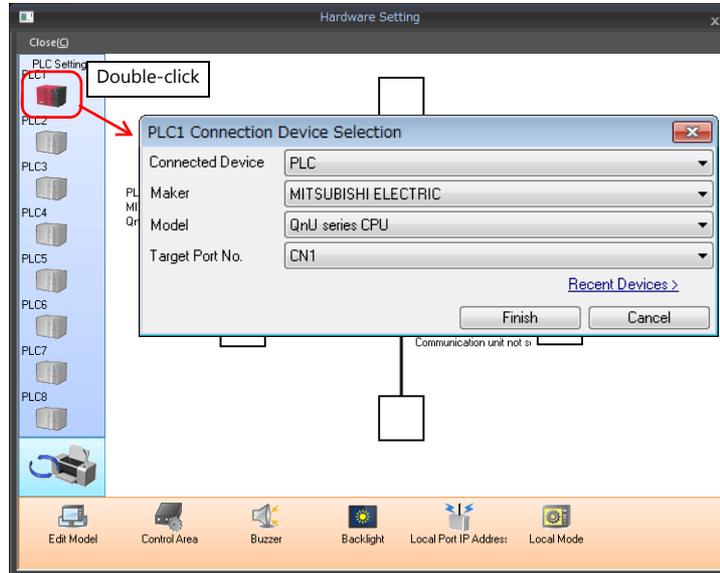


V-SFT Ver. 6 Settings

Hardware Settings

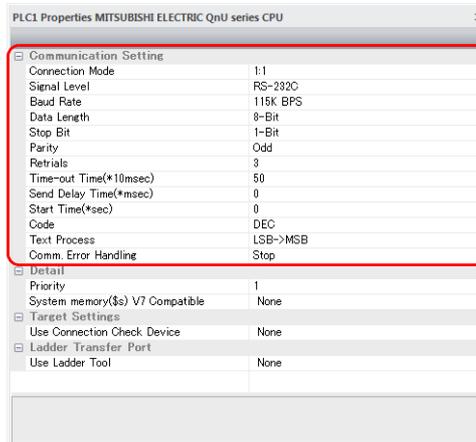
Selecting a device to be connected

Select the device for connection from [System Setting] → [Hardware Setting].



PLC properties

Configure [Communication Setting] on the [PLC Properties] window.



| Item | Contents |
|-------------------|--|
| Connection Mode | 1 : 1 |
| Signal Level | Configure according to the connected device. |
| Baud Rate | |
| Data Length | |
| Stop Bit | |
| Parity | |
| Target Port No. | |
| Transmission Mode | |

For settings other than the above, see "1.4 Hardware Settings" (page 1-43).

Settings of a Connected Device

Refer to the chapter of the respective manufacturer.
For descriptions of connecting PLCs, refer to the manual for each PLC.

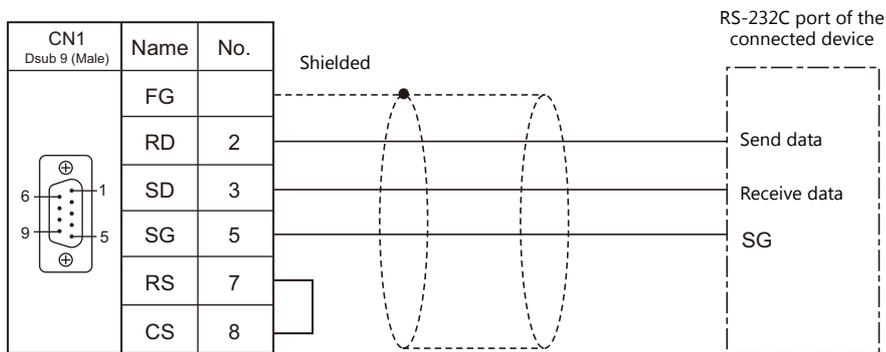
Wiring

| | |
|---|--|
|  DANGER | Be sure to turn off the power before connecting cables. Otherwise, electrical shock or damage may occur. |
|---|--|

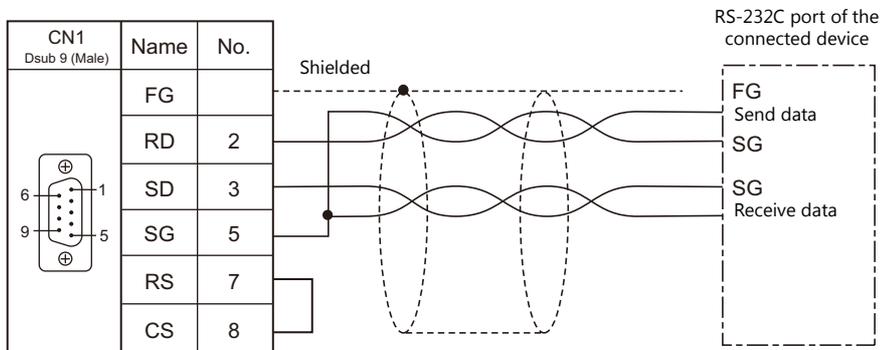
CN1

RS-232C connection

- Prepare a communication cable on your side. Twisted pairs of 0.3 mm sq. or above are recommended.
- The maximum length for wiring is 15 m.
 - * The maximum length varies depending on the connected device. Check the specifications for each device.
- Connect a shielded cable to either the V9 series or the connected device. The connection diagram shows the case where the shielded cable is connected on the V9 series side. Connect the cable to the FG terminal on the backside of MONITOUCH.

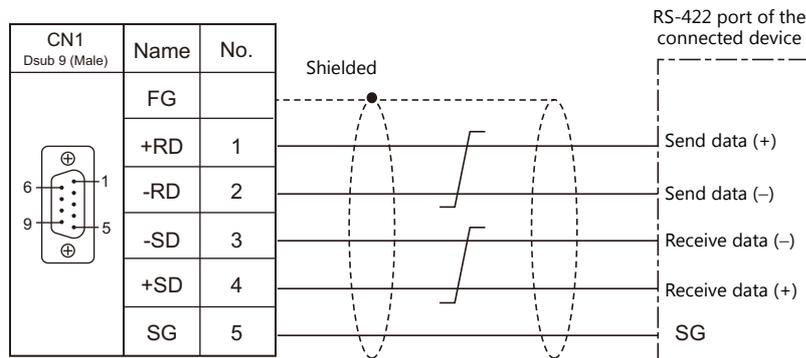


- If noise disturbs communications, establish connections between SD and SG and between RD and SG as pairs respectively, and connect a shielded cable to both the V9 series and the connected device.

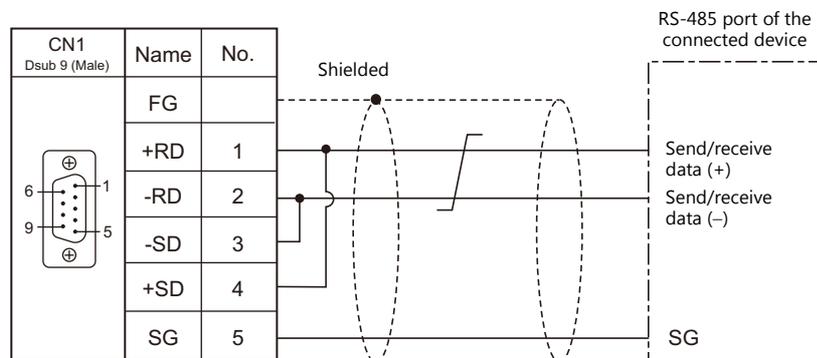


RS-422/RS-485 connection

- Prepare a communication cable on your side. Twisted pairs of 0.3 mm sq. or above are recommended.
- The maximum length of wiring is 500 m.
 - * The maximum length varies depending on the connected device. Check the specifications for each device.
- Connect twisted pairs between +SD and –SD, and between +RD and –RD.
- If the PLC has a signal ground (SG) terminal, connect it.
- To use a terminal block for connection, use Hakko Electronics' optionally available "TC-D9".
- The DIP switch on the back of the V9 unit is used to set the terminating resistance. For more information on DIP switches, refer to "1.2.6 DIP Switch (DIPSW) Settings" (page 1-7).
- Connect a shielded cable to either the V9 series or the connected device. The connection diagram shows the case where the shielded cable is connected on the V9 series side. Connect the cable to the FG terminal on the backside of MONITOUCH.
 - RS-422 (4-wire system)

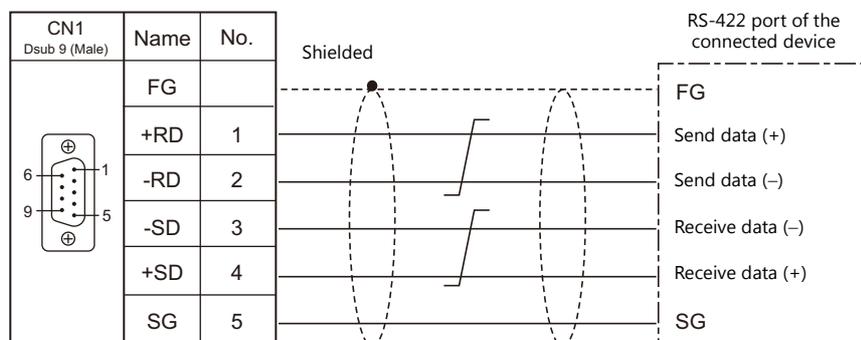


- RS-485 (2-wire system)

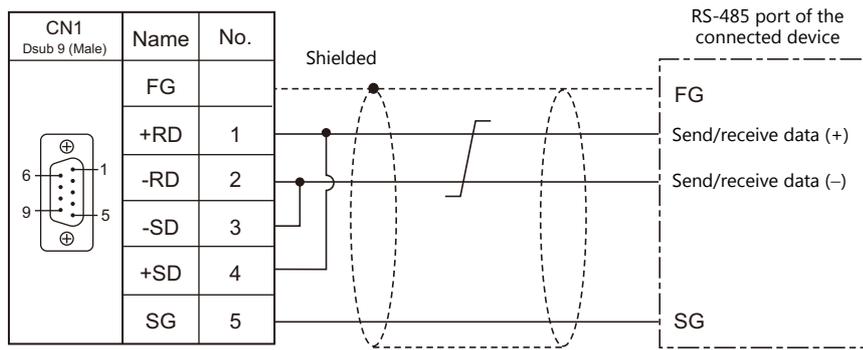


- If noise disturbs communications, connect a shielded cable to both the V9 series and the connected device.

- RS-422 (4-wire system)



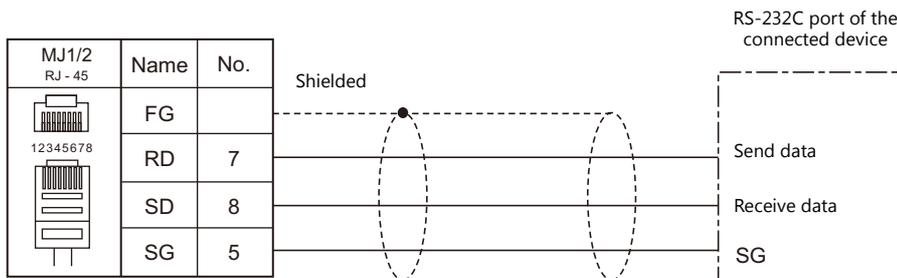
- RS-485 (2-wire system)



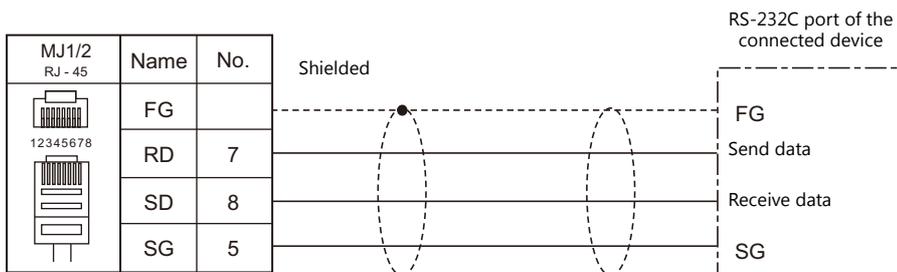
MJ1/MJ2

RS-232C connection

- Use Hakko Electronics' cable "V6-TMP" (3, 5, 10 m) as a communication cable.
- The maximum length of wiring is 15 m.
 - * The maximum length varies depending on the connected device. Check the specifications for each device.
- Connect a shielded cable to either the V9 series or the connected device. Connect the cable to the FG terminal on the backside of MONITOUCH.



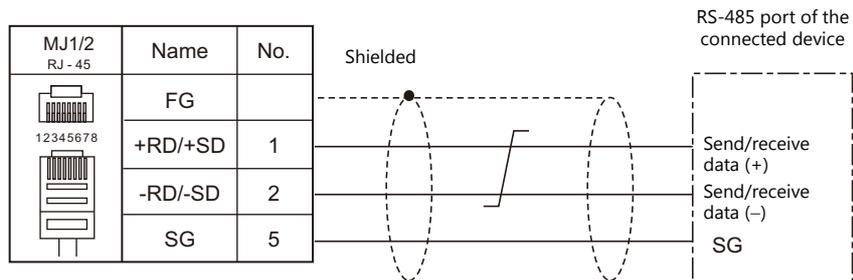
- If noise disturbs communications, connect a shielded cable to both the V9 series and the connected device.



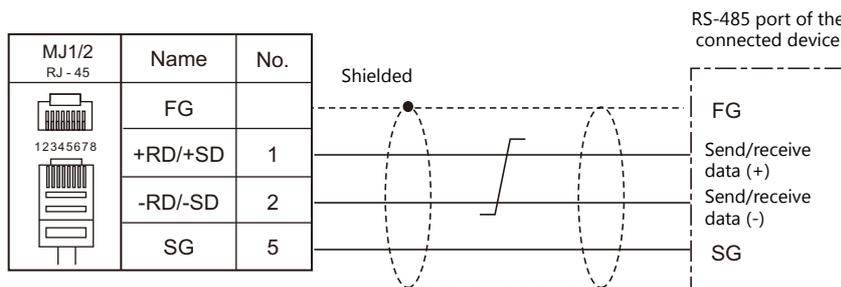
RS-485 (2-wire system) connection**CAUTION**

The MJ1 and MJ2 are not usable for connection via RS-422 (4-wire system). Use the CN1 port instead or a commercially available RS-232C-to-RS-422 converter.

- Use Hakko Electronics' cable "V6-TMP" (3, 5, 10 m) as a communication cable.
- The maximum length of wiring is 500 m.
 - * The maximum length varies depending on the connected device. Check the specifications for each device.
- If the PLC has a signal ground (SG) terminal, connect it.
- The DIP switch on the back of the V9 unit is used to set the terminating resistance. For more information, see "1.2.6 DIP Switch (DIPSW) Settings" (page 1-7).
- Connect a shielded cable to either the V9 series or the connected device. Connect the cable to the FG terminal on the backside of MONITOUCH.



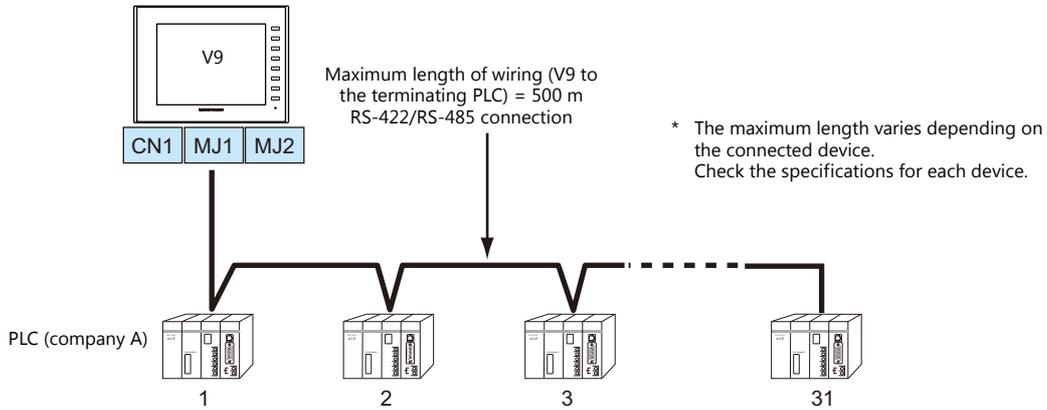
- If noise disturbs communications, connect a shielded cable to both the V9 series and the connected device.



1 : n Connection (Multi-drop)

Overview

- Multi-drop connection connects one V9 unit to multiple PLCs of the same model as a 1 : n connection. (Maximum connectable units: 31)
- You can make settings for 1 : n communication in [Communication Setting] for the logical ports PLC1 - PLC8. A communication port is selectable from CN1, MJ1, and MJ2.



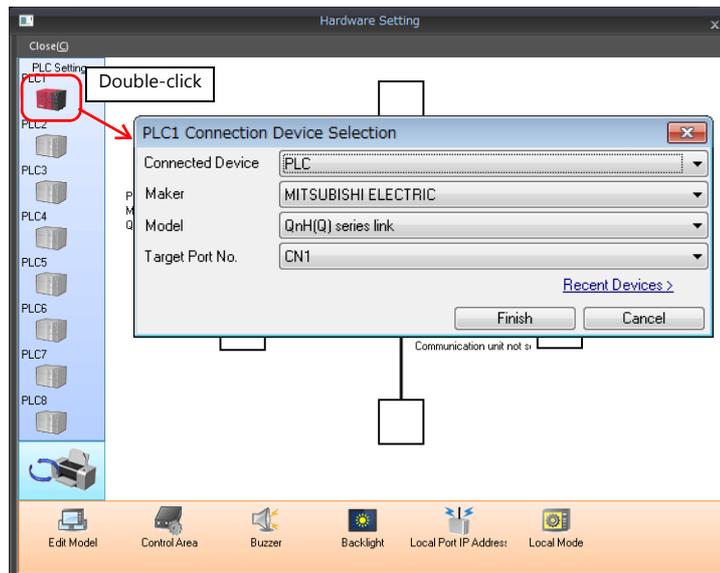
- The ladder transfer function is not available for a 1 : n connection.
- For models that support multi-drop connection, refer to the Connection Compatibility List provided at the end of this manual or the chapters on individual manufacturers.

V-SFT Ver. 6 Settings

Hardware Settings

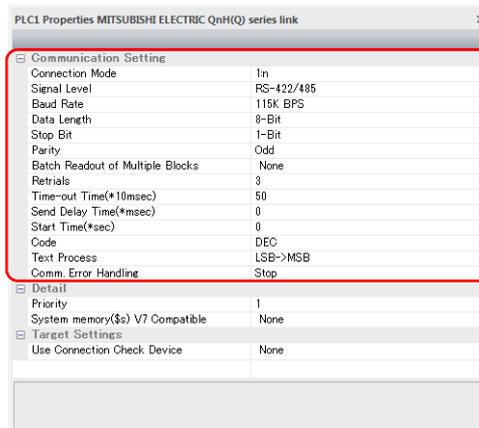
Selecting a device to be connected

Select the device for connection from [System Setting] → [Hardware Setting].



PLC properties

Configure [Communication Setting] on the [PLC Properties] window.



| Item | Contents |
|-------------------|--|
| Connection Mode | 1 : n |
| Signal Level | RS-422/485 |
| Baud Rate | Configure according to the connected device. |
| Data Length | |
| Stop Bit | |
| Parity | |
| Target Port No. | |
| Transmission Mode | |

For settings other than the above, see "1.4 Hardware Settings" (page 1-43).

Settings of a Connected Device

Refer to the chapter of the respective manufacturer.

For descriptions of connecting PLCs, refer to the manual for each PLC.

Wiring



DANGER

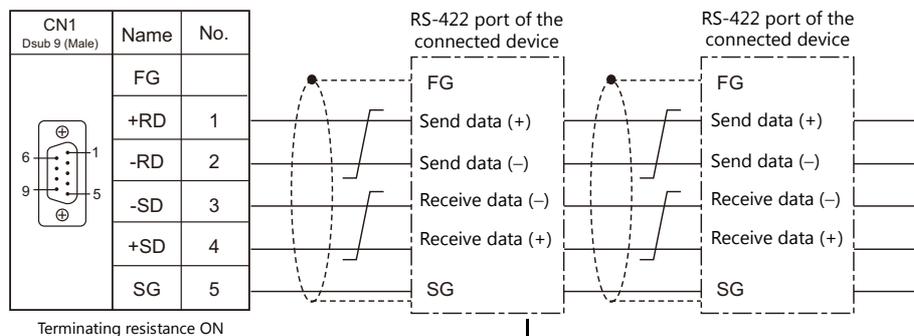
Be sure to turn off the power before connecting cables. Otherwise, electrical shock or damage may occur.

CN1

The wiring between a V9 and a connected device is the same as that for 1 : 1 communication. For description of wiring between connected devices, refer to the manuals issued by the manufacturers.

RS-422 (4-wire system) connection

- Connection example

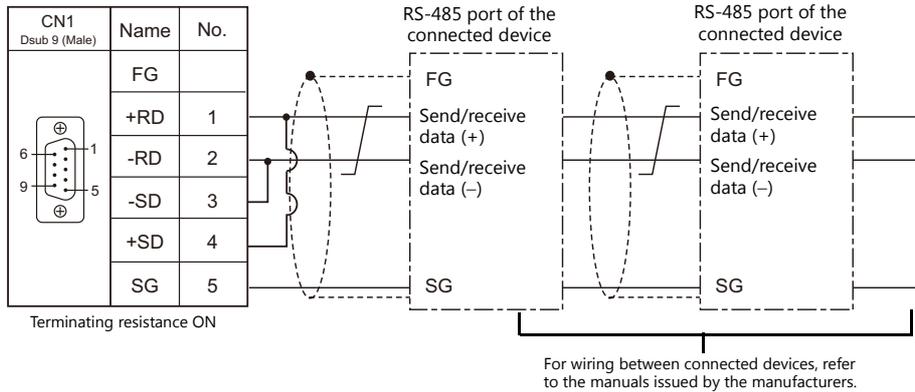


Terminating resistance ON

For wiring between connected devices, refer to the manuals issued by the manufacturers.

RS-485 (2-wire system) connection

- Connection example

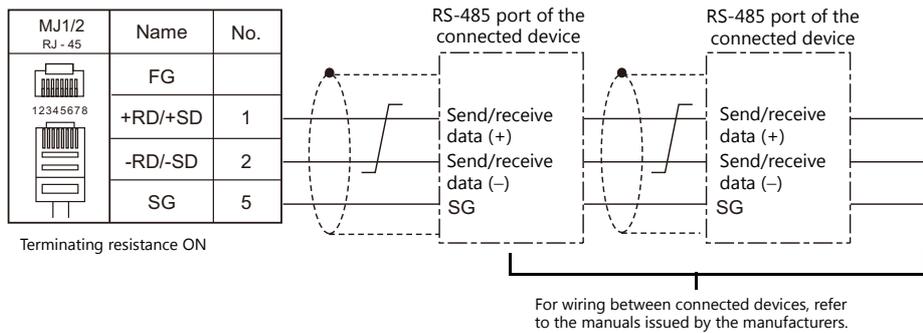


MJ1/MJ2

The wiring between a V9 and a connected device is the same as that for 1 : 1 communication. For description of wiring between connected devices, refer to the manuals issued by the manufacturers.

RS-485 (2-wire system) connection

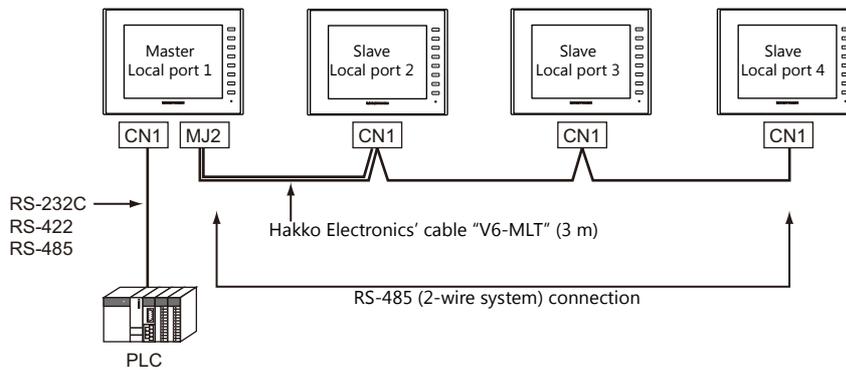
- Connection example



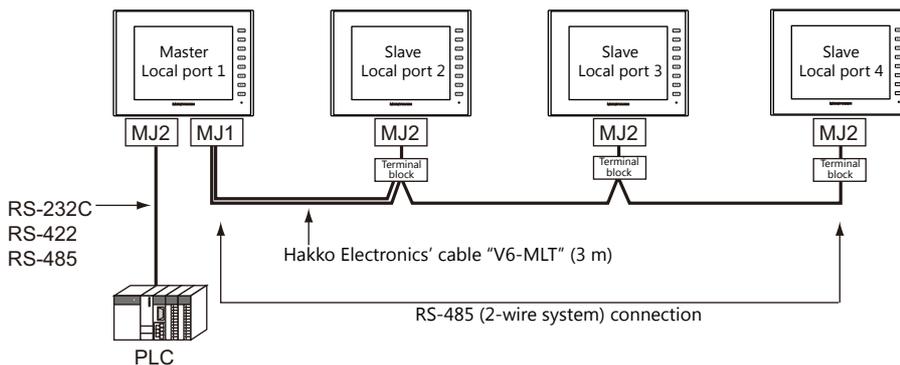
n : 1 Connection (Multi-link2) (Under Development)

Overview

- One PLC is connected to a maximum of four V9 units. The V8, V7, and V6 series can be used together.
- Multi-link2 enables you to establish an original network consisting of a master V9 of local port No. 1 and slave V9 units of local port Nos. 2, 3, and 4. The master V9 communicates with the PLC directly, and the slave V9 units communicate with the PLC through the master.
 - Connection example 1:



- Connection example 2:

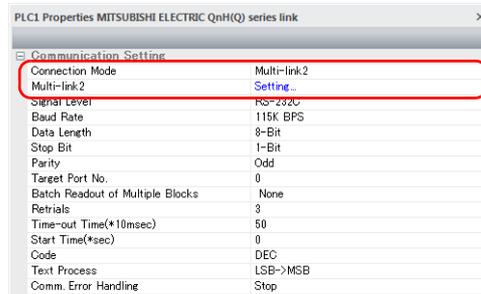


- You can make settings for multi-link2 in [Communication Setting] for PLC1. Therefore, multi-link2 connection is not possible concurrently with a network connection that uses a "CUR-xx" communication interface unit (under development).
- Multi-link2 enables sharing of data stored in PLC1 device memory among the V9 units. However, sharing data in PLC2 - PLC8 is not possible.
- The communication speed between the master and the PLC depends on the setting made on the PLC. The maximum communication speed between V9 units is 115 kbps, which is higher than the one available with multi-link connection described in "n : 1 Connection (Multi-link) (Under Development)".
- For PLCs that support multi-link2 connection, see Connection Compatibility List provided at the end of this manual. The connection between the master and the PLC is the same as the one for 1 : 1 connection. RS-485 (2-wire system) connection is adopted to connect a master with slaves. At this time, use Hakko Electronics' cable "V6-MLT" for the multi-link2 master.
- When connecting the V6 series together with the V9 series, note the following points:
 - When V609E, V606e, V606, or V606i is connected as a master, only V609E, V606e, V606, or V606i can be connected as a slave.
The V9 series cannot be used as a slave in this case.
 - Multi-link2 cannot be used for the V6 series with which temperature control network/PLC2Way is used.
 - Multi-link2 may not be used on the V6 series depending on its hardware version.
For more information, refer to the V6 Series Hardware Specifications manual.
- If the master station becomes faulty (communication error), the master and slave stations do not work, and as a result, "Communication Error Time-Out" is displayed. If a slave station becomes faulty, "Data Loading..." is displayed due to a communication error only on the faulty station.
- The ladder transfer function is not available for a multi-link2 connection.

V-SFT Ver. 6 Settings

Make settings on [Hardware Setting] → [PLC Properties]. The differences with respect to a 1 : 1 connection and the points where caution is required are explained here.
 For details on other settings, refer to Hardware Settings in " 1 : 1 Connection" (page 1-8).

PLC Properties

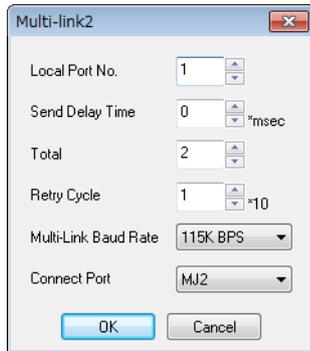


| Item | | Contents |
|-----------------------|-----------------|---|
| Communication Setting | Connection Mode | Multi-link2 |
| | Multi-link2 | Click [Setting] to display the [Multi-link] dialog, then make the necessary settings in this dialog. For more information on settings, see " Multi-link2" (page 1-18). |

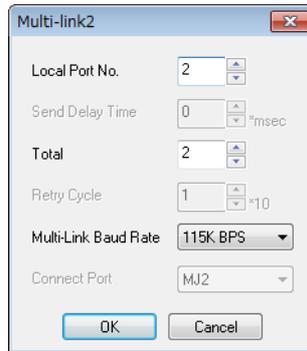
Multi-link2

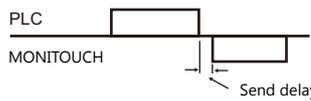
For a master, set all of the items. For a slave, set only those items marked "◆".

- Master



- Slave

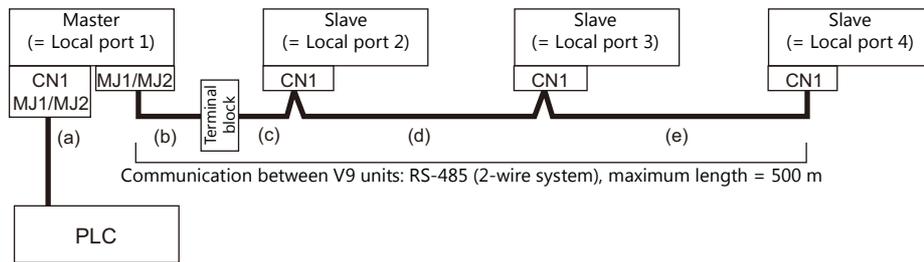


| | |
|-----------------------|--|
| Local Port No.◆ | 1 to 4 Specify a port number of the V9. For the master set "1", and for the slaves set "2" to "4". Note that if the port number specified is the same as that already set for another V9 unit, the system will not operate correctly. |
| Send Delay Time | Specify a delay time that elapses before V9 sends the next command after receiving data from the PLC. Normally use the default setting (0).  |
| Total◆ | 2 to 4 Set the total number of V9 units connected in the multi-link2 connection. The setting must be the same as other V9 series on the same communication line. |
| Retry Cycle | Set the number of cycles before the master sends an inquiry for restoration to a slave that has a communication problem (= system down). When a slave has a problem, it is temporarily removed from the communication targets, and the master sends an inquiry for restoration every number of cycles specified for [Retry Cycle]. This setting does not affect the communication speed if no problem is occurring on the slave; however, if there is any problem, it does affect the communication speed. When the setting value is small: Restoration will not take long. When the setting value is large: Restoration will take a longer time. |
| Multi-Link Baud Rate◆ | 4800/9600/19200/38400/57600/115 Kbps Set the baud rate for between V9 series units. The setting must be the same as other V9 series on the same communication line. |
| Connect Port | CN1/MJ1/MJ2 Set the port to be connected to slaves. |

System Configurations and Wiring Diagrams

Connection Method 1

Connecting the MJ1/MJ2 of the master to CN1 connectors of the slaves



(a) Connection between master and PLC

Select the port for connection from among CN1, MJ1 and MJ2.

The communication settings and connection method are the same as those for 1 : 1 connection.

(b), (c) Connection between master and slave

Choose the connecting port of the master between MJ1 and MJ2.

The connecting port of the slave should be CN1. It is convenient to install the optional terminal converter "TC-D9".

Use the "V6-MLT" cable (3 m). If the distance is greater than 3 meters the customer should prepare a terminal block and extension cable (c), and should make the connection through that terminal block.

(d), (e) Connection between slaves

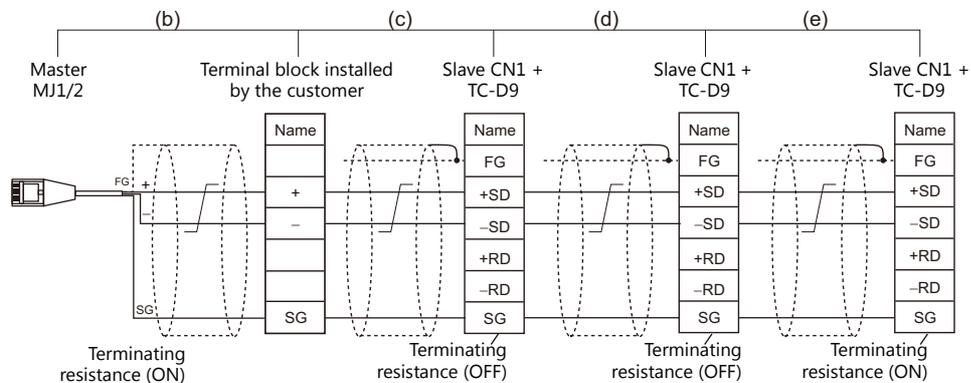
Use the RS-485 (2-wire system) connection. It is convenient to install the optional terminal converter "TC-D9". Use twisted-pair cables of 0.3 mm sq or greater.

(b), (c), (d), (e) The maximum length of the wiring among the master and slave is 500 m.

Wiring diagrams

- When a TC-D9 is used:

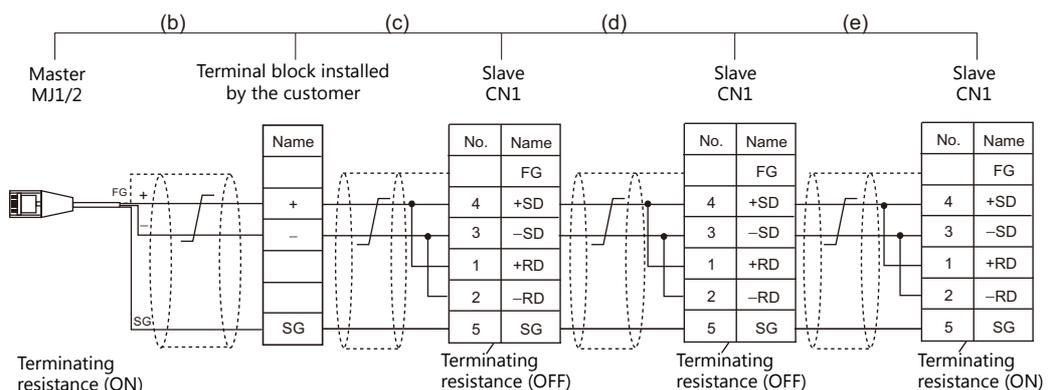
Set the slide switch of "TC-D9" to ON (2-wire system).



* As a measure against noise, connect the frame ground terminal of each V9 series at one side only. The frame ground of V6-MLT must be connected to the V9 series.

- When no TC-D9 is used:

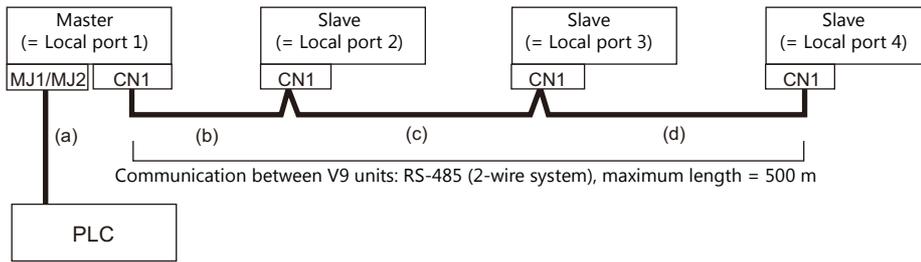
Install jumpers between +SD and +RD as well as -SD and -RD.



* As a measure against noise, connect the frame ground terminal of each V9 series at one side only. The frame ground of V6-MLT must be connected to the V9 series.

Connection Method 2

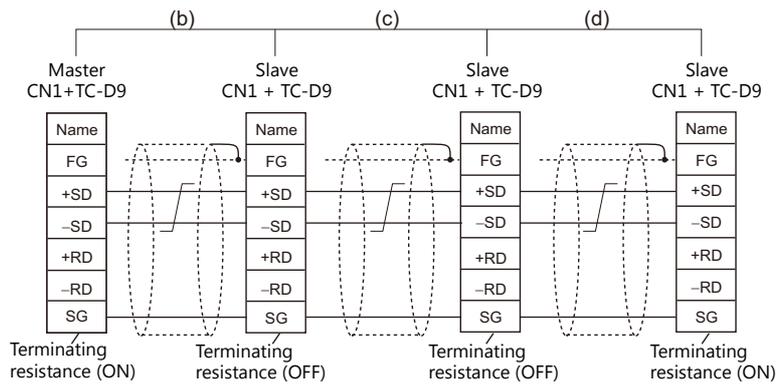
Connecting the CN1 of the master to the CN1s of the slaves



- (a) Connection between master and PLC
Choose the connection port between MJ1 and MJ2.
The communication settings and connection method are the same as those for 1 : 1 connection.
- (b), (c), (d) Connection between master and slave
Use the RS-485 (2-wire system) connection. It is convenient to install the optional terminal converter "TC-D9". Use twisted-pair cables of 0.3 mm sq or greater. The maximum length of the wiring is 500 m.

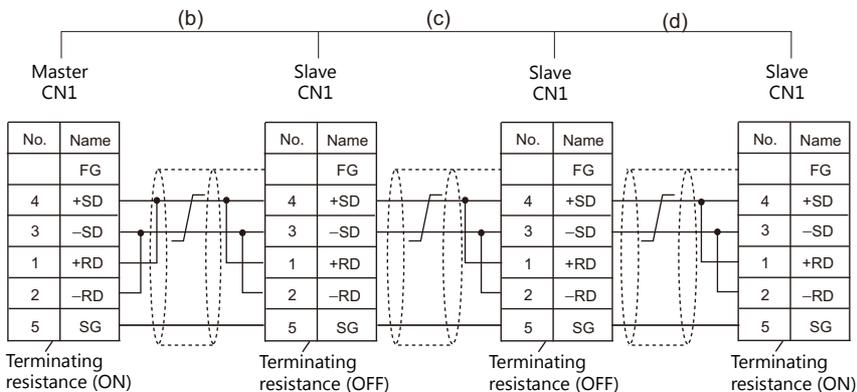
Wiring diagrams

- When a TC-D9 is used:
Set the slide switch of "TC-D9" to ON (2-wire system).



* As a measure against noise, connect the frame ground terminal of each V9 series at one side only.

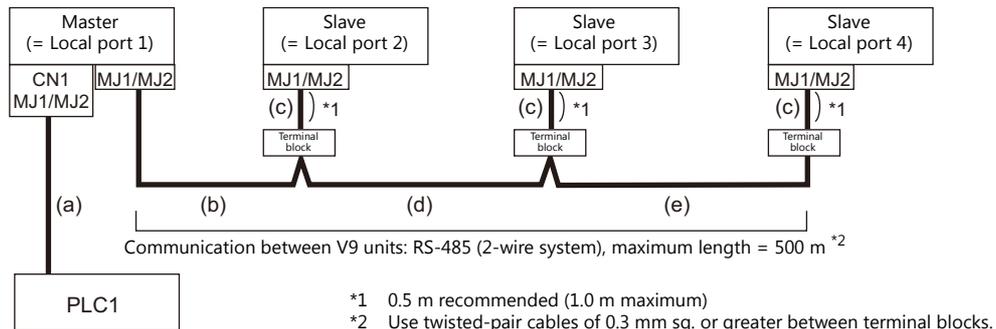
- When no TC-D9 is used:
Install jumpers between +SD and +RD as well as -SD and -RD.



* As a measure against noise, connect the frame ground terminal of each V9 series at one side only.

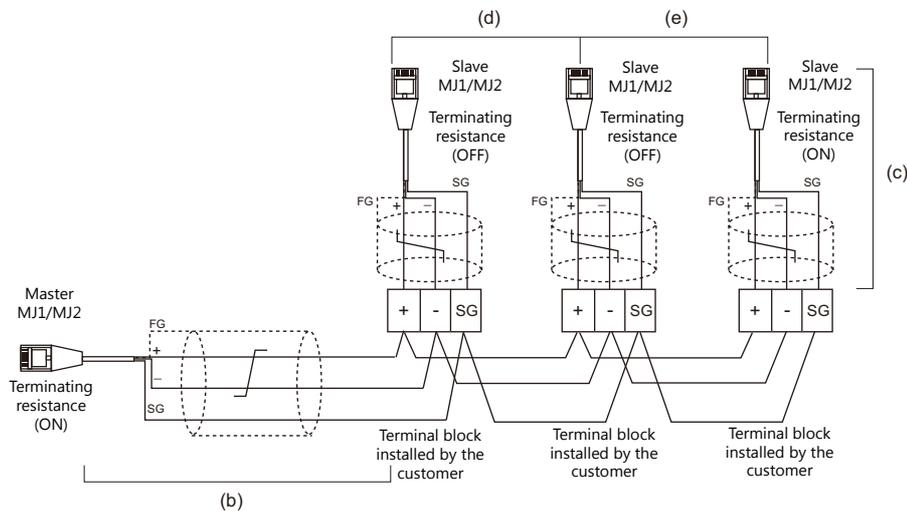
Connection Method 3

Connecting the MJ1/MJ2 of the master to the MJ1/MJ2 ports of the slaves



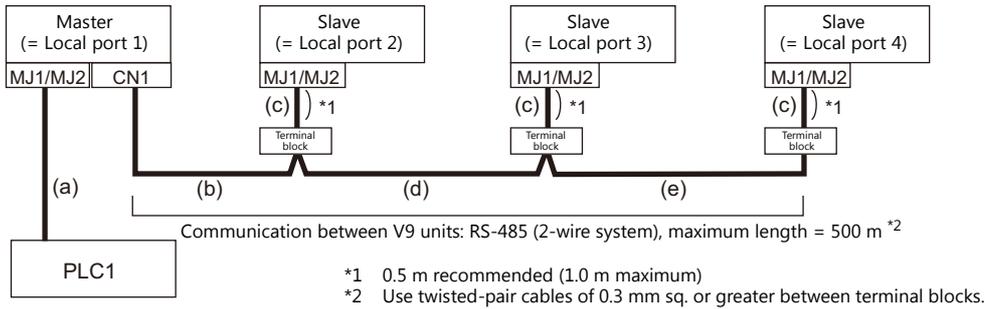
- (a) Connection between master and PLC
Select the port for connection from among CN1, MJ1 and MJ2.
The communication settings and connection method are the same as those for 1 : 1 connection.
- (b) Connection between master and terminal block
Choose the connecting port of the master between MJ1 and MJ2.
For the cable, use "V6-MLT" (3 m). Connect the terminals of this cable to a terminal block prepared by the customer.
- (c) Connection between terminal block and slave
Choose the connecting port of the slave between MJ1 and MJ2.
Use the "V6-MLT" cable (3 m).
- (d) Connection between terminal blocks
Use the RS-485 (2-wire system) connection. Use twisted-pair cables of 0.3 mm sq or greater.
- (b), (c), (d) The maximum length of the wiring among the master and slave is 500 m.

Wiring diagrams



Connection Method 4

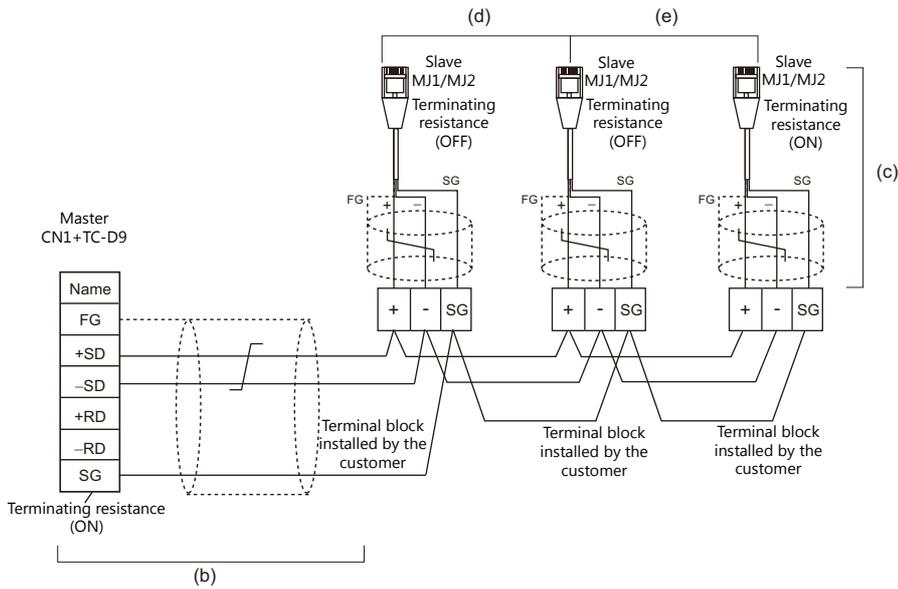
Connecting the CN1 of the master to the MJ1/MJ2 of the slaves



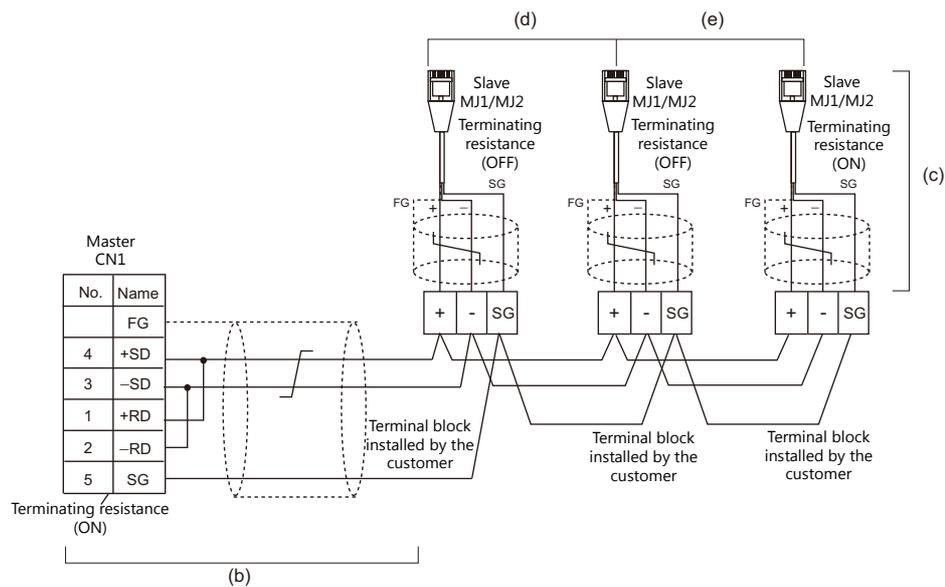
- (a) Connection between master and PLC
 Choose the connection port between MJ1 and MJ2.
 The communication settings and connection method are the same as those for 1 : 1 connection.
- (b), (d), (e) Connection between master and terminal block
 For the connecting port of the master, choose CN1. For the slave, choose between MJ1 and MJ2.
 Use the RS-485 (2-wire system) connection. Use twisted-pair cables of 0.3 mm sq or greater. The maximum length of the wiring is 500 m.
- (c) Connection between terminal block and slave
 The connecting port of the slave should be MJ1 or MJ2.
 Use the "V6-MLT" cable (3 m).

Wiring diagrams

- When a TC-D9 is used:
Set the slide switch of "TC-D9" to ON (2-wire system).

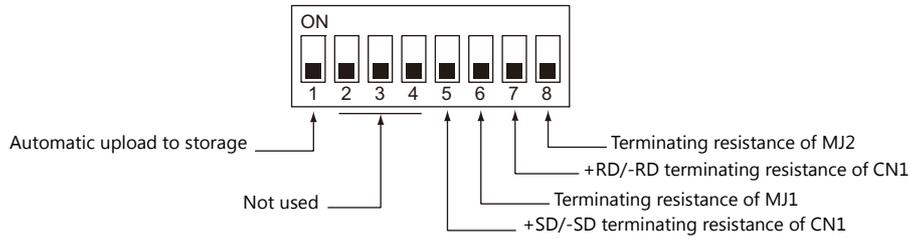


- When no TC-D9 is used:
Install jumpers between +SD and +RD as well as -SD and -RD.



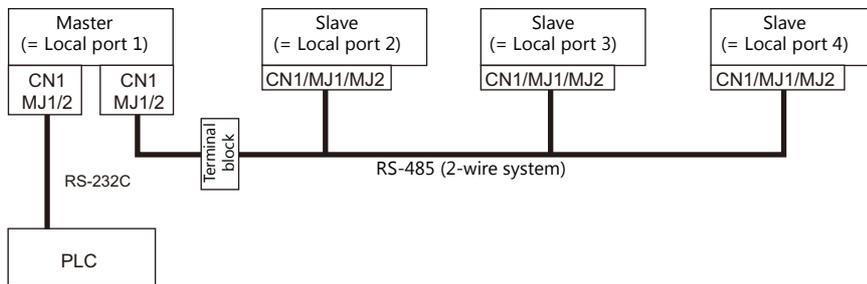
Terminating Resistance Setting

The terminating resistance should be set on the DIP switch.

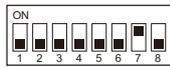


When the PLC is connected to the master via RS-232C:

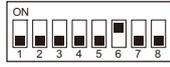
There is no terminating resistance setting for communications between the master and the PLC. Set terminating resistances for connections between V9 units.



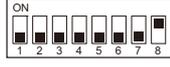
When CN1 is used:



When MJ1 is used:



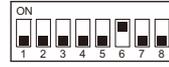
When MJ2 is used:



When CN1 is used:



When MJ1 is used:

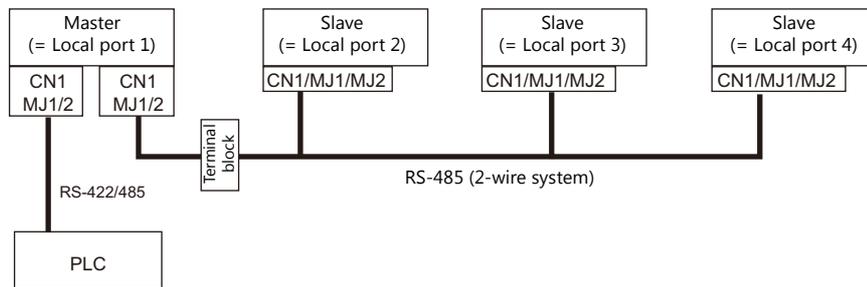


When MJ2 is used:

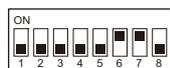


When the PLC is connected to the master via RS-422/485:

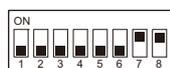
Make terminating resistance settings for communications between the master and PLC, and between V9 units.



When CN1 and MJ1 are used:



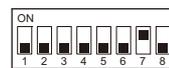
When CN1 and MJ2 are used:



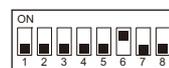
When MJ1 and MJ2 are used:



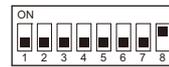
When CN1 is used:



When MJ1 is used:



When MJ2 is used:

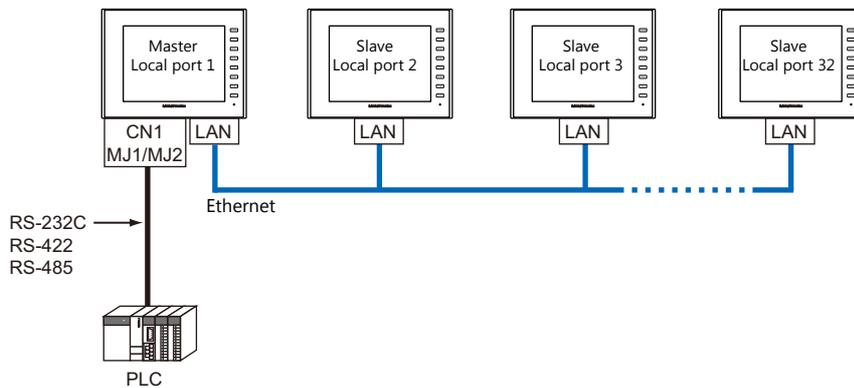


n: 1 Connection (Multi-link2 (Ethernet)) (Under Development)

Overview

- One PLC is connected to a maximum of 32 V9 units. The V8 series can be used together.
- Multi-link2 (Ethernet) enables you to establish an original network consisting of a master V9 of local port No. 1 and slave V9 units of local port Nos. 2 to 32. The master V9 communicates with the PLC directly, and the slave V9 units communicate with the PLC through the master.

- Connection example



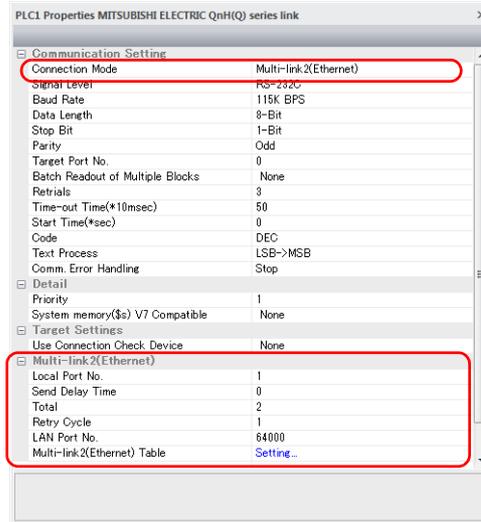
- You can make settings for multi-link2 (Ethernet) in [Communication Setting] for PLC1. Therefore, multi-link2 connection is not possible concurrently with a network connection that uses a "CUR-xx" communication interface unit.
- Multi-link2 (Ethernet) enables sharing of data stored in PLC1 device memory among the V9 units. However, sharing data in PLC2 - PLC8 is not possible.
- The V7 and V6 series cannot be used together.
- The communication speed between the master station and the PLC depends on the setting made on the PLC; however, communication among V9 units is performed via Ethernet, thus, high-speed communication is possible among them.
- For PLCs that support multi-link2 (Ethernet) connection, see Connection Compatibility List provided at the end of this manual.
The connection between the master and the PLC is the same as the one for 1 : 1 connection.
Ethernet connection is adopted to connect a master with slaves.
- If the master station becomes faulty (communication error), the master and slave stations do not work, and as a result, "Communication Error Time-Out" is displayed. If a slave station becomes faulty, "Data Loading..." is displayed due to a communication error only on the faulty station.
- The ladder transfer function is not available for a multi-link2 (Ethernet) connection.

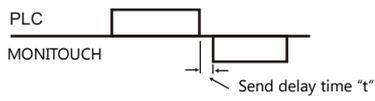
V-SFT Ver. 6 Settings

Make settings on [Hardware Setting] → [PLC Properties]. The differences with respect to a 1 : 1 connection and the points where caution is required are explained here.

For details on other settings, refer to Hardware Settings in “ 1 : 1 Connection” (page 1-8).

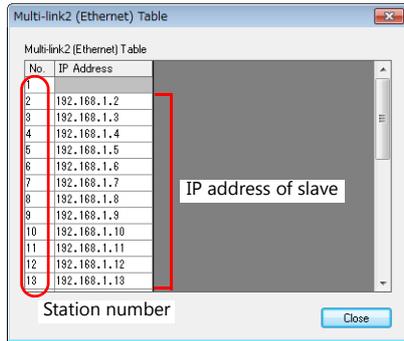
PLC Properties



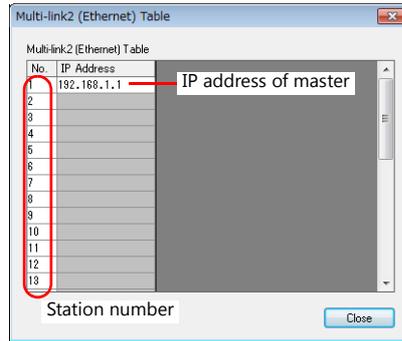
| Item | | Contents |
|------------------------|------------------------------|---|
| Communication Setting | Connection Mode | Multi-link2 (Ethernet) |
| Multi-link2 (Ethernet) | Local Port No. | 1: Master 2 to 32: Slave * Note that if the port number specified is the same as that already set for another V9 unit, the system will not operate correctly. |
| | Send Delay Time | Specify a delay time that elapses before V9 sends the next command after receiving data from the PLC. Normally use the default setting (0).  |
| | Total | 2 to 32 Set the total number of V9 units connected in the multi-link2 (Ethernet) connection. The setting must be the same as other V9 series on the same communication line. |
| | Retry Cycle | Valid only when the local port is “1” (master). Set the number of cycles before the master sends an inquiry for restoration to a slave that has a communication problem (= system down). When a slave has a problem, it is temporarily removed from the communication targets, and the master sends an inquiry for restoration every number of cycles specified for [Retry Cycle]. This setting does not affect the communication speed if no problem is occurring on the slave; however, if there is any problem, it does affect the communication speed. When the setting value is small: Restoration will not take long. When the setting value is large: Restoration will take a longer time. |
| | LAN Port No. | Set a value in the range from 1024 to 65535 (excluding 8001 and 8020). Default: 64000 * Set the same port number for all master and slave stations. |
| | Multi-link2 (Ethernet) Table | Click [Setting] to display the [Multi-link2 (Ethernet) Table] window. For details on settings, refer to the next section. |

Multi-link2 (Ethernet) table

• Master



• Slave



| Item | Contents |
|------------------------------|---|
| Multi-link2 (Ethernet) Table | <ul style="list-style-type: none"> For local port 1 (master) Set the IP addresses of all V9 units used as slave to respective local port numbers. For local port 2 to 32 (slave) Set the IP address of the master V9 for No. 1. |

Wiring

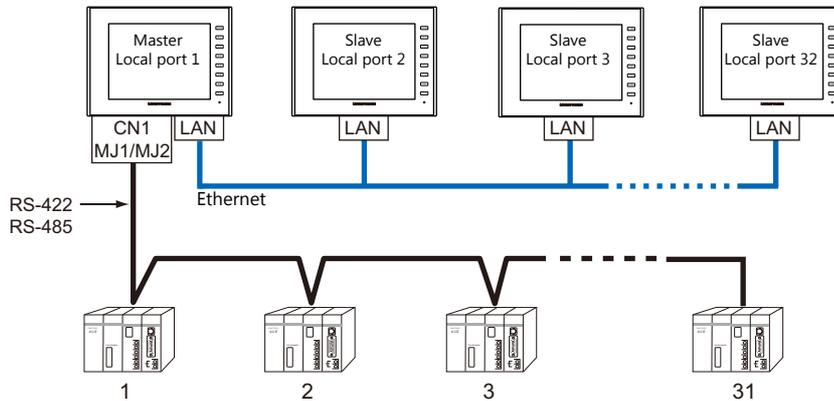
The connection between the master and the PLC is the same as the one for 1 : 1 connection. Refer to " Wiring" (page 1-10) in " 1 : 1 Connection".

Use a LAN cable to connect a master with slaves.

n : n Connection (1: n Multi-link2 (Ethernet)) (Under Development)

Overview

- A maximum of 32 units of V9 series can be connected to a maximum of 31 units of PLCs.
- Multi-link2 (Ethernet) enables you to establish an original network consisting of a master V9 of local port No. 1 and slave V9 units of local port Nos. 2 to 32. The master V9 communicates with the PLC directly, and the slave V9 units communicate with the PLC through the master.



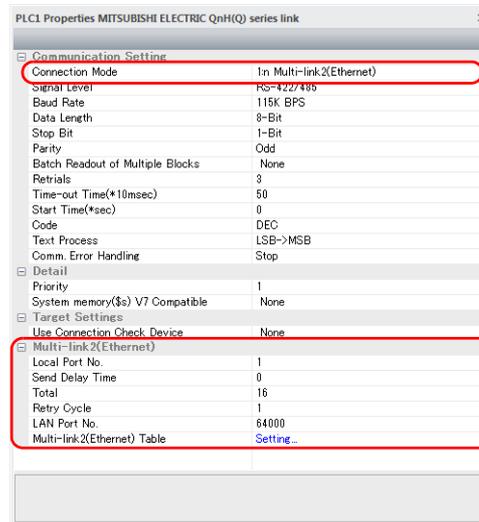
- You can make settings for 1 : n multi-link2 (Ethernet) in [Communication Setting] for PLC1. Therefore, multi-link2 connection is not possible concurrently with a network connection that uses a "CUR-xx" communication interface unit.
- 1 : n multi-link2 (Ethernet) enables sharing of data stored in PLC1 device memory among the V9 units. However, sharing data in PLC2 - PLC8 is not possible.
- The V7 and V6 series cannot be used together.
- The communication speed between the master station and the PLC depends on the setting made on the PLC; however, communication among V9 units is performed via Ethernet, thus, high-speed communication is possible among them.
- For PLCs that support 1 : n multi-link2 (Ethernet) connection, see Connection Compatibility List provided at the end of this manual.
The connection between the master and the PLC is the same as the one for 1 : n connection.
Ethernet connection is adopted to connect a master with slaves.
- If the master station becomes faulty (communication error), the master and slave stations do not work, and as a result, "Communication Error Time-Out" is displayed. If a slave station becomes faulty, "Data Loading..." is displayed due to a communication error only on the faulty station.
- The ladder transfer function is not available for a 1 : n multi-link2 (Ethernet) connection.

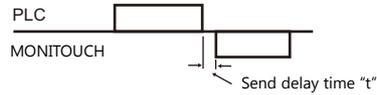
V-SFT Ver. 6 Settings

Make settings on [Hardware Setting] → [PLC Properties]. The differences with respect to a 1 : n connection and the points where care is required are explained here.

For details on other settings, refer to "Hardware Settings" (page 1-14) in "1 : n Connection (Multi-drop)".

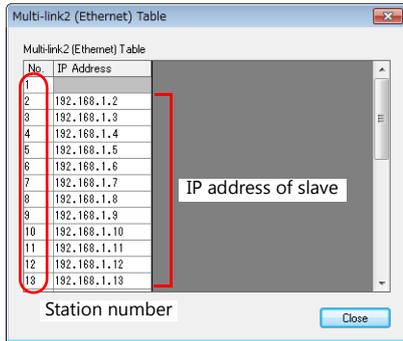
PLC Properties



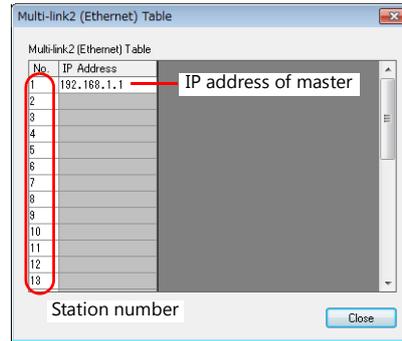
| Item | | Contents |
|------------------------|------------------------------|---|
| Communication Setting | Connection Mode | 1 : n Multi-link2 (Ethernet) |
| Multi-link2 (Ethernet) | Local Port No. | 1: Master 2 to 32: Slave * Note that if the port number specified is the same as that already set for another V9 unit, the system will not operate correctly. |
| | Send Delay Time | Specify a delay time that elapses before V9 sends the next command after receiving data from the PLC. Normally use the default setting (0).  |
| | Total | 2 to 32 Set the total number of V9 units connected in the multi-link2 (Ethernet) connection. The setting must be the same as other V9 series on the same communication line. |
| | Retry Cycle | Valid only when the local port is "1" (master). Set the number of cycles before the master sends an inquiry for restoration to a slave that has a communication problem (= system down). When a slave has a problem, it is temporarily removed from the communication targets, and the master sends an inquiry for restoration every number of cycles specified for [Retry Cycle]. This setting does not affect the communication speed if no problem is occurring on the slave; however, if there is any problem, it does affect the communication speed. When the setting value is small: Restoration will not take long. When the setting value is large: Restoration will take a longer time. |
| | LAN Port No. | Set a value in the range from 1024 to 65535 (excluding 8001 and 8020). Default: 64000 * Set the same port number for all master and slave stations. |
| | Multi-link2 (Ethernet) Table | Click [Setting] to display the [Multi-link2 (Ethernet) Table] window. For details on settings, refer to the next section. |

Multi-link2 (Ethernet) table

• Master



• Slave



| Item | Contents |
|------------------------------|---|
| Multi-link2 (Ethernet) Table | <ul style="list-style-type: none"> For local port 1 (master) Set the IP addresses of all V9 units used as slave to respective local port numbers. For local port 2 to 32 (slave) Set the IP address of the master V9 for No. 1. |

Wiring

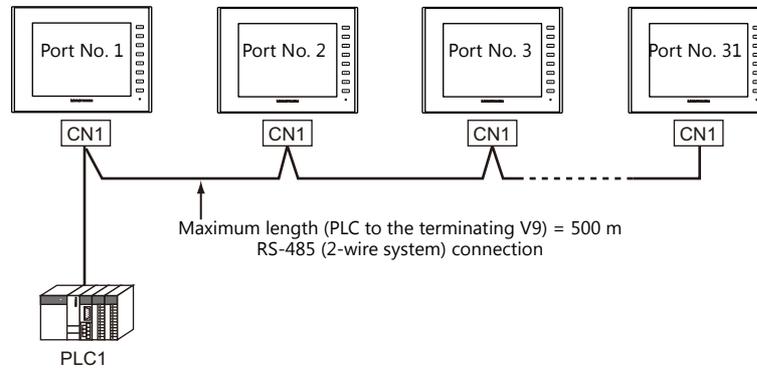
The connection between the master and the PLC is the same as the one for 1 : n connection. Refer to "Wiring" (page 1-15) in "1 : n Connection (Multi-drop)".

Use a LAN cable to connect a master with slaves.

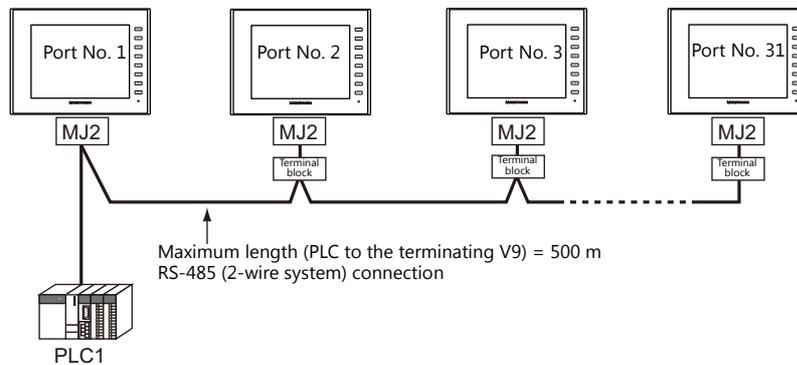
n : 1 Connection (Multi-link) (Under Development)

Overview

- One PLC is connected to a maximum of 31 V9 units. The V8, V7, and V6 series can be used together.
 - Connection example 1:



- Connection example 2:

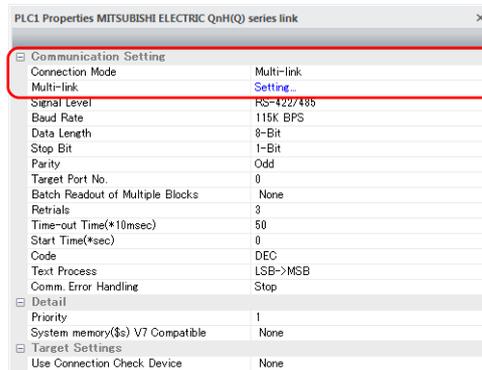


- You can make settings for multi-link at the PLC1. For the V9 and V8 series, a physical port is selectable from CN1, MJ1, and MJ2. For the V7 or V6 series, however, use CN1 only.
- Only a PLC [Signal Level: RS422/RS485] and with a port number set. RS-485 (2-wire system) connection is adopted to connect a V-series unit and a PLC. For available models, see Connection Compatibility List provided at the end of this manual.
- Use twisted-pair cables of 0.3 mm sq. or greater between terminal blocks.
- The ladder transfer function is not available for a multi-link connection.

V-SFT Ver. 6 Settings

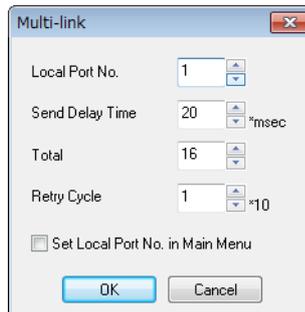
Make settings on [Hardware Setting] → [PLC Properties]. The differences with respect to a 1 : 1 connection and the points where care is required are explained here.
 For details on other settings, refer to Hardware Settings in " 1 : 1 Connection" (page 1-8).

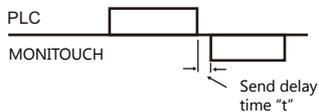
PLC Properties



| Item | | Contents |
|-----------------------|-----------------|--|
| Communication Setting | Connection Mode | Multi-link |
| | Multi-link | Display the [Multi-link] dialog by pressing the [Setting] button, then make the necessary settings in this dialog. For more information on settings, see " Multi-link" (page 1-32). |

Multi-link



| Item | Contents |
|---------------------------------|--|
| Local Port No. | 1 to 32 Specify a port number of the V9. * Note that if the port number specified is the same as that already set for another V9 unit, the system will not operate correctly. |
| Send Delay Time *1 | 0 to 255 msec (Default setting: 20 msec) Specify a delay time that elapses before V9 sends the next command after receiving data from the PLC.  |
| Total *1 | 2 to 32 Set the maximum number of V series units to be connected in multi-link connection. *2 |
| Retry Cycle *1 | 1 to 100 (× 10) When the V9 series has a problem, it is temporarily removed from the communication targets, and the master sends an inquiry for restoration every number of cycles specified for [Retry Cycle]. This setting does not affect the communication speed if no problem is occurring; however, if there is any problem, it does affect the communication speed. When the setting value is small: Restoration will not take long. When the setting value is large: Restoration will take a longer time. |
| Set Local Port No. in Main Menu | <ul style="list-style-type: none"> • Unchecked Set the local port number on the screen program. • Checked Set the local port number on MONITOUCH (see page 1-33). |

*1 For [Send Delay Time], [Total] and [Retry Cycle], the same values must be set on all the V9 series that are connected in the same communication line.

*2 When connecting three units with the local port numbers 1, 2 and 10, specify "10" for [Total].

MONITOUCH Setting

Local port setting (Local mode)

When [Set Local Port No. in Main Menu] is checked in the [Multi-link] window, the local port number must be set in Local mode on the V9 series.

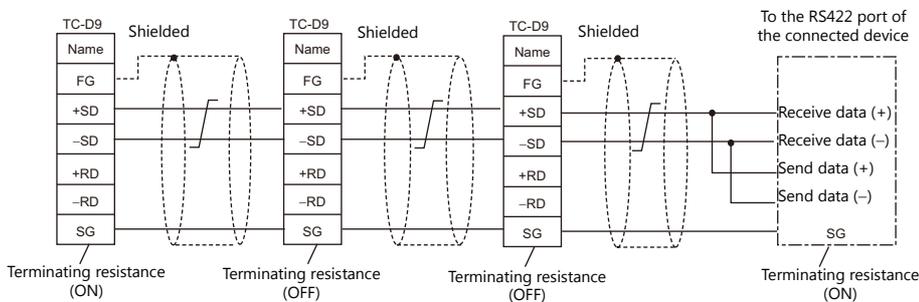
1. Transfer the screen program.
2. Switch to Local mode on MONITOUCH.
3. Press the [Communication Setting] switch and display the Communication Setting screen.
4. Set the [Local Port No] on the [Individual Parameter] tab window.
5. Press the [Apply] switch.

Wiring

When Connected at CN1

This shows the situation when a multi-link connection is made at CN1. It is convenient to use the Hakko Electronics' optional terminal converter "TC-D9".

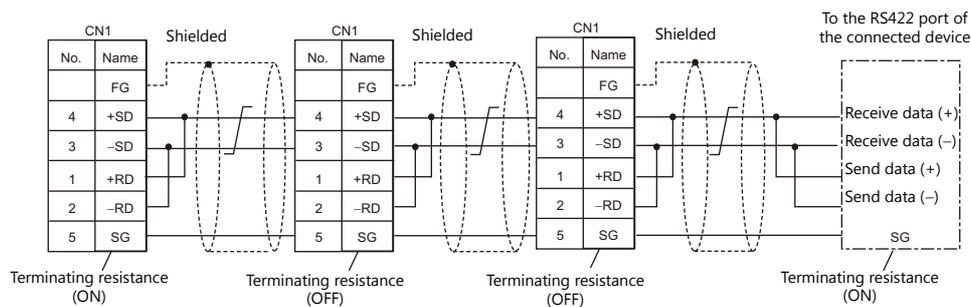
- When a TC-D9 is used:
Set the slide switch of "TC-D9" to ON (2-wire system).



* Use shielded twist-pair cables.

* Jumpers may not be necessary, depending on the connected device.

- When no TC-D9 is used:
Install jumpers between +SD and +RD as well as -SD and -RD.



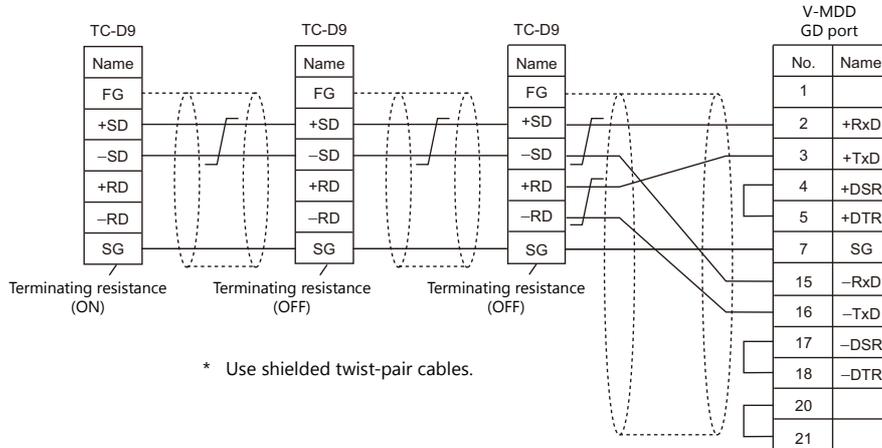
* Use shielded twist-pair cables.

* Jumpers may not be necessary, depending on the connected device.

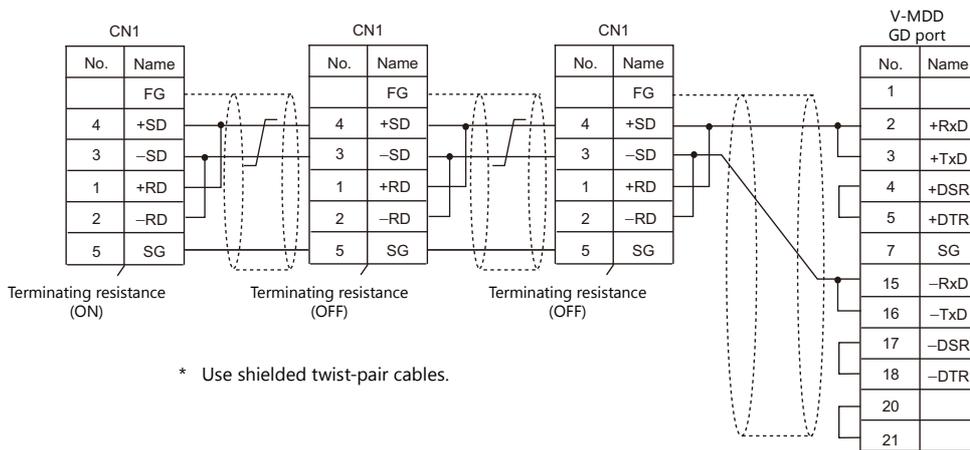
When connecting to Mitsubishi Electric's QnA CPU:

Use the GD port of Hako Electronics' optional dual port interface V-MDD for the PLC CPU port.

- When a TC-D9 is used:
Set the slide switch of "TC-D9" to ON (2-wire system).

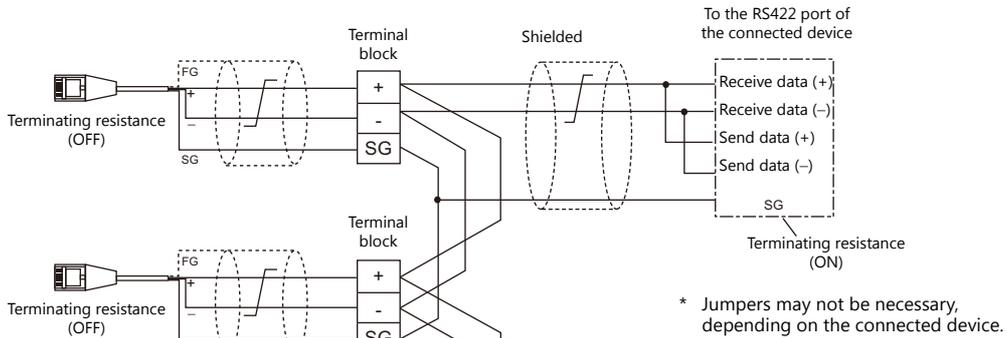


- When no TC-D9 is used:
Install jumpers between +SD and +RD as well as -SD and -RD.



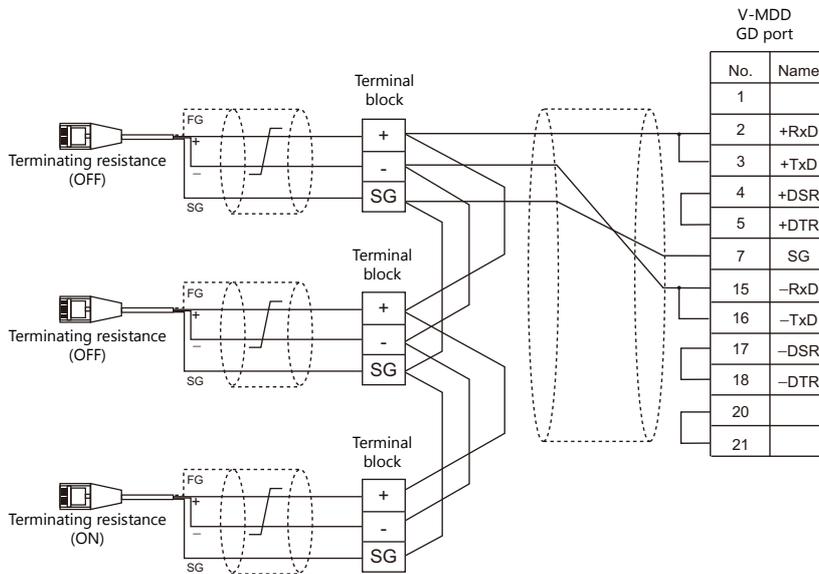
When Connected at MJ1/MJ2:

This shows the situation when a multi-link connection is made at MJ1 or MJ2.



When connecting to Mitsubishi Electric's QnA CPU:

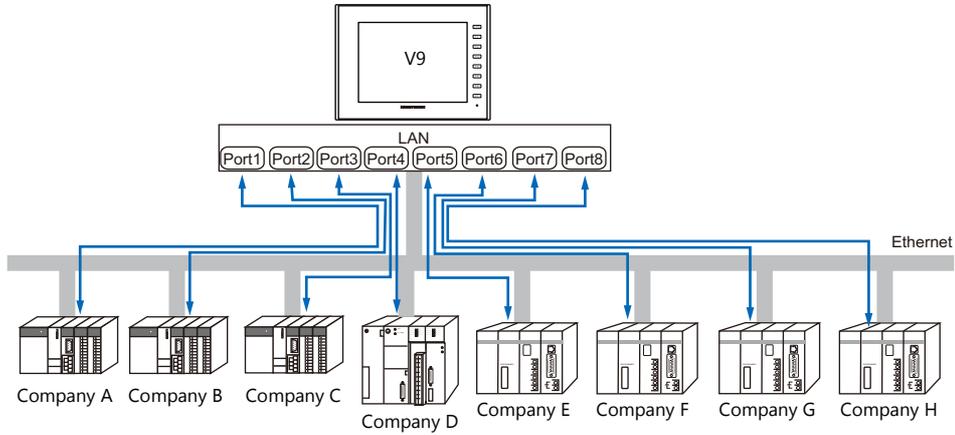
Use the GD port of Hako Electronics' optional dual port interface V-MDD for the PLC CPU port.



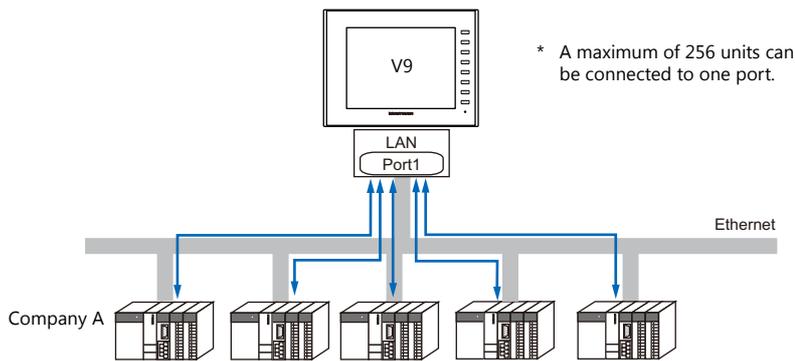
1.3.2 Ethernet Communication

Overview

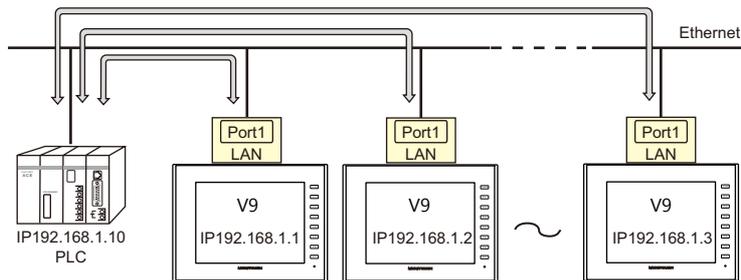
- Because eight communication ports can be opened, the V9 series is allowed to communicate with eight models of PLCs at the same time.



- When there are two or more PLCs of the same model, the V9 series is allowed to carry out 1 : n communication via one single port.



- If multiple V9 units are connected to one single PLC, the maximum permissible number of these units depends on the PLC specifications. Refer to the PLC manual issued by the manufacturer.



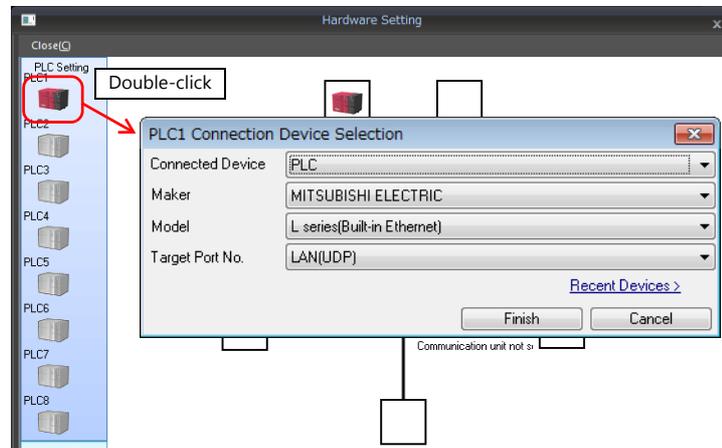
- You can make settings for Ethernet communication in [Communication Setting] for the logical ports PLC1 - PLC8.

V-SFT Ver. 6 Settings

Hardware Settings

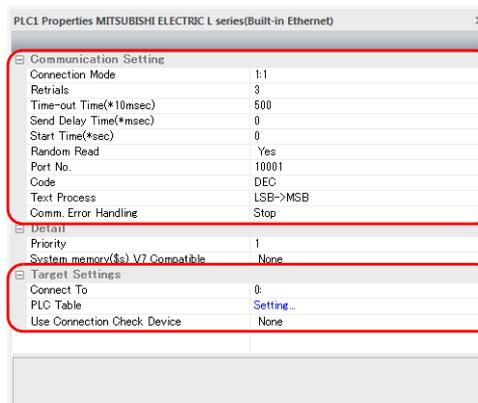
Selecting a device to be connected

Select the device for connection from [System Setting] → [Hardware Setting].

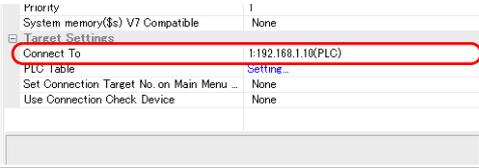
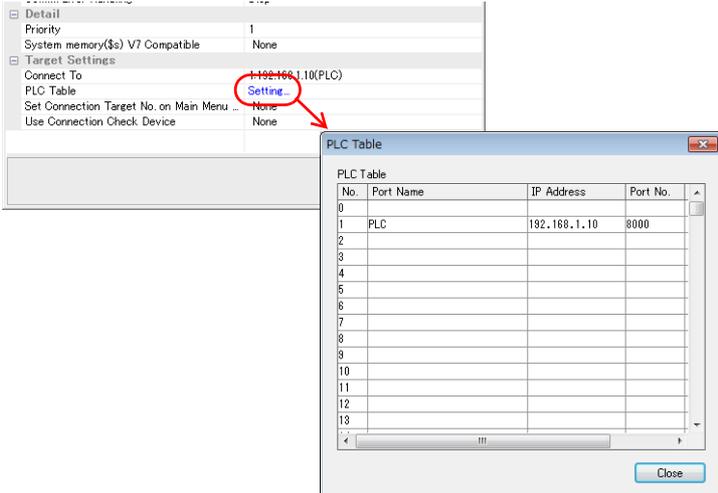


PLC properties

Configure the [PLC Properties].



| Item | | Contents |
|-----------------------|-------------------------------|---|
| Communication Setting | Connection Mode | 1:1/1:n Set the number of PLCs that are to be communicated with. |
| | Port No. | Set the port number of the V9 series to be used for communications with the PLCs. |
| | KeepAlive (Under development) | <p>This setting is used when using the "KeepAlive" function. The "KeepAlive" function is used for periodically checking the connection with devices on the network. This function enables a prompt detection of a communication error, thus, significantly shortens the time to wait until a "disconnect" process takes place after an occurrence of the time-out error.</p> <p>* When using this function, select [Disconnect] for [Comm. Error Handling].</p> <ul style="list-style-type: none"> [Use KeepAlive] Select [Yes] when using the "KeepAlive" function. The following settings will take effect. <ul style="list-style-type: none"> [Retrials] Specify the number of retries. If a timeout persists even after as many retries as specified, an error handling routine will take place. 0 to 255 Default: 0 [Time-out Time] Specify a period of time allowed for V9 to monitor a response from its connected device. If no response is given within the specified time, retry will be made. 1 to 999 (× 10 msec) Default: 30 (× 10 msec) [Checking Cycle] Set the cycle time of "KeepAlive" communication. 1 to 999 (× 10 msec) Default: 10 (× 10 msec) |

| Item | Contents |
|-----------------|--|
| Target Settings | <p>These settings are valid when [1 : 1] is selected for [Connection Mode]. Select the IP address of the PLC registered in the PLC table. 1 : 1 communications are executed with the PLC selected here.</p>  |
| | <p>Click [Setting] to display the [PLC Table] window. Set the IP address, port number and KeepAlive function (under development) of the PLC.</p>  |

* For settings other than the above, see "1.4 Hardware Settings" (page 1-43).

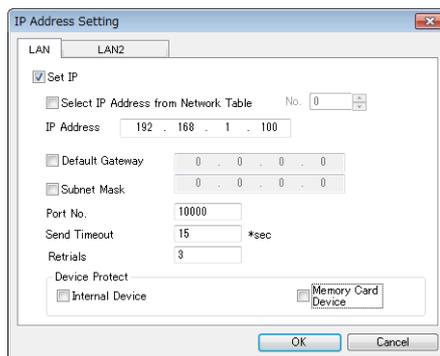
IP Address Setting of the V9 Series

An IP address must be set for the V9 to connect to devices via Ethernet. Set the IP address either on the V9 unit or for the screen program using the V-SFT editor.

Setting Using the V-SFT Editor

Set the IP address at [System Setting] → [Hardware Setting] → [Local Port IP Address].

Local port IP address setting



| Item | Contents |
|--------------------------------------|--|
| Select IP Address from Network Table | This is valid when the IP address of the V9 has been registered in the network table. Select a network table number from 0 to 255 to set the IP address. * For more information on the network table, refer to "Network table" (page 1-50). |
| IP Address *1 | Set the IP address for the V9. |
| Default Gateway *1 | Set the default gateway. |
| Subnet Mask *1 | Set the subnet mask. When this box is not checked, the subnet mask is automatically assigned based on the byte at the extreme left of the IP address. Example: When IP address is "172.16.200.185", "255.255.0.0" is set. When IP address is "192.168.1.185", "255.255.255.0" is set. |
| Port No. *1 | Set a port number from 1024 to 65535. (Excluding 8001 and 8020) |

| Item | Contents |
|---|---|
| Send Timeout | Specify the timeout time to send the EREAD/EWRITE/SEND/MES command. |
| Retrials | 0 to 255 Set the number of retrials to be performed when a time-out occurs. |
| Device Protect Internal Device Memory Card Device | Check either check box to write-protect the device memory from computers or other stations. |

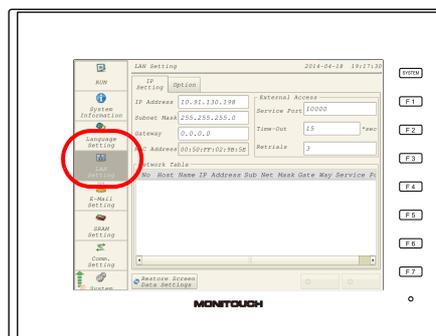
*1 For more information on each setting item, see "Basics of ethernet settings" (page 1-51).

Settings in Local Mode on the V9 Unit

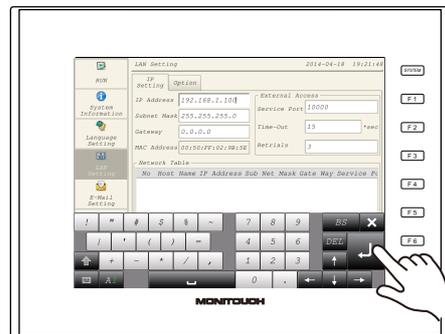
Set the IP address in Local mode on the V9 unit.

If IP address setting has been performed on the V-SFT editor, this setting will be taken as the valid one.

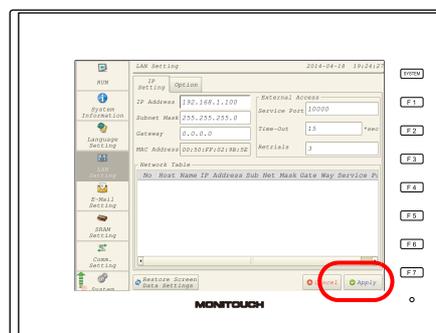
1. Press the [SYSTEM] switch on MONITOUCH to display the system menu.
2. Press the [Local] switch. The display switches to Local mode.
3. Press the [LAN Setting] switch and display the LAN Setting screen.



4. Set each item.



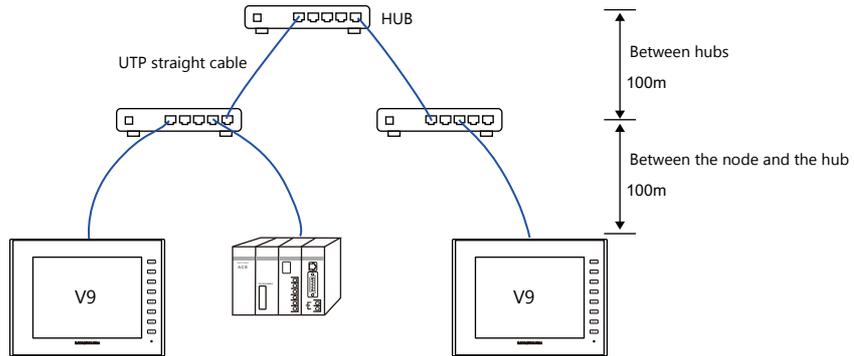
5. Press the [Apply] switch to determine the setting.



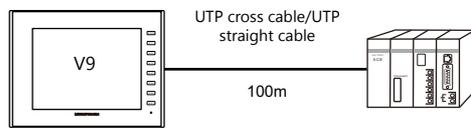
* Press the [Return to Screen Data Setting] to return to the settings made on the V-SFT editor.

Connection Example

With hub



Without hub

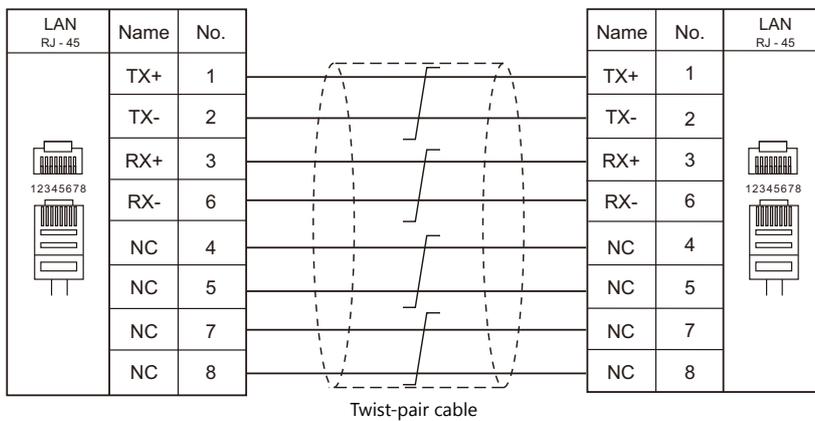


Wiring

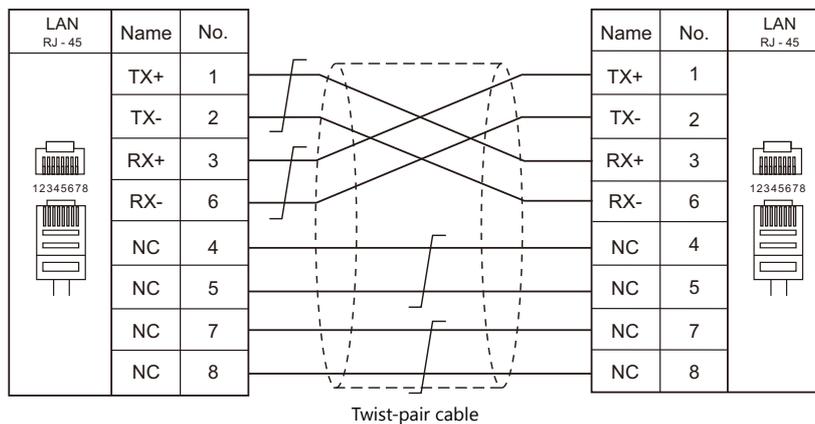
CAUTION

- Use a commercially available cable. Using a self-made cable may cause an error in network connection.
- If the use of a cross cable cannot stabilize communication, use a hub.

- Straight cable



- Cross cable



1.3.3 Network Communication (Under Development)

Overview

- The optional communication interface unit "CUR-xx" is required to enable a network communication listed below.

| Communication Interface Unit | Network | Available Models | | Remarks |
|------------------------------|-----------------|---|--|-------------------|
| CUR-00 | OPCN-1 | Mitsubishi Electric OMRON Fuji Electric | A series (OPCN-1) SYSMAC C (OPCN-1) MICREX-SX (OPCN-1) | Under development |
| CUR-01 | T-Link | Fuji Electric Fuji Electric | MICREX-F (T-LINK) MICREX SX (T-LINK) | Under development |
| CUR-02 | CC-LINK Ver.2.0 | Mitsubishi Electric Mitsubishi Electric Mitsubishi Electric | A series (CC-LINK) QnA series (CC-LINK) QnH (Q) series (CC-LINK) | Under development |
| CUR-03 | Ethernet *1 | Various PLCs | Ethernet UDP/IP communication | Under development |
| CUR-04 | PROFIBUS-DP | Siemens Universal | S7 PROFIBUS-DP PROFIBUS-DP | Under development |
| CUR-06 | SX BUS | Fuji Electric | MICREX-SX (SX BUS) | Under development |
| CUR-07 | DeviceNet | | - | Under development |
| CUR-08 | FL-Net | Universal | FL-Net | Under development |

*1 In addition to UDP/IP communication with a PLC, screen program transfer, the MES interface function, and TELLUS & V-Server connection can be enabled by connecting a PC. Use the built-in LAN port for TCP/IP communication.

- You can make settings for network communication in [Communication Setting] for the logical port PLC1. Thus, devices available with only PLC1, as those used for multi-link or multi-link2, cannot be connected concurrently for network communication.

V-SFT Ver. 6 Settings

For more information, refer to the communication unit specifications provided for each network.

Wiring

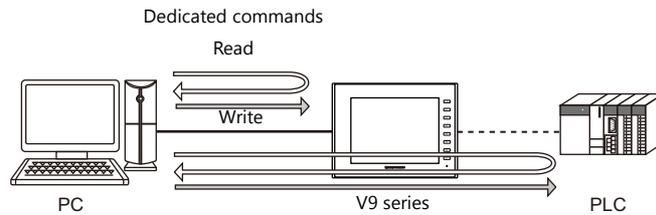
For more information, refer to the communication unit specifications provided for each network.

1.3.4 Slave Communication

Connecting via V-Link, Modbus RTU, or Modbus TCP/IP is applicable to slave communication using the V9. V-Link and Modbus RTU are used for serial communication, and Modbus TCP/IP is used for Ethernet (TCP/IP) communication.

V-Link

- "V-Link" is the network where the PC reads from and writes to the internal device memory of the V9 series, memory card device memory, or PLC1 to 8 device memory using a dedicated protocol.



- You can make settings for V-Link communication in [Communication Setting] for the logical ports PLC2 - PLC8. A communication port is selectable from CN1, MJ1, and MJ2.
- For more information, refer to "V-Link" in book 3 of the V9 Series Connection Manual.

MODBUS RTU

- The V9 series is connected to a Modbus RTU master via serial connection.
- The device memory table for Modbus slave communication is prepared for the V9. The master is allowed to gain access to the device memory table and read/write the PLC data.
- For more information, refer to the Modbus Slave Communication Specifications manual separately provided.

MODBUS TCP/IP

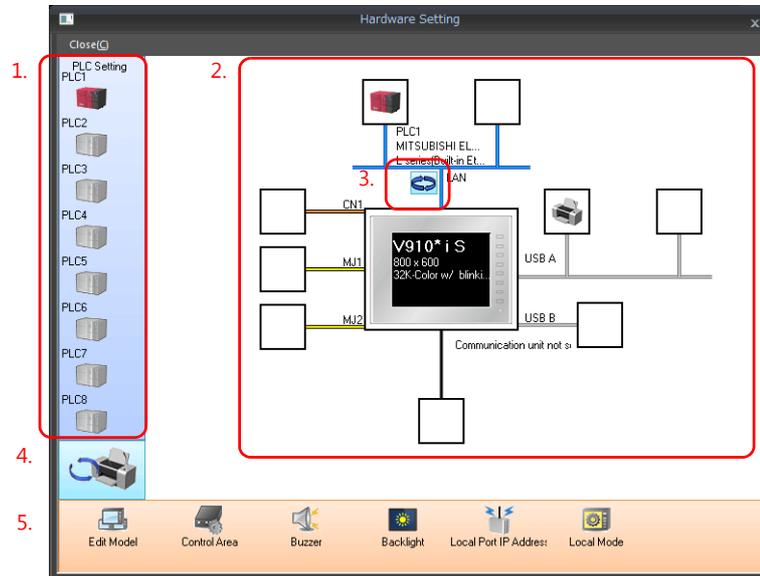
- The V9 is connected to a Modbus TCP/IP master via Ethernet communication.
- The device memory table for Modbus slave communication is prepared for the V9. The master is allowed to gain access to the device memory table and read/write the PLC data.
- For more information, refer to the Modbus Slave Communication Specifications manual separately provided.

1.3.5 Other Connections

For connection to a serial printer that is not in 8-way communication, serial ports of MJ1 and MJ2 are used.

1.4 Hardware Settings

Select and set the devices to connect to the V9 series on the Hardware Setting screen.

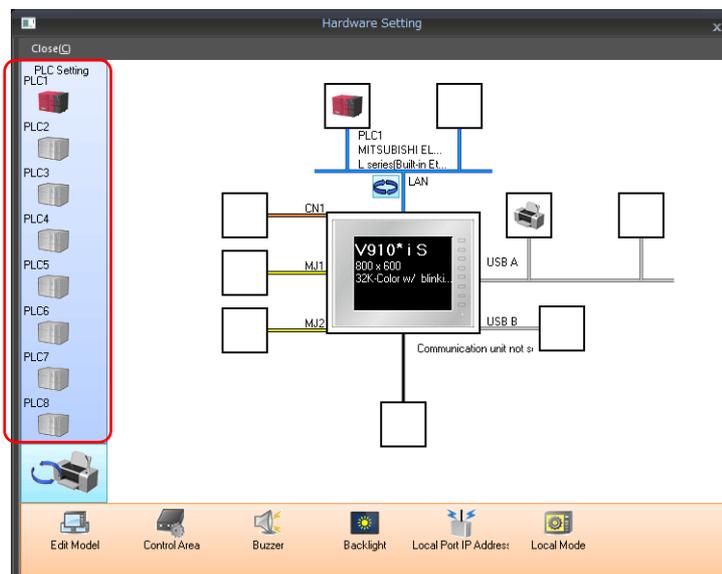


| | Item | Contents |
|----|-------------------------------------|--|
| 1. | PLC Setting | Set the devices (PLC, temperature controller, servo, inverter, barcode reader etc.) to connect to PLC1 to PLC8. |
| 2. | Connection Diagram | The devices which are set for connection are displayed. Devices as well as communication settings can be changed. |
| 3. | Built-in LAN / Ethernet unit switch | Select the Ethernet connection port on the V9 series from the internal LAN communication unit. The icon changes each time it is clicked. |
| 4. | PLC Setting / Other Setting switch | Switch between PLC settings and other settings. The icon changes each time it is clicked. |
| 5. | MONITOUCH Settings | Make MONITOUCH settings on the V9 series. |

1.4.1 PLC Settings

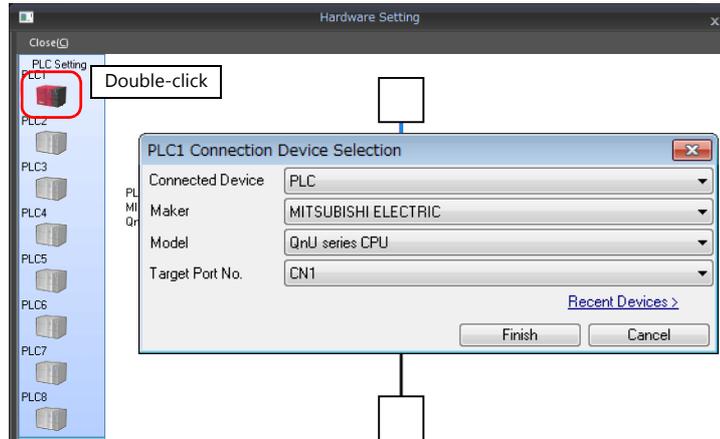
To enable communication with a PLC, a temperature controller, an inverter, etc., the following settings are required to be set on the editor. You can see the contents of these settings in the V9 Local mode.

For information on Local mode, refer to the V9 Series Troubleshooting/Maintenance Manual.



Selecting a Device to be Connected

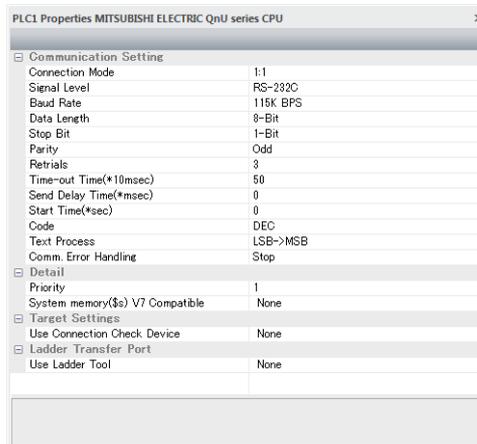
Double-click on a PLC icon in the [Hardware Setting] window to display the window shown below.



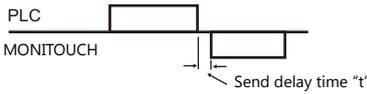
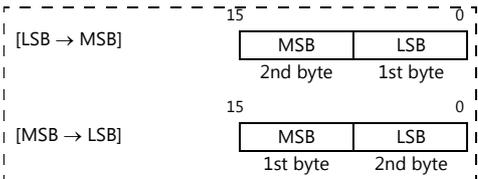
| Item | Contents |
|------------------|--|
| Connected Device | Select the device to connect. |
| Maker | Select the maker of the device. |
| Model | Select the model of the device to connect. Refer to the respective chapter of each maker and select the appropriate model. |
| Target Port No. | Select the port to which the device connects to on the V9 series. |

PLC Properties

Click on the PLC icon in [Hardware Setting] to display the window shown below.



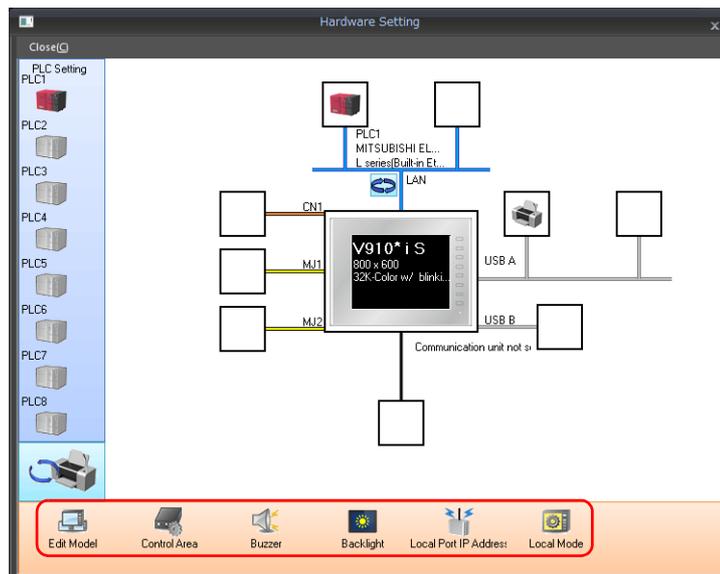
| Item | Contents | |
|-----------------------|-------------------------------|---|
| Communication Setting | Connection Mode | Select a connection mode. 1 : 1 / 1 : n / Multi-link / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet) Available options vary, depending on which device is connected. For details, see Connection Compatibility List provided at the end of this manual. |
| | Signal Level ^{*1} | Select a signal level. RS-232C/RS-422/485 |
| | Baud Rate ^{*1} | Select a baud rate. 4800/9600/19200/38400/57600/76800/115K/187.5K ¹ bps [*] Available only when connecting via Siemens S7-200PPI or S7-300/400MPI and CN1. |
| | Data Length ^{*1} | Select a data length. 7 / 8 bits |
| | Stop Bit ^{*1} | Select a stop bit. 1 / 2 bits |
| | Parity ^{*1} | Select an option for parity bit. None / Odd / Even |
| | Target Port No. ^{*1} | Specify a port number of the connected device. 0 to 31 (Modbus RTU: 1 to 255) |

| Item | | Contents | |
|--|---------------------------------|--|---|
| Communication Setting | Transmission Mode ^{*1} | Select a transmission mode for the connected device. This setting is required if a device of Mitsubishi, Omron, Hitachi Industrial Equipment Systems, Yokogawa, JTEKT, or Yaskawa is in use. | |
| | Retrials | Specify the number of retrials to be allowed in the event of a timeout during communication. If a timeout persists even after as many retrials as specified, an error handling routine will take place. 1 to 255 | |
| | Time-out Time | Specify a period of time allowed for V9 to monitor a response from its connected device. If no response is given within the specified time, retrial will be made. 0 to 999 (×10 msec) | |
| | Send Delay Time | Specify a delay time that elapses before V9 sends the next command after receiving a response from its connected device. Normally use the default setting. 0 to 255 (×1 msec)  | |
| | Start Time | Specify a delay time that elapses before V9 starts to send commands upon power-up. If V9 and its connected device are turned on at the same time and the device is slower to start up, set [Start Time]. 0 to 255 (×1 sec) | |
| | Code | Select a code for the connected device. The selected option is reflected through the data displayed on graphs or trending sampling parts. DEC/BCD | |
| | Text Process | Specify a byte order in text data. This setting is valid for macro commands that handle text. LSB → MSB/MSB → LSB  | |
| | Comm. Error Handling | Select an action to be taken in the event of a communication error. <ul style="list-style-type: none"> • [Stop] Communication will be stopped entirely and the communication error screen will be displayed. The [RETRY] switch is available for attempting reestablishment of communication. • [Continue] The communication error message will be displayed at the center of the screen. The same communication will continue until restoration, and screen operation is not allowed then. When communication has been returned to a normal state, the message disappears and screen operation is allowed. • [Disconnect] No error message will appear and communication will proceed to the next one. However, communication with the device, in which a timeout was detected, will be disconnected. When a timeout is detected, ⚠ will be displayed for the part that is monitoring the address of the timeout device. <p>* The communication status is displayed on the status bar. For information, refer to the V9 Series Troubleshooting/Maintenance Manual.</p> | |
| | Recovery Condition | Use Recovery Time | This setting is valid when [Disconnect] is selected for [Comm. Error Handling]. |
| | | Recovery Time | Return Time 1 to 255 (×10 sec) When the specified time has elapsed, V9 checks the recovery of the device which discontinued communicating. |
| Auto-restoration upon screen switch-over | | When the screen is switched, V9 checks the recovery of the device which discontinued communicating. | |

| Item | | Contents |
|------------------------------------|---|--|
| Detail | Priority | [1] (higher priority) - [8] (lower priority) Specify the priority taken during 8-way communication. If interrupts from two or more devices occur at the same time, communication with these devices will take place in order of priority. |
| | System device (\$) V7 Compatible (PLC1) | This is set to [Yes] if the V7-series screen program (including temperature control network/PLC2Way settings) has been converted to data for the V9 series. System information relevant to 8-way communication will be stored in device memory addresses \$P1 and \$s. * For more information, see "1.5.1 \$Pn (For 8-way Communication)" (page 1-55). |
| | System device (\$) V7 Compatible (PLC2) | This is set to [Yes] if the V7-series screen program (including temperature control network/PLC2Way settings) has been converted to data for the V9 series. <ul style="list-style-type: none"> [None] \$P2:493/494/495 is used as the transfer table control device memory. [Yes] \$s762/763/764 is used as the transfer table control device memory. * For more information, see "1.5.1 \$Pn (For 8-way Communication)" (page 1-55). |
| | Device Memory Map Control Device | Specify the device memory for controlling device memory maps of PLC1 - PLC8. The device memory specified here is the same as [Control Device] in [Device Memory Map Setting] ([System Setting] → [Device Memory Map] → [Device Memory Map Edit] window → [Device Memory Map Setting]). * For more information, refer to the V9 Series Reference Manual. |
| Target Settings | Connect To PLC Table | Set this for Ethernet communication. For more information, see "1.3.2 Ethernet Communication" (page 1-36). |
| | Use Connection Check Device | |
| | Connection Check Device | Specify a desired device memory address used for connection confirmation. |
| | Ladder Transfer Port | Use Ladder Tool |
| Connection target | | |
| Ladder Communication in Local Mode | | |

*1 Be sure to match the settings to those made on the connected device.

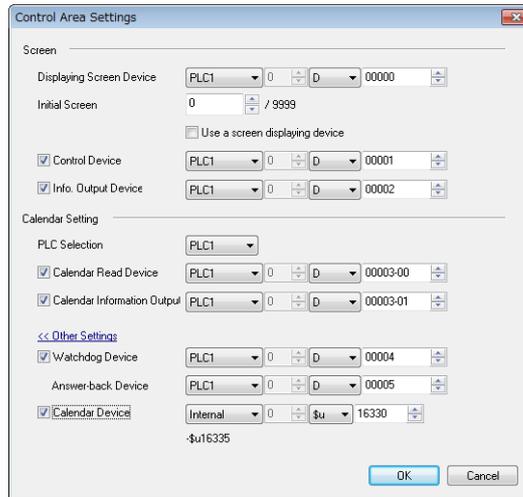
1.4.2 MONITOUCH Settings



Select Edit Model

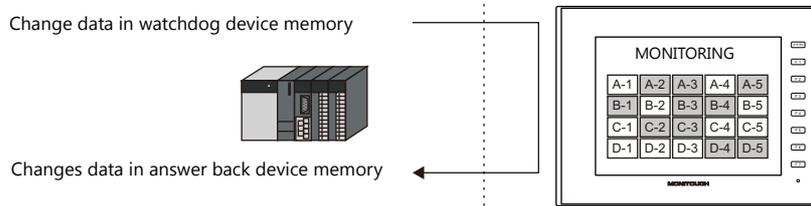
Set the model of the V series to edit.
For more information, refer to the V9 Series Reference Manual.

Control Area

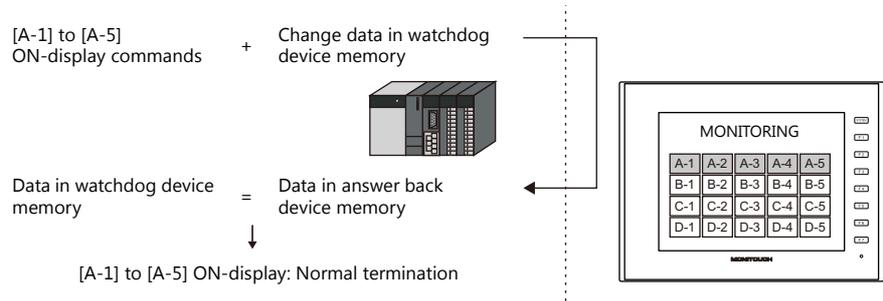


| Item | | Contents |
|------------------|---------------------------------------|--|
| Screen | Displaying Screen Device | This device memory is used for switching the screen by an external command. When a screen number is specified in a device memory, the screen is displayed. When the screen is switched by an internal switch, the currently displayed screen number is stored in this device memory. |
| | Initial Screen | Set the number of the screen to be displayed at start up. * When recovering from a communication error, the screen number which was set for the screen displaying device memory is displayed. |
| | Use a screen displaying device | When this is checked, the screen number which was set for the screen displaying device memory is displayed as the initial screen. |
| | Control Device Info. Output Device | For more information, refer to the V9 Series Reference Manual. |
| Calendar Setting | PLC Selection | This setting is valid when the V9 s built-in clock is not used. The setting allows the calendar data to be read from device memory via the selected port at PLC1 - PLC8. |
| | Calendar Read Device | This setting is valid when the V9 s built-in clock is not used. This bit should be used differently depending on whether the connected PLC is equipped with the calendar function. <ul style="list-style-type: none"> When MONITOUCH is connected to a PLC with calendar function: When calendar data in the PLC is updated, it can forcibly be read by setting this bit (at the leading edge of [0 → 1]). In addition to calendar data update using this bit, calendar data in the PLC is automatically read and updated when: <ul style="list-style-type: none"> The power is turned on. STOP → RUN The date changes (AM 00:00:00). When MONITOUCH is connected to a PLC without calendar function: A virtual calendar area can be provided by setting [Calendar Device] in [Other Settings]. Setting this bit (ON) will set the data stored in the calendar device memory as calendar data for MONITOUCH. |
| | Calendar Information Output Device | The status of the calendar read device memory is stored. |
| Other Settings | Watchdog Device | When data is saved in this area, the same data is written to [Answer-back Device] after the screen has been displayed. |
| | Answer-back Device | |
| | Calendar Device | Use this device memory when the connected device is not equipped with the calendar function and the V9 series built-in clock is not used. |

*1 Watchdog
When the PLC is communicating with MONITOUCH, there is no means for the PLC to know whether or not MONITOUCH is doing operations correctly. To solve this one-way communication, forcibly change data in the watchdog device memory and check that the same data is saved in the answer back device memory. This proves that the V series is correctly doing operations through communications with the PLC. This verification is called "watchdog".



- *2 Display scanning
This operation can be utilized for display scanning. Forcibly change data in the watchdog device memory when giving a graphic change command and check that the same data is saved in the answer back device memory. This can prove that the graphic change command is received and executed correctly.



Calendar device memory

Follow the steps below to set the calendar.

1. Specify the desired device memory address for [Calendar Device]. Six words are occupied consecutively.
2. Save calendar data in the calendar device memory address specified in step 1 in BCD notation. The address allocation of calendar device memory is shown below.

| Device Memory | Contents |
|---------------|-------------------------|
| n | Year (BCD 0 to 99) |
| n + 1 | Month (BCD 1 to 12) |
| n + 2 | Day (BCD 1 to 31) |
| n + 3 | Hour (BCD 0 to 23) |
| n + 4 | Minute(s) (BCD 0 to 59) |
| n + 5 | Second(s) (BCD 0 to 59) |

The day of the week is automatically recognized from the above data. It is not necessary to input any data.

3. Set the calendar read device memory to ON. At the leading edge of this bit (0 → 1), data in the calendar device memory is set for calendar data on MONITOUCH.
 - *1 Calendar data is cleared when the power is turned off. When the power is turned on, set calendar data according to the procedure mentioned above.
 - *2 When using the calendar device memory, automatic reading of calendar data at the time of PLC connection as well as once-a-day automatic correction is not performed. Consequently, some errors may be introduced. Perform the procedure described above at regular intervals.

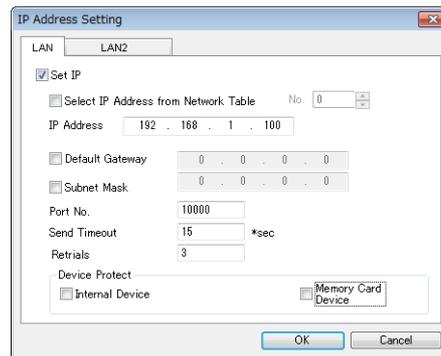
Buzzer

Make settings for the buzzer.
For more information, refer to the V9 Series Reference Manual.

Backlight

Make settings for the backlight.
For more information, refer to the V9 Series Reference Manual.

Local IP Address



| Item | Contents |
|---|---|
| Select IP Address from Network Table | This is valid when the IP address of the V9 has been registered in the network table. Select a network table number from 0 to 255 to set the IP address. * For more information on the network table, refer to "Network table" (page 1-50). |
| IP Address ^{*1} | Set the IP address for the V9. |
| Default Gateway ^{*1} | Set the default gateway. |
| Subnet Mask ^{*1} | Set the subnet mask. When this box is not checked, the subnet mask is automatically assigned based on the byte at the extreme left of the IP address. Example: When IP address is "172.16.200.185", "255.255.0.0" is set. When IP address is "192.168.1.185", "255.255.255.0" is set. |
| Port No. ^{*1} | Set a port number from 1024 to 65535. Other than 8001. |
| Send Timeout | Specify the timeout time to send the EREAD/EWRITE/SEND/MES command. |
| Retrials | 0 to 255 Set the number of retrials to be performed when a time-out occurs. |
| Device Protect Internal Device Memory Card Device | Check either check box to write-protect the device memory from computers or other stations. |

^{*1} For more information on each setting item, see "Basics of ethernet settings" (page 1-51).

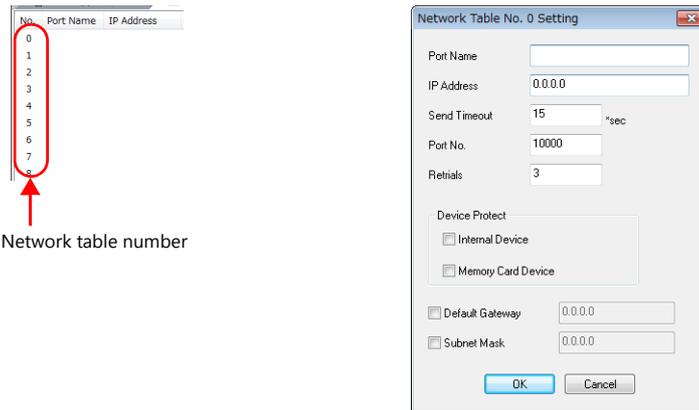
Network table

This is an area for registering IP addresses of the MONITOUCH, PC and other devices.

Select [System Setting] → [Ethernet Communication] → [Network Table] and register.



Double-click a number in the No. column to display the [Network Table Setting] dialog. An IP address and other items can be registered.



| Item | Contents |
|---|---|
| Port Name | Set the name of the V9 or the computer. |
| IP Address ^{*1} | Set the IP address of the V9 or the computer. |
| Send Timeout ^{*2} | Specify the timeout time to send the EREAD/EWRITE/SEND/MES command. |
| Port No. ^{*1} | Set the port number of the V9 or the computer. |
| Retrials ^{*2} | 0 to 255 Set the number of retrials to be performed when a time-out occurs. |
| Device Protect ^{*2} Internal Device Memory Card Device | Check either check box to write-protect the device memory from computers or other stations. |
| Default Gateway ^{*1 *2} | Set the default gateway. |
| Subnet Mask ^{*1 *2} | Set the subnet mask. |

^{*1} For more information on each setting item, see "Basics of ethernet settings" (page 1-51).

^{*2} Invalid if V9 units or PCs at other ports are registered. Only valid when set as the local port IP of the V9 unit.

Basics of ethernet settings

| IP address | | | | |
|--|---|-------------------|----------------------|-------------------|
| This is an address that is used for recognizing each node on the Ethernet and should be unique. The IP address is 32-bit data which consists of the network address and the host address and can be classified into classes A to C depending on the network size. | | | | |
| Class A | <table border="1"> <tr> <td>0</td> <td>Network address (7)</td> <td>Host address (24)</td> </tr> </table> | 0 | Network address (7) | Host address (24) |
| 0 | Network address (7) | Host address (24) | | |
| Class B | <table border="1"> <tr> <td>10</td> <td>Network address (14)</td> <td>Host address (16)</td> </tr> </table> | 10 | Network address (14) | Host address (16) |
| 10 | Network address (14) | Host address (16) | | |
| Class C | <table border="1"> <tr> <td>110</td> <td>Network address (14)</td> <td>Host address (8)</td> </tr> </table> | 110 | Network address (14) | Host address (8) |
| 110 | Network address (14) | Host address (8) | | |
| <p><Notation> A string of 32-bit data is divided into four, and each segment delimited with a period is in decimal notation. Example: The IP address in class C shown below is represented as "192.128.1.50". 11000000 10000000 00000001 00110010</p> <p><Unusable IP addresses></p> <ul style="list-style-type: none"> • "0" is specified for one byte at the extreme left. Example: 0.x.x.x • "127" is specified for one byte at the extreme left (loop back address). Example: 127.x.x.x • "224" or more is specified for one byte at the extreme left (for multi-cast or experiment). Example: 224.x.x.x • The host address consists of only "0" or "255" (broadcast address). Example: 128.0.255.255, 192.168.1.0 | | | | |

| Port No. |
|---|
| Multiple applications are running on each node, and communications are carried out for each application between the nodes. Consequently, it is necessary to have a means to identify the application that data should be transferred to. The port number works as this identifier. Each port number is 16-bit data (from 0 to 65535). The V9 series uses the port for screen program transfer (8001), PLC communication (as desired), and the simulator (8020). Set a unique number in the range of 1024 to 65535. For a PLC or a computer, set the port number in the range of 256 to 65535. It is recommended to set a greater number. |

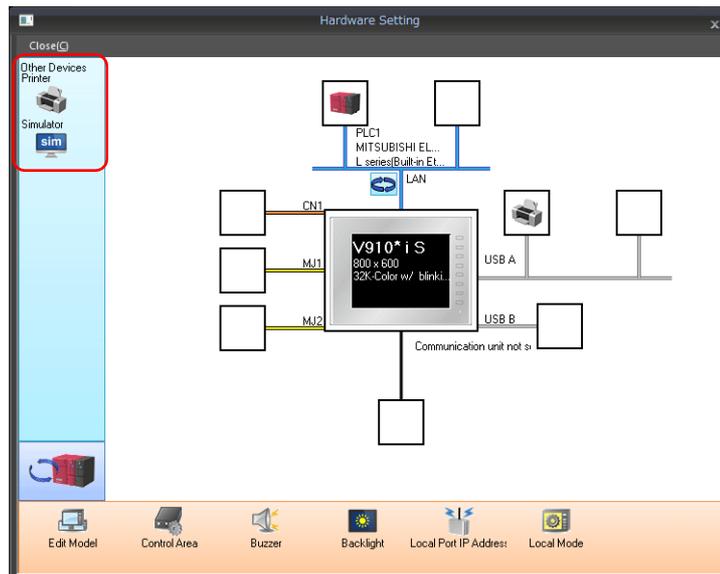
| Default gateway |
|--|
| A gateway and a router are used for communication between different networks. The IP address of the gateway (router) should be set to communicate with the node(s) on other networks. |

| Subnet mask | | | | | | | | | | | | | | | | | | | |
|---|-----------------|----------------------|----------------------|-------------------|-------------|-----|-----|-----|---|--|----------|----------|----------|----------|--|-----------------|----------------|--------------|--|
| A subnet mask is used for dividing one network address into multiple networks (subnet). The subnet is assigned by specifying a part of the host address in the IP address as a subnet address. | | | | | | | | | | | | | | | | | | | |
| <table border="1"> <tr> <td>Class B</td> <td>10</td> <td>Network address (14)</td> <td>Host address (16)</td> </tr> <tr> <td>Subnet mask</td> <td>255</td> <td>255</td> <td>255</td> <td>0</td> </tr> <tr> <td></td> <td>11111111</td> <td>11111111</td> <td>11111111</td> <td>00000000</td> </tr> <tr> <td></td> <td>Network address</td> <td>Subnet address</td> <td>Host address</td> <td></td> </tr> </table> | Class B | 10 | Network address (14) | Host address (16) | Subnet mask | 255 | 255 | 255 | 0 | | 11111111 | 11111111 | 11111111 | 00000000 | | Network address | Subnet address | Host address | |
| Class B | 10 | Network address (14) | Host address (16) | | | | | | | | | | | | | | | | |
| Subnet mask | 255 | 255 | 255 | 0 | | | | | | | | | | | | | | | |
| | 11111111 | 11111111 | 11111111 | 00000000 | | | | | | | | | | | | | | | |
| | Network address | Subnet address | Host address | | | | | | | | | | | | | | | | |
| <p><Unusable subnet masks></p> <ul style="list-style-type: none"> • All bits are set to "0". 0.0.0.0 • All bits are set to "1". 255.255.255.255 | | | | | | | | | | | | | | | | | | | |

Local Mode Screen

Make prohibition settings for Local mode.
For more information, refer to the V9 Series Reference Manual.

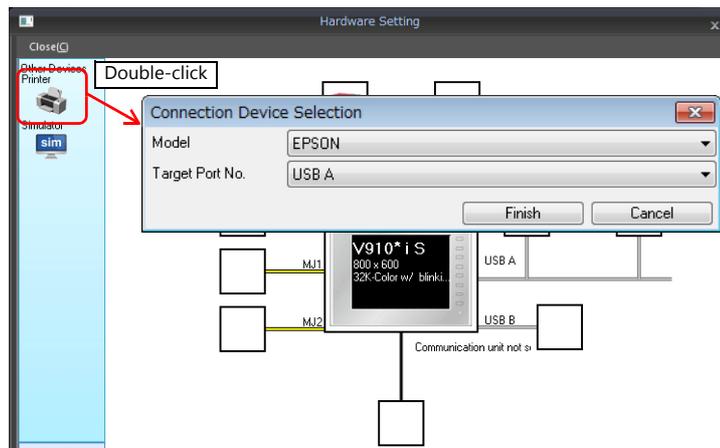
1.4.3 Other Equipment



Printer

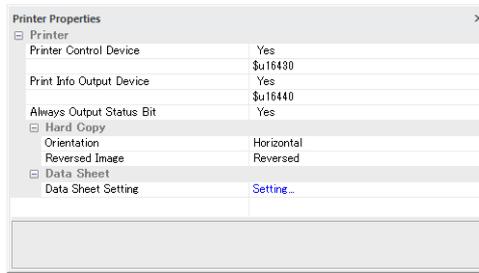
Configure these settings when connecting a printer.

Selecting the printer model



| Item | Contents |
|-----------------|--|
| Model | Select the model of the printer to connect. |
| Target Port No. | Select the port to connect the printer cable to. USB A: Select when connecting an EPSON, ESC/P-R compatible printer. Also use this setting when connecting a parallel printer using a commercially available parallel-to-USB cable. USB B: Select when connecting a PictBridge-compatible printer. MJ1/MJ2: Select when connecting with the serial interface of a printer. Also select whether to use MJ1 or MJ2 of the V9 series. |

Printer properties



| Item | Contents | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
|--|--|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|
| Printer Control Device | <p>When this setting is enabled and the bit is set to ON (0 → 1), screen images and data sheets can be printed out.</p> <p>MSB LSB</p> <table border="1" style="width: 100%; text-align: center;"> <tr> <td>15</td><td>14</td><td>13</td><td>12</td><td>11</td><td>10</td><td>09</td><td>08</td><td>07</td><td>06</td><td>05</td><td>04</td><td>03</td><td>02</td><td>01</td><td>00</td> </tr> <tr> <td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td> </tr> </table> <p style="text-align: right;">0 → 1: Screen image output 0 → 1: Data sheet output</p> | 15 | 14 | 13 | 12 | 11 | 10 | 09 | 08 | 07 | 06 | 05 | 04 | 03 | 02 | 01 | 00 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| 15 | 14 | 13 | 12 | 11 | 10 | 09 | 08 | 07 | 06 | 05 | 04 | 03 | 02 | 01 | 00 | | | | | | | | | | | | | | | | | | |
| 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | | | | | | | | | | | | | | | | | | |
| Printer Info Output Device | <p>When this setting is enabled, the status of the printer is stored in the specified address.</p> <p>MSB LSB</p> <table border="1" style="width: 100%; text-align: center;"> <tr> <td>15</td><td>14</td><td>13</td><td>12</td><td>11</td><td>10</td><td>09</td><td>08</td><td>07</td><td>06</td><td>05</td><td>04</td><td>03</td><td>02</td><td>01</td><td>00</td> </tr> <tr> <td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td> </tr> </table> <p style="text-align: right;">0: End (standby) 1: Transferring print data 0: Not busy status 1: Busy status</p> | 15 | 14 | 13 | 12 | 11 | 10 | 09 | 08 | 07 | 06 | 05 | 04 | 03 | 02 | 01 | 00 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| 15 | 14 | 13 | 12 | 11 | 10 | 09 | 08 | 07 | 06 | 05 | 04 | 03 | 02 | 01 | 00 | | | | | | | | | | | | | | | | | | |
| 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | | | | | | | | | | | | | | | | | | |
| Always Output Status Bit | <p>The V9 series outputs [0 → 1] when starting to transfer data upon receiving a print command, and outputs [1 → 0] upon finishing transfer. However, these signals may not be output if the print data is small. Select [Yes] to output a signal regardless of the data size.</p> <p>The output area is as follows:</p> <ul style="list-style-type: none"> • Bit 1 of the device memory for printer information output • Bit 0 of internal device memory \$s16 <p>\$s16</p> <p>MSB LSB</p> <table border="1" style="width: 100%; text-align: center;"> <tr> <td>15</td><td>14</td><td>13</td><td>12</td><td>11</td><td>10</td><td>09</td><td>08</td><td>07</td><td>06</td><td>05</td><td>04</td><td>03</td><td>02</td><td>01</td><td>00</td> </tr> <tr> <td></td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td> </tr> </table> <p style="text-align: right;">0: End (standby) 1: Transferring print data</p> | 15 | 14 | 13 | 12 | 11 | 10 | 09 | 08 | 07 | 06 | 05 | 04 | 03 | 02 | 01 | 00 | | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| 15 | 14 | 13 | 12 | 11 | 10 | 09 | 08 | 07 | 06 | 05 | 04 | 03 | 02 | 01 | 00 | | | | | | | | | | | | | | | | | | |
| | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | | | | | | | | | | | | | | | | | | |
| Hard Copy | <p>Orientation</p> <p>Specify the printing orientation of the screen on paper. In vertical output, the screen is rotated 90° clockwise with respect to the printing paper and printed out.</p> <ul style="list-style-type: none"> • Printing examples of hard copies: <div style="display: flex; justify-content: space-around; align-items: center;"> <div style="text-align: center;"> <p>Horizontal</p> </div> <div style="text-align: center;"> <p>Vertical</p> </div> </div> | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| | <p>Reversed Image</p> <p>Reversed: Screens are printed with black and white inverted. Normal: Screens are printed as they are displayed on MONITOUCH.</p> | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Data Sheet | <p>Data Sheet Setting</p> <p>Make settings for printing data sheets. For more information, refer to the V9 Series Reference Manual.</p> | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| <p>Use PictBridge only on USB-B port.</p> <p>Make this setting when using a PictBridge-compatible printer. Select [Yes] when starting up the USB-B port as the connection port for a PictBridge printer in the RUN mode. When transferring screen programs via the USB-B port, switch to Local mode.</p> | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |

| Item | | Contents |
|-------------|-------------|--|
| Serial Port | Baud Rate | Set the communication baud rate. 4800/9600/19200/38400/57600/76800/115K BPS |
| | Parity | Select an option for parity bit. None / Odd / Even |
| | Data Length | Select a data length. 7 bits / 8 bits |
| | Stop Bit | Select a stop bit. 1 bit / 2 bits |

* For details on printing, refer to the V9 Series Reference Manual.

Touch Switch (CH5)

Configure this setting when emulating touch switches on the RGB input screen.
The optional unit "GUR-01/GUR-10/GUR-11" (under development) is required for RGB input display.
For details on touch switch emulation, refer to the V9 Series Reference Manual.

Simulator

Configure this setting when saving a simulator communication program to a storage device (SD card or USB flash drive) in addition to screen program data using the storage manager.

1.5 System Device Memory for Communication Confirmation

The V9 series has addresses \$s and \$Pn as system device memory.

- \$Pn
This is the system device memory for 8-way communications, and 512 words are allocated for each logical port. For more information, see "1.5.1 \$Pn (For 8-way Communication)".
- \$s518
This is the system device memory for confirming the Ethernet status. For more information, see "1.5.2 \$s518 (Ethernet Status Confirmation)".

For the device memory address \$s, \$s0 to 2047 (2 K words) are assigned and data can be read from written to this area. For more information on addresses other than \$s518, refer to the V9 Series Reference Manual.

1.5.1 \$Pn (For 8-way Communication)

This is the system device memory for 8-way communications, and 512 words are assigned for each logical port. Refer to the next section for more information.

| | |
|-------------------------------|-----------|
| \$P1: 0000 : \$P1: 0511 | PLC1 area |
| \$P2: 0000 : \$P2: 0511 | PLC2 area |
| \$P3: 0000 : \$P3: 0511 | PLC3 area |
| \$P4: 0000 : \$P4: 0511 | PLC4 area |
| \$P5: 0000 : \$P5: 0511 | PLC5 area |
| \$P6: 0000 : \$P6: 0511 | PLC6 area |
| \$P7: 0000 : \$P7: 0511 | PLC7 area |
| \$P8: 0000 : \$P8: 0511 | PLC8 area |

\$Pn List

The \$Pn list is presented below. Part of the information of logical ports PLC1/PLC2 can also be stored in \$.^{*1}

| \$Pn (n = 1 to 8) | \$. ^{*1} | Contents | Device Type |
|----------------------|-----------------------------|---|----------------|
| 000 | 111 (PLC1) | V9 local port number Stores the local port number of the V9 series. (Universal serial communication, slave communication, etc.) | ←V |
| : | - | : | |
| 004 | 130 (PLC1) ^{*2} | Modbus TCP/IP Sub Station communications Relay station No. designated device memory When a relay station number is set with a MOV macro command, the error information of the sub station number that is connected to that relay station is stored in \$Pn010 to 025. | →V |
| : | - | : | |
| 010 | 128 (PLC1) | Link down information (station No. 0 - 15) 0: Normal 1: Down | ←V |
| 011 | 129 (PLC1) | Link down information (station No. 16 - 31) 0: Normal 1: Down | |
| 012 | 114 (PLC1) | Link down information (station No. 32 - 47) 0: Normal 1: Down | |
| 013 | 115 (PLC1) | Link down information (station No. 48 - 63) 0: Normal 1: Down | |
| 014 | 116 (PLC1) | Link down information (station No. 64 - 79) 0: Normal 1: Down | |
| 015 | 117 (PLC1) | Link down information (station No. 80 - 95) 0: Normal 1: Down | |
| 016 | 118 (PLC1) | Link down information (station No. 96 - 111) 0: Normal 1: Down | |
| 017 | 119 (PLC1) | Link down information (station No. 112 - 127) 0: Normal 1: Down | |
| 018 | 120 (PLC1) | Link down information (station No. 128 - 143) 0: Normal 1: Down | |
| 019 | 121 (PLC1) | Link down information (station No. 144 - 159) 0: Normal 1: Down | |
| 020 | 122 (PLC1) | Link down information (station No. 160 - 175) 0: Normal 1: Down | |
| 021 | 123 (PLC1) | Link down information (station No. 176 - 191) 0: Normal 1: Down | |
| 022 | 124 (PLC1) | Link down information (station No. 192 - 207) 0: Normal 1: Down | |
| 023 | 125 (PLC1) | Link down information (station No. 208 - 223) 0: Normal 1: Down | |
| 024 | 126 (PLC1) | Link down information (station No. 224 - 239) 0: Normal 1: Down | |
| 025 | 127 (PLC1) | Link down information (station No. 240 - 255) 0: Normal 1: Down | |
| : | - | : | |
| 099 | - | Error information hold (page 1-59) Setting for the update timing of the \$Pn: 010 to 025 link down information 0: Always updated with the latest information Other than 0: Only updated when a communication error occurs | →V |
| 100 | 730 (PLC2) | Error status Station No. 00 status (page 1-60) | ←V |
| 101 | 731 (PLC2) | Error status Station No. 01 status (page 1-60) | |
| 102 | 732 (PLC2) | Error status Station No. 02 status (page 1-60) | |
| 103 | 733 (PLC2) | Error status Station No. 03 status (page 1-60) | |
| 104 | 734 (PLC2) | Error status Station No. 04 status (page 1-60) | |
| 105 | 735 (PLC2) | Error status Station No. 05 status (page 1-60) | |
| 106 | 736 (PLC2) | Error status Station No. 06 status (page 1-60) | |
| 107 | 737 (PLC2) | Error status Station No. 07 status (page 1-60) | |
| 108 | 738 (PLC2) | Error status Station No. 08 status (page 1-60) | |
| 109 | 739 (PLC2) | Error status Station No. 09 status (page 1-60) | |

| \$Pn (n = 1 to 8) | \$s ^{*1} | Contents | Device Type |
|----------------------|-------------------|---|----------------|
| 110 | 740 (PLC2) | Error status Station No. 10 status (page 1-60) | ←V |
| : | : | : | |
| 120 | 750 (PLC2) | Error status Station No. 20 status (page 1-60) | |
| : | : | : | |
| 130 | 760 (PLC2) | Error status Station No. 30 status (page 1-60) | |
| 131 | 761 (PLC2) | Error status Station No. 31 status (page 1-60) | |
| 132 | 820 (PLC2) | Error status Station No. 32 status (page 1-60) | |
| 133 | 821 (PLC2) | Error status Station No. 33 status (page 1-60) | |
| : | : | : | |
| 140 | 828 (PLC2) | Error status Station No. 40 status (page 1-60) | |
| : | : | : | |
| 150 | 838 (PLC2) | Error status Station No. 50 status (page 1-60) | |
| : | : | : | |
| 160 | 848 (PLC2) | Error status Station No. 60 status (page 1-60) | |
| : | : | : | |
| 170 | 858 (PLC2) | Error status Station No. 70 status (page 1-60) | |
| : | : | : | |
| 180 | 868 (PLC2) | Error status Station No. 80 status (page 1-60) | |
| : | : | : | |
| 190 | 878 (PLC2) | Error status Station No. 90 status (page 1-60) | |
| : | : | : | |
| 199 | 887 (PLC2) | Error status Station No. 99 status (page 1-60) | |
| 200 | - | Error status Station No. 100 status (page 1-60) | |
| : | : | : | |
| 350 | - | Error status Station No. 250 status (page 1-60) | |
| : | : | : | |
| 355 | - | Error status Station No. 255 status (page 1-60) | |
| 356 | - | Device memory map 0 Status | ←V |
| 357 | - | Device memory map 0 Error code 1 | |
| 358 | - | Device memory map 0 Error code 2 | |
| 359-361 | - | Device memory map 1 Status, error code | |
| 362-364 | - | Device memory map 2 Status, error code | |
| 365-367 | - | Device memory map 3 Status, error code | |
| 368-370 | - | Device memory map 4 Status, error code | |
| 371-373 | - | Device memory map 5 Status, error code | |
| 374-376 | - | Device memory map 6 Status, error code | |
| 377-379 | - | Device memory map 7 Status, error code | |
| 380-382 | - | Device memory map 8 Status, error code | |
| 383-385 | - | Device memory map 9 Status, error code | |
| 386-388 | - | Device memory map 10 Status, error code | |
| 389-391 | - | Device memory map 11 Status, error code | |
| 392-394 | - | Device memory map 12 Status, error code | |
| 395-397 | - | Device memory map 13 Status, error code | |
| 398-400 | - | Device memory map 14 Status, error code | |
| 401-403 | - | Device memory map 15 Status, error code | |
| 404-406 | - | Device memory map 16 Status, error code | |
| 407-409 | - | Device memory map 17 Status, error code | |
| 410-412 | - | Device memory map 18 Status, error code | |
| 413-415 | - | Device memory map 19 Status, error code | |
| 416-418 | - | Device memory map 20 Status, error code | |

| \$Pn (n = 1 to 8) | \$s ^{*1} | Contents | Device Type |
|----------------------|-----------------------------|--|----------------|
| 419-421 | - | Device memory map 21 Status, error code | ←V |
| 422-424 | - | Device memory map 22 Status, error code | |
| 425-427 | - | Device memory map 23 Status, error code | |
| 428-430 | - | Device memory map 24 Status, error code | |
| 431-433 | - | Device memory map 25 Status, error code | |
| 434-436 | - | Device memory map 26 Status, error code | |
| 437-439 | - | Device memory map 27 Status, error code | |
| 440-442 | - | Device memory map 28 Status, error code | |
| 443-445 | - | Device memory map 29 Status, error code | |
| 446-448 | - | Device memory map 30 Status, error code | |
| 449 | - | Device memory map 31 Status | |
| 450 | - | Device memory map 31 Error code 1 | |
| 451 | - | Device memory map 31 Error code 2 | |
| : | : | : | |
| 493 | 762 (PLC2) ^{*3} | Device memory map reading prohibited flag (refer to the V9 Series Reference Manual). 0: Periodical reading/synchronized reading executed Other than 0: Periodical reading/synchronized reading stopped | →V |
| 494 | 763 (PLC2) ^{*3} | Forced execution of the device memory map TRL_READ/TBL_WRITE macro Setting for macro operation when there is a station with a communication error 0: The macro is not executed in relation to any of the stations. Other than 0: The macro is executed in relation to connected stations. | |
| 495 | 764 (PLC2) ^{*3} | Device memory map writing prohibited flag (refer to the V9 Series Reference Manual). 0: Periodical writing/synchronized writing executed Other than 0: Periodical writing/synchronized writing stopped | |
| : | - | : | |
| 500 | 800 (PLC3) | Device memory for Modbus slave communications Used for setting the number of the reference device memory map and the device memory for referring free area 31.Used for setting the number of the reference device memory map and the device memory for referring free area 31. \$Pn500 to 505 are exclusively used for monitoring; \$s800 to 805 are used for writing from the Modbus master. Refer to the Modbus Slave Communication Specifications. | →V |
| 501 | 801 (PLC3) | | |
| 502 | 802 (PLC3) | | |
| 503 | 803 (PLC3) | | |
| 504 | 804 (PLC3) | | |
| 505 | 805 (PLC3) | | |
| : | : | : | |
| 508 | 765 (PLC2) | Error response code (page 1-62) If "800BH" (error code received) is stored for the error status (\$Pn100 to 355), it is possible to check the error code. | ←V |
| 509 | 766 (PLC2) | | |
| 510 | 767 (PLC2) | | |
| 511 | 768 (PLC2) | | |

*1 For PLC1, select [Yes] for [System memory (\$s) V7 Compatible] under [Detail] on the [PLC Properties] window. The same information is stored in the \$P1 and \$s.

*2 If designating the relay station number using \$s130, select [Yes] for [System memory (\$s) V7 Compatible] under [Detail] on the [PLC Properties] window for PLC1. \$P1: 004 cannot be used in this case.

*3 If executing device memory map control using \$s762, \$s763 and \$s764, select yes for [System memory (\$s) V7 Compatible] under [Detail] on the [PLC Properties] window for PLC2. Note that \$P2: 493/494/495 cannot be used in this case.

Details

\$Pn:99

The update timing for the link down information stored in \$Pn:010 to 025 is set here.

- 0: Always updated with the latest information
- Other than 0: Only updated when a communication error occurs

- Example:

An error has occurred at station No. 18. 2nd bit of \$Pn: 011 is set (ON).

| | | | | | | | | | | | | | | | | | | |
|-----------|----------------|----|----|----|----|----|---|---|---|---|---|---|---|----------------|---|---|--|--|
| | Station No. 31 | | | | | | | | | | | | | Station No. 16 | | | | |
| | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | | |
| \$Pn: 011 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 0 | 0 | | |

↓
↓
Station No. 18 Link down

After resetting communications

- If \$Pn: 99 = 0, the link down information is updated.

| | | | | | | | | | | | | | | | | | | |
|-----------|----------------|----|----|----|----|----|---|---|---|---|---|---|---|----------------|---|---|--|--|
| | Station No. 31 | | | | | | | | | | | | | Station No. 16 | | | | |
| | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | | |
| \$Pn: 011 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | | |

↓
Station No. 18 Normal communication

- If \$Pn: 99 = other than 0, the link down information is not updated.

| | | | | | | | | | | | | | | | | | | |
|-----------|----------------|----|----|----|----|----|---|---|---|---|---|---|---|----------------|---|---|--|--|
| | Station No. 31 | | | | | | | | | | | | | Station No. 16 | | | | |
| | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | | |
| \$Pn: 011 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 0 | 0 | | |

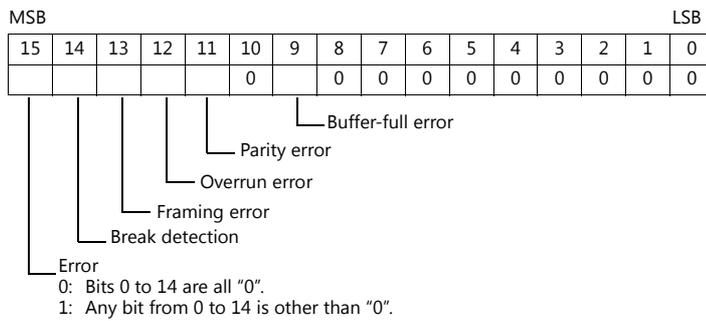
↓
Station No. 18 Link down

\$Pn: 100 to 355

The results of communication with each station are stored here. The status codes are shown below.

| Code (HEX) | Contents |
|------------|---|
| 0000H | Normal |
| FFFFH | Time-out |
| 8001H | Check code error |
| 8002H | Data error |
| 800BH | Receives the error code from the connected device |

Errors other than the above are stored as shown below.



| Error | Details | Solution |
|---------------------|--|---|
| Time-out | Although a request to send is given, no answer is returned within the specified time. | Implement solutions 1, 2, and 3. |
| Check code | The check code of the response is incorrect. | Implement solutions 1 and 3. |
| Data error | The code of the received data is invalid. | Implement solutions 1, 2, and 3. |
| Error code received | An error occurred on the connected device. | Refer to the instruction manual for the PLC. |
| Buffer full | The V9 buffer is full. | Contact your local distributor. |
| Parity | An error occurred in parity check. | Implement solutions 2 and 3. |
| Overrun | After receiving one character, the next character was received before internal processing was completed. | Implement solutions 1 and 3. |
| Framing | Although the stop bit must be "1", it was detected as "0". | Implement solutions 1, 2, and 3. |
| Break detection | The connected device's SD is remaining at the low level. | Examine the connection with the connected device's SD and RD. |

- Solution

- 1) Check if the communication settings of the V9 series and the connected device are matched.
- 2) Check the cable connection.
- 3) Data may be disrupted because of noise. Fix noise.

If you still cannot solve the error even after following the solutions above, contact your local distributor.

\$Pn: 356 to 451

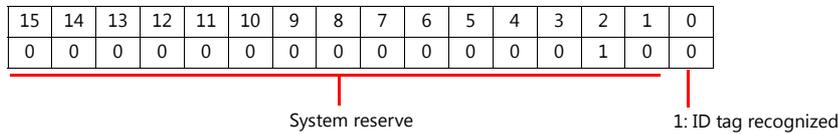
This device memory is valid when an Omron ID controller (V600/620/680) is connected with [Guarantee synchronism of the data] checked on the [Device Memory Map Setting] dialog.

- Status (\$Pn 356, 359, ...)

The execution status of the device memory map is stored here.

The bit is set (ON) when reading or writing of the first data in the device memory map is correctly finished.

When the control device memory (command bit) is set (ON), the bit is reset.



- Error code 1 (\$Pn 357, 360, ...)

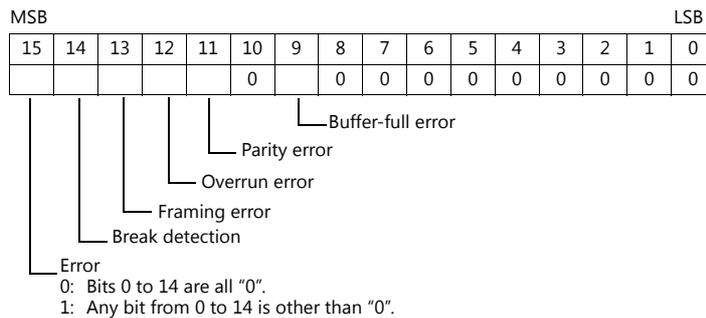
An error code is stored when an error occurs in the reading or writing of data in the device memory map.

If multiple errors occur in the device memory map, the last error code is stored.

When the control device memory (command bit) is set (ON), the bit is reset.

| Code (HEX) | Contents |
|------------|---|
| FFFFH | Time-out |
| 8001H | Check code error |
| 8002H | Data error |
| 800BH | Receives the error code from the connected device |

Errors other than the above are stored as shown below.



- Error code 2 (\$Pn 358, 361, ...)

The exit code is stored here when "800BH" of error code 1 is stored.

| Exit Code (HEX) | Contents |
|-----------------|---|
| 10 | Parity error |
| 11 | Framing error |
| 12 | Overrun error |
| 13 | FCS error |
| 14 | Format error, execution status error |
| 18 | Frame length error |
| 70 | Tag communication error |
| 71 | Inconsistency error |
| 72 | Tag absence error |
| 76 | Copy error |
| 7A | Address error |
| 7C | Antenna disconnection error |
| 7D | Write protect error |
| 75 | Data check command Exit code stored when the writing count management command has been successfully processed (without any error) |
| 76 | Data check command Exit code stored when the writing count management command has abnormally been processed (comparison error, excessive writing counts) |
| 92 | Abnormal mains voltage at antenna |
| 93 | Internal device memory error |

\$Pn: 508 to 511

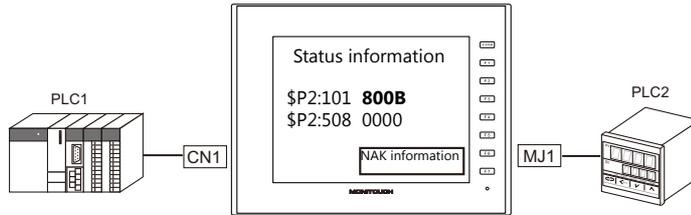
If "800BH" is stored for the error status information (\$Pn: 100 to 355), on transferring the data of that station number to any internal device memory address, the reception code will be obtained at \$Pn: 508 to 511.

Notes on use

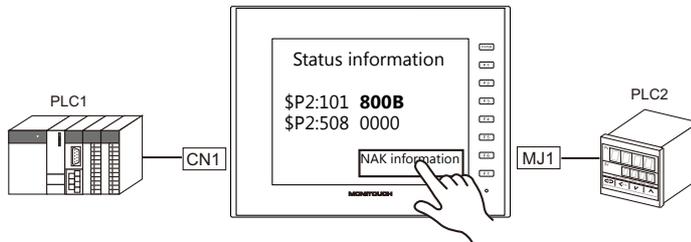
- Use \$u/\$T as the target internal device memory.
- Use the macro command MOV (W). MOV (D) cannot be used.
- "0" is stored to device memory addresses that have no expansion error code.

- Example PLC2: Fuji Electric PXR station No. 1

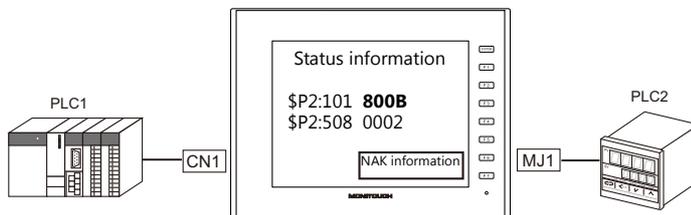
- 1) On receipt of an error code at station No. 1 of PLC2, "800BH" is stored in \$P2:101.



- 2) The data of \$P2: 101 is transferred to \$u1000 by a MOV command.
\$u1000 = \$P2: 101 (W)



- 3) The reception code is stored in \$P2: 508.
\$P2:508 = 0002H



- 4) The PXR manual shows that code 002H means "device memory address range exceeded". Amend the screen program address designation.

1.5.2 \$s518 (Ethernet Status Confirmation)

Stores the current status of the Ethernet.

| Address | Contents | Stored Value |
|---------|---|--|
| \$s518 | Ethernet status (for built-in LAN port) | <ul style="list-style-type: none"> • [0]: Normal • [Other than 0]: Error * For details on errors, refer to the next section. |

Error details

| No. | Built-in LAN | Contents | Solution |
|------|--------------|--|---|
| 201 | ○ | Send error | Check that the setting on the target station is consistent with the network table setting. |
| 203 | ○ | TCP socket creation error | The TCP socket cannot be created. Turn the power off and back on again, or check the communication line status, e.g., if the port number is duplicated. |
| 204 | ○ | TCP connection over | The number of connections reaches the maximum (256), and no more connection is possible. Check the communication lines. |
| 205 | ○ | TCP connection error | Connection cannot be established. Check the communication lines, or turn the power off and back on again. |
| 207 | ○ | TCP send error | TCP communication has failed. Check the communication lines. |
| 208 | ○ | TCP connection interruption notification from the connected device | Check the connected device and communication lines. |
| 261 | ○ | Send processing full error | Sending process is disabled. Check the communication lines. |
| 350 | ○ | Send buffer full | The line is busy. Consult the network administrator of your company. The communication unit is of an old version or is faulty. |
| 801 | ○ | Link down error | Check the HUB or the link confirmation LED on the communication unit. If the LED is not on, check cable connection and the port setting on the network table. |
| 1202 | ○ | MAC address error | The MAC address is not registered. Repair is necessary. |
| 2001 | ○ | Undefined error | Turn the power off and back on again. If the problem persists, the unit may be faulty. Contact your local distributor. |

MEMO

Please use this page freely.

2. ALLEN BRADLEY

2.1 PLC Connection

2.1 PLC Connection

Serial Connection

| PLC Selection on the Editor | CPU | Unit/Port | Signal Level | Connection | | Ladder Transfer ^{*3} |
|-------------------------------|---|---|--------------|---|--|-------------------------------|
| | | | | CN1 | MJ1/MJ2 | |
| PLC-5 | PLC-5/10, PLC-5/12, PLC-5/15, PLC-5/25 | 1785-KE | RS-232C | Wiring diagram 3 - C2 | Wiring diagram 4 - M2 | × |
| | | 1770-KF2 | RS-232C | Wiring diagram 4 - C2 | Wiring diagram 5 - M2 | |
| | | | RS-422 | Wiring diagram 2 - C4 | × | |
| | | PLC-5/11, PLC-5/20, PLC-5/20E, PLC-5/30, PLC-5/40, PLC-5/40L, PLC-5/40E, PLC-5/60, PLC-5/60L, PLC-5/80, PLC-5/80E | Channel 0 | RS-232C | Wiring diagram 4 - C2 | |
| | RS-422 | | | Wiring diagram 3 - C4 | × | |
| | 1785-KE | | RS-232C | Wiring diagram 3 - C2 | Wiring diagram 4 - M2 | |
| | | | 1770-KF2 | RS-232C | Wiring diagram 4 - C2 | |
| | RS-422 | Wiring diagram 2 - C4 | | × | | |
| Control Logix / Compact Logix | 1756 Control Logix | Logix 5550 | RS-232C | Wiring diagram 1 - C2 ^{*1} | Wiring diagram 1 - M2 | × |
| | 1769 Compact Logix | Channel 0 | | | | ○ |
| SLC500 | SLC5/03 and later | Channel 0 | RS-232C | Wiring diagram 2 - C2 | Wiring diagram 2 - M2 | × |
| | | 1747-KE DF1 | RS-232C | Wiring diagram 1 - C4 | × | |
| | | | RS-422 | Wiring diagram 1 - C4 | × | |
| MicroLogix | MicroLogix 1000 MicroLogix 1100 MicroLogix 1500 | Channel 0 | RS-232C | AB's "1761-CBL-PM02" + Gender changer ^{*2} | AB's "1761-CBL-PM02" + Wiring diagram 3 - M2 | × |

*1 Can be connected using the AB's "1756-CP3" cable + D-sub gender changer (9-pin, female-to-male) commercially available.

*2 Use a D-sub gender changer (9-pin, female-to-male) commercially available.

| Manufacturer | Model |
|--------------|----------|
| Black Box | FA440-R2 |
| Misumi | DGC-9PP |

*3 For the ladder transfer function, see the V9 Series Reference Manual.

Ethernet Connection

| PLC Selection on the Editor | CPU | Unit | TCP/IP | UDP/IP | Port No. | Keep Alive ^{*1} | Ladder Transfer ^{*2} |
|--------------------------------------|--|-------------------------------------|--------|--------|-------------------------------|--------------------------|-------------------------------|
| PLC-5 (Ethernet) | PLC-5/20E PLC-5/40E PLC-5/80E | - | ○ | × | 44818 fixed | ○ | × |
| Control Logix (Ethernet) | Logix 5550 | 1756-ENBT/A | ○ | × | 44818 fixed | ○ | × |
| | 1769-L32E 1769-L35E 1769-L27ERM-QBFC1B ^{*2} | - | | | | | |
| SLC500 (Ethernet TCP/IP) | SLC 5/05 | 1747-L551 1747-L552 1747-L553 | ○ | × | 44818 fixed | ○ | × |
| MicroLogix (Ethernet TCP/IP) | MicroLogix 1100 | - | | | | | |
| NET-ENI (SLC500 Ethernet TCP/IP) | SLC 5/03 SLC 5/04 SLC 5/05 | 1761-NET-ENI 1761-NET-ENI W | ○ | × | Fixed to 44818 (Max. 6 units) | ○ | × |
| NET-ENI (MicroLogix Ethernet TCP/IP) | MicroLogix 1000 MicroLogix 1100 MicroLogix 1200 MicroLogix 1500 | 1761-NET-ENI 1761-NET-ENI W | ○ | × | Fixed to 44818 (Max. 6 units) | ○ | × |

*1 For KeepAlive functions, see "1.3.2 Ethernet Communication".

*2 For the ladder transfer function, see the V9 Series Reference Manual.

2.1.1 PLC-5

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|--|--------------------------------------|
| Connection Mode | <u>1</u> : 1 / 1 : n / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet) | |
| Signal Level | <u>RS-232C</u> / RS-422/485 | |
| Baud Rate | 4800 / 9600 / <u>19200</u> bps | |
| Data Length | 7 / <u>8</u> bits | Fixed to 8 bits except for Channel 0 |
| Stop Bit | <u>1</u> / 2 bits | |
| Parity | None / <u>Even</u> | |
| Target Port No. | <u>0</u> to 31 | |

PLC

Series A 1785-KE

SW-1 (RS-232C link features)

| No. | Item | Setting | Remarks |
|---------|---------------------------|----------------------------------|---|
| 1, 2, 5 | RS-232C Link Features | SW1: OFF SW2: OFF SW5: OFF | Error check: BCC Parity: None Embedded response: No |
| | | SW1: ON SW2: OFF SW5: OFF | Error check: BCC Parity: Even Embedded response: No |
| 3 | Detect duplicate messages | ON | Detect and ignore duplicate messages |
| 4 | Hand shaking signals | OFF | Ignore handshaking signals |

SW-2 (for future use)

| No. | Setting | Remarks |
|------|--|---------|
| 1, 2 | OFF Always OFF (system reserved) | |

SW-3, SW-4 (node number)

| SW | Item | Setting | Remarks |
|------|--------------------|---------|--|
| SW-3 | First digit (OCT) | No. | 0 1 2 3 4 5 6 7 |
| | | SW1 | OFF ON OFF ON OFF ON OFF ON |
| | | SW2 | OFF OFF ON ON OFF OFF ON ON |
| | | SW3 | OFF OFF OFF OFF ON ON ON ON |
| SW-4 | Second digit (OCT) | No. | 0 1 2 3 4 5 6 7 |
| | | SW1 | OFF ON OFF ON OFF ON OFF ON |
| | | SW2 | OFF OFF ON ON OFF OFF ON ON |
| | | SW3 | OFF OFF OFF OFF ON ON ON ON |
| | | | Setting example: Station number 15 (DEC) = 17 (OCT) SW-3: ON, OFF, OFF SW-4: ON, ON, ON |

SW-5 (network link communication rate)

| No. | Item | Setting | Remarks |
|-----|----------------------------|------------------|--------------|
| 1 | Network Communication Rate | ON | For DH+ port |
| 2 | | ON | |
| | | 57600 bps | |

SW-6 (RS-232C communication rate and diagnostic commands)

| No. | Item | Setting | | | | Remarks |
|-----|----------------------------|-----------|------------------------------------|----------|-----------|--|
| 1 | RS-232C Communication Rate | | | | | Set the same value as the one set on V9. |
| 2 | | | 4800 bps | 9600 bps | 19200 bps | |
| 3 | | SW1 | ON | OFF | ON | |
| | | SW2 | OFF | ON | ON | |
| | SW3 | ON | ON | ON | | |
| 4 | Diagnostic Commands | ON | Execute diagnostic commands | | | |

Series B 1785-KE**SW-1 (RS-232C link features)**

| No. | Item | Setting | | Remarks |
|-----|---------------------------|----------------------------------|---|---------|
| 1-3 | RS-232C Link Features | SW1: OFF SW2: OFF SW3: OFF | Error check: BCC Parity: None Embedded response: No | |
| | | SW1: ON SW2: OFF SW3: OFF | Error check: BCC Parity: Even Embedded response: No | |
| 4 | Detect duplicate messages | ON | Detect and ignore duplicate messages | |
| 5 | Hand shaking signals | OFF | Ignore handshaking signals | |
| 6 | Diagnostic Commands | ON | Execute diagnostic commands | |

SW-2 (node number)

| No. | Item | Setting | | | | | | | | | | Remarks |
|-----|---------------|----------------------------|-----|-----|-----|----|-----|-----|-----|----|--|--|
| 1 | Octal Digit 0 | 0 | | | | | | | | | | |
| 2 | | SW1: ON SW2: ON | | | | | | | | | | |
| 3-5 | Octal Digit 1 | | | | | | | | | | | Setting example: Station number 15 (DEC) = 17 (OCT) |
| | | No. | 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | | |
| | | SW3 | OFF | ON | OFF | ON | OFF | ON | OFF | ON | | |
| | | SW4 | OFF | OFF | ON | ON | OFF | OFF | ON | ON | | |
| 6-8 | Octal Digit 2 | | | | | | | | | | | SW3-5: ON, OFF, OFF SW6-8: ON, ON, ON |
| | | No. | 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | | |
| | | SW6 | OFF | ON | OFF | ON | OFF | ON | OFF | ON | | |
| | | SW7 | OFF | OFF | ON | ON | OFF | OFF | ON | ON | | |
| | SW8 | OFF | OFF | OFF | OFF | ON | ON | ON | ON | | | |

SW-3 (communication rates and local/remote option)

| No. | Item | Setting | | | | Remarks |
|-----|----------------------------|-----------|-------------------|------------------|-----------|--|
| 1 | Network Communication Rate | ON | | 57600 bps | | For DH+ port |
| 2 | | ON | | | | |
| 3-5 | RS-232 Link Baud Rate | | | | | Set the same value as the one set on V9. |
| | | | 4800 bps | 9600 bps | 19200 bps | |
| | | SW3 | ON | OFF | ON | |
| | | SW4 | OFF | ON | ON | |
| | SW5 | ON | ON | ON | | |
| 6 | Local / Remote operation | ON | Local mode | | | |

SW-4 (for future use)

| No. | Setting | | Remarks |
|-----|------------|-------------------------------------|---------|
| 1-4 | OFF | Always OFF (system reserved) | |

* Series B 1785-KE switch: ON = 0: DOWN (lower), OFF = 1: UP (upper)

1770-KF2

Setting changes will take effect when the power is turned on. After changing a setting, turn the power off and back on again.

SW-1 (asynchronous link features)

| No. | Item | Setting | | Remarks |
|---------|----------------------------|----------------------------------|---|---------|
| 1, 2, 5 | Asynchronous Link Features | SW1: OFF SW2: OFF SW5: OFF | Error check: BCC Parity: None Embedded response: No | |
| | | SW1: ON SW2: OFF SW5: OFF | Error check: BCC Parity: Even Embedded response: No | |
| 3 | Detect duplicate messages | ON | Detect and ignore duplicate messages | |
| 4 | Hand shaking signals | OFF | Ignore handshaking signals | |

SW-2, SW-3, SW-4 (station number)

| SW | Item | Setting | | | | | | | | | Remarks | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
|------|--------------------|---|----------------------------|-----|-----|-----|-----|-----|-----|----|---------|---|---|---|---|---|---|---|---|-----|-----|----|-----|----|-----|----|-----|----|-----|-----|-----|----|----|-----|-----|----|----|-----|-----|-----|-----|-----|----|----|----|----|--|
| SW-2 | First Digit | 0 | SW1: ON SW2: ON | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| SW-3 | Second Digit (OCT) | <table border="1"> <thead> <tr> <th>No.</th> <th>0</th> <th>1</th> <th>2</th> <th>3</th> <th>4</th> <th>5</th> <th>6</th> <th>7</th> </tr> </thead> <tbody> <tr> <td>SW3</td> <td>OFF</td> <td>ON</td> <td>OFF</td> <td>ON</td> <td>OFF</td> <td>ON</td> <td>OFF</td> <td>ON</td> </tr> <tr> <td>SW4</td> <td>OFF</td> <td>OFF</td> <td>ON</td> <td>ON</td> <td>OFF</td> <td>OFF</td> <td>ON</td> <td>ON</td> </tr> <tr> <td>SW5</td> <td>OFF</td> <td>OFF</td> <td>OFF</td> <td>OFF</td> <td>ON</td> <td>ON</td> <td>ON</td> <td>ON</td> </tr> </tbody> </table> | | | | | | | | | No. | 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | SW3 | OFF | ON | OFF | ON | OFF | ON | OFF | ON | SW4 | OFF | OFF | ON | ON | OFF | OFF | ON | ON | SW5 | OFF | OFF | OFF | OFF | ON | ON | ON | ON | Setting example: Station number 15 (DEC) = 17 (OCT) |
| | | No. | 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| | | SW3 | OFF | ON | OFF | ON | OFF | ON | OFF | ON | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| | | SW4 | OFF | OFF | ON | ON | OFF | OFF | ON | ON | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| SW5 | OFF | OFF | OFF | OFF | ON | ON | ON | ON | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| SW-4 | Third Digit (OCT) | <table border="1"> <thead> <tr> <th>No.</th> <th>0</th> <th>1</th> <th>2</th> <th>3</th> <th>4</th> <th>5</th> <th>6</th> <th>7</th> </tr> </thead> <tbody> <tr> <td>SW6</td> <td>OFF</td> <td>ON</td> <td>OFF</td> <td>ON</td> <td>OFF</td> <td>ON</td> <td>OFF</td> <td>ON</td> </tr> <tr> <td>SW7</td> <td>OFF</td> <td>OFF</td> <td>ON</td> <td>ON</td> <td>OFF</td> <td>OFF</td> <td>ON</td> <td>ON</td> </tr> <tr> <td>SW8</td> <td>OFF</td> <td>OFF</td> <td>OFF</td> <td>OFF</td> <td>ON</td> <td>ON</td> <td>ON</td> <td>ON</td> </tr> </tbody> </table> | | | | | | | | | No. | 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | SW6 | OFF | ON | OFF | ON | OFF | ON | OFF | ON | SW7 | OFF | OFF | ON | ON | OFF | OFF | ON | ON | SW8 | OFF | OFF | OFF | OFF | ON | ON | ON | ON | SW-3: ON, OFF, OFF SW-4: ON, ON, ON |
| | | No. | 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| | | SW6 | OFF | ON | OFF | ON | OFF | ON | OFF | ON | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| SW7 | OFF | OFF | ON | ON | OFF | OFF | ON | ON | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| SW8 | OFF | OFF | OFF | OFF | ON | ON | ON | ON | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |

SW-5 (network link communication rate)

| No. | Item | Setting | | Remarks |
|-----|----------------------------|-----------|------------------|--------------|
| 1 | Network Communication Rate | ON | 57600 bps | For DH+ port |
| 2 | | ON | | |

SW-6 (asynchronous link communication rate and diagnostic commands)

| No. | Item | Setting | | | Remarks | | | | | | | | | | | | |
|---------|---------------------------------|--|---|----------|---------|----------|----------|-----|----|-----|-----|-----|----|-----|----|----|--|
| 1, 2, 3 | Asynchronous Communication Rate | <table border="1"> <thead> <tr> <th></th> <th>4800 bps</th> <th>9600 bps</th> </tr> </thead> <tbody> <tr> <td>SW1</td> <td>ON</td> <td>OFF</td> </tr> <tr> <td>SW2</td> <td>OFF</td> <td>ON</td> </tr> <tr> <td>SW3</td> <td>ON</td> <td>ON</td> </tr> </tbody> </table> | | | | 4800 bps | 9600 bps | SW1 | ON | OFF | SW2 | OFF | ON | SW3 | ON | ON | Set the same value as the one set on V9. |
| | | | 4800 bps | 9600 bps | | | | | | | | | | | | | |
| | | SW1 | ON | OFF | | | | | | | | | | | | | |
| | | SW2 | OFF | ON | | | | | | | | | | | | | |
| SW3 | ON | ON | | | | | | | | | | | | | | | |
| | | | | | | | | | | | | | | | | | |
| | | | | | | | | | | | | | | | | | |
| | | | | | | | | | | | | | | | | | |
| 4 | Diagnostic Commands | ON | Execute Received Diagnostic Commands | | | | | | | | | | | | | | |

SW-7 (selecting the network link)

| No. | Item | Setting | | Remarks |
|-----|----------------------------|------------|--------------------------------|---------|
| 1 | Selecting the Network Link | ON | Peer Communication Link | |
| 2 | | OFF | | |

SW-8 (RS-232-C/RS-422-A selection)

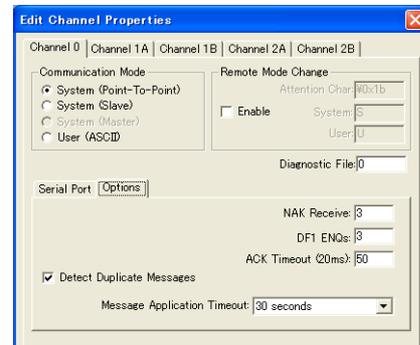
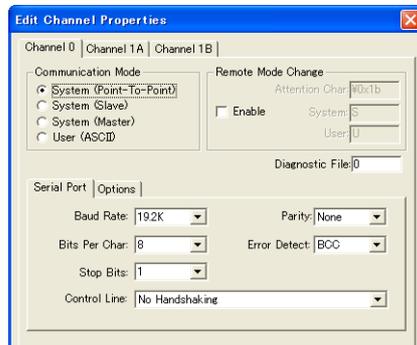
| No. | Item | Setting | | | Remarks | | | | | | | | | |
|------|---------------------------------|---|---------|--------|---------|---------|--------|-----|-----|----|-----|----|-----|--|
| 1, 2 | Selection of RS-232C / RS-422-A | <table border="1"> <thead> <tr> <th></th> <th>RS-232C</th> <th>RS-422</th> </tr> </thead> <tbody> <tr> <td>SW1</td> <td>OFF</td> <td>ON</td> </tr> <tr> <td>SW2</td> <td>ON</td> <td>OFF</td> </tr> </tbody> </table> | | | | RS-232C | RS-422 | SW1 | OFF | ON | SW2 | ON | OFF | |
| | | | RS-232C | RS-422 | | | | | | | | | | |
| | | SW1 | OFF | ON | | | | | | | | | | |
| SW2 | ON | OFF | | | | | | | | | | | | |
| | | | | | | | | | | | | | | |
| | | | | | | | | | | | | | | |

Channel 0

SW-2 (selection of RS-232C/RS-422A)

| SW | Setting | | | Remarks |
|-----|---------|---------|---------|---|
| | No. | RS-232C | RS-422A | |
| SW2 | 1 | ON | OFF | ON: Lower position OFF: Upper position |
| | 2 | ON | OFF | |
| | 3 | ON | ON | |
| | 4 | OFF | OFF | |
| | 5 | OFF | OFF | |
| | 6 | ON | OFF | |
| | 7 | ON | OFF | |
| | 8 | OFF | OFF | |
| | 9 | ON | ON | |
| | 10 | OFF | OFF | |

Channel configuration



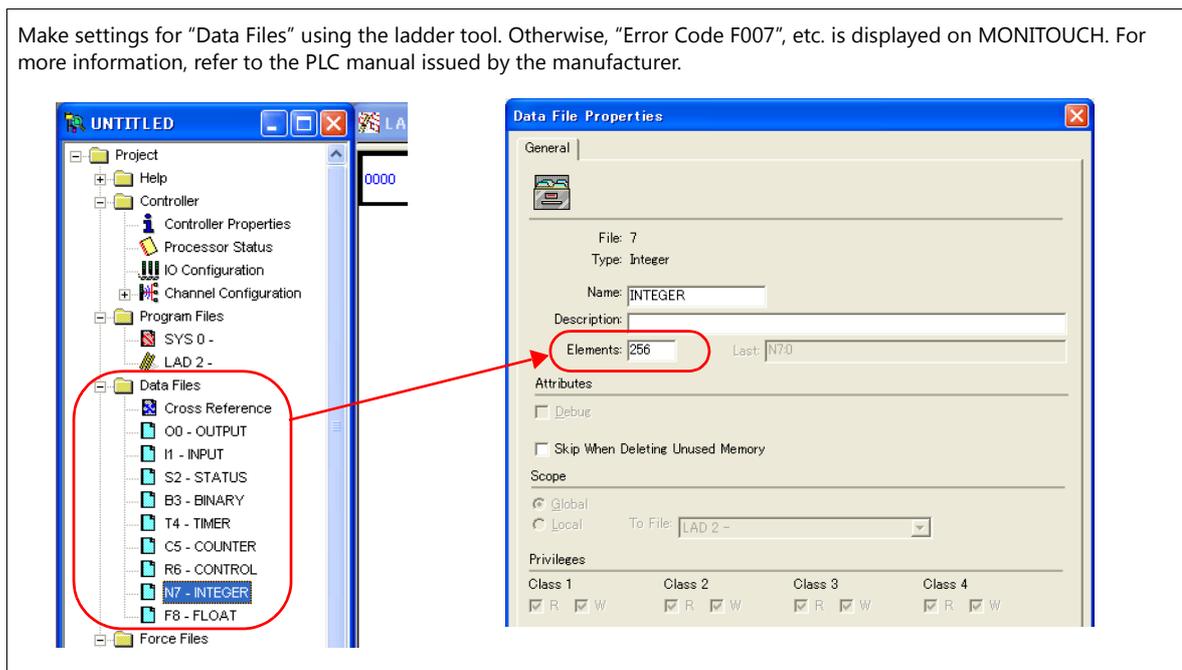
| | Item | Setting | Remarks |
|-------------|-----------------------------|--------------------------------|---------|
| Channel 0 | Communication Mode | System (Point-To-Point) | |
| | Remote Mode Change | Unchecked | |
| Serial Port | Baud Rate | 4800 / 9600 / 19.2 K | |
| | Bits Per Char | 7 / 8 | |
| | Stop Bits | 1 / 2 | |
| | Control Line | No Handshaking | |
| | Parity | None / Even | |
| | Error Detect | BCC | |
| Options | Detect Duplicate Messages | Checked | |
| | NAK Receive | 3 | |
| | DF1 ENQs | 3 | |
| | ACK Timeout (20 msec) | 50 | |
| | Message application timeout | 30 seconds | |

Available Device Memory

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|-------------------------------|------|-------------|
| N (integer) | 00H | |
| B (bit) | 01H | |
| T.ACC (timer/current value) | 02H | |
| T.PRE (timer/set value) | 03H | |
| C.ACC (counter/current value) | 04H | |
| C.PRE (counter/set value) | 05H | |
| I (input) | 06H | |
| O (output) | 07H | |
| S (status) | 08H | |
| T (timer/control) | 09H | |
| C (counter/control) | 0AH | |
| R (control) | 0BH | |
| R.LEN (control/data length) | 0CH | |
| R.POS (control/data position) | 0DH | |
| D (BCD) | 0EH | |
| A (ASCII) | 0FH | |
| F (FLOAT) | 10H | Real number |
| ST (STRING) | 11H | |

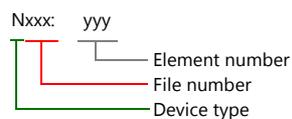
Make settings for "Data Files" using the ladder tool. Otherwise, "Error Code F007", etc. is displayed on MONITOUCH. For more information, refer to the PLC manual issued by the manufacturer.



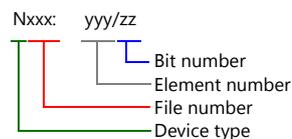
Address denotations

The assigned device memory is expressed as shown below when editing the screen.

Example: For word access



For bit access



The file number will not be displayed for the input, output or status device memory.

Indirect Device Memory Designation

- For the file numbers 0 to 65:

| | 15 | MSB | 8 | 7 | LSB | 0 |
|-------|-------------|-----|-----------------|-------------|-----|---|
| n + 0 | Model | | | Device type | | |
| n + 1 | Address No. | | | | | |
| n + 2 | 00 | | Bit designation | | | |
| n + 3 | 00 | | Station number | | | |

- For the file numbers 66 to 255:

| | 15 | MSB | 8 | 7 | LSB | 0 |
|-------|--------------------|-----|-----------------|-------------|-----|---|
| n + 0 | Model | | | Device type | | |
| n + 1 | Lower address No. | | | | | |
| n + 2 | Higher address No. | | | | | |
| n + 3 | 00 | | Bit designation | | | |
| n + 4 | 00 | | Station number | | | |

- Specify the file number as well as the element number for the address number.

Example: When specifying N007:123
Specify "7123" (DEC) for the address number.

Example: When specifying N120:123
Specify "120123" (DEC) for the address number.
120123 (DEC) is equivalent to 1D53B (HEX). Specify "D53B (HEX)" for the lower address number and "0001" for the upper address number.

- When specifying an address for the timer (control), counter (control) or control device memory in bit designation, specify the bit number in decimal notation as shown below:
 - T: Timer (control)
DN = 13, TT = 14, EN = 15
 - C: Counter (control)
UA = 10, UN = 11, OV = 12, DN = 13, CD = 14, CU = 15
 - R: Control
FD = 08, IN = 09, UL = 10, ER = 11, EM = 12, DN = 13, EU = 14, EN = 15

2.1.2 PLC-5 (Ethernet)

Communication Setting

Editor

Make the following settings on the editor. For more information, see "1.3.2 Ethernet Communication".

- IP address for the V9 unit
 - When specified on the screen program:
[System Setting] → [Hardware Setting] → [Local Port IP Address]
 - When specified on the V9 unit:
Local mode → [LAN Setting]
- Port number for the V9 unit (for communication with PLC)
[System Setting] → [Hardware Setting] → [PLC Properties] → [Communication Setting]
- IP address and port number (No. 44818) of the PLC
Register on the [PLC Table] in [System Setting] → [Hardware Setting] → [PLC Properties] → [Target Settings].

PLC

Channel 2

Channel configuration (channel 2)

The screenshot shows the 'Edit Channel Properties' window for Channel 2. It is divided into two main sections: 'Ethernet Configuration' and 'Advanced Functions'.
 In the 'Ethernet Configuration' section:
 - Ethernet Address: 00:00:BC:1C:BF:D2
 - Network Configuration Type: Static, Dynamic
 - Use DHCP to obtain network configuration:
 - Use BOOTP to obtain network configuration:
 - IP Address: 192.168.1.2
 - Message Connect Timeout (msec): 15000
 - Message Reply Timeout (msec): 3000
 - Inactivity Timeout (minutes): 30
 - Link ID: 0
 In the 'Advanced Functions' section:
 - Subnet Mask: 255.255.255.0
 - Gateway Address: 0.0.0.0

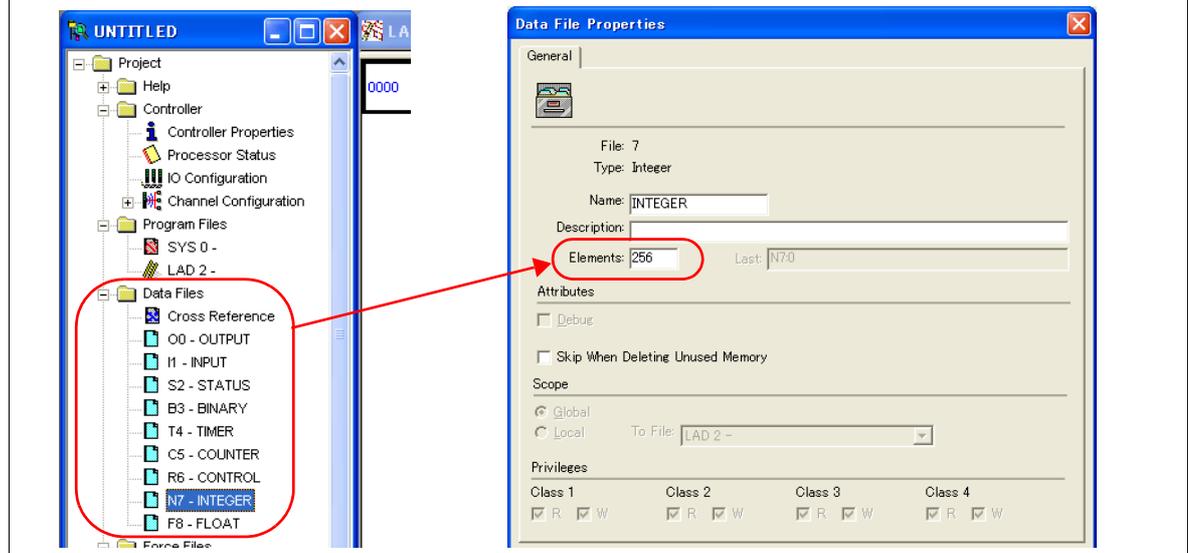
| Item | Setting | Remarks |
|----------------------------|---------------------------------------|---------|
| Network Configuration Type | Static | |
| IP Address | Set the IP address of the PLC. | |
| Subnet Mask | Set the subnet mask of the PLC. | |
| Gateway Address | Specify according to the environment. | |

Available Device Memory

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|-------------------------------|------|-------------|
| N (integer) | 00H | |
| B (bit) | 01H | |
| T.ACC (timer/current value) | 02H | |
| T.PRE (timer/set value) | 03H | |
| C.ACC (counter/current value) | 04H | |
| C.PRE (counter/set value) | 05H | |
| I (input) | 06H | |
| O (output) | 07H | |
| S (status) | 08H | |
| T (timer/control) | 09H | |
| C (counter/control) | 0AH | |
| R (control) | 0BH | |
| R.LEN (control/data length) | 0CH | |
| R.POS (control/data position) | 0DH | |
| D (BCD) | 0EH | |
| A (ASCII) | 0FH | |
| F (FLOAT) | 10H | Real number |
| ST (STRING) | 11H | |

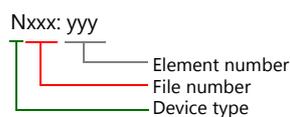
Make settings for "Data Files" using the ladder tool. Otherwise, "Error Code F007", etc. is displayed on MONITOUCH. For more information, refer to the PLC manual issued by the manufacturer.



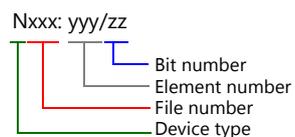
Address denotations

The assigned device memory is expressed as shown below when editing the screen.

Example: For word access



For bit access



The file number will not be displayed for the input, output or status device memory.

Indirect Device Memory Designation

- For the file numbers 0 to 65:

| | | | | | | |
|-----|-------------|-----|---|-----------------|-----|---|
| | 15 | MSB | 8 | 7 | LSB | 0 |
| n+0 | Model | | | Device type | | |
| n+1 | Address No. | | | | | |
| n+2 | 00 | | | Bit designation | | |
| n+3 | 00 | | | Station number | | |

- For the file numbers 66 to 255:

| | | | | | | |
|-----|--------------------|-----|---|-----------------|-----|---|
| | 15 | MSB | 8 | 7 | LSB | 0 |
| n+0 | Model | | | Device type | | |
| n+1 | Lower address No. | | | | | |
| n+2 | Higher address No. | | | | | |
| n+3 | 00 | | | Bit designation | | |
| n+4 | 00 | | | Station number | | |

- Specify the file number as well as the element number for the address number.

Example: When specifying N007:123
Specify "7123" (DEC) for the address number.

Example: When specifying N120:123
Specify "120123" (DEC) for the address number.
120123 (DEC) is equivalent to 1D53B (HEX). Specify "D53B (HEX)" for the lower address number and "0001" for the higher address number.

- When specifying an address for the timer (control), counter (control) or control device memory in bit designation, specify the bit number in decimal notation as shown below:
 - T: Timer (control)
DN = 13, TT = 14, EN = 15
 - C: Counter (control)
UA = 10, UN = 11, OV = 12, DN = 13, CD = 14, CU = 15
 - R: Control
FD = 08, IN = 09, UL = 10, ER = 11, EM = 12, DN = 13, EU = 14, EN = 15

2.1.3 Control Logix / Compact Logix

The logical port PLC1 can only be selected because the tag table is used.

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|---|--|
| Connection Mode | <u>1</u> :1 / Multi-link2 / Multi-link2 (Ethernet) | For multi-link2 and multi-link2 (Ethernet), be sure to use the same tag table. |
| Signal Level | <u>RS-232C</u> / RS-422/485 | |
| Baud Rate | 4800 / 9600 / <u>19200</u> / 38400 / 57600 115k bps | |
| Data Length | <u>8</u> bits | |
| Stop Bit | <u>1</u> / 2 bits | |
| Parity | <u>None</u> / Odd / Even | |
| Target Port No. | <u>0</u> to 31 | |

PLC

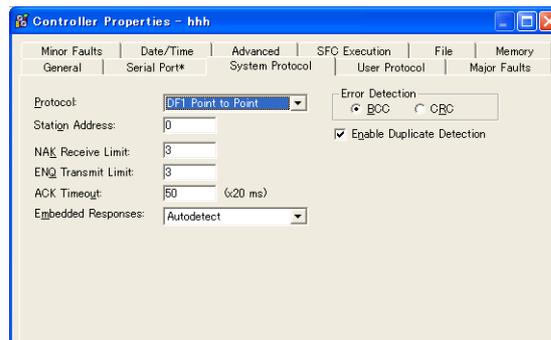
Control Logix

Serial port



| Item | Setting | Remarks |
|--------------|--------------|---------|
| Mode | System | |
| Baud Rate | 38400 | |
| Data Bits | 8 | |
| Parity | None | |
| Stop Bits | 1 | |
| Control Line | No Handshake | |

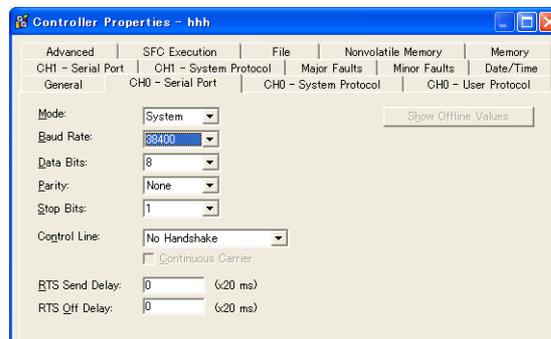
System protocol



| Item | Setting | Remarks |
|----------------------------|--------------------|---------|
| Protocol | DF1 Point to Point | |
| Station Address | 0 | |
| NAK Receive Limit | 3 | |
| ENQ Transmit Limit | 3 | |
| ACK Timeout | 50 | |
| Embedded Responses | Autodetect | |
| Error Detection | BCC | |
| Enable Duplicate Detection | Checked | |

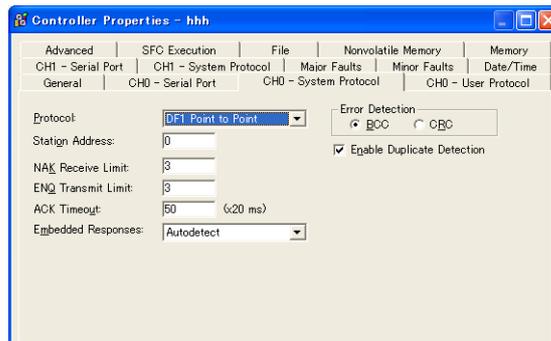
Compact Logix

CH0 - serial port



| Item | Setting | Remarks |
|--------------|--------------|---------|
| Mode | System | |
| Baud Rate | 38400 | |
| Data Bits | 8 | |
| Parity | None | |
| Stop Bits | 1 | |
| Control Line | No Handshake | |

CH0 - system protocol



| Item | Setting | Remarks |
|----------------------------|--------------------|---------|
| Protocol | DF1 Point to Point | |
| Station Address | 0 | |
| NAK Receive Limit | 3 | |
| ENQ Transmit Limit | 3 | |
| ACK Timeout | 50 | |
| Embedded Responses | Autodetect | |
| Error Detection | BCC | |
| Enable Duplicate Detection | Checked | |

Available Device Memory

Create a CSV file by exporting "tag" created by using the ladder tool of the PLC. Then import the CSV file into the editor to set the PLC device memory.

For more information on importing, exporting and creating a tag, refer to "Connection with A*B Control Logix" provided separately.

Indirect Device Memory Designation

Not available

2.1.4 Control Logix (Ethernet)

The logical port PLC1 can only be selected because the tag table is used.

Communication Setting

Editor

Make the following settings on the editor. For more information, see "1.3.2 Ethernet Communication".

- IP address for the V9 unit
 - When specified on the screen program:
[System Setting] → [Hardware Setting] → [Local Port IP Address]
 - When specified on the V9 unit:
Local mode → [LAN Setting]
- Port number for the V9 unit (for communication with PLC)
[System Setting] → [Hardware Setting] → [PLC Properties] → [Communication Setting]
- IP address and port number (No. 44818) of the PLC
Register on the [PLC Table] in [System Setting] → [Hardware Setting] → [PLC Properties] → [Target Settings].

Valid only for 1 : 1 connection

| No. | Port Name | IP Address | Port No. |
|-----|-----------|-------------|----------|
| 0 | | | |
| 1 | PLC | 192.168.1.1 | 44818 |
| 2 | | | |
| 3 | | | |
| 4 | | | |
| 5 | | | |
| 6 | | | |
| 7 | | | |
| 8 | | | |
| 9 | | | |
| 10 | | | |
| 11 | | | |
| 12 | | | |
| 13 | | | |

IP address and port number (No. 44818) of the PLC

- Others
[System Setting] → [Hardware Setting] → [PLC Properties] → [Communication Setting] → [Use CPU Slot No. Setting]
 - [None] (default)
The CPU slot No. is fixed to "0".

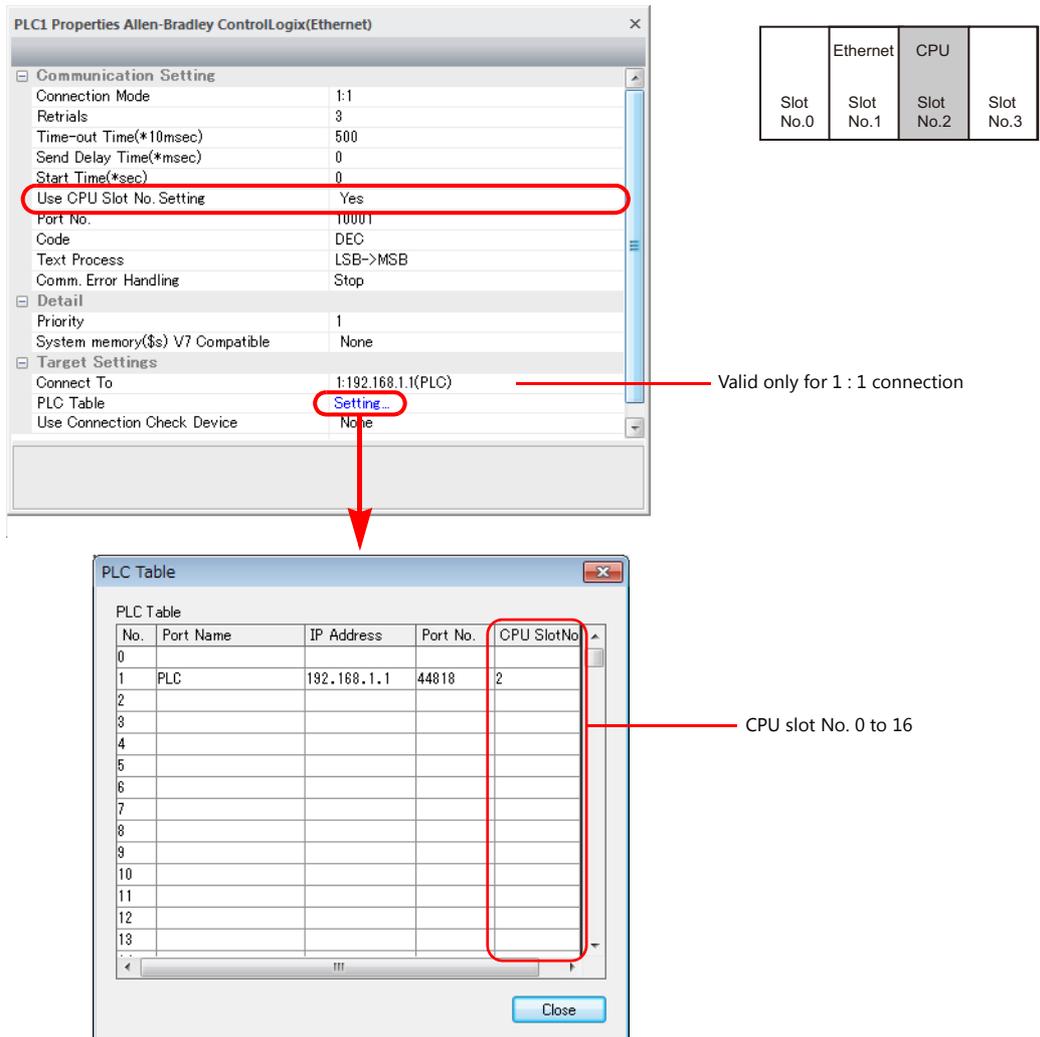
PLC1 Properties Allen-Bradley ControlLogix(Ethernet)

Use CPU Slot No. Setting: None

Connect To: 1:192.168.1.1(PLC)

| CPU | Ethernet | | |
|-----------|-----------|-----------|-----------|
| Slot No.0 | Slot No.1 | Slot No.2 | Slot No.3 |

- [Yes]
Specify the CPU slot number at the [PLC Table] under [Target Settings] on the [PLC Properties] window ([System Setting] → [Hardware Setting]).
Setting range: 0 to 16



| | Ethernet | CPU | |
|-----------|-----------|-----------|-----------|
| Slot No.0 | Slot No.1 | Slot No.2 | Slot No.3 |

Valid only for 1 : 1 connection

CPU slot No. 0 to 16

PLC

Use one of the following utilities to set an IP address. For more information, refer to the PLC manual issued by the manufacturer.

- BOOTP utility
- RSLinx software
- RSLogix 5000 software

Available Device Memory

Create a CSV file by exporting "tag" created by using the ladder tool of the PLC. Then import the CSV file into the editor to set the PLC device memory.

For more information on importing, exporting and creating a tag, refer to "Connection with A*B Control Logix" provided separately.

Indirect Device Memory Designation

Not available

2.1.5 SLC500

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|---|---------|
| Connection Mode | <u>1</u> :1 / 1:n / Multi-link2 / Multi-link2 (Ethernet) / 1:n Multi-link2 (Ethernet) | |
| Signal Level | <u>RS-232C</u> / RS-422/485 | |
| Baud Rate | 4800 / 9600 / <u>19200</u> / 38400 bps | |
| Data Length | 7 / <u>8</u> bits | |
| Stop Bit | <u>1</u> / 2 bits | |
| Parity | None / <u>Even</u> | |
| Target Port No. | <u>0</u> to 31 | |

PLC

Channel 0

Channel configuration (chan. 0 - system)

Channel Configuration

General | Chan. 1 - System | Chan. 0 - System | Chan. 0 - User

Driver: DF1 Full Duplex | Source ID: 9 (decimal)

Baud: 19200

Parity: NONE

Stop Bits: 1

Protocol Control:

Control Line: No Handshaking | ACK Timeout (x20 ms): 50

Error Detection: BCC

Embedded Responses: Auto Detect

Duplicate Packet Detect

NAK Retries: 3

ENQ Retries: 3

(Underlined setting: default)

| Item | Setting | Remarks |
|-------------------------|------------------------|---------|
| Driver | DF1 Full Duplex | |
| Baud | 9600 / 19200 / 38400 | |
| Parity | <u>None</u> / Even | |
| Stop Bits | <u>1</u> / 2 | |
| Control Line | No Handshaking | |
| Error Detection | BCC | |
| Embedded Responses | Auto Detect | |
| Duplicate Packet Detect | Checked | |

1747-KE**Jumper JW2**

| Item | Setting | Remarks |
|--------|---|---------|
| RS-232 |  | |
| RS-422 |  | |

DF1 port setup menu

| Item | Setting | Remarks |
|--------------------|---------|---------|
| Baudrate | 19200 | |
| Bits Per Character | 8 | |
| Parity | Even | |
| Stop Bits | 1 | |

DF1 full-duplex setup menu

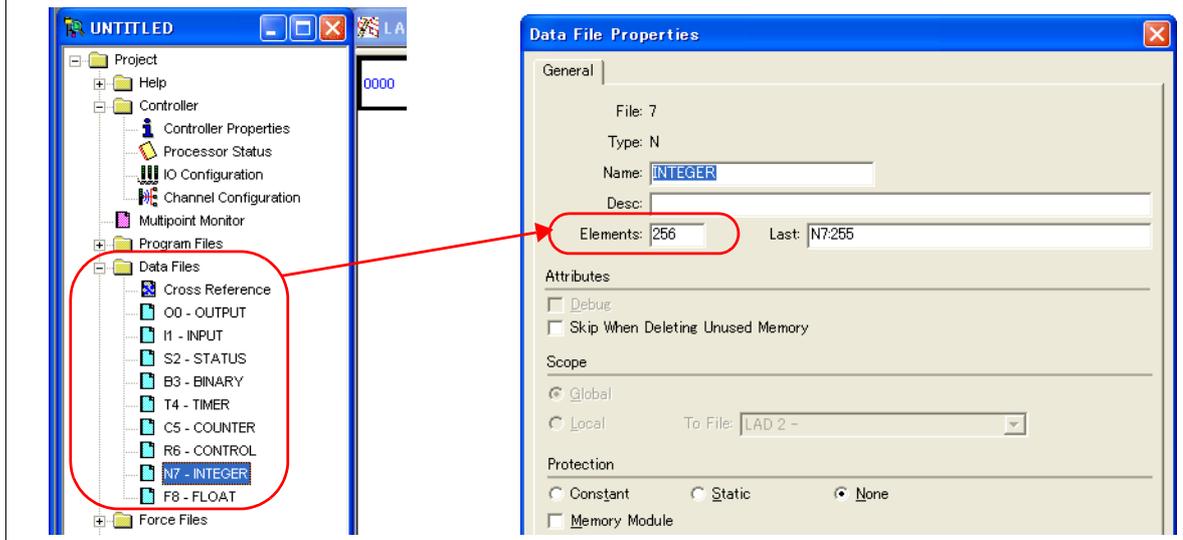
| Item | Setting | Remarks |
|----------------------------|-------------|---------|
| Duplicate Packet Detection | Enabled | |
| Checksum | BCC | |
| Constant Carrier Detect | Disabled | |
| Message Timeout | 400 | |
| Hardware Handshaking | Disabled | |
| Embedded Response Detect | Auto Detect | |
| ACK Timeout (× 5 ms) | 90 | |
| ENQuiry Retries | 3 | |
| NAK Received Retries | 3 | |

Available Device Memory

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|--------------------------------|------|-------------|
| N (integer) | 00H | |
| B (bit) | 01H | |
| T. ACC (timer/current value) | 02H | |
| T. PRE (timer/set value) | 03H | |
| C. ACC (counter/current value) | 04H | |
| C. PRE (counter/set value) | 05H | |
| I (input) | 06H | |
| O (output) | 07H | |
| S (status) | 08H | |
| T (timer/control) | 09H | |
| C (counter/control) | 0AH | |
| R (control) | 0BH | |
| R. LEN (control/data length) | 0CH | |
| R. POS (control/data position) | 0DH | |
| D (BCD) | 0EH | |
| A (ASCII) | 0FH | |
| F (FLOAT) | 10H | Real number |
| ST (STRING) | 11H | |

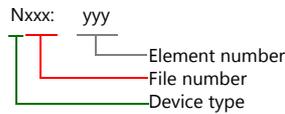
Make settings for "Data Files" using the ladder tool. Otherwise, "Error Code 10 00" is displayed on MONITOUCH. For more information, refer to the PLC manual issued by the manufacturer.



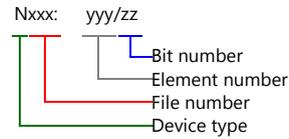
Address denotations

The assigned device memory is expressed as shown below when editing the screen.

- Address other than input/output
- For word access

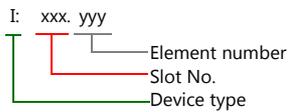


For bit access

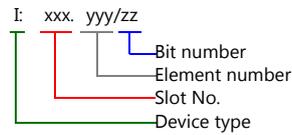


The file number will not be displayed for the input, output or status device memory.

- Input/output address
- For word access



For bit access



Indirect Device Memory Designation

- For the file or slot numbers 0 to 65:

| | 15 | MSB | 8 | 7 | LSB | 0 |
|-------|-------------|-----|---|-----------------|-----|---|
| n + 0 | Model | | | Device type | | |
| n + 1 | Address No. | | | | | |
| n + 2 | 00 | | | Bit designation | | |
| n + 3 | 00 | | | Station number | | |

- For the file or slot numbers 66 to 255:

| | 15 | MSB | 8 | 7 | LSB | 0 |
|-------|--------------------|-----|---|-----------------|-----|---|
| n + 0 | Model | | | Device type | | |
| n + 1 | Lower address No. | | | | | |
| n + 2 | Higher address No. | | | | | |
| n + 3 | 00 | | | Bit designation | | |
| n + 4 | 00 | | | Station number | | |

- Specify the file number or slot number and the element number for the address number.

Example: When specifying N007:123
Specify "7123" (DEC) for the address number.

Example: When specifying N120:123
Specify "120123" (DEC) for the address number.
120123 (DEC) is equivalent to 1D53B (HEX). Specify "D53B (HEX)" for the lower address number and "0001" for the upper address number.

- When specifying an address for the timer (control), counter (control) or control device memory in bit designation, specify the bit number in decimal notation as shown below:

- T: Timer (control)
DN = 13, TT = 14, EN = 15
- C: Counter (control)
UA = 10, UN = 11, OV = 12, DN = 13, CD = 14, CU = 15
- R: Control
FD = 08, IN = 09, UL = 10, ER = 11, EM = 12, DN = 13, EU = 14, EN = 15

2.1.6 SLC500 (Ethernet TCP/IP)

Communication Setting

Editor

Make the following settings on the editor. For more information, see "1.3.2 Ethernet Communication".

- IP address for the V9 unit
 - When specified on the screen program:
[System Setting] → [Hardware Setting] → [Local Port IP Address]
 - When specified on the V9 unit:
Local mode → [LAN Setting]
- Port number for the V9 unit (for communication with PLC)
[System Setting] → [Hardware Setting] → [PLC Properties] → [Communication Setting]
- IP address and port number (No. 44818) of the PLC
Register on the [PLC Table] in [System Setting] → [Hardware Setting] → [PLC Properties] → [Target Settings].

PLC

Channel 1

Channel configuration (channel 1)

The screenshot shows the 'Channel Configuration' dialog box with the 'Channel 1' tab selected. The 'Driver' is set to 'Ethernet'. The 'Hardware Address' is 000F:73:01:07:FD. The 'IP Address' is 10.91.131.188, 'Subnet Mask' is 255.255.255.0, and 'Gateway Address' is 10.91.131.1. The 'DHRIO Link ID' is 0. Under 'Protocol Control', 'HTTP Server Enable' and 'Auto Negotiate' are checked. 'Msg Connection Timeout (< 1mS):' is 15000 and 'Msg Reply Timeout (< 1mS):' is 3000. 'Port Setting' is 10/100 Mbps Full Duplex/Half Duplex. 'Contact' and 'Location' fields are empty.

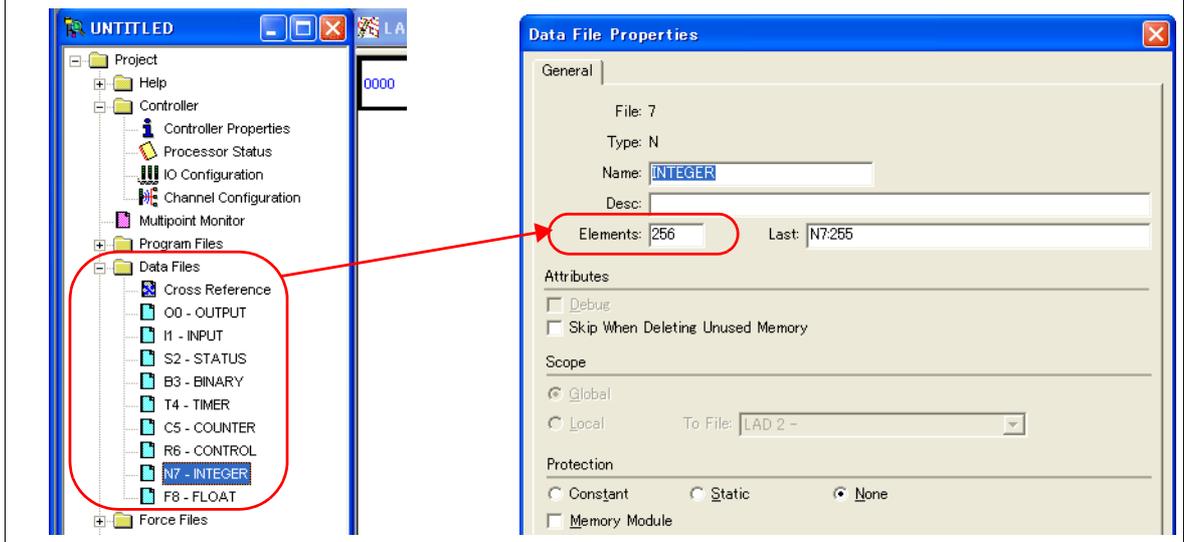
| Item | Setting | Remarks |
|-----------------|---|---------|
| Driver | Ethernet | |
| IP Address | PLC's IP address | |
| Subnet Mask | PLC's subnet mask | |
| Gateway Address | Make settings in accordance with the network environment. | |

Available Device Memory

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|--------------------------------|------|-------------|
| N (integer) | 00H | |
| B (bit) | 01H | |
| T. ACC (timer/current value) | 02H | |
| T. PRE (timer/set value) | 03H | |
| C. ACC (counter/current value) | 04H | |
| C. PRE (counter/set value) | 05H | |
| I (input) | 06H | |
| O (output) | 07H | |
| S (status) | 08H | |
| T (timer/control) | 09H | |
| C (counter/control) | 0AH | |
| R (control) | 0BH | |
| R. LEN (control/data length) | 0CH | |
| R. POS (control/data position) | 0DH | |
| A (ASCII) | 0FH | |
| F (FLOAT) | 10H | Real number |
| ST (STRING) | 11H | |

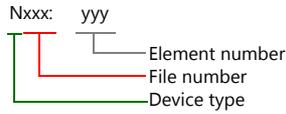
Make settings for "Data Files" using the ladder tool. Otherwise, "Error Code 10 00" is displayed on MONITOUCH. For more information, refer to the PLC manual issued by the manufacturer.



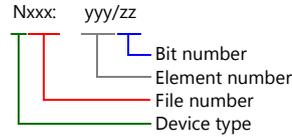
Address denotations

The assigned device memory is expressed as shown below when editing the screen.

- Address other than input/output
 - For word access

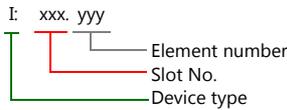


For bit access

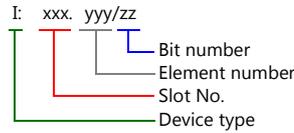


The file number will not be displayed for the input, output or status device memory.

- Input/output address
 - For word access



For bit access



Indirect Device Memory Designation

- For the file or slot numbers 0 to 65:

| | | | | | | |
|-------|-------------|-----|-----------------|-------------|-----|---|
| | 15 | MSB | 8 | 7 | LSB | 0 |
| n + 0 | Model | | | Device type | | |
| n + 1 | Address No. | | | | | |
| n + 2 | 00 | | Bit designation | | | |
| n + 3 | 00 | | Station number | | | |

- For the file or slot numbers 66 to 255:

| | | | | | | |
|-------|--------------------|-----|-----------------|-------------|-----|---|
| | 15 | MSB | 8 | 7 | LSB | 0 |
| n + 0 | Model | | | Device type | | |
| n + 1 | Lower address No. | | | | | |
| n + 2 | Higher address No. | | | | | |
| n + 3 | 00 | | Bit designation | | | |
| n + 4 | 00 | | Station number | | | |

- Specify the file number or slot number and the element number for the address number.

Example: When specifying N007:123
Specify "7123" (DEC) for the address number.

Example: When specifying N120:123
Specify "120123" (DEC) for the address number.
120123 (DEC) is equivalent to 1D53B (HEX). Specify "D53B (HEX)" for the lower address number and "0001" for the upper address number.

- When specifying an address for the timer (control), counter (control) or control device memory in bit designation, specify the bit number in decimal notation as shown below:

- T: Timer (control)
DN = 13, TT = 14, EN = 15
- C: Counter (control)
UA = 10, UN = 11, OV = 12, DN = 13, CD = 14, CU = 15
- R: Control
FD = 08, IN = 09, UL = 10, ER = 11, EM = 12, DN = 13, EU = 14, EN = 15

2.1.7 Micro Logix

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|---|---------|
| Connection Mode | <u>1</u> :1 / 1 : n / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet) | |
| Signal Level | <u>RS-232C</u> / RS-422/485 | |
| Baud Rate | 4800 / <u>9600</u> / 19200 / 38400 bps | |
| Data Length | 7 / <u>8</u> bits | |
| Stop Bit | 1 bit | |
| Parity | <u>None</u> / Even | |
| Target Port No. | <u>0</u> to 31 | |

PLC

Channel Configuration

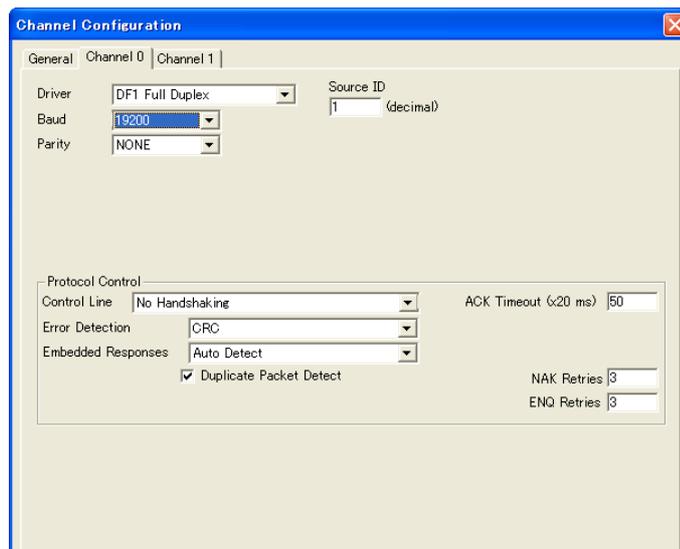
Micro Logix 1000



(Underlined setting: default)

| Item | Setting | Remarks |
|------|------------------------------------|---------|
| Baud | 4800 / <u>9600</u> / 19200 / 38.4K | |

Micro Logix 1100, 1500



(Underlined setting: default)

| Item | Setting | Remarks |
|-----------|-------------------------|------------------------------------|
| Channel 0 | Driver | DF1 Full Duplex |
| | Baud | 4800 / 9600 / <u>19200</u> / 38.4K |
| | Parity | <u>None</u> / Even |
| | Control Line | No Handshaking |
| | Error Detection | BCC |
| | Embedded Responses | Auto Detect |
| | Duplicate Packet Detect | Checked |

Calendar

This model is not equipped with the calendar function. Use the built-in clock of the V series.

Available Device Memory

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|--------------------------------|------|-------------|
| N (integer) | 00H | |
| B (bit) | 01H | |
| T. ACC (timer/current value) | 02H | |
| T. PRE (timer/set value) | 03H | |
| C. ACC (counter/current value) | 04H | |
| C. PRE (counter/set value) | 05H | |
| I (input) | 06H | |
| O (output) | 07H | |
| S (status) | 08H | |
| T (timer/control) | 09H | |
| C (counter/control) | 0AH | |
| R (control) | 0BH | |
| R. LEN (control/data length) | 0CH | |
| R. POS (control/data position) | 0DH | |
| D (BCD) | 0EH | |
| A (ASCII) | 0FH | |
| F (FLOAT) | 10H | Real number |
| ST (STRING) | 11H | |
| L (LONG) | 12H | Double-word |

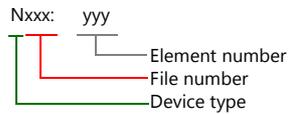
Make settings for "Data Files" using the ladder tool. Otherwise, "Error Code 10 00" is displayed on MONITOUCH. For more information, refer to the PLC manual issued by the manufacturer.

The screenshot shows the 'ML1100.RSS' software interface. On the left, the 'Data Files' folder is expanded and circled in red. A red arrow points from this folder to the 'Data File Properties' dialog box on the right. In the dialog box, the 'Elements' field is circled in red and set to 256. The 'Last' field is set to N7:255. The 'Name' field is set to INTEGER. The 'Type' is set to N. The 'Scope' is set to Global. The 'Protection' is set to None. The 'Memory Module / Download' checkbox is checked.

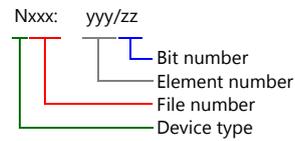
Address denotations

The assigned device memory is expressed as shown below when editing the screen.

- Address other than input/output
- For word access

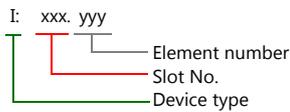


For bit access

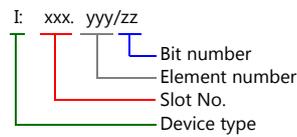


The file number will not be displayed for the input, output or status device memory.

- Input/output address
- For word access



For bit access



Indirect Device Memory Designation

- For the file or slot numbers 0 to 65:

| | 15 | MSB | 8 | 7 | LSB | 0 |
|-------|-------------|-----|-----------------|---|-----|---|
| n + 0 | Model | | Device type | | | |
| n + 1 | Address No. | | | | | |
| n + 2 | 00 | | Bit designation | | | |
| n + 3 | 00 | | Station number | | | |

- For the file or slot numbers 66 to 255:

| | 15 | MSB | 8 | 7 | LSB | 0 |
|-------|--------------------|-----|-----------------|---|-----|---|
| n + 0 | Model | | Device type | | | |
| n + 1 | Lower address No. | | | | | |
| n + 2 | Higher address No. | | | | | |
| n + 3 | 00 | | Bit designation | | | |
| n + 4 | 00 | | Station number | | | |

- Specify the file number or slot number and the element number for the address number.

Example: When specifying `N007:123`
Specify "7123" (DEC) for the address number.

Example: When specifying `N120:123`
Specify "120123" (DEC) for the address number.
120123 (DEC) is equivalent to 1D53B (HEX). Specify "D53B (HEX)" for the lower address number and "0001" for the upper address number.

- When specifying an address for the timer (control), counter (control) or control device memory in bit designation, specify the bit number in decimal notation as shown below:

- T: Timer (control)
DN = 13, TT = 14, EN = 15
- C: Counter (control)
UA = 10, UN = 11, OV = 12, DN = 13, CD = 14, CU = 15
- R: Control
FD = 08, IN = 09, UL = 10, ER = 11, EM = 12, DN = 13, EU = 14, EN = 15

2.1.8 Micro Logix (Ethernet TCP/IP)

Communication Setting

Editor

Make the following settings on the editor. For more information, see "1.3.2 Ethernet Communication".

- IP address for the V9 unit
 - When specified on the screen program:
[System Setting] → [Hardware Setting] → [Local Port IP Address]
 - When specified on the V9 unit:
Local mode → [LAN Setting]
- Port number for the V9 unit (for communication with PLC)
[System Setting] → [Hardware Setting] → [PLC Properties] → [Communication Setting]
- IP address and port number (No. 44818) of the PLC
Register on the [PLC Table] in [System Setting] → [Hardware Setting] → [PLC Properties] → [Target Settings].

PLC

Channel 1

Channel configuration (channel 1)

The screenshot shows the 'Channel Configuration' dialog box with the following settings:

- Driver: Ethernet
- Hardware Address: 000F:73:01:07:FD
- DHRIO Link ID: 0
- IP Address: 10 91 131 188
- Subnet Mask: 255 255 255 0
- Gateway Address: 10 91 131 1
- Default Domain Name: (empty)
- Primary Name Server: 0 0 0 0
- Secondary Name Server: 0 0 0 0
- Protocol Control:
 - Bootp Enable
 - DHCP Enable
 - SNMP Server Enable
 - HTTP Server Enable
 - Auto Negotiate
 - Msg Connection Timeout (< 1mS): 15000
 - Msg Reply Timeout (< 1mS): 3000
 - Port Setting: 10/100 Mbps Full Duplex/Half Duplex
- Contact: (empty)
- Location: (empty)

| Item | Setting | Remarks |
|-----------------|---|---------|
| Driver | Ethernet | |
| IP Address | PLC's IP address | |
| Subnet Mask | PLC's subnet mask | |
| Gateway Address | Make settings in accordance with the network environment. | |

Calendar

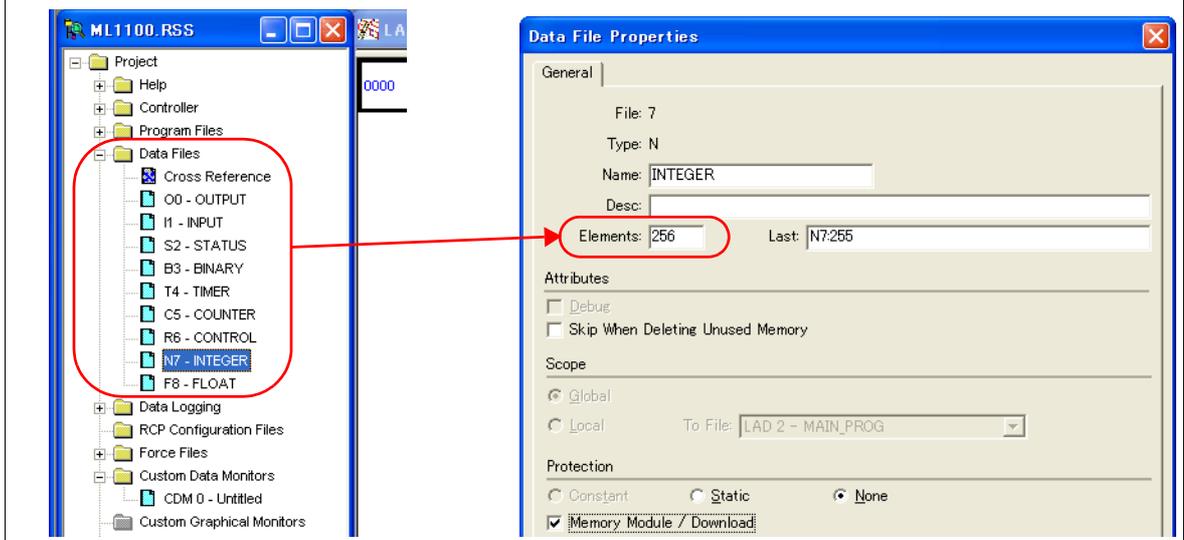
This model is not equipped with the calendar function. Use the built-in clock of the V series.

Available Device Memory

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|--------------------------------|------|-------------|
| N (integer) | 00H | |
| B (bit) | 01H | |
| T. ACC (timer/current value) | 02H | |
| T. PRE (timer/set value) | 03H | |
| C. ACC (counter/current value) | 04H | |
| C. PRE (counter/set value) | 05H | |
| I (input) | 06H | |
| O (output) | 07H | |
| S (status) | 08H | |
| T (timer/control) | 09H | |
| C (counter/control) | 0AH | |
| R (control) | 0BH | |
| R. LEN (control/data length) | 0CH | |
| R. POS (control/data position) | 0DH | |
| A (ASCII) | 0FH | |
| F (FLOAT) | 10H | Real number |
| ST (STRING) | 11H | |
| L (LONG) | 12H | Double-word |

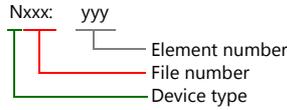
Make settings for "Data Files" using the ladder tool. Otherwise, "Error Code 10 00" is displayed on MONITOUCH. For more information, refer to the PLC manual issued by the manufacturer.



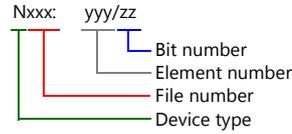
Address denotations

The assigned device memory is expressed as shown below when editing the screen.

- Address other than input/output
- For word access

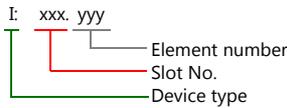


For bit access

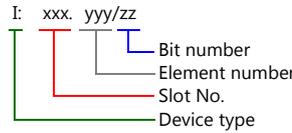


The file number will not be displayed for the input, output or status device memory.

- Input/output address
- For word access



For bit access



Indirect Device Memory Designation

- For the file or slot numbers 0 to 65:

| | | | | | | |
|-------|-------------|-----|-----------------|-------------|-----|---|
| | 15 | MSB | 8 | 7 | LSB | 0 |
| n + 0 | Model | | | Device type | | |
| n + 1 | Address No. | | | | | |
| n + 2 | 00 | | Bit designation | | | |
| n + 3 | 00 | | Station number | | | |

- For the file or slot numbers 66 to 255:

| | | | | | | |
|-------|--------------------|-----|-----------------|-------------|-----|---|
| | 15 | MSB | 8 | 7 | LSB | 0 |
| n + 0 | Model | | | Device type | | |
| n + 1 | Lower address No. | | | | | |
| n + 2 | Higher address No. | | | | | |
| n + 3 | 00 | | Bit designation | | | |
| n + 4 | 00 | | Station number | | | |

- Specify the file number or slot number and the element number for the address number.

Example: When specifying N007:123
 Specify "7123" (DEC) for the address number.

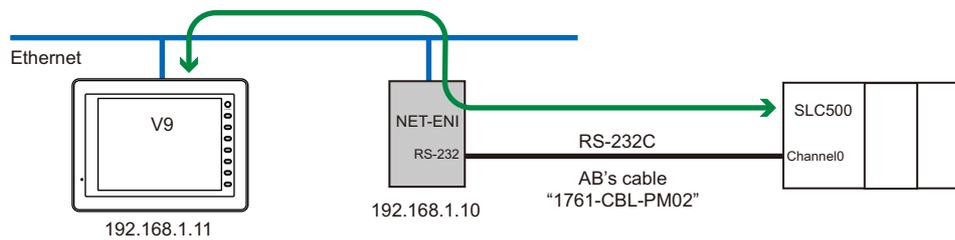
Example: When specifying N120:123
 Specify "120123" (DEC) for the address number.
 120123 (DEC) is equivalent to 1D53B (HEX). Specify "D53B (HEX)" for the lower address number and "0001" for the upper address number.

- When specifying an address for the timer (control), counter (control) or control device memory in bit designation, specify the bit number in decimal notation as shown below:

- T: Timer (control)
 DN = 13, TT = 14, EN = 15
- C: Counter (control)
 UA = 10, UN = 11, OV = 12, DN = 13, CD = 14, CU = 15
- R: Control
 FD = 08, IN = 09, UL = 10, ER = 11, EM = 12, DN = 13, EU = 14, EN = 15

2.1.9 NET-ENI (SLC500 Ethernet TCP/IP)

The V9 series establishes communication with SLC500 via NET-ENI.



Communication Setting

Editor

Make the following settings on the editor. For more information, see "1.3.2 Ethernet Communication".

- IP address for the V9 unit
 - When specified on the screen program:
[System Setting] → [Hardware Setting] → [Local Port IP Address]
 - When specified on the V9 unit:
Local mode → [LAN Setting]
- Port number for the V9 unit (for communication with PLC)
[System Setting] → [Hardware Setting] → [PLC Properties] → [Communication Setting]
- IP address and port number (No. 44818) of the PLC
Register on the [PLC Table] in [System Setting] → [Hardware Setting] → [PLC Properties] → [Target Settings].

PLC

NET-ENI / NET-ENIW

ENI / ENIW utility

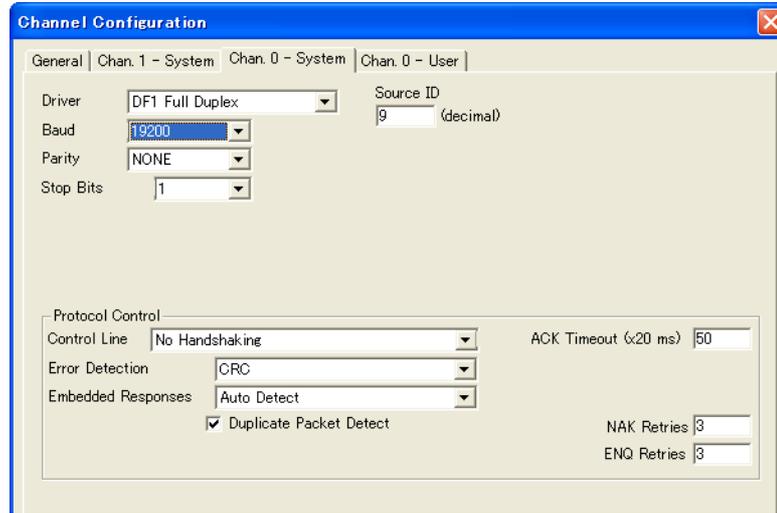
The screenshot shows the 'ENI / ENIW Utility' window. The 'Utility Settings' tab is selected. The 'ENI Series' is set to 'D'. The '232 Baud Rate' is set to 'Auto'. The 'CompactLogix Routing' checkbox is unchecked. The 'ENI IP Address' is set to 192.168.001.010, 'Subnet Mask' is 255.255.255.000, and 'Gateway' is 192.168.001.001. The 'Ethernet Speed/Duplex' is set to 'Auto Negotiate'. The 'Security Mask 1' and 'Security Mask 2' are both set to 000.000.000.000. The 'Device Values' section shows 'File Load' and 'File Save' buttons, with 'ENI' and 'ENI RQM' buttons highlighted.

| Item | Setting | Remarks |
|-------------|----------------|---|
| ENI IP Addr | 232 Baud Rate | Auto |
| | ENI IP Address | Set the IP address of NET-ENI. |
| | Subnet Mask | Set the subnet mask of NET-ENI. |
| | Gateway | Make settings in accordance with the network environment. |

Press [ENI RQM] to save the settings.

SLC500

Channel configuration



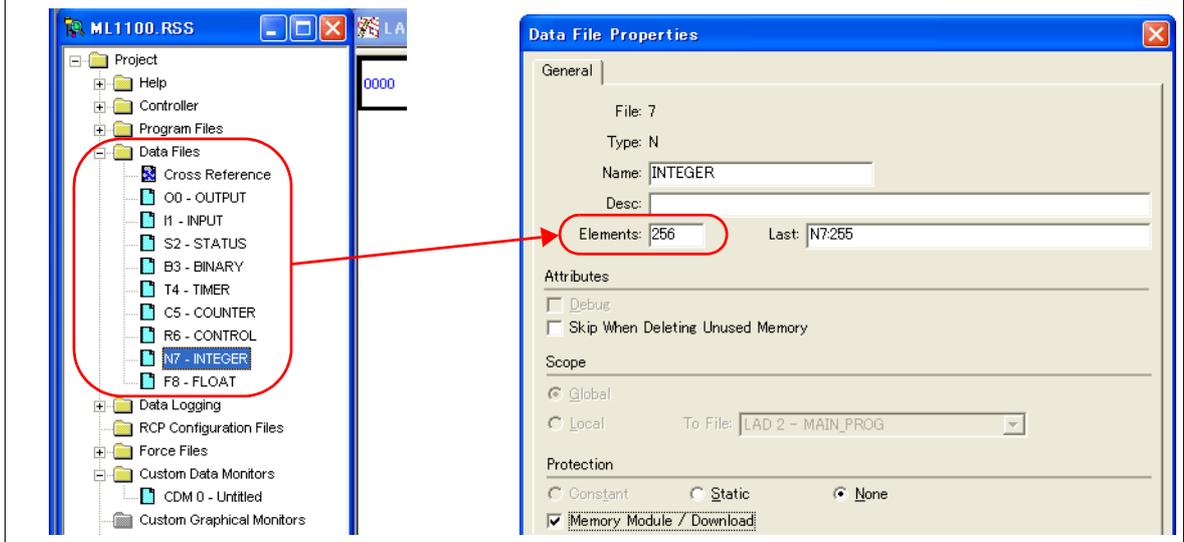
| Item | Setting | Remarks | |
|------------------|-------------------------|------------------------|--|
| Chan. 0 - System | Driver | DF1 Full Duplex | |
| | Baud | 9600 / 19200 / 38400 | |
| | Parity | NONE | |
| | Stop Bits | 1 | |
| | Control Line | No Handshaking | |
| | Error Detection | CRC | |
| | Embedded Responses | Auto Detect | |
| | Duplicate Packet Detect | Checked | |

Available Device Memory

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|--------------------------------|------|-------------|
| N (integer) | 00H | |
| B (bit) | 01H | |
| T. ACC (timer/current value) | 02H | |
| T. PRE (timer/set value) | 03H | |
| C. ACC (counter/current value) | 04H | |
| C. PRE (counter/set value) | 05H | |
| I (input) | 06H | |
| O (output) | 07H | |
| S (status) | 08H | |
| T (timer/control) | 09H | |
| C (counter/control) | 0AH | |
| R (control) | 0BH | |
| R. LEN (control/data length) | 0CH | |
| R. POS (control/data position) | 0DH | |
| A (ASCII) | 0FH | |
| F (FLOAT) | 10H | Real number |
| ST (STRING) | 11H | |

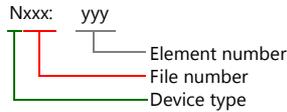
Make settings for "Data Files" using the ladder tool. Otherwise, "Error Code 10 00" is displayed on MONITOUCH. For more information, refer to the PLC manual issued by the manufacturer.



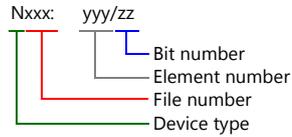
Address denotations

The assigned device memory is expressed as shown below when editing the screen.

- Address other than input/output
 - For word access

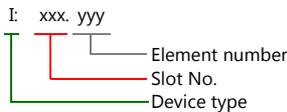


For bit access

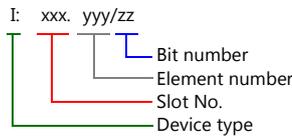


The file number will not be displayed for the input, output or status device memory.

- Input/output address
 - For word access



For bit access



Indirect Device Memory Designation

- For the file or slot numbers 0 to 65:

| | | | | | | |
|-------|-------------|-----|-----------------|---|-----|---|
| | 15 | MSB | 8 | 7 | LSB | 0 |
| n + 0 | Model | | Device type | | | |
| n + 1 | Address No. | | | | | |
| n + 2 | 00 | | Bit designation | | | |
| n + 3 | 00 | | Station number | | | |

- For the file or slot numbers 66 to 255:

| | | | | | | |
|-------|--------------------|-----|-----------------|---|-----|---|
| | 15 | MSB | 8 | 7 | LSB | 0 |
| n + 0 | Model | | Device type | | | |
| n + 1 | Lower address No. | | | | | |
| n + 2 | Higher address No. | | | | | |
| n + 3 | 00 | | Bit designation | | | |
| n + 4 | 00 | | Station number | | | |

- Specify the file number or slot number and the element number for the address number.

Example: When specifying N007:123
Specify "7123" (DEC) for the address number.

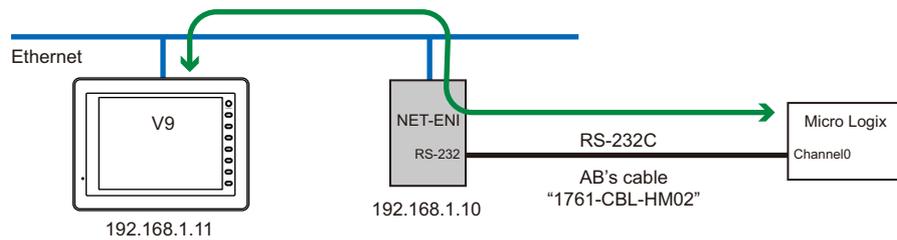
Example: When specifying N120:123
Specify "120123" (DEC) for the address number.
120123 (DEC) is equivalent to 1D53B (HEX). Specify "D53B (HEX)" for the lower address number and "0001" for the upper address number.

- When specifying an address for the timer (control), counter (control) or control device memory in bit designation, specify the bit number in decimal notation as shown below:

- T: Timer (control)
DN = 13, TT = 14, EN = 15
- C: Counter (control)
UA = 10, UN = 11, OV = 12, DN = 13, CD = 14, CU = 15
- R: Control
FD = 08, IN = 09, UL = 10, ER = 11, EM = 12, DN = 13, EU = 14, EN = 15

2.1.10 NET-ENI (MicroLogix Ethernet TCP/IP)

The V9 series establishes communication with MicroLogix via NET-ENI.



Communication Setting

Editor

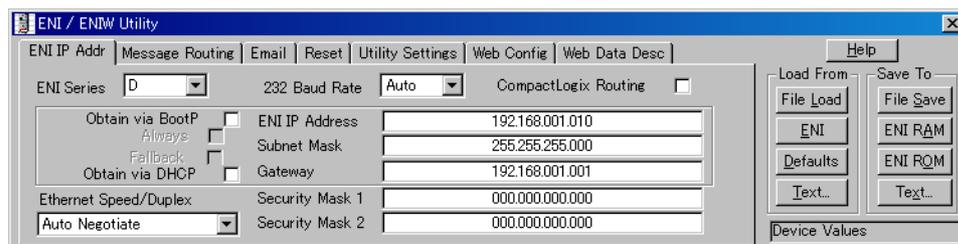
Make the following settings on the editor. For more information, see "1.3.2 Ethernet Communication".

- IP address for the V9 unit
 - When specified on the screen program:
[System Setting] → [Hardware Setting] → [Local Port IP Address]
 - When specified on the V9 unit:
Local mode → [LAN Setting]
- Port number for the V9 unit (for communication with PLC)
[System Setting] → [Hardware Setting] → [PLC Properties] → [Communication Setting]
- IP address and port number (No. 44818) of the PLC
Register on the [PLC Table] in [System Setting] → [Hardware Setting] → [PLC Properties] → [Target Settings].

PLC

NET-ENI / NET-ENIW

ENI / ENIW utility



| Item | Setting | Remarks | |
|-------------|----------------|---|--|
| ENI IP Addr | 232 Baud Rate | Auto | |
| | ENI IP Address | Set the IP address of NET-ENI. | |
| | Subnet Mask | Set the subnet mask of NET-ENI. | |
| | Gateway | Make settings in accordance with the network environment. | |

Press [ENI RQM] to save the settings.

MicroLogix

Channel Configuration

The screenshot shows the 'Channel Configuration' dialog box with the 'Channel 0' tab selected. The settings are as follows:

- Driver: DF1 Full Duplex
- Baud: 19200
- Parity: NONE
- Source ID: 1 (decimal)
- Control Line: No Handshaking
- Error Detection: CRC
- Embedded Responses: Auto Detect
- Duplicate Packet Detect
- ACK Timeout (x20 ms): 50
- NAK Retries: 3
- ENQ Retries: 3

(Underlined setting: default)

| Item | Setting | Remarks | |
|---------|-------------------------|------------------------------------|--|
| Chan. 0 | Driver | DF1 Full Duplex | |
| | Baud | 4800 / 9600 / <u>19200</u> / 38.4K | |
| | Parity | NONE | |
| | Control Line | No Handshaking | |
| | Error Detection | CRC | |
| | Embedded Responses | Auto Detect | |
| | Duplicate Packet Detect | Checked | |

Calendar

This model is not equipped with the calendar function. Use the built-in clock of the V series.

Available Device Memory

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|--------------------------------|------|-------------|
| N (integer) | 00H | |
| B (bit) | 01H | |
| T. ACC (timer/current value) | 02H | |
| T. PRE (timer/set value) | 03H | |
| C. ACC (counter/current value) | 04H | |
| C. PRE (counter/set value) | 05H | |
| I (input) | 06H | |
| O (output) | 07H | |
| S (status) | 08H | |
| T (timer/control) | 09H | |
| C (counter/control) | 0AH | |
| R (control) | 0BH | |
| R. LEN (control/data length) | 0CH | |
| R. POS (control/data position) | 0DH | |
| A (ASCII) | 0FH | |
| F (FLOAT) | 10H | Real number |
| ST (STRING) | 11H | |
| L (LONG) | 12H | Double-word |

Make settings for "Data Files" using the ladder tool. Otherwise, "Error Code 10 00" is displayed on MONITOUCH. For more information, refer to the PLC manual issued by the manufacturer.

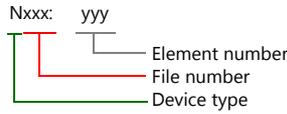
The screenshot shows the ML1100.RSS software interface. On the left, the 'Data Files' folder is selected in the project tree, and the 'Data File Properties' dialog box is open on the right. The dialog box has the following settings:

- File: 7
- Type: N
- Name: INTEGER
- Desc: (empty)
- Elements: 256 (highlighted with a red circle)
- Last: N7:255
- Attributes:
 - Debug
 - Skip When Deleting Unused Memory
- Scope:
 - Global
 - Local
 - To File: LAD 2 - MAIN_PROG
- Protection:
 - Constant
 - Static
 - None
- Memory Module / Download

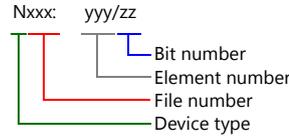
Address denotations

The assigned device memory is expressed as shown below when editing the screen.

- Address other than input/output
 - For word access

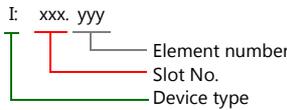


For bit access

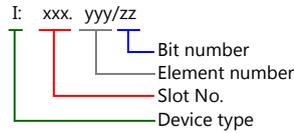


The file number will not be displayed for the input, output or status device memory.

- Input/output address
 - For word access



For bit access



Indirect Device Memory Designation

- For the file or slot numbers 0 to 65:

| | | | | | | |
|-------|-------------|-----|-----------------|-------------|-----|---|
| | 15 | MSB | 8 | 7 | LSB | 0 |
| n + 0 | Model | | | Device type | | |
| n + 1 | Address No. | | | | | |
| n + 2 | 00 | | Bit designation | | | |
| n + 3 | 00 | | Station number | | | |

- For the file or slot numbers 66 to 255:

| | | | | | | |
|-------|--------------------|-----|-----------------|-------------|-----|---|
| | 15 | MSB | 8 | 7 | LSB | 0 |
| n + 0 | Model | | | Device type | | |
| n + 1 | Lower address No. | | | | | |
| n + 2 | Higher address No. | | | | | |
| n + 3 | 00 | | Bit designation | | | |
| n + 4 | 00 | | Station number | | | |

- Specify the file number or slot number and the element number for the address number.

Example: When specifying N007:123
Specify "7123" (DEC) for the address number.

Example: When specifying N120:123
Specify "120123" (DEC) for the address number.
120123 (DEC) is equivalent to 1D53B (HEX). Specify "D53B (HEX)" for the lower address number and "0001" for the upper address number.

- When specifying an address for the timer (control), counter (control) or control device memory in bit designation, specify the bit number in decimal notation as shown below:

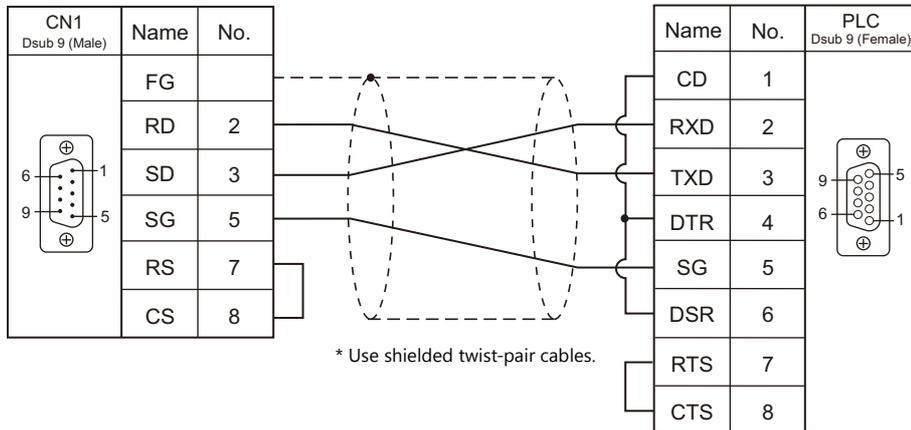
- T: Timer (control)
DN = 13, TT = 14, EN = 15
- C: Counter (control)
UA = 10, UN = 11, OV = 12, DN = 13, CD = 14, CU = 15
- R: Control
FD = 08, IN = 09, UL = 10, ER = 11, EM = 12, DN = 13, EU = 14, EN = 15

2.1.11 Wiring Diagrams

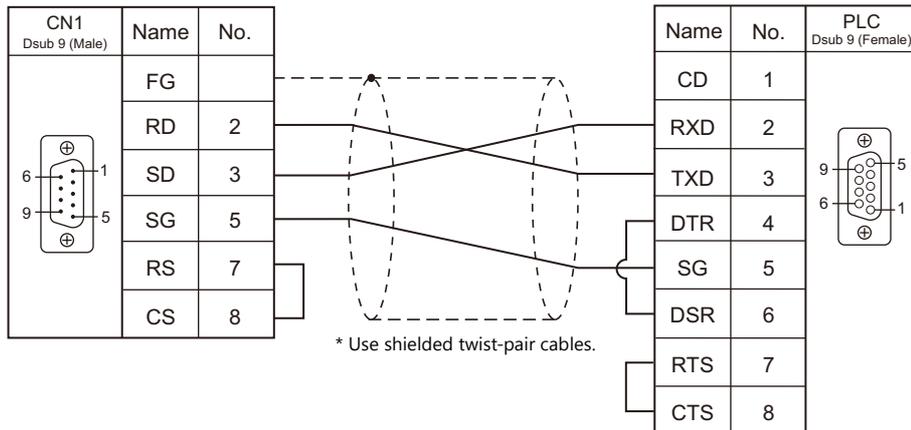
When Connected at CN1:

RS-232C

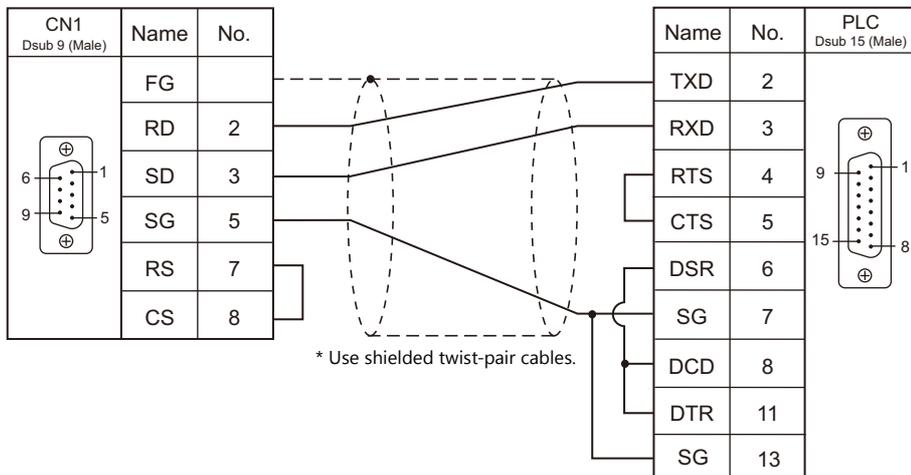
Wiring diagram 1 - C2



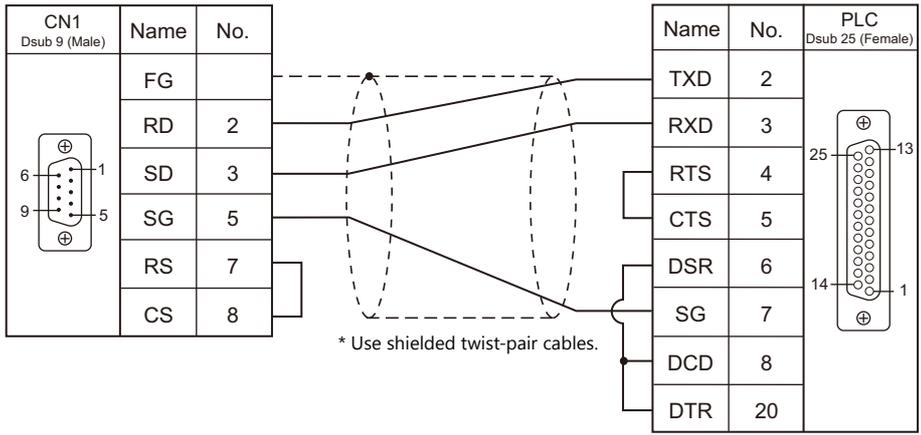
Wiring diagram 2 - C2



Wiring diagram 3 - C2

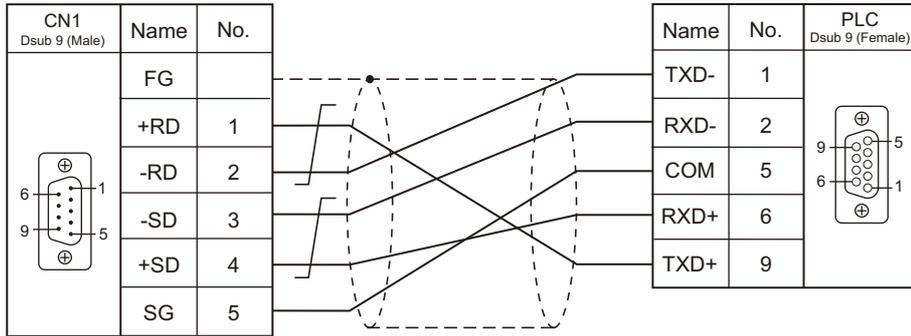


Wiring diagram 4 - C2



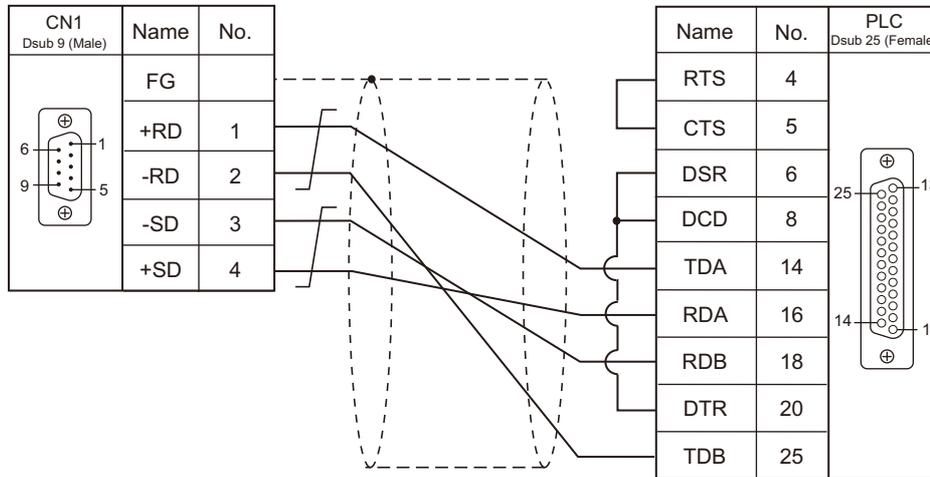
RS-422/RS-485

Wiring diagram 1 - C4



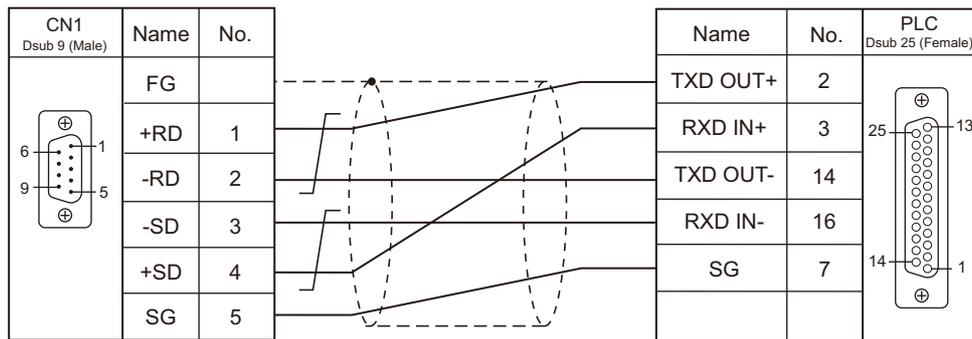
* Use shielded twist-pair cables.

Wiring diagram 2 - C4



* Use shielded twist-pair cables.

Wiring diagram 3 - C4

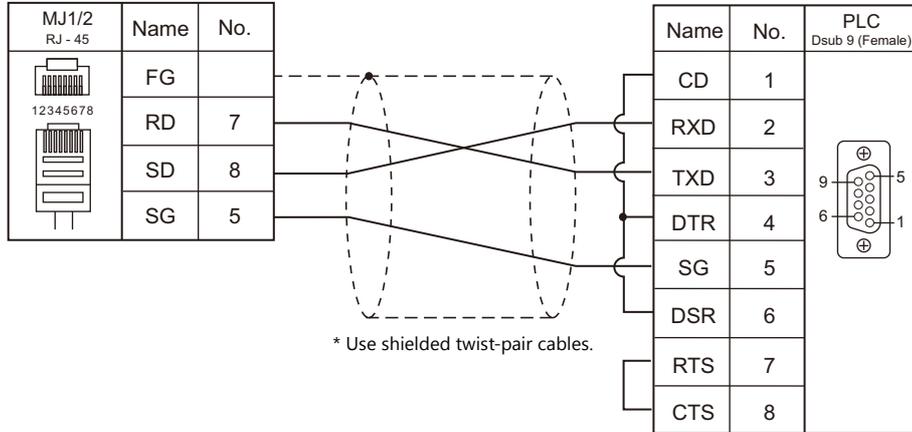


* Use shielded twist-pair cables.

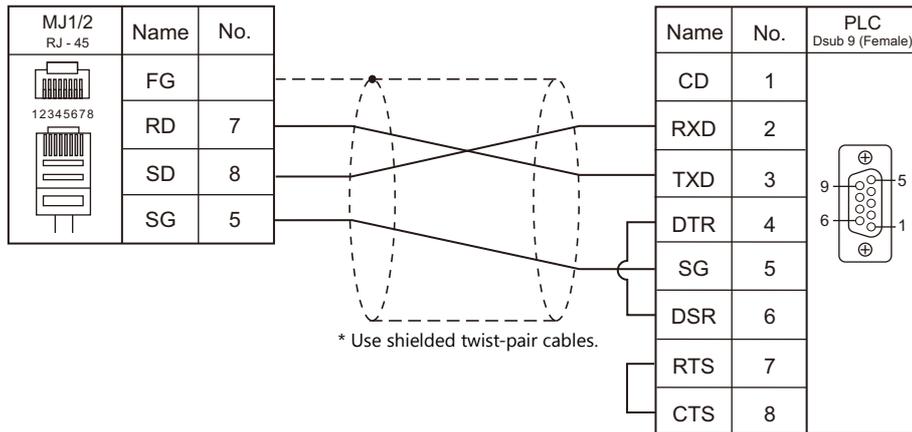
When Connected at MJ1/MJ2:

RS-232C

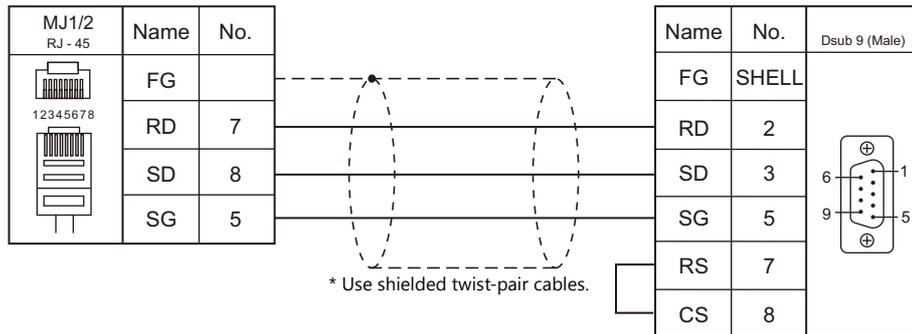
Wiring diagram 1 - M2



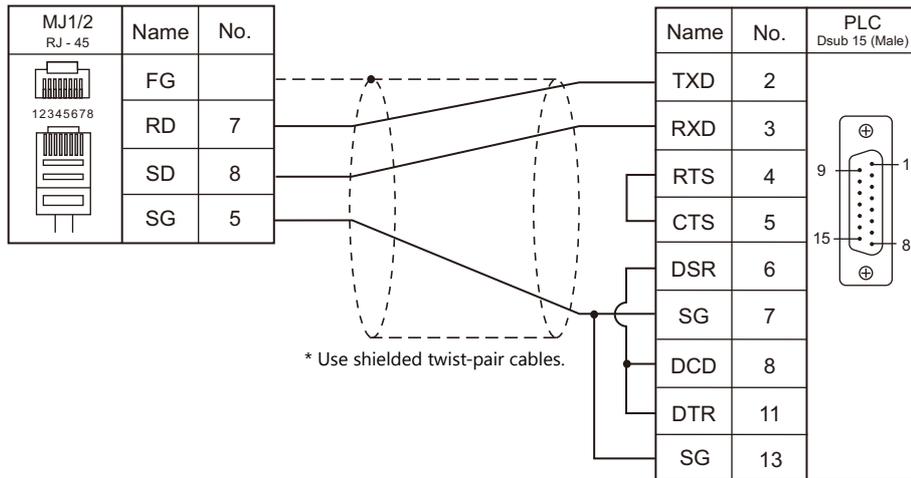
Wiring diagram 2 - M2



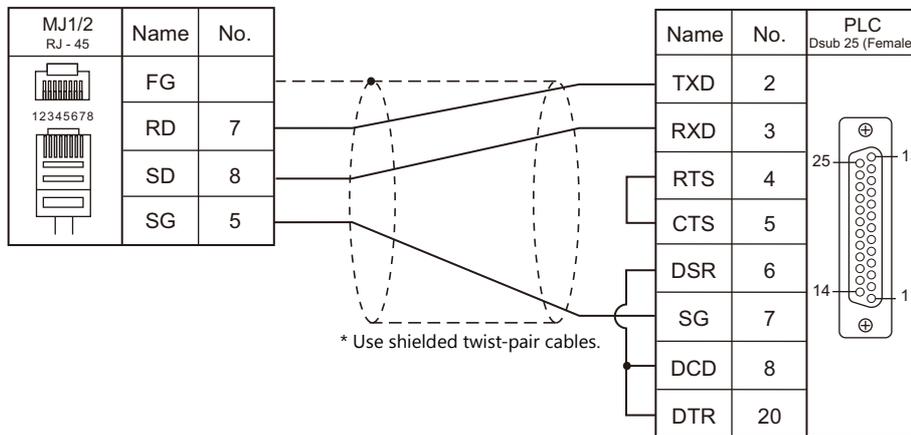
Wiring diagram 3 - M2



Wiring diagram 4 - M2



Wiring diagram 5 - M2



MEMO

Please use this page freely.

3. Automationdirect

3.1 PLC Connection

3.1 PLC Connection

Serial Connection

| PLC Selection on the Editor | PLC | Port | Signal Level | Connection | | Ladder Transfer ^{*1} |
|-----------------------------|----------------------------|--------|-----------------------|-----------------------|-----------------------|-------------------------------|
| | | | | CN1 | MJ1/MJ2 | |
| Direct LOGIC (K-Sequence) | D4-430 D4-440 | Port 0 | RS-232C | Wiring diagram 4 - C2 | Wiring diagram 4 - M2 | × |
| | | Port 1 | RS-232C | Wiring diagram 1 - C2 | Wiring diagram 1 - M2 | |
| | RS-422 | | Wiring diagram 1 - C4 | × | | |
| | D4-450 | Port 0 | RS-232C | Wiring diagram 4 - C2 | Wiring diagram 4 - M2 | |
| | | Port 1 | RS-232C | Wiring diagram 1 - C2 | Wiring diagram 1 - M2 | |
| | | | RS-422 | Wiring diagram 1 - C4 | × | |
| | | Port 2 | RS-232C | Wiring diagram 3 - C2 | Wiring diagram 3 - M2 | |
| | Port 3 | RS-422 | Wiring diagram 2 - C4 | × | | |
| | D2-230 | PORT1 | RS-232C | Wiring diagram 3 - C2 | Wiring diagram 3 - M2 | |
| | D2-240 DL05 | PORT1 | | | | |
| | | PORT2 | | | | |
| | D2-250-1 D2-260 DL06 | PORT1 | RS-232C | Wiring diagram 2 - C2 | Wiring diagram 2 - M2 | |
| PORT2 | | RS-422 | Wiring diagram 3 - C4 | × | | |
| | Direct LOGIC (MODBUS RTU) | D4-450 | Port 1 | RS-232C | Wiring diagram 1 - C2 | Wiring diagram 1 - M2 |
| RS-422 | | | | Wiring diagram 1 - C4 | × | |
| Port 3 | | | RS-422 | Wiring diagram 2 - C4 | × | |
| D2-250-1 D2-260 | | PORT2 | RS-232C | Wiring diagram 2 - C2 | Wiring diagram 2 - M2 | |
| | | | RS-422 | Wiring diagram 3 - C4 | × | |

*1 For the ladder transfer function, see the V9 Series Reference Manual.

Ethernet Connection

| PLC Selection on the Editor | CPU | Unit | TCP/IP | UDP/IP | Port No. | Keep Alive ^{*1} | Ladder Transfer ^{*2} |
|--------------------------------|------------------------------|-----------------------|--------|--------|---------------|--------------------------|-------------------------------|
| Direct LOGIC (Ethernet UDP/IP) | DL05 DL06 | H0-ECOM H0-ECOM100 | × | ○ | 28784 (fixed) | ○ | × |
| | D2-240 D2-250-1 D2-260 | H2-ECOM H2-ECOM100 | | | | | |

*1 For KeepAlive functions, see "1.3.2 Ethernet Communication".

*2 For the ladder transfer function, see the V9 Series Reference Manual.

3.1.1 Direct LOGIC (K-Sequence)

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|---|---------|
| Connection Mode | <u>1:1</u> / Multi-link2 / Multi-link2 (Ethernet) | |
| Signal Level | <u>RS-232C</u> / RS-422/485 | |
| Baud Rate | 4800 / 9600 / <u>19200</u> / 38400 bps | |
| Data Length | <u>8</u> bits | |
| Stop Bit | <u>1</u> / 2 bits | |
| Parity | None / <u>Odd</u> / Even | |
| Target Port No. | 0 to 31 | |

D4-450

PORT0

No particular setting is necessary on the PLC. The PLC always performs communication functions using the following parameters. Set the following parameters under [Communication Setting] of the editor.

| Item | Setting | |
|-------------|----------|--|
| Baud Rate | 9600 bps | |
| Parity | Odd | |
| Data Length | 8 | |
| Stop Bit | 1 | |
| Data Type | HEX | |

PORT1

Set parameters into the special register "R772, 773", then set "AA5A" (HEX) into the setting complete register "R767". When the set value at R767 is changed to "AAAA" (HEX), it is regarded as normal; if it is changed to "AAEA" (HEX), it is regarded as erroneous.

Parameter setting register

(Underlined setting: default)

| Register | Setting | Setting Example |
|----------|---|--|
| R772 | <p>Communication protocol 80: K-Sequence <u>E0</u>: Automatic recognition (Modbus, CCM, K-Sequence)</p> <p>Communication timeout 0: 800 ms</p> <p>Response delay time 0: 0 ms</p> | <p>00E0H K-Sequence</p> |
| R773 | <p>Station number 01 to 1F (HEX)</p> <p>Baud rate 4: 4800 bps 5: 9600 bps 6: <u>19200 bps</u> 7: 38400 bps</p> <p>Parity stop bit 0: Without parity, stop bit 1 2: Without parity, stop bit 2 8: <u>Odd parity, stop bit 1</u> A: Odd parity, stop bit 2 C: Even parity, stop bit 1 E: Even parity, stop bit 2</p> | <p>8701H 38400 bps Odd parity Stop bit 1 Station number 01</p> |

PORT2

Set parameters into the special register "R774, 775", then set "A5AA" (HEX) into the setting complete register "R767". When the set value at R767 is changed to "AAAA" (HEX), it is regarded as normal; if it is changed to "AEAA" (HEX), it is regarded as erroneous.

Parameter setting register

| Register | Setting | Setting Example |
|----------|---|-----------------|
| R774 | Same as the setting register R772 for PORT1 | 00E0H |
| R775 | Same as the setting register R773 for PORT1 | 8701H |

PORT3

Set parameters into the special register "R776, 777", then set "5AAA" (HEX) into the setting complete register "R767". When the set value at R767 is changed to "AAAA" (HEX), it is regarded as normal; if it is changed to "EAAA" (HEX), it is regarded as erroneous.

Parameter setting register

| Register | Setting | Setting Example |
|----------|---|-----------------|
| R776 | Same as the setting register R772 for PORT1 | 00E0H |
| R777 | Same as the setting register R773 for PORT1 | 8701H |

D2-240/D2-250-1

PORT1 / PORT2

No particular setting is necessary on the PLC. The PLC performs communication functions using the following parameters. Set the following parameters under [Communication Setting] of V9.

| Item | Setting | Remarks |
|-------------|----------|---|
| Baud Rate | 9600 bps | For PORT2: 19200 bps can be set in the special register. |
| Parity | Odd | |
| Data Length | 8 | |
| Stop Bit | 1 | |
| Data Type | HEX | |

Available Device Memory

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|---|------|---------|
| V (data register) | 00H | |
| X (input) | 01H | |
| Y (output) | 02H | |
| C (internal relay) | 03H | |
| S (stage) | 04H | |
| GX (transmission relay for all stations) | 05H | |
| GY (transmission relay for specified station) | 06H | |
| T (timer/contact) | 07H | |
| CT (counter/contact) | 08H | |

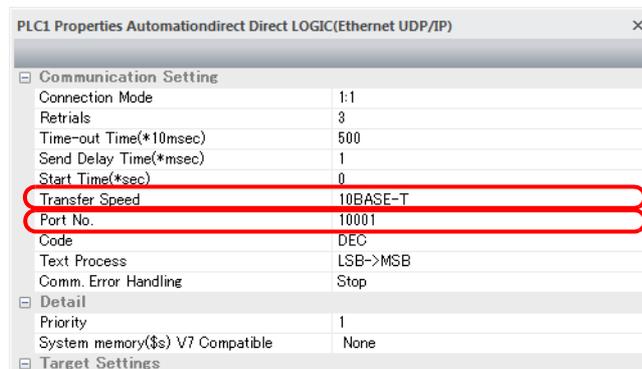
3.1.2 Direct LOGIC (Ethernet UDP/IP)

Communication Setting

Editor

Make the following settings on the editor. For more information, see 1.3.2 Ethernet Communication.

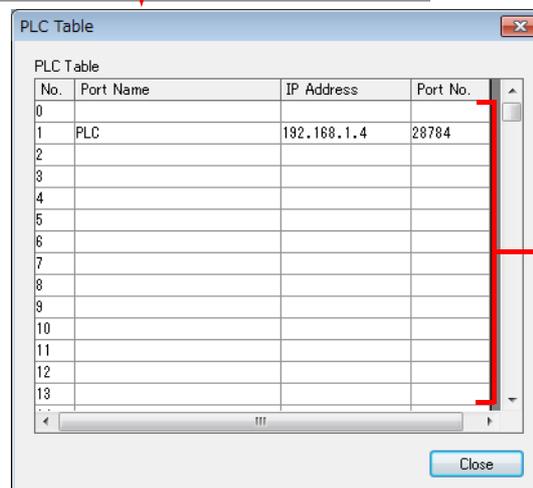
- IP address for the V9 unit
 - When specified on the screen program:
[System Setting] → [Hardware Setting] → [Local Port IP Address]
 - When specified on the V9 unit:
Local mode → [LAN Setting]
- Port number for the V9 unit (for communication with PLC)
[System Setting] → [Hardware Setting] → [PLC Properties] → [Communication Setting]
- Others
[System Setting] → [Hardware Setting] → [PLC Properties] → [Communication Setting]
 - For [Transfer Speed], select the same setting as the specification of the connected communication module.*
For Hx-ECOM: 10BASE-T
For Hx-ECOM100: 100BASE-TX
 - * If the transfer speed is not selected correctly, a check code error occurs.



- IP address and port number (No. 28784) of the PLC
Register on the [PLC Table] window in [System Setting] → [Hardware Setting] → [PLC Properties] → [Target Settings].



Valid only for 1 : 1 connection
Select the PLC for connection from those registered on the PLC table.



Set the IP address, port number and whether or not to use the KeepAlive function of the PLC.

DirectLOGIC/SU Series

Make PLC settings by using the software "DirectSOFT". For more information, refer to the PLC manual issued by the manufacturer.

Link wizard

| Contents | Setting | Remarks |
|--------------------|---|---|
| Transport Protocol | UDP/IP | |
| Module ID | Make settings in accordance with the network environment. | "0" cannot be set. Set all DIP switches on Hx-ECOM to the OFF positions. |
| IP Address | | |

* The port number is fixed to "28784".

* The module ID or IP address can also be set by using the Hx-ECOM configuration software "NetEdit3" or HTML of the module (only for Hx-ECOM100). For more information, refer to the PLC manual issued by the manufacturer.

DIP switch

The module ID can be set by the DIP switch.

When any of the DIP switches is set in the ON position upon power-on, the module ID set by the DIP switch will take effect.

| DIP Switch | Setting Example | Remarks |
|---|--------------------------|--|
|  | $14 (= 2^1 + 2^2 + 2^3)$ | Setting range: 1 to 63 Set the value in binary notation by referring to the figures printed on the PCB. Note that the DIP switches 6 and 7 are not used. |

Available Device Memory

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|---|------|---------|
| V (data register) | 00H | |
| X (input) | 01H | |
| Y (output) | 02H | |
| C (internal relay) | 03H | |
| S (stage) | 04H | |
| GX (transmission relay for all stations) | 05H | |
| GY (transmission relay for specified station) | 06H | |
| T (timer/contact) | 07H | |
| CT (counter/contact) | 08H | |

3.1.3 Direct LOGIC (MODBUS RTU)

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|---|---------|
| Connection Mode | <u>1</u> : 1 / 1 : n / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet) | |
| Signal Level | <u>RS-232C</u> / RS-422/485 | |
| Baud Rate | 4800 / 9600 / <u>19200</u> / 38400 bps | |
| Data Length | 8 bits | |
| Stop Bit | <u>1</u> / 2 bits | |
| Parity | None / Odd / Even | |
| Target Port No. | 1 | |

D4-450

PORT1

Set parameters into the special register "R772, 773", then set "AA5A" (HEX) into the setting complete register "R767". When the set value at R767 is changed to "AAAA" (HEX), it is regarded as normal; if it is changed to "AAEA" (HEX), it is regarded as erroneous.

Parameter setting register

(Underlined setting: default)

| Register | Setting | Setting Example |
|----------|---|---|
| R772 | <p>0 0 <u>E</u> 0</p> <p>Communication protocol 20: MODBUS RTU <u>E</u>: Automatic recognition (Modbus, CCM, K-Sequence)</p> <p>Communication timeout 0: 800 ms</p> <p>Response delay time 0: 0 ms</p> | 00E0H |
| R773 | <p>8 6 0 1</p> <p>Station number 01 to 1F (HEX)</p> <p>Baud rate 4: 4800 bps 5: 9600 bps <u>6</u>: 19200 bps 7: 38400 bps</p> <p>Parity stop bit 0: Without parity, stop bit 1 2: Without parity, stop bit 2 <u>8</u>: Odd parity, stop bit 1 A: Odd parity, stop bit 2 C: Even parity, stop bit 1 E: Even parity, stop bit 2</p> | 8701H 38400 bps Odd parity Stop bit 1 Station number 01 |

PORT3

Set parameters into the special register "R776, 777", then set "5AAA" (HEX) into the setting complete register "R767". When the set value at R767 is changed to "AAAA" (HEX), it is regarded as normal; if it is changed to "EAAA" (HEX), it is regarded as erroneous.

Parameter setting register

| Register | Setting | Setting Example |
|----------|---|-----------------|
| R776 | Same as the setting register R772 for PORT1 | 00E0H |
| R777 | Same as the setting register R773 for PORT1 | 8701H |

D2-250-1**PORT2**

Set parameters into the special register "R7655, 7656", then set "0500" (HEX) into the setting complete register "R7657". When the set value at R7657 is changed to "0A00" (HEX), it is regarded as normal; if it is changed to "0E00" (HEX), it is regarded as erroneous.

Parameter setting register

(Underlined setting: default)

| Register | Setting | Setting Example |
|----------|---|---|
| R7655 | <p>0 0 2 0</p> <p>Response delay time 0: 0 ms</p> <p>Communication timeout 0: Specified time</p> <p>Communication protocol 20: MODBUS RTU</p> | 0020H |
| R7656 | <p>8 7 0 1</p> <p>Parity stop bit 0: Without parity, stop bit 1 2: Without parity, stop bit 2 <u>8: Odd parity, stop bit 1</u> A: Odd parity, stop bit 2 C: Even parity, stop bit 1 E: Even parity, stop bit 2</p> <p>Baud rate 4: 4800 bps 5: 9600 bps <u>6: 19200 bps</u> 7: 38400 bps</p> <p>Station number 01 to 7A (HEX)</p> | 8701H 38400 bps Odd parity Stop bit 1 Station number 01 |

Available Device Memory

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

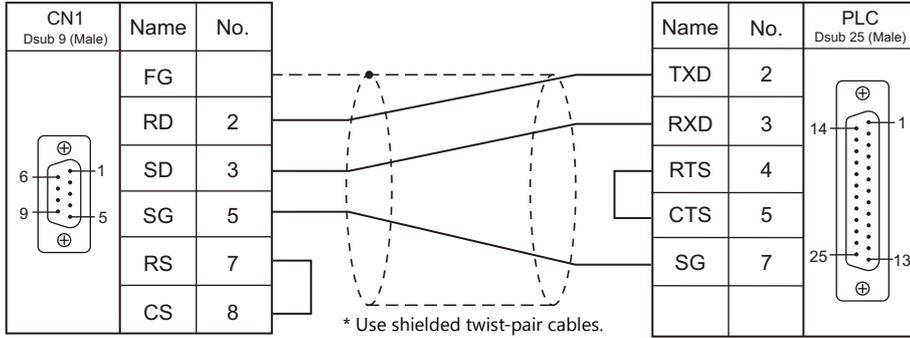
| Device Memory | TYPE | Remarks |
|---|------|---------|
| V (data register) | 00H | |
| X (input) | 01H | |
| Y (output) | 02H | |
| C (internal relay) | 03H | |
| S (stage) | 04H | |
| GX (transmission relay for all stations) | 05H | |
| GY (transmission relay for specified station) | 06H | |
| T (timer/contact) | 07H | |
| CT (counter/contact) | 08H | |

3.1.4 Wiring Diagrams

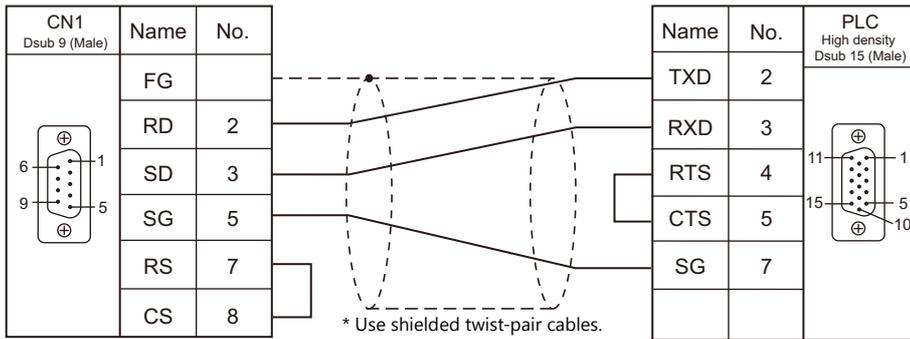
When Connected at CN1:

RS-232C

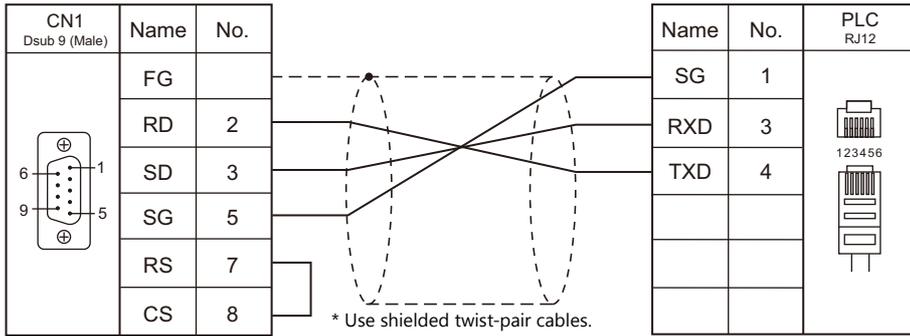
Wiring diagram 1 - C2



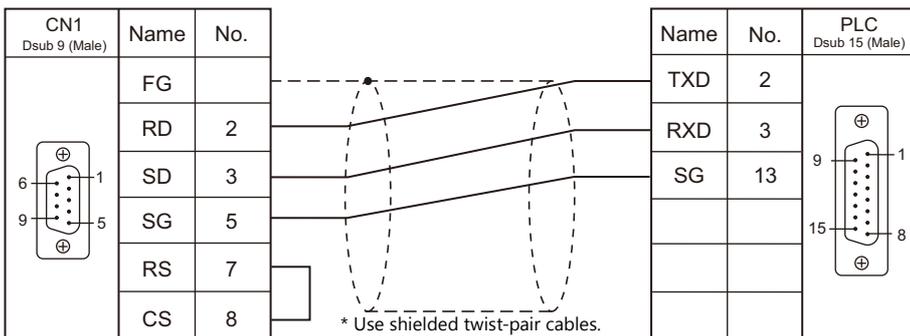
Wiring diagram 2 - C2



Wiring diagram 3 - C2

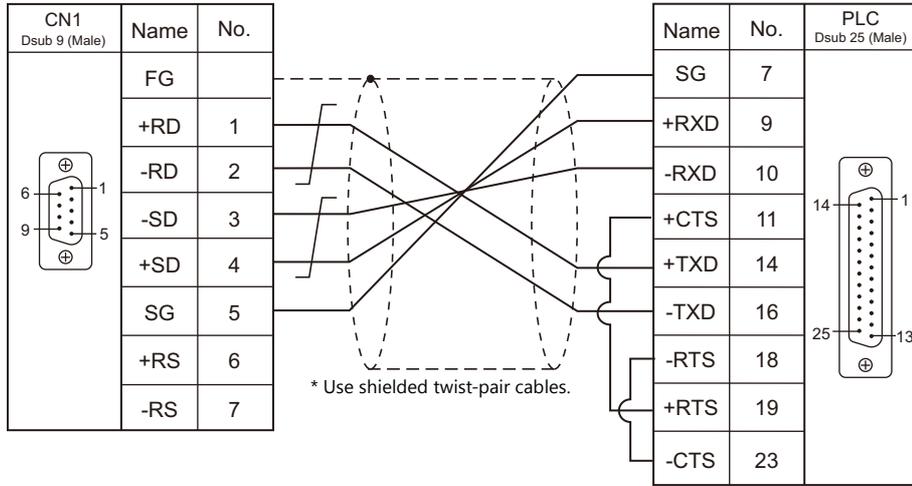


Wiring diagram 4 - C2

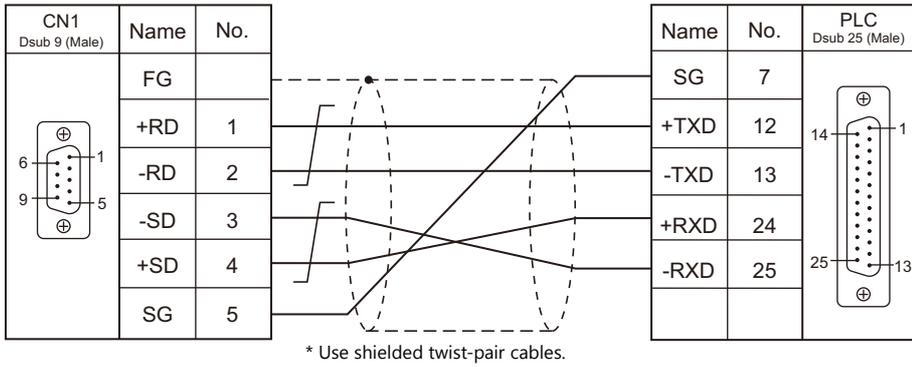


RS-422/RS-485

Wiring diagram 1 - C4

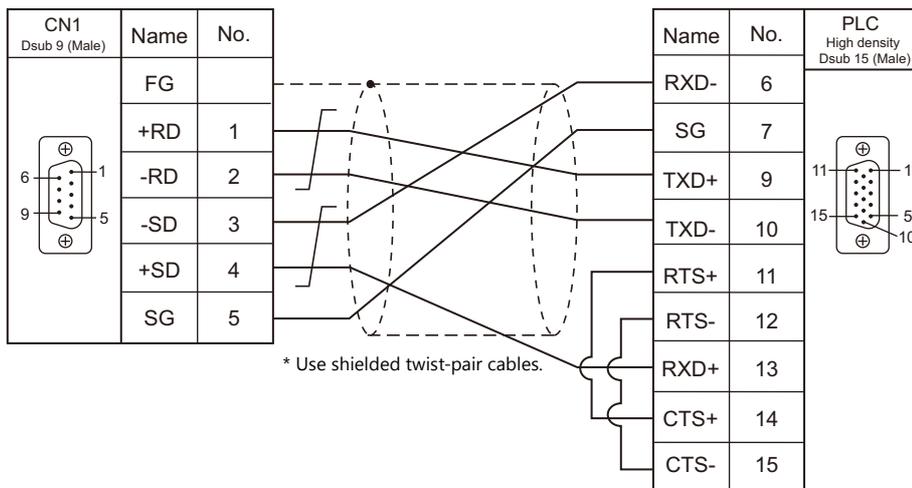


Wiring diagram 2 - C4



* SU-6M: Terminal block connectable

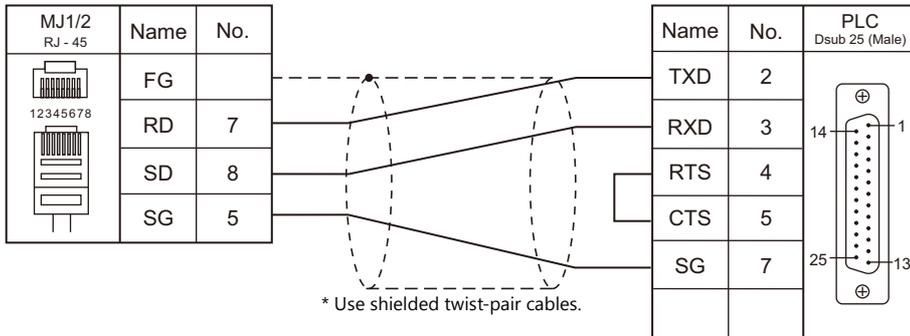
Wiring diagram 3 - C4



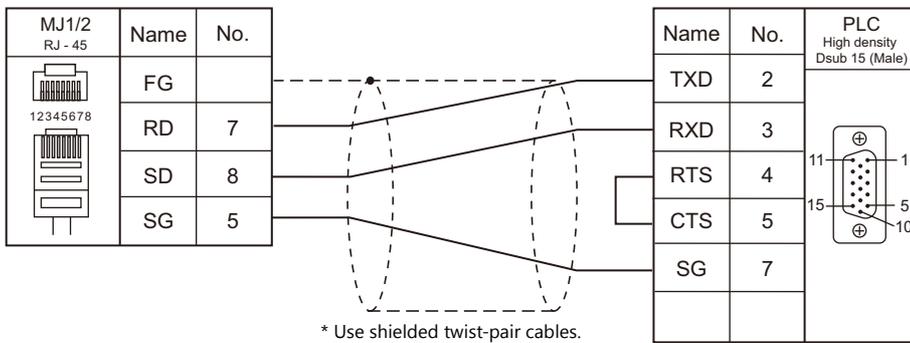
When Connected at MJ1/MJ2:

RS-232C

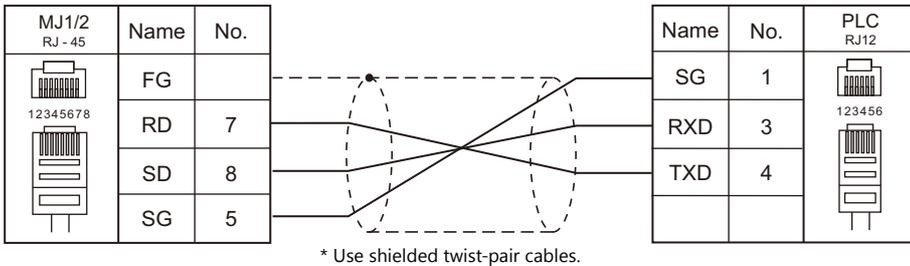
Wiring diagram 1 - M2



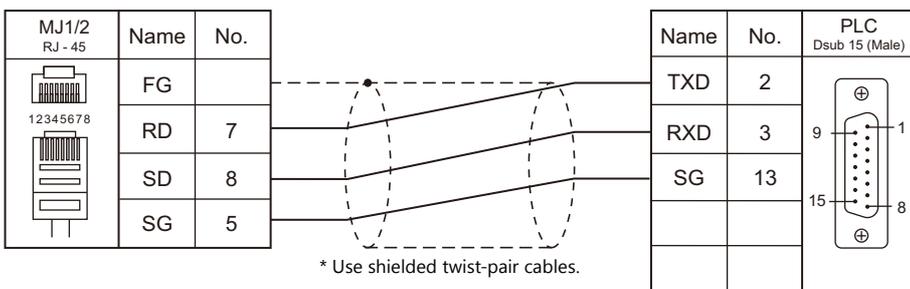
Wiring diagram 2 - M2



Wiring diagram 3 - M2



Wiring diagram 4 - M2



4. Azbil

4.1 PLC Connection

4.2 Temperature Controller/Servo/Inverter Connection

4.1 PLC Connection

Serial Connection

| PLC Selection on the Editor | Model | Port | Signal Level | Connection | | Ladder Transfer ^{*1} |
|-----------------------------|-------|-----------------------|--------------|-----------------------|-----------------------|-------------------------------|
| | | | | CN1 | MJ1/MJ2 | |
| MX series | MX50 | LOAD connector (CN7) | RS-232C | Wiring diagram 1 - C2 | Wiring diagram 1 - M2 | × |
| | | ASCII connector (CN8) | | Wiring diagram 2 - C2 | Wiring diagram 2 - M2 | |
| | MX200 | LOAD connector | RS-232C | Wiring diagram 2 - C2 | Wiring diagram 2 - M2 | |
| | | ASCII connector | | | | |

*1 For the ladder transfer function, see the V9 Series Reference Manual.

4.1.1 MX Series

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|---|---------|
| Connection Mode | <u>1:1</u> / Multi-link2 / Multi-link2 (Ethernet) | |
| Signal Level | <u>RS-232C</u> | |
| Baud Rate | 4800 / <u>9600</u> / 19200 bps | |
| Data Length | <u>8 bits</u> | |
| Stop Bit | <u>1</u> / 2 bits | |
| Parity | None / <u>Even</u> | |
| Target Port No. | <u>1</u> to 63, 127 | |

PLC

MX50

Communication setting

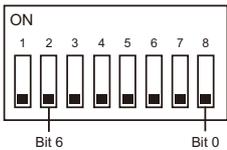
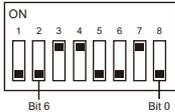
Make the following settings using the application software. For more information, refer to the PLC manual issued by the manufacturer.

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------|---|---------|
| Baud rate | 4800 / <u>9600</u> / 19200 bps | |
| Data type | <u>Even parity 1 STOP</u> No parity 2 STOP | |

Station number

Set a station number using the DIP switches.

| DipSW | Setting | Remarks |
|---|--|---|
|  | 1 to 63, 127 (Set a binary number using bits 0 to 6.) | Example: Station No. 50 50(DEC) = 0110010(BIN)  |

* Set SW No. 1 to OFF at all times.

Calendar

This model is equipped with a calendar function; however, the calendar data cannot be written from the V series. Thus, time correction must be performed on the PLC side.

MX200

Make the following settings on the front panel. For more information, refer to the PLC manual issued by the manufacturer.

LOAD connector

(Underlined setting: default)

| Communication Setup Mode | | Setting | Remarks |
|--------------------------|----------------------------|--|--|
| LOAD connector setting | Item 0: Address setting | <u>1</u> to 63 (DEC): 1 to 63 7F(HEX): 127 | Settings can also be made in the PLC application software. For more information, refer to the PLC manual issued by the manufacturer. |
| | Item 1: Baud rate | 48: 4800 bps <u>96</u> : 9600 bps 192: 19200 bps | |
| | Item 2: Communication mode | <u>8E1</u> : data length 8 bits, even parity, 1 stop bit 8n2: data length 8 bits, without parity, 2 stop bits | |

ASCII connector

(Underlined setting: default)

| Communication Setup Mode | | Setting | Remarks |
|--------------------------|-------------------------------------|--|--|
| ASCII connector setting | Item 0: Baud rate | 48: 4800 bps <u>96</u> : 9600 bps 192: 19200 bps | Settings can also be made in the PLC application software. For more information, refer to the PLC manual issued by the manufacturer. |
| | Item 1: Data length | 7b: 7 bits <u>8b</u> : 8 bits | |
| | Item 2: Parity bit | <u>EP</u> : Even oP: Odd nP: None | |
| | Item 3: Stop bit | <u>1S</u> : 1 bit 2S: 2 bits | |
| | Item 4: Connector usage | Ldr: LOAD connector | |
| | Item 5: Connecting device selection | CPL: Yamatake communication support device | |
| | Item 7: RTS control | non: No RTS control | |
| | Item 8: Signal level selection | <u>232</u>: RS-232C | |

Station number

Make the following setting on the front panel.

(Underlined setting: default)

| MX Address Display/Setting Mode | Setting | Remarks |
|---------------------------------|----------------|---------|
| Addr | <u>1</u> to 63 | |

Calendar

This model is equipped with a calendar function; however, the calendar data cannot be written from the V series. Thus, time correction must be performed on the PLC side.

Available Device Memory

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

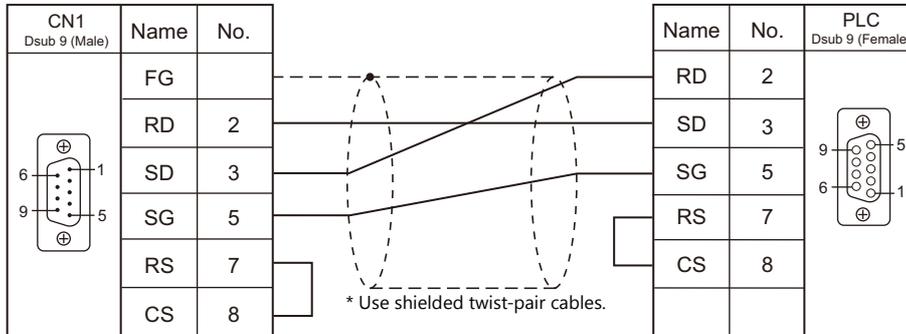
| Device Memory | TYPE | Remarks |
|----------------------------|------|---|
| R (data register) | 00H | R910, 929, 930, 956 to 987, 994 to 997: Read only |
| M (auxiliary relay) | 01H | M920 to 940, 970 to 990: Read only |
| L (latch relay) | 02H | |
| X (input relay) | 03H | |
| Y (output relay) | 04H | |
| TP (timer/current value) | 05H | Data format: BCD |
| TS (timer/set value) | 06H | Data format: BCD |
| CP (counter/current value) | 07H | Data format: BCD |
| CS (counter/set value) | 08H | Data format: BCD |
| T (timer/contact) | 09H | |
| C (counter/contact) | 0AH | |
| P (link register) | 0BH | |

4.1.2 Wiring Diagrams

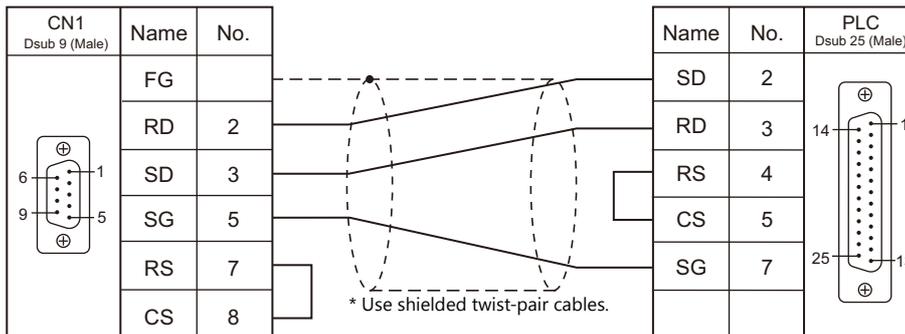
When Connected at CN1:

RS-232C

Wiring diagram 1 - C2



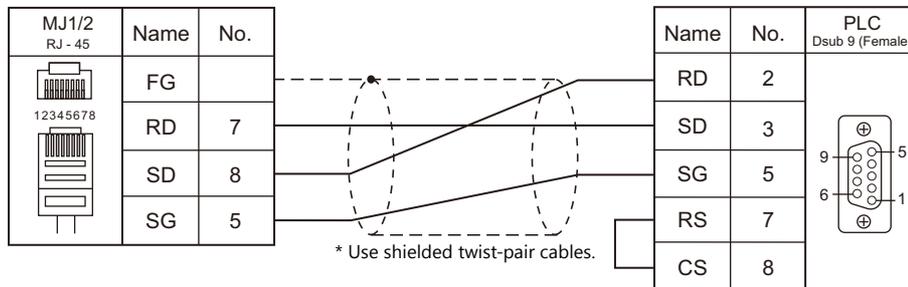
Wiring diagram 2 - C2



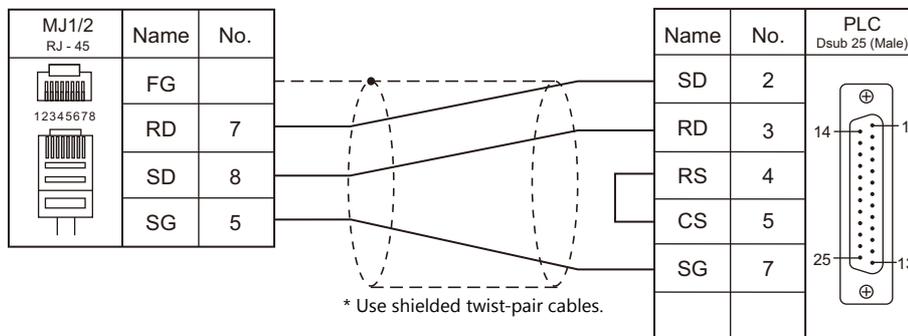
When Connected at MJ1/MJ2:

RS-232C

Wiring diagram 1 - M2



Wiring diagram 2 - M2



4.2 Temperature Controller/Servo/Inverter Connection

Serial Connection

Digital Indicating Controller

| PLC Selection on the Editor | Model | Port | Signal Level | Connection | | Lst File | | | | | |
|--|---|--|---------------------------------|-----------------------|-----------------------|-----------------------|-----------------------|----------------------|--------|-----------------------|-----------------------|
| | | | | CN1 | MJ1/MJ2 | | | | | | |
| SDC10 | SDC10xxxx05xx | Terminal on the back | RS-485 | Wiring diagram 1 - C4 | Wiring diagram 1 - M4 | SDC10.Lst | | | | | |
| SDC20 | SDC20xxx02xx SDC20xxx04xx SDC20xxx09xx | Terminal on the back | RS-485 | Wiring diagram 2 - C4 | Wiring diagram 2 - M4 | SDC20.Lst | | | | | |
| | SDC20xxx03xx SDC20xxx05xx SDC20xxx10xx | Terminal on the back | RS-232C | Wiring diagram 1 - C2 | Wiring diagram 1 - M2 | | | | | | |
| | SDC21 | SDC21xxx03xx SDC21xxx06xx SDC21xxx08xx | Terminal on the back | RS-485 | Wiring diagram 2 - C4 | | Wiring diagram 2 - M4 | | | | |
| SDC21xxx04xx SDC21xxx07xx SDC21xxx09xx | | Terminal on the back | RS-232C | Wiring diagram 1 - C2 | Wiring diagram 1 - M2 | | | | | | |
| SDC30/31 | | SDC30xxx040xx SDC30xxx041xx | Terminal on the back | RS-485 | Wiring diagram 2 - C4 | Wiring diagram 2 - M4 | SDC30.Lst | | | | |
| | SDC31xxx045xx SDC31xxx446xx SDC31xxx546xx | | | | | | | | | | |
| | SDC35/36 | SDC35xxxxx2xx SDC35xxxxx4xx SDC36xxxxx2xx SDC36xxxxx4xx | | | | | | Terminal on the back | RS-485 | Wiring diagram 1 - C4 | Wiring diagram 1 - M4 |
| SDC15Txxx03xx SDC15Txxx06xx SDC25Txxx2xx SDC26Txxx2xx | | None*1 | | | | | | | | | |
| SDC40A | | SDC40Axxxxxx2xx | Terminal on the back | RS-485 | Wiring diagram 2 - C4 | Wiring diagram 2 - M4 | SDC40A.Lst | | | | |
| | | SDC40Axxxxxx3xx | Terminal on the back | RS-232C | Wiring diagram 1 - C2 | Wiring diagram 1 - M2 | | | | | |
| SDC40G | | SDC40Gxxxx095xx | Additional terminal on the back | RS-485 | Wiring diagram 2 - C4 | Wiring diagram 2 - M4 | SDC40G.Lst | | | | |

*1 Enter addresses manually by referring to the instruction manual for the controller.

Module-type Controller

| PLC Selection on the Editor | Model | Port | Signal Level | Connection | | Lst File |
|-----------------------------|--|---------------------------------|--------------|-----------------------|-----------------------|-------------|
| | | | | CN1 | MJ1/MJ2 | |
| DMC10 | DMC10S DMC10D | CPL communication terminal | RS-485 | Wiring diagram 1 - C4 | Wiring diagram 1 - M4 | DMC10.Lst |
| DMC50 (COM) | DMC50ME20X DMC50MR20X | RS-485 port 1 | RS-485 | Wiring diagram 2 - C4 | Wiring diagram 2 - M4 | DMC50.Lst |
| | | Display communication port | RS-485 | Wiring diagram 3 - C4 | Wiring diagram 3 - M4 | |
| | DMC50CH40X DMC50CH20X DMC50CS40X DMC50CS20X | Display communication port | RS-485 | | | |
| AHC2001 | AHC2001 | CPU | RS-232C | Wiring diagram 2 - C2 | Wiring diagram 2 - M2 | AHC2001.Lst |
| | | SCU | RS-232C | | | |
| | | SCU | RS-485 | Wiring diagram 4 - C4 | Wiring diagram 4 - M4 | |
| AHC2001+DC P31/32 | AHC2001 | SCU | RS-485 | Wiring diagram 4 - C4 | Wiring diagram 4 - M4 | AHC_DCPLst |
| | DCP31Axx0ASxx2xx DCP32AxxxASxx2xx | Additional terminal on the back | RS-485 | Wiring diagram 2 - C4 | Wiring diagram 2 - M4 | |
| | IBS | Terminal block | | | | |

Program Controller

| PLC Selection on the Editor | Model | Port | Signal Level | Connection | | Lst File |
|-----------------------------|--------------------------------------|---------------------------------|--------------|-----------------------|-----------------------|-----------|
| | | | | CN1 | MJ1/MJ2 | |
| DCP31/32 | DCP31Axx0ASxx2xx DCP32AxxxASxx2xx | Additional terminal on the back | RS-485 | Wiring diagram 2 - C4 | Wiring diagram 2 - M4 | DCP32.Lst |

Instrumentation Network Module

| PLC Selection on the Editor | CPU | Unit/Port | Signal Level | Connection | | Lst File |
|-----------------------------|----------------------------|--|--------------|-----------------------|-----------------------|------------|
| | | | | CN1 | MJ1/MJ2 | |
| NX (CPL) | NX-D15 NX-D25 NX-D35 | Built-in terminal | RS-485 | Wiring diagram 1 - C4 | Wiring diagram 1 - M4 | NX_CPL.Lst |
| NX (MODBUS RTU) | | NX-CB1N (terminal) NX-CB1R (terminal) | | | | NX_Mod.Lst |

Ethernet Connection

Instrumentation Network Module

| PLC Selection on the Editor | CPU | Unit/Port | TCP/IP | UDP/IP | Port No. | Keep Alive ^{*1} | Lst File |
|-----------------------------|----------------------------|--------------------|--------|--------|--------------------------------|--------------------------|----------------|
| NX (MODBUS TCP/IP) | NX-D15 NX-D25 NX-D35 | NX-CB1N NX-CB1R | ○ | × | 502: Default (Max. 2 units) | ○ | NX_Mod_Eth.Lst |
| | | NX-CR1 | ○ | × | | | |

*1 For KeepAlive functions, see "1.3.2 Ethernet Communication".

4.2.1 SDC10

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|---|---------|
| Connection Mode | 1 : 1 / <u>1 : n</u> / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet) | |
| Signal Level | <u>RS-422/485</u> | |
| Baud Rate | 4800 / <u>9600</u> bps | |
| Data Length | <u>8 bits</u> | |
| Stop Bit | <u>1</u> / 2 bits | |
| Parity | None / Odd / <u>Even</u> | |
| Target Port No. | <u>1</u> to 31 | |

Controller

Make the following settings.

When the [PARA] key is held down for three seconds or longer in the run mode, the parameter mode is selected. When the [PARA] key is held down for three seconds or longer again, the setup mode is selected.

(Underlined setting: default)

| Item | Indication | Setting | Remarks |
|-------------------------|------------|---|--|
| Communication address | C22 | 1 to 31 | Communication is disabled when "0" is set. |
| Communication condition | C23 | <u>0: 9600 bps, 8 bits, even parity, 1 stop bit</u> 1: 9600 bps, 8 bits, without parity, 2 stop bit 2: 4800 bps, 8 bits, even parity, 1 stop bit 3: 4800 bps, 8 bits, without parity, 2 stop bit | |

Available Device Memory

The available setting range of device memory varies depending on the model. Be sure to set within the range available for the model to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|---------------|------|--|
| --- | 00H | Without "*": RAM With "*": RAM + EEPROM |

* The number of times EEPROM can be reprogrammed is limited (approx. 100,000 times). Accordingly, we recommend that you write such a parameter as to be reprogrammed frequently into RAM, where the number of reprogramming times is not limited. However, when the parameter has been written into RAM, and the power is turned off and back on again, data in EEPROM is transferred.

For more information, refer to the instruction manual for the controller issued by the manufacturer.

4.2.2 SDC20

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|--|---------|
| Connection Mode | 1 : 1 / <u>1 : n</u> / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet) | |
| Signal Level | RS-232C / <u>RS-422/485</u> | |
| Baud Rate | 4800 / <u>9600</u> bps | |
| Data Length | 8 bits | |
| Stop Bit | <u>1</u> / 2 bits | |
| Parity | None / Odd / <u>Even</u> | |
| Target Port No. | <u>1</u> to 31 | |

Controller

Make the following settings.

(Underlined setting: default)

| Item | Indication | Setting | Remarks |
|-----------------------|------------|--|--|
| Communication address | C31 | 1 to 31 | Communication is disabled when "0" is set. |
| Baud rate | C32 | <u>0</u> : 9600 bps 1: 4800 bps | |
| Data type | C33 | <u>0</u> : 8 bits, <u>1</u> stop bit, even parity 1: 8 bits, 2 stop bit, without parity | |

Available Device Memory

The available setting range of device memory varies depending on the model. Be sure to set within the range available for the model to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|---------------|------|--|
| --- | 00H | Without "*": RAM With "*": RAM + EEPROM |

* The number of times EEPROM can be reprogrammed is limited (approx. 100,000 times). Accordingly, we recommend that you write such a parameter as to be reprogrammed frequently into RAM, where the number of reprogramming times is not limited. However, when the parameter has been written into RAM, and the power is turned off and back on again, data in EEPROM is transferred.

For more information, refer to the instruction manual for the controller issued by the manufacturer.

4.2.3 SDC21

Settings are the same as those described in "4.2.2 SDC20".

4.2.4 SDC30/31

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|---|---------|
| Connection Mode | 1 : 1 / <u>1 : n</u> / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet) | |
| Signal Level | <u>RS-422/485</u> | |
| Baud Rate | 4800 / <u>9600</u> bps | |
| Data Length | <u>8 bits</u> | |
| Stop Bit | <u>1</u> / 2 bits | |
| Parity | None / Odd / <u>Even</u> | |
| Target Port No. | <u>1</u> to 31 | |

Controller

Make the following settings.

When the [PARA] key is held down for three seconds or longer in the run mode, the parameter mode is selected. When the [PARA] key is held down for three seconds or longer again, the setup mode is selected.

(Underlined setting: default)

| Item | Indication | Setting | Remarks |
|-----------------------|------------|--|--|
| Communication address | C31 | 1 to 31 | Communication is disabled when "0" is set. |
| Baud rate | C32 | <u>0: 9600 bps</u> 1: 4800 bps | |
| Data type | C33 | <u>0: 8 bits, 1 stop bit, even parity</u> 1: 8 bits, 2 stop bit, without parity | |

Available Device Memory

The available setting range of device memory varies depending on the model. Be sure to set within the range available for the model to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|---------------|------|--|
| --- | 00H | Without "*": RAM With "*": RAM + EEPROM |

* The number of times EEPROM can be reprogrammed is limited (approx. 100,000 times). Accordingly, we recommend that you write such a parameter as to be reprogrammed frequently into RAM, where the number of reprogramming times is not limited. However, when the parameter has been written into RAM, and the power is turned off and back on again, data in EEPROM is transferred.

For more information, refer to the instruction manual for the controller issued by the manufacturer.

4.2.5 SDC35/36

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|--|---------|
| Connection Mode | 1 : 1 / <u>1 : n</u> / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet) | |
| Signal Level | RS-232C / <u>RS-422/485</u> | |
| Baud Rate | 4800 / 9600 / <u>19200</u> / 38400 bps | |
| Data Length | 7 / <u>8</u> bits | |
| Stop Bit | <u>1</u> / 2 bits | |
| Parity | None / Odd / <u>Even</u> | |
| Target Port No. | <u>1</u> to 31 | |

Controller

CPL communication setting

(Underlined setting: default)

| Item (Bank) | Indication | Setting | Remarks |
|-------------------------------------|------------|---|--|
| Communication type (Setup bank) | C64 | <u>0: CPL</u> | See "20. MODBUS". |
| Device address (Setup bank) | C65 | 1 to 127 | Communication is disabled when "0" is set. |
| Baud rate (Setup bank) | C66 | 0: 4800 bps 1: 9600 bps <u>2: 19200 bps</u> 3: 38400 bps | |
| Data type: data length (Setup bank) | C67 | 0: 7 bits <u>1: 8 bits</u> | |
| Data type: parity (Setup bank) | C68 | 0: <u>Even</u> 1: Odd 2: None | |
| Data type: stop bit (Setup bank) | C69 | <u>0: 1 bit</u> 1: 2 bits | |

Available Device Memory

The available setting range of device memory varies depending on the model. Be sure to set within the range available for the model to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|---------------|------|--|
| --- | 00H | Without "*": RAM With "*": RAM + EEPROM |

- * The number of times EEPROM can be reprogrammed is limited (approx. 100,000 times). Accordingly, we recommend that you write such a parameter as to be reprogrammed frequently into RAM, where the number of reprogramming times is not limited. However, when the parameter has been written into RAM, and the power is turned off and back on again, data in EEPROM is transferred.

For more information, refer to the instruction manual for the controller issued by the manufacturer.

4.2.6 SDC40A

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|--|---------|
| Connection Mode | 1 : 1 / <u>1 : n</u> / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet) | |
| Signal Level | RS-232C / <u>RS-422/485</u> | |
| Baud Rate | 4800 / <u>9600</u> bps | |
| Data Length | <u>8</u> bits | |
| Stop Bit | <u>1</u> / 2 bits | |
| Parity | None / Odd / <u>Even</u> | |
| Target Port No. | <u>1</u> to 31 | |

Controller

Make the following settings.

(Underlined setting: default)

| Item | Indication | Setting | Remarks |
|-----------------------|------------|--|--|
| Communication address | C84 | 1 to 31 | Communication is disabled when "0" is set. |
| Baud rate | C85 | <u>0</u> : 9600 bps, even parity, 1 stop bit 1: 9600 bps, without parity, 2 stop bit 2: 4800 bps, even parity, 1 stop bit 3: 4800 bps, without parity, 2 stop bit | |

Available Device Memory

The available setting range of device memory varies depending on the model. Be sure to set within the range available for the model to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|---------------|------|--|
| --- | 00H | Without "*": RAM With "*": RAM + EEPROM |

* The number of times EEPROM can be reprogrammed is limited (approx. 100,000 times). Accordingly, we recommend that you write such a parameter as to be reprogrammed frequently into RAM, where the number of reprogramming times is not limited. However, when the parameter has been written into RAM, and the power is turned off and back on again, data in EEPROM is transferred.

For more information, refer to the instruction manual for the controller issued by the manufacturer.

4.2.7 SDC40G

Settings are the same as those described in "4.2.6 SDC40A".

4.2.8 DMC10

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|--|---------|
| Connection Mode | 1 : 1 / <u>1 : n</u> / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet) | |
| Signal Level | <u>RS-232C</u> / RS-422/485 | |
| Baud Rate | 4800 / 9600 / <u>19200</u> bps | |
| Data Length | 7 / <u>8</u> bits | |
| Stop Bit | <u>1</u> / 2 bits | |
| Parity | None / Odd / <u>Even</u> | |
| Target Port No. | <u>1</u> to 31 | |

Controller

Rotary switch for device address

| MODULE ADDRESS | Setting | Remarks |
|--|---------|--|
|  | 1 to F | Communication is disabled when "0" is set. |

CPL communication setting

Make the following settings on the PC loader. (Underlined setting: default)

| Setting Items | Setting | Remarks |
|---------------|--|-------------------|
| CPL/MODBUS | <u>0: CPL</u> | See "20. MODBUS". |
| Baud rate | 1: 4800 bps 2: 9600 bps <u>3: 19200 bps</u> | |
| Data type | <u>0: 8 bits / 1 bit / even</u> 1: 8 bits / 2 bits / none | |

Available Device Memory

The available setting range of device memory varies depending on the controller model. Be sure to set within the range available for the controller to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|---------------|------|--|
| --- | 00H | Without "*": RAM With "*": RAM + EEPROM |

* The number of times EEPROM can be reprogrammed is limited (approx. 100,000 times). Accordingly, we recommend that you write such a parameter as to be reprogrammed frequently into RAM, where the number of reprogramming times is not limited. However, when the parameter has been written into RAM, and the power is turned off and back on again, data in EEPROM is transferred.

For more information, refer to the instruction manual for the controller issued by the manufacturer.

4.2.9 DMC50 (COM)

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|--|---|
| Connection Mode | 1 : 1 / <u>1 : n</u> / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet) | |
| Signal Level | RS-232C / <u>RS-422/485</u> | |
| Baud Rate | <u>9600</u> / 19200 / 38400 bps | |
| Data Length | <u>8</u> bits | |
| Stop Bit | <u>1</u> bit | |
| Parity | <u>Even</u> | |
| Target Port No. | <u>1</u> to 16 | When connecting to the COM module: Station number: COM module Sub-station number: CTRL module |
| Sub-station No. | <u>0</u> to 16 | When connecting to the CTRL module: Station number: CTRL module Sub-station number: 0 |

Controller

Rotary address for module address

| MODULE ADDRESS | Setting | Remarks |
|---|---------|--|
|  | 1 to F | Communication is disabled when "0" is set. |

COM module: RS-485 port 1

Make the following settings on the PC loader.

(Underlined setting: default)

| Setting Items | Contents | Remarks |
|--------------------|---|---------|
| Baud rate (port 1) | <u>9600 bps</u> 19200 bps 38400 bps | |
| Protocol (port 1) | <u>1: CPL communication</u> | |

CTRL module: Display communication port

Make the following settings on the PC loader.

(Underlined setting: default)

| Setting Items | Contents | Remarks |
|--|---|---------|
| Baud rate for display communication port | <u>9600 bps</u> 19200 bps 38400 bps | |

* The display communication port is a dedicated port for 1 : 1 communication.

Available Device Memory

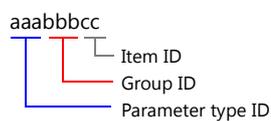
The available setting range of device memory varies depending on the controller model. Be sure to set within the range available for the controller to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory (Parameter Type ID) | TYPE | Remarks |
|--|------|------------------------|
| 000 (NA area) | 00H | Double-word |
| 001 (H/W information) | 01H | Double-word, read only |
| 002 (calendar time setting) | 02H | Double-word |
| 021 (AI setting) high-resolution monitor: for standard input | 03H | Double-word |
| 022 (AI setting) special monitor | 04H | Double-word |
| 023 (AI setting) high-resolution monitor: for option input | 05H | Double-word |
| 041 (AUX-IN setting) | 06H | Double-word |
| 045 (AO setting) | 07H | Double-word |
| 061 (DO setting) | 08H | Double-word |
| 071 (TP setting) | 09H | Double-word |
| 074 (zener barrier adjustment value) | 0AH | Double-word |
| 0A1 (communication setting: for ME200) | 0BH | Double-word, read only |
| 0A2 (communication setting: for MR200) | 0CH | Double-word, read only |
| 0A3 (communication setting: front port) | 0DH | Double-word, read only |
| 0C1 (system status) | 0EH | Double-word, read only |
| 0C3 (calendar time display) | 0FH | Double-word, read only |
| 0C4 (log: system alarm) | 10H | Double-word |
| 0C5 (log: AI alarm) | 11H | Double-word |
| 0C6 (log: AUX-IN alarm) | 12H | Double-word |
| 0E1 (AI status) | 13H | Double-word, read only |
| 0E2 (AUX-IN setting) | 14H | Double-word, read only |
| 0E3 (AO status) | 15H | Double-word |
| 0E5 (DI status) | 16H | Double-word, read only |
| 0E6 (AO status) | 17H | Double-word |
| 0E7 (TP status) | 18H | Double-word |
| 0E8 (zener barrier adjustment count) | 19H | Double-word, read only |
| 0F1 (communication setting in use: for ME200) | 1AH | Double-word, read only |
| 0F2 (communication setting in use: for MR200) | 1BH | Double-word, read only |
| 0F3 (communication setting in use: front port) | 1CH | Double-word, read only |
| 201 (PID_A setting) | 1DH | Double-word |
| 202 (PID_A constant) | 1EH | Double-word |
| 203 (PID_A monitor) | 1FH | Double-word, read only |
| 211 (PID_CAS setting) | 20H | Double-word |
| 212 (PID_CAS constant: master side) | 21H | Double-word |
| 213 (PID_CAS constant: slave side) | 22H | Double-word |
| 214 (PID_CAS monitor) | 23H | Double-word, read only |
| 234 (Ra_PID setting) | 24H | Double-word |
| 235 (Ra_PID constant) | 25H | Double-word |
| 236 (Ra_PID monitor) | 26H | Double-word, read only |
| 241 (UP_PID setting) | 27H | Double-word |
| 242 (UP_PID constant) | 28H | Double-word |
| 243 (UP_PID monitor) | 29H | Double-word, read only |
| 301 (TBL/TBR setting) | 2AH | Double-word |
| 801 (user-defined parameter) | 2BH | Double-word |
| 802 (user-defined parameter) | 2CH | Double-word |
| 803 (user-defined parameter) | 2DH | Double-word |
| 804 (user-defined parameter) | 2EH | Double-word |
| 805 (user-defined parameter) | 2FH | Double-word |
| 806 (user-defined parameter) | 30H | Double-word |
| 80D (user-defined parameter) | 31H | Double-word |
| 80E (user-defined parameter) | 32H | Double-word |
| E01 (user-defined parameter) | 33H | Double-word |
| E02 (user-defined parameter) | 34H | Double-word |
| E04 (user-defined parameter) | 35H | Double-word |
| E05 (user-defined parameter) | 36H | Double-word |
| E06 (user-defined parameter) | 37H | Double-word |
| E07 (user-defined parameter) | 38H | Double-word |
| E08 (user-defined parameter) | 39H | Double-word |

| Device Memory (Parameter Type ID) | TYPE | Remarks |
|-----------------------------------|------|------------------------|
| E0A (user-defined parameter) | 3AH | Double-word |
| E12 (user-defined parameter) | 3BH | Double-word |
| E13 (user-defined parameter) | 3CH | Double-word |
| E14 (user-defined parameter) | 3DH | Double-word |
| E15 (user-defined parameter) | 3EH | Double-word |
| 610 (user-defined parameter) | 3FH | Double-word |
| C00 (pattern setup) | 40H | Double-word |
| CF1 (pattern FB monitor) | 41H | Double-word, read only |
| C01 (segment setup) | 42H | Double-word |
| C02 (segment setup) | 43H | Double-word |
| C03 (segment setup) | 44H | Double-word |
| C04 (segment setup) | 45H | Double-word |
| C05 (segment setup) | 46H | Double-word |
| C06 (segment setup) | 47H | Double-word |
| C07 (segment setup) | 48H | Double-word |
| C08 (segment setup) | 49H | Double-word |
| C09 (segment setup) | 4AH | Double-word |
| C0A (segment setup) | 4BH | Double-word |
| C0B (segment setup) | 4CH | Double-word |
| C0C (segment setup) | 4DH | Double-word |
| C0D (segment setup) | 4EH | Double-word |
| C0E (segment setup) | 4FH | Double-word |
| C0F (segment setup) | 50H | Double-word |
| C10 (segment setup) | 51H | Double-word |
| C11 (segment setup) | 52H | Double-word |
| C12 (segment setup) | 53H | Double-word |
| C13 (segment setup) | 54H | Double-word |
| C14 (segment setup) | 55H | Double-word |
| C15 (segment setup) | 56H | Double-word |
| C16 (segment setup) | 57H | Double-word |
| C17 (segment setup) | 58H | Double-word |
| C18 (segment setup) | 59H | Double-word |
| C19 (segment setup) | 5AH | Double-word |
| C1A (segment setup) | 5BH | Double-word |
| C1B (segment setup) | 5CH | Double-word |
| C1C (segment setup) | 5DH | Double-word |
| C1D (segment setup) | 5EH | Double-word |
| C1E (segment setup) | 5FH | Double-word |
| C1F (segment setup) | 60H | Double-word |

Address denotations

On the signal name reference list, every group ID is designated as "001". To access any group ID other than "001", input the desired ID via manual operation.

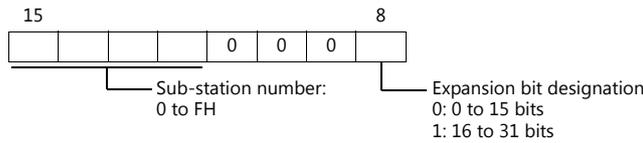


Indirect Device Memory Designation

- When the address (group ID) is 0 to FFH:

| | | | |
|-------|------------------|-----|-----------------|
| | 15 | 8 7 | 0 |
| n + 0 | Model | | Device type |
| n + 1 | Group ID | | Item ID |
| n + 2 | Expansion code * | | Bit designation |
| n + 3 | 00 | | Station number |

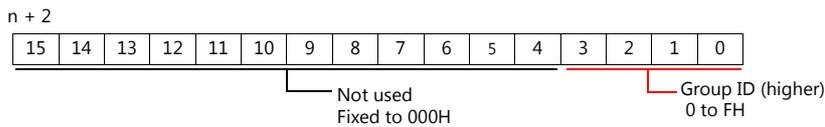
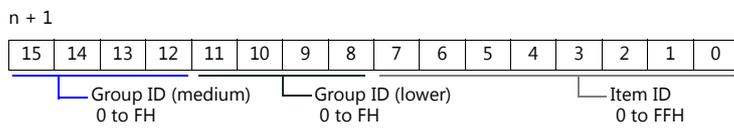
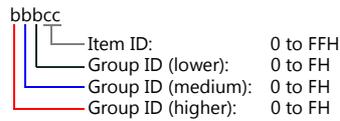
* In the expansion code, specify the sub-station number, and set which word, higher or lower, is to be read when a 2-word address is specified (expansion bit designation).



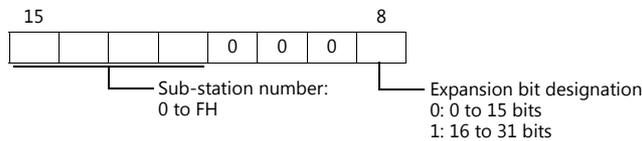
- When the address (group ID) is 100 to FFFH:

| | | | | |
|-------|----------------------------|-----|----------------------|---|
| | 15 | 8 7 | 4 3 | 0 |
| n + 0 | Model | | Device type | |
| n + 1 | Group ID (medium/lower) *1 | | Item ID *1 | |
| n + 2 | 000 | | Group ID (higher) *1 | |
| n + 3 | Expansion code *2 | | Bit designation | |
| n + 4 | 00 | | Station number | |

*1 Set the address (group ID + item ID) for "n + 1" and "n + 2".



*2 In the expansion code, specify the sub-station number, and set which word, higher or lower, is to be read when a 2-word address is specified (expansion bit designation).



4.2.10 AHC2001

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|--|---------|
| Connection Mode | 1 : 1 / <u>1 : n</u> / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet) | |
| Signal Level | <u>RS-232C</u> / RS-422/485 | |
| Baud Rate | 9600 / <u>19200</u> / 38400 / 57600 bps | |
| Data Length | 7 / <u>8</u> bits | |
| Stop Bit | <u>1</u> / 2 bits | |
| Parity | None / Odd / <u>Even</u> | |
| Target Port No. | <u>1</u> to 31 | |

Controller

CPU unit RS-232C setting

(Underlined setting: default)

| Parameter Type ID | Group ID | Item ID | Setting Items | Contents | Remarks |
|-------------------|----------|---------|--------------------|--|---------|
| 0D2 | 001 | 01 | Baud rate (port 1) | 9600 bps <u>19200 bps</u> 38400 bps 57600 bps | |
| | | 02 | Mode | 1: CPL | |
| | | 03 | CPL address | <u>1</u> to 31 | |

The following settings are fixed; parity: even, and stop bit: 1 bit.

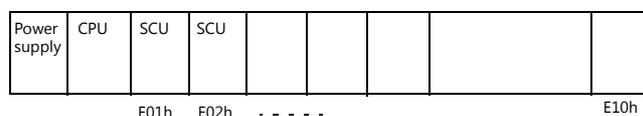
SCU unit setting

(Underlined setting: default)

| Parameter Type ID | Group ID | Item ID | Setting Items | Contents | Remarks |
|-------------------|---------------|---------|---------------------------|---|--|
| Exx *1 | 001 002 *2 | 01 | Baud rate | 9600 bps <u>19200 bps</u> 38400 bps | |
| | | 02 | Data bit length | 7: 7 bits <u>8: 8 bits</u> | |
| | | 03 | Parity | 0: None <u>1: Even</u> 2: Odd | |
| | | 04 | Stop bit | <u>1: 1 bit</u> 2: 2 bits | |
| | | 05 | Half duplex / full duplex | <u>0: Half duplex</u> 1: Full duplex | Half duplex: 2-wire connection Full duplex: 4-wire connection Invalid during RS-232C communication |
| | | 07 | Protocol selection | 2: CPL server | |

*1 xx: Unit position 01 to 10H

The unit position varies depending on the mounting position of the SCU unit.



← Unit position E01H - E10H

*2 Group ID of port 1 (RS-232C): 001, group ID of port 2 (RS-485): 002

Available Device Memory

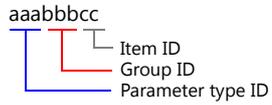
The available setting range of device memory varies depending on the controller model. Be sure to set within the range available for the controller to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory (Parameter Type ID) | TYPE | Remarks |
|-------------------------------------|------|------------------------|
| 000 (NA area) | 00H | Double-word |
| 001 (H/W information) | 01H | Double-word, read only |
| 002 (calendar time setting) | 02H | Double-word |
| 0C3 (calendar time display) | 03H | Double-word, read only |
| 0D0 (system information data) | 04H | Double-word, read only |
| 0D1 (unit information data) | 05H | Double-word, read only |
| 0D2 (CPU unit RS-232C setting) | 06H | Double-word, read only |
| 0D3 (system operation setting) | 07H | Double-word, read only |
| 0D4 (system configuration setting) | 08H | Double-word, read only |
| 0D5 (analog cycle setting) | 09H | Double-word, read only |
| 0D6 (memory capacity monitor) | 0AH | Double-word, read only |
| 201 (PID_A setting) | 0BH | Double-word |
| 202 (PID_A constant) | 0CH | Double-word |
| 203 (PID_A monitor) | 0DH | Double-word, read only |
| 211 (PID_CAS setting) | 0EH | Double-word |
| 212 (PID_CAS constant: master side) | 0FH | Double-word |
| 213 (PID_CAS constant: slave side) | 10H | Double-word |
| 214 (PID_CAS monitor) | 11H | Double-word, read only |
| 234 (Ra_PID setting) | 12H | Double-word |
| 235 (Ra_PID constant) | 13H | Double-word |
| 236 (Ra_PID monitor) | 14H | Double-word, read only |
| 241 (UP_PID setting) | 15H | Double-word |
| 242 (UP_PID constant) | 16H | Double-word |
| 243 (UP_PID monitor) | 17H | Double-word, read only |
| 301 (TBL/TBR setting) | 18H | Double-word |
| 600 (PLC link basic setting) | 19H | Double-word, read only |
| 801 (user-defined area) | 1AH | Double-word |
| 802 (user-defined area) | 1BH | Double-word |
| 803 (user-defined area) | 1CH | Double-word |
| 804 (user-defined area) | 1DH | Double-word |
| 805 (user-defined area) | 1EH | Double-word |
| 806 (user-defined area) | 1FH | Double-word |
| 807 (user-defined area) | 20H | Double-word |
| 808 (user-defined area) | 21H | Double-word |
| 809 (user-defined area) | 22H | Double-word |
| 80A (user-defined area) | 23H | Double-word |
| 80B (user-defined area) | 24H | Double-word |
| 80C (user-defined area) | 25H | Double-word |
| 80D (user-defined area) | 26H | Double-word |
| 80E (user-defined area) | 27H | Double-word |
| 80F (user-defined area) | 28H | Double-word |
| 810 (user-defined area) | 29H | Double-word |
| 811 (user-defined area) | 2AH | Double-word |
| 812 (user-defined area) | 2BH | Double-word |
| 813 (user-defined area) | 2CH | Double-word |
| 814 (user-defined area) | 2DH | Double-word |
| 815 (user-defined area) | 2EH | Double-word |
| 816 (user-defined area) | 2FH | Double-word |
| 817 (user-defined area) | 30H | Double-word |
| 820 (user-defined area) | 31H | Double-word |
| E01 (user-defined area) | 32H | Double-word |
| E02 (user-defined area) | 33H | Double-word |
| E03 (user-defined area) | 34H | Double-word |
| E04 (user-defined area) | 35H | Double-word |
| F01 (user-defined area) | 36H | Double-word |
| F02 (user-defined area) | 37H | Double-word |
| F03 (user-defined area) | 38H | Double-word |
| F04 (user-defined area) | 39H | Double-word |

| Device Memory (Parameter Type ID) | TYPE | Remarks |
|-----------------------------------|------|-------------|
| F05 (user-defined area) | 3AH | Double-word |
| F06 (user-defined area) | 3BH | Double-word |

Address denotations

On the signal name reference list, every group ID is designated as "001". To access any group ID other than "001", manually input the desired ID.



PLC_CTL

Macro command "PLC_CTL F0 F1 F2"

| Contents | F0 | F1 (= \$u n) | | F2 |
|---------------------------------------|---------------------|--------------|---------------------|----|
| | | n | Station number | |
| ISaGRAF application Start/stop | 1 - 8 (PLC1 - 8) | n + 1 | Command: 0 | 3 |
| | | n + 2 | 0: Stop 1: Start | |
| | | n | Station number | |
| ISaGRAF application Current status | 1 - 8 (PLC1 - 8) | n + 1 | Command: 1 | 2 |
| | | n + 2 | 0: Stop 1: Run | |
| | | n | Station number | |
| Reserve for parameter backup | 1 - 8 (PLC1 - 8) | n | Station number | 2 |
| | | n + 1 | Command: 2 | |

Return data: Data stored from temperature controller to V series

4.2.11 AHC2001+DCP31/32

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|--|---------|
| Connection Mode | 1 : 1 / <u>1 : n</u> / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet) | |
| Signal Level | RS-232C / <u>RS-422/485</u> | |
| Baud Rate | <u>9600</u> / 19200 / 38400 bps | |
| Data Length | 7 / <u>8</u> bits | |
| Stop Bit | <u>1</u> / 2 bits | |
| Parity | None / Odd / <u>Even</u> | |
| Target Port No. | <u>1</u> to 31 | |

Controller

AHC2001 SCU unit setting

(Underlined setting: default)

| Parameter Type ID | Group ID | Item ID | Setting Items | Contents | Remarks |
|-------------------|----------|---------|---------------------------|---|--|
| Exx *1 | 002 | 01 | Baud rate | 9600 bps <u>19200 bps</u> 38400 bps | |
| | | 02 | Data bit length | 7: 7 bits <u>8: 8 bits</u> | |
| | | 03 | Parity | 0: None <u>1: Even</u> 2: Odd | |
| | | 04 | Stop bit | <u>1: 1 bit</u> 2: 2 bits | |
| | | 05 | Half duplex / full duplex | <u>0: Half duplex</u> 1: Full duplex | Half duplex: 2-wire connection Full duplex: 4-wire connection |
| | | 07 | Protocol selection | 2: CPL server | |

*1 xx: Unit position 01 to 10H
The unit position varies depending on the mounting position of the SCU unit.

| | | | | | | | | | |
|--------------|-----|-----|-----|--|--|--|--|--|--|
| Power supply | CPU | SCU | SCU | | | | | | |
|--------------|-----|-----|-----|--|--|--|--|--|--|

E01h E02h - - - - - E10h

← Unit position E01H - E10H

DCP31/32

Setting group: Make the following setting on the setup data.

(Underlined setting: default)

| Item | Indication | Setting | Remarks |
|-----------------------|------------|---|--|
| Communication address | C84 | 1 to 31 | Communication is disabled when "0" is set. |
| Baud rate | C85 | <u>0: 9600 bps, even parity, 1 stop bit</u> 1: 9600 bps, without parity, 2 stop bit 2: 4800 bps, even parity, 1 stop bit 3: 4800 bps, without parity, 2 stop bit | |
| Data type | C93 | <u>0: Additional terminal</u> | |

IBS (air-fuel ratio controller)

Set the baud rate by the jumper setting (J2) on the CPU board.

(Underlined setting: default)

| Item | Setting | Remarks |
|------|-----------------------------|---|
| J2 | RS-485 Baud rate setting | <u>9600 bps: short-circuited between 1 and 2, 3 and 4, open between 5 and 6</u> 4800 bps: open between 1 and 2, short-circuited between 3 and 4, open between 5 and 6 |

Available Device Memory

The available setting range of device memory varies depending on the controller model. Be sure to set within the range available for the controller to be used. Use [TYPE] when assigning indirect device memory for macro programs.

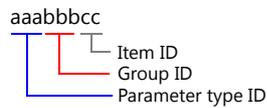
| Device Memory (Parameter Type ID) | TYPE | Remarks |
|-------------------------------------|------|---------------------------------|
| 000 (NA area) | 00H | AHC2001, double-word |
| 001 (H/W information) | 01H | AHC2001, double-word, read only |
| 002 (calendar time setting) | 02H | AHC2001, double-word |
| 0C3 (calendar time display) | 03H | AHC2001, double-word, read only |
| 0D0 (system information data) | 04H | AHC2001, double-word, read only |
| 0D1 (unit information data) | 05H | AHC2001, double-word, read only |
| 0D2 (CPU unit RS-232C setting) | 06H | AHC2001, double-word, read only |
| 0D3 (system operation setting) | 07H | AHC2001, double-word, read only |
| 0D4 (system configuration setting) | 08H | AHC2001, double-word, read only |
| 0D5 (analog cycle setting) | 09H | AHC2001, double-word, read only |
| 0D6 (memory capacity monitor) | 0AH | AHC2001, double-word, read only |
| 201 (PID_A setting) | 0BH | AHC2001, double-word |
| 202 (PID_A constant) | 0CH | AHC2001, double-word |
| 203 (PID_A monitor) | 0DH | AHC2001, double-word, read only |
| 211 (PID_CAS setting) | 0EH | AHC2001, double-word |
| 212 (PID_CAS constant: master side) | 0FH | AHC2001, double-word |
| 213 (PID_CAS constant: slave side) | 10H | AHC2001, double-word |
| 214 (PID_CAS monitor) | 11H | AHC2001, double-word, read only |
| 234 (Ra_PID setting) | 12H | AHC2001, double-word |
| 235 (Ra_PID constant) | 13H | AHC2001, double-word |
| 236 (Ra_PID monitor) | 14H | AHC2001, double-word, read only |
| 241 (UP_PID setting) | 15H | AHC2001, double-word |
| 242 (UP_PID constant) | 16H | AHC2001, double-word |
| 243 (UP_PID monitor) | 17H | AHC2001, double-word, read only |
| 301 (TBL/TBR setting) | 18H | AHC2001, double-word |
| 600 (PLC link basic setting) | 19H | AHC2001, double-word, read only |
| 801 (user-defined area) | 1AH | AHC2001, double-word |
| 802 (user-defined area) | 1BH | AHC2001, double-word |
| 803 (user-defined area) | 1CH | AHC2001, double-word |
| 804 (user-defined area) | 1DH | AHC2001, double-word |
| 805 (user-defined area) | 1EH | AHC2001, double-word |
| 806 (user-defined area) | 1FH | AHC2001, double-word |
| 807 (user-defined area) | 20H | AHC2001, double-word |
| 808 (user-defined area) | 21H | AHC2001, double-word |
| 809 (user-defined area) | 22H | AHC2001, double-word |
| 80A (user-defined area) | 23H | AHC2001, double-word |
| 80B (user-defined area) | 24H | AHC2001, double-word |
| 80C (user-defined area) | 25H | AHC2001, double-word |
| 80D (user-defined area) | 26H | AHC2001, double-word |
| 80E (user-defined area) | 27H | AHC2001, double-word |
| 80F (user-defined area) | 28H | AHC2001, double-word |
| 810 (user-defined area) | 29H | AHC2001, double-word |
| 811 (user-defined area) | 2AH | AHC2001, double-word |
| 812 (user-defined area) | 2BH | AHC2001, double-word |
| 813 (user-defined area) | 2CH | AHC2001, double-word |
| 814 (user-defined area) | 2DH | AHC2001, double-word |
| 815 (user-defined area) | 2EH | AHC2001, double-word |
| 816 (user-defined area) | 2FH | AHC2001, double-word |
| 817 (user-defined area) | 30H | AHC2001, double-word |

| Device Memory (Parameter Type ID) | TYPE | Remarks |
|-----------------------------------|------|----------------------|
| 820 (user-defined area) | 31H | AHC2001, double-word |
| E01 (user-defined area) | 32H | AHC2001, double-word |
| E02 (user-defined area) | 33H | AHC2001, double-word |
| E03 (user-defined area) | 34H | AHC2001, double-word |
| E04 (user-defined area) | 35H | AHC2001, double-word |
| F01 (user-defined area) | 36H | AHC2001, double-word |
| F02 (user-defined area) | 37H | AHC2001, double-word |
| F03 (user-defined area) | 38H | AHC2001, double-word |
| F04 (user-defined area) | 39H | AHC2001, double-word |
| F05 (user-defined area) | 3AH | AHC2001, double-word |
| F06 (user-defined area) | 3BH | AHC2001, double-word |
| --- (DCP) | 3CH | DCP31/32 |

Address denotations

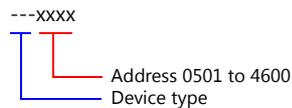
- AHC2001

On the signal name reference list, every group ID is designated as "001". To access any group ID other than "001", manually input the desired ID.



- DCP31/32

The address for DCP31/32 is not provided in the signal name reference list. Manually set the address by referring to the instruction manual for DCP31/32.



PLC_CTL

Macro command "PLC_CTL F0 F1 F2"

| Contents | F0 | F1 (= \$u n) | | F2 |
|---------------------------------------|---------------------|--------------|---------------------|----|
| ISaGRAF application Start/stop | 1 - 8 (PLC1 - 8) | n | Station number | 3 |
| | | n + 1 | Command: 0 | |
| | | n + 2 | 0: Stop 1: Start | |
| ISaGRAF application Current status | 1 - 8 (PLC1 - 8) | n | Station number | 2 |
| | | n + 1 | Command: 1 | |
| | | n + 2 | 0: Stop 1: Run | |
| Reserve for parameter backup | 1 - 8 (PLC1 - 8) | n | Station number | 2 |
| | | n + 1 | Command: 2 | |

Return data: Data stored from temperature controller to V series

4.2.12 DCP31/32

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|--|---------|
| Connection Mode | 1 : 1 / <u>1 : n</u> / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet) | |
| Signal Level | <u>RS-422/485</u> | |
| Baud Rate | 4800 / <u>9600</u> bps | |
| Data Length | <u>8 bits</u> | |
| Stop Bit | <u>1</u> / 2 bits | |
| Parity | None / Odd / <u>Even</u> | |
| Target Port No. | <u>1</u> to 31 | |

Controller

Setting group: Make the following setting on the setup data.

(Underlined setting: default)

| Item | Indication | Setting | Remarks |
|-----------------------|------------|---|--|
| Communication address | C84 | 1 to 31 | Communication is disabled when "0" is set. |
| Baud rate | C85 | <u>0: 9600 bps, even parity, 1 stop bit</u> 1: 9600 bps, without parity, 2 stop bit 2: 4800 bps, even parity, 1 stop bit 3: 4800 bps, without parity, 2 stop bit | |
| Data type | C93 | <u>0: Additional terminal</u> | |

Available Device Memory

The available setting range of device memory varies depending on the model. Be sure to set within the range available for the model to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|---------------|------|---------|
| --- | 00H | |

4.2.13 NX (CPL)

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|--|---------|
| Connection Mode | 1 : 1 / <u>1 : n</u> / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet) | |
| Signal Level | RS-232C / <u>RS-422/485</u> | |
| Baud Rate | 4800 / 9600 / <u>19200</u> / 38400 / 57600 / 115K bps | |
| Data Length | 7 / <u>8</u> bits | |
| Stop Bit | <u>1</u> / 2 bits | |
| Parity | None / Odd / <u>Even</u> | |
| Target Port No. | 1 to <u>127</u> | |

Controller

Make the following settings on [Actual Module Configuration] in the [SLP-NX] software.

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------------|---|--|
| RS-485 Address | 1 to <u>127</u> | Communication is disabled when "0" is set. |
| RS-485 Protocol | CPL | |
| RS-485 Baud Rate | 4800 / 9600 / <u>19200</u> / 38400 / 57600 / 115200 bps | |
| RS-485 Bit Length | 7 / <u>8</u> bits | |
| RS-485 Parity Setting | None / Odd / <u>Even</u> | |
| RS-485 Stop Bit | <u>1</u> / 2 bits | |

Available Device Memory

The available setting range of device memory varies depending on the model. Be sure to set within the range available for the model to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|---------------|------|---------|
| --- | 00H | |

4.2.14 NX (MODBUS RTU)

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|--|---------|
| Connection Mode | 1 : 1 / <u>1 : n</u> / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet) | |
| Signal Level | RS-232C / <u>RS-422/485</u> | |
| Baud Rate | 4800 / 9600 / <u>19200</u> / 38400 / 57600 / 115K bps | |
| Data Length | 8 bits | |
| Stop Bit | <u>1</u> / 2 bits | |
| Parity | None / Odd / <u>Even</u> | |
| Target Port No. | 1 to <u>127</u> | |

Controller

Make the following settings on [Actual Module Configuration] in the [SLP-NX] software.

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------------|---|--|
| RS-485 Address | 1 to <u>127</u> | Communication is disabled when "0" is set. |
| RS-485 Protocol | MODBUS (RTU) | |
| RS-485 Baud Rate | 4800 / 9600 / <u>19200</u> / 38400 / 57600 / 115200 bps | |
| RS-485 Bit Length | 8 bits | |
| RS-485 Parity Setting | None / Odd / <u>Even</u> | |
| RS-485 Stop Bit | <u>1</u> / 2 bits | |

Available Device Memory

The available setting range of device memory varies depending on the model. Be sure to set within the range available for the model to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|---------------|------|---------|
| --- | 02H | |

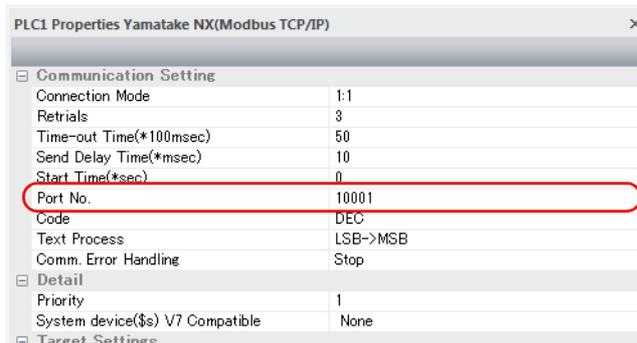
4.2.15 NX (MODBUS TCP/IP)

Communication Setting

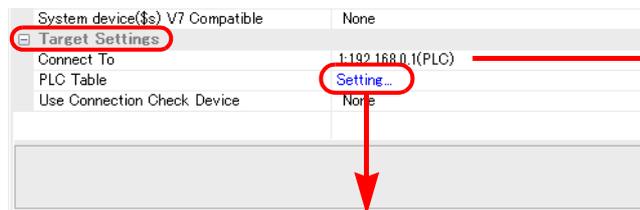
Editor

Make the following settings on the editor. For more information, see "1.3.2 Ethernet Communication".

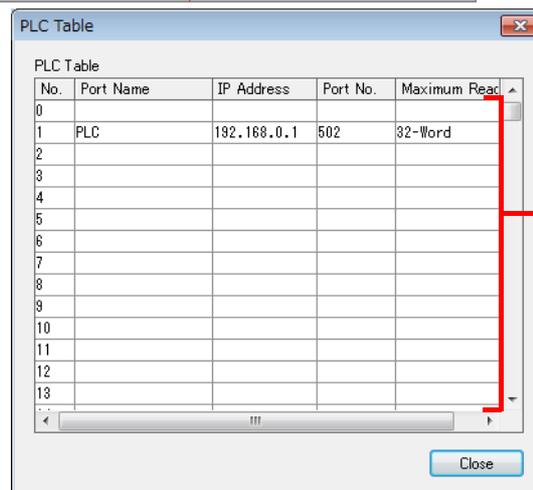
- IP address for the V9 unit
 - When specified on the screen program:
[System Setting] → [Hardware Setting] → [Local Port IP Address]
 - When specified on the V9 unit:
Local mode → [LAN Setting]
- Port number for the V9 unit (for communication with PLC)
[System Setting] → [Hardware Setting] → [PLC Properties] → [Communication Setting]



- IP address, port number, and maximum read value of the PLC
Register on the [PLC Table] in [System Setting] → [Hardware Setting] → [PLC Properties] → [Target Settings].



Valid only for 1 : 1 connection
Select the PLC for connection from those registered on the PLC table.



Set the IP address, port number, maximum read value, and whether or not to use the KeepAlive function of the controller.

Maximum read value:
Set a value according to the controller specification.
32 or 64 words

Controller

Make the following settings on [Actual Module Configuration] in the [SLP-NX] software.

| | Item | Remarks |
|--------------|----------------------------------|--------------|
| IP Address | - | |
| IP Setting | Net mask | |
| | Default gateway | |
| Port Setting | MODBUS communication port number | Default: 502 |

Available Device Memory

The available setting range of device memory varies depending on the model. Be sure to set within the range available for the model to be used. Use [TYPE] when assigning indirect device memory for macro programs.

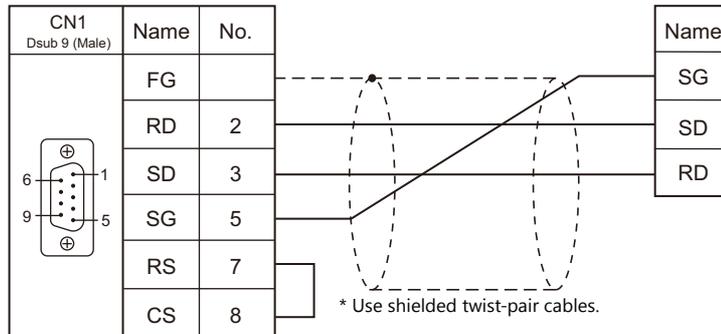
| Device Memory | TYPE | Remarks |
|---------------|------|---------|
| --- | 02H | |

4.2.16 Wiring Diagrams

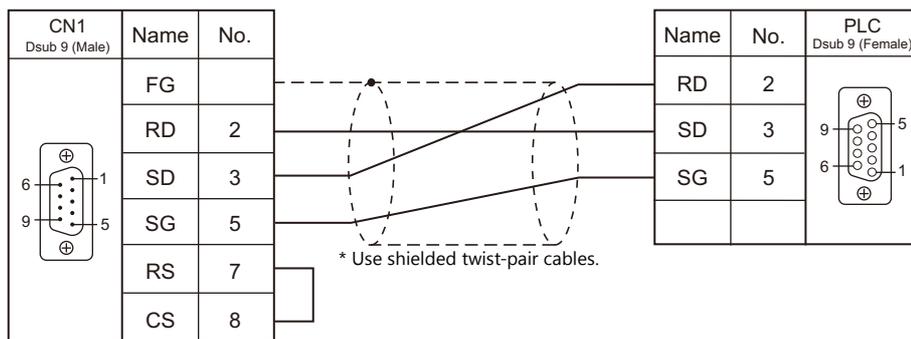
When Connected at CN1:

RS-232C

Wiring diagram 1 - C2

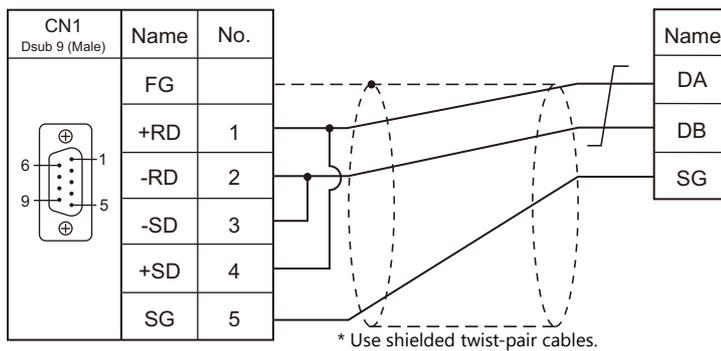


Wiring diagram 2 - C2

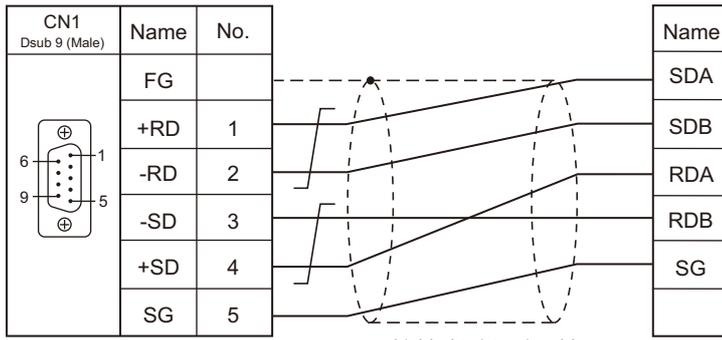


RS-422/RS-485

Wiring diagram 1 - C4

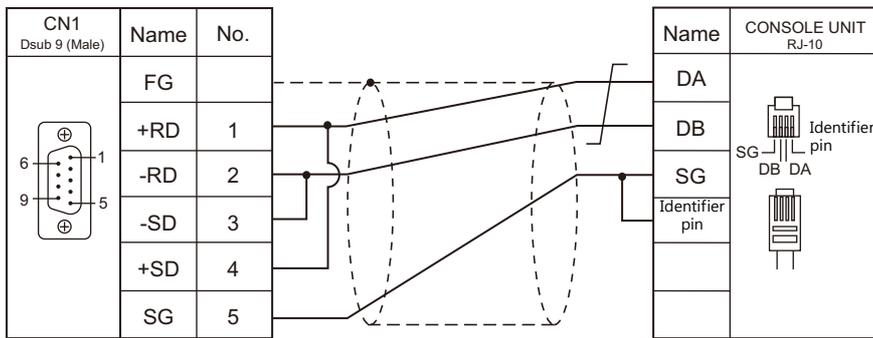


Wiring diagram 2 - C4



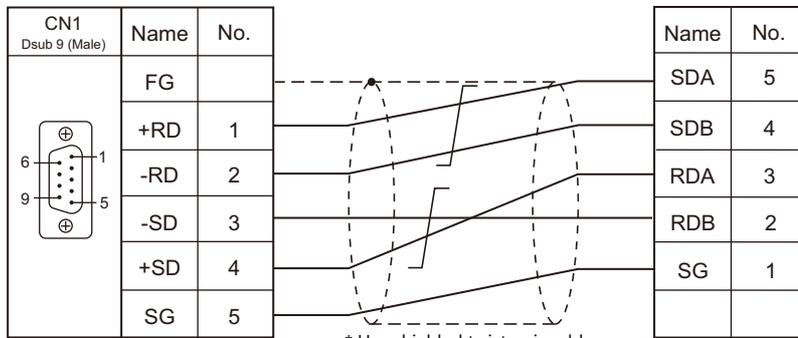
* Use shielded twist-pair cables.

Wiring diagram 3 - C4



* Use shielded twist-pair cables.

Wiring diagram 4 - C4

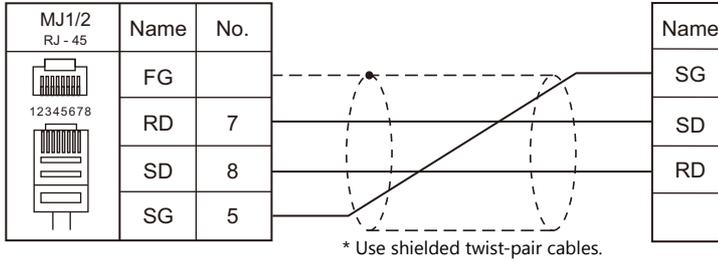


* Use shielded twist-pair cables.

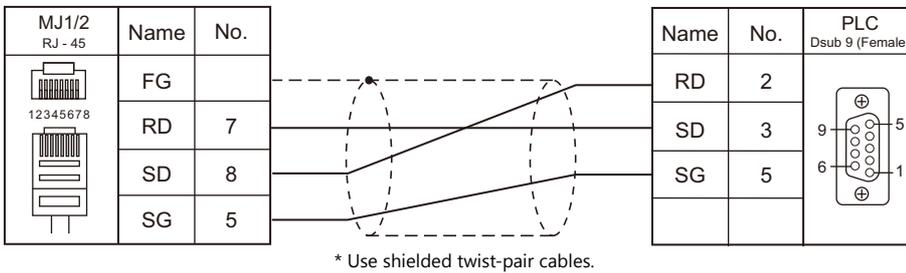
When Connected at MJ1/MJ2:

RS-232C

Wiring diagram 1 - M2

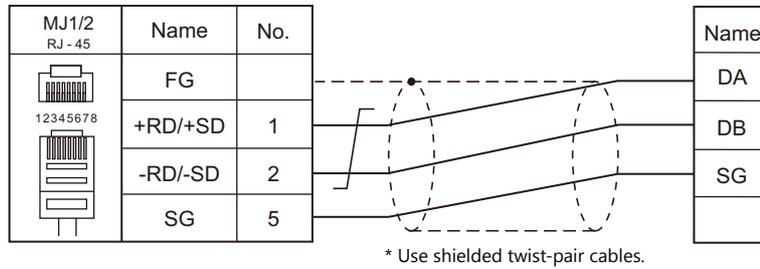


Wiring diagram 2 - M2

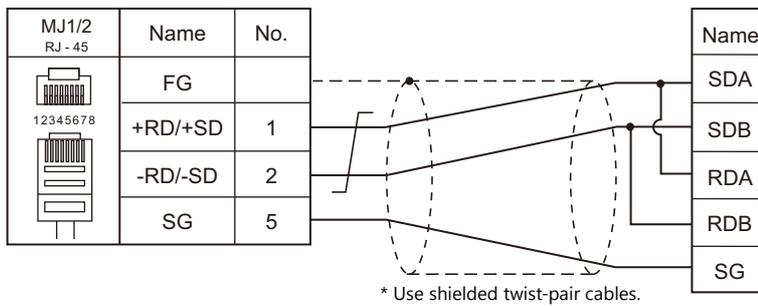


RS-422/RS-485

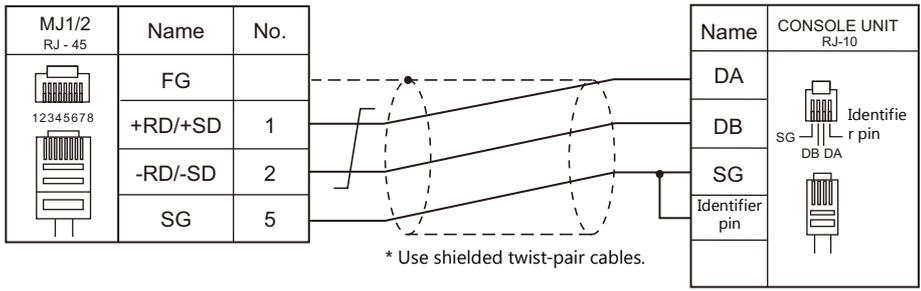
Wiring diagram 1 - M4



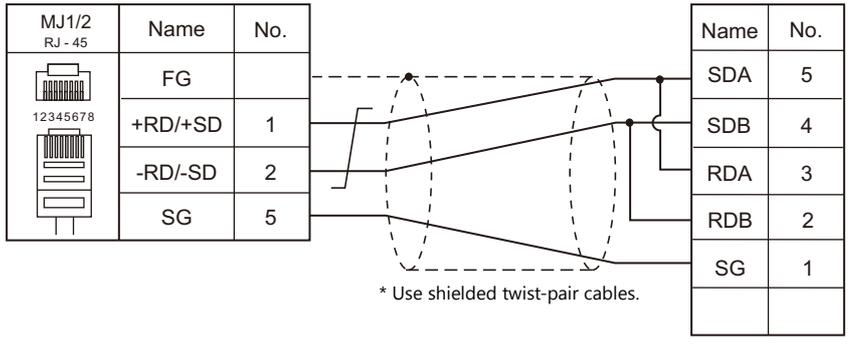
Wiring diagram 2 - M4



Wiring diagram 3 - M4



Wiring diagram 4 - M4



5. Baumuller

5.1 PLC Connection

5.1 PLC Connection

Serial Connection

| PLC Selection on the Editor | CPU | Unit/Port | Signal Level | Connection | | Ladder Transfer ^{*1} |
|-----------------------------|-----------|--------------|--------------|-----------------------|-----------------------|-------------------------------|
| | | | | CN1 | MJ1/MJ2 | |
| BMx-x-PLC | BMx-x-PLC | RS-232C port | RS-232C | Wiring diagram 1 - C2 | Wiring diagram 1 - M2 | × |
| | | RS-422 port | RS-422 | Wiring diagram 1 - C4 | × | |

*1 For the ladder transfer function, see the V9 Series Reference Manual.

5.1.1 BMx-x-PLC

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|---|---------|
| Connection Mode | <u>1:1</u> / Multi-link2 / Multi-link2 (Ethernet) | |
| Signal Level | RS-232C / <u>RS-422/485</u> | |
| Baud Rate | 4800 / 9600 / <u>19200</u> / 38400 bps | |
| Data Length | <u>8 bits</u> | |
| Stop Bit | <u>1 bit</u> | |
| Parity | <u>Even</u> | |

PLC

No particular setting is necessary on the PLC.

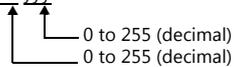
Available Device Memory

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|-----------------|------|---------|
| DB (Data Block) | 00H | |

* The assigned device memory is expressed as shown on the right when editing the screen.

Example: DB xxx yyy

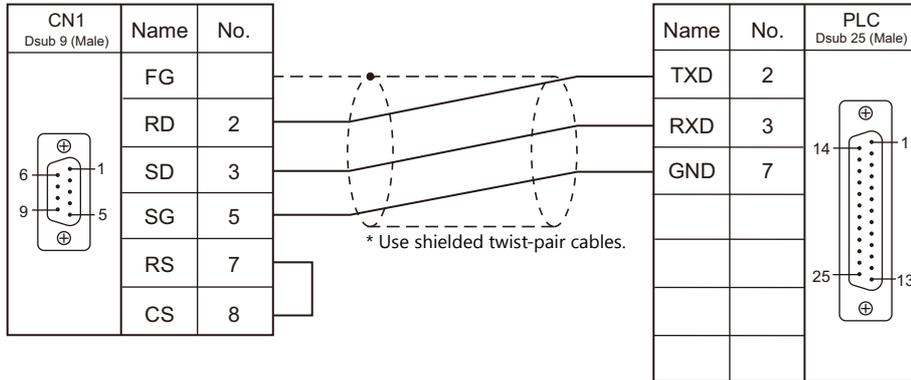


5.1.2 Wiring Diagrams

When Connected at CN1:

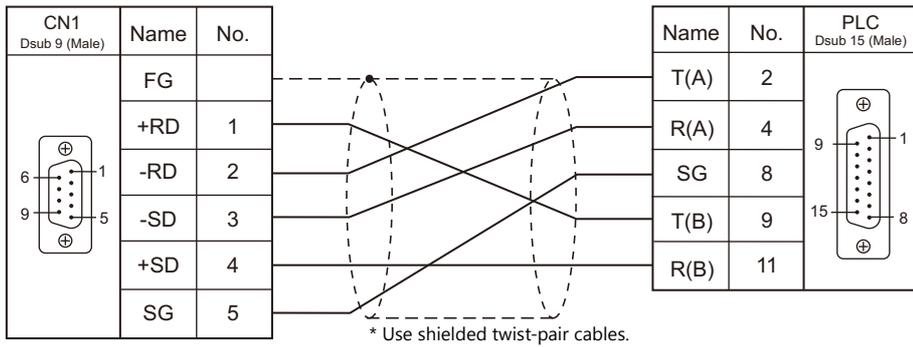
RS-232C

Wiring diagram 1 - C2



RS-422/RS-485

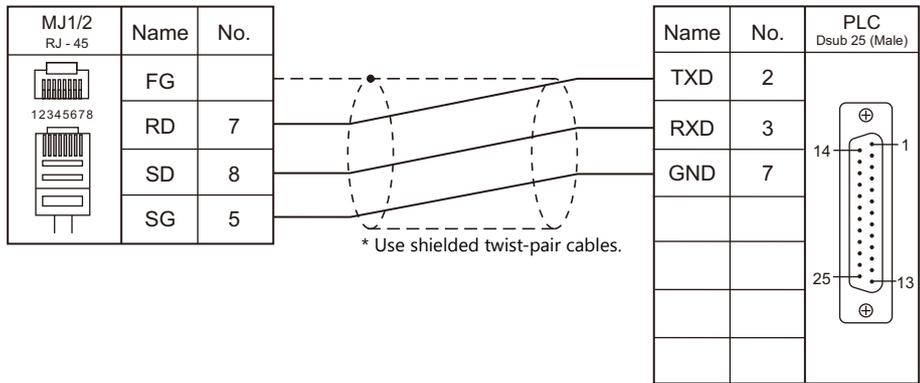
Wiring diagram 1 - C4



When Connected at MJ1/MJ2:

RS-232C

Wiring diagram 1 - M2



6. BECKHOFF

6.1 PLC Connection

6.1 PLC Connection

Ethernet Connection

| PLC Selection on the Editor | CPU | Unit | LAN port | TCP/IP | UDP/IP | Port No. | Keep Alive ^{*1} | Ladder Transfer ^{*2} |
|-----------------------------|----------------------------|----------------------|----------------|--------|--------|-------------|--------------------------|-------------------------------|
| ADS protocol (Ethernet) | BC9000 BC9100 BX9000 | KLxxxx ^{*3} | CPU (built-in) | ○ | × | 48898 fixed | ○ | × |

*1 For KeepAlive functions, see "1.3.2 Ethernet Communication".

*2 For the ladder transfer function, see the V9 Series Reference Manual.

*3 Use the same voltage (24 V) as for the CPU.

6.1.1 ADS Protocol (Ethernet)

Communication Setting

Editor

Communication settings

Make the following settings on the editor. For more information, see "1.3.2 Ethernet Communication".

- IP address for the V9 unit
 - When specified on the screen program:
[System Setting] → [Hardware Setting] → [Local Port IP Address]
 - When specified on the V9 unit:
Local mode → [LAN Setting]
- Port number for the V9 unit (for communication with PLC)
[System Setting] → [Hardware Setting] → [PLC Properties] → [Communication Setting]
- IP address and port number of the PLC
Register on the [PLC Table] in [System Setting] → [Hardware Setting] → [PLC Properties] → [Target Settings].

PLC

IP address setting

1. Set the DIP switches 9 and 10 to OFF.
2. Connect the PLC with the computer.
3. Launch "Command Prompt" on the computer.
4. Enter "Arp -a" and execute it.
The IP address (xxx.xxx.xxx.xxx) and the MAC address (zzz.zzz.zzz.zzz) of the PLC previously set are displayed.
(Check whether you can ping the IP address of the PLC ("ping xxx.xxx.xxx.xxx") successfully.)
5. Enter "Arp -d xxx.xxx.xxx.xxx" (IP address displayed in step 4.) and execute.
6. Enter "Arp -s yyy.yyy.yyy.yyy zzz.zzz.zzz.zzz" (new IP address and MAC address) and execute.
7. Enter "ping -l 123 yyy.yyy.yyy.yyy" (new IP address) and execute it. The new IP address becomes valid.

Port No.

TCP/IP port No. 48898 (fixed)

Available Device Memory

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | | TYPE | Remarks |
|---------------|--------------------------|------|--------------------------|
| P100-0 | Port 100 - Index group 0 | 00H | |
| P300-I | Port 300 - Inputs | 01H | Read only ^{*1} |
| P300-O | Port 300 - Outputs | 02H | Write only ^{*1} |
| P800-I | Port 800 - Inputs | 03H | *1 |
| P800-O | Port 800 - Outputs | 04H | *1 |
| P800-F | Port 800 - Flags | 05H | *1 |
| P801-I | Port 801 - Inputs | 06H | *1 |
| P801-O | Port 801 - Outputs | 07H | *1 |
| P801-F | Port 801 - Flags | 08H | *1 |

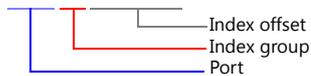
* Access to the device memory area is not allowed if a password is set for the area.

*1 The addresses are expressed in "bytes". For word designation, specify an even-numbered address.

Address denotations

The assigned device memory is expressed as shown below when editing the screen.

Example: P800 - F00000001



Indirect Device Memory Designation

For P300 / P800 / P801 device memory:

Specify a value obtained by dividing the address by 2. (Discard the fraction.)

Example: With indirect device memory designation, "9" is assigned for "P300-I00000013".
 $13 \text{ (HEX)} = 19 \text{ (DEC)}$
 $19 \div 2 = 9.5$

PLC_CTL

Macro command "PLC_CTL F0 F1 F2"

| Contents | F0 | F1 (= \$u n) | | F2 |
|----------------|---------------------|--------------|----------------------------|----|
| Access Inputs | 1 - 8 (PLC1 - 8) | n | Station number | 7 |
| | | n + 1 | Command: 0001H | |
| | | n + 2 | Port ^{*1} | |
| | | n + 3 | Index Group ^{*2} | |
| | | n + 4 | | |
| | | n + 5 | Index Offset ^{*2} | |
| | | n + 6 | | |
| n + 7 | Data | | | |
| Access Outputs | 1 - 8 (PLC1 - 8) | n | Station number | 8 |
| | | n + 1 | Command: 0002H | |
| | | n + 2 | Port ^{*1} | |
| | | n + 3 | Index Group ^{*2} | |
| | | n + 4 | | |
| | | n + 5 | Index Offset ^{*2} | |
| | | n + 6 | | |
| n + 7 | Data | | | |

 Return data: Data stored from temperature controller to V series

*1 Port setting values

| Port | Name |
|-------|------------------------|
| 100 | Logger (only NT - Log) |
| 110 | Eventlogger |
| 300 | IO |
| 301 | Additional Task 1 |
| 302 | Additional Task 2 |
| 801 | PLC Run-time System 1 |
| 811 | PLC Run-time System 2 |
| 821 | PLC Run-time System 3 |
| 831 | PLC Run-time System 4 |
| 900 | Camshaft Controller |
| 10000 | System Service |
| 14000 | Scope |

*2 Setting values for "Index Group" and "Index Offset"

| Access | | Index Group | Index Offset | Description |
|--------|--------|-------------|----------------|---|
| Input | Output | | | |
| ○ | ○ | 00004020H | 0 - 65535 | READ_M / WRITE_M |
| ○ | × | 00004025H | 0 | PLCADS_IJR_RMSIZE |
| ○ | ○ | 0000F003H | 0 | GET_SYMHANDLE_BYNAME |
| ○ | ○ | 0000F005H | 0 - 4294967295 | READ_SYMVAL_BYHANDLE WRITE_SYMVAL_BYHANDLE |
| × | ○ | 0000F006H | 0 | RELEASE_SYMHANDLE |
| ○ | ○ | 0000F020H | 0 - 4294967295 | READ_I / WRITE_I |
| ○ | × | 0000F025H | 0 | ADSIGRP_IOIMAGE_RISIZE |
| ○ | ○ | 0000F030H | 0 - 4294967295 | READ_Q / WRITE_Q |
| ○ | × | 0000F035H | 0 | ADSIGRP_IOIMAGE_ROSIZE |

7. CHINO

7.1 Temperature Controller/Servo/Inverter Connection

7.1 Temperature Controller/Servo/Inverter Connection

Digital Temperature Controller

| PLC Selection on the Editor | Model | Port | | Signal Level | Connection | | Lst File |
|-----------------------------|----------------------------------|----------------|--------|-----------------------|-----------------------|-----------------------|-------------|
| | | | | | CN1 | MJ1/MJ2 | |
| DP1000 | DP1xxxBRxx | Terminal block | | RS-232C | Wiring diagram 1 - C2 | Wiring diagram 1 - M2 | DP1000.Lst |
| | DP1xxxBAxx | Terminal block | | RS-422 | Wiring diagram 1 - C4 | × | |
| | DP10xxGRxx-xxx | Terminal block | COM1 | RS-232C | Wiring diagram 1 - C2 | Wiring diagram 1 - M2 | |
| | DP10xxGSxx-xxx | Terminal block | COM1 | RS-485 | Wiring diagram 2 - C4 | Wiring diagram 1 - M4 | |
| | DP10xxGAxx-xxx | Terminal block | COM1 | RS-422 | Wiring diagram 1 - C4 | × | |
| | DP10xxGBxx-xxx | Terminal block | COM1 | RS-232C | Wiring diagram 2 - C2 | Wiring diagram 2 - M2 | |
| | | | COM2 | | Wiring diagram 3 - C2 | Wiring diagram 3 - M2 | |
| | DP10xxGCxx-xxx | Terminal block | COM1 | RS-485 | Wiring diagram 3 - C4 | Wiring diagram 2 - M4 | |
| | | | COM2 | RS-232C | Wiring diagram 3 - C2 | Wiring diagram 3 - M2 | |
| | DP10xxGDxx-xxx | Terminal block | COM1 | RS-422 | Wiring diagram 4 - C4 | × | |
| | | | COM2 | RS-232C | Wiring diagram 3 - C2 | Wiring diagram 3 - M2 | |
| | DP10xxGExx-xxx | Terminal block | COM1 | RS-232C | Wiring diagram 2 - C2 | Wiring diagram 2 - M2 | |
| | | | COM2 | RS-485 | Wiring diagram 5 - C4 | Wiring diagram 3 - M4 | |
| | DP10xxGFxx-xxx | Terminal block | COM1 | RS-485 | Wiring diagram 3 - C4 | Wiring diagram 2 - M4 | |
| COM2 | | | RS-485 | Wiring diagram 5 - C4 | Wiring diagram 3 - M4 | | |
| DP10xxGGxx-xxx | Terminal block | COM1 | RS-422 | Wiring diagram 4 - C4 | × | | |
| | | COM2 | RS-485 | Wiring diagram 5 - C4 | Wiring diagram 3 - M4 | | |
| DB1000B (MODBUS RTU) | DB1xxxBRxx-xxx | Terminal block | | RS-232C | Wiring diagram 1 - C2 | Wiring diagram 1 - M2 | DB1000B.Lst |
| | DB1xxxBAxx-xxx | | | RS-422 | Wiring diagram 1 - C4 | × | |
| | DB1xxxBSxx-xxx | | | RS-485 | Wiring diagram 2 - C4 | Wiring diagram 1 - M4 | |
| LT230 (MODBUS RTU) | LT23xxxS00-xx LT23xxx200-xx | Terminal block | | RS-485 | Wiring diagram 2 - C4 | Wiring diagram 1 - M4 | LT230.Lst |
| LT300 (MODBUS RTU) | LT35xxxRx0-xxx LT37xxxRx0-xxx | Terminal block | | RS-232C | Wiring diagram 1 - C2 | Wiring diagram 1 - M2 | LT300.Lst |
| | LT35xxxAx0-xxx LT37xxxAx0-xxx | | | RS-422 | Wiring diagram 1 - C4 | × | |
| | LT35xxxSx0-xxx LT37xxxSx0-xxx | | | RS-485 | Wiring diagram 2 - C4 | Wiring diagram 1 - M4 | |
| | | | | | | | |
| LT400 Series (MODBUS RTU) | LT45xxxRxx-xxx LT47xxxRxx-xxx | Terminal block | | RS-232C | Wiring diagram 1 - C2 | Wiring diagram 1 - M2 | LT400.Lst |
| | LT45xxxAxx-xxx LT47xxxAxx-xxx | | | RS-422 | Wiring diagram 1 - C4 | × | |
| | LT45xxxSxx-xxx | | | RS-485 | Wiring diagram 2 - C4 | Wiring diagram 1 - M4 | |
| | | | | | | | |
| LT830 (MODBUS RTU) | LT830xx000-2xx | Terminal block | | RS-485 | Wiring diagram 2 - C4 | Wiring diagram 1 - M4 | LT830.Lst |

Graphic Recorder

| PLC Selection on the Editor | Model | Port | | Signal Level | Connection | | Lst File |
|-----------------------------|------------|----------------|--|--------------|-----------------------|-----------------------|------------|
| | | | | | CN1 | MJ1/MJ2 | |
| KR2000 (MODBUS RTU) | KR21xxxRxA | Terminal block | | RS-232C | Wiring diagram 1 - C2 | Wiring diagram 1 - M2 | KR2000.Lst |
| | | | | RS-485 | Wiring diagram 2 - C4 | Wiring diagram 1 - M4 | |
| | KR21xxxQxA | Terminal block | | RS-232C | Wiring diagram 1 - C2 | Wiring diagram 1 - M2 | |
| | | | | RS-485 | Wiring diagram 2 - C4 | Wiring diagram 1 - M4 | |

7.1.1 DP1000

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|---|---------|
| Connection Mode | 1 : 1 / <u>1 : n</u> / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet) | |
| Signal Level | <u>RS-232C</u> / RS-422/485 | |
| Baud Rate | 4800 / <u>9600</u> / 19200 / 38400 bps | |
| Data Length | <u>7</u> / 8 bits | |
| Stop Bit | <u>1</u> / 2 bits | |
| Parity | None / Odd / <u>Even</u> | |
| Target Port No. | <u>1</u> to 99 | |

Digital Program Controller

DP1000

The communication parameters can be set using keys attached to the digital program controller. Be sure to match the settings to those made under [Communication Setting] of the editor.

(Underlined setting: default)

| Mode No. | Item | Setting | Remarks |
|---|--|---|--|
| Mode 1 (Operation status selection) | Program start method * | MASTER COM.: Start by communication | |
| | Pattern selection method * | COM: Selection by communication | |
| Mode 8 (Communication setting) | Communication function, type | COM: Host communication | |
| | Device No. | 01 to 99 | Invalid during RS-232C communication 00: Communication not possible |
| | Baud rate | 4800 / 9600 bps | |
| | Communication characters (Data length, parity, stop bit) | Data length: <u>7</u> / 8 bits Parity: <u>Even</u> / Odd / None Stop bit: <u>1</u> / 2 bits | |

* To start program operation from the V series, select "MASTER COM." for program start method. To select a pattern number from the V series, select "COM" for pattern selection method.

DP1000G

The communication parameters can be set using keys attached to the digital program controller. Be sure to match the settings to those made under [Communication Setting] of the editor.

(Underlined setting: default)

| Mode No. | Item | Setting | | Remarks |
|--|---|---|--------------|---|
| | | COM1 | COM2 | |
| Mode 1 (Operation status selection) | Program start method * | COM: Start by communication | | |
| | Pattern selection method * | COM: Selection by communication | | |
| Mode 8 (Communication setting) | Communication type | Fixed according to communication specification | PORT2 | |
| | Protocol | PRIVATE: CHINO's conventional protocol | | When establishing a connection by using MODBUS RTU format, refer to "25. MODBUS". |
| | Communication function, type | COMM: Host communication | | |
| | Device No. | 01 to 99 | | Invalid during RS-232C communication 00: Communication not possible |
| | Baud rate | 4800 / 9600 / <u>19200</u> / 38400 bps | | |
| | Communication characters (Data length, parity, stop bit) | 7N1: data length 7 bits, without parity, stop bit 1 7N2: data length 7 bits, without parity, stop bit 2 7E1: data length 7 bits, even parity, stop bit 1 7E2: data length 7 bits, even parity, stop bit 2 7O1: data length 7 bits, odd parity, stop bit 1 7O2: data length 7 bits, odd parity, stop bit 2 <u>8N1: data length 8 bits, without parity, stop bit 1</u> 8N2: data length 8 bits, without parity, stop bit 2 8E1: data length 8 bits, even parity, stop bit 1 8E2: data length 8 bits, even parity, stop bit 2 8O1: data length 8 bits, odd parity, stop bit 1 8O2: data length 8 bits, odd parity, stop bit 2 | | |

* To start program operation from the V series, select "COM" for program start method. To select a pattern number from the V series, select "COM" for pattern selection method.

Notes on parameter change from the V series

Before changing parameters from the V series, function keys and the related mode in the setting menu must be locked using keys on the digital program controller.
For more information, refer to the instruction manual for the controller issued by the manufacturer.

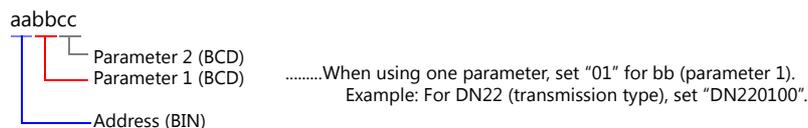
Available Device Memory

The available setting range of device memory varies depending on the model. Be sure to set within the range available for the model to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|----------------------|------|-------------|
| D (data) | 00H | Double-word |
| DN (individual data) | 01H | Double-word |
| PG (program) | 02H | Double-word |

Address denotations

The assigned device memory is expressed as shown below when editing the screen.



Note on device memory setting

Do not access addresses that are not assigned in the device memory map.

D (Data)

| Address Denotations | | | Name | Decimal Place | Command | |
|---------------------|-------------------|-------------------|--|---------------|----------|----------|
| Address (BIN) | Parameter 1 (BCD) | Parameter 2 (BCD) | | | Read | Write |
| 00 | 0 | 0 | Pattern No. | - | △ 1, △ 1 | - |
| 01 | 0 | 0 | Step No. | - | △ 1, △ 1 | - |
| 02 | 0 | 0 | PV status | - | △ 1, △ 1 | - |
| 03 | 0 | 0 | PV (measurement value) | 4 | △ 1, △ 1 | - |
| 04 | 0 | 0 | SV (setting value) | 4 | △ 1, △ 1 | - |
| 05 | 0 | 0 | Time display method | - | △ 1, △ 1 | △ 2, △ 8 |
| 06 | 0 | 0 | Time unit 1 | - | △ 1, △ 1 | - |
| 07 | 0 | 0 | Time | 2 | △ 1, △ 1 | - |
| 08 | 0 | 0 | MV1 status | - | △ 1, △ 1 | - |
| 09 | 0 | 0 | MV1 | 2 | △ 1, △ 1 | △ 2, △ 3 |
| 0a | 0 | 0 | MV2 status | - | △ 1, △ 1 | - |
| 0b | 0 | 0 | MV2 | 2 | △ 1, △ 1 | △ 2, △ 3 |
| 0e | 0 | 0 | Execution target SV | 4 | △ 1, △ 2 | - |
| 0f | 0 | 0 | Execution P | 1 | △ 1, △ 2 | △ 2, △ 2 |
| 10 | 0 | 0 | Execution I | - | △ 1, △ 2 | △ 2, △ 2 |
| 11 | 0 | 0 | Execution D | - | △ 1, △ 2 | △ 2, △ 2 |
| 12 | 0 | 0 | Execution AL1 | 4 | △ 1, △ 2 | △ 2, △ 2 |
| 13 | 0 | 0 | Execution AL2 | 4 | △ 1, △ 2 | △ 2, △ 2 |
| 14 | 0 | 0 | Execution AL3 | 4 | △ 1, △ 2 | △ 2, △ 2 |
| 15 | 0 | 0 | Execution AL4 | 4 | △ 1, △ 2 | △ 2, △ 2 |
| 16 | 0 | 0 | Execution OL | 1 | △ 1, △ 2 | △ 2, △ 2 |
| 17 | 0 | 0 | Execution OH | 1 | △ 1, △ 2 | △ 2, △ 2 |
| 18 | 0 | 0 | Execution change amount (OSL) | 1 | △ 1, △ 2 | △ 2, △ 2 |
| 19 | 0 | 0 | Execution sensor offset | 4 | △ 1, △ 2 | △ 2, △ 2 |
| 1a | 0 | 0 | SV value offset | 4 | △ 1, △ 2 | △ 2, △ 2 |
| 1b | 0 | 0 | 2nd P | 1 | △ 1, △ 2 | - |
| 1c | 0 | 0 | 2nd I | - | △ 1, △ 2 | - |
| 1d | 0 | 0 | 2nd D | - | △ 1, △ 2 | - |
| 20 | 0 | 0 | Controller / setting device | - | △ 1, △ 6 | - |
| 21 | 0 | 0 | Setting device / thermoelectric type / resistance type | - | △ 1, △ 6 | - |
| 22 | 0 | 0 | 1st output | - | △ 1, △ 6 | - |
| 23 | 0 | 0 | 2nd output | - | △ 1, △ 6 | - |
| 24 | 0 | 0 | Transmission | - | △ 1, △ 6 | - |
| 25 | 0 | 0 | Time signal | - | △ 1, △ 6 | - |
| 26 | 0 | 0 | External drive | - | △ 1, △ 6 | - |
| 27 | 0 | 0 | Pattern select | - | △ 1, △ 6 | - |
| 28 | 0 | 0 | Time unit 2 | - | △ 1, △ 6 | - |
| 2b | 0 | 0 | FNC key (lock / non-lock) | - | △ 1, △ 7 | △ 2, △ 7 |
| 2c | 0 | 0 | Mode 0 (lock / non-lock) | - | △ 1, △ 7 | △ 2, △ 7 |
| 2d | 0 | 0 | Lock 1 (lock / non-lock) | - | △ 1, △ 7 | △ 2, △ 7 |
| 2e | 0 | 0 | Lock 2 (lock / non-lock) | - | △ 1, △ 7 | △ 2, △ 7 |
| 2f | 0 | 0 | Lock 3 (lock / non-lock) | - | △ 1, △ 7 | △ 2, △ 7 |
| 30 | 0 | 0 | Lock 4 (lock / non-lock) | - | △ 1, △ 7 | △ 2, △ 7 |
| 31 | 0 | 0 | Lock 5 (lock / non-lock) | - | △ 1, △ 7 | △ 2, △ 7 |
| 32 | 0 | 0 | Lock 6 (lock / non-lock) | - | △ 1, △ 7 | △ 2, △ 7 |
| 33 | 0 | 0 | Lock 7 (lock / non-lock) | - | △ 1, △ 7 | △ 2, △ 7 |
| 34 | 0 | 0 | Lock 8 (lock / non-lock) | - | △ 1, △ 7 | △ 2, △ 7 |
| 35 | 0 | 0 | Lock 9 (lock / non-lock) | - | △ 1, △ 7 | △ 2, △ 7 |
| 38 | 0 | 0 | AL1 (ON/OFF) | - | △ 1, △ 8 | - |
| 39 | 0 | 0 | AL2 (ON/OFF) | - | △ 1, △ 8 | - |
| 3a | 0 | 0 | AL3 (ON/OFF) | - | △ 1, △ 8 | - |
| 3b | 0 | 0 | AL4 (ON/OFF) | - | △ 1, △ 8 | - |
| 3c | 0 | 0 | Wait time alert | - | △ 1, △ 8 | - |
| 3d | 0 | 0 | Error | - | △ 1, △ 8 | - |

| Address Denotations | | | Name | Decimal Place | Command | |
|---------------------|-------------------|-------------------|---------------|---------------|----------|----------|
| Address (BIN) | Parameter 1 (BCD) | Parameter 2 (BCD) | | | Read | Write |
| 3e | 0 | 0 | TS1 (ON/OFF) | - | △ 1, △ 8 | - |
| 3f | 0 | 0 | TS2 (ON/OFF) | - | △ 1, △ 8 | - |
| 40 | 0 | 0 | TS3 (ON/OFF) | - | △ 1, △ 8 | - |
| 41 | 0 | 0 | TS4 (ON/OFF) | - | △ 1, △ 8 | - |
| 42 | 0 | 0 | TS5 (ON/OFF) | - | △ 1, △ 8 | - |
| 43 | 0 | 0 | TS6 (ON/OFF) | - | △ 1, △ 8 | - |
| 44 | 0 | 0 | TS7 (ON/OFF) | - | △ 1, △ 8 | - |
| 45 | 0 | 0 | TS8 (ON/OFF) | - | △ 1, △ 8 | - |
| 46 | 0 | 0 | TS9 (ON/OFF) | - | △ 1, △ 8 | - |
| 47 | 0 | 0 | TS10 (ON/OFF) | - | △ 1, △ 8 | - |
| 4a | Pattern No. | 0 | RUN | - | △ 1, △ 9 | △ 2, △ 1 |
| 4b | 0 | 0 | STOP | - | △ 1, △ 9 | △ 2, △ 1 |
| 4c | 0 | 0 | RESET | - | △ 1, △ 9 | △ 2, △ 1 |
| 4d | 0 | 0 | END | - | △ 1, △ 9 | - |
| 4e | 0 | 0 | ADV | - | △ 1, △ 9 | △ 2, △ 1 |
| 4f | 0 | 0 | CONST | - | △ 1, △ 9 | △ 2, △ 4 |
| 50 | 0 | 0 | MAN1 | - | △ 1, △ 9 | △ 2, △ 3 |
| 51 | 0 | 0 | MAN2 | - | △ 1, △ 9 | △ 2, △ 3 |
| 52 | 0 | 0 | WAIT | - | △ 1, △ 9 | - |
| 53 | 0 | 0 | AT | - | △ 1, △ 9 | △ 2, △ 6 |
| 54 | 0 | 0 | FNC key LOCK | - | △ 1, △ 9 | - |
| 55 | 0 | 0 | M/S | - | △ 1, △ 9 | - |
| 56 | 0 | 0 | FAST | - | △ 1, △ 9 | - |
| 57 | 0 | 0 | SV Up | - | △ 1, △ 9 | - |
| 58 | 0 | 0 | SV Down | - | △ 1, △ 9 | - |
| 5b | 0 | 0 | Constant SV | 4 | △ 1, △ 1 | △ 2, △ 4 |

DN (Individual Data)

| Address Denotations | | | Name | Decimal Place | Command | |
|---------------------|----------------------------|-------------------|---------------------------------|---------------|----------|-------|
| Address (BIN) | Parameter 1 (BCD) | Parameter 2 (BCD) | | | Read | Write |
| 00 | Alarm No. (1 to 8) | 0 | AL1 | 4 | △ 1, △ 4 | △ 12 |
| 01 | Alarm No. (1 to 8) | 0 | AL2 | 4 | △ 1, △ 4 | △ 12 |
| 02 | Alarm No. (1 to 8) | 0 | AL3 | 4 | △ 1, △ 4 | △ 12 |
| 03 | Alarm No. (1 to 8) | 0 | AL4 | 4 | △ 1, △ 4 | △ 12 |
| 06 | PID No. (1 to 8, 91 to 98) | 0 | P | 1 | △ 1, △ 4 | △ 13 |
| 07 | PID No. (1 to 8, 91 to 98) | 0 | I | - | △ 1, △ 4 | △ 13 |
| 08 | PID No. (1 to 8, 91 to 98) | 0 | D | - | △ 1, △ 4 | △ 13 |
| 0b | Parameter No. (1 to 8) | 0 | Output change amount limit | 1 | △ 1, △ 4 | △ 14 |
| 0e | Parameter No. (1 to 8) | 0 | Output lower limit | 1 | △ 1, △ 4 | △ 15 |
| 0f | Parameter No. (1 to 8) | 0 | Output upper limit | 1 | △ 1, △ 4 | △ 15 |
| 12 | Parameter No. (1 to 8) | 0 | Sensor offset | 4 | △ 1, △ 4 | △ 16 |
| 15 | Parameter No. (1 to 8) | 0 | Actual temperature compensation | 4 | △ 1, △ 4 | △ 17 |
| 18 | Parameter No. (1 to 8) | 0 | Wait time alert | 2 | △ 1, △ 4 | △ 18 |
| 1b | Parameter No. (1 to 8) | 0 | Time signal ON time | 2 | △ 1, △ 4 | △ 19 |
| 1c | Parameter No. (1 to 8) | 0 | Time signal OFF time | 2 | △ 1, △ 4 | △ 19 |
| 1f | 1 | 0 | Digital filter | 1 | △ 1, △ 4 | △ 20 |

| Address Denotations | | | Name | Decimal Place | Command | |
|---------------------|---------------------------|-------------------|---|---------------|----------|-------|
| Address (BIN) | Parameter 1 (BCD) | Parameter 2 (BCD) | | | Read | Write |
| 22 | 1 | 0 | Transmission type | - | △ 1, △ 4 | △ 21 |
| 23 | 1 | 0 | Scale (min.) | 4 | △ 1, △ 4 | △ 21 |
| 24 | 1 | 0 | Scale (max.) | 4 | △ 1, △ 4 | △ 21 |
| 27 | 1 | 0 | 2nd output gap | 1 | △ 1, △ 4 | △ 22 |
| 2a | 1 | 0 | 2nd output P | 1 | △ 1, △ 4 | △ 23 |
| 2b | 1 | 0 | 2nd output I | - | △ 1, △ 4 | △ 23 |
| 2c | 1 | 0 | 2nd output D | - | △ 1, △ 4 | △ 23 |
| 2f | 1 | 0 | 2nd output change amount limit | 1 | △ 1, △ 4 | △ 24 |
| 32 | 1 | 0 | 2nd OL | 1 | △ 1, △ 4 | △ 25 |
| 33 | 1 | 0 | 2nd OH | 1 | △ 1, △ 4 | △ 25 |
| 36 | 1 | 0 | 2nd deadband | 1 | △ 1, △ 4 | △ 26 |
| 39 | 1 | 0 | 2nd PV output error | 1 | △ 1, △ 4 | △ 27 |
| 3c | 1 | 0 | 2nd output normal/reverse | - | △ 1, △ 4 | △ 28 |
| 3f | 1 | 0 | 2nd pulse cycle | - | △ 1, △ 4 | △ 29 |
| 42 | 1 | 0 | Measurement input unit (input type No.) | - | △ 1, △ 4 | △ 30 |
| 43 | 1 | 0 | Measurement input unit (unit) | - | △ 1, △ 4 | △ 30 |
| 46 | 1 | 0 | CJ INT/EXT | - | △ 1, △ 4 | △ 31 |
| 49 | 1 | 0 | SV decimal place | - | △ 1, △ 4 | △ 32 |
| 4c | 1 | 0 | PV decimal place | - | △ 1, △ 4 | △ 33 |
| 4f | 1 | 0 | Alarm filter | - | △ 1, △ 4 | △ 34 |
| 52 | Alarm No. (1 to 4) | 0 | Alarm mode | - | △ 1, △ 4 | △ 35 |
| 53 | 1 | 0 | Alarm deadband | 4 | △ 1, △ 4 | △ 35 |
| 56 | 1 | 0 | Deadband | 1 | △ 1, △ 4 | △ 36 |
| 59 | 1 | 0 | Pulse cycle | - | △ 1, △ 4 | △ 37 |
| 5c | 1 | 0 | Zero | 1 | △ 1, △ 4 | △ 38 |
| 5d | 1 | 0 | Span | 1 | △ 1, △ 4 | △ 38 |
| 5e | 1 | 0 | Deadband | 1 | △ 1, △ 4 | △ 38 |
| 61 | 1 | 0 | Output preset | 1 | △ 1, △ 4 | △ 39 |
| 64 | 1 | 0 | Output in PV error | 1 | △ 1, △ 4 | △ 40 |
| 67 | 1 | 0 | Output normal/reverse | - | △ 1, △ 4 | △ 41 |
| 6a | 1 | 0 | Linear range (zero) | 4 | △ 1, △ 4 | △ 42 |
| 6b | 1 | 0 | Linear range (span) | 4 | △ 1, △ 4 | △ 42 |
| 6e | 1 | 0 | Linear scale (min.) | 4 | △ 1, △ 4 | △ 43 |
| 6f | 1 | 0 | Linear scale (max.) | 4 | △ 1, △ 4 | △ 43 |
| 72 | 1 | 0 | ARW (lower limit) | 1 | △ 1, △ 4 | △ 44 |
| 73 | 1 | 0 | ARW (upper limit) | 1 | △ 1, △ 4 | △ 44 |
| 76 | Parameter No. (1 to 8) | 0 | AT2SV (ON/OFF) | - | △ 1, △ 4 | △ 45 |
| 77 | Parameter No. (1 to 8) | 0 | AT2SV | 4 | △ 1, △ 4 | △ 45 |
| 7a | Parameter No. (1 to 7) | 0 | Break SV | 4 | △ 1, △ 4 | △ 46 |
| 7d | Parameter No. (1 to 8) | 0 | AT3SV (ON/OFF) | - | △ 1, △ 4 | △ 47 |
| 7e | Parameter No. (1 to 8) | 0 | AT3SV | 4 | △ 1, △ 4 | △ 47 |
| 81 | 1 | 0 | AT start direction | - | △ 1, △ 4 | △ 48 |
| 84 | 1 | 0 | SV at reset | 4 | △ 1, △ 4 | △ 49 |
| 87 | 1 | 0 | SV display scale (min.) | 4 | △ 1, △ 4 | △ 50 |
| 88 | 1 | 0 | SV display scale (max.) | 4 | △ 1, △ 4 | △ 50 |
| 8b | 1 | 0 | Thermocouple type (thermocouple No.) | - | △ 1, △ 4 | △ 51 |
| 8c | 1 | 0 | Thermocouple type (unit) | - | △ 1, △ 4 | △ 51 |
| 8f | 1 | 0 | SV scale (min.) | 4 | △ 1, △ 4 | △ 52 |
| 90 | 1 | 0 | SV scale (max.) | 4 | △ 1, △ 4 | △ 52 |

PG (Program)

| Address Denotations | | | Name | Decimal Place | Command | |
|---------------------|-------------------|-------------------|-------------------------------------|---------------|----------|----------|
| Address (BIN) | Parameter 1 (BCD) | Parameter 2 (BCD) | | | Read | Write |
| 00 | Pattern No. | 0 | Start SV | 4 | △ 1, △ 3 | △ 3, △ 1 |
| 01 | Pattern No. | 0 | SV/PV start | - | △ 1, △ 3 | △ 3, △ 1 |
| 04 | Pattern No. | Step No. | Program setting SV | 4 | △ 1, △ 3 | △ 3, △ 2 |
| 05 | Pattern No. | Step No. | Program setting time | 2 | △ 1, △ 3 | △ 3, △ 2 |
| 06 | Pattern No. | Step No. | Step repeat times | - | △ 1, △ 3 | - |
| 07 | Pattern No. | Step No. | PID No. | - | △ 1, △ 3 | △ 3, △ 4 |
| 08 | Pattern No. | Step No. | ALM No. | - | △ 1, △ 3 | △ 3, △ 4 |
| 09 | Pattern No. | Step No. | OPL No. | - | △ 1, △ 3 | △ 3, △ 4 |
| 0a | Pattern No. | Step No. | OSL No. | - | △ 1, △ 3 | △ 3, △ 4 |
| 0b | Pattern No. | Step No. | Sensor offset No. | - | △ 1, △ 3 | △ 3, △ 4 |
| 0c | Pattern No. | Step No. | Actual temperature compensation No. | - | △ 1, △ 3 | △ 3, △ 4 |
| 0d | Pattern No. | Step No. | Wait time No. | - | △ 1, △ 3 | △ 3, △ 4 |
| 0e | Pattern No. | Step No. | TS1 | - | △ 1, △ 3 | △ 3, △ 4 |
| 0f | Pattern No. | Step No. | TS2 | - | △ 1, △ 3 | △ 3, △ 4 |
| 10 | Pattern No. | Step No. | TS3 | - | △ 1, △ 3 | △ 3, △ 4 |
| 11 | Pattern No. | Step No. | TS4 | - | △ 1, △ 3 | △ 3, △ 4 |
| 12 | Pattern No. | Step No. | TS5 | - | △ 1, △ 3 | △ 3, △ 4 |
| 13 | Pattern No. | Step No. | TS6 | - | △ 1, △ 3 | △ 3, △ 4 |
| 14 | Pattern No. | Step No. | TS7 | - | △ 1, △ 3 | △ 3, △ 4 |
| 15 | Pattern No. | Step No. | TS8 | - | △ 1, △ 3 | △ 3, △ 4 |
| 16 | Pattern No. | Step No. | TS9 | - | △ 1, △ 3 | △ 3, △ 4 |
| 17 | Pattern No. | Step No. | TS10 | - | △ 1, △ 3 | △ 3, △ 4 |
| 1a | Pattern No. | Step No. | Link target pattern No. | - | △ 1, △ 3 | △ 3, △ 3 |
| 1b | Pattern No. | Step No. | Output at 1st end | - | △ 1, △ 3 | △ 3, △ 3 |
| 1c | Pattern No. | Step No. | Output at 2nd end | - | △ 1, △ 3 | △ 3, △ 3 |
| 1f | 0 | 0 | Pattern repeat times | - | △ 1, △ 3 | △ 3, △ 6 |
| 22 | Pattern No. | 0 | Set number of steps | - | △ 1, △ 5 | - |
| 23 | Pattern No. | 0 | Remaining number of steps | - | △ 1, △ 5 | - |

PLC_CTL

Macro command "PLC_CTL F0 F1 F2"

| Contents | F0 | F1 (= \$u n) | | F2 |
|----------------|---------------------|--------------|--|----|
| Alarm reset | 1 - 8 (PLC1 - 8) | n | Station number | 2 |
| | | n + 1 | Command: 0000H | |
| Pattern select | 1 - 8 (PLC1 - 8) | n | Station number | 3 |
| | | n + 1 | Command: 0001H | |
| | | n + 2 | Pattern No. | |
| Step repeat | 1 - 8 (PLC1 - 8) | n | Station number | 6 |
| | | n + 1 | Command: 0002H | |
| | | n + 2 | Pattern No. | |
| | | n + 3 | Start step | |
| | | n + 4 | End step | |
| Pattern copy | 1 - 8 (PLC1 - 8) | n | Station number | 4 |
| | | n + 1 | Command: 0003H | |
| | | n + 2 | Copy source pattern No. | |
| | | n + 3 | Copy target pattern No. | |
| Pattern clear | 1 - 8 (PLC1 - 8) | n | Station number | 3 |
| | | n + 1 | Command: 0004H | |
| | | n + 2 | Pattern No. Clear all patterns: 0000H Clear individual pattern: 0001H to 0030H | |

7.1.2 DB1000B (MODBUS RTU)

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|--|---------|
| Connection Mode | 1 : 1 / <u>1 : n</u> / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet) | |
| Signal Level | RS-232C / <u>RS-422/485</u> | |
| Baud Rate | 4800 / <u>9600</u> / 19200 / 38400 bps | |
| Data Length | <u>8 bits</u> | |
| Stop Bit | <u>1</u> / 2 bits | |
| Parity | <u>None</u> / Odd / Even | |
| Target Port No. | <u>1</u> to 99 | |

Digital Indicating Controller

The communication parameters can be set using keys attached to the digital indicating controller. Be sure to match the settings to those made under [Communication Setting] of the editor.

(Underlined setting: default)

| Mode No. | Item | Setting | Remarks |
|-----------------------------------|---|--|---------|
| Mode 7 (Communication setting) | Baud rate | 4800 / <u>9600</u> / 19200 / 38400 bps | |
| | Device No. | <u>01</u> to 99 | |
| | Communication function | <u>COM: Host communication</u> | |
| | Communication protocol | <u>MODBUS (RTU)</u> | |
| | Communication characters (Data length, parity, stop bit) | <u>8 bits / without parity / 1 bit</u> 8 bits / without parity / 2 bits 8 bits / even parity / 1 bit 8 bits / even parity / 2 bits 8 bits / odd parity / 1 bit 8 bits / odd parity / 2 bits | |

Notes on parameter change from the V series

Before changing parameters from the V series, all modes on the setting screen must be locked using keys on the digital indicating controller. For more information, refer to the instruction manual for the controller issued by the manufacturer.

Available Device Memory

The available setting range of device memory varies depending on the model. Be sure to set within the range available for the model to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|---------------------------|------|-----------|
| 4 (analog setting value) | 00H | |
| 3 (analog input data) | 01H | Read only |
| 0 (digital setting value) | 02H | |
| 1 (digital input data) | 03H | Read only |

Indirect Device Memory Designation

For the device memory address number, specify the value obtained by subtracting "1" from the actual address.

7.1.3 LT230 (MODBUS RTU)

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|--|---------|
| Connection Mode | 1 : 1 / <u>1 : n</u> / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet) | |
| Signal Level | <u>RS-422/485</u> | |
| Baud Rate | <u>9600</u> / 19200 bps | |
| Data Length | <u>8 bits</u> | |
| Stop Bit | <u>1</u> / 2 bits | |
| Parity | <u>None</u> / Odd / Even | |
| Target Port No. | <u>1</u> to 99 | |

Digital Indicating Controller

The communication parameters can be set using keys attached to the digital indicating controller. Be sure to match the settings to those made under [Communication Setting] of the editor.

(Underlined setting: default)

| Mode | Indication | Item | Setting |
|---------------------------------------|------------|---|---|
| Mode 1 eng (engineering) | LoCK | Key lock | 4: All items prohibited * |
| Mode 7 com (communication setting) | PtCL | Communication protocol | <u>rtU: MODBUS (RTU)</u> |
| | FUnC | Communication function | <u>Com: Host communication</u> |
| | AdrS | Device No. | <u>1</u> to 99 |
| | rAtE | Baud rate | <u>9600</u> / 19200 bps |
| | CHAr | Character (Data length, parity, stop bit) | <u>5: 8 bits / without parity / 1 bit</u> 6: 8 bits / without parity / 2 bits 7: 8 bits / even parity / 1 bit 8: 8 bits / even parity / 2 bits 9: 8 bits / odd parity / 1 bit 10: 8 bits / odd parity / 2 bits |

* When changing parameters from the V series, set "LoCK (key lock): 4".

Available Device Memory

The available setting range of device memory varies depending on the model. Be sure to set within the range available for the model to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|---------------------------|------|-----------|
| 4 (analog setting value) | 00H | |
| 3 (analog input data) | 01H | Read only |
| 0 (digital setting value) | 02H | |
| 1 (digital input data) | 03H | Read only |

Indirect Device Memory Designation

For the device memory address number, specify the value obtained by subtracting "1" from the actual address.

7.1.4 LT300 (MODBUS RTU)

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|---|---------|
| Connection Mode | 1 : 1 / <u>1 : n</u> / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet) | |
| Signal Level | RS-232C / <u>RS-422/485</u> | |
| Baud Rate | <u>9600</u> / 19200 bps | |
| Data Length | <u>8 bits</u> | |
| Stop Bit | <u>1</u> / 2 bits | |
| Parity | <u>None</u> / Odd / Even | |
| Target Port No. | <u>1</u> to 99 | |

Digital Indicating Controller

The communication parameters can be set using keys attached to the digital indicating controller. Be sure to match the settings to those made under [Communication Setting] of the editor.

(Underlined setting: default)

| Mode | Indication | Item | Setting |
|---------------------------------------|------------|---|---|
| Mode 1 eng (engineering) | LoCK | Key lock | 4: All items prohibited * |
| Mode 7 com (communication setting) | PtCL | Communication protocol | <u>rtU: MODBUS (RTU)</u> |
| | FUnC | Communication function | <u>Com: Host communication</u> |
| | AdrS | Device No. | <u>01</u> to 99 |
| | rAtE | Baud rate | <u>9600</u> / 19200 bps |
| | CHAR | Character (Data length, parity, stop bit) | <u>5: 8 bits / without parity / 1 bit</u> 6: 8 bits / without parity / 2 bits 7: 8 bits / even parity / 1 bit 8: 8 bits / even parity / 2 bits 9: 8 bits / odd parity / 1 bit 10: 8 bits / odd parity / 2 bits |

* When changing parameters from the V series, set "LoCK (key lock): 4".

Available Device Memory

The available setting range of device memory varies depending on the model. Be sure to set within the range available for the model to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|---------------------------|------|-----------|
| 4 (analog setting value) | 00H | |
| 3 (analog input data) | 01H | Read only |
| 0 (digital setting value) | 02H | |
| 1 (digital input data) | 03H | Read only |

Indirect Device Memory Designation

For the device memory address number, specify the value obtained by subtracting "1" from the actual address.

7.1.5 LT400 Series (MODBUS RTU)

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|---|---------|
| Connection Mode | <u>1</u> : 1 / <u>1:n</u> / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet) | |
| Signal Level | RS-232C / <u>RS-422/485</u> | |
| Baud Rate | <u>9600</u> / 19200 bps | |
| Data Length | <u>8</u> bits | |
| Stop Bit | <u>1</u> / 2 bits | |
| Parity | <u>None</u> / Odd / Even | |
| Target Port No. | <u>1</u> to 99 | |

Digital Indicating Controller

The communication parameters can be set using keys attached to the digital indicating controller. Be sure to match the settings to those made under [Communication Setting] of the editor.

(Underlined setting: default)

| Mode | Display | Item | Setting |
|--|---------|---|---|
| Mode 1 eng (engineering) | LoCK | Key lock | 4: All items prohibited * |
| Mode 7 commu (communication setting) | PrtCL | Communication protocol | <u>rtU: MODBUS (RTU)</u> |
| | FUnC | Communication function | <u>Com: Host communication</u> |
| | AdrS | Device No. | <u>01</u> to 99 |
| | rAtE | Baud rate | <u>9600</u> / 19200 bps |
| | CHArA | Character (Data length, parity, stop bit) | <u>8N1</u> : 8 bits / without parity / 1 bit 8N2: 8 bits / without parity / 2 bits 8E1: 8 bits / even parity / 1 bit 8E2: 8 bits / even parity / 2 bits 8O1: 8 bits / odd parity / 1 bit 8O2: 8 bits / odd parity / 2 bits |

* When changing parameters from the V series, set "LoCK (key lock): 4".

Available Device Memory

The available setting range of device memory varies depending on the model. Be sure to set within the range available for the model to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|---------------------------|------|-----------|
| 4 (analog setting value) | 00H | |
| 3 (analog input data) | 01H | Read only |
| 0 (digital setting value) | 02H | |
| 1 (digital input data) | 03H | Read only |

Indirect Device Memory Designation

For the device memory address number, specify the value obtained by subtracting "1" from the actual address.

7.1.6 LT830 (MODBUS RTU)

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|--|---------|
| Connection Mode | 1 : 1 / <u>1 : n</u> / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet) | |
| Signal Level | <u>RS-422/485</u> | |
| Baud Rate | <u>9600</u> / 19200 bps | |
| Data Length | <u>8 bits</u> | |
| Stop Bit | <u>1</u> / 2 bits | |
| Parity | <u>None</u> / Odd / Even | |
| Target Port No. | <u>1</u> to 99 | |

Digital Indicating Controller

The communication parameters can be set using keys attached to the digital indicating controller. Be sure to match the settings to those made under [Communication Setting] of the editor.

(Underlined setting: default)

| Mode | Indication | Item | Setting | Remarks |
|--|------------|---|--|---------|
| Mode 5 type (type) | LoCK | Lock function | 3: All items prohibited * | |
| Mode 6 com (communication setting) | PtCL | Communication protocol | <u>rtU: MODBUS (RTU)</u> | |
| | FUnC | Communication function | <u>Com: Host communication</u> | |
| | AdrS | Device No. | <u>1</u> to 99 | |
| | rAtE | Baud rate | <u>9600</u> / 19200 bps | |
| | CHAr | Character (Data length, parity, stop bit) | <u>8n1: 8 bits / without parity / 1 bit</u> 8n2: 8 bits / without parity / 2 bits 8E1: 8 bits / even parity / 1 bit 8E2: 8 bits / even parity / 2 bits 8o1: 8 bits / odd parity / 1 bit 8o2: 8 bits / odd parity / 2 bits | |

* When changing parameters from the V series, set "LoCK (lock function): 3".

Available Device Memory

The available setting range of device memory varies depending on the model. Be sure to set within the range available for the model to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|---------------------------|------|-----------|
| 4 (analog setting value) | 00H | |
| 3 (analog input data) | 01H | Read only |
| 0 (digital setting value) | 02H | |
| 1 (digital input data) | 03H | Read only |

Indirect Device Memory Designation

For the device memory address number, specify the value obtained by subtracting "1" from the actual address.

7.1.7 KR2000 (MODBUS RTU)

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|--|---------|
| Connection Mode | 1 : 1 / <u>1 : n</u> / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet) | |
| Signal Level | RS-232C / <u>RS-422/485</u> | |
| Baud Rate | <u>9600</u> / 19200 bps | |
| Data Length | <u>8 bits</u> | |
| Stop Bit | <u>1</u> / 2 bits | |
| Parity | <u>None</u> / Odd / Even | |
| Target Port No. | <u>1</u> to 31 | |

Graphic Recorder

Selector switch

When establishing a communication with a graphic recorder, set the selector switch at the top of the unit.

(Underlined setting: default)

| Selector switch | Setting | Remarks |
|--|---|---|
| 485  232C | 232C: RS-232C connection <u>485: RS-485 connection</u> | Switch the signal with the power to the recorder OFF. |

Communication setting

The communication parameters can be set using MENU keys attached to the graphic recorder. Be sure to match the settings to those made under [Communication Setting] of the editor.

(Underlined setting: default)

| Setting Menu | Menu | Item | Setting | Remarks |
|----------------|--------------------|--|--|---------|
| System setting | Host communication | Communication mode | <u>RTU: MODBUS (RTU)</u> | |
| | | Device address | <u>01</u> to 31 | |
| | | Bit rate | <u>9600</u> / 19200 bps | |
| | | Communication characters (Data length, parity, stop bit) | <u>8N1: 8 bits / without parity / 1 bit</u> 8N2: 8 bits / without parity / 2 bits 8E1: 8 bits / even parity / 1 bit 8E2: 8 bits / even parity / 2 bits 8O1: 8 bits / odd parity / 1 bit 8O2: 8 bits / odd parity / 2 bits | |

Available Device Memory

The available setting range of device memory varies depending on the model. Be sure to set within the range available for the model to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|---------------------------|------|-----------|
| 4 (analog setting value) | 00H | |
| 3 (analog input data) | 01H | Read only |
| 0 (digital setting value) | 02H | |
| 1 (digital input data) | 03H | Read only |

Indirect Device Memory Designation

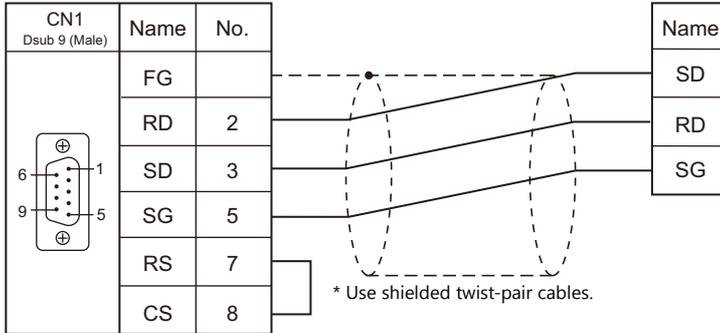
For the device memory address number, specify the value obtained by subtracting "1" from the actual address.

7.1.8 Wiring Diagrams

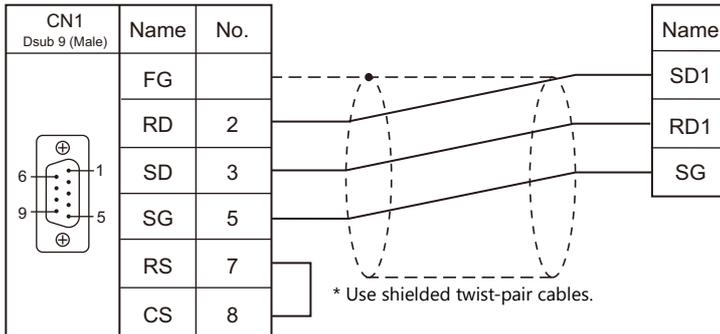
When Connected at CN1:

RS-232C

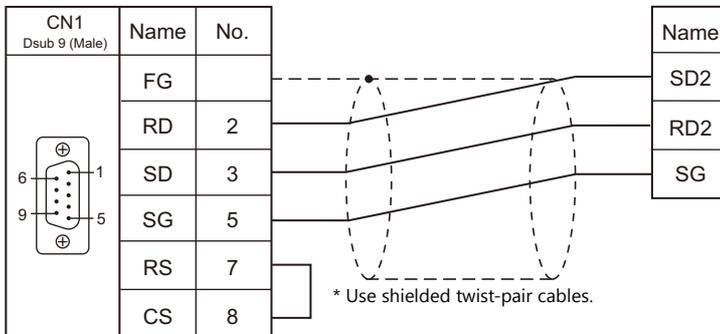
Wiring diagram 1 - C2



Wiring diagram 2 - C2

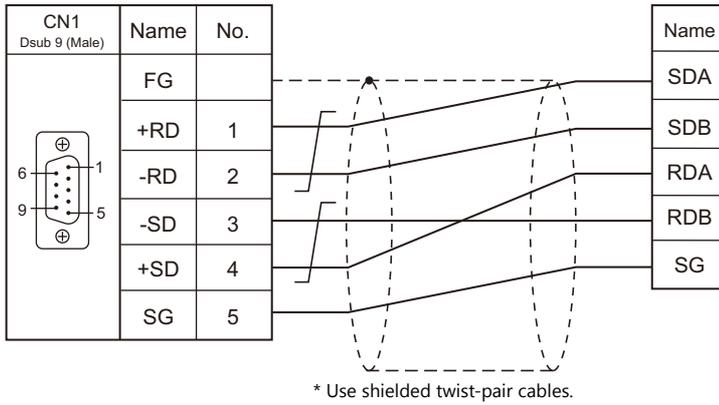


Wiring diagram 3 - C2

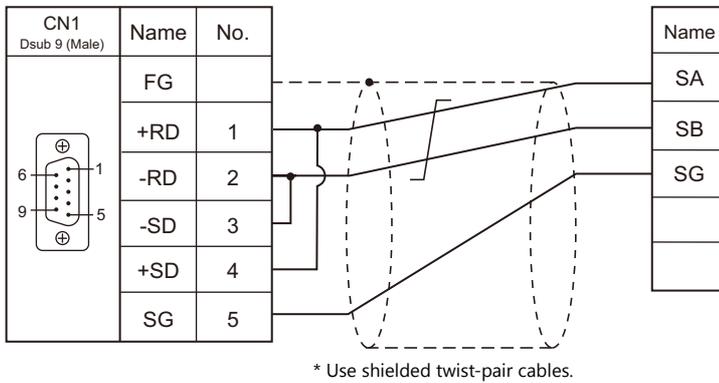


RS-422/RS-485

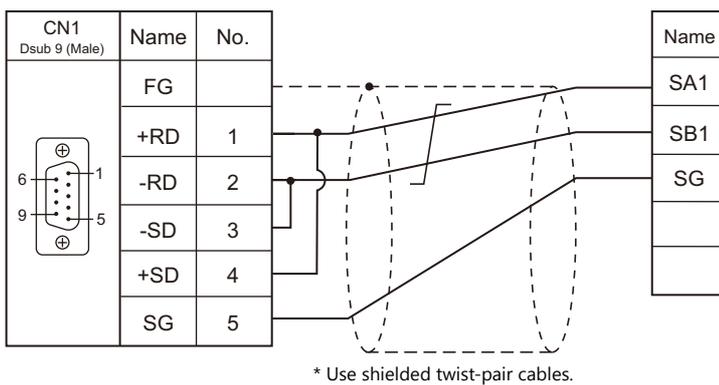
Wiring diagram 1 - C4



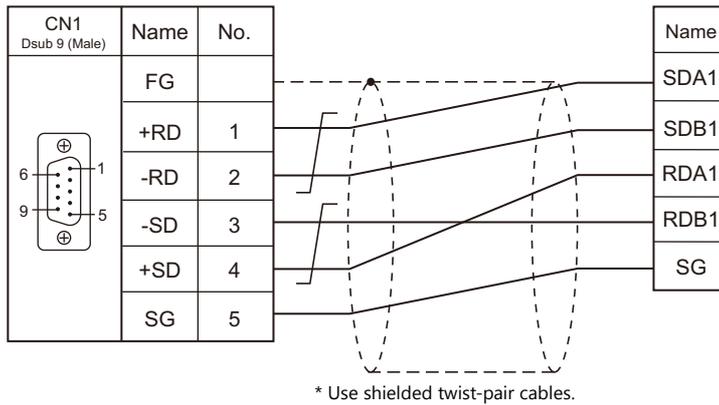
Wiring diagram 2 - C4



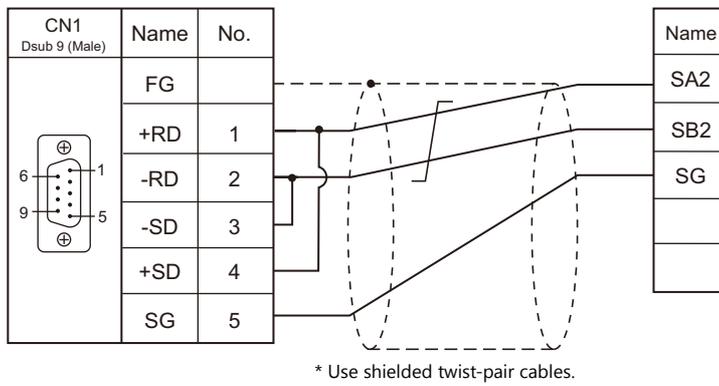
Wiring diagram 3 - C4



Wiring diagram 4 - C4



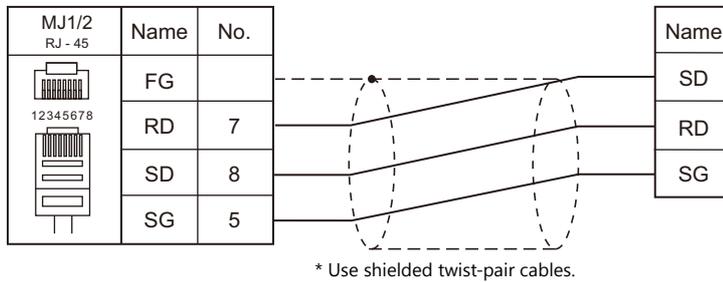
Wiring diagram 5 - C4



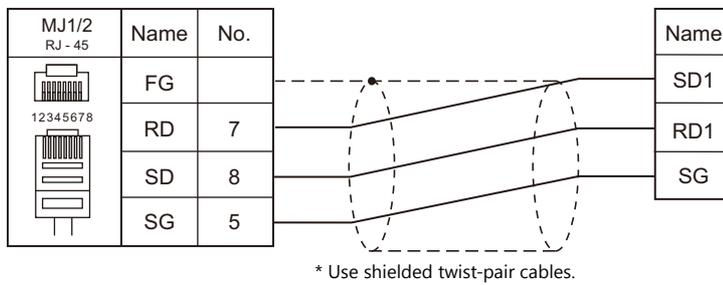
When Connected at MJ1/MJ2:

RS-232C

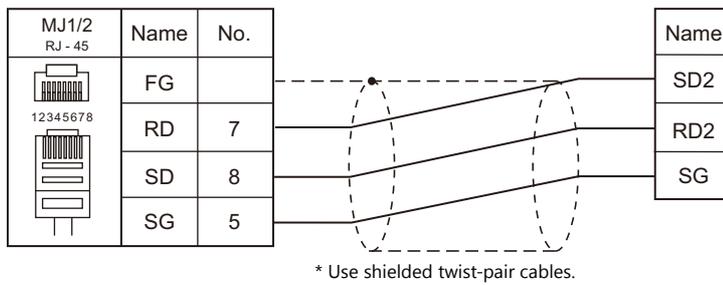
Wiring diagram 1 - M2



Wiring diagram 2 - M2

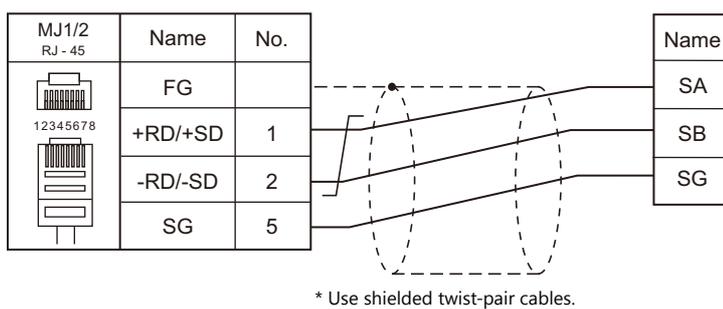


Wiring diagram 3 - M2

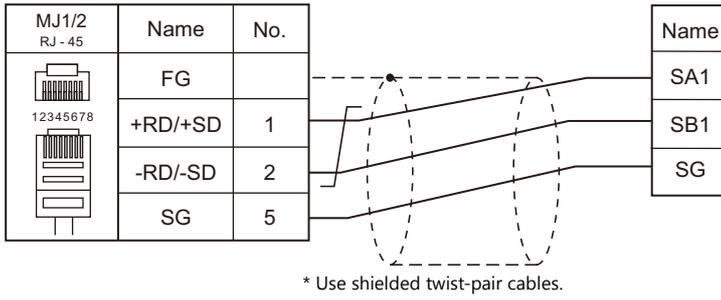


RS-422/RS-485

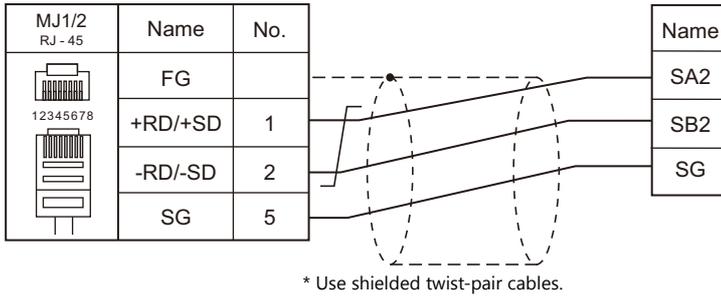
Wiring diagram 1 - M4



Wiring diagram 2 - M4



Wiring diagram 3 - M4



8. CIMON

8.1 PLC Connection

8.1 PLC Connection

Serial Connection

| PLC Selection on the Editor | CPU | Unit/Port | | Signal Level | Connection | | Ladder Transfer ^{*1} |
|-----------------------------|--|-------------|-----------------------|-----------------------|-----------------------|-----------------------|-------------------------------|
| | | | | | CN1 | MJ1/MJ2 | |
| BP series | CM2-BPxxMDxx-R CM2-BPxxMDxx-T CM2-BPxxMDxx-S CM2-BPxxMDxx-U | LOADER port | | RS-232C | Wiring diagram 1 - C2 | Wiring diagram 1 - M2 | × |
| | CM2-BPxxMDxx-R | Comm port | | RS-232C | Wiring diagram 3 - C2 | Wiring diagram 3 - M2 | |
| | CM2-BPxxMDxx-T | CH1 | | RS-232C | Wiring diagram 2 - C2 | Wiring diagram 2 - M2 | |
| | | CH2 | | RS-422/485 | Wiring diagram 3 - C4 | Wiring diagram 1 - M4 | |
| | CM2-BPxxMDxx-S | Comm port | | RS-422/485 | Wiring diagram 1 - C4 | Wiring diagram 2 - M4 | |
| | CM2-BPxxMDxx-U | CH1 | | RS-422 | Wiring diagram 2 - C4 | × | |
| CH2 | | RS-422/485 | Wiring diagram 3 - C4 | Wiring diagram 1 - M4 | | | |
| CP series | CM1-CPxx | LOADER port | | RS-232C | Wiring diagram 1 - C2 | Wiring diagram 1 - M2 | |
| | CM1-CP4C | Comm port | | RS-232C | Wiring diagram 4 - C2 | Wiring diagram 4 - M2 | |
| | CM1-CP4D | Comm port | | RS-422/485 | Wiring diagram 4 - C4 | Wiring diagram 3 - M4 | |
| | CM1-CPxx | CM1-SC01A | CH1 | RS-232C | Wiring diagram 2 - C2 | Wiring diagram 2 - M2 | |
| | | CM1-SC01B | CH1 | RS-422 | Wiring diagram 5 - C4 | × | |
| | | | CH2 | RS-422/485 | Wiring diagram 5 - C4 | Wiring diagram 4 - M4 | |
| | | CM1-SC02A | CH1 | RS-232C | Wiring diagram 2 - C2 | Wiring diagram 2 - M2 | |
| | CH2 | | RS-422/485 | Wiring diagram 5 - C4 | Wiring diagram 4 - M4 | | |

*1 For the ladder transfer function, see the V9 Series Reference Manual.

8.1.1 BP Series

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|---|---------|
| Connection Mode | <u>1:1</u> / Multi-link2 / Multi-link2 (Ethernet) | |
| Signal Level | <u>RS-232C</u> / RS-422/485 | |
| Baud Rate | 9600 / 19200 / <u>38400</u> bps | |
| Data Length | 7 / <u>8</u> bits | |
| Stop Bit | <u>1</u> / 2 bits | |
| Parity | <u>None</u> / Odd / Even | |

PLC

CM2-BPxxMDxx-R, T, S, U (LOADER Port)

No particular setting is necessary on the PLC.

The communication parameters are fixed; signal level: RS-232C, baud rate: 38400 bps, data length: 8 bits, stop bit: 1 bit, parity: none.

CM2-BPxxMDxx-T, U (CH1)

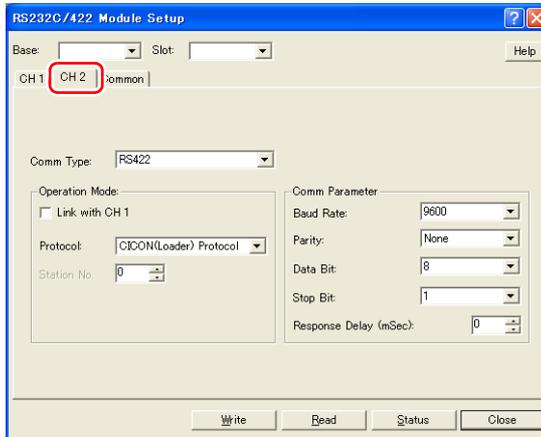
Make communication settings using the application software "CICON". For more information, refer to the instruction manual issued by CIMON.



| Item | Setting | Remarks |
|-----------|-------------------------------|---------|
| Protocol | CICON(Loader) Protocol | |
| Baud Rate | 9600 / 19200 / 38400 bps | |
| Parity | Even / Odd / None | |
| Data Bit | 7 / 8 bits | |
| Stop Bit | 1 / 2 bits | |

CM2-BPxxMDxx-T, U (CH2)

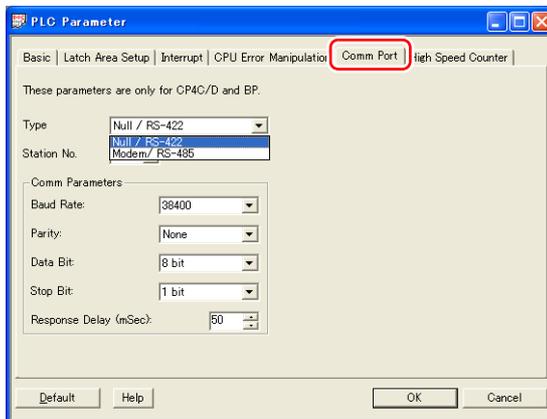
Make communication settings using the application software "CICON". For more information, refer to the instruction manual issued by CIMON.



| Item | Setting | Remarks |
|-----------|-------------------------------|----------------------------------|
| Comm Type | RS422 / RS485 | RS-422: 4-wire RS-485: 2-wire |
| Protocol | CICON(Loader) Protocol | |
| Baud Rate | 9600 / 19200 / 38400 bps | |
| Parity | Even / Odd / None | |
| Data Bit | 7 / 8 bits | |
| Stop Bit | 1 / 2 bits | |

CM2-BPxxMDxx-R, S

Make communication settings using the application software "CICON". For more information, refer to the instruction manual issued by CIMON.



| Item | Setting | Remarks |
|-----------|-------------------------------|--|
| Type | Null / RS-422, Modem / RS-485 | RS-232C connection: Null / RS-422 RS-422 (4-wire) connection: Null / RS-422 RS-485 (2-wire) connection: Modem / RS-485 |
| Baud Rate | 9600 / 19200 / 38400 bps | |
| Parity | Even / Odd / None | |
| Data Bit | 7 / 8 bits | |
| Stop Bit | 1 / 2 bits | |

Available Device Memory

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|------------------------|------|-----------|
| D (Data Memory) | 00H | |
| X (External Input) | 01H | |
| Y (External Output) | 02H | |
| M (Internal Relay) | 03H | |
| L (Internal Relay) | 04H | |
| K (Latch Relay) | 05H | |
| F (Flags) | 06H | Read only |
| T (Timer Output) | 07H | |
| TS (Timer SV) | 08H | |
| TC (Timer PV) | 09H | |
| C (Counter Output) | 0AH | |
| CS (Counter SV) | 0BH | |
| CC (Counter PV) | 0CH | |
| S (Step Control Relay) | 0DH | *1 |

*1 The addresses are expressed in "bytes". For word designation, specify an even-numbered address.

8.1.2 CP Series

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|---|---------|
| Connection Mode | <u>1:1</u> / Multi-link2 / Multi-link2 (Ethernet) | |
| Signal Level | <u>RS-232C</u> / RS-422/485 | |
| Baud Rate | 9600 / 19200 / <u>38400</u> bps | |
| Data Length | 7 / <u>8</u> bits | |
| Stop Bit | <u>1</u> / 2 bits | |
| Parity | <u>None</u> / Odd / Even | |

PLC

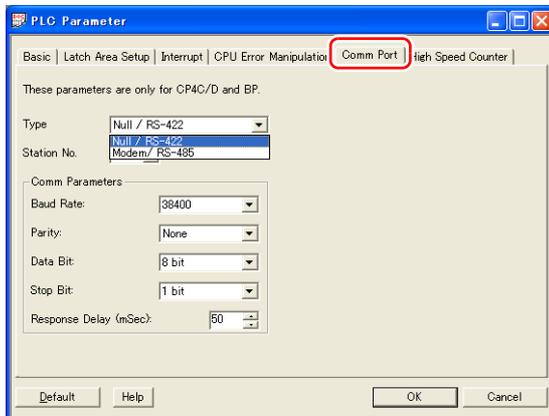
LOADER Port

No particular setting is necessary on the PLC.

The communication parameters are fixed; signal level: RS-232C, baud rate: 38400 bps, data length: 8 bits, stop bit: 1 bit, parity: none.

CM1-CP4C/CM1-CP4D

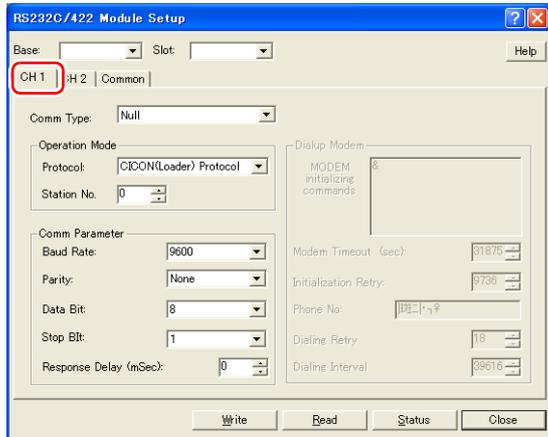
Make communication settings using the application software "CICON". For more information, refer to the instruction manual issued by CIMON.



| Item | Setting | Remarks |
|-----------|-------------------------------|--|
| Type | Null / RS-422, Modem / RS-485 | RS-232C connection: Null / RS-422 RS-422 (4-wire) connection: Null / RS-422 RS-485 (2-wire) connection: Modem / RS-485 |
| Baud Rate | 9600 / 19200 / 38400 bps | |
| Parity | Even / Odd / None | |
| Data Bit | 7 / 8 bits | |
| Stop Bit | 1 / 2 bits | |

CM1-SC01A, CM1-SC01B, CM1-SC02A (CH1)

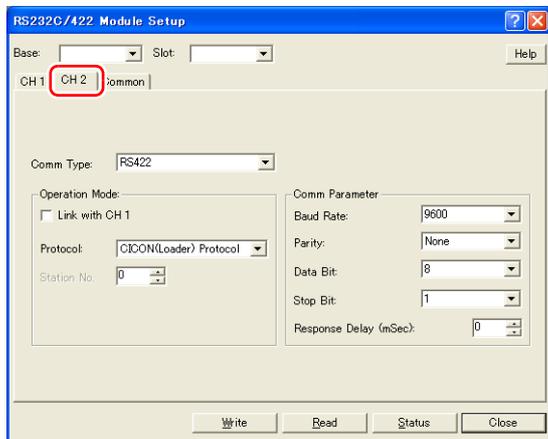
Make communication settings using the application software "CIMON". For more information, refer to the instruction manual issued by CIMON.



| Item | Setting | Remarks |
|-----------|-------------------------------|---------|
| Protocol | CICON(Loader) Protocol | |
| Baud Rate | 9600 / 19200 / 38400 bps | |
| Parity | Even / Odd / None | |
| Data Bit | 7 / 8 bits | |
| Stop Bit | 1 / 2 bits | |

CM1-SC01B, CM1-SC02A (CH2)

Make communication settings using the application software "CIMON". For more information, refer to the instruction manual issued by CIMON.



| Item | Setting | Remarks |
|-----------|-------------------------------|----------------------------------|
| Comm Type | RS422 / RS485 | RS-422: 4-wire RS-485: 2-wire |
| Protocol | CICON(Loader) Protocol | |
| Baud Rate | 9600 / 19200 / 38400 bps | |
| Parity | Even / Odd / None | |
| Data Bit | 7 / 8 bits | |
| Stop Bit | 1 / 2 bits | |

Available Device Memory

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|------------------------|------|-----------|
| D (Data Memory) | 00H | |
| X (External Input) | 01H | |
| Y (External Output) | 02H | |
| M (Internal Relay) | 03H | |
| L (Internal Relay) | 04H | |
| K (Latch Relay) | 05H | |
| F (Flags) | 06H | Read only |
| T (Timer Output) | 07H | |
| TS (Timer SV) | 08H | |
| TC (Timer PV) | 09H | |
| C (Counter Output) | 0AH | |
| CS (Counter SV) | 0BH | |
| CC (Counter PV) | 0CH | |
| S (Step Control Relay) | 0DH | *1 |

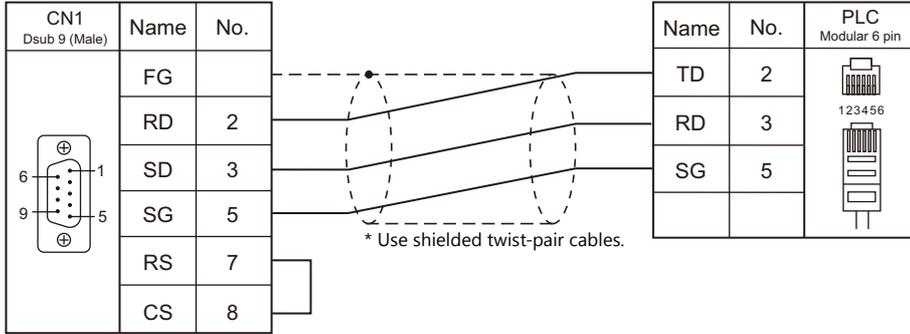
*1 The addresses are expressed in "bytes". For word designation, specify an even-numbered address.

8.1.3 Wiring Diagrams

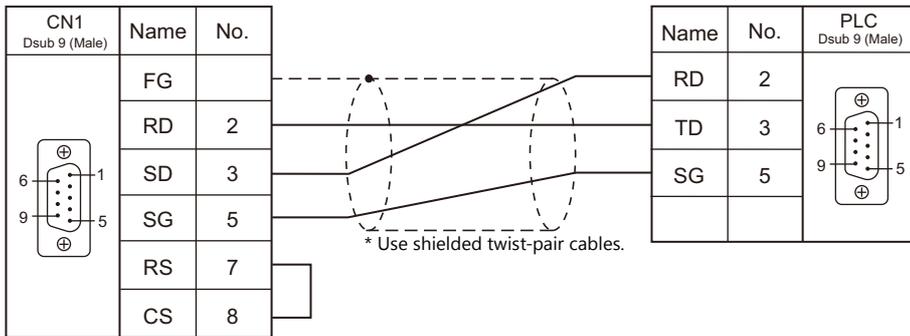
When Connected at CN1:

RS-232C

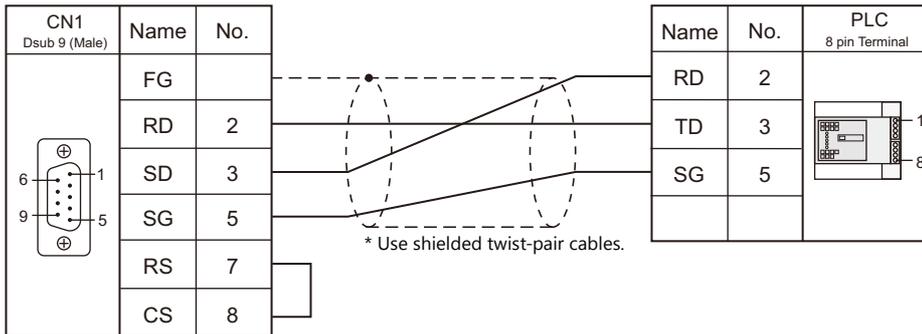
Wiring diagram 1 - C2



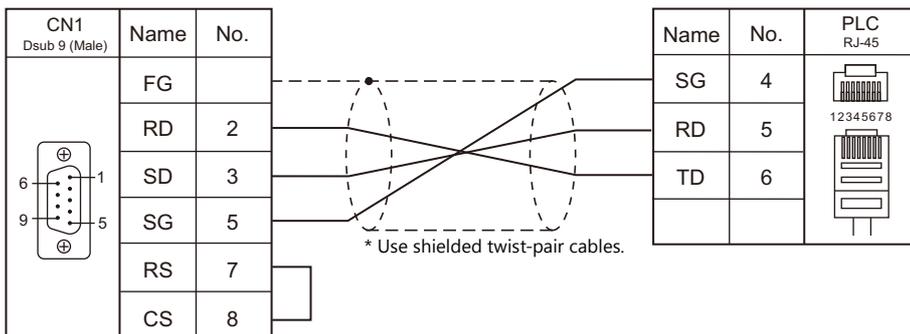
Wiring diagram 2 - C2



Wiring diagram 3 - C2

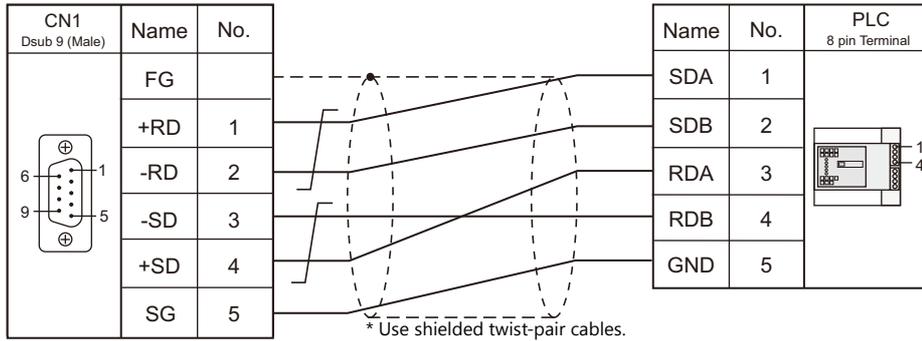


Wiring diagram 4 - C2

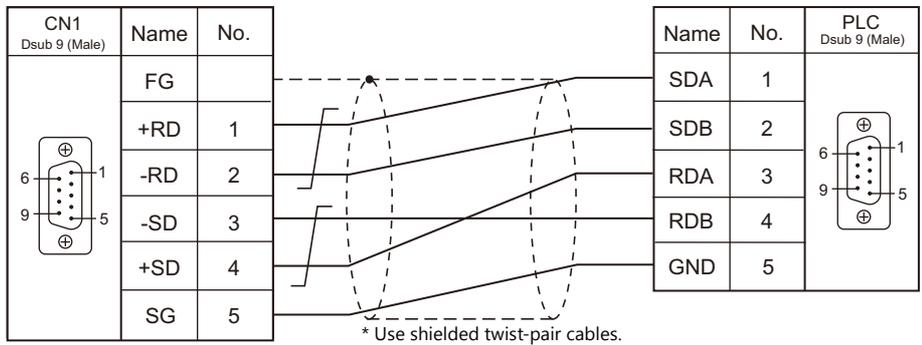


RS-422/RS-485

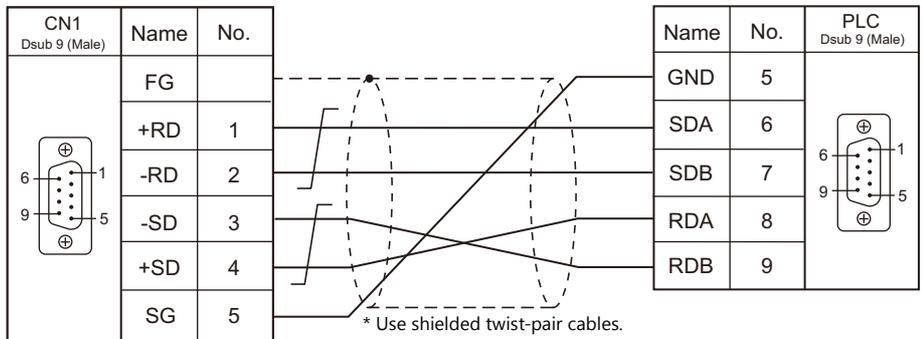
Wiring diagram 1 - C4



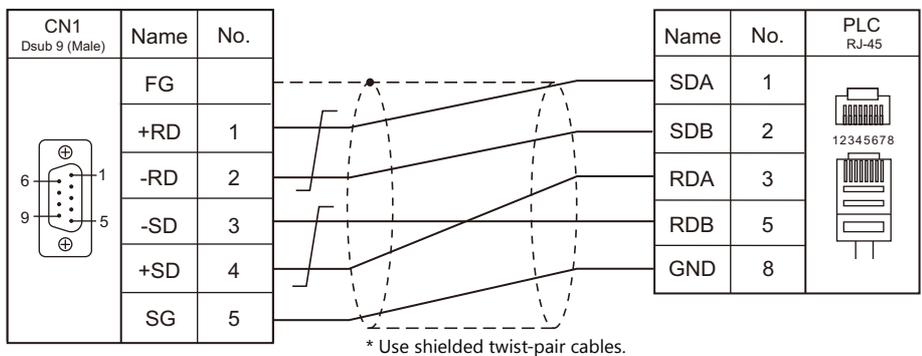
Wiring diagram 2 - C4



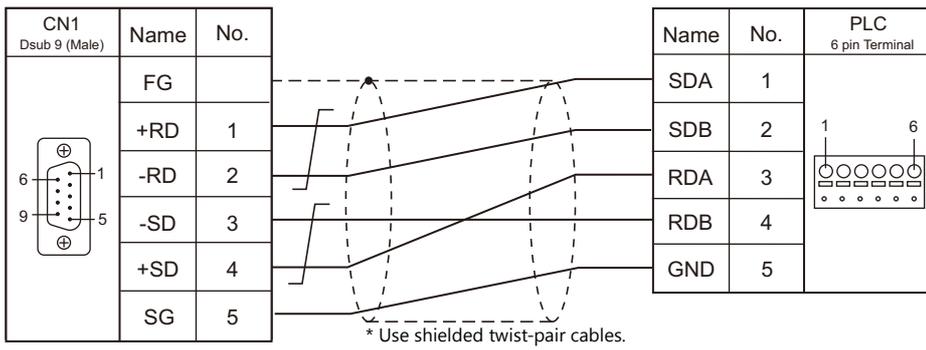
Wiring diagram 3 - C4



Wiring diagram 4 - C4



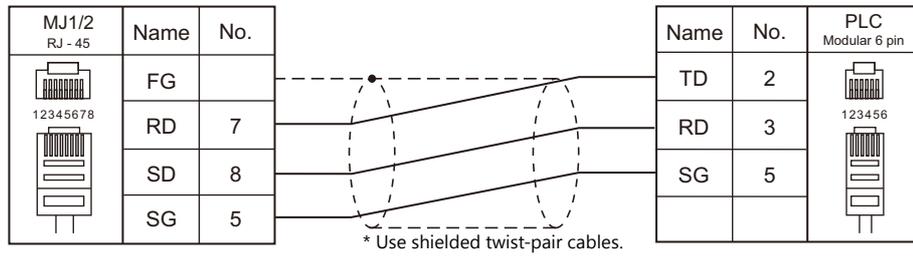
Wiring diagram 5 - C4



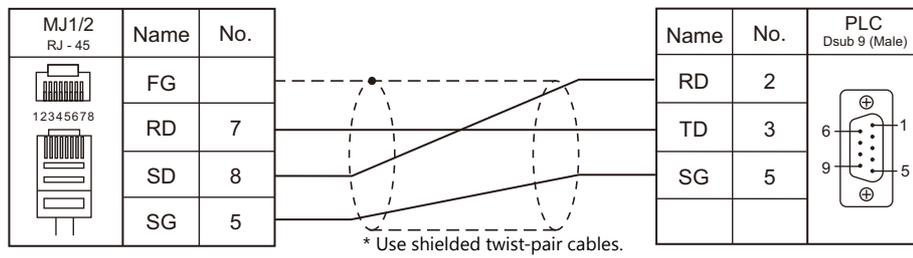
When Connected at MJ1/MJ2:

RS-232C

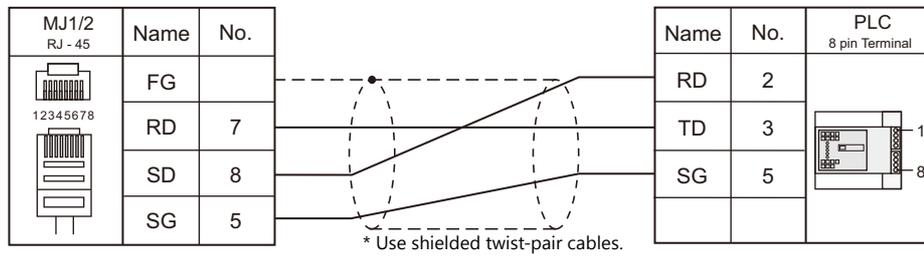
Wiring diagram 1 - M2



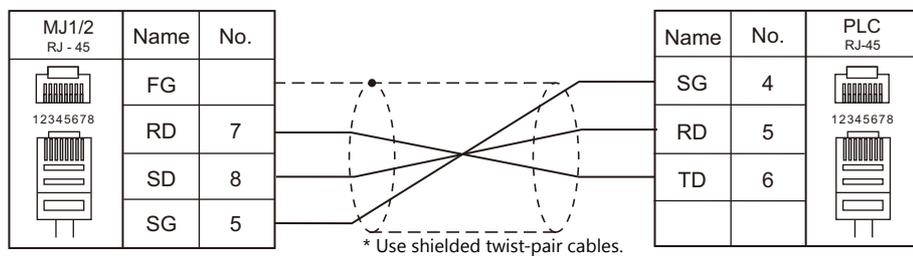
Wiring diagram 2 - M2



Wiring diagram 3 - M2

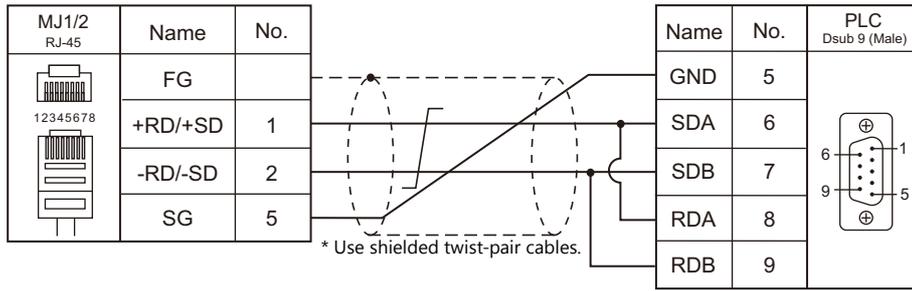


Wiring diagram 4 - M2

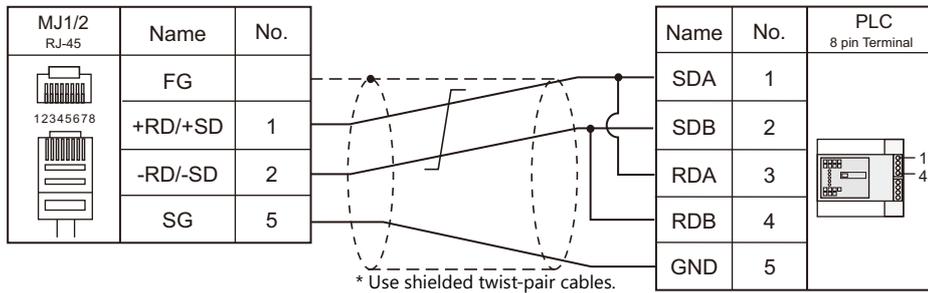


RS-422/RS-485

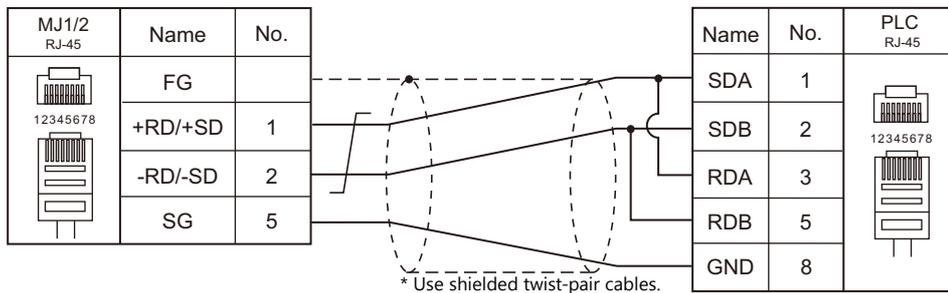
Wiring diagram 1 - M4



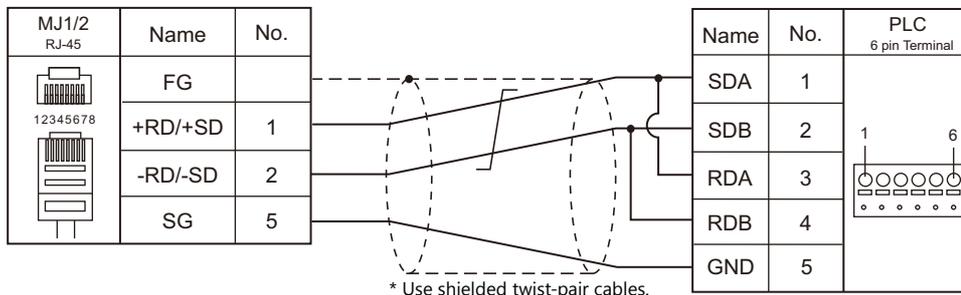
Wiring diagram 2 - M4



Wiring diagram 3 - M4



Wiring diagram 4 - M4



9. DELTA

9.1 PLC Connection

9.1 PLC Connection

Serial Connection

| PLC Selection on the Editor | CPU | Unit/Port | Signal Level | Connection | | Ladder Transfer ^{*1} |
|-----------------------------|---|----------------------------|--------------|-----------------------|-----------------------|-------------------------------|
| | | | | CN1 | MJ1/MJ2 | |
| DVP series | DVP-EH2 DVP-ES DVP-EX DVP-SS DVP-SA DVP-SX DVP-SC DVP-SV DVP-PM | RS-232C communication port | RS-232C | Wiring diagram 1 - C2 | Wiring diagram 1 - M2 | × |
| | | RS-485 communication port | RS-485 | Wiring diagram 1 - C4 | Wiring diagram 1 - M4 | |

*1 For the ladder transfer function, see the V9 Series Reference Manual.

9.1.1 DVP Series

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|--|---------|
| Connection Mode | <u>1</u> :1 / 1 : n / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet) | |
| Signal Level | RS-232C / <u>RS-422/485</u> | |
| Baud Rate | <u>9600</u> / 19200 / 38400 / 57600 / 115200 bps | |
| Data Length | <u>7</u> / 8 bits | |
| Stop Bit | <u>1</u> / 2 bits | |
| Parity | None / Odd / <u>Even</u> | |
| Target Port No. | <u>1</u> to 31 | |

PLC

(Underlined setting: default)

| Item | Setting | Remarks |
|----------------|-------------|---|
| Baud rate | <u>9600</u> | For more information, refer to the PLC manual issued by the manufacturer. |
| Station number | <u>1</u> | |
| Data length | <u>7</u> | |
| Stop bit | <u>1</u> | |
| Parity | <u>Even</u> | |

Available Device Memory

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

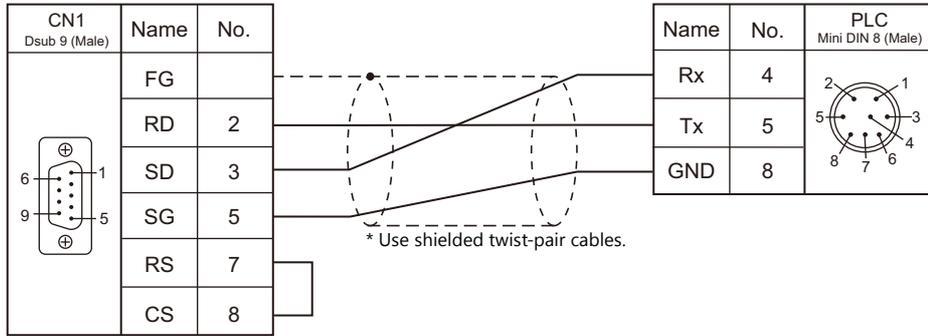
| Device Memory | TYPE | Remarks |
|--------------------------|------|-------------|
| D (Data register) | 00H | |
| X (Input relay) | 01H | Read only |
| Y (Output relay) | 02H | |
| M (Auxiliary relay) | 03H | |
| S | 04H | |
| T (Timer) | 05H | |
| C (Counter) | 06H | |
| 32C (High-speed counter) | 07H | Double-word |

9.1.2 Wiring Diagrams

When Connected at CN1:

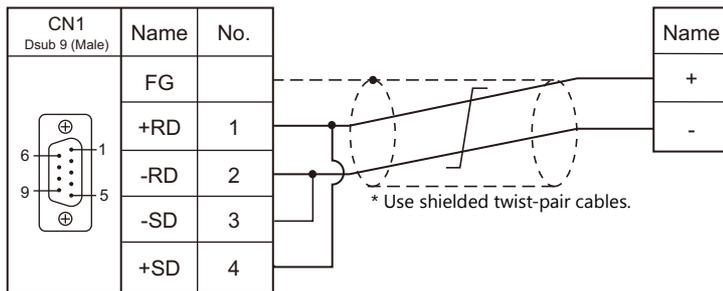
RS-232C

Wiring diagram 1 - C2



RS-422/RS-485

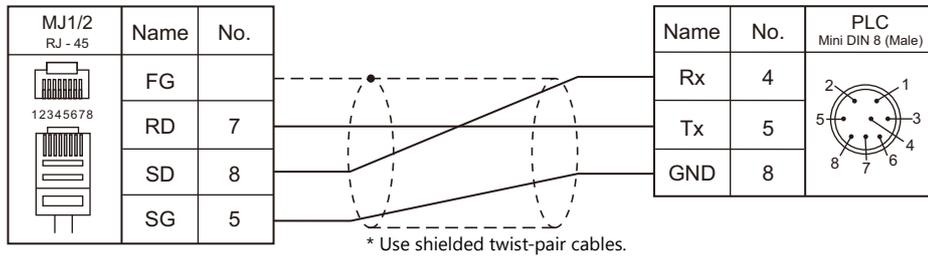
Wiring diagram 1 - C4



When Connected at MJ1/MJ2:

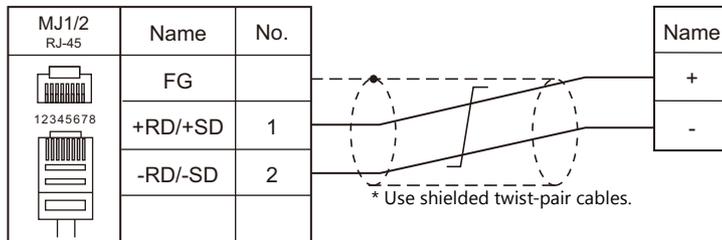
RS-232C

Wiring diagram 1 - M2



RS-422/RS-485

Wiring diagram 1 - M4



10. DELTA TAU DATA SYSTEMS

10.1 Temperature Controller/Servo/Inverter Connection

10.1 Temperature Controller/Servo/Inverter Connection

Serial Connection

Motion Controller

| PLC Selection on the Editor | Model | Port | | Signal Level | Connection | | Lst File |
|-----------------------------|-----------------|-----------------|----|--------------|-----------------------|-----------------------|----------|
| | | | | | CN1 | MJ1/MJ2 | |
| PMAC | PMAC PCI | Serial port | J4 | RS-232C | Wiring diagram 1 - C2 | Wiring diagram 1 - M2 | PMAC.Lst |
| | Turbo PMAC PCI | Option-9T | J8 | | Wiring diagram 2 - C2 | Wiring diagram 2 - M2 | |
| | PMAC2 PCI | Serial port | J5 | | | | |
| | Turbo PMAC2 PCI | Option-9T | J8 | | | | |
| | UMAC Turbo CPU | Serial port | J7 | | | | |
| | | Sub-serial port | J8 | | | | |
| | 3U Turbo PMAC2 | Serial port | J7 | | Wiring diagram 1 - C2 | Wiring diagram 1 - M2 | |
| | | Option-9T | J8 | | Wiring diagram 2 - C2 | Wiring diagram 2 - M2 | |

Ethernet Connection

Motion Controller

| PLC Selection on the Editor | Model | Unit | TCP/IP | UDP/IP | Port No. | Keep Alive *1 | Lst File |
|-----------------------------|----------------|----------------------------|--------|--------|---------------------|---------------|--------------|
| PMAC (Ethernet TCP/IP) | UMAC Turbo CPU | CPU with built-in Ethernet | ○ | × | 1025 (max. 4 units) | ○ | PMAC_Eth.Lst |

*1 For KeepAlive functions, see "1.3.2 Ethernet Communication".

10.1.1 PMAC

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|---|---------|
| Connection Mode | <u>1:1</u> / Multi-link2 / Multi-link2 (Ethernet) | |
| Signal Level | RS-232C | |
| Baud Rate | 4800 / 9600 / 19200 / <u>38400</u> / 57600 / 76800 / 115K bps | |
| Data Length | 8 bits | |
| Stop Bit | 1 bit | |
| Parity | None | |
| Target Port No. | <u>0</u> to 31 | |

PMAC

Make PMAC settings by using the software "PEWIN32PRO2". For more information, refer to the PMAC instruction manual issued by the manufacturer.

Values after change are saved in FROM and determined when the power is turned off and back on again.

I-Variables by number

| Address | Contents | Setting |
|---------|------------------------------|---|
| I0 | Serial card number | 0: 1:1 connection |
| I1 | Serial port mode | 0: CTS signal used |
| I3 | Handshake I/O control | 2 |
| I4 | Communication sum check mode | 0: Without sum check |
| I6 | Error notification mode | 1 |
| I43 | Protocol selection *1 | 0: Standard protocol |
| I53 | Sub port *2 | Baud rate 6: 4800, 8: 9600, 10: 19200, 12: 38400, 13: 57600, 14: 78600, 15: 115K *3 bps |
| I54 | Main port | Baud rate 6: 4800, 8: 9600, 10: 19200, 12: 38400, 13: 57600, 14: 78600, 15: 115K *3 bps |
| I63 | Echo back selection | 1: Valid |

*1 Set when Turbo PMAC PCI, Turbo PMAC2 CPCI, UMAC Turbo CPU or 3U Turbo PMAC2 is used.

*2 Valid when "Option-9T" is used with Turbo PMAC PCI, Turbo PMAC2 CPCI / 3U Turbo PMAC2 or the sub port of UMAC Turbo CPU is used.

*3 When "115K bps" is set, set the multiples of 30 MHz for "I52" (CPU frequency).

PMAC PCI

MAIN BOARD E-POINT

| E-POINT | Contents | Setting |
|--|---|---|
|  E49 | Parity control for serial communication | No parity: Install a jumper between pins 1 and 2. |
|  E110 | Serial port setting | RS-232C: Install a jumper between pins 1 and 2. |

PMAC2 PCI

BASE BOARD E-POINT

| E-POINT | Contents | Setting |
|---|------------|---|
|  | E17 E18 | Serial port type selection RS-232C: Install a jumper between pins 1 and 2. |

Turbo PMAC PCI

MAIN BOARD E-POINT

| E-POINT | Contents | Setting |
|---|----------|--|
|  | E49 | Parity control for serial communication No parity: Install a jumper between pins 1 and 2. |
|  | E110 | Serial port setting RS-232C: Install a jumper between pins 1 and 2. |

Turbo PMAC2 PCI

BASE BOARD E-POINT

| E-POINT | Contents | Setting |
|---|------------|---|
|  | E17 E18 | Serial port type selection RS-232C: Install a jumper between pins 1 and 2. |

UMAC Turbo CPU

TURBO CPU BOARD E-POINT

| E-POINT | Contents | Setting |
|---|----------|---|
|  | E17A | PHASE+ valid/invalid Invalid: Install a jumper between pins 1 and 2. |
| | E17B | PHASE- valid/invalid Invalid: Install a jumper between pins 1 and 2. |
| | E18A | SERVO+ valid/invalid Invalid: Install a jumper between pins 1 and 2. |
| | E18B | SERVO- valid/invalid Invalid: Install a jumper between pins 1 and 2. |

3U Turbo MPMAC2

TURBO CPU BOARD E-POINT

| E-POINT | Contents | Setting |
|---|------------|--|
|  | E17 E18 | Serial port selection RS-232C: Install a jumper between pins 1 and 2. |

Available Device Memory

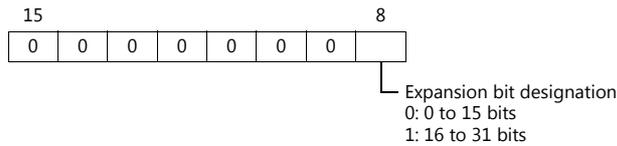
The available setting range of device memory varies depending on the model. Be sure to set within the range available for the model to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | | TYPE | Remarks |
|---------------|------------------------|------|-------------|
| P | (variable P) | 00H | Real number |
| Q | (variable Q) | 01H | Real number |
| M | (variable M) | 02H | Real number |
| I | (variable I) | 03H | Real number |
| M_INT | (variable M (integer)) | 04H | Double-word |
| I_INT | (variable I (integer)) | 05H | Double-word |
| P_INT | (variable P (integer)) | 06H | Double-word |

Indirect Device Memory Designation

| | 15 | 8 | 7 | 0 |
|-------|------------------|---|-----------------|---|
| n + 0 | Model | | Device type | |
| n + 1 | Address No. | | | |
| n + 2 | Expansion code * | | Bit designation | |
| n + 3 | 00 | | Station number | |

* In the expansion code, set which word, higher or lower, is to be read when a double-word address is specified (expansion bit designation).



PLC_CTL

Macro command "PLC_CTL F0 F1 F2"

| Contents | F0 | F1 (= \$u n) | | F2 |
|---------------|---------------------|--------------|---|----|
| Write of data | 1 - 8 (PLC1 - 8) | n | Station number | 3 |
| | | n + 1 | Command: 0000H | |
| | | n + 2 | Timeout time: 1 to 300 sec. (0: Time set on the editor*) | |
| Control-X | 1 - 8 (PLC1 - 8) | n | Station number | 2 |
| | | n + 1 | Command: 0001H | |

* Depends on the time set for [Time-out Time] under [Communication Setting] in the [PLC Properties] window ([System Setting] → [Hardware Setting]).

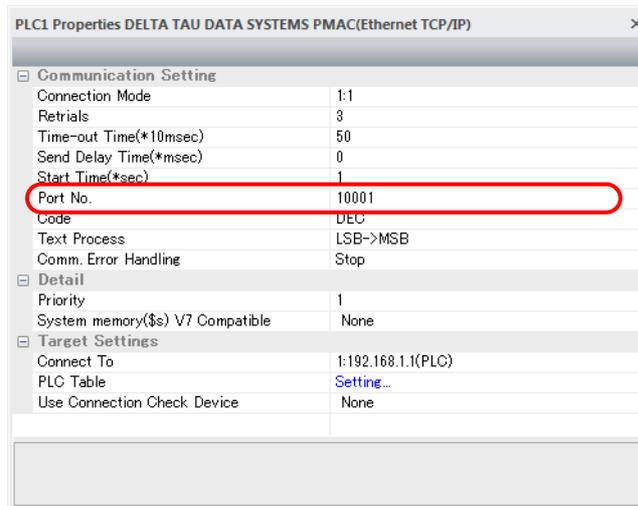
10.1.2 PMAC (Ethernet TCP/IP)

Communication Setting

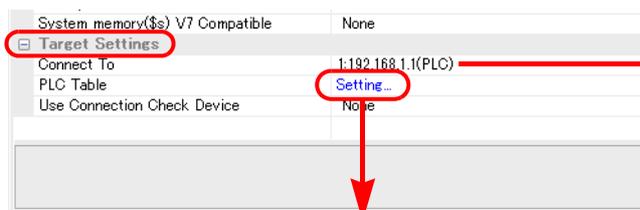
Editor

Make the following settings on the editor. For more information, see "1.3.2 Ethernet Communication".

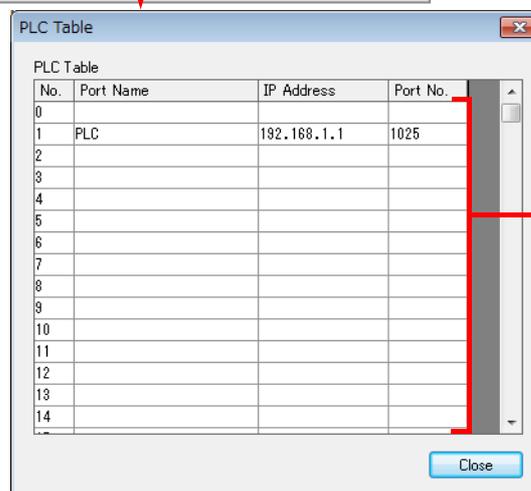
- IP address for the V9 unit
 - When specified on the screen program:
[System Setting] → [Hardware Setting] → [Local Port IP Address]
 - When specified on the V9 unit:
Local mode → [LAN Setting]
- Port number for the V9 unit (for communication with PLC)
[System Setting] → [Hardware Setting] → [PLC Properties] → [Communication Setting]



- IP address and port number of the PLC
Register on the [PLC Table] in [System Setting] → [Hardware Setting] → [PLC Properties] → [Target Settings].



Valid only for 1 : 1 connection
Select the PLC for connection from those registered on the PLC table.



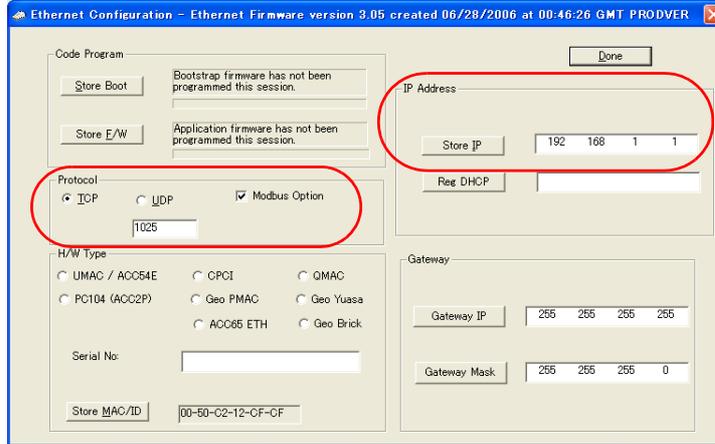
Set the IP address, port number 1025 and whether or not to use the KeepAlive function of the PLC.

UMAC

Make UMAC settings by using the software "PEWIN32PRO2 *". For more information, refer to the UMAC manual issued by the manufacturer.

* For Ethernet communication, PEWIN32PRO service pack 2.0 and later is necessary.

Ethernet configuration



| Item | Setting | Remarks |
|------------|---------------------|---|
| Protocol | TCP | For more information, refer to the UMAC instruction manual. |
| Port No. | 1025 (fixed) | |
| IP Address | IP address of UMAC | |

Procedure for changing the IP address

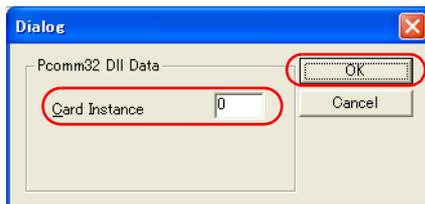
1. Change the IP address on the [Ethernet Configuration] dialog.
2. Click [Store IP] on the [Ethernet Configuration] dialog.



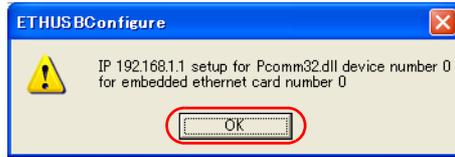
3. The [Ethernet Configure] dialog is displayed. Click [Yes].



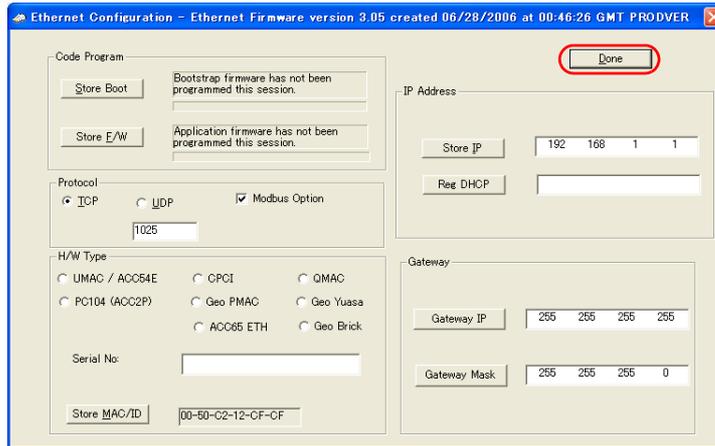
4. The [Dialog] dialog is displayed. Set "0" for [Card Instance] and click [OK].



- The [ETHUSBConfigure] dialog is displayed.
Click [OK].



- The [Ethernet Configuration] dialog is displayed again.
Click [Done] in the dialog.



- Turn the power off and back on again.

* UMAC settings must be made via USB communication.
Before performing Ethernet communication with MONITOUCH, turn the power to UMAC off and remove the USB cable. Then, insert the Ethernet cable and turn the power on again.

I-Variables by number

| Address | Contents | Setting |
|---------|--------------------------------|----------|
| I3 | Handshake I/O control | 2 |
| I6 | Error notification mode | 1 |
| I63 | <Control-X> Echo valid/invalid | 1: Valid |

* Values after change are saved in FROM and determined when the power is turned off and back on again.

UMAC Turbo CPU

TURBO CPU BOARD E-POINT

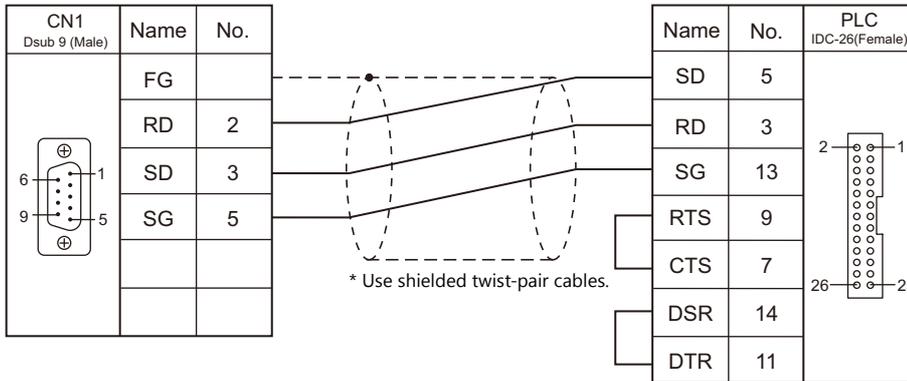
| E-POINT | Contents | Setting |
|---|---|--|
|  E6 | Reloading the micro controller firmware | Normal operation: Install a jumper between pins 1 and 2. |

10.1.3 Wiring Diagrams

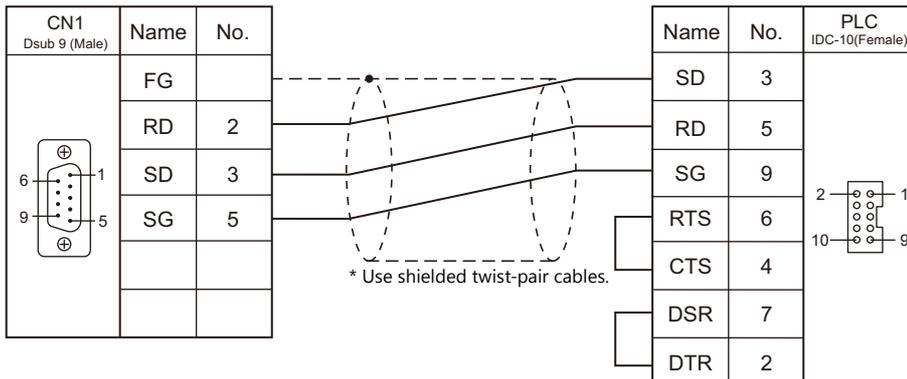
When Connected at CN1:

RS-232C

Wiring diagram 1 - C2



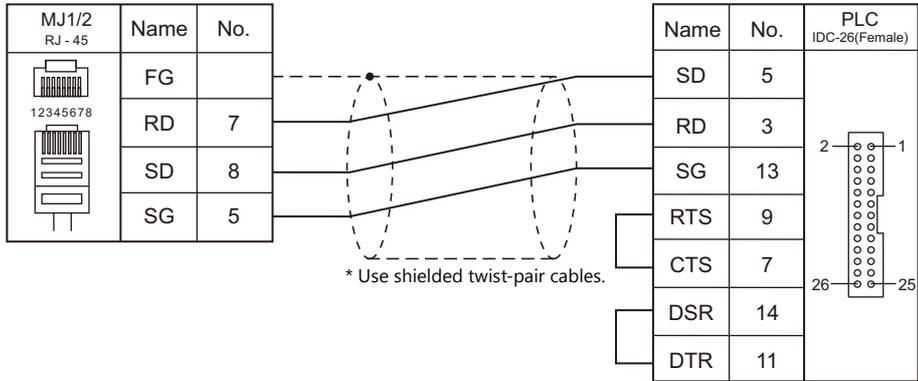
Wiring diagram 2 - C2



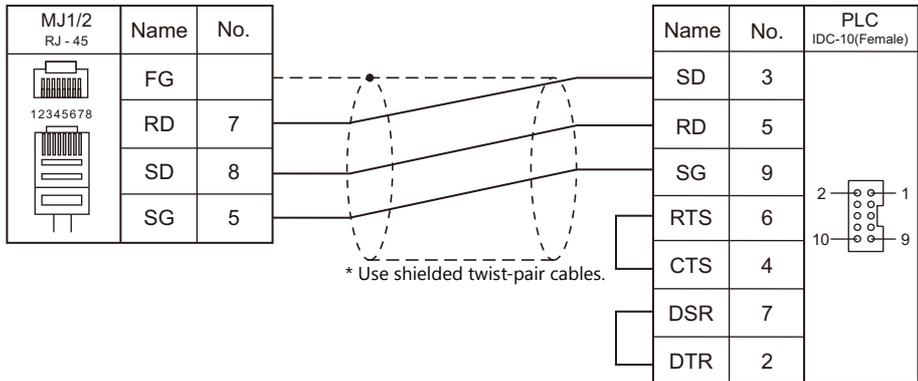
When Connected at MJ1/MJ2:

RS-232C

Wiring diagram 1 - M2



Wiring diagram 2 - M2



11. EATON Cutler-Hammer

11.1 PLC Connection

11.1 PLC Connection

The PLC models shown below can be connected.

Serial Connection

| PLC Selection on the Editor | CPU | Unit/Port | Signal Level | Connection | | Ladder Transfer ^{*1} |
|-----------------------------|--|---|--------------|-----------------------|-----------------------|-------------------------------|
| | | | | CN1 | MJ1/MJ2 | |
| ELC | ELC-PA10 ELC-PC12 ELC-PH12 ELC-PB14 | Programming port on the CPU unit (COM1) | RS-232C | Wiring diagram 1 - C2 | Wiring diagram 1 - M2 | × |
| | | Communication port on the CPU unit (COM2) | RS-485 | Wiring diagram 1 - C4 | Wiring diagram 1 - M4 | |

*1 For the ladder transfer function, see the V9 Series Reference Manual.

11.1.1 ELC

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|---|---------|
| Connection Mode | <u>1</u> :1 / 1 : n / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet) | |
| Signal Level | RS-232C / <u>RS-422/485</u> | |
| Baud Rate | 4800 / <u>9600</u> / 19200 / 38400 / 57600 / 115200 bps | |
| Data Length | <u>7</u> / 8 bits | |
| Stop Bit | <u>1</u> / 2 bits | |
| Parity | None / Odd / <u>Even</u> | |
| Target Port No. | <u>1</u> to 31 | |

PLC

Make the PLC setting using device memory "D" (data register). For more information, refer to the PLC manual issued by the manufacturer.

Available Device Memory

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

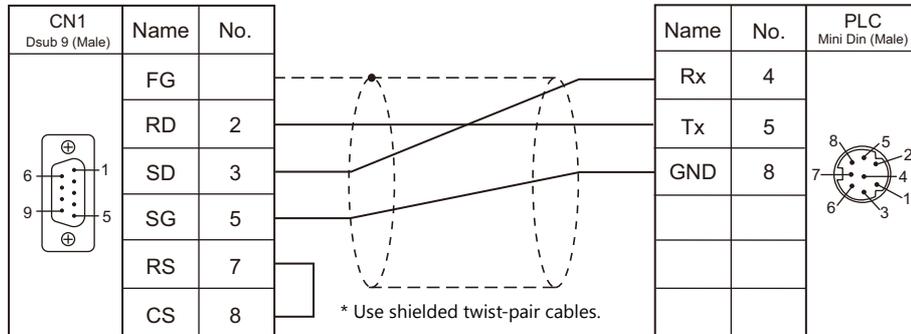
| Device Memory | TYPE | Remarks |
|--------------------------|------|-------------|
| D (data register) | 00H | |
| X (input) | 01H | Read only |
| Y (output) | 02H | |
| M (auxiliary relay) | 03H | |
| S (step point) | 04H | |
| T (timer) | 05H | |
| C (counter) | 06H | |
| 32C (high-speed counter) | 07H | Double-word |

11.1.2 Wiring Diagrams

When Connected at CN1:

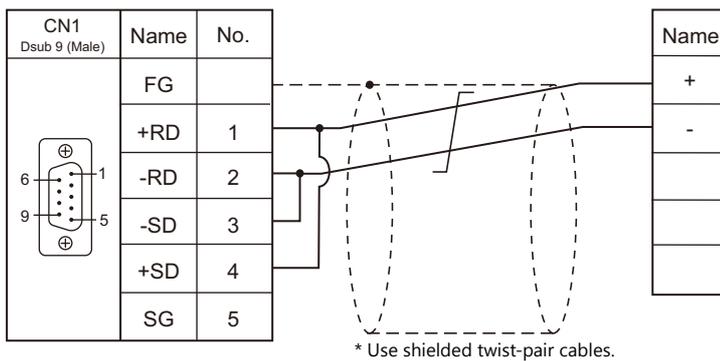
RS-232C

Wiring diagram 1 - C2



RS-422

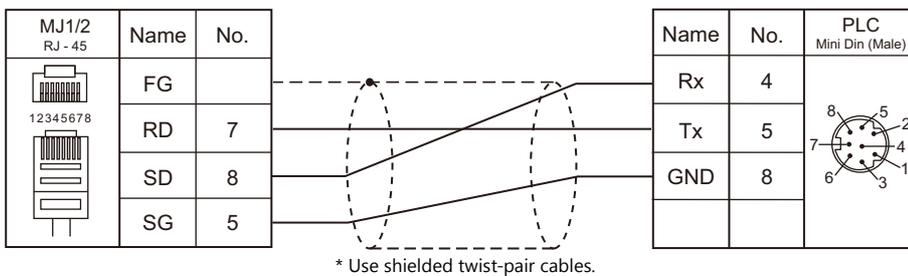
Wiring diagram 1 - C4



When Connected at MJ1/MJ2:

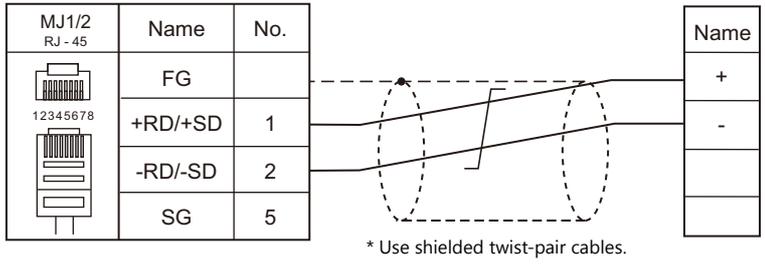
RS-232C

Wiring diagram 1 - M2



RS-422

Wiring diagram 1 - M4



12. EMERSON

12.1 PLC Connection

12.1 PLC Connection

Serial Connection

| PLC Selection on the Editor | CPU | Unit/Port | Signal Level | Connection | | Ladder Transfer ^{*1} |
|---------------------------------|------|---------------------|--------------|-----------------------|-----------------------|-------------------------------|
| | | | | CN1 | MJ1/MJ2 | |
| EC10/EC20/EC20H (MODBUS RTU) | EC10 | Port1 ^{*2} | RS-232C | Wiring diagram 1 - C2 | Wiring diagram 1 - M2 | × |
| | | | RS-485 | Wiring diagram 1 - C4 | Wiring diagram 1 - M4 | |
| | EC20 | COM2 ^{*2} | RS-232C | Wiring diagram 1 - C2 | Wiring diagram 1 - M2 | |
| | | | RS-485 | Wiring diagram 1 - C4 | Wiring diagram 1 - M4 | |

*1 For the ladder transfer function, see the V9 Series Reference Manual.

*2 The concurrent use of RS-232C and RS-485 terminals is not allowed for connection.

12.1.1 EC10/EC20/EC20H (MODBUS RTU)

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|---|---------|
| Connection Mode | <u>1:1</u> / 1 : n / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet) | |
| Signal Level | <u>RS-232C</u> / RS-422/485 | |
| Baud Rate | 4800 / 9600 / <u>19200</u> / 38400 bps | |
| Data Length | 8 bits | |
| Stop Bit | <u>1</u> / 2 bits | |
| Parity | Odd / <u>Even</u> / None | |
| Target Port No. | <u>1</u> to 247 | |

PLC

Be sure to match the settings to those made under [Communication Setting] of the editor.

Calendar

This model is equipped with a calendar function; however, the calendar data cannot be written from the V series. Thus, time correction must be performed on the controller side.

Available Device Memory

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|--------------------------------|------|-------------|
| D (Data register) | 00H | |
| SD (Special data register) | 01H | |
| Y (Output I/O) | 02H | |
| X (Input I/O) | 03H | |
| M (Auxiliary relay) | 04H | |
| SM (Special auxiliary relay) | 05H | |
| S (State relay) | 06H | |
| T (Timer) | 07H | |
| C (Counter) | 08H | |
| Z (Offset addressing register) | 09H | |
| TW (Timer) | 0AH | |
| CW (Counter) | 0BH | |
| CDW (Counter) | 0CH | Double-word |
| R (R) | 0DH | |

Indirect Device Memory Designation

| | 15 | 8 7 | 0 |
|-----|------------------|-----|-----------------|
| n+0 | Model | | Device type |
| n+1 | Address No. | | |
| n+2 | Expansion code * | | Bit designation |
| n+3 | 00 | | Station number |

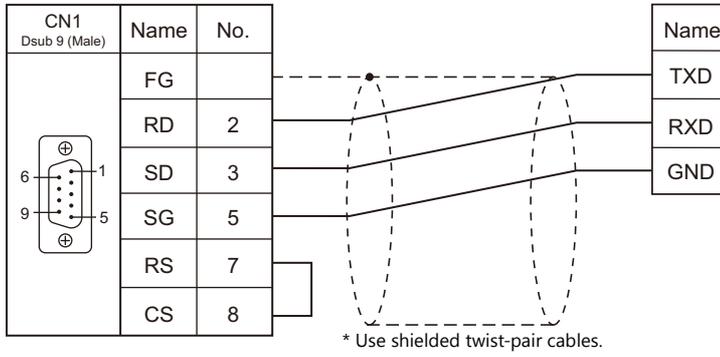
- * For bit designation, an expansion code setting is required.
 00H: when designating bit 0 to 15
 01H: when designating bit 16 to 31

12.1.2 Wiring Diagrams

When Connected at CN1:

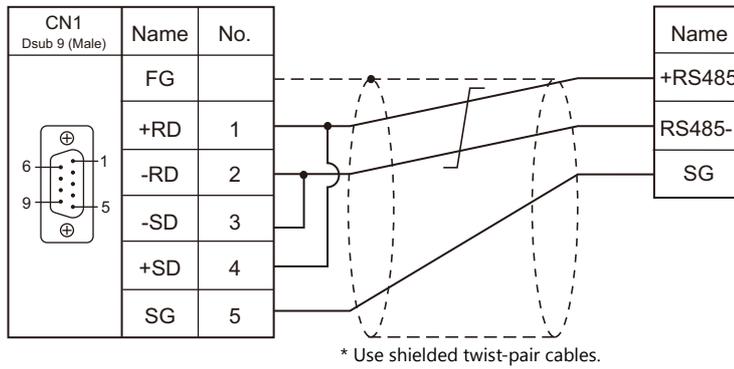
RS-232C

Wiring diagram 1 - C2



RS-422/RS-485

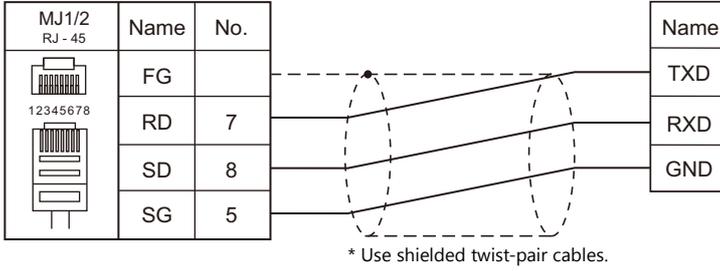
Wiring diagram 1 - C4



When Connected at MJ1/MJ2:

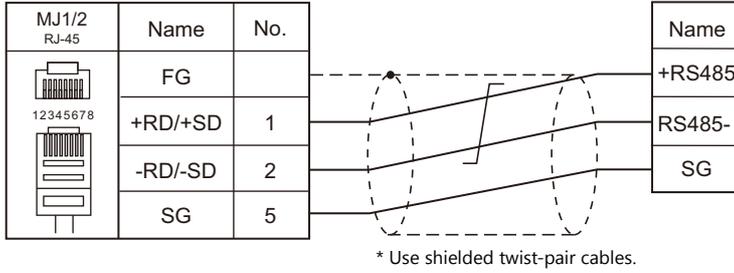
RS-232C

Wiring diagram 1 - M2



RS-422/RS-485

Wiring diagram 1 - M4



13. FANUC

13.1 PLC Connection

13.1 PLC Connection

Serial Connection

| PLC Selection on the Editor | CPU | Port | Signal Level | Connection | | Ladder Transfer ^{*1} |
|--------------------------------|--|-------|--------------|-----------------------|-----------------------|----------------------------------|
| | | | | CN1 | MJ1/MJ2 | |
| Power Mate | Power Mate Model H/D | JD14 | RS-422 | Wiring diagram 1 - C4 | × | × |
| | Power Mate i Model H/D | JD40 | RS-422 | Wiring diagram 2 - C4 | × | |
| | | JD42 | RS-232C | Wiring diagram 1 - C2 | Wiring diagram 1 - M2 | |
| | 16-Model C | JD5B | RS-232C | Wiring diagram 2 - C2 | Wiring diagram 2 - M2 | |
| | 16i-Model A 16i-Model B 18i-Model A 18i-Model B 18-Model C 21i-Model A 21i-Model B | JD36B | RS-232C | | | |
| | 30i-Model A 31i-Model A 32i-Model A | JD36A | | | | |
| | | JD54 | | Wiring diagram 3 - C2 | Wiring diagram 3 - M2 | |

*1 For the ladder transfer function, see the V9 Series Reference Manual.

13.1.1 Power Mate

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|---|---------|
| Connection Mode | <u>1:1</u> / Multi-link2 / Multi-link2 (Ethernet) | |
| Signal Level | RS-232C / <u>RS-422/485</u> | |
| Baud Rate | 19200 bps (fixed) | |
| Data Length | 8 bits (fixed) | |
| Stop Bit | 1 bit (fixed) | |
| Parity | Even (fixed) | |

Available Device Memory

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

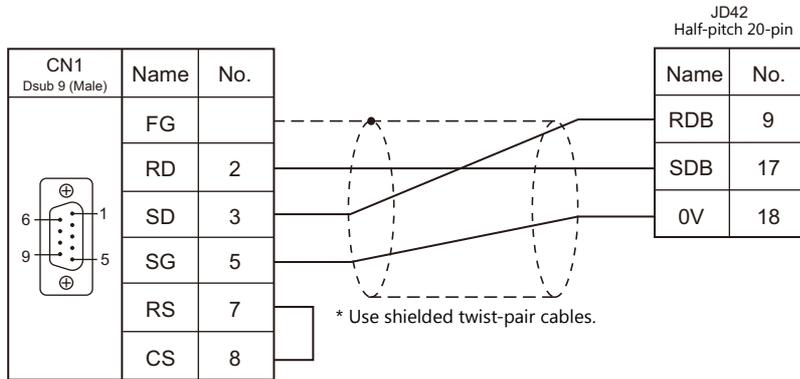
| Device Memory | TYPE | Remarks |
|-----------------------|------|---|
| D (data table) | 00H | |
| X (input relay) | 01H | WX as word device |
| Y (output relay) | 02H | WY as word device |
| R (internal relay) | 03H | WR as word device |
| K (keep relay) | 04H | WK as word device |
| T (timer) | 05H | |
| C (counter) | 06H | |
| E (extensional relay) | 07H | WE as word device, available only with 30i/31i/32i-ModelA |

13.1.2 Wiring Diagrams

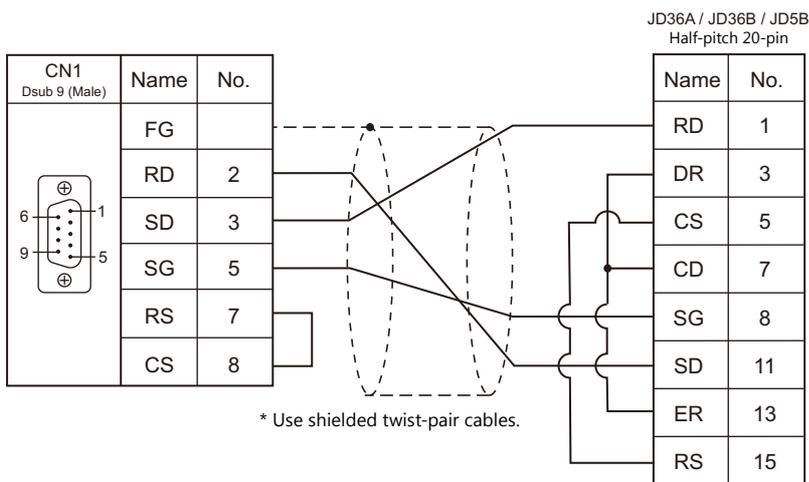
When Connected at CN1:

RS-232C

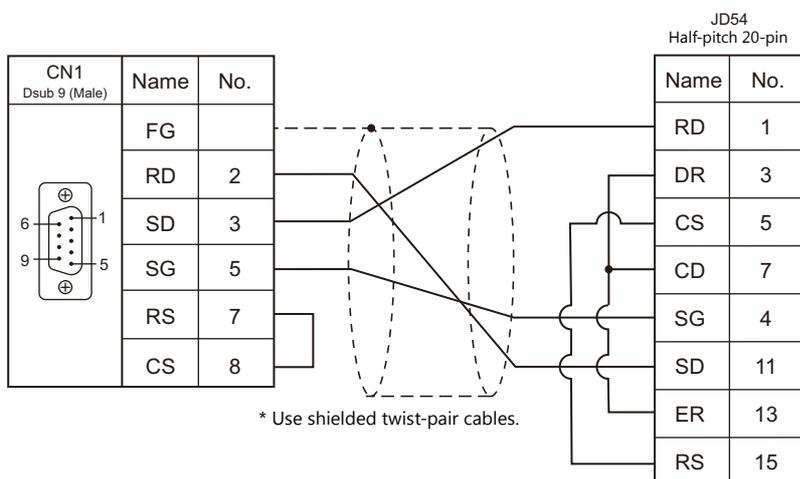
Wiring diagram 1 - C2



Wiring diagram 2 - C2

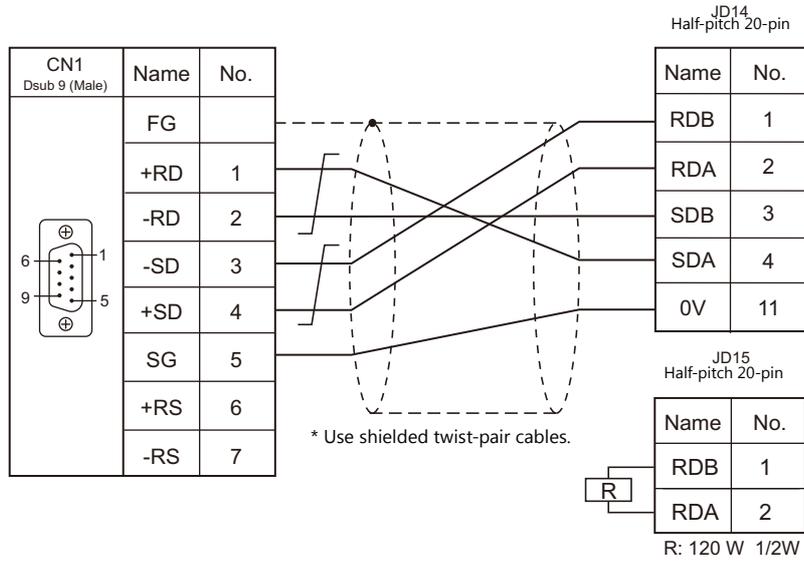


Wiring diagram 3 - C2

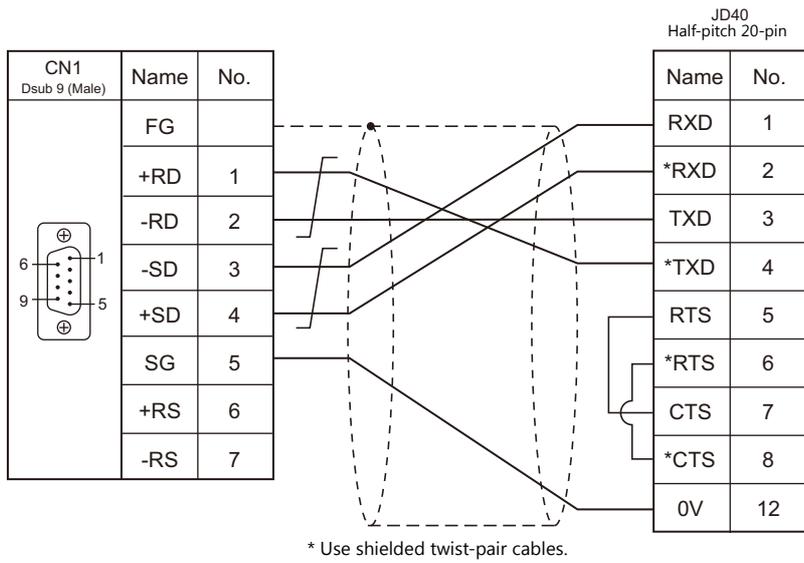


RS-422

Wiring diagram 1 - C4



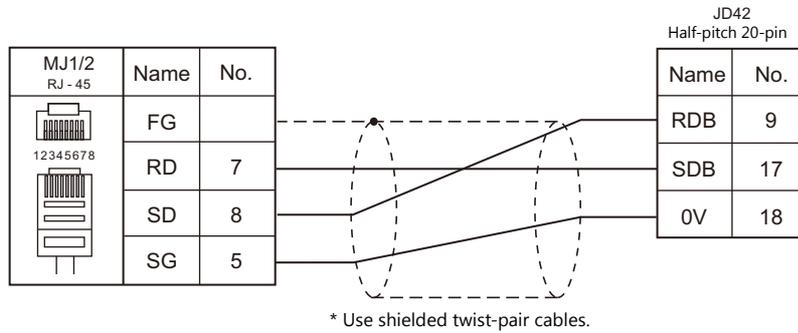
Wiring diagram 2 - C4



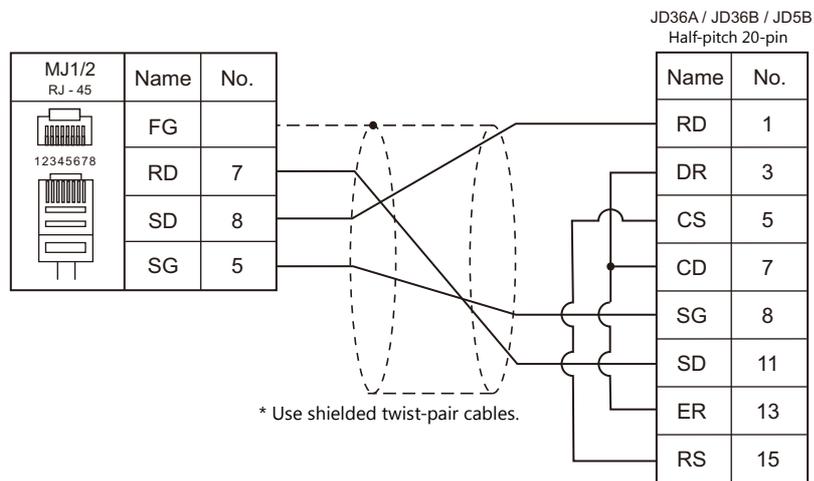
When Connected at MJ1/MJ2:

RS-232C

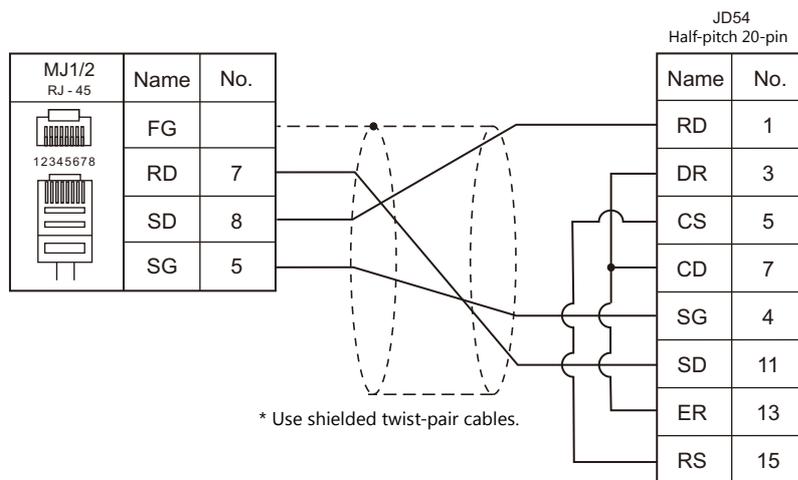
Wiring diagram 1 - M2



Wiring diagram 2 - M2



Wiring diagram 3 - M2



MEMO

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14. Fatek Automation

14.1 PLC Connection

14.1 PLC Connection

Serial Connection

| PLC Selection on the Editor | CPU | Unit/Port | | Signal Level | Connection | | Ladder Transfer ^{*1} |
|-----------------------------|----------------------------------|------------------------------|---------------------------|--------------|-----------------------|-----------------------|-------------------------------|
| | | | | | CN1 | MJ1/MJ2 | |
| FACON FB series | FBE-20MC FBE-28MC FBE-40MC | CPU unit Programming port | Port1 | RS-232C | Wiring diagram 1 - C2 | Wiring diagram 1 - M2 | × |
| | | | Port2 | RS-485 | Wiring diagram 1 - C4 | Wiring diagram 1 - M4 | |
| | | FB-DTBR | Port1 (D-sub 15) | RS-232C | Wiring diagram 1 - C2 | Wiring diagram 1 - M2 | |
| | | | Port1 (D-sub 9) | RS-232C | Wiring diagram 2 - C2 | Wiring diagram 2 - M2 | |
| | | | Port2 (terminal block) | RS-485 | Wiring diagram 2 - C4 | Wiring diagram 2 - M4 | |
| | | | | | | | |

*1 For the ladder transfer function, see the V9 Series Reference Manual.

14.1.1 FACON FB Series

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|---|---------|
| Connection Mode | <u>1</u> :1 / 1:n / Multi-link2 / Multi-link2 (Ethernet) / 1:n Multi-link2 (Ethernet) | |
| Signal Level | <u>RS-232C</u> / RS-422/485 | |
| Baud Rate | <u>9600</u> / 19200 / 38400 bps | |
| Data Length | <u>7</u> / 8 bits | |
| Stop Bit | <u>1</u> / 2 bits | |
| Parity | None / Odd / <u>Even</u> | |
| Target Port No. | <u>1</u> to 31 | |

PLC

Make the PLC setting using the configuration tool "PRO_LADDER". For more information, refer to the PLC manual issued by the manufacturer.

Available Device Memory

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|------------------------------------|------|-------------------|
| HR (data register) | 00H | |
| DR (data register) | 01H | |
| X (input relay) | 02H | WX as word device |
| Y (output relay) | 03H | WY as word device |
| M (internal relay) | 04H | WM as word device |
| S (step relay) | 05H | WS as word device |
| T (timer/contact) | 06H | WT as word device |
| C (counter/contact) | 07H | WC as word device |
| RT (timer/current value) | 08H | |
| RC (counter/current value) | 09H | |
| DRC (32-bit counter/current value) | 0AH | *1 |

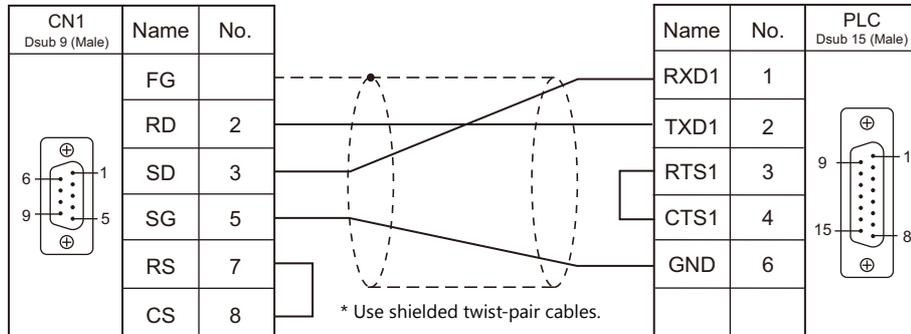
- *1 For items where double-words can be used (Num. Display, Graph, Sampling), data is processed as double-words. For those where bits or words can be used, data is processed as words consisting of lower 16 bits.
 For input: Upper 16 bits are ignored.
 For output: "0" is written for upper 16 bits.

14.1.2 Wiring Diagrams

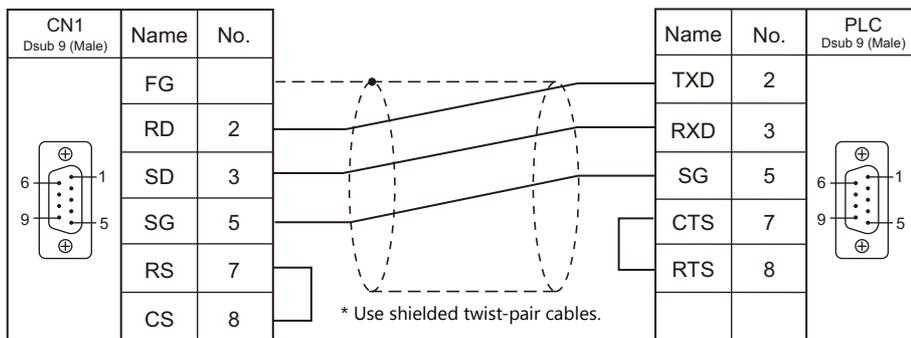
When Connected at CN1:

RS-232C

Wiring diagram 1 - C2

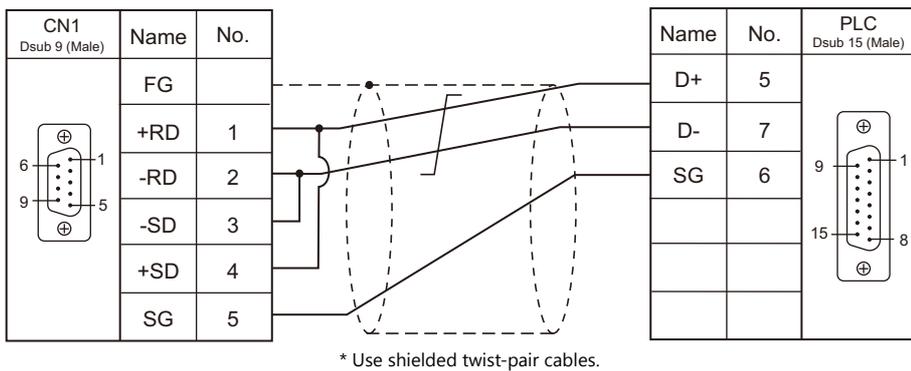


Wiring diagram 2 - C2

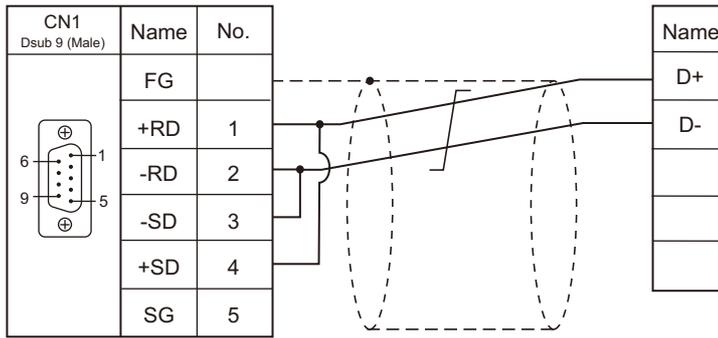


RS-422

Wiring diagram 1 - C4



Wiring diagram 2 - C4

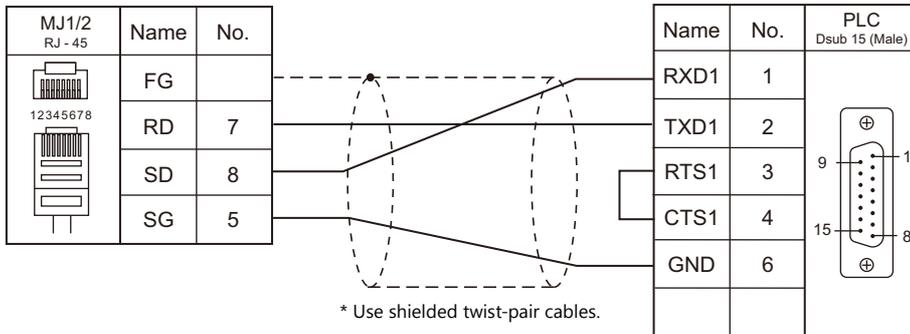


* Use shielded twist-pair cables.

When Connected at MJ1/MJ2:

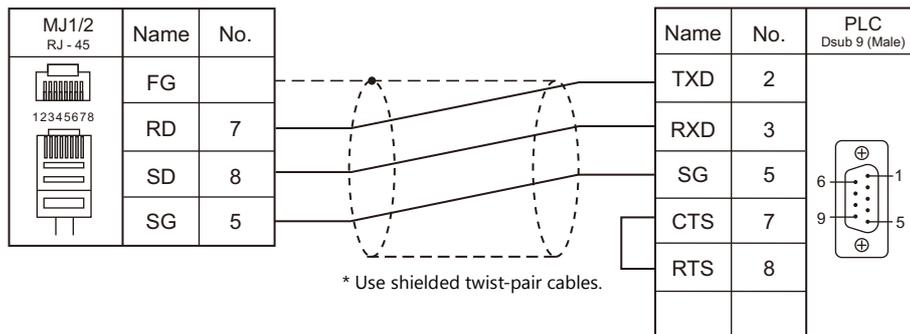
RS-232C

Wiring diagram 1 - M2



* Use shielded twist-pair cables.

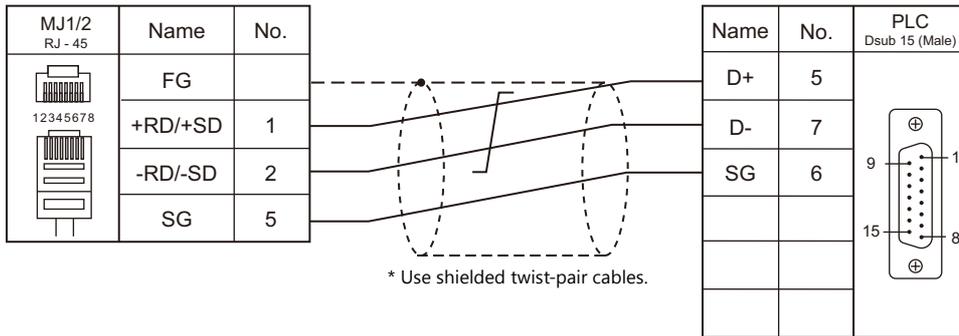
Wiring diagram 2 - M2



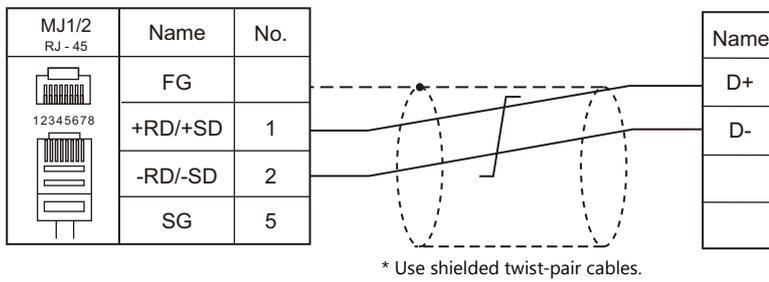
* Use shielded twist-pair cables.

RS-422

Wiring diagram 1 - M4



Wiring diagram 2 - M4



MEMO

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15. FUFENG

15.1 PLC Connection

15.1 PLC Connection

Serial Connection

| PLC Selection on the Editor | CPU | Unit/Port | Signal Level | Connection | | Ladder Transfer ^{*1} |
|-----------------------------|--------|-----------|--------------|-----------------------|-----------------------|-------------------------------|
| | | | | CN1 | MJ1/MJ2 | |
| APC Series Controller | APB-50 | COM1 | RS-232C | Wiring diagram 1 - C2 | Wiring diagram 1 - M2 | × |
| | | | RS-422/485 | Wiring diagram 1 - C4 | Wiring diagram 1 - M4 | |
| | | COM2 | RS-232C | Wiring diagram 2 - C2 | Wiring diagram 2 - M2 | |

*1 For the ladder transfer function, see the V9 Series Reference Manual.

15.1.1 APC Series Controller

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|---|---------|
| Connection Mode | <u>1:1</u> / 1 : n / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet) | |
| Signal Level | <u>RS-232C</u> / RS-422/485 | |
| Baud Rate | 4800 / 9600 / 19200 / 38400 / <u>115K</u> bps | |
| Data Length | <u>8 bits</u> | |
| Stop Bit | <u>1 bit</u> | |
| Parity | <u>None</u> | |
| Target Port No. | <u>0</u> to 98 | |

PLC

COM1

Communication setting

Make PLC settings using the application software "APC Pro". For more information, refer to the PLC manual issued by the manufacturer.

| Item | Setting | Remarks |
|------------|---------------------|--------------------------------------|
| APC system | APC number setup | 0 to 98 |
| | APC baud rate setup | 115200 / 38400 / 19200 / 9600 / 4800 |

Parity: none, data length: 8 bits, stop bit: 1 bit (fixed)

Signal level selection

| Item | Setting | Remarks |
|--------|---------|--|
| Jumper | RS-232C | J1-1: Jumper across pins 2 and 3 J1-2: Jumper across pins 2 and 3 J1-3: Jumper across pins 2 and 3 |
| | RS-485 | J1-1: Jumper across pins 1 and 2 J1-2: Jumper across pins 1 and 2 J1-3: Jumper across pins 1 and 2 |

COM2

Station number: 0, parity: none, data length: 8 bits, stop bit: 1 bit, baud rate: 115200 bps (fixed)

Calendar

This model is not equipped with the calendar function. Use the calendar function of the V series.

Available Device Memory

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|--|------|-----------------------------------|
| D (Data area) | 00H | |
| T (Timer relay area) | 01H | Read only |
| C (Counter relay area) | 02H | Read only |
| R (Accessory relay area) | 03H | Common to D0 to D15 *1 |
| X (Input channel) | 04H | Common to D16 to D30 *1 |
| Y (Output channel) | 05H | Common to D31 to D40 *1 |
| S (System relay area) | 06H | Common to D41 to D55 *1 |
| K (Thermal control relay area) | 07H | Common to D56 to D63 *1 |
| TSW (Timer setting area) | 08H | Common to D208 to D335 |
| TP (Present timer setting area) | 09H | Read only, common to D336 to D463 |
| CSW (Counter setting area) | 0AH | Common to D464 to D591 |
| CP (Present counter setting area) | 0BH | Read only, common to D592 to D719 |
| KJS (Thermal control temperature setting) | 0CH | Common to D80 to D95 |
| KP (Present thermal control temperature setting) | 0DH | Read only, common to D96 to D111 |
| KJL (Thermal control low-temperature alarm setting) | 0EH | Common to D112 to D127 |
| KJH (Thermal control high-temperature alarm setting) | 0FH | Common to D128 to D143 |
| KI (Present thermal control current setting) | 10H | Read only, common to D144 to D159 |
| KJC (Insufficient thermal control) | 11H | Common to D160 to D175 |
| KJR (Thermal control cycle setting) | 12H | Common to D192 to D207 |

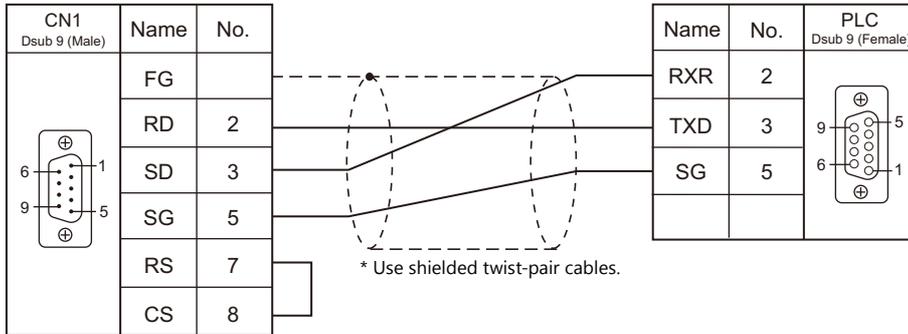
*1 When using consecutive bit devices, select device memory "D" for improved performance.

15.1.2 Wiring Diagrams

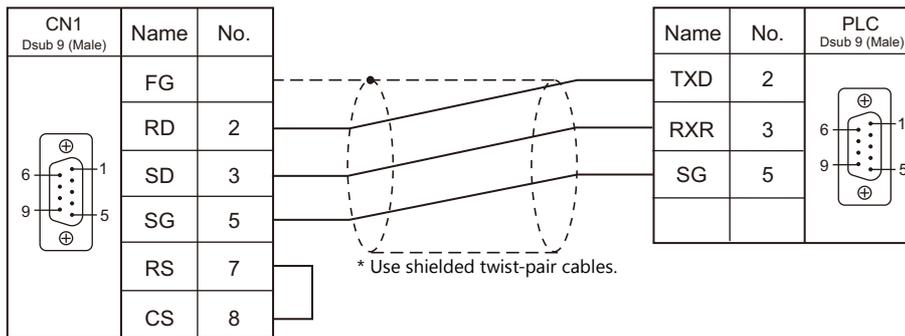
When Connected at CN1:

RS-232C

Wiring diagram 1 - C2

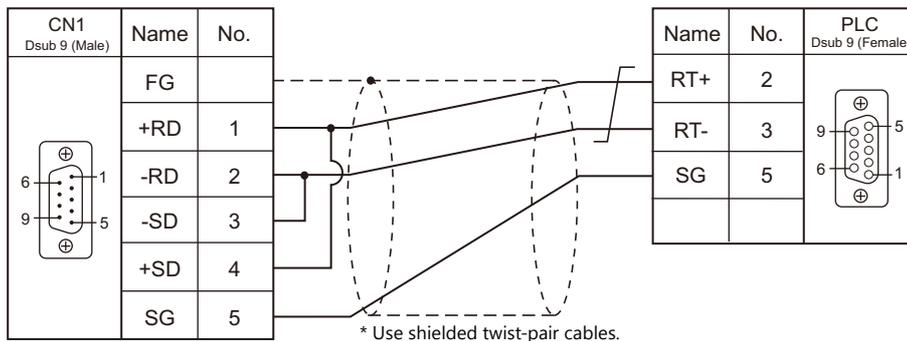


Wiring diagram 2 - C2



RS-422/RS-485

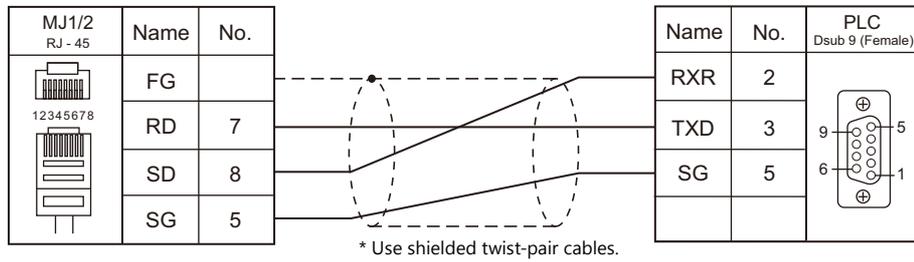
Wiring diagram 1 - C4



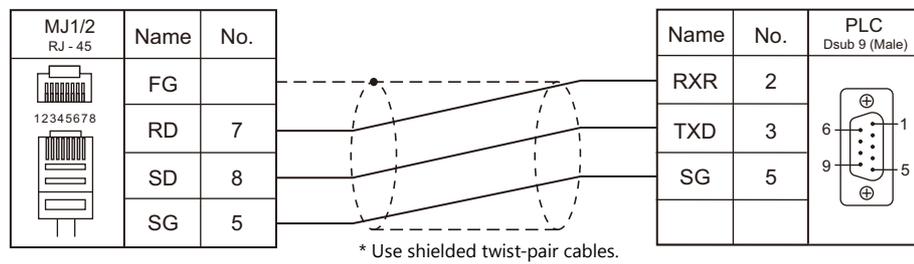
When Connected at MJ1/MJ2:

RS-232C

Wiring diagram 1 - M2

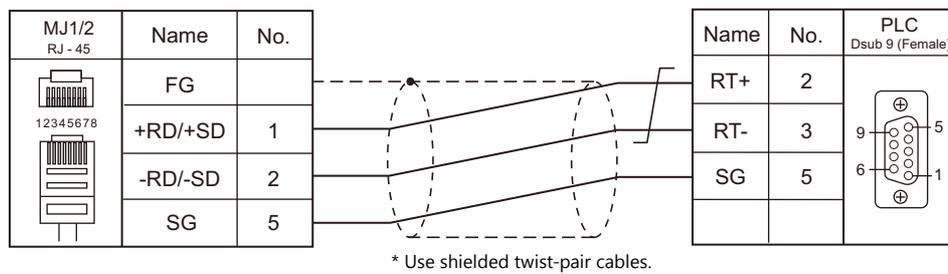


Wiring diagram 2 - M2



RS-422/RS-485

Wiring diagram 1 - M4



MEMO

Please use this page freely.

16. Fuji Electric

16.1 PLC Connection

16.2 Temperature Controller/Servo/Inverter Connection

16.1 PLC Connection

The PLC models shown below can be connected.

Serial Connection

MICREX-F Series

| PLC Selection on the Editor | CPU | Unit/Port | Signal Level | Connection | | Ladder Transfer ^{*1} |
|-----------------------------|--|-----------|--------------|-----------------------|-----------------------|-------------------------------|
| | | | | CN1 | MJ1/MJ2 | |
| MICREX-F series | NV1P-x (F55) | NV1L-RS2 | RS-232C | Wiring diagram 1 - C2 | Wiring diagram 1 - M2 | × |
| | NC1P-E (F70) NC1P-S (F70S) | NC1L-RS2 | RS-232C | Wiring diagram 1 - C2 | Wiring diagram 1 - M2 | |
| | | NC1L-RS4 | RS-485 | Wiring diagram 1 - C4 | Wiring diagram 1 - M4 | |
| | FPU080H (F80H) FPU120H (F120H) FPU120S (F120S) FPU140S (F140S) FPU15xS (F15xS) | FFU120B | RS-232C | Wiring diagram 1 - C2 | Wiring diagram 1 - M2 | |
| | | FFK120A | RS-485 | Wiring diagram 1 - C4 | Wiring diagram 1 - M4 | |

*1 For the ladder transfer function, see the V9 Series Reference Manual.

SPB (N Mode), FLEX-PC

| PLC Selection on the Editor | CPU | Unit/Port | Signal Level | Connection | | Ladder Transfer ^{*1} |
|-------------------------------|--------------|-----------------|-----------------------|-----------------------|-----------------------|-------------------------------|
| | | | | CN1 | MJ1/MJ2 | |
| SPB (N mode) & FLEX-PC series | NS-CPU-xx | NS-RS1 | RS-232C | Wiring diagram 1 - C2 | Wiring diagram 1 - M2 | × |
| | | | RS-485 | Wiring diagram 1 - C4 | × | |
| | NJ-CPU-xx | NJ-RS2 | RS-232C | Wiring diagram 1 - C2 | Wiring diagram 1 - M2 | |
| | | | NJ-RS4 | RS-485 | Wiring diagram 1 - C4 | |
| | NBxx | NB-RS1 | RS-232C | Wiring diagram 1 - C2 | Wiring diagram 1 - M2 | |
| | | | RS-485 | Wiring diagram 1 - C4 | × | |
| | NW0Pxx (SPB) | NW0LA-RS2 | RS-232C | Wiring diagram 3 - C2 | Wiring diagram 3 - M2 | |
| | | | NW0LA-RS4 | RS-485 (4-wire) | Wiring diagram 1 - C4 | |
| | | RS-485 (2-wire) | Wiring diagram 2 - C4 | Wiring diagram 1 - M4 | | |

*1 For the ladder transfer function, see the V9 Series Reference Manual.

*2 Cable length: XXX-FU-SPBCPU-□M (□ = 2, 3, 5 m)

MICREX-SX, SPB (IEC Mode)

| PLC Selection on the Editor | CPU | Unit/Port | Signal Level | Connection | | Ladder Transfer ^{*1} |
|-----------------------------|----------------|-----------------------|-----------------------|---|-----------------------|-------------------------------|
| | | | | CN1 | MJ1/MJ2 | |
| MICREX-SX SPH/SPB series | NP1Px-xx (SPH) | NP1L-RS1 | RS-232C | Wiring diagram 4 - C2 | Wiring diagram 4 - M2 | × |
| | | | RS-485 | Wiring diagram 3 - C4 | × | |
| | | NP1L-RS2, NP1L-RS3 | RS-232C | Wiring diagram 4 - C2 | Wiring diagram 4 - M2 | |
| | | | NP1L-RS4 | RS-485 | Wiring diagram 3 - C4 | |
| | | NP1L-RS5 | RS-485 | Wiring diagram 1 - C4 | × | |
| | NW0Pxx (SPB) | | NW0LA-RS2 | RS-232C | Wiring diagram 3 - C2 | |
| NW0LA-RS4 | | RS-485 | Wiring diagram 1 - C4 | × | | |
| MICREX-SX SPH/SPB CPU | NP1Px-xx (SPH) | CPU port | RS-485 | Hakko Electronics' cable "D9-FU-SPHCPU" ^{*2} | × | ○ |
| | NW0Pxx (SPB) | CPU port | RS-485 | Hakko Electronics' cable "D9-FU-SPBCPU" ^{*2} | × | |

*1 For the ladder transfer function, see the V9 Series Reference Manual.

*2 Cable length: XXX-FU-SPHCPU-□M, XXX-FU-SPBCPU-□M (□ = 2, 3, 5 m)

Ethernet Connection

MICREX-SX Series

| PLC Selection on the Editor | CPU | Unit | TCP/IP | UDP/IP | Port No. | Keep Alive ^{*1} | Ladder Transfer ^{*2} |
|-----------------------------|--|----------------------------|--------|--------|------------------------------|--------------------------|-------------------------------|
| MICREX-SX (Ethernet) | NP1PH-xx (SPH200) NP1PS-xx (SPH300) NP1PM-xx (SPH2000) | NP1L-ET1 | ○ | × | Self port standard No. + 251 | ○ | × |
| | NP1PM-xx (SPH2000) | CPU with built-in Ethernet | | | | | |

*1 For KeepAlive functions, see "1.3.2 Ethernet Communication".

*2 For the ladder transfer function, see the V9 Series Reference Manual.

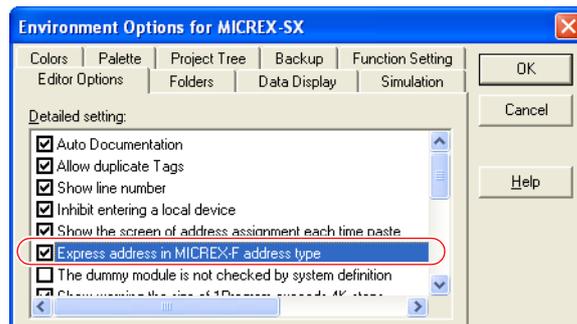
MICREX-SX Model Selection

When the MICREX-SX SPH or SPB series is connected, a mode selection may be required on the V9 editor depending on the programming tool used on the PLC or the setting on the programming tool.

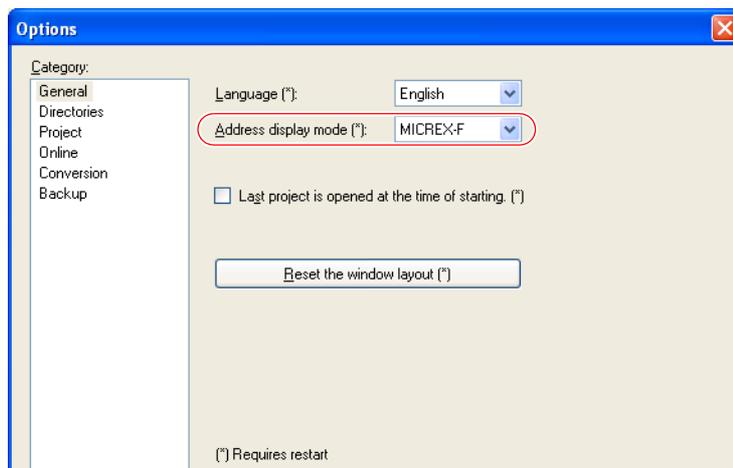
| PLC | PLC Programming Tool | | Setting on the V9 Editor | | |
|--------------------|-------------------------------------|--------------------|---|-------------------|-------------------------------|
| | | Address Expression | PLC Selection | Mode Selection *2 | |
| SPH series | SX-Programmer Expert (D300win) | | MICREX-SX SPH/SPB series MICREX-SX SPH / SPB CPU MICREX-SX (Ethernet) | IEC Mode | |
| | SX-Programmer Standard (Ver. 1 / 2) | Unchecked *1 | | N Mode | |
| | | Checked *1 | | F Mode | |
| | SX-Programmer Standard (Ver. 3) | FLEX-PC *1 | | N Mode | |
| MICREX-F *1 | | F Mode | | | |
| SPF series | SX-Programmer Expert (D300win) | | MICREX-SX SPH/SPB series MICREX-SX SPH / SPB CPU | IEC Mode | |
| | SX-Programmer Standard (Ver. 1 / 2) | SX-MODE | | Unchecked *1 | N Mode |
| | | | | Checked *1 | F Mode |
| | SX-Programmer Standard (Ver. 3) | FLEX-PC *1 | | N Mode | |
| | | MICREX-F *1 | | F Mode | |
| | SX-Programmer Standard (Ver. 1 / 2) | N-MODE | | - | SPB (N mode) & FLEX-PC series |
| FLEX-PC Programmer | - | - | SPB (N mode) & FLEX-PC CPU | - | |

*1 The setting procedure differs depending on the version of the SX-Programmer Standard tool.

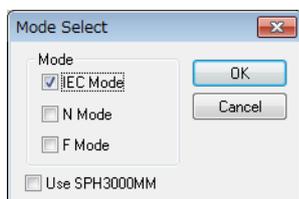
- Ver. 1 or 2:
Check or uncheck the box for [Express address in MICREX-F address type] on the [Editor Options] tab window in the [Environment Options for MICREX-SX] dialog ([Options] → [MICREX-SX Environment]).



- Ver. 3:
Select "MICREX-F" from [Address display mode] ([Tool] → [Options] → [Category: General]).



*2 [Mode Select] dialog on the V9 editor



- [IEC Mode]: Variable name cooperation function
 - [N Mode]: Address denotation "hexadecimal" *
 - [F Mode]: Address denotation "decimal" *
- * Except bit addresses

16.1.1 MICREX-F Series

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|--|---------|
| Connection Mode | <u>1</u> : 1 / 1 : n / Multi-link / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet) | |
| Signal Level | <u>RS-232C</u> / RS-422/485 | |
| Baud Rate | 4800 / 9600 / <u>19200</u> bps | |
| Data Length | <u>7</u> / 8 bits | |
| Stop Bit | <u>1</u> / 2 bits | |
| Parity | None / Odd / <u>Even</u> | |
| Target Port No. | <u>0</u> to 31 | |

PLC

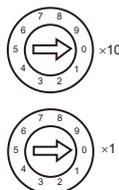
Be sure to match the settings to those made under [Communication Setting] of the editor.

Mode setting

| MODE | Setting | Contents | |
|--|---------|----------|--|
|  | 1 | RS-232C | Command-defined asynchronous communication (non-procedure) |
| | 3 | RS-485 | Command-defined asynchronous communication (non-procedure) |

* The mode setting switch is common to NV1L-RS2, NC1L-RS2, NC1L-RS4, FFU120B and FFK120A.

Station number setting

| ADDRESS | Setting | Contents |
|---|---------|---|
|  | 0 to 31 | Station number ×10: the tens place ×1: the ones place |

* The station number setting switch is common to NC1L-RS4, FFU120B and FFK120A.
It is not provided on NV1L-RS2 nor NC1L-RS2.

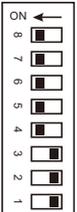
Transmission setting

NV1L-RS2, NC1L-RS2, NC1L-RS4, FFU120B

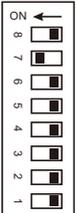
| Switch | Contents | ON | OFF | E.g.) Editor Default Setting |
|--------|---------------------|----------|--------------|---|
| 8 | Initializing method | Switch | Initial file |  |
| 7 | Parity | Provided | Not provided | |
| 6 | Parity bit | Even | Odd | |
| 5 | Data bit length | 7 bits | 8 bits | |
| 4 | Stop bit length | 1 bit | 2 bits | |
| 3 | Baud rate | 19200 | 9600 | |
| 2 | | ON | OFF | |
| 1 | | ON | OFF | |
| | | OFF | ON | |

FFK120A

- Character switches

| Switch | Contents | ON | OFF | E.g.) Editor Default Setting |
|--------|---------------------|----------|--------------|--|
| 8 | Initializing method | Switch | Initial file |  |
| 7 | Parity | Provided | Not provided | |
| 6 | Parity bit | Even | Odd | |
| 5 | Data bit length | 7 bits | 8 bits | |
| 4 | Stop bit length | 2 bits | 1 bit | |
| 3 | Not used | - | OFF | |
| 2 | | - | OFF | |
| 1 | | - | OFF | |
| | | - | OFF | |

- Baud rate setting switches
Set a switch to the ON position.

| Switch | Contents | Example: 19,200 bps |
|--------|------------|---|
| 8 | Not used |  |
| 7 | 19,200 bps | |
| 6 | 9,600 bps | |
| 5 | 4,800 bps | |
| 4 | 2,400 bps | |
| 3 | 1,200 bps | |
| 2 | 600 bps | |
| 1 | 300 bps | |

Available Device Memory

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|----------------------------------|------|-------------------|
| M (auxiliary relay) | 00H | WM as word device |
| K (keep relay) | 01H | WK as word device |
| B (input/output relay) | 02H | WB as word device |
| L (link relay) | 09H | WL as word device |
| F (special relay) | 0AH | WF as word device |
| TS (timer/set value) | 0BH | *1 |
| TR (timer/current value) | 0CH | *1 |
| W9 (0.1-sec timer/current value) | 0DH | *1 |
| CS (counter/set value) | 0EH | *1 |
| CR (counter/current value) | 0FH | *1 |
| BD (data memory) | 10H | *1 |
| WS (step relay) | 11H | *2 |
| Wn (file memory) | 12H | *3, *4 |

*1 For items where double-words can be used (Num. Display, Graph, Sampling), data is processed as double-words. For those where bits or words can be used, data is processed as words consisting of lower 16 bits.

For input: Upper 16 bits are ignored.

For output: "0" is written for upper 16 bits.

*2 WS (step relay) is a byte device processed as described below.

For input: Upper 8 bits are "0".

For output: Lower 8 bits are written.

*3 To set up the file memory on the editor, enter "file number" + ":(colon)" + "address" in order.

Example: W30 : 00002



*4 Define the file area as "**SL**".

16.1.2 SPB (N Mode) & FLEX-PC Series

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|---|---------|
| Connection Mode | <u>1</u> : 1 / 1 : n / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet) | |
| Signal Level | <u>RS-232C</u> / RS-422/485 | |
| Baud Rate | 4800 / 9600 / <u>19200</u> / 38400 bps | |
| Data Length | <u>7</u> / 8 bits | |
| Stop Bit | <u>1</u> / 2 bits | |
| Parity | None / Odd / <u>Even</u> | |
| Target Port No. | <u>0</u> to 31 | |

PLC

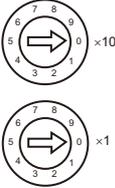
Be sure to match the settings to those made under [Communication Setting] of the editor.

NS-RS1, NJ-RS2, NJ-RS4, NB-RS1

Mode setting

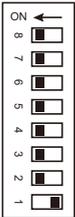
| MODE | Setting | Contents | |
|---|---------|----------|--|
|  | 1 | RS-232C | Command-defined asynchronous communication (non-procedure) |
| | 3 | RS-485 | Command-defined asynchronous communication (non-procedure) |

Station number setting

| ADDRESS | Setting | Contents |
|---|---------|---|
|  | 0 to 31 | Station number ×10: the tens place ×1: the ones place |

* The station number setting switch is not provided on NJ-RS2.

Transmission setting

| Switch | Contents | ON | OFF | E.g.) Editor Default Setting |
|--------|---------------------|----------|--------------|---|
| 8 | Initializing method | Switch | Initial file |  |
| 7 | Parity | Provided | Not provided | |
| 6 | Parity bit | Even | Odd | |
| 5 | Data bit length | 7 bits | 8 bits | |
| 4 | Stop bit length | 1 bit | 2 bits | |
| 3 | Baud rate | 19200 | 9600 | |
| | | ON | ON | |
| 2 | | ON | OFF | |
| 1 | | OFF | ON | |

NWOLA-RS2, NWOLA-RS4 (parameter setting)

On the PLC loader, set parameters for general communications.

Be sure to match the settings to those made under [Communication Setting] of the editor.



| Item | Setting | Remarks |
|-------------------|-----------------------------|---|
| Mode | General (Command asyn) | These settings can also be specified for the parameter area. For more information, refer to the MICREX-SX SPB Series User's Manual <Communication Adapter> (FEH405). |
| Station No. | RS-232C: 0, RS-485: 0 to 31 | |
| Initialize method | Set parameters | |
| Baud rate | 4800 / 9600 / 19200 / 38400 | |
| Parity | Odd / Even / None | |
| Data bits | 8 / 7 | |
| Stop bits | 1 / 2 | |

Notes on use of 2-wire connection with NWOLA-RS4

The settings show above are not enough to establish a 2-wire connection with NWOLA-RS4.

To establish a connection, select [Initial file transfer] for [Initial Setting Mode] on the PLC loader, and select 2-wire connection for [485 mode] in the initial setting file.

For more information, refer to the MICREX-SX SPB Series User's Manual <Communication Adapter> (FEH405).

Available Device Memory

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Standard Device Memory | TYPE | Remarks |
|----------------------------|------|-------------------|
| D (data register) | 00H | |
| W (link register) | 01H | |
| M (internal relay) | 02H | WM as word device |
| L (latch relay) | 03H | WL as word device |
| X (input relay) | 04H | WX as word device |
| Y (output relay) | 05H | WY as word device |
| R (file register) | 06H | |
| TN (timer/current value) | 07H | |
| CN (counter/current value) | 08H | |
| T (timer/contact) | 09H | |
| C (counter/contact) | 0AH | |
| WS (step relay) | 0BH | |

16.1.3 SPB (N Mode) & FLEX-PC CPU

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|--|---|
| Connection Mode | <u>1:1</u> / Multi-link2 / Multi-link2 (Ethernet) | |
| Signal Level | RS-232C / <u>RS-422/485</u> | When connecting MONITOUCH to the RS-232C port on NJ-CPU-B16, select [RS-232C]. In other cases, select [RS-422/485]. |
| Baud Rate | <u>19200</u> bps | |
| Data Length | <u>8</u> bits | |
| Stop Bit | <u>1</u> bit | |
| Parity | <u>Odd</u> | |
| Target Port No. | <u>0</u> | |

PLC

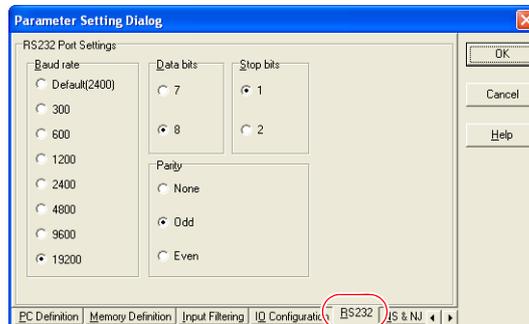
SPB, FLEX-PC CPU port

No particular setting is necessary on the PLC.

Built-in RS-232C port on NJ-CPU-B16

On the PLC loader, set parameters for the built-in RS-232C port.

Be sure to match the settings to those made under [Communication Setting] of the editor.



Available Device Memory

The available device memory is the same as the one described in "16.1.2 SPB (N Mode) & FLEX-PC Series".

16.1.4 MICREX-SX SPH/SPB Series (IEC Mode)

Communication Setting

Editor

Communication setting

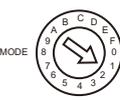
(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|--|---|
| Connection Mode | <u>1</u> :1 / Multi-link2 / Multi-link2 (Ethernet) | |
| Signal Level | <u>RS-232C</u> / RS-422/485 | |
| Baud Rate | 38400 bps | For the SPH series: Do not change the default setting. |
| Data Length | 8 bits | |
| Stop Bit | 1 bits | |
| Parity | Even | |
| Target Port No. | <u>0</u> to 31 | |

PLC

NP1L-RS1, NP1L-RS2, NP1L-RS3, NP1L-RS4, NP1L-RS5

Mode setting

| MODE | Setting | RS1, 2, 4 | RS-232C Port | RS-485 Port | Remarks |
|---|---------|-----------|-------------------------|-------------------------|-------------------------|
| | | RS3, 5 | CH1 | CH2 | |
|  | 0 | | General equipment | General equipment | |
| | 1 | | Loader | General equipment | |
| | 2 | | General equipment | Loader | |
| | 3 | | Loader | Loader | |
| | 4 | | General equipment | General equipment | RS3 and 5 are not used. |
| | 5 | | Not used | | |
| | 6 | | Modem loader 19200 bps | General equipment | |
| | 7 | | Self-diagnosis mode 1 | | |
| | 8 | | Self-diagnosis mode 2 | | |
| | 9 | | Modem loader 19200 bps | Loader | |
| | A | | Modem loader 9600 bps | General equipment | |
| | B | | Modem loader 9600 bps | Loader | |
| | C | | Modem loader 38400 bps | General equipment | |
| | D | | Modem loader 38400 bps | Loader | |
| | E | | Modem loader 76800 bps | General equipment | |
| | F | | Modem loader 115200 bps | Modem loader 115200 bps | |

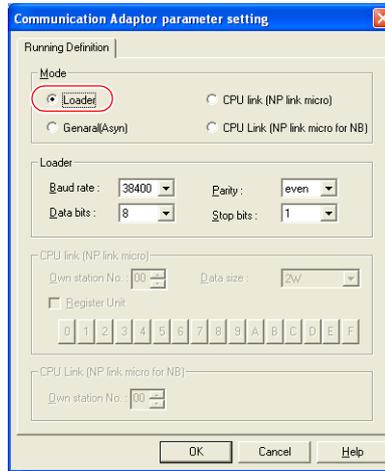
* Set the port (or CH No.) where the V9 is connected to "loader".

Communication parameters are fixed to 38400 bps (baud rate), 8 bits (data length), 1 bit (stop bit), and even (parity).

* When the PLC is connected with the V9, the station number setting switch for RS-485 is not used.

NWOLA-RS2, NWOLA-RS4 (parameter setting)

On the PLC loader, set parameters for general communications.
Be sure to match the settings to those made under [Communication Setting] of the editor.



| Item | Setting | Remarks |
|-----------|-----------------------------|---------|
| Mode | Loader | |
| Baud rate | 4800 / 9600 / 19200 / 38400 | |
| Parity | Odd / Even / None | |
| Data bits | 8 | |
| Stop bits | 1 / 2 | |

Available Device Memory

Variable name cooperation function
The variable name cooperation function can be used only for PLC1. For device memory assignment, basically use the variable name cooperation function. **It is recommended that you specify a device memory address in the [AT] field to define the area (variable) that is used for communications with the V9.**

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|-------------------------|------|---|
| %IX (input memory) *1 | - | %IW as word device, %ID as double-word device *3 |
| %QX (output memory) *1 | - | %QW as word device, %QD as double-word device *3 |
| %MX1. (standard memory) | 02H | %MW1. as word device, %MD1. as double-word device *2 *3 |
| %MX3. (retain memory) | 04H | %MW3. as word device, %MD3. as double-word device *2 *3 |
| %MX10. (system memory) | 08H | %MW10. as word device, %MD10. as double-word device *2 *3 |

*1 For the input/output memory, the variable name cooperation function of the PLC1 must be used. Indirect designation is not available with the input/output memory.

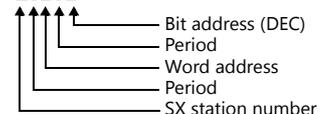
*2 Double-word addresses (%MD1., %MD3., %MD10.) can be specified only for PLC1. In the case with PLC2 to PLC8, access to the above addresses is possible when the data length is set to 2 words in the word address (%MW1., %MW3., %MW10.).
Example: When accessing the address in %MD1.100:
Set the data length to 2 words for %MW1.100.

*3 The assigned device memory is expressed as shown below when editing the screen.

- For %IX or %QX:



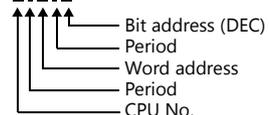
Example: %IX1 . 1 . 0



- For %MX1., %MX3., or %MX10:



Example: %MX1 . 1 . 1 . 0



Indirect Device Memory Designation

Specify the CPU number in the expansion code.

PLC_CTL

Macro command "PLC_CTL F0 F1 F2"

| Contents | F0 | F1 (= \$u n) | | F2 |
|---------------------------------|---------------------|--------------|---|----|
| All start | 1 - 8 (PLC1 - 8) | n | Station number: 0000H | 2 |
| | | n + 1 | Command: 0400H | |
| All stop | 1 - 8 (PLC1 - 8) | n | Station number: 0000H | 2 |
| | | n + 1 | Command: 0402H | |
| Operation / standby switching * | 1 - 8 (PLC1 - 8) | n | Station number: 0000H | 3 |
| | | n + 1 | Command: 040BH | |
| | | n + 2 | CPU No. operated by default: m (0, 2, 4, 6) | |

* Valid only for the redundant system.

16.1.5 MICREX-SX SPH/SPB Series (N Mode / F Mode)

Communication Setting

The communication setting is the same as the one described in "16.1.4 MICREX-SX SPH/SPB Series (IEC Mode)".

Available Device Memory

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|----------------------|------|---|
| X (input memory) *1 | - | WX as word device, DX as double-word device *3 |
| Y (output memory) *1 | - | WY as word device, DY as double-word device *3 |
| M (standard memory) | 02H | WM as word device, DM as double-word device *2 *3 |
| L (retain memory) | 04H | WL as word device, DL as double-word device *2 *3 |
| SM (system memory) | 08H | WSM as word device, DSM as double-word device *2 *3 |

1 Input/output memory does not operate normally unless you import the ".ini" file created using [Export Device Information] in the PLC programming tool.

Can be used only for PLC1. Indirect designation is not available.

*2 Double-word addresses (DM, DL, DSM) can be specified only for PLC1.

In the case with PLC2 to PLC8, access to the above addresses is possible when the data length is set to 2 words in the word address (WM, WL, WSM).

Example: When accessing the address in DM100:

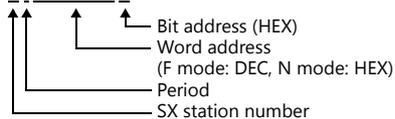
Set the data length to 2 words for WM100.

*3 The assigned device memory is expressed as shown below when editing the screen.

- For X or Y:



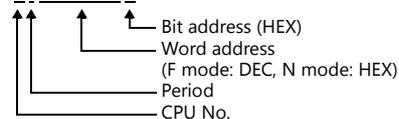
Example: X 1 . 00000001 0



- For M, L or SM



Example: M 1 . 00000001 0



Indirect Device Memory Designation

Specify the CPU number in the expansion code.

PLC_CTL

The macro command is the same as the one described in "16.1.4 MICREX-SX SPH/SPB Series (IEC Mode)".

16.1.6 MICREX-SX SPH/SPB CPU (IEC Mode)

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|---|---|
| Connection Mode | <u>1:1</u> / Multi-link2 / Multi-link2 (Ethernet) | Do not change the setting from default. |
| Signal Level | RS-422/485 | |
| Baud Rate | 38400 bps | |
| Data Length | 8 bits | |
| Stop Bit | 1 bit | |
| Parity | Even | |
| Target Port No. | <u>0</u> to 31 | |

PLC

No particular setting is necessary on the PLC.

Communication parameters are fixed to 38400 bps (baud rate), RS-422 (signal level), 8 bits (data length), 1 bit (stop bit), and even (parity).

Available Device Memory

The available device memory is the same as the one described in "16.1.4 MICREX-SX SPH/SPB Series (IEC Mode)".

PLC_CTL

The macro command is the same as the one described in "16.1.4 MICREX-SX SPH/SPB Series (IEC Mode)".

16.1.7 MICREX-SX SPH/SPB CPU (N Mode / F Mode)

Communication Setting

The communication setting is the same as the one described in "16.1.6 MICREX-SX SPH/SPB CPU (IEC Mode)".

Available Device Memory

The available device memory is the same as the one described in "16.1.5 MICREX-SX SPH/SPB Series (N Mode / F Mode)".

PLC_CTL

The macro command is the same as the one described in "16.1.4 MICREX-SX SPH/SPB Series (IEC Mode)".

16.1.8 MICREX-SX (Ethernet) (IEC Mode)

Communication Setting

Editor

Make the following settings on the editor. For more information, see "1.3.2 Ethernet Communication".

- IP address for the V9 unit
 - When specified on the screen program:
[System Setting] → [Hardware Setting] → [Local Port IP Address]
 - When specified on the V9 unit:
Local mode → [LAN Setting]
- Port number for the V9 unit (for communication with PLC)
[System Setting] → [Hardware Setting] → [PLC Properties] → [Communication Setting]
- IP address and port number of the PLC
Register on the [PLC Table] in [System Setting] → [Hardware Setting] → [PLC Properties] → [Target Settings].
The PLC port number is "Self port standard No." plus 251 set on the PLC.

PLC (Ethernet Parameter Setting)

The table below shows settings required for communication with the V9.

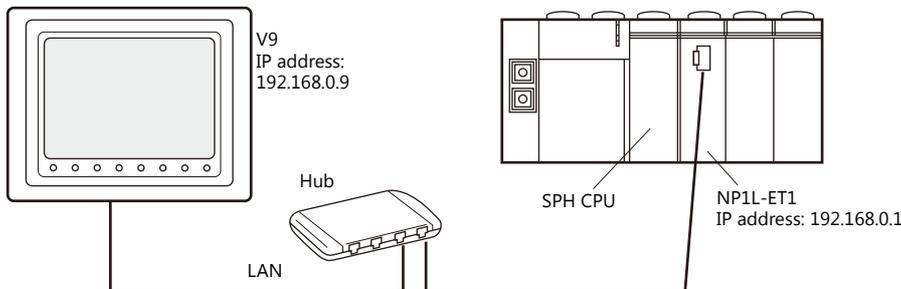
(Underlined setting: default)

| Item | Setting | Remarks |
|------------------------|----------------------|---------|
| IP Address | <u>192.168.0.1</u> | |
| Subnet Mask | <u>255.255.255.0</u> | |
| Self-port Standard No. | <u>256</u> | |

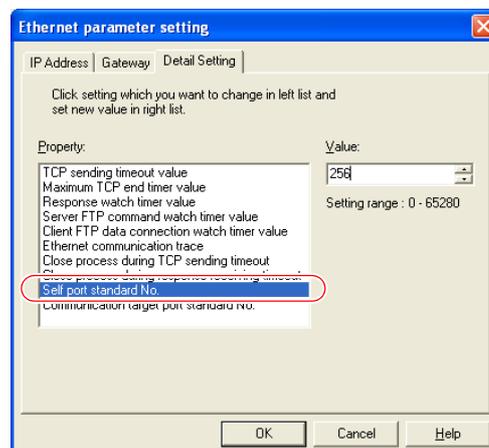
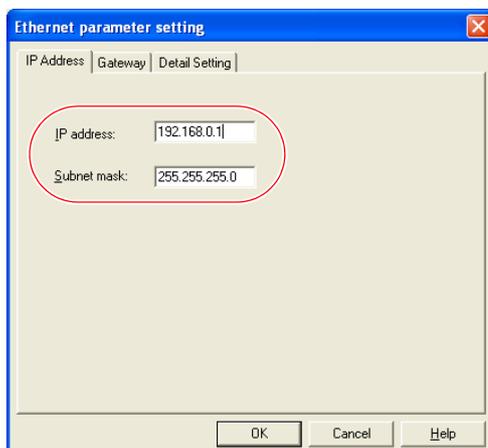
For more information on other setting items, refer to the PLC manual issued by the manufacturer.

Setting Example

The following example shows the setting for communication between MICREX-SX ET1 module and the V9 unit via Ethernet.

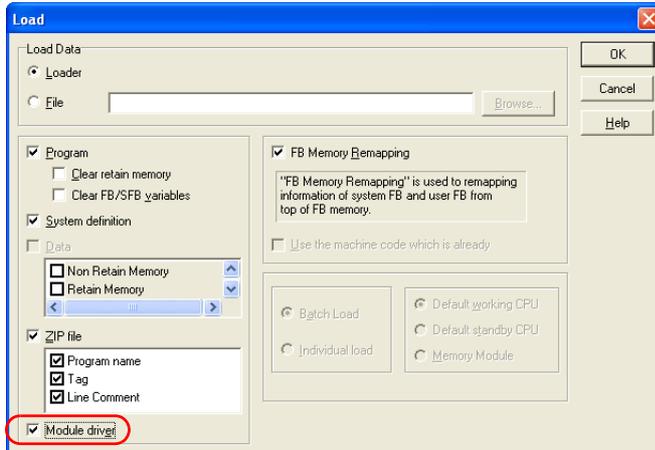


Setting on the PLC loader

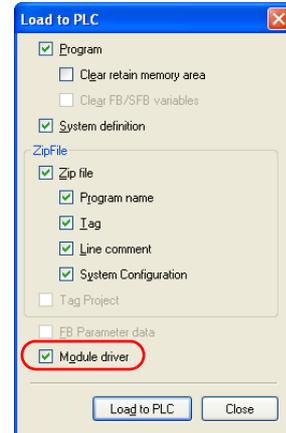


When the Ethernet module is used, the module driver must be transferred to the PLC.
To transfer it to the PLC, check [Module driver] on the relevant PLC transfer setting dialog.

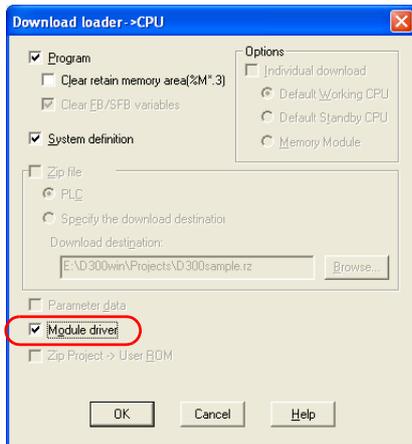
- SX Programmer Standard Ver. 2



- SX Programmer Standard Ver. 3

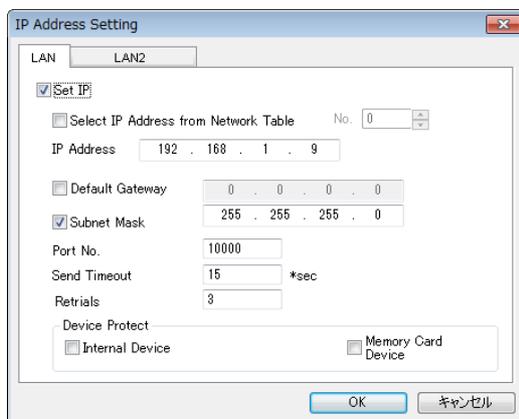


- D300win



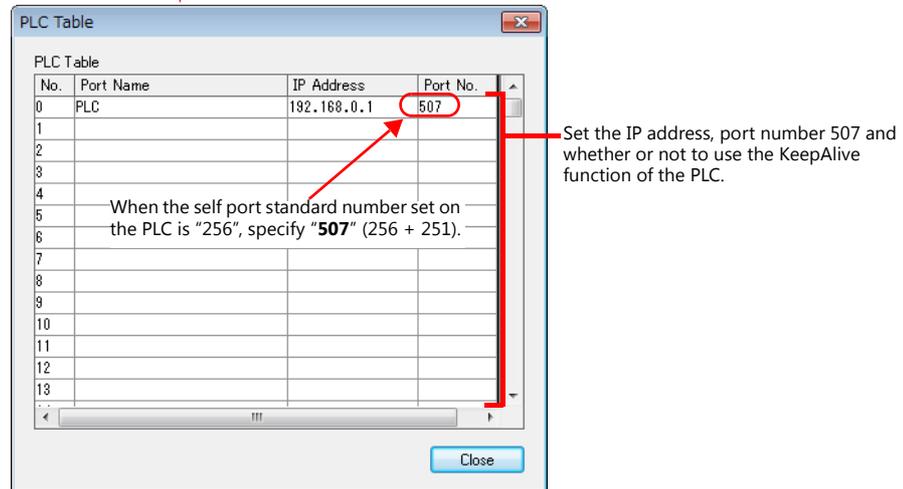
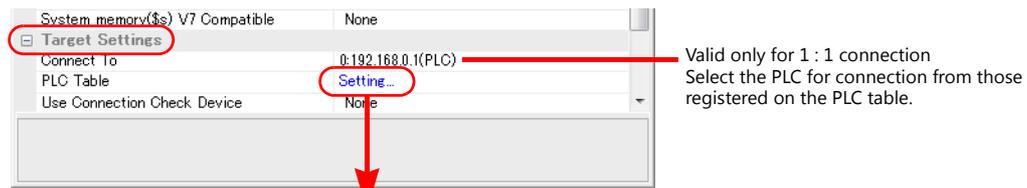
Settings on the editor

- IP address setting for the V9 unit (on the editor)
[System Setting] → [Hardware Setting] → [Local Port IP Address]



- PLC Table

[System Setting] → [Hardware Setting] → [PLC Properties] → [Target Settings] → [PLC Table]



Available Device Memory

The available device memory is the same as the one described in "16.1.4 MICREX-SX SPH/SPB Series (IEC Mode)".

PLC_CTL

Macro command "PLC_CTL F0 F1 F2"

| Contents | F0 | F1 (= \$u n) | | F2 |
|---|---------------------|--------------|---|----|
| All start | 1 - 8 (PLC1 - 8) | n | Station number: 00H to FFH ^{*1} | 2 |
| | | n + 1 | Command: 0400H | |
| All stop | 1 - 8 (PLC1 - 8) | n | Station number: 00H to FFH ^{*1} | 2 |
| | | n + 1 | Command: 0402H | |
| Operation / standby switching ^{*2} | 1 - 8 (PLC1 - 8) | n | Station number: 00H to FFH ^{*1} | 3 |
| | | n + 1 | Command: 040BH | |
| | | n + 2 | CPU No. operated by default: m (0, 2, 4, 6) | |

*1 Valid only when "1 : n" connection mode is selected under [Communication Setting] in the [PLC Properties] window ([System Setting] → [Hardware Setting]).
For the station number, set the PLC table number under [Target Settings] in the [PLC Properties] window ([System Setting] → [Hardware Setting]).

*2 Valid only for a redundant system.

16.1.9 MICREX-SX (Ethernet) (N Mode / F Mode)

Communication Setting

The communication setting is the same as the one described in "16.1.8 MICREX-SX (Ethernet) (IEC Mode)".

Available Device Memory

The available device memory is the same as the one described in "16.1.5 MICREX-SX SPH/SPB Series (N Mode / F Mode)".

PLC_CTL

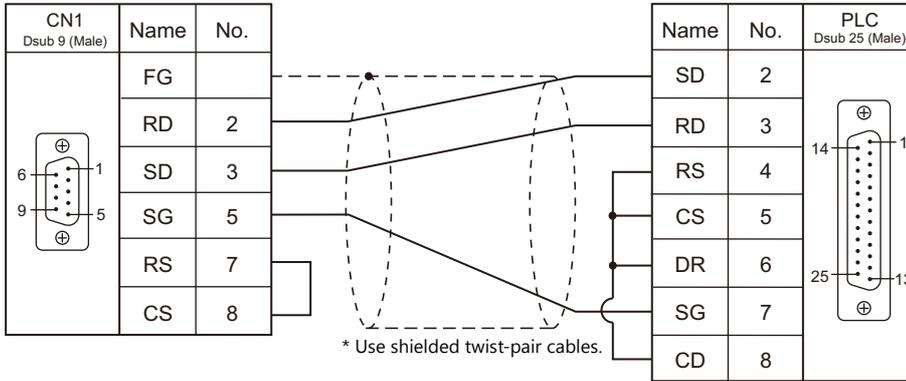
The macro command is the same as the one described in "16.1.8 MICREX-SX (Ethernet) (IEC Mode)".

16.1.10 Wiring Diagrams

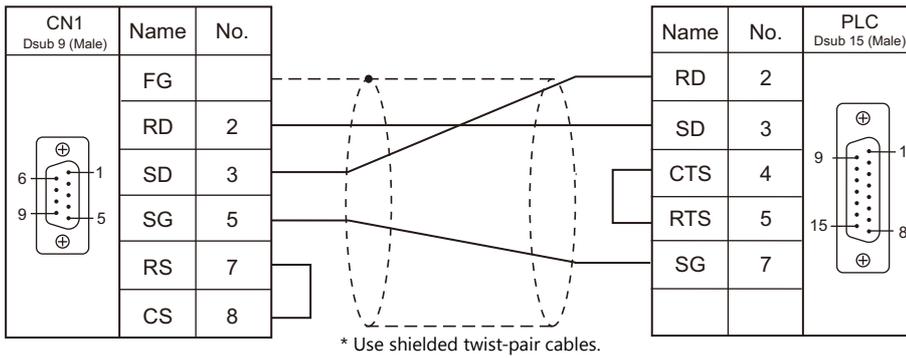
When Connected at CN1:

RS-232C

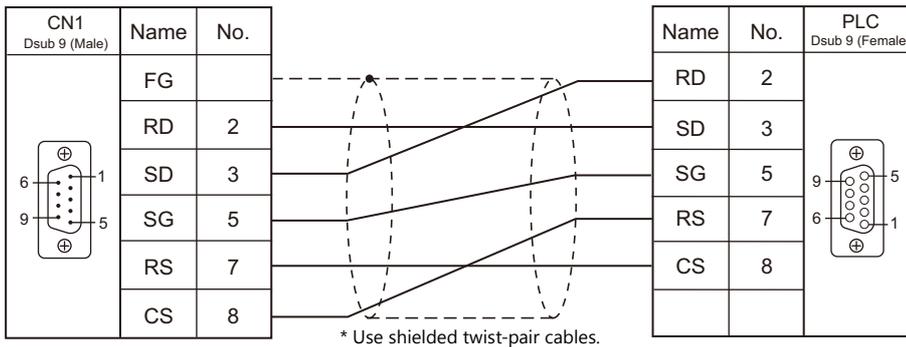
Wiring diagram 1 - C2



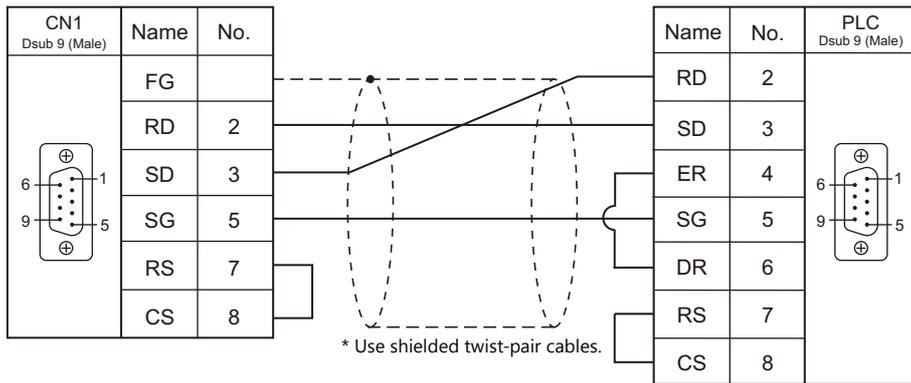
Wiring diagram 2 - C2



Wiring diagram 3 - C2

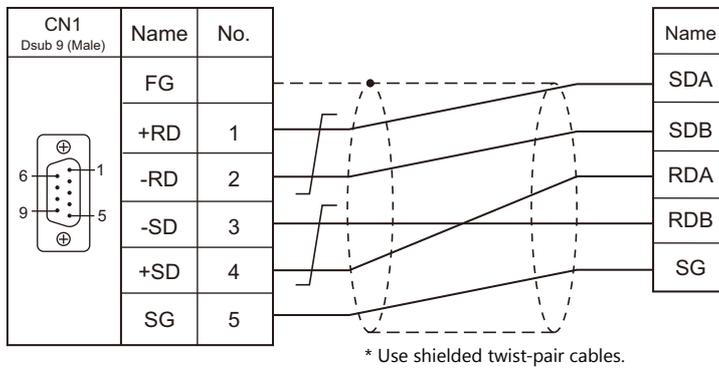


Wiring diagram 4 - C2

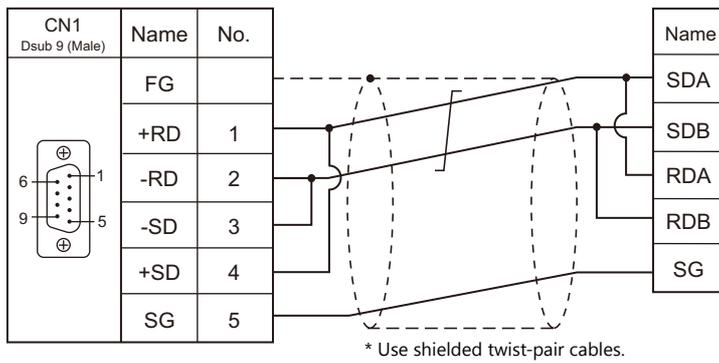


RS-422/RS-485

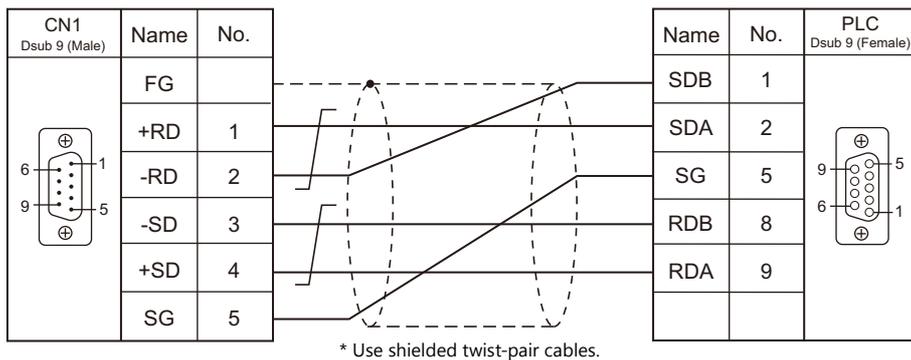
Wiring diagram 1 - C4



Wiring diagram 2 - C4



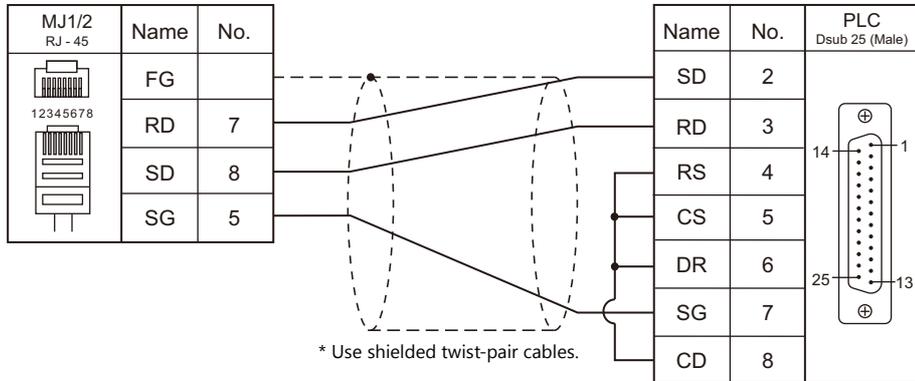
Wiring diagram 3 - C4



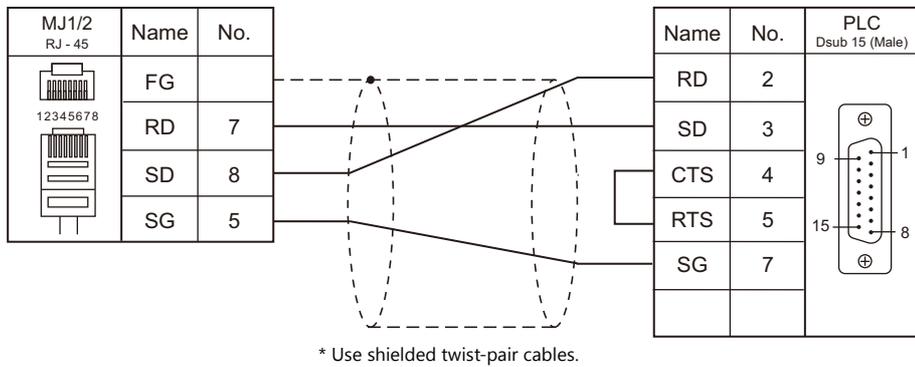
When Connected at MJ1/MJ2:

RS-232C

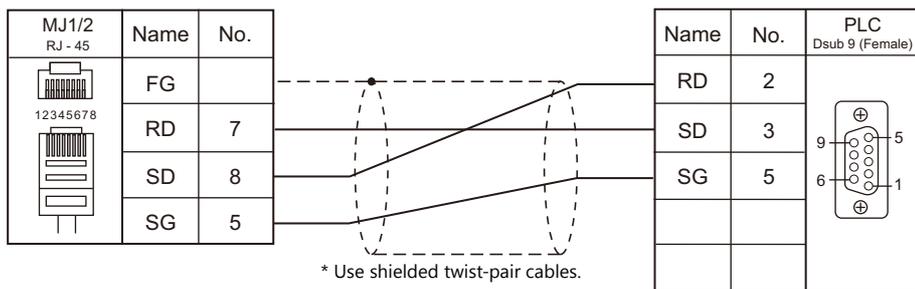
Wiring diagram 1 - M2



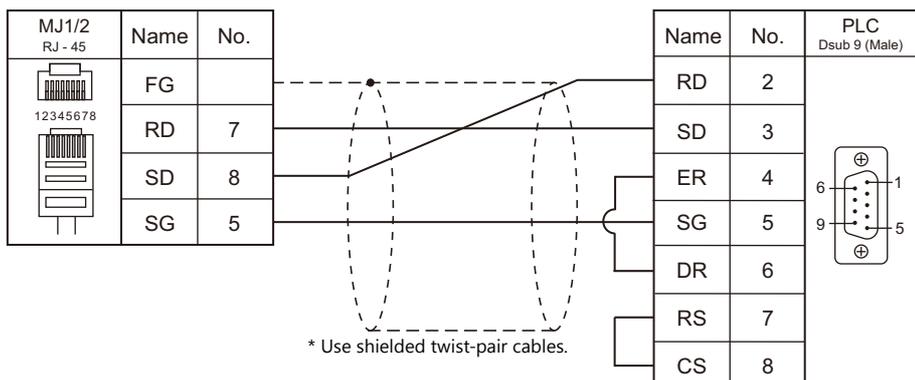
Wiring diagram 2 - M2



Wiring diagram 3 - M2

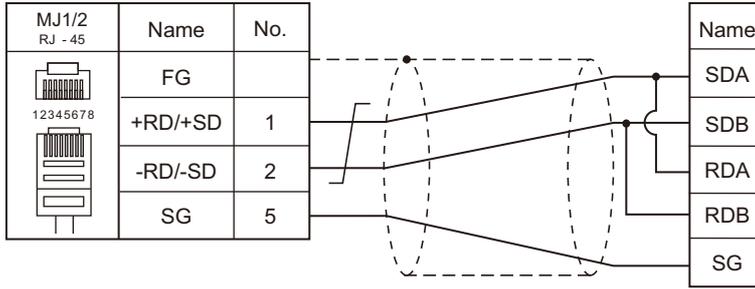


Wiring diagram 4 - M2



RS-422/RS-485

Wiring diagram 1 - M4



* Use shielded twist-pair cables.

16.2 Temperature Controller/Servo/Inverter Connection

The controllers shown below can be connected.

Temperature Controller

| PLC Selection on the Editor | Model | Port | Signal Level | Connection | | Lst File |
|-----------------------------|---|-----------------------|--------------|-----------------------|-----------------------|----------------------------|
| | | | | CN1 | MJ1/MJ2 | |
| PYX (MODBUS RTU) | PYX4xx PYX5xx PYX9xx *1 | Terminal block | RS-485 | Wiring diagram 1 - C4 | Wiring diagram 1 - M4 | PYX.Lst |
| PXR (MODBUS RTU) | PXR3xx PXR4xx PXR5xx PXR7xx PXR9xx *1 | Terminal block | RS-485 | Wiring diagram 1 - C4 | Wiring diagram 1 - M4 | PXR.Lst |
| PXG (MODBUS RTU) | PXG4xx PXG5xx PXG9xx *1 | Terminal block | RS-485 | Wiring diagram 1 - C4 | Wiring diagram 1 - M4 | F_PXG.Lst |
| PXH (MODBUS RTU) | PXH9xx *1 | Terminal block | RS-485 | Wiring diagram 2 - C4 | Wiring diagram 2 - M4 | F_PXH.Lst |
| PUM (MODBUS RTU) | PUMxx | Terminal block (base) | RS-485 | Wiring diagram 2 - C4 | Wiring diagram 2 - M4 | F_PUMA_B.Lst F_PUME.Lst |

*1 Select a model on which Modbus communication is available.

Power Monitor Unit

| PLC Selection on the Editor | Series Name | Model | Port | Signal Level | Connection | | Lst File | |
|-----------------------------|----------------------------|----------------------------------|---------------------|-----------------------|-----------------------|-----------------------|-----------------------|-------------------|
| | | | | | CN1 | MJ1/MJ2 | | |
| F-MPC04P (loader) | F-MPC04P | UM02-AR2 UM02-AR3 UM02-AR4 | RS-485 connector | RS-485 | Wiring diagram 3 - C4 | Wiring diagram 3 - M4 | F-MPC04P.Lst | |
| F-MPC series / FePSU | F-MPC04 | UM01-ARxx | Terminal block | RS-485 | Wiring diagram 4 - C4 | Wiring diagram 4 - M4 | UM01_ARA4.Lst | |
| | | UM02-AR2 UM02-AR3 UM02-AR4 | Terminal block | RS-485 | Wiring diagram 4 - C4 | Wiring diagram 4 - M4 | UM02_AR2.Lst | |
| | | | | | | | UM02_AR3.Lst | |
| | UM02-AR4 | | | | | UM02_AR4.Lst | | |
| | F-MPC04S | UM03-AR3x | Terminal block | RS-485 | Wiring diagram 4 - C4 | Wiring diagram 4 - M4 | UM03_ARA3GLst | |
| | F-MPC30 | UM5ACxx *1 | Terminal block | RS-485 | Wiring diagram 4 - C4 | Wiring diagram 4 - M4 | UM5A.Lst | |
| | | UM45xx *1 | | | | | | |
| | F-MPC50 | UM50xx *1 | Terminal block | RS-485 | Wiring diagram 4 - C4 | Wiring diagram 4 - M4 | UM50.Lst | |
| | F-MPC55 | UM55V | Terminal block | RS-485 | Wiring diagram 4 - C4 | Wiring diagram 4 - M4 | UM55V.Lst | |
| | F-MPC60B | F-MPC60B | UM4Bxx *1 | Terminal block | RS-485 | Wiring diagram 4 - C4 | Wiring diagram 4 - M4 | UM4_UM42_UM43.Lst |
| | | | UM42Cxx *1 | | | | | |
| | | | UM42Fxx *1 | | | | | |
| | | | UM43FDxx *1 | | | | | |
| | | | UM43FGxx *1 | | | | | |
| UM44Bxx *1 | | | | | | | | |
| UM44CDxx *1 | | | | | | UM44.Lst | | |
| FePSU | FePSU | EAxx EGxx SAXX SGxx | Terminal block | RS-485 | Wiring diagram 5 - C4 | Wiring diagram 5 - M4 | FePSU.Lst | |
| | | BWxxxxxx EWxxxxxx | Terminal block | RS-485 | Wiring diagram 5 - C4 | Wiring diagram 5 - M4 | FePSUBk.Lst | |
| F*JF-R | F*JF-R F2JF-R F3JF-R | Terminal block | RS-485 | Wiring diagram 4 - C4 | Wiring diagram 4 - M4 | FJF-R.Lst | | |

*1 Select a model on which RS-485 communication is available.

Inverter

| PLC Selection on the Editor | Model | Port | Signal Level | Connection | | Lst File |
|------------------------------------|--------------------------------|-----------------------------------|--------------|------------------------|------------------------|--|
| | | | | CN1 | MJ1/MJ2 | |
| FVR-E11S | FVRxxE11S-x | Touch panel connector | RS-485 | Wiring diagram 6 - C4 | Wiring diagram 6 - M4 | FVR-E11S.Lst |
| FVR-E11S (MODBUS RTU) | | | | | | FVR-E11S (Modbus).Lst |
| FVR-C11S (MODBUS RTU) | FVRxxC11S-x | OPC-C11S-RSx | RS-485 | Wiring diagram 7 - C4 | Wiring diagram 7 - M4 | FVR-C11S (Modbus).Lst |
| FRENIC5000G11S / P11S | FRNxxG11S-x FRNxxP11S-x | Terminal block | RS-485 | Wiring diagram 8 - C4 | Wiring diagram 8 - M4 | F-G11S.Lst |
| FRENIC5000G11S / P11S (MODBUS RTU) | | | | | | FRENIC5000G11S_P11S (Modbus).Lst |
| FRENIC5000VG7 (MODBUS RTU) | FRNxxVG7S-x | RS-485 connector | RS-485 | Wiring diagram 9 - C4 | Wiring diagram 9 - M4 | FRENIC5000VG7S (Modbus).Lst |
| | | OPC-VG7-RS (communication board) | | Wiring diagram 8 - C4 | Wiring diagram 8 - M4 | |
| FRENIC-Mini (MODBUS RTU) | FRNxxC1S-x | OPC-C1-RS (communication board) | RS-485 | Wiring diagram 10 - C4 | Wiring diagram 10 - M4 | F-Mini.Lst |
| FRENIC-Eco (MODBUS RTU) | FRNxxF1S-x | Touch panel connector | RS-485 | Wiring diagram 10 - C4 | Wiring diagram 10 - M4 | F-Eco (Modbus).Lst |
| | | OPC-F1-RS (communication board) | | Wiring diagram 8 - C4 | Wiring diagram 8 - M4 | |
| FRENIC-Multi (MODBUS RTU) | FRNxxE1S-x | Touch panel connector | RS-485 | Wiring diagram 10 - C4 | Wiring diagram 10 - M4 | F-Multi.Lst |
| | | OPC-E1-RS (communication board) | | Wiring diagram 10 - C4 | Wiring diagram 10 - M4 | |
| FRENIC-MEGA (MODBUS RTU) | FRNxxxG1x-xx | Touch panel connector | RS-485 | Wiring diagram 10 - C4 | Wiring diagram 10 - M4 | FRENIC-MEGA (Modbus).Lst |
| | | Terminal block on control circuit | | Wiring diagram 8 - C4 | Wiring diagram 8 - M4 | |
| FRENIC-MEGA SERVO (MODBUS RTU) | FRNxxxG1x-xxxQ | Touch panel connector | RS-485 | Wiring diagram 10 - C4 | Wiring diagram 10 - M4 | FRENIC-MEGA SERVO (Modbus).Lst |
| | | Control circuit terminal block | | Wiring diagram 8 - C4 | Wiring diagram 8 - M4 | |
| FRENIC-HVAC/AQUA (MODBUS RTU) | FRNxxxAR1x-4x FRNxxxAQ1x-4x | Touch panel connector | RS-485 | Wiring diagram 10 - C4 | Wiring diagram 10 - M4 | FRENIC-HVAC (Modbus).Lst FRENIC-AQUA (Modbus).Lst |
| | | Control circuit terminal block | | Wiring diagram 8 - C4 | Wiring diagram 8 - M4 | |

IH Inverter

| PLC Selection on the Editor | Model | Port | Signal Level | Connection | | Lst File |
|-----------------------------|--|---------------------------------|--------------|------------------------|------------------------|--------------|
| | | | | CN1 | MJ1/MJ2 | |
| HFR-C9K | HFR030C9Kxx HFR050C9Kxx | HFR-OPC01 (communication board) | RS-485 | Wiring diagram 13 - C4 | Wiring diagram 13 - M4 | F_HFR.Lst |
| HFR-C11K | HFR3.0C11Kxx HFR5.0C11Kxx HFR7.0C11Kxx | Terminal block | RS-485 | Wiring diagram 8 - C4 | Wiring diagram 8 - M4 | HFR-C11K.Lst |

AC Power Monitor

| PLC Selection on the Editor | Model | Port | Signal Level | Connection | | Lst File |
|-----------------------------|-----------|----------------|--------------|-----------------------|-----------------------|------------|
| | | | | CN1 | MJ1/MJ2 | |
| PPMC (MODBUS RTU) | PPMCxx *1 | Terminal block | RS-232C | Wiring diagram 1 - C2 | Wiring diagram 1 - M2 | F-PPMC.Lst |
| | | | RS-485 | Wiring diagram 1 - C4 | Wiring diagram 1 - M4 | |

*1 Select a model on which RS-485 or RS-232C communication is available.

Servo Amplifier

| PLC Selection on the Editor | Model | Port | Signal Level | Connection | | Lst File |
|------------------------------|-------------------|----------------|--------------|------------------------|------------------------|-----------------|
| | | | | CN1 | MJ1/MJ2 | |
| FALDIC- α series | RYSxx *1 | CN3 | RS-485 | Wiring diagram 12 - C4 | Wiring diagram 12 - M4 | F_FAL-A.Lst |
| FALDIC-W series | RYCxxx x3-VVT2 | CN3A (UP port) | RS-485 | Wiring diagram 17 - C4 | Wiring diagram 17 - M4 | F_Fal-W.Lst |
| ALPHA5 (MODBUS RTU) | RYTxxx5-VV x | CN3A | RS-485 | Wiring diagram 14 - C4 | Wiring diagram 14 - M4 | ALPHA5.Lst |
| ALPHA5 Smart (MODBUS RTU) | RYHxxxF5-V V2 | CN3A | RS-485 | Wiring diagram 14 - C4 | Wiring diagram 14 - M4 | ALPHA5Smart.Lst |

*1 Select a model on which host interface: universal communication (RS-485) is available.

Controller

| PLC Selection on the Editor | Model | Port | Signal Level | Connection | | Lst File | |
|-----------------------------|--|----------|--------------|-----------------------|------------------------|----------|------------------------|
| | | | | CN1 | MJ1/MJ2 | | |
| WSZ series | WSZ-24MCT2-AC WSZ-32MCT2-AC WSZ-40MCT2-AC WSZ-60MCT2-AC | PORT0 | RS-232C | Wiring diagram 3 - C2 | Wiring diagram 3 - M2 | WSZ.Lst | |
| | | WSZ-CB25 | PORT1 | RS-232C | Wiring diagram 4 - C2 | | Wiring diagram 4 - M2 |
| | | | PORT2 | RS-485 | Wiring diagram 18 - C4 | | Wiring diagram 18 - M4 |

Recorder

| PLC Selection on the Editor | Model | Port | Signal Level | Connection | | Lst File |
|-----------------------------|----------------------------------|----------------|--------------|------------------------|------------------------|-----------|
| | | | | CN1 | MJ1/MJ2 | |
| PH series | PHAxxxx4-xxxRY PHCxxxx3-xxxRY | Terminal block | RS-485 | Wiring diagram 16 - C4 | Wiring diagram 16 - M4 | F_PHC.Lst |
| PHR (MODBUS RTU) | PHRxx | Terminal block | RS-485 | Wiring diagram 2 - C4 | Wiring diagram 2 - M4 | F_PHR.Lst |

Digital Panel Meter

| PLC Selection on the Editor | Model | Port | Signal Level | Connection | | Lst File |
|-----------------------------|--|--------------|--------------|------------------------|------------------------|------------|
| | | | | CN1 | MJ1/MJ2 | |
| WA5000 | WA5xx3-yy WA5xx4-yy WA5xx6-yy WA5xx7-yy | Modular Jack | RS-232C | Wiring diagram 2 - C2 | Wiring diagram 2 - M2 | WA5000.Lst |
| | | | RS-485 | Wiring diagram 11 - C4 | Wiring diagram 11 - M4 | |

*1 Specify an input unit (-yy: 01 to 12, or 18) when selecting the model.

AC Power Regulator

| PLC Selection on the Editor | Model | Port | Signal Level | Connection | | Lst File |
|-----------------------------|--------------------------|------------------------------------|--------------|-----------------------|-----------------------|-------------|
| | | | | CN1 | MJ1/MJ2 | |
| APR-N (MODBUS RTU) | RPNExxx-xx-ZA M-xx/xx | RPN003-AM (communication board) | RS-485 | Wiring diagram 4 - C4 | Wiring diagram 4 - M4 | F_APR-N.Lst |

Electronic Multimeter

| PLC Selection on the Editor | Model | Port | Signal Level | Connection | | Lst File |
|--------------------------------|-----------------|----------------|--------------|------------------------|------------------------|---|
| | | | | CN1 | MJ1/MJ2 | |
| WE1MA (Ver. A) (MODBUS RTU) | WE1MA-AFxxx-Mxx | Terminal block | RS-485 | Wiring diagram 15 - C4 | Wiring diagram 15 - M4 | F_WE1MA.Lst |
| | WE1MA-AGxxx-Mxx | | | | | F_WE1MA_1P.Lst ^{*1} |
| | WE1MA-A1xxx-Mxx | | | | | F_WE1MA_1P3LL.Lst ^{*1} |
| | WE1MA-A5xxx-Mxx | | | | | F_WE1MA_3P3LL.Lst ^{*1} |
| | WE1MA-A2xxx-Mxx | | | | | F_WE1MA_3P4LL.Lst ^{*1} |
| | WE1MA-A6xxx-Mxx | | | | | |
| | WE1MA-A7xxx-Mxx | | | | | |
| WE1MA (Ver. B) (MODBUS RTU) | WE1MA-AFxxx-Mxx | Terminal block | RS-485 | Wiring diagram 15 - C4 | Wiring diagram 15 - M4 | F_WE1MA (Ver. B).Lst |
| | WE1MA-AGxxx-Mxx | | | | | F_WE1MA_1P (Ver. B).Lst ^{*1} |
| | WE1MA-A1xxx-Mxx | | | | | F_WE1MA_1P3L (Ver. B).Lst ^{*1} |
| | WE1MA-A5xxx-Mxx | | | | | F_WE1MA_3P3L (Ver. B).Lst ^{*1} |
| | WE1MA-A2xxx-Mxx | | | | | F_WE1MA_3P4L (Ver. B).Lst ^{*1} |
| | WE1MA-A6xxx-Mxx | | | | | |
| | WE1MA-A7xxx-Mxx | | | | | |
| | WE1MA-A4xxx-Mxx | | | | | |

*1 List files "F_WE1MA.Lst" and "F_WE1MA(Ver. B).Lst" can be browsed as default through the [Refer] button. These files can be used for device memory settings.

16.2.1 PYX (MODBUS RTU)

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|--|--|
| Connection Mode | 1 : 1 / <u>1 : n</u> / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet) | |
| Signal Level | <u>RS-422/485</u> | Do not change the default settings because these settings on the temperature controller cannot be changed. |
| Baud Rate | <u>9600 bps</u> | |
| Data Length | <u>8 bits</u> | |
| Stop Bit | <u>1 bit</u> | |
| Parity | <u>Odd</u> | |
| Target Port No. | 1 to 31 | |

Temperature Controller

The communication parameter can be set using keys attached to the front of the temperature controller. Be sure to match the settings to those made under [Communication Setting] of the editor.

(Underlined setting: default)

| Parameter | Item | Setting | Example |
|-------------|---|----------------|---------|
| Sfno | Digital transmission function (station number) | <u>1</u> to 31 | 1 |

- * The communication function of the temperature controller can be selected from Fuji protocol or Modbus protocol at the time of purchase. For communication with a V9, select a model on which the Modbus protocol is available.
- * The following communication parameters are fixed; baud rate: 9600 bps, data length: 8 bits, stop bit: 1 bit, and parity: odd.

Available Device Memory

The available setting range of device memory varies depending on the model. Be sure to set within the range available for the model to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|---------------|------|-----------|
| 0 | 00H | |
| 1 | 01H | Read only |
| 4 | 02H | |
| 3 | 03H | Read only |

16.2.2 PXR (MODBUS RTU)

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|--|--|
| Connection Mode | 1 : 1 / <u>1:n</u> / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet) | |
| Signal Level | RS-422/485 | Do not change the default settings because these settings on the temperature controller cannot be changed. |
| Baud Rate | 9600 bps | |
| Data Length | 8 bits | |
| Stop Bit | 1 bit | |
| Parity | None / Even / <u>Odd</u> | |
| Target Port No. | 1 to 31 | |

Temperature Controller

The communication parameter can be set using keys attached to the front of the temperature controller. Be sure to match the settings to those made under [Communication Setting] of the editor.

(Underlined setting: default)

| Parameter | Display | Item | Setting | Example | |
|-----------------------|-------------|------|------------------------|--|---|
| Third block parameter | Sfno | STno | Station number | <u>1</u> - 31 | 1 |
| | CoM | CoM | Parity | <u>0: Odd</u> 1: Even 2: None | 0 |
| | PCoL | PCoL | Communication protocol | <u>1: Modbus</u> ^{*1} 2: Z-ASCII | 1 |

*1 The communication function of the temperature controller can be selected at the time of purchase. Select a model on which RS-485 (Modbus) communication is available.

*2 The following communication parameters are fixed; baud rate: 9600 bps, data length: 8 bits, and stop bit: 1 bit.

Available Device Memory

The available setting range of device memory varies depending on the model. Be sure to set within the range available for the model to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|---------------|------|-----------|
| 0 | 00H | |
| 1 | 01H | Read only |
| 4 | 02H | |
| 3 | 03H | Read only |

16.2.3 PXG (MODBUS RTU)

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|--|--|
| Connection Mode | 1 : 1 / <u>1:n</u> / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet) | |
| Signal Level | RS-422/485 | Do not change the default settings of the signal level, data length and stop bit because these settings on the temperature controller cannot be changed. |
| Baud Rate | <u>9600</u> / 19200 bps | |
| Data Length | 8 bits | |
| Stop Bit | 1 bit | |
| Parity | None / Even / <u>Odd</u> | |
| Target Port No. | 1 to 31 | |

Temperature Controller

The communication parameter can be set using keys attached to the front of the temperature controller. Be sure to match the settings to those made under [Communication Setting] of the editor.

(Underlined setting: default)

| Channel | Parameter Display | Item | Setting | Example |
|----------------------------------|-------------------|-------------------------|---|---------|
| "CoM Ch9" Communication (Ch9) | "STno" STno | Station number | <u>1</u> to 31 | 1 |
| | "CoM" CoM | Parity | <u>96od</u> (9600 bps / odd parity) 96Ev (9600 bps / even parity) 96no (9600 bps / without parity) 19od (19200 bps / odd parity) 19Ev (19200 bps / even parity) 196no (19200 bps / without parity) | 96od |
| | "SCC" SCC | Communication authority | r (Read only) <u>rW</u> (Read/write allowed) | rW |

* The communication function of the temperature controller can be selected at the time of purchase. Select a model on which RS-485 (Modbus) communication is available.

* The following communication parameters are fixed; data length: 8 bits and stop bit: 1 bit.

Available Device Memory

The available setting range of device memory varies depending on the model. Be sure to set within the range available for the model to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|----------------------|------|---------|
| 1 (input relay) | 01H | |
| 4 (holding register) | 02H | |
| 3 (input register) | 03H | |

16.2.4 PXH (MODBUS RTU)

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|--|--|
| Connection Mode | 1 : 1 / <u>1:n</u> / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet) | |
| Signal Level | RS-422/485 | Do not change the default settings of the signal level, data length and stop bit because these settings on the temperature controller cannot be changed. |
| Baud Rate | 9600 / 19200 / <u>38400</u> bps | |
| Data Length | 8 bits | |
| Stop Bit | 1 bit | |
| Parity | None / Even / <u>Odd</u> | |
| Target Port No. | 1 to 31 | |

Temperature Controller

The communication parameter can be set using keys attached to the front of the temperature controller. Be sure to match the settings to those made under [Communication Setting] of the editor.

(Underlined setting: default)

| Channel | Parameter Display | Item | Setting | Example |
|---|-------------------|--------------------|--|---------|
|  Communication (Ch B) | STn4 | RS-485 station No. | <u>1</u> to 31 | 1 |
| | SPd4 | RS-485 baud rate | 96: 9600 bps 192: 19200 bps <u>384: 38400 bps</u> | 384 |
| | biT4 | RS-485 bit format | 8n: Data length 8 bits, without parity <u>8o: Data length 8 bits, odd parity</u> 8E: Data length 8 bits, even parity | 8o |

* The communication function of the temperature controller can be selected at the time of purchase. Select a model on which RS-485 (Modbus) communication is available.

* The following communication parameters are fixed; data length: 8 bits and stop bit: 1 bit.

Available Device Memory

The available setting range of device memory varies depending on the model. Be sure to set within the range available for the model to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|----------------------|------|---------|
| 4 (holding register) | 02H | |
| 3 (input register) | 03H | |

16.2.5 PUM (MODBUS RTU)

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|--|--|
| Connection Mode | 1 : 1 / <u>1:n</u> / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet) | |
| Signal Level | RS-422/485 | Do not change the default settings of the signal level, data length and stop bit because these settings on the temperature controller cannot be changed. |
| Baud Rate | 9600 / <u>19200</u> / 38400 / 115200 bps | |
| Data Length | 8 bits | |
| Stop Bit | 1 bit | |
| Parity | <u>None</u> / Even / Odd | |
| Target Port No. | 1 to 15 [DEC] | |

Temperature Controller

Be sure to match the settings to those made under [Communication Setting] of the editor.

Station number setting

(Underlined setting: default)

| STATION | Setting | Example |
|---|---------------------|---|
|  | <u>0</u> to F [HEX] | 0: Station number 1 F: Station number 16 |

Communication setting

On the temperature controller loader, set communication parameters.

(Underlined setting: default)

| Item | Setting | Example | Remarks |
|--|--|---------|---|
| RS-485 parity setting | <u>0: None</u> 1: Odd 2: Even | 0 | |
| RS-485 baud rate setting | 0: 9600 <u>1: 19200</u> 2: 38400 4: 115200 kbps | 1 | |
| RS-485 communication authority setting | 0: Read only <u>1: Read/write allowed</u> | 1 | |
| RS-485 response interval setting | 0 to 25 (default: <u>1</u>) | 1 | Response interval = setting value × 20 ms |
| Extensional communication module (PUMC) connection | <u>0: Without PUMC (RS-485 valid)</u> 1: With PUMC (RS-485 invalid) | 0 | When using RS-485 communication, set "0". |

* The following communication parameters are fixed; data length: 8 bits and stop bit: 1 bit.

Available Device Memory

The available setting range of device memory varies depending on the model. Be sure to set within the range available for the model to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|----------------------|------|---------|
| 4 (holding register) | 02H | |
| 3 (input register) | 03H | |

Note on Setting the Device Memory

In accordance with the connected PUM model, set the "List" file name to be browsed by pressing the [Refer] button.

| Model | | List File Name |
|-------|---------------------------|----------------|
| PUMAx | Control module (4 ch) | F_PUMA_B.Lst |
| PUMBx | Control module (2 ch) | |
| PUMEx | Event input/output module | F_PUME.Lst |

"F_PUMA_B.Lst" is set as default.

16.2.6 F-MPC04P (Loader)

Communication Setting

Editor

Communication setting

(Underlined setting: default)

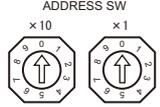
| Item | Setting | Remarks |
|-----------------|--|--|
| Connection Mode | 1 : 1 / <u>1:n</u> / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet) | |
| Signal Level | RS-422/485 | |
| Baud Rate | 4800 / 9600 / <u>19200</u> bps | |
| Data Length | <u>7</u> / 8 bits | |
| Stop Bit | 1 bit | Do not change the default setting because the setting on the power monitor unit cannot be changed. |
| Parity | None / <u>Odd</u> / Even | |
| Target Port No. | 1 to 99* ¹ | |

*1 To use port No. 32 to 99, use the station number table.

Power Monitor Unit

Be sure to match the settings to those made under [Communication Setting] of the editor.

Station number setting

| Station | Setting | Example | Remarks |
|---|-------------------------------------|---------|---------|
|  | 01 to 99 [DEC] (default: <u>0</u>) | 1 | |

Communication setting

The communication parameter can be set using keys attached to the front of the power monitor unit.

(Underlined setting: default)

| Circuit No. | Setting Code | Item | Setting | Example |
|-------------|--------------|-------------|--|---------|
| C | L1-□□ | Baud rate | 00: 4800 bps 01: 9600 bps <u>02: 19200 bps</u> | 02 |
| | L2-□□ | Parity | 00: None 01: Even <u>02: Odd</u> | 02 |
| | L3-□□ | Data length | <u>00: 7 bits</u> 01: 8 bits | 00 |

* The communication parameter (stop bit) is fixed to 1 bit.

Available Device Memory

The available setting range of device memory varies depending on the model. Be sure to set within the range available for the model to be used. Use [TYPE] when assigning indirect device memory for macro programs.

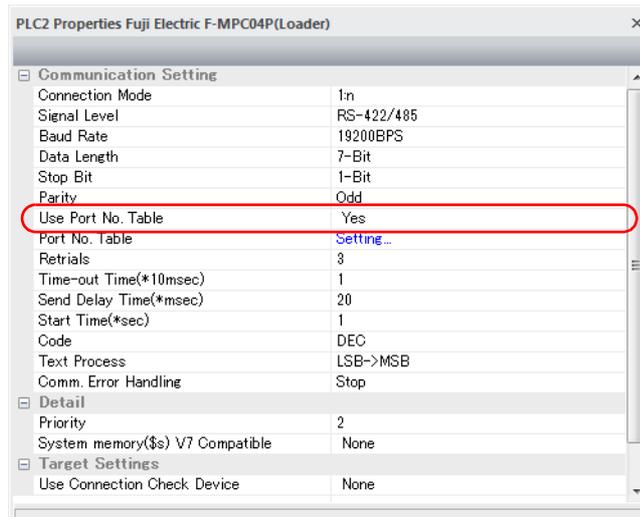
| Device Memory | TYPE | Remarks |
|---------------|------|-------------|
| --- | 00H | Double-word |

Station Number Table

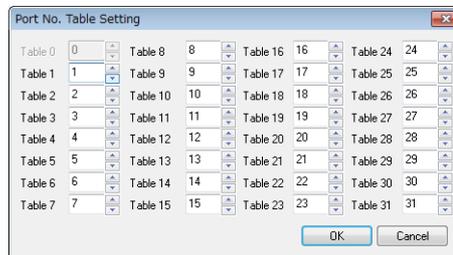
- A maximum of 31 units can be connected via serial communication. Port numbers from 0 to 31 can be set on the [Device Setting] dialog of the editor; however, depending on the controller, port numbers exceeding 32 may be available. In such a case, use the station number table to enable communications with devices of port No. 32 or greater.
- It is easier to specify port numbers for each network in the field by making the screen for setting the port number when creating the screen program. In this case, it is not necessary to transfer the screen program again.

Setting the Station Number Table

1. Select [Yes] for [Use Port No. Table] under [Communication Setting] on the [PLC Properties] window ([System Setting] → [Hardware Setting]).



2. Click "Setting..." next to [Port No. Table]. The [Port No. Table Setting] dialog is displayed.
3. Specify port numbers of the temperature controllers for "Table 0" to "31".



Macro

To rewrite the station number table on the V series screen, use macro commands [FROM_WR] and [RESTART].

FROM_WR

FROM_WR F0 F1

- Function: Writing to FROM
As many words as specified for F1 from the device memory address set for F0 is written in the FP-ROM.
- Available device memory

| | Internal Device Memory | PLC n Device Memory | Memory Card | Constant |
|----|------------------------|---------------------|-------------|----------|
| F0 | ⊙ | ⊙ | ⊙ | |
| F1 | | | | ○ |

○: Setting enabled (indirect designation disabled)
⊙: Setting enabled (indirect designation enabled)

- Data range

| | Setting | Remarks |
|----|---|---|
| F0 | Top device memory address of the source | 32 words from the top address of the specified device memory are used. Set port numbers from 0 to 31 for each address. For the station number table not used, set [-1]. |
| F1 | Number of transmission words: 32 | If any other value than "32" is set, the write error (\$s728 = 1) occurs. |

- Notes
 - The maximum possible number of write operations to the FP-ROM is 100,000 times. This is not related to the number of words that are written.
 - Do not include the FROM_WR command in a cycle macro or an event timer macro.
 - Writing to FP-ROM takes a longer time.
 - When the station number table has been rewritten using the [FROM_WR] command, be sure to execute the [RESTART] command.
 - When the station number table is used, it is not possible to set Use Internal Flash ROM as Back-up Area] on the [General Settings] tab window that is displayed by selecting [System Setting] → [Unit Setting] → [General Settings]. Be sure to leave this box unchecked.

RESTART

When the station number table has been rewritten using the [FROM_WR] command, be sure to execute this command.

SYS (RESTART) F0

- Function: Reconnection
This macro command reconnects the controller when the time specified for F1 has elapsed.
- Available device memory

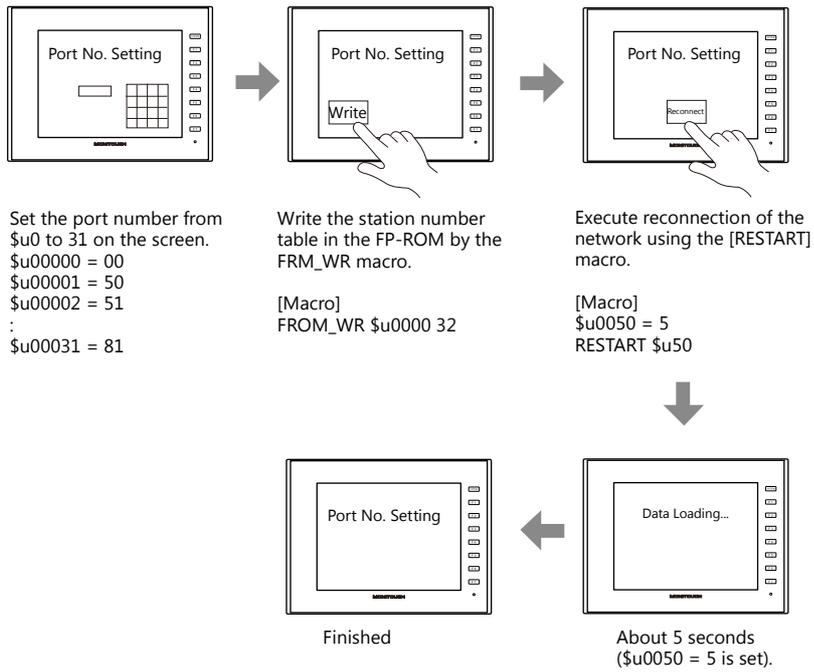
| | Internal Device Memory | PLC n Device Memory | Memory Card | Constant |
|----|------------------------|---------------------|-------------|----------|
| F1 | ⊙ | | | |

○: Setting enabled (indirect designation disabled)
⊙: Setting enabled (indirect designation enabled)

- Data range

| | Setting |
|----|-----------------|
| F0 | RESTART |
| F1 | Time: 0 to 60 s |

Example of Procedure for Rewriting the Station Number Table



System Device Memory

The result of [FROM_WR] macro execution is stored in \$s728.

[0]: Normal

[1]: Error

16.2.7 F-MPC Series / FePSU

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|--|--|
| Connection Mode | 1 : 1 / <u>1:n</u> / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet) | |
| Signal Level | RS-422/485 | |
| Baud Rate | 4800 / 9600 / <u>19200</u> bps | |
| Data Length | <u>7</u> / 8 bits | |
| Stop Bit | 1 bit | Do not change the default setting because the setting on the power monitor unit cannot be changed. |
| Parity | None / <u>Odd</u> / Even | |
| Target Port No. | 1 to 99*1 | |

*1 To use port numbers 32 to 99, use the station number table. For the station number table, see "Station Number Table" (page 16-32).

F-MPC04

Communication setting

The communication parameters can be set using keys attached to the front of the power monitor unit. Be sure to match the settings to those made under [Communication Setting] of the editor.

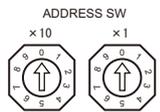
(Underlined setting: default)

| Circuit No. | Setting Code | Item | Setting | Example |
|-------------|--------------|--------------------------|--|---------|
| C | 4-0 | RS-485 address | <u>Loc: Communication not used</u> 01 to 99 | 01 |
| | 4-1 | RS-485 baud rate setting | 4.8: 4800 bps 9.6: 9600 bps <u>19.2: 19200 bps</u> | 19.2 |
| | 4-2 | RS-485 data length | <u>7: 7 bits</u> 8: 8 bits | 7 |
| | 4-3 | RS-485 parity | 00: None 01: Even <u>02: Odd</u> | 02 |

F-MPC04P

Be sure to match the settings to those made under [Communication Setting] of the editor.

Station number setting

| Station | Setting | Example | Remarks |
|---|-------------------------------------|---------|---------|
|  | 01 to 99 [DEC] (default: <u>0</u>) | 1 | |

Communication setting

The communication parameters can be set using keys attached to the front of the power monitor unit.

(Underlined setting: default)

| Circuit No. | Setting Code | Item | Setting | Example |
|-------------|--------------|-------------|--|---------|
| C | L1-□□ | Baud rate | 00: 4800 bps 01: 9600 bps <u>02: 19200 bps</u> | 02 |
| | L2-□□ | Parity | 00: None 01: Even <u>02: Odd</u> | 02 |
| | L3-□□ | Data length | <u>00: 7 bits</u> 01: 8 bits | 00 |

* The communication parameter (stop bit) is fixed to 1 bit.

F-MPC04S

Communication setting

The communication parameters can be set using keys attached to the front of the power monitor unit. Be sure to match the settings to those made under [Communication Setting] of the editor.

(Underlined setting: default)

| Setting Code | Item | Setting | Example |
|--------------|--|---|---------|
| L-□□ | Baud rate | 4.8: 4800 bps 9.6: 9600 bps <u>19.2: 19200 bps</u> | 19.2 |
| L2-□□ | Data length and parity | 8n: Data length 8 bits, without parity 8E: Data length 8 bits, even parity 8o: Data length 8 bits, odd parity 7n: Data length 7 bits, without parity 7E: Data length 7 bits, even parity <u>7o: Data length 7 bits, odd parity</u> | 7o |
| LA-□□ | Address (Transmission station number) | <u>Loc: Station number not set</u> 01 to 99 | 01 |
| Lt-□□ | Communication model mode | <u>04: F-MPC04 mode</u> *1 PP: PPM (B) mode | 04 |

*1 The communication function of F-MPC04 can be selected at the time of purchase. Select a model on which "F-MPC04 mode" is available.

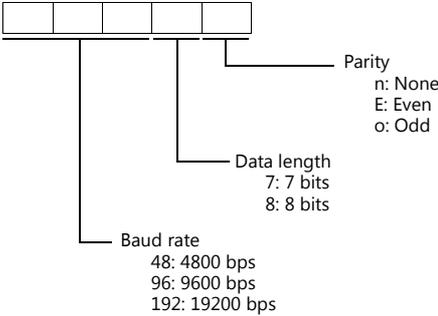
*2 The communication parameter (stop bit) is fixed to 1 bit.

F-MPC30

Communication setting

The communication parameters can be set using keys attached to the front of the power monitor unit. Be sure to match the settings to those made under [Communication Setting] of the editor.

(Underlined setting: default)

| Setting Code | Item | Setting | Example |
|--------------|-----------------------------------|---|---------|
| 90 | RS-485 address setting | <u>Loc: Communication not used</u> 01 to 99 | 01 |
| 91 | RS-485 transmission specification | 7SEG LED  <p>Parity n: None E: Even o: Odd</p> <p>Data length 7: 7 bits 8: 8 bits</p> <p>Baud rate 48: 4800 bps 96: 9600 bps 192: 19200 bps</p> <p>* "<u>b192E</u>" is set as default.</p> | 1927o |

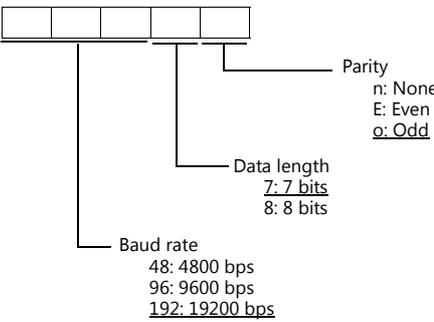
* The communication parameter (stop bit) is fixed to 1 bit.

F-MPC50/F-MPC55/F-MPC60B (UM4Bx, UM42xx, UM43xx)

Communication setting

The communication parameters can be set using keys attached to the front of the power monitor unit. Be sure to match the settings to those made under [Communication Setting] of the editor.

(Underlined setting: default)

| Setting Code | Item | Setting | Example |
|--------------|-----------------------------------|--|---------|
| 90 | RS-485 address setting | <u>Loc: communication not used</u> 01 to 99 | 01 |
| 91 | RS-485 transmission specification | 7SEG LED  | 1927o |

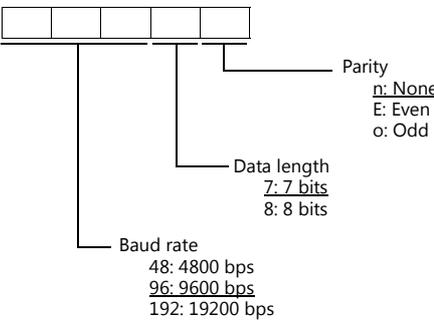
* The communication parameter (stop bit) is fixed to 1 bit.

F-MPC60B (UM44xx)

Communication setting

The communication parameters can be set using keys attached to the front of the power monitor unit. Be sure to match the settings to those made under [Communication Setting] of the editor.

(Underlined setting: default)

| Setting Code | Item | Setting | Example |
|--------------|-----------------------------------|--|---------|
| 90 | RS-485 address setting | <u>Loc: communication not used</u> 01 to 99 | 01 |
| 91 | RS-485 transmission specification | 7SEG LED  | 1927o |

* The communication parameter (stop bit) is fixed to 1 bit.

FePSU

Communication setting

The communication parameters can be set using keys attached to the front of the power monitor unit. Be sure to match the settings to those made under [Communication Setting] of the editor.

(Underlined setting: default)

| Type | Parameter Display | Item | Setting | Example |
|-------|-------------------|------------------------------|---|---------|
| SEL-c | Adr. □ □ | Communicating station number | <u>Loc: Communication not used</u> 01 to 99 | 01 |
| | bud □ □ | Baud rate | 4.8: 4800 bps 9.6: 9600 bps <u>19.2: 19200 bps</u> | 19.2 |
| | cbit. □ □ | Data length, parity | 8n: Data length 8 bits, without parity 8E: Data length 8 bits, even parity 8o: Data length 8 bits, odd parity 7n: Data length 7 bits, without parity 7E: Data length 7 bits, even parity <u>7o: Data length 7 bits, odd parity</u> | 7o |
| | LtY. □ □ | Communication Mode | <u>Psu: FePSU mode</u> *1 _PP: PPM(B) mode | Psu |

*1 The communication function of FePSU can be selected at the time of purchase. Select a model on which "FePSU mode" is available.

*2 The communication parameter (stop bit) is fixed to 1 bit.

F*JF-R

Communication setting

The communication parameters can be set using keys attached to the front of the digital regular electricity meter. Be sure to match the settings to those made under [Communication Setting] of the editor.

(Underlined setting: default)

| Type | Item | Setting | Example |
|-----------------------|-------------|--------------------------------------|-----------|
| Communication setting | Address | 01 - 99 | 01 |
| | Baud Rate | 4800bps / 9600bps / <u>19.2 kbps</u> | 19.2 kbps |
| | Data Length | <u>7</u> / 8 bits | 7 bits |
| | Parity Bit | None / Even / <u>Odd</u> | Odd |

* The communication parameter (stop bit) is fixed to 1 bit.

Available Device Memory

The available setting range of device memory varies depending on the model. Be sure to set within the range available for the model to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|--|------|------------------------|
| 00 (data request of circuit No. 1 to 4) *1 | 00H | Double-word, read only |
| 01 (data request of circuit No. 5 to 8) *1 | 01H | Double-word, read only |
| 02 (data request of circuit No. 9, 10 or E) *1 | 02H | Double-word, read only |
| 03 (Data request of the minimum/maximum voltage, power factor of circuit 1 to 10, and invalid power) *1 *2 | 03H | Double-word, read only |
| 09 (model code) | 09H | Read only |
| 10 (operation status) | 0AH | Read only |
| 11 (pre-alarm value) *1 | 0BH | Double-word, read only |
| 12 (current value measurement data) *1 *2 | 0CH | Double-word, read only |
| 13 (integrated value data) *1 *2 | 0DH | Double-word, read only |
| 14 (demand measurement data) *1 *2 | 0EH | Double-word, read only |
| 15 (data of a maximum value of demand measurement) *1 *2 | 0FH | Double-word, read only |
| 16 (historical data 1) *1 *2 | 10H | Double-word, read only |
| 17 (historical data 2) | 11H | Double-word, read only |
| 18 (setting data) *3 | 12H | Double-word |

*1 When a device memory other than status is used, set the decimal point of the numerical display part to "3".

*2 "0" is stored in the address for which "(Blank)" is indicated in the table below.

*3 For setting data, see "18 (Setting Data)" described below.

18 (Setting Data)

| Address | F-MPC04/F-MPC04P/F-MPC04S | FePSU | F-MPC30/F-MPC50/F-MPC55V/F-MPC60B |
|---------|--|---------------------|---------------------------------------|
| 00zz | Wiring method (voltage measured) | (Blank) | CT primary rated current |
| 01zz | Ratio of VT 1 (primary voltage) *1 | (Blank) | Ratio of VT (primary voltage) |
| 02zz | Ratio of VT 1 (secondary voltage) *1 | (Blank) | Ratio of VT (secondary voltage) |
| 03zz | Demand average time | Demand average time | Rated frequency |
| 04zz | Frequency | (Blank) | Protective INST (current setting) *2 |
| 05zz | Number of applicable circuits | (Blank) | Protective INST (output setting) |
| 06zz | Pulse multiplying factor | (Blank) | Protective DT (current setting) *2 |
| 07zz | Ratio of VT 2 (primary voltage) *1 | (Blank) | Protective DT (operation time) *2 |
| 08zz | Ratio of VT 2 (secondary voltage) *1 | (Blank) | Protective DT (output setting) *2 |
| 09zz | Number of turns for CT2 secondary line | (Blank) | Protective OC (current setting) |
| 10zz | CT primary current *1 | (Blank) | Protective OC (characteristic) |
| 11zz | OCG sensitivity current | (Blank) | Protective OC (time magnification) *2 |

| Address | F-MPC04/F-MPC04P/F-MPC04S | FePSU | F-MPC30/F-MPC50/F-MPC55V/F-MPC60B |
|---------|--|--|--|
| 12zz | OCG operation time * ² | (Blank) | Protective OC (output setting) |
| 13zz | Load pre-alarm sensitivity current | (Blank) | Protective OCA overcurrent pre-alarm (current setting) |
| 14zz | Load pre-alarm operation time | (Blank) | Protective OCA overcurrent pre-alarm (operation time) |
| 15zz | Automatic display circuit register | (Blank) | Protective OCA overcurrent pre-alarm (output setting) |
| 16zz | ZCT select | (Blank) | Protective OCG (51G) (current setting) * ³ |
| 17zz | VT select | (Blank) | Protective OCG (51G) (characteristic) |
| 18zz | (Blank) | (Blank) | Protective OCG (51G) (time magnification) * ² |
| 19zz | (Blank) | (Blank) | Protective OCG (51G) (output setting) |
| 20zz | Phase selection | (Blank) | Protective OCG (50G) (current setting) * ² |
| 21zz | Power alarm upper limit | Power alarm upper limit | Protective OCG (50G) (operation time) * ² |
| 22zz | Integral power pulse multiplying factor * ⁴ | Pulse multiplying factor * ⁴ | Protective OCG (50G) (output setting) |
| 23zz | Load pre-alarm operation value | Load pre-alarm operation value | Protective DG (DG/OCG) (current setting) * ³ |
| 24zz | Load pre-alarm operation time | (Blank) | Protective DG (DG/OCG) (operation time) * ³ |
| 25zz | Leak pre-alarm sensitivity current | Leak pre-alarm sensitivity current | Protect DG (DG/OCG) (output setting) |
| 26zz | Leak pre-alarm operation time * ² | Leak pre-alarm operation time * ² | Protective DG (DG/OCG) (maximum sensitivity phase angle) |
| 27zz | OCG sensitivity current | Leak alarm sensitivity current | Protective DG (DG/OCG) (voltage setting) * ² |
| 28zz | OCG operation time * ² | Leak alarm operation time * ² | Protective DG (DG/OCG) (selected from DG or OCG) |
| 29zz | Operation type for power | Operation type for power | Protective 0 V (voltage setting) |
| 30zz | (Blank) | Phase R input position | Protective 0 V (operation time) * ² |
| 31zz | (Blank) | History of turning breaker ON | Protective 0 V (output setting) |
| 32zz | (Blank) | Show/hide cause of trouble | Protective UV (voltage setting) |
| 33zz | (Blank) | Phase interruption alarm of neutral line | Protective UV (operation time) * ² |
| 34zz | (Blank) | Alarm output 1 | Protective UV (output setting) |
| 35zz | (Blank) | Alarm output 2 | Protective UV2 (voltage setting) |
| 36zz | (Blank) | Contact input 1 | Protective UV2 (operation time) * ² |
| 37zz | (Blank) | Contact input 2 | Protective UV2 (output setting) |
| 38zz | (Blank) | (Blank) | Protective UV operation setting |
| 39zz | (Blank) | Rated current (IN) | Voltage establishment VR (voltage setting) |
| 40zz | (Blank) | Current demand time | Voltage establishment VR (operation time) * ² |
| 41zz | (Blank) | Voltage demand time | Voltage establishment VR (output setting) |
| 42zz | (Blank) | Power demand time | Protective OVG (voltage setting) * ² |
| 43zz | (Blank) | Leak demand time | Protective OVG (operation time) |
| 44zz | (Blank) | (Blank) | Protective OVG (output setting) |
| 45zz | (Blank) | (Blank) | ZPD/EVT selection |
| 46zz | (Blank) | (Blank) | Phase interruption relay |

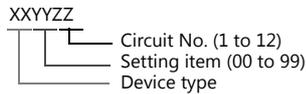
| Address | F-MPC04/F-MPC04P/F-MPC04S | FePSU | F-MPC30/F-MPC50/F-MPC55V/F-MPC60B |
|---------|---------------------------|----------------|--|
| 47zz | (Blank) | (Blank) | Reverse phase relay |
| 48zz | (Blank) | (Blank) | Demand average time |
| 49zz | (Blank) | Year setting | CB opening jam monitoring time ^{*3} |
| 50zz | (Blank) | Month setting | CB closing jam monitoring time ^{*3} |
| 51zz | (Blank) | Date setting | Monitoring trip coil TC disconnection, OFF expedited, function application setting |
| 52zz | (Blank) | Hour setting | kWh pulse constant ^{*5} |
| 53zz | (Blank) | Minute setting | kvarh pulse constant ^{*5} |
| 54zz | (Blank) | (Blank) | Selective input 1 function setting |
| 55zz | (Blank) | (Blank) | Selective input 2 function setting |
| 56zz | (Blank) | (Blank) | Selective input 3 function setting |
| 57zz | (Blank) | (Blank) | Selective input 4 function setting |
| 58zz | (Blank) | (Blank) | Selective input 5 function setting |
| 59zz | (Blank) | (Blank) | Selective input 6 function setting |
| 60zz | (Blank) | (Blank) | Selective input 7 function setting |
| 61zz | (Blank) | (Blank) | Selective input 8 function setting |
| 62zz | (Blank) | (Blank) | Device fault detection function setting |
| 63zz | (Blank) | (Blank) | Fault pick-up output setting |
| 64zz | (Blank) | (Blank) | Transmission component 1 output setting |
| 65zz | (Blank) | (Blank) | Transmission component 2 output setting |
| 66zz | (Blank) | (Blank) | Distant/direct state output setting |
| 67zz | (Blank) | (Blank) | Transducer output current phase setting |
| 68zz | (Blank) | (Blank) | Transducer output voltage phase setting |
| 69zz | (Blank) | (Blank) | Residue/CT 3rd selection (zero-phase current) |
| 70zz | (Blank) | (Blank) | Protective INST (phase N) (current setting) ^{*2} |
| 71zz | (Blank) | (Blank) | Protective INST (phase N) (output setting) |
| 72zz | (Blank) | (Blank) | Protective OC (phase N) (current setting) |
| 73zz | (Blank) | (Blank) | Protective OC (phase N) (characteristic) |
| 74zz | (Blank) | (Blank) | Protective OC (phase-N) (time magnification) ^{*2} |
| 75zz | (Blank) | (Blank) | Protective OC (phase N) (output setting) |
| 76zz | (Blank) | (Blank) | Protective OCA overcurrent pre-alarm (phase N) (current setting) |
| 77zz | (Blank) | (Blank) | Protective OCA overcurrent pre-alarm (phase N) (operation time) |
| 78zz | (Blank) | (Blank) | Protective OCA overcurrent pre-alarm (phase N) (output setting) |
| 79zz | (Blank) | (Blank) | Protective OCGA pre-alarm (current setting) |
| 80zz | (Blank) | (Blank) | Protective OCGA pre-alarm (operation time) |
| 81zz | (Blank) | (Blank) | Protective OCGA pre-alarm (output setting) |
| 82zz | (Blank) | (Blank) | Protective DT2 (current setting) |
| 83zz | (Blank) | (Blank) | Protective DT2 (operation time) ^{*2} |
| 84zz | (Blank) | (Blank) | Protective DT2 (output setting) |

| Address | F-MPC04/F-MPC04P/F-MPC04S | FePSU | F-MPC30/F-MPC50/F-MPC55V/F-MPC60B |
|---------|---------------------------|---------|--|
| 85zz | (Blank) | (Blank) | Transducer output CH1 setting |
| 86zz | (Blank) | (Blank) | Transducer output CH2 setting |
| 87zz | (Blank) | (Blank) | Transducer output CH3 setting |
| 88zz | (Blank) | (Blank) | Transducer output CH4 setting |
| 89zz | (Blank) | (Blank) | Transducer output CH5 setting |
| 90zz | (Blank) | (Blank) | Transducer output CH6 setting |
| 91zz | (Blank) | (Blank) | External change-over function setting of transducer output |
| 92zz | (Blank) | (Blank) | Display mode selection |

- *1 When using a direct value, set [DEC (with sign)] for [Display Format] on the [Num. Display] window.
- *2 Specify "1" for [Decimal Point] on the [Num. Display] window.
- *3 Specify "2" for [Decimal Point] on the [Num. Display] window.
- *4 Specify the multiplying factor in the range of -3 to 2.
- *5 Specify the pulse constant in the range of -2 to 4 or F.

Address denotations:

- For the device memory for which the circuit number is set (00 to 02, 12 to 18):



- * For circuit No. E, specify "11" for the circuit number.

- For the device memory for which the circuit number is not set (03, 09 to 11):



Note on Setting the Device Memory

Only the "List" file of "F-MPC04S" can be browsed by pressing the [Refer] button by default.

If any power monitor unit other than above is used, refer to each "List" file by pressing the [Refer] button and set the device memory.

PLC_CTL

| Content | F0 | F1 (= \$u n) | | F2 |
|--|---------------------|--------------|---|--|
| kWh integrated value reset ^{*1} | 1 - 8 (PLC1 - 8) | n | Station number | 2 |
| | | n + 1 | Command: 0 | |
| Max. kW (amount of power) reset | 1 - 8 (PLC1 - 8) | n | Station number | 2 |
| | | n + 1 | Command: 1 | |
| Operation control ^{*2} | 1 - 8 (PLC1 - 8) | n | Station number | 3 |
| | | n + 1 | Command: 2 | |
| | | n + 2 | 0: Turning ON the input/output 1: Turning ON the output of Power OFF 2: Turning OFF the output of power ON/OFF | |
| Reset all of the demand maximum values ^{*3} | 1 - 8 (PLC1 - 8) | n | Station number | 2 |
| | | n + 1 | Command: 3 | |
| Alarm reset ^{*3} | 1 - 8 (PLC1 - 8) | n | Station number | 2 |
| | | n + 1 | Command: 4 | |
| Time setting ^{*3} | 1 - 8 (PLC1 - 8) | n | Station number ^{*4} | 8 (9 when broadcast is specified) |
| | | n + 1 | Command: 5 | |
| | | n + 2 | 0: Specific station number 1: Broadcast | |
| | | n + 3 | Year | |
| | | n + 4 | Month | |
| | | n + 5 | Day | |
| | | n + 6 | Hour | |
| | | n + 7 | Minute | |
| Reset the maximum and minimum voltage values ^{*6} | 1 - 8 (PLC1 - 8) | n | Station number | 2 |
| | | n + 1 | Command: 6 | |
| Entering test mode ^{*6} | 1 - 8 (PLC1 - 8) | n | Station number ^{*4} | 3 |
| | | n + 1 | Command: 7 | |
| | | n + 2 | 0: Specific station number 1: Broadcast | |
| Exiting test mode ^{*6} | 1 - 8 (PLC1 - 8) | n | Station number ^{*4} | 3 |
| | | n + 1 | Command: 8 | |
| | | n + 2 | 0: Specific station number 1: Broadcast | |

*1 Not available with F*JF-R.

*2 Available only with F-MPC60B.

*3 Available only with FePSU.

*4 Select station No. 0 for broadcast commands.

*5 Can be set only for a broadcast command.

*6 Available only with F*JF-R.

16.2.8 FVR-E11S

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|--|---------|
| Connection Mode | 1 : 1 / <u>1:n</u> / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet) | |
| Signal Level | <u>RS-422/485</u> | |
| Baud Rate | 4800 / <u>9600</u> / 19200 bps | |
| Data Length | 7 / <u>8</u> bits | |
| Stop Bit | <u>1</u> / 2 bits | |
| Parity | <u>None</u> / Odd / Even | |
| Target Port No. | <u>1</u> to 31 | |

Inverter

Set communication parameters. Be sure to match the settings to those made under [Communication Setting] of the editor.

(Underlined setting: default)

| Function Code | Item | Setting | Example | | | | | | | | | | | | | | | | | | | | |
|---------------|---------------------------|---|---------|-----------|-------------------|-------------------|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|
| H30 | Link function *1 | <table border="1"> <thead> <tr> <th></th> <th>Monitor</th> <th>Frequency</th> <th>Operation Command</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>○</td> <td>X</td> <td>X</td> </tr> <tr> <td>1</td> <td>○</td> <td>○</td> <td>X</td> </tr> <tr> <td>2</td> <td>○</td> <td>X</td> <td>○</td> </tr> <tr> <td>3</td> <td>○</td> <td>○</td> <td>○</td> </tr> </tbody> </table> | | Monitor | Frequency | Operation Command | 0 | ○ | X | X | 1 | ○ | ○ | X | 2 | ○ | X | ○ | 3 | ○ | ○ | ○ | 3 |
| | | | Monitor | Frequency | Operation Command | | | | | | | | | | | | | | | | | | |
| | | 0 | ○ | X | X | | | | | | | | | | | | | | | | | | |
| | | 1 | ○ | ○ | X | | | | | | | | | | | | | | | | | | |
| | | 2 | ○ | X | ○ | | | | | | | | | | | | | | | | | | |
| 3 | ○ | ○ | ○ | | | | | | | | | | | | | | | | | | | | |
| H31 | Station address | <u>1</u> to 31 | 1 | | | | | | | | | | | | | | | | | | | | |
| H34 | Baud rate | 0: 19200 bps <u>1: 9600 bps</u> 2: 4800 bps | 1 | | | | | | | | | | | | | | | | | | | | |
| H35 | Data length | <u>0: 8 bits</u> 1: 7 bits | 0 | | | | | | | | | | | | | | | | | | | | |
| H36 | Parity bit | <u>0: None</u> 1: Even 2: Odd | 0 | | | | | | | | | | | | | | | | | | | | |
| H37 | Stop bit | <u>0: 1 bits</u> 1: 2 bits | 0 | | | | | | | | | | | | | | | | | | | | |
| - | Communication protocol *2 | "FGI-bus" is set as default. | - | | | | | | | | | | | | | | | | | | | | |

*1 Available when the communication is enabled by digital input.

Example: To make the communication enabled when digital input terminal X1 is turned ON;

Set "18 (link operation)" for function code E01 and turn on the digital input terminal X1 externally.

Terminals from X2 to X5 can also be used. Set the function code corresponding to the digital input terminal to use.

*2 When "FVR-E11S" is selected for model selection on the editor, use "FGI-bus" for the communication protocol on the inverter.

Available Device Memory

The available setting range of device memory varies depending on the model. Be sure to set within the range available for the model to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|-------------------------|------|-------------|
| S (command data) | 00H | |
| M (monitor data) | 01H | Double-word |
| F (basic function) | 02H | |
| E (terminal function) | 03H | |
| C (control function) | 04H | |
| P (motor 1) | 05H | |
| H (high level function) | 06H | |
| A (motor 2) | 07H | |
| o (optional function) | 08H | |

PLC_CTL

Macro command "PLC_CTL F0 F1 F2"

| Contents | F0 | F1 (= \$u n) | | F2 |
|---------------|---------------------|--------------|----------------|----|
| Reset command | 1 - 8 (PLC1 - 8) | n | Station number | 2 |
| | | n + 1 | Command: 0 | |

16.2.9 FVR-E11S (MODBUS RTU)

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|--|---------|
| Connection Mode | 1 : 1 / <u>1:n</u> / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet) | |
| Signal Level | RS-422/485 | |
| Baud Rate | 4800 / <u>9600</u> / 19200 bps | |
| Data Length | 8 bits | |
| Stop Bit | <u>1</u> / 2 bits | |
| Parity | <u>None</u> / Odd / Even | |
| Target Port No. | <u>1</u> to 31 | |

Inverter

Be sure to match the communication settings of the inverter to those made on the editor.

Available Device Memory

The available setting range of device memory varies depending on the model. Be sure to set within the range available for the model to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|---------------|------|---------|
| 4 | 02H | |

16.2.10 FVR-C11S (MODBUS RTU)

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|--|---------|
| Connection Mode | 1 : 1 / <u>1:n</u> / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet) | |
| Signal Level | RS-422/485 | |
| Baud Rate | 4800 / <u>9600</u> / 19200 bps | |
| Data Length | 8 bits | |
| Stop Bit | 1 / <u>2</u> bits | |
| Parity | <u>None</u> / Odd / Even | |
| Target Port No. | <u>1</u> to 31 | |

Inverter

Be sure to match the communication settings of the inverter to those made on the editor.

Available Device Memory

The available setting range of device memory varies depending on the model. Be sure to set within the range available for the model to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|---------------|------|---------|
| 4 | 02H | |

16.2.11 FRENIC5000 G11S / P11S

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|--|---------|
| Connection Mode | 1 : 1 / <u>1:n</u> / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet) | |
| Signal Level | RS-422/485 | |
| Baud Rate | 4800 / <u>9600</u> / 19200 bps | |
| Data Length | 7 / <u>8</u> bits | |
| Stop Bit | 1 / <u>2</u> bits | |
| Parity | <u>None</u> / Odd / Even | |
| Target Port No. | <u>1</u> to 31 | |

Inverter

Set communication parameters.

Be sure to match the settings to those made under [Communication Setting] of the editor.

(Underlined setting: default)

| Function Code | Item | Setting | Example | | | | | | | | | | | | | | | | | | | | |
|---------------|--------------------------|--|----------------------------------|----------------------------------|-------------------|-------------------|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|
| H30 | Link function *1 | <table border="1"> <thead> <tr> <th></th> <th>Writing of Monitor/function Data</th> <th>Frequency Setting</th> <th>Operation Command</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>○</td> <td>X</td> <td>X</td> </tr> <tr> <td>1</td> <td>○</td> <td>○</td> <td>X</td> </tr> <tr> <td>2</td> <td>○</td> <td>X</td> <td>○</td> </tr> <tr> <td>3</td> <td>○</td> <td>○</td> <td>○</td> </tr> </tbody> </table> | | Writing of Monitor/function Data | Frequency Setting | Operation Command | 0 | ○ | X | X | 1 | ○ | ○ | X | 2 | ○ | X | ○ | 3 | ○ | ○ | ○ | 3 |
| | | | Writing of Monitor/function Data | Frequency Setting | Operation Command | | | | | | | | | | | | | | | | | | |
| | | 0 | ○ | X | X | | | | | | | | | | | | | | | | | | |
| | | 1 | ○ | ○ | X | | | | | | | | | | | | | | | | | | |
| | | 2 | ○ | X | ○ | | | | | | | | | | | | | | | | | | |
| 3 | ○ | ○ | ○ | | | | | | | | | | | | | | | | | | | | |
| H31 | Station address | <u>1</u> to 31 | 1 | | | | | | | | | | | | | | | | | | | | |
| H34 | Baud rate | 0: 19200 bps <u>1: 9600 bps</u> 2: 4800 bps | 1 | | | | | | | | | | | | | | | | | | | | |
| H35 | Data length | <u>0: 8 bits</u> 1: 7 bits | 0 | | | | | | | | | | | | | | | | | | | | |
| H36 | Parity bit | <u>0: None</u> 1: Even 2: Odd | 0 | | | | | | | | | | | | | | | | | | | | |
| H37 | Stop bit | <u>0: 2 bits</u> 1: 1 bit | 0 | | | | | | | | | | | | | | | | | | | | |
| U49 | Communication protocol*2 | <u>0: FGI-bus</u> 1: Modbus RTU | 1 | | | | | | | | | | | | | | | | | | | | |

*1 Available when the communication is enabled by digital input.

Example: To make the communication enabled when digital input terminal X1 is turned ON;

Set "24 (link operation)" for function code E01 and turn on the digital input terminal X1 externally.

Terminals from X2 to X9 can also be used. Set the function code corresponding to the digital input terminal to use.

*2 When "FRENIC5000G11S/P11S" is selected for model selection on the editor, select "FGI-bus" for the communication protocol on the inverter.

Available Device Memory

The available setting range of device memory varies depending on the model. Be sure to set within the range available for the model to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|-------------------------|------|------------------------|
| S (command data) | 00H | |
| M (monitor data) | 01H | Double-word, read only |
| F (basic function) | 02H | |
| E (terminal function) | 03H | |
| C (control function) | 04H | |
| P (motor 1) | 05H | |
| H (high level function) | 06H | |
| A (motor 2) | 07H | |
| o (optional function) | 08H | |
| U (user function) | 0AH | |

Indirect Device Memory Designation

- When "S" (command data) or "M" (monitor data) is used:
For the device memory address number, specify the value obtained by subtracting "1" from the actual address.

PLC_CTL

Macro command "PLC_CTL F0 F1 F2"

| Contents | F0 | F1 (= \$u n) | | F2 |
|---------------|---------------------|--------------|----------------|----|
| Reset command | 1 - 8 (PLC1 - 8) | n | Station number | 2 |
| | | n + 1 | Command: 0 | |

16.2.12 FRENIC5000 G11S / P11S (MODBUS RTU)

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|--|---------|
| Connection Mode | 1 : 1 / <u>1:n</u> / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet) | |
| Signal Level | RS-422/485 | |
| Baud Rate | 4800 / <u>9600</u> / 19200 bps | |
| Data Length | <u>8</u> bits | |
| Stop Bit | 1 / <u>2</u> bits | |
| Parity | <u>None</u> / Odd / Even | |
| Target Port No. | <u>1</u> to 31 | |

Inverter

Set communication parameters.

Be sure to match the settings to those made under [Communication Setting] of the editor.

(Underlined setting: default)

| Function Code | Item | Setting | Example | | | | | | | | | | | | | | | | | | | | |
|---------------|--------------------------|---|----------------------------------|----------------------------------|-------------------|-------------------|----------|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|
| H30 | Link function *1 | <table border="1"> <thead> <tr> <th></th> <th>Writing of Monitor/function Data</th> <th>Frequency Setting</th> <th>Operation Command</th> </tr> </thead> <tbody> <tr> <td><u>0</u></td> <td>○</td> <td>X</td> <td>X</td> </tr> <tr> <td>1</td> <td>○</td> <td>○</td> <td>X</td> </tr> <tr> <td>2</td> <td>○</td> <td>X</td> <td>○</td> </tr> <tr> <td>3</td> <td>○</td> <td>○</td> <td>○</td> </tr> </tbody> </table> | | Writing of Monitor/function Data | Frequency Setting | Operation Command | <u>0</u> | ○ | X | X | 1 | ○ | ○ | X | 2 | ○ | X | ○ | 3 | ○ | ○ | ○ | 3 |
| | | | Writing of Monitor/function Data | Frequency Setting | Operation Command | | | | | | | | | | | | | | | | | | |
| | | <u>0</u> | ○ | X | X | | | | | | | | | | | | | | | | | | |
| | | 1 | ○ | ○ | X | | | | | | | | | | | | | | | | | | |
| | | 2 | ○ | X | ○ | | | | | | | | | | | | | | | | | | |
| 3 | ○ | ○ | ○ | | | | | | | | | | | | | | | | | | | | |
| H31 | Station address | <u>1</u> to 31 | 1 | | | | | | | | | | | | | | | | | | | | |
| H34 | Baud rate | 0: 19200 bps <u>1: 9600 bps</u> 2: 4800 bps | 1 | | | | | | | | | | | | | | | | | | | | |
| H35 | Data length | <u>0: 8 bits</u> 1: 7 bits | 0 | | | | | | | | | | | | | | | | | | | | |
| H36 | Parity bit | <u>0: None</u> 1: Even 2: Odd | 0 | | | | | | | | | | | | | | | | | | | | |
| H37 | Stop bit | <u>0: 2 bits</u> 1: 1 bit | 0 | | | | | | | | | | | | | | | | | | | | |
| U49 | Communication protocol*2 | <u>0: FGI-bus</u> 1: Modbus RTU | 1 | | | | | | | | | | | | | | | | | | | | |

*1 Available when the communication is enabled by digital input.

Example: To make the communication enabled when digital input terminal X1 is turned ON;

Set "24 (link operation)" for function code E01 and turn on the digital input terminal X1 externally.

Terminals from X2 to X9 can also be used. Set the function code corresponding to the digital input terminal to use.

*2 When "FRENIC5000G11S/P11S (MODBUS RTU)" is selected for model selection on the editor, select "Modbus RTU" for the communication protocol on the inverter.

Available Device Memory

The available setting range of device memory varies depending on the model. Be sure to set within the range available for the model to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|---------------|------|---------|
| 4 | 02H | |

16.2.13 FRENIC5000 VG7S (MODBUS RTU)

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|--|--|
| Connection Mode | 1 : 1 / <u>1:n</u> / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet) | |
| Signal Level | RS-422/485 | |
| Baud Rate | 4800 / 9600 / 19200 / <u>38400</u> bps | |
| Data Length | 8 bits | Do not change the default setting because the setting on the inverter cannot be changed. |
| Stop Bit | <u>1</u> / 2 bits ^{*1} | |
| Parity | None / Odd / <u>Even</u> | |
| Target Port No. | <u>1</u> to 31 | |

*1 When no parity setting is made, set "2 bits" for stop bit.
When a parity setting (even or odd) is made, set "1 bit" for stop bit.

When Connecting to the Built-in RS-485 Port on the Inverter:

Set communication parameters.

Be sure to match the settings to those made under [Communication Setting] of the editor.

(Underlined setting: default)

| Function Code | Item | Setting | Example | | | | | | | | | | | | | | | | | | | | |
|---------------|--------------------------------------|--|----------------------------------|----------------------------------|-------------------|-------------------|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|
| H30 | Link function ^{*1} | <table border="1"> <thead> <tr> <th></th> <th>Writing of Monitor/function Data</th> <th>Frequency Setting</th> <th>Operation Command</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>○</td> <td>X</td> <td>X</td> </tr> <tr> <td>1</td> <td>○</td> <td>○</td> <td>X</td> </tr> <tr> <td>2</td> <td>○</td> <td>X</td> <td>○</td> </tr> <tr> <td>3</td> <td>○</td> <td>○</td> <td>○</td> </tr> </tbody> </table> | | Writing of Monitor/function Data | Frequency Setting | Operation Command | 0 | ○ | X | X | 1 | ○ | ○ | X | 2 | ○ | X | ○ | 3 | ○ | ○ | ○ | 3 |
| | | | Writing of Monitor/function Data | Frequency Setting | Operation Command | | | | | | | | | | | | | | | | | | |
| | | 0 | ○ | X | X | | | | | | | | | | | | | | | | | | |
| | | 1 | ○ | ○ | X | | | | | | | | | | | | | | | | | | |
| | | 2 | ○ | X | ○ | | | | | | | | | | | | | | | | | | |
| 3 | ○ | ○ | ○ | | | | | | | | | | | | | | | | | | | | |
| H31 | Station address | <u>1</u> to 31 | 1 | | | | | | | | | | | | | | | | | | | | |
| H34 | Baud rate | <u>0: 38400 bps</u> 1: 19200 bps 2: 9600 bps 3: 4800 bps | 0 | | | | | | | | | | | | | | | | | | | | |
| H36 | Parity bit | 0: None <u>1: Even</u> 2: Odd | 1 | | | | | | | | | | | | | | | | | | | | |
| H37 | Stop bit | For Modbus RTU communication, the stop bit setting is automatically made according to the parity bit setting. When no parity setting is made, "2 bits" is set for stop bit. When a parity setting (even or odd) is made, "1 bit" is set for stop bit. | 1 | | | | | | | | | | | | | | | | | | | | |
| H40 | Communication protocol ^{*2} | 0: FGI-bus <u>1: SX (loader) protocol</u> 2: Modbus RTU | 2 | | | | | | | | | | | | | | | | | | | | |

* The communication parameter (data length) is fixed to 8 bits.

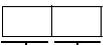
When Connecting to the Terminal Block on “OPC-VG7-RS” (Optional Communication Board):

Communication setting

Set communication parameters.

Be sure to match the settings to those made under [Communication Setting] of the editor.

(Underlined setting: default)

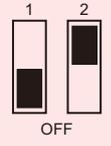
| Function Code | Item | Setting | Example | | | | | | | | | | | | | | | | | | | | |
|---------------|----------------------------------|---|-------------------|----------------------------------|-------------------|-------------------|----------|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|
| H30 | Link function *1 | <table border="1"> <thead> <tr> <th></th> <th>Writing of Monitor/function Data</th> <th>Frequency Setting</th> <th>Operation Command</th> </tr> </thead> <tbody> <tr> <td><u>0</u></td> <td>○</td> <td>X</td> <td>X</td> </tr> <tr> <td>1</td> <td>○</td> <td>○</td> <td>X</td> </tr> <tr> <td>2</td> <td>○</td> <td>X</td> <td>○</td> </tr> <tr> <td>3</td> <td>○</td> <td>○</td> <td>○</td> </tr> </tbody> </table> | | Writing of Monitor/function Data | Frequency Setting | Operation Command | <u>0</u> | ○ | X | X | 1 | ○ | ○ | X | 2 | ○ | X | ○ | 3 | ○ | ○ | ○ | 3 |
| | Writing of Monitor/function Data | Frequency Setting | Operation Command | | | | | | | | | | | | | | | | | | | | |
| <u>0</u> | ○ | X | X | | | | | | | | | | | | | | | | | | | | |
| 1 | ○ | ○ | X | | | | | | | | | | | | | | | | | | | | |
| 2 | ○ | X | ○ | | | | | | | | | | | | | | | | | | | | |
| 3 | ○ | ○ | ○ | | | | | | | | | | | | | | | | | | | | |
| H31 | Station address | <u>1</u> to 31 | 1 | | | | | | | | | | | | | | | | | | | | |
| o37 | Communication definition setting |  <p>Baud rate <u>0: 38400 bps</u> 1: 19200 bps 2: 9600 bps 3: 4800 bps</p> <p>Parity 0: None (stop bit: 2 bits) <u>1: Even (stop bit: 1 bit)</u> 2: Even (stop bit: 1 bit)</p> | 10 | | | | | | | | | | | | | | | | | | | | |
| H40 | Communication protocol*2 | 0: FGI-bus <u>1: SX (loader) protocol</u> 2: Modbus RTU | 2 | | | | | | | | | | | | | | | | | | | | |

- *1 Available when the communication is enabled by digital input.
 Example: To make the communication enabled when digital input terminal X1 is turned ON;
 Set "24 (link operation)" for function code E01 and turn on the digital input terminal X1 externally.
 Terminals from X2 to X9 can also be used. Set the function code corresponding to the digital input terminal to use.
- *2 When "FRENIC5000G11S/P11S (MODBUS RTU)" is selected for model selection on the editor, select "Modbus RTU" for the communication protocol on the inverter.
- *3 The communication parameter (data length) is fixed to 8 bits.

Notes on Using “OPC-VG7-RS” (Optional Communication Board)

Set the DIPSW2 on the optional communication board “OPC-VG7-RS” as shown below when connecting the V9 and the terminal block of the board.

The underlined settings are set as default.

| SW2 | SW2-1 Setting | SW2-2 Setting | Function | Remarks |
|---|---------------|---------------|--------------------------------------|--|
|  | OFF | OFF | - | - |
| | ON | OFF | - | - |
| | <u>OFF</u> | <u>ON</u> | Optional communication board enabled | Do not change the default setting when connecting with the V9. |
| | ON | ON | - | - |

Available Device Memory

The available setting range of device memory varies depending on the model. Be sure to set within the range available for the model to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|---------------|------|---------|
| 4 | 02H | |

16.2.14 FRENIC-Mini (MODBUS RTU)

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|--|--|
| Connection Mode | 1 : 1 / <u>1:n</u> / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet) | |
| Signal Level | <u>RS-422/485</u> | |
| Baud Rate | 4800 / 9600 / <u>19200</u> bps | |
| Data Length | 8 bits | Do not change the default setting because the setting on the inverter cannot be changed. |
| Stop bit | 1 / <u>2 bits</u> ^{*1} | |
| Parity | <u>None</u> / Odd / Even | |
| Target Port No. | <u>1</u> to 31 | |

*1 When no parity setting is made, "2 bits" is set for stop bit.
When a parity setting (even or odd) is made, "1 bit" is set for stop bit.

Inverter

Set communication parameters.

Be sure to match the settings to those made under [Communication Setting] of the editor.

(Underlined setting: default)

| Function Code | Item | Setting | Example | | | | | | | | | | | | | | | |
|---------------|--------------------------------------|---|---------|-----------|-------------------|----------|-------------------|-------------------|---|-----------------------|-------------------|---|-------------------|-----------------------|---|-----------------------|-----------------------|---|
| y01 | Station address | <u>1</u> to 31 | 1 | | | | | | | | | | | | | | | |
| y04 | Baud rate | 1: 4800 bps 2: 9600 bps 3: <u>19200 bps</u> | 3 | | | | | | | | | | | | | | | |
| y06 | Parity bit | <u>0: None</u> 1: Even 2: Odd | 0 | | | | | | | | | | | | | | | |
| y07 | Stop bit | For Modbus RTU communication, the stop bit setting is automatically made according to the parity bit setting. When no parity setting is made, "2 bits" is set for stop bit. When a parity setting (even or odd) is made, "1 bit" is set for stop bit. | - | | | | | | | | | | | | | | | |
| y10 | Communication protocol ^{*1} | 0: Modbus RTU 1: <u>SX (loader) protocol</u> 2: FGI-bus | 0 | | | | | | | | | | | | | | | |
| y99 | Support link function | <table border="1"> <thead> <tr> <th></th> <th>Frequency</th> <th>Operation Command</th> </tr> </thead> <tbody> <tr> <td><u>0</u></td> <td>Function code H30</td> <td>Function code H30</td> </tr> <tr> <td>1</td> <td>Commanded from RS-485</td> <td>Function code H30</td> </tr> <tr> <td>2</td> <td>Function code H30</td> <td>Commanded from RS-485</td> </tr> <tr> <td>3</td> <td>Commanded from RS-485</td> <td>Commanded from RS-485</td> </tr> </tbody> </table> | | Frequency | Operation Command | <u>0</u> | Function code H30 | Function code H30 | 1 | Commanded from RS-485 | Function code H30 | 2 | Function code H30 | Commanded from RS-485 | 3 | Commanded from RS-485 | Commanded from RS-485 | 0 |
| | Frequency | Operation Command | | | | | | | | | | | | | | | | |
| <u>0</u> | Function code H30 | Function code H30 | | | | | | | | | | | | | | | | |
| 1 | Commanded from RS-485 | Function code H30 | | | | | | | | | | | | | | | | |
| 2 | Function code H30 | Commanded from RS-485 | | | | | | | | | | | | | | | | |
| 3 | Commanded from RS-485 | Commanded from RS-485 | | | | | | | | | | | | | | | | |
| H30 | Link function ^{*2} | <table border="1"> <thead> <tr> <th></th> <th>Frequency</th> <th>Operation Command</th> </tr> </thead> <tbody> <tr> <td><u>0</u></td> <td>Inverter</td> <td>Inverter</td> </tr> <tr> <td>1</td> <td>RS-485 communication</td> <td>Inverter</td> </tr> <tr> <td>2</td> <td>Inverter</td> <td>RS-485 communication</td> </tr> <tr> <td>3</td> <td>RS-485 communication</td> <td>RS-485 communication</td> </tr> </tbody> </table> | | Frequency | Operation Command | <u>0</u> | Inverter | Inverter | 1 | RS-485 communication | Inverter | 2 | Inverter | RS-485 communication | 3 | RS-485 communication | RS-485 communication | 3 |
| | Frequency | Operation Command | | | | | | | | | | | | | | | | |
| <u>0</u> | Inverter | Inverter | | | | | | | | | | | | | | | | |
| 1 | RS-485 communication | Inverter | | | | | | | | | | | | | | | | |
| 2 | Inverter | RS-485 communication | | | | | | | | | | | | | | | | |
| 3 | RS-485 communication | RS-485 communication | | | | | | | | | | | | | | | | |

*1 Select "Modbus RTU" for the communication protocol on the inverter when connecting with the V9.

*2 When "0" is specified for y99 (support link function), command from function code H30 is valid for the frequency setting and operation command.

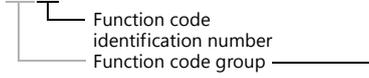
*3 The communication parameter (data length) is fixed to 8 bits.

Available Device Memory

The available setting range of device memory varies depending on the model. Be sure to set within the range available for the model to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|---------------|------|---------|
| --- | 02H | |

Address denotations XYY



| Group | Code | Name |
|-------|------|-----------------------|
| F | 00H | Basic function |
| E | 01H | Terminal function |
| C | 02H | Control function |
| P | 03H | Motor parameter |
| H | 04H | High level function |
| S | 07H | Command/function data |
| M | 08H | Monitor data |
| J | 0DH | Application function |
| y | 0EH | Link function |
| W | 0FH | Monitor 2 |
| X | 10H | Alarm 1 |
| Z | 11H | Alarm 2 |

16.2.15 FRENIC-Eco (MODBUS RTU)

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|---|--|
| Connection Mode | 1 : 1 / <u>1 : n</u> / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet) | |
| Signal Level | RS-422/485 | |
| Baud Rate | 4800 / 9600 / <u>19200</u> / 38400 bps | |
| Data Length | 8 bits | Do not change the default setting because the setting on the inverter cannot be changed. |
| Stop Bit | 1 / <u>2</u> bits | When no parity setting is made, "2 bits" is set for stop bit. When a parity setting is made, "1 bit" is set for stop bit. |
| Parity | <u>None</u> / Odd / Even | |
| Target Port No. | <u>1</u> to 31 | |

Inverter

Set communication parameters.

Be sure to match the settings to those made under [Communication Setting] of the editor.

(Underlined setting: default)

| Function Code | Item | Setting | Example | | | | | | | | | | | | | | | |
|---------------|--------------------------------------|---|---------|-----------|-------------------|----------|------------------------|------------------------|---|-----------------------------|------------------------|---|------------------------|-----------------------------|---|-----------------------------|-----------------------------|---|
| y01 | Station address | <u>1</u> to 31 | 1 | | | | | | | | | | | | | | | |
| y04 | Baud rate | 1: 4800 bps 2: 9600 bps 3: <u>19200 bps</u> 4: 38400 bps | 3 | | | | | | | | | | | | | | | |
| y06 | Parity bit | <u>0: None</u> 1: Even 2: Odd | 0 | | | | | | | | | | | | | | | |
| y07 | Stop bit | For Modbus RTU communication, the stop bit setting is automatically made according to the parity bit setting. When no parity setting is made, "2 bits" is set for stop bit. When a parity setting (even or odd) is made, "1 bit" is set for stop bit. | - | | | | | | | | | | | | | | | |
| y10 | Communication protocol* ¹ | 0: Modbus RTU <u>1: SX (loader) protocol</u> 2: FGI-bus | 0 | | | | | | | | | | | | | | | |
| y11 | Station address | <u>1</u> to 31 | 1 | | | | | | | | | | | | | | | |
| y14 | Baud rate | 1: 4800 bps 2: 9600 bps 3: <u>19200 bps</u> 4: 38400 bps | 3 | | | | | | | | | | | | | | | |
| y16 | Parity bit | <u>0: None</u> 1: Even 2: Odd | 0 | | | | | | | | | | | | | | | |
| y17 | Stop bit | For Modbus RTU communication, the stop bit setting is automatically made according to the parity bit setting. When no parity setting is made, "2 bits" is set for stop bit. When a parity setting (even or odd) is made, "1 bit" is set for stop bit. | - | | | | | | | | | | | | | | | |
| y20 | Communication protocol* ¹ | 0: Modbus RTU 2: FGI-bus | 0 | | | | | | | | | | | | | | | |
| y98 | Bus function | <table border="1"> <thead> <tr> <th></th> <th>Frequency</th> <th>Operation Command</th> </tr> </thead> <tbody> <tr> <td><u>0</u></td> <td>Function code H30</td> <td>Function code H30</td> </tr> <tr> <td>1</td> <td>Commanded from the fieldbus</td> <td>Function code H30</td> </tr> <tr> <td>2</td> <td>Function code H30</td> <td>Commanded from the fieldbus</td> </tr> <tr> <td>3</td> <td>Commanded from the fieldbus</td> <td>Commanded from the fieldbus</td> </tr> </tbody> </table> | | Frequency | Operation Command | <u>0</u> | Function code H30 | Function code H30 | 1 | Commanded from the fieldbus | Function code H30 | 2 | Function code H30 | Commanded from the fieldbus | 3 | Commanded from the fieldbus | Commanded from the fieldbus | 0 |
| | Frequency | Operation Command | | | | | | | | | | | | | | | | |
| <u>0</u> | Function code H30 | Function code H30 | | | | | | | | | | | | | | | | |
| 1 | Commanded from the fieldbus | Function code H30 | | | | | | | | | | | | | | | | |
| 2 | Function code H30 | Commanded from the fieldbus | | | | | | | | | | | | | | | | |
| 3 | Commanded from the fieldbus | Commanded from the fieldbus | | | | | | | | | | | | | | | | |
| y99 | Support link function | <table border="1"> <thead> <tr> <th></th> <th>Frequency</th> <th>Operation Command</th> </tr> </thead> <tbody> <tr> <td><u>0</u></td> <td>Function code H30, y98</td> <td>Function code H30, y98</td> </tr> <tr> <td>1</td> <td>Commanded from RS-485</td> <td>Function code H30, y98</td> </tr> <tr> <td>2</td> <td>Function code H30, y98</td> <td>Commanded from RS-485</td> </tr> <tr> <td>3</td> <td>Commanded from RS-485</td> <td>Commanded from RS-485</td> </tr> </tbody> </table> | | Frequency | Operation Command | <u>0</u> | Function code H30, y98 | Function code H30, y98 | 1 | Commanded from RS-485 | Function code H30, y98 | 2 | Function code H30, y98 | Commanded from RS-485 | 3 | Commanded from RS-485 | Commanded from RS-485 | 0 |
| | Frequency | Operation Command | | | | | | | | | | | | | | | | |
| <u>0</u> | Function code H30, y98 | Function code H30, y98 | | | | | | | | | | | | | | | | |
| 1 | Commanded from RS-485 | Function code H30, y98 | | | | | | | | | | | | | | | | |
| 2 | Function code H30, y98 | Commanded from RS-485 | | | | | | | | | | | | | | | | |
| 3 | Commanded from RS-485 | Commanded from RS-485 | | | | | | | | | | | | | | | | |

| Function Code | Item | Setting | | Example | |
|---------------|---------------------------------|---------------------------------|---------------------------------|---------|---------------------------------|
| H30 | Link function ^{*2} | | | 3 | |
| | | | | | |
| | | 0 | Inverter | | Inverter |
| | | 1 | RS-485 communication | | Inverter |
| | | 2 | Inverter | | RS-485 communication |
| | | 3 | RS-485 communication | | RS-485 communication |
| | | 4 | RS-485 communication (optional) | | Inverter |
| | | 5 | RS-485 communication (optional) | | RS-485 communication |
| | | 6 | Inverter | | RS-485 communication (optional) |
| 7 | RS-485 communication | RS-485 communication (optional) | | | |
| 8 | RS-485 communication (optional) | RS-485 communication (optional) | | | |

*1 Select "Modbus RTU" for the communication protocol on the inverter when connecting with the V9.

*2 When "0" is specified for y98 (bus function) as well as y99 (support link function), the frequency and operation command can be set on the V9.
When making the frequency and operation command settings on the V9 connected to the connector for the touch panel, specify "3" for function code H30. When making those settings on the V9 connected to the optional communication board, specify "8" for function code H30.

*3 The communication parameter (data length) is fixed to 8 bits.

Available Device Memory

The available setting range of device memory varies depending on the model. Be sure to set within the range available for the model to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|---------------|------|---------|
| 4 | 02H | |

16.2.16 FRENIC-Multi (MODBUS RTU)

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|---|---|
| Connection Mode | 1 : 1 / <u>1 : n</u> / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet) | |
| Signal Level | RS-422/485 | |
| Baud Rate | 4800 / 9600 / <u>19200</u> / 38400 bps | |
| Data Length | 8 bits | Do not change the default setting because the setting on the inverter cannot be changed. |
| Stop Bit | 1 / <u>2</u> bits | On the inverter: 2 bits when "0" is specified for y06 or y16 1 bit when "1", "2" or "3" is specified for y06 or y16 |
| Parity | <u>None</u> / Odd / Even | |
| Target Port No. | <u>1</u> to 31 | |

Inverter

Set communication parameters.

Be sure to match the settings to those made under [Communication Setting] of the editor.

(Underlined setting: default)

| Function Code | Item | Setting | Example | | | | | | | | | | | | | | | |
|---------------|-----------------------------|---|---------|-----------|-------------------|----------|-------------------|-------------------|---|-----------------------------|-------------------|---|-------------------|-----------------------------|---|-----------------------------|-----------------------------|---|
| y01 | Station address | <u>1</u> to 31 | 1 | | | | | | | | | | | | | | | |
| y04 | Baud rate | 1: 4800 bps 2: 9600 bps <u>3: 19200 bps</u> 4: 38400 bps | 3 | | | | | | | | | | | | | | | |
| y06 | Parity bit | <u>0: None</u> 1: Even 2: Odd 3: None | 0 | | | | | | | | | | | | | | | |
| y07 | Stop bit | For Modbus RTU communication, the stop bit setting is automatically made according to the parity bit setting. When "0" is specified for y06, "2 bits" is set for stop bit. When "1", "2", or "3" is specified for y06, "1 bit" is set for stop bit. | - | | | | | | | | | | | | | | | |
| y10 | Communication protocol*1 | 0: Modbus RTU <u>1: SX (loader) protocol</u> 2: FGI-bus | 0 | | | | | | | | | | | | | | | |
| y11 | Station address | <u>1</u> to 31 | 1 | | | | | | | | | | | | | | | |
| y14 | Baud rate | 1: 4800 bps 2: 9600 bps <u>3: 19200 bps</u> 4: 38400 bps | 3 | | | | | | | | | | | | | | | |
| y16 | Parity bit | <u>0: None</u> 1: Even 2: Odd 3: None | 0 | | | | | | | | | | | | | | | |
| y17 | Stop bit | For Modbus RTU communication, the stop bit setting is automatically made according to the parity bit setting. When "0" is specified for y16, "2 bits" is set for stop bit. When "1", "2", or "3" is specified for y16, "1 bit" is set for stop bit. | - | | | | | | | | | | | | | | | |
| y20 | Communication protocol*1 | 0: Modbus RTU 2: FGI-bus | 0 | | | | | | | | | | | | | | | |
| y98 | Bus function | <table border="1"> <thead> <tr> <th></th> <th>Frequency</th> <th>Operation Command</th> </tr> </thead> <tbody> <tr> <td><u>0</u></td> <td>Function code H30</td> <td>Function code H30</td> </tr> <tr> <td>1</td> <td>Commanded from the fieldbus</td> <td>Function code H30</td> </tr> <tr> <td>2</td> <td>Function code H30</td> <td>Commanded from the fieldbus</td> </tr> <tr> <td>3</td> <td>Commanded from the fieldbus</td> <td>Commanded from the fieldbus</td> </tr> </tbody> </table> | | Frequency | Operation Command | <u>0</u> | Function code H30 | Function code H30 | 1 | Commanded from the fieldbus | Function code H30 | 2 | Function code H30 | Commanded from the fieldbus | 3 | Commanded from the fieldbus | Commanded from the fieldbus | 0 |
| | Frequency | Operation Command | | | | | | | | | | | | | | | | |
| <u>0</u> | Function code H30 | Function code H30 | | | | | | | | | | | | | | | | |
| 1 | Commanded from the fieldbus | Function code H30 | | | | | | | | | | | | | | | | |
| 2 | Function code H30 | Commanded from the fieldbus | | | | | | | | | | | | | | | | |
| 3 | Commanded from the fieldbus | Commanded from the fieldbus | | | | | | | | | | | | | | | | |

| Function Code | Item | Setting | | Example | |
|---------------|---------------------------------|---------------------------------|---------------------------------|---------------------------------|---|
| y99 | Support link function | | Frequency | Operation Command | 0 |
| | | 0 | Function code H30, y98 | Function code H30, y98 | |
| | | 1 | Commanded from RS-485 | Function code H30, y98 | |
| | | 2 | Function code H30, y98 | Commanded from RS-485 | |
| | | 3 | Commanded from RS-485 | Commanded from RS-485 | |
| H30 | Link function *2 | | Frequency | Operation Command | 3 |
| | | 0 | Inverter | Inverter | |
| | | 1 | RS-485 communication | Inverter | |
| | | 2 | Inverter | RS-485 communication | |
| | | 3 | RS-485 communication | RS-485 communication | |
| | | 4 | RS-485 communication (optional) | Inverter | |
| | | 5 | RS-485 communication (optional) | RS-485 communication | |
| | | 6 | Inverter | RS-485 communication (optional) | |
| | | 7 | RS-485 communication | RS-485 communication (optional) | |
| 8 | RS-485 communication (optional) | RS-485 communication (optional) | | | |

*1 Select "Modbus RTU" for the communication protocol on the inverter when connecting with the V9.

*2 When "0" is specified for y98 (bus function) as well as y99 (support link function), the frequency and operation command can be set on the V9.
When making the frequency and operation command settings on the V9 connected to the connector for the touch panel, specify "3" for function code H30. When making those settings on the V9 connected to the optional communication board, specify "8" for function code H30.

*3 The communication parameter (data length) is fixed to 8 bits.

Available Device Memory

The available setting range of device memory varies depending on the model. Be sure to set within the range available for the model to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|---------------|------|---------|
| 4 | 02H | |

16.2.17 FRENIC-MEGA (MODBUS RTU)

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|---|---|
| Connection Mode | 1 : 1 / <u>1 : n</u> / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet) | |
| Signal Level | RS-422/485 | |
| Baud Rate | 4800 / 9600 / <u>19200</u> / 38400 bps | |
| Data Length | 8 bits | Do not change the default setting because the setting on the inverter cannot be changed. |
| Stop Bit | 1 / <u>2</u> bits | On the inverter: 2 bits when "0" is specified for y06 or y16 1 bit when "1", "2" or "3" is specified for y06 or y16 |
| Parity | <u>None</u> / Odd / Even | |
| Target Port No. | <u>1</u> to 31 | |

Inverter

Set communication parameters.

Be sure to match the settings to those made under [Communication Setting] of the editor.

(Underlined setting: default)

| Function Code | Item | Setting | Example | | | | | | | | | | | | | | | |
|---------------|-----------------------------|---|---------|-----------|-------------------|----------|-------------------|-------------------|---|-----------------------------|-------------------|---|-------------------|-----------------------------|---|-----------------------------|-----------------------------|---|
| y01 | Station address | <u>1</u> to 31 | 1 | | | | | | | | | | | | | | | |
| y04 | Baud rate | 1: 4800 bps 2: 9600 bps <u>3: 19200 bps</u> 4: 38400 bps | 3 | | | | | | | | | | | | | | | |
| y06 | Parity bit | <u>0: None</u> 1: Even 2: Odd 3: None | 0 | | | | | | | | | | | | | | | |
| y07 | Stop bit | For Modbus RTU communication, the stop bit setting is automatically made according to the parity bit setting. When "0" is specified for y06, "2 bits" is set for stop bit. When "1", "2", or "3" is specified for y06, "1 bit" is set for stop bit. | - | | | | | | | | | | | | | | | |
| y10 | Communication protocol*1 | 0: Modbus RTU <u>1: SX (loader) protocol</u> 2: FGI-bus | 0 | | | | | | | | | | | | | | | |
| y11 | Station address | <u>1</u> to 31 | 1 | | | | | | | | | | | | | | | |
| y14 | Baud rate | 1: 4800 bps 2: 9600 bps <u>3: 19200 bps</u> 4: 38400 bps | 3 | | | | | | | | | | | | | | | |
| y16 | Parity bit | <u>0: None</u> 1: Even 2: Odd 3: None | 0 | | | | | | | | | | | | | | | |
| y17 | Stop bit | For Modbus RTU communication, the stop bit setting is automatically made according to the parity bit setting. When "0" is specified for y16, "2 bits" is set for stop bit. When "1", "2", or "3" is specified for y16, "1 bit" is set for stop bit. | - | | | | | | | | | | | | | | | |
| y20 | Communication protocol*1 | 0: Modbus RTU 2: FGI-bus | 0 | | | | | | | | | | | | | | | |
| y98 | Bus function | <table border="1"> <thead> <tr> <th></th> <th>Frequency</th> <th>Operation Command</th> </tr> </thead> <tbody> <tr> <td><u>0</u></td> <td>Function code H30</td> <td>Function code H30</td> </tr> <tr> <td>1</td> <td>Commanded from the fieldbus</td> <td>Function code H30</td> </tr> <tr> <td>2</td> <td>Function code H30</td> <td>Commanded from the fieldbus</td> </tr> <tr> <td>3</td> <td>Commanded from the fieldbus</td> <td>Commanded from the fieldbus</td> </tr> </tbody> </table> | | Frequency | Operation Command | <u>0</u> | Function code H30 | Function code H30 | 1 | Commanded from the fieldbus | Function code H30 | 2 | Function code H30 | Commanded from the fieldbus | 3 | Commanded from the fieldbus | Commanded from the fieldbus | 0 |
| | Frequency | Operation Command | | | | | | | | | | | | | | | | |
| <u>0</u> | Function code H30 | Function code H30 | | | | | | | | | | | | | | | | |
| 1 | Commanded from the fieldbus | Function code H30 | | | | | | | | | | | | | | | | |
| 2 | Function code H30 | Commanded from the fieldbus | | | | | | | | | | | | | | | | |
| 3 | Commanded from the fieldbus | Commanded from the fieldbus | | | | | | | | | | | | | | | | |

| Function Code | Item | Setting | Example | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
|---------------|--|--|---------|-----------|-------------------|---|------------------------|------------------------|---|---------------------------|------------------------|---|------------------------|---------------------------|---|---------------------------|---------------------------|---|--|----------|---|--|----------------------|---|----------|--|---|----------------------|--|---|--|--|---|
| y99 | Support link function | <table border="1"> <thead> <tr> <th></th> <th>Frequency</th> <th>Operation Command</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>Function code H30, y98</td> <td>Function code H30, y98</td> </tr> <tr> <td>1</td> <td>Commanded from the loader</td> <td>Function code H30, y98</td> </tr> <tr> <td>2</td> <td>Function code H30, y98</td> <td>Commanded from the loader</td> </tr> <tr> <td>3</td> <td>Commanded from the loader</td> <td>Commanded from the loader</td> </tr> </tbody> </table> | | Frequency | Operation Command | 0 | Function code H30, y98 | Function code H30, y98 | 1 | Commanded from the loader | Function code H30, y98 | 2 | Function code H30, y98 | Commanded from the loader | 3 | Commanded from the loader | Commanded from the loader | 0 | | | | | | | | | | | | | | | |
| | Frequency | Operation Command | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 0 | Function code H30, y98 | Function code H30, y98 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 1 | Commanded from the loader | Function code H30, y98 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 2 | Function code H30, y98 | Commanded from the loader | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 3 | Commanded from the loader | Commanded from the loader | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| H30 | Link function *2 | <table border="1"> <thead> <tr> <th></th> <th>Frequency</th> <th>Operation Command</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>Inverter</td> <td>Inverter</td> </tr> <tr> <td>1</td> <td>RS-485 communication</td> <td>Inverter</td> </tr> <tr> <td>2</td> <td>Inverter</td> <td>RS-485 communication</td> </tr> <tr> <td>3</td> <td>RS-485 communication</td> <td>RS-485 communication</td> </tr> <tr> <td>4</td> <td>RS-485 communication (control circuit)</td> <td>Inverter</td> </tr> <tr> <td>5</td> <td>RS-485 communication (control circuit)</td> <td>RS-485 communication</td> </tr> <tr> <td>6</td> <td>Inverter</td> <td>RS-485 communication (control circuit)</td> </tr> <tr> <td>7</td> <td>RS-485 communication</td> <td>RS-485 communication (control circuit)</td> </tr> <tr> <td>8</td> <td>RS-485 communication (control circuit)</td> <td>RS-485 communication (control circuit)</td> </tr> </tbody> </table> | | Frequency | Operation Command | 0 | Inverter | Inverter | 1 | RS-485 communication | Inverter | 2 | Inverter | RS-485 communication | 3 | RS-485 communication | RS-485 communication | 4 | RS-485 communication (control circuit) | Inverter | 5 | RS-485 communication (control circuit) | RS-485 communication | 6 | Inverter | RS-485 communication (control circuit) | 7 | RS-485 communication | RS-485 communication (control circuit) | 8 | RS-485 communication (control circuit) | RS-485 communication (control circuit) | 3 |
| | Frequency | Operation Command | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 0 | Inverter | Inverter | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 1 | RS-485 communication | Inverter | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 2 | Inverter | RS-485 communication | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 3 | RS-485 communication | RS-485 communication | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 4 | RS-485 communication (control circuit) | Inverter | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 5 | RS-485 communication (control circuit) | RS-485 communication | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 6 | Inverter | RS-485 communication (control circuit) | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 7 | RS-485 communication | RS-485 communication (control circuit) | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 8 | RS-485 communication (control circuit) | RS-485 communication (control circuit) | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |

*1 Select "Modbus RTU" for the communication protocol on the inverter when connecting with the V9.

*2 When "0" is specified for y98 (bus function) as well as y99 (support link function), the frequency and operation command can be set on the V9.
When making the frequency and operation command settings on the V9 connected to the connector for the touch panel, specify "3" for function code H30. When making those settings on the V9 connected to the terminal block on control circuit, specify "8" for function code H30.

*3 The communication parameter (data length) is fixed to 8 bits.

Available Device Memory

The available setting range of device memory varies depending on the model. Be sure to set within the range available for the model to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|---------------|------|---------|
| 4 | 02H | |

16.2.18 FRENIC-MEGA SERVO (MODBUS RTU)

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|--|---|
| Connection Mode | 1 : 1 / <u>1:n</u> / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet) | |
| Signal Level | <u>RS-422/485</u> | |
| Baud Rate | 4800 / 9600 / <u>19200</u> / 38400 bps | |
| Data Length | <u>8 bits</u> | |
| Stop Bit | 1 / <u>2</u> bits | On the inverter: 2 bits when "0" is specified for y06 or y16 1 bit when "1", "2" or "3" is specified for y06 or y16 |
| Parity | <u>None</u> / Odd / Even | |
| Target Port No. | 0 to 247 | 0: Broadcast |

Inverter

Set communication parameters.

Be sure to match the settings to those made under [Communication Setting] of the editor.

(Underlined setting: default)

| Function Code | Item | Setting | Example | | | | | | | | | | | | | | | |
|---------------|-----------------------------|--|---------|-----------|-------------------|---|-------------------|-------------------|---|-----------------------------|-------------------|---|-------------------|-----------------------------|---|-----------------------------|-----------------------------|---|
| y01 | Station address | <u>1</u> to 247 | 1 | | | | | | | | | | | | | | | |
| y04 | Baud rate | 1: 4800 bps 2: 9600 bps <u>3: 19200 bps</u> 4: 38400 bps | 3 | | | | | | | | | | | | | | | |
| y06 | Parity bit | <u>0: None</u> 1: Even 2: Odd 3: None | 0 | | | | | | | | | | | | | | | |
| y07 | Stop bit | For Modbus RTU communication, the stop bit setting is automatically made according to the parity bit setting. When "0" is specified for y06, "2 bits" is set for stop bit. When "1", "2", or "3" is specified for y06, "1 bit" is set for stop bit. | - | | | | | | | | | | | | | | | |
| y10 | Communication protocol *1 | <u>0: Modbus RTU</u> <u>1: SX (loader) protocol</u> 2: FGI-bus | 0 | | | | | | | | | | | | | | | |
| y11 | Station address | <u>1</u> to 247 | 1 | | | | | | | | | | | | | | | |
| y14 | Baud rate | 1: 4800 bps 2: 9600 bps <u>3: 19200 bps</u> 4: 38400 bps | 3 | | | | | | | | | | | | | | | |
| y16 | Parity bit | <u>0: None</u> 1: Even 2: Odd 3: None | 0 | | | | | | | | | | | | | | | |
| y17 | Stop bit | For Modbus RTU communication, the stop bit setting is automatically made according to the parity bit setting. When "0" is specified for y16, "2 bits" is set for stop bit. When "1", "2", or "3" is specified for y16, "1 bit" is set for stop bit. | - | | | | | | | | | | | | | | | |
| y20 | Communication protocol *1 | <u>0: Modbus RTU</u> 2: FGI-bus | 0 | | | | | | | | | | | | | | | |
| y98 | Bus function | <table border="1"> <thead> <tr> <th></th> <th>Frequency</th> <th>Operation Command</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>Function code H30</td> <td>Function code H30</td> </tr> <tr> <td>1</td> <td>Commanded from the fieldbus</td> <td>Function code H30</td> </tr> <tr> <td>2</td> <td>Function code H30</td> <td>Commanded from the fieldbus</td> </tr> <tr> <td>3</td> <td>Commanded from the fieldbus</td> <td>Commanded from the fieldbus</td> </tr> </tbody> </table> | | Frequency | Operation Command | 0 | Function code H30 | Function code H30 | 1 | Commanded from the fieldbus | Function code H30 | 2 | Function code H30 | Commanded from the fieldbus | 3 | Commanded from the fieldbus | Commanded from the fieldbus | 0 |
| | Frequency | Operation Command | | | | | | | | | | | | | | | | |
| 0 | Function code H30 | Function code H30 | | | | | | | | | | | | | | | | |
| 1 | Commanded from the fieldbus | Function code H30 | | | | | | | | | | | | | | | | |
| 2 | Function code H30 | Commanded from the fieldbus | | | | | | | | | | | | | | | | |
| 3 | Commanded from the fieldbus | Commanded from the fieldbus | | | | | | | | | | | | | | | | |

| Function Code | Item | Setting | Example | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
|---------------|--|--|---------|-----------|-------------------|---|------------------------|------------------------|---|------------------------------|------------------------|---|------------------------|------------------------------|---|------------------------------|------------------------------|---|--|----------|---|--|----------------------|---|----------|--|---|----------------------|--|---|--|--|---|
| y99 | Support link function | <table border="1"> <thead> <tr> <th></th> <th>Frequency</th> <th>Operation Command</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>Function code H30, y98</td> <td>Function code H30, y98</td> </tr> <tr> <td>1</td> <td>Commanded from FRENIC loader</td> <td>Function code H30, y98</td> </tr> <tr> <td>2</td> <td>Function code H30, y98</td> <td>Commanded from FRENIC loader</td> </tr> <tr> <td>3</td> <td>Commanded from FRENIC loader</td> <td>Commanded from FRENIC loader</td> </tr> </tbody> </table> | | Frequency | Operation Command | 0 | Function code H30, y98 | Function code H30, y98 | 1 | Commanded from FRENIC loader | Function code H30, y98 | 2 | Function code H30, y98 | Commanded from FRENIC loader | 3 | Commanded from FRENIC loader | Commanded from FRENIC loader | 0 | | | | | | | | | | | | | | | |
| | Frequency | Operation Command | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 0 | Function code H30, y98 | Function code H30, y98 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 1 | Commanded from FRENIC loader | Function code H30, y98 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 2 | Function code H30, y98 | Commanded from FRENIC loader | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 3 | Commanded from FRENIC loader | Commanded from FRENIC loader | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| H30 | Link function *2 | <table border="1"> <thead> <tr> <th></th> <th>Frequency</th> <th>Operation Command</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>Inverter</td> <td>Inverter</td> </tr> <tr> <td>1</td> <td>RS-485 communication</td> <td>Inverter</td> </tr> <tr> <td>2</td> <td>Inverter</td> <td>RS-485 communication</td> </tr> <tr> <td>3</td> <td>RS-485 communication</td> <td>RS-485 communication</td> </tr> <tr> <td>4</td> <td>RS-485 communication (Control circuit)</td> <td>Inverter</td> </tr> <tr> <td>5</td> <td>RS-485 communication (Control circuit)</td> <td>RS-485 communication</td> </tr> <tr> <td>6</td> <td>Inverter</td> <td>RS-485 communication (Control circuit)</td> </tr> <tr> <td>7</td> <td>RS-485 communication</td> <td>RS-485 communication (Control circuit)</td> </tr> <tr> <td>8</td> <td>RS-485 communication (Control circuit)</td> <td>RS-485 communication (Control circuit)</td> </tr> </tbody> </table> | | Frequency | Operation Command | 0 | Inverter | Inverter | 1 | RS-485 communication | Inverter | 2 | Inverter | RS-485 communication | 3 | RS-485 communication | RS-485 communication | 4 | RS-485 communication (Control circuit) | Inverter | 5 | RS-485 communication (Control circuit) | RS-485 communication | 6 | Inverter | RS-485 communication (Control circuit) | 7 | RS-485 communication | RS-485 communication (Control circuit) | 8 | RS-485 communication (Control circuit) | RS-485 communication (Control circuit) | 3 |
| | Frequency | Operation Command | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 0 | Inverter | Inverter | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 1 | RS-485 communication | Inverter | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 2 | Inverter | RS-485 communication | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 3 | RS-485 communication | RS-485 communication | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 4 | RS-485 communication (Control circuit) | Inverter | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 5 | RS-485 communication (Control circuit) | RS-485 communication | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 6 | Inverter | RS-485 communication (Control circuit) | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 7 | RS-485 communication | RS-485 communication (Control circuit) | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 8 | RS-485 communication (Control circuit) | RS-485 communication (Control circuit) | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |

*1 Select "Modbus RTU" for the communication protocol on the inverter when connecting with the V9.

*2 When "0" is specified for y98 (bus function) as well as y99 (support link function), the frequency and operation command can be set on the V9.

When making frequency and operation command settings on the V9 connected to the connector for the touch panel, specify "3" for function code H30. When making the settings on the V9 connected to the control circuit terminal block, specify "8" for H30.

*3 The communication parameter (data length) is fixed to 8 bits.

Available Device Memory

The available setting range of device memory varies depending on the model. Be sure to set within the range available for the model to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|---------------|------|---------|
| 4 | 02H | |

16.2.19 FRENIC-HVAC/AQUA (MODBUS RTU)

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|--|---|
| Connection Mode | 1 : 1 / <u>1:n</u> / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet) | |
| Signal Level | <u>RS-422/485</u> | |
| Baud Rate | 4800 / 9600 / <u>19200</u> / 38400 bps | |
| Data Length | <u>8 bits</u> | |
| Stop Bit | 1 / <u>2</u> bits | On the inverter: 2 bits when "0" is specified for y06 or y16 1 bit when "1", "2" or "3" is specified for y06 or y16 |
| Parity | <u>None</u> / Odd / Even | |
| Target Port No. | 0 to 247 | 0: Broadcast |

Inverter

Set communication parameters.

Be sure to match the settings to those made under [Communication Setting] of the editor.

(Underlined setting: default)

| Function Code | Item | Setting | Example | | | | | | | | | | | | | | | |
|---------------|-----------------------------|--|---------|-----------|-------------------|---|-------------------|-------------------|---|-----------------------------|-------------------|---|-------------------|-----------------------------|---|-----------------------------|-----------------------------|---|
| y01 | Station address | <u>1</u> to 247 | 1 | | | | | | | | | | | | | | | |
| y04 | Baud rate | 1: 4800 bps 2: 9600 bps <u>3: 19200 bps</u> 4: 38400 bps | 3 | | | | | | | | | | | | | | | |
| y06 | Parity bit | <u>0: None</u> 1: Even 2: Odd 3: None | 0 | | | | | | | | | | | | | | | |
| y07 | Stop bit | For Modbus RTU communication, the stop bit setting is automatically made according to the parity bit setting. When "0" is specified for y06, "2 bits" is set for stop bit. When "1", "2", or "3" is specified for y06, "1 bit" is set for stop bit. | - | | | | | | | | | | | | | | | |
| y10 | Communication protocol *1 | 0: Modbus RTU | 0 | | | | | | | | | | | | | | | |
| y11 | Station address | <u>1</u> to 247 | 1 | | | | | | | | | | | | | | | |
| y14 | Baud rate | 1: 4800 bps 2: 9600 bps <u>3: 19200 bps</u> 4: 38400 bps | 3 | | | | | | | | | | | | | | | |
| y16 | Parity bit | <u>0: None</u> 1: Even 2: Odd 3: None | 0 | | | | | | | | | | | | | | | |
| y17 | Stop bit | For Modbus RTU communication, the stop bit setting is automatically made according to the parity bit setting. When "0" is specified for y16, "2 bits" is set for stop bit. When "1", "2", or "3" is specified for y16, "1 bit" is set for stop bit. | - | | | | | | | | | | | | | | | |
| y20 | Communication protocol *1 | 0: Modbus RTU | 0 | | | | | | | | | | | | | | | |
| y98 | Bus function | <table border="1"> <thead> <tr> <th></th> <th>Frequency</th> <th>Operation Command</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>Function code H30</td> <td>Function code H30</td> </tr> <tr> <td>1</td> <td>Commanded from the fieldbus</td> <td>Function code H30</td> </tr> <tr> <td>2</td> <td>Function code H30</td> <td>Commanded from the fieldbus</td> </tr> <tr> <td>3</td> <td>Commanded from the fieldbus</td> <td>Commanded from the fieldbus</td> </tr> </tbody> </table> | | Frequency | Operation Command | 0 | Function code H30 | Function code H30 | 1 | Commanded from the fieldbus | Function code H30 | 2 | Function code H30 | Commanded from the fieldbus | 3 | Commanded from the fieldbus | Commanded from the fieldbus | 0 |
| | Frequency | Operation Command | | | | | | | | | | | | | | | | |
| 0 | Function code H30 | Function code H30 | | | | | | | | | | | | | | | | |
| 1 | Commanded from the fieldbus | Function code H30 | | | | | | | | | | | | | | | | |
| 2 | Function code H30 | Commanded from the fieldbus | | | | | | | | | | | | | | | | |
| 3 | Commanded from the fieldbus | Commanded from the fieldbus | | | | | | | | | | | | | | | | |

| Function Code | Item | Setting | Example | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
|---------------|--|--|---------|-----------|-------------------|---|------------------------|------------------------|---|------------------------------|------------------------|---|------------------------|----------------------------|---|----------------------------|----------------------------|---|--|----------|---|--|----------------------|---|----------|--|---|----------------------|--|---|--|--|---|
| y99 | Support link function | <table border="1"> <thead> <tr> <th></th> <th>Frequency</th> <th>Operation Command</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>Function code H30, y98</td> <td>Function code H30, y98</td> </tr> <tr> <td>1</td> <td>Commanded from FRENIC loader</td> <td>Function code H30, y98</td> </tr> <tr> <td>2</td> <td>Function code H30, y98</td> <td>Command from FRENIC loader</td> </tr> <tr> <td>3</td> <td>Command from FRENIC loader</td> <td>Command from FRENIC loader</td> </tr> </tbody> </table> | | Frequency | Operation Command | 0 | Function code H30, y98 | Function code H30, y98 | 1 | Commanded from FRENIC loader | Function code H30, y98 | 2 | Function code H30, y98 | Command from FRENIC loader | 3 | Command from FRENIC loader | Command from FRENIC loader | 0 | | | | | | | | | | | | | | | |
| | Frequency | Operation Command | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 0 | Function code H30, y98 | Function code H30, y98 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 1 | Commanded from FRENIC loader | Function code H30, y98 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 2 | Function code H30, y98 | Command from FRENIC loader | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 3 | Command from FRENIC loader | Command from FRENIC loader | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| H30 | Link function *2 | <table border="1"> <thead> <tr> <th></th> <th>Frequency</th> <th>Operation command</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>Inverter</td> <td>Inverter</td> </tr> <tr> <td>1</td> <td>RS-485 communication</td> <td>Inverter</td> </tr> <tr> <td>2</td> <td>Inverter</td> <td>RS-485 communication</td> </tr> <tr> <td>3</td> <td>RS-485 communication</td> <td>RS-485 communication</td> </tr> <tr> <td>4</td> <td>RS-485 communication (Control circuit)</td> <td>Inverter</td> </tr> <tr> <td>5</td> <td>RS-485 communication (Control circuit)</td> <td>RS-485 communication</td> </tr> <tr> <td>6</td> <td>Inverter</td> <td>RS-485 communication (Control circuit)</td> </tr> <tr> <td>7</td> <td>RS-485 communication</td> <td>RS-485 communication (Control circuit)</td> </tr> <tr> <td>8</td> <td>RS-485 communication (Control circuit)</td> <td>RS-485 communication (Control circuit)</td> </tr> </tbody> </table> | | Frequency | Operation command | 0 | Inverter | Inverter | 1 | RS-485 communication | Inverter | 2 | Inverter | RS-485 communication | 3 | RS-485 communication | RS-485 communication | 4 | RS-485 communication (Control circuit) | Inverter | 5 | RS-485 communication (Control circuit) | RS-485 communication | 6 | Inverter | RS-485 communication (Control circuit) | 7 | RS-485 communication | RS-485 communication (Control circuit) | 8 | RS-485 communication (Control circuit) | RS-485 communication (Control circuit) | 3 |
| | Frequency | Operation command | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 0 | Inverter | Inverter | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 1 | RS-485 communication | Inverter | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 2 | Inverter | RS-485 communication | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 3 | RS-485 communication | RS-485 communication | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 4 | RS-485 communication (Control circuit) | Inverter | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 5 | RS-485 communication (Control circuit) | RS-485 communication | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 6 | Inverter | RS-485 communication (Control circuit) | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 7 | RS-485 communication | RS-485 communication (Control circuit) | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 8 | RS-485 communication (Control circuit) | RS-485 communication (Control circuit) | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |

*1 Select "Modbus RTU" for the communication protocol on the inverter when connecting with the V9.

*2 When "0" is specified for y98 (bus function) as well as y99 (support link function), the frequency and operation command can be set on the V9.

When making frequency and operation command settings on the V9 connected to the connector for the touch panel, specify "3" for function code H30. When making the settings on the V9 connected to the control circuit terminal block, specify "8" for H30.

*3 The communication parameter (data length) is fixed to 8 bits.

Available Device Memory

The available setting range of device memory varies depending on the model. Be sure to set within the range available for the model to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|---------------|------|---------|
| 4 | 02H | |

16.2.20 HFR-C9K

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|--|---------|
| Connection Mode | 1 : 1 / <u>1:n</u> / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet) | |
| Signal Level | RS-422/485 | |
| Baud Rate | 4800 / <u>9600</u> / 19200 bps | |
| Data Length | 7 / <u>8</u> bits | |
| Stop Bit | 1 / <u>2</u> bits | |
| Parity | None / Odd / <u>Even</u> | |
| Target Port No. | <u>1</u> to 31 | |

IH Inverter

Be sure to match the settings to those made under [Communication Setting] of the editor.

SW1 setting (Station address / Optional selection)

| Switch | Contents | Example: Station Address: 1 Optional Selection: Selection for Communication Operation (Start from LSB) | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
|--|---|---|--------------------|--|----------|-----|-----|--|-----|-----|--|-----|-----|---|----|-----|-----|-----|-----|---|-----|----|-----|-----|-----|---|----|----|-----|-----|-----|---|---|---|---|---|---|----|-----|-----|----|----|----|----|----|----|----|----|----|----|-----|----|----|----|----|----|----|----|----|----|----|--|
| 1 | <table border="1"> <thead> <tr> <th>Switch Address</th> <th>1</th> <th>2</th> <th>3</th> <th>4</th> <th>5</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>OFF</td> <td>OFF</td> <td>OFF</td> <td>OFF</td> <td>OFF</td> </tr> <tr> <td>1</td> <td>ON</td> <td>OFF</td> <td>OFF</td> <td>OFF</td> <td>OFF</td> </tr> <tr> <td>2</td> <td>OFF</td> <td>ON</td> <td>OFF</td> <td>OFF</td> <td>OFF</td> </tr> <tr> <td>3</td> <td>ON</td> <td>ON</td> <td>OFF</td> <td>OFF</td> <td>OFF</td> </tr> <tr> <td>:</td> <td>:</td> <td>:</td> <td>:</td> <td>:</td> <td>:</td> </tr> <tr> <td>28</td> <td>OFF</td> <td>OFF</td> <td>ON</td> <td>ON</td> <td>ON</td> </tr> <tr> <td>29</td> <td>ON</td> <td>ON</td> <td>ON</td> <td>ON</td> <td>ON</td> </tr> <tr> <td>30</td> <td>OFF</td> <td>ON</td> <td>ON</td> <td>ON</td> <td>ON</td> </tr> <tr> <td>31</td> <td>ON</td> <td>ON</td> <td>ON</td> <td>ON</td> <td>ON</td> </tr> </tbody> </table> | Switch Address | 1 | 2 | 3 | 4 | 5 | 0 | OFF | OFF | OFF | OFF | OFF | 1 | ON | OFF | OFF | OFF | OFF | 2 | OFF | ON | OFF | OFF | OFF | 3 | ON | ON | OFF | OFF | OFF | : | : | : | : | : | : | 28 | OFF | OFF | ON | ON | ON | 29 | ON | ON | ON | ON | ON | 30 | OFF | ON | ON | ON | ON | 31 | ON | ON | ON | ON | ON | |
| Switch Address | | 1 | 2 | 3 | 4 | 5 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 0 | | OFF | OFF | OFF | OFF | OFF | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 1 | | ON | OFF | OFF | OFF | OFF | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 2 | | OFF | ON | OFF | OFF | OFF | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 3 | ON | ON | OFF | OFF | OFF | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| : | : | : | : | : | : | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 28 | OFF | OFF | ON | ON | ON | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 29 | ON | ON | ON | ON | ON | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 30 | OFF | ON | ON | ON | ON | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 31 | ON | ON | ON | ON | ON | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 2 | Station Address*1 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 3 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 4 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 5 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 6 | | | Optional Selection | <table border="1"> <thead> <tr> <th>Contents</th> <th>LSB</th> <th>MSB</th> </tr> </thead> <tbody> <tr> <td>Selection for Communication Operation (Start from LSB)</td> <td>ON</td> <td>OFF</td> </tr> <tr> <td>Selection for Communication Operation (Start from MSB)</td> <td>OFF</td> <td>ON</td> </tr> </tbody> </table> | Contents | LSB | MSB | Selection for Communication Operation (Start from LSB) | ON | OFF | Selection for Communication Operation (Start from MSB) | OFF | ON | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Contents | LSB | MSB | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Selection for Communication Operation (Start from LSB) | ON | OFF | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Selection for Communication Operation (Start from MSB) | OFF | ON | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |

*1 For connection to a V9, be sure to set the station address other than 0.

Communication setting

Set communication parameters.

Be sure to match the settings to those made under [Communication Setting] of the editor.

(Underlined setting: default)

| Function Code | Item | Setting | Example |
|---------------|-------------|---|---------|
| F16 | Baud rate | 4: 4800 bps <u>5: 9600 bps</u> 6: 19200 bps | 5 |
| F17 | Data length | 0: 7 bit <u>1: 8 bits</u> | 1 |
| F18 | Parity bit | 0: None <u>1: Even</u> 2: Odd | 1 |
| F19 | Stop bit | 0: 1 bit <u>1: 2 bits</u> | 1 |

Available Device Memory

The available setting range of device memory varies depending on the model. Be sure to set within the range available for the model to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|---------------|------|---------|
| --- | 00H | |

16.2.21 HFR-C11K

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|--|---------|
| Connection Mode | 1 : 1 / <u>1 : n</u> / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet) | |
| Signal Level | RS-422/485 | |
| Baud Rate | 4800 / <u>9600</u> / 19200 bps | |
| Data Length | <u>7</u> / 8 bits | |
| Stop Bit | <u>1</u> / 2 bits | |
| Parity | None / Odd / <u>Even</u> | |
| Target Port No. | <u>1</u> to 31 | |

IH Inverter

Be sure to match the settings to those made under [Communication Setting] of the editor. (Underlined setting: default)

SW3 setting (station address / terminating resistance)

| Switch | Contents | Example: | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
|------------------------|--|---|----------|-----|-----|------------------------|-------------|----------|-----|-----|-----|-----|-----|---|----|-----|-----|-----|-----|---|-----|----|-----|-----|-----|---|----|----|-----|-----|-----|---|---|---|---|---|---|----|-----|-----|----|----|----|----|----|-----|----|----|----|----|-----|----|----|----|----|----|----|----|----|----|----|--|
| 1 | <table border="1"> <thead> <tr> <th>Switch Address</th> <th>1</th> <th>2</th> <th>3</th> <th>4</th> <th>5</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>OFF</td> <td>OFF</td> <td>OFF</td> <td>OFF</td> <td>OFF</td> </tr> <tr> <td>1</td> <td>ON</td> <td>OFF</td> <td>OFF</td> <td>OFF</td> <td>OFF</td> </tr> <tr> <td>2</td> <td>OFF</td> <td>ON</td> <td>OFF</td> <td>OFF</td> <td>OFF</td> </tr> <tr> <td>3</td> <td>ON</td> <td>ON</td> <td>OFF</td> <td>OFF</td> <td>OFF</td> </tr> <tr> <td>:</td> <td>:</td> <td>:</td> <td>:</td> <td>:</td> <td>:</td> </tr> <tr> <td>28</td> <td>OFF</td> <td>OFF</td> <td>ON</td> <td>ON</td> <td>ON</td> </tr> <tr> <td>29</td> <td>ON</td> <td>OFF</td> <td>ON</td> <td>ON</td> <td>ON</td> </tr> <tr> <td>30</td> <td>OFF</td> <td>ON</td> <td>ON</td> <td>ON</td> <td>ON</td> </tr> <tr> <td>31</td> <td>ON</td> <td>ON</td> <td>ON</td> <td>ON</td> <td>ON</td> </tr> </tbody> </table> | Switch Address | 1 | 2 | 3 | 4 | 5 | 0 | OFF | OFF | OFF | OFF | OFF | 1 | ON | OFF | OFF | OFF | OFF | 2 | OFF | ON | OFF | OFF | OFF | 3 | ON | ON | OFF | OFF | OFF | : | : | : | : | : | : | 28 | OFF | OFF | ON | ON | ON | 29 | ON | OFF | ON | ON | ON | 30 | OFF | ON | ON | ON | ON | 31 | ON | ON | ON | ON | ON | Station Address: 1 Terminating Resistance: None |
| Switch Address | | 1 | 2 | 3 | 4 | 5 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 0 | | OFF | OFF | OFF | OFF | OFF | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 1 | | ON | OFF | OFF | OFF | OFF | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 2 | | OFF | ON | OFF | OFF | OFF | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 3 | ON | ON | OFF | OFF | OFF | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| : | : | : | : | : | : | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 28 | OFF | OFF | ON | ON | ON | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 29 | ON | OFF | ON | ON | ON | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 30 | OFF | ON | ON | ON | ON | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 31 | ON | ON | ON | ON | ON | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 2 | Station Address*1 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 3 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 4 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 5 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 6 | Terminating Resistance | <table border="1"> <thead> <tr> <th>Contents</th> <th>OFF</th> <th>ON</th> </tr> </thead> <tbody> <tr> <td>Terminating resistance</td> <td><u>None</u></td> <td>Provided</td> </tr> </tbody> </table> | Contents | OFF | ON | Terminating resistance | <u>None</u> | Provided | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Contents | OFF | ON | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Terminating resistance | <u>None</u> | Provided | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |

*1 For connection to a V9, be sure to set the station address other than 0.

Communication setting

Set communication parameters.

Be sure to match the settings to those made under [Communication Setting] of the editor.

(Underlined setting: default)

| Function Code | Item | Setting | Example |
|---------------|-------------------------|---|---------|
| r 04 | Baud rate | 2: 4800 bps 3: <u>9600 bps</u> 4: 19200 bps | 3 |
| r 05 | Data length | 0: 8 bit <u>1: 7 bits</u> | 1 |
| r 06 | Parity bit | 0: None <u>1: Even</u> 2: Odd | 1 |
| r 07 | Stop bit | 0: 2 bit <u>1: 1 bits</u> | 1 |
| r 10 | Communication protocol* | <u>0: FGI-bus</u> 1: C9K mode | 0 |

* RS-485 communication is available when the communication is enabled by digital input.

Example: To make the communication enabled when digital input terminal X1 is turned ON;

Set "11 (RS485 communication selection (RS))" for function code i01 and turn on the digital input terminal X1 externally. Terminals from X2 to X5 can also be used. Set the function code corresponding to the digital input terminal to use.

Available Device Memory

The available setting range of device memory varies depending on the model. Be sure to set within the range available for the model to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|--|------|---------|
| S (command data) | 00H | |
| M (monitor data) | 01H | |
| F (basic function) | 02H | |
| E (error display function) | 03H | |
| C (control function) | 04H | |
| P (optional function) | 05H | |
| H (high level function) | 06H | |
| o (output terminal function) | 08H | |
| i (input terminal function) | 0BH | |
| t (control function in the event of trip (alarm) occurrence) | 0CH | |
| r (RS communication function) | 0DH | |
| Pn (touch panel function) | 0EH | |

PLC_CTL

| Content | F0 | F1 (= \$u n) | | F2 |
|---------------|---------------------|--------------|----------------|----|
| Reset command | 1 - 8 (PLC1 - 8) | n | Station number | 2 |
| | | n + 1 | Command: 0 | |

16.2.22 PPMC (MODBUS RTU)

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|--|--|
| Connection Mode | 1 : 1 / <u>1:n</u> / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet) | |
| Signal Level | <u>RS-232C</u> / RS-422/485 | |
| Baud Rate | <u>9600</u> / 19200 bps | |
| Data Length | 8 bits | Do not change the default setting because the setting on the AC power monitor cannot be changed. |
| Stop Bit | 1 bit | |
| Parity | <u>None</u> / Even / Odd | |
| Target Port No. | 1 to 31 | |

AC Power Monitor

The communication parameters can be set using keys attached to the front of the AC power monitor. Be sure to match the settings to those made under [Communication Setting] of the editor.

(Underlined setting: default)

| Parameter | Item | Setting | Example | |
|---------------------|---------------|----------------------------------|--|-----|
| Setting condition 2 | Item number 2 | ID number | 1 to 31 (default: unit number ^{*1}) | 1 |
| | Item number 3 | Communication protocol selection | <u>nor: Dedicated protocol</u> rtu: Modbus RTU protocol *2 | rtu |
| | Item number 7 | Baud rate | <u>9.6: 9600 bps</u> 19.2: 19200 bps 4.8: 4800 bps | 9.6 |
| | Item number 8 | Data length, parity | <u>8n: Data length 8 bits, without parity</u> 8o: Data length 8 bits, odd parity 8E: Data length 8 bits, even parity | 8n |

- *1 The unit number is set for the ID number upon delivery. The unit number is indicated on the instruction plate attached to the side of the case.
- *2 Select "rtu (Modbus RTU)" for the communication protocol when communicating with the V9.
- *3 The communication parameter (stop bit) is fixed to 1 bit.
- *4 The communication function of the AC power monitor can be selected at the time of purchase. Select a model on which RS-485/RS-232C communication is available.

Available Device Memory

The available setting range of device memory varies depending on the model. Be sure to set within the range available for the model to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|----------------------|------|-----------|
| 4 (holding register) | 02H | |
| 3 (input register) | 03H | Read only |

- * Remarks on data format for the following device memory:
 40022 (fixed voltage), 40028 (Ip fixed power factor): 6-byte character string
 40046 (calendar): 14-byte character string
 Measurement data: real type (Float)
 40060 (alarm clear), 40062 (amount of power clear), 40064 (cumulative value of invalid power clear): write only

16.2.23 FALDIC- α Series

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|--|--|
| Connection Mode | 1 : 1 / <u>1 : n</u> / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet) | |
| Signal Level | RS-422/485 | Do not change the default setting other than baud rate because the setting on the servo amplifier cannot be changed. |
| Baud Rate | <u>9600</u> / 19200 / 38400 bps | |
| Data Length | 8 bits | |
| Stop Bit | 1 bit | |
| Parity | Even | |
| Target Port No. | 1 to 31 | |

Servo Amplifier

Set the communication parameters using the touch panel mounted on the servo amplifier. Be sure to match the settings to those made under [Communication Setting] of the editor.

(Underlined setting: default)

| Parameter | Item | Setting | Example |
|----------------------------------|-----------------------|----------------|---|
| <i>Pn002</i> System parameter | <i>PP096</i> (No. 96) | Station number | 1 to 31 1 |
| | <i>PP097</i> (No. 97) | Baud rate | <u>0: 9600 bps</u> 1: 19200 bps 2: 38400 bps 0 |

*1 The communication function of the servo amplifier can be selected at the time of purchase. Select a model on which host interface: universal communication (RS-485) is available.

*2 The following communication parameters are fixed; data length: 8 bits, stop bit: 1 bit, and parity: even.

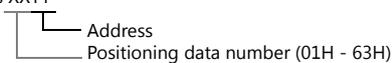
Available Device Memory

The available setting range of device memory varies depending on the model. Be sure to set within the range available for the model to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|---|------|---------------------------|
| 00 (monitor data) | 00H | Double-word, read only |
| 01 (data on positioning being executed) | 01H | Double-word, read only |
| 10 (sequence mode) | 02H | Read only |
| 11 (control input/output signal) | 03H | Read only |
| 12 (alarm detection log) | 04H | Read only |
| 13 (detected alarm contents) | 05H | Read only |
| 20 (standard parameter) | 06H | Double-word ^{*1} |
| 21 (system parameter) | 07H | Double-word ^{*1} |
| 30 (positioning data) | 08H | Double-word ^{*2} |
| 40 (control command) | 09H | Double-word, write only |

*1 Input a parameter number by manual operation.

*2 Address denotations XXYY



PLC_CTL

| Contents | F0 | F1 (= \$u n) | | F2 |
|--|---------------------|----------------|-----------------|----|
| Positioning data (immediate) setting | 1 - 8 (PLC1 - 8) | n | Station number | 6 |
| | | n + 1 | Command: 9 | |
| | | n + 2 | ABS/INC | |
| | | n + 3 | Speed selection | |
| | | n + 4 to n + 5 | Position data | |
| Automatic start (immediate) | 1 - 8 (PLC1 - 8) | n | Station number | 6 |
| | | n + 1 | Command: 11 | |
| | | n + 2 | ABS/INC | |
| | | n + 3 | Speed selection | |
| | | n + 4 to n + 5 | Position data | |
| Automatic start (positioning data number) | 1 - 8 (PLC1 - 8) | n | Station number | 3 |
| | | n + 1 | Command: 12 | |
| | | n + 2 | Start number | |
| Override setting | 1 - 8 (PLC1 - 8) | n | Station number | 4 |
| | | n + 1 | Command: 33 | |
| | | n + 2 | Data type | |
| | | n + 3 | Setting | |

16.2.24 FALDIC-W Series

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|--|--|
| Connection Mode | 1 : 1 / <u>1:n</u> / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet) | |
| Signal Level | RS-422/485 | Do not change the default setting other than baud rate because the setting on the servo amplifier cannot be changed. |
| Baud Rate | 9600 / 19200 / <u>38400</u> bps | |
| Data Length | 8 bits | |
| Stop Bit | 1 bit | |
| Parity | Even | |
| Target Port No. | 1 to 31 | |

- * When changing the time-out time, note the following points. (Default: 500 (msec))
- When the baud rate is 19200 bps or 38400 bps, set 200 (msec) or greater.
 - When the baud rate is 9600 bps, set 500 (msec) or greater.

Servo Amplifier

Set the communication parameters using the touch panel mounted on the servo amplifier. Be sure to match the settings to those made under [Communication Setting] of the editor.

(Underlined setting: default)

| Parameter | Item | Setting | Example | Remarks |
|---------------------------------------|-----------------------|----------------|---|--|
| <i>Pn01</i> Parameter editing mode | <i>no.82</i> (No. 82) | Station number | <u>1</u> to 31 | The setting takes effect when the power is turned off and back on again. |
| | <i>no.83</i> (No. 83) | Baud rate | <u>0</u> : 38400 bps 1: 19200 bps 2: 9600 bps | |

- * The following communication parameters are fixed; data length: 8 bits, stop bit: 1 bit, and parity: even.

Available Device Memory

The available setting range of device memory varies depending on the model. Be sure to set within the range available for the model to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|----------------------------|------|------------------------|
| 01 (monitor data) | 00H | Double-word, read only |
| 02 (sequence mode) | 01H | Read only |
| 03 (sequence I/O signal) | 02H | Read only |
| 04 (alarm history) | 03H | Read only |
| 06 (current alarm readout) | 04H | Read only |
| 07 (parameter) | 05H | Double-word |
| 09 (alarm reset) | 06H | Write only |

16.2.25 PH Series

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|--|--|
| Connection Mode | 1 : 1 / <u>1:n</u> / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet) | |
| Signal Level | RS-422/485 | |
| Baud Rate | 4800 / 9600 / <u>19200</u> bps | |
| Data Length | 8 bits | Do not change the default setting because the setting on the recorder cannot be changed. |
| Stop Bit | <u>1</u> / 2 bits | |
| Parity | None / <u>Odd</u> / Even | |
| Target Port No. | <u>1</u> to 31 | |

Recorder

The communication parameters can be set using keys attached to the front of the recorder. Be sure to match the settings to those made under [Communication Setting] of the editor.

(Underlined setting: default)

| Parameter | Setting | Example | Remarks |
|-------------|--------------------------------|-----------|---------|
| Station No. | <u>1</u> to 31 | 1 | |
| Baud rate | 4800 / 9600 / <u>19200</u> bps | 19200 bps | |
| Stop bit | <u>1</u> / 2 bits | 1 | |
| Parity | None / Even / <u>Odd</u> | Odd | |

- * The communication function of the recorder can be selected at the time of purchase. Select a model on which RS-485 transmission mode is available.
- * The communication parameter (data length) is fixed to 8 bits.

Available Device Memory

The available setting range of device memory varies depending on the model. Be sure to set within the range available for the model to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|---------------------------------------|------|------------|
| F00 (setting value file) | 00H | |
| F01 (range file CH1) | 01H | |
| F02 (range file CH2) | 02H | |
| F03 (range file CH3) | 03H | |
| F04 (range file CH4) | 04H | |
| F05 (range file CH5) | 05H | |
| F06 (range file CH6) | 06H | |
| F07 (range file CH7) | 07H | |
| F08 (range file CH8) | 08H | |
| F09 (range file CH9) | 09H | |
| F10 (range file CH10) | 0AH | |
| F11 (range file CH11) | 0BH | |
| F12 (range file CH12) | 0CH | |
| F13 (warning setting file) | 0DH | |
| F14 (system file) | 0EH | |
| F15 (command file) | 0FH | |
| F16 (abnormal input information file) | 10H | Read only |
| F17 (input data file) | 11H | Read only |
| F19 (alarm output file) | 13H | Read only |
| F21 (transmission input data file) | 15H | Write only |
| F22 (message file) | 16H | |
| F33 (daily report file 1) | 21H | Read only |
| F34 (daily report file 2) | 22H | Read only |
| F35 (daily report file 3) | 23H | Read only |
| F37 (integral file 1) | 25H | Read only |
| F38 (integral file 2) | 26H | Read only |
| F51 (status information control file) | 33H | |

16.2.26 PHR (MODBUS RTU)

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|--|--|
| Connection Mode | 1 : 1 / <u>1:n</u> / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet) | |
| Signal Level | RS-422/485 | Do not change the default settings of the signal level, data length and stop bit because these settings on the recorder cannot be changed. |
| Baud Rate | 9600 / <u>19200</u> bps | |
| Data Length | 8 bits | |
| Stop Bit | 1 bit | |
| Parity | None / Even / <u>Odd</u> | |
| Target Port No. | 1 to 31 | |

Recorder

The communication parameters can be set using keys attached to the front of the recorder. Be sure to match the settings to those made under [Communication Setting] of the editor.

(Underlined setting: default)

| Parameter | Setting | Example | Remarks |
|------------------------------|--------------------------|-----------|-------------------------|
| Modbus station No. | <u>1</u> to 31 | 1 | |
| Modbus baud rate | 9600 / <u>19200</u> bps | 19200 bps | |
| Modbus parity | None / Even / <u>Odd</u> | Odd | |
| Front communication function | ON / OFF | ON | Be sure to set to "ON". |

- *1 The communication function of the recorder can be selected at the time of purchase. Select a model on which RS-485 communication is available.
- *2 The following communication parameters are fixed; data length: 8 bits and stop bit: 1 bit.

Available Device Memory

The available setting range of device memory varies depending on the model. Be sure to set within the range available for the model to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|----------------------|------|---------|
| 4 (holding register) | 02H | |
| 3 (input register) | 03H | |

16.2.27 WA5000

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|--|---------|
| Connection Mode | 1 : 1 / <u>1:n</u> / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet) | |
| Signal Level | <u>RS-232C</u> / RS-422/485 | |
| Baud Rate | 4800 / <u>9600</u> / 19200 / 38400 bps | |
| Data Length | <u>7</u> / 8 bits | |
| Stop Bit | 1 / <u>2</u> bits | |
| Parity | None / <u>Even</u> / Odd | |
| CR / LF | <u>cr</u> / CR/LF | |
| Target Port No. | <u>1</u> to 31 | |
| Send Delay Time | 0 to 255 msec | *1 |

*1 If the send delay time is too short, "Communication Error "Format"" may occur. If this error occurs, set the send delay time to 5 msec or longer.

Digital Panel Meter

The communication parameters can be set using keys attached to the front of the digital panel meter. Be sure to match the settings to those made under [Communication Setting] of the editor.

(Underlined setting: default)

| Parameter | Item | Setting | Example | Remarks | |
|-----------|-------|---------------------|---|--------------|---|
| | BAUD | Baud rate setting | 4800: 4800 <u>9600: 9600</u> 192: 19200 384: 38400 | 9600 | |
| | DATA | Data length setting | <u>7: 7 bits</u> 8: 8 bits | 7 bits | |
| | P.BIT | Parity bit setting | <u>E: Even</u> o: Odd n: None | E: Even | |
| | S.BIT | Stop bit setting | <u>2: 2 bits</u> 1: 1 bit | 2: 2 bits | |
| | T- | Delimiter setting | <u>cr LF: CR/LF</u> cr: CR | cr LF: CR/LF | |
| | ADR | Unit ID setting | 01 to 31 (default: <u>00</u>) | 01 | Specify a value when using RS-485 connection. |

* The communication function of the temperature controller can be selected with the output unit specified at the time of purchase. Select a model on which RS-485/RS-232C communication is available.

Available Device Memory

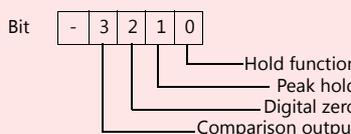
The available setting range of device memory varies depending on the model. Be sure to set within the range available for the model to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|------------------------|------|---------|
| DSP (display) | 00H | |
| CMP (comparator) | 01H | |
| SCL (scaling) | 02H | |
| CAL1 (calibration 1)*1 | 03H | |
| CAL2 (calibration 2) | 04H | |

*1 To perform zero calibration (0000), specify a value other than 0.

PLC_CTL

| Contents | F0 | F1 (= \$u n) | | F2 |
|--------------------------------------|---------------------|--------------|---|----|
| Hold remote control response | 1 - 8 (PLC1 - 8) | n | Station number | 2 |
| | | n + 1 | Command: 0 | |
| | | n + 2 | Hold status 0: OFF, 1: ON | |
| Hold terminal response | 1 - 8 (PLC1 - 8) | n | Station number | 2 |
| | | n + 1 | Command: 1 | |
| | | n + 2 | Hold status 0: OFF, 1: ON | |
| Hold remote control | 1 - 8 (PLC1 - 8) | n | Station number | 3 |
| | | n + 1 | Command: 2 | |
| | | n + 2 | Hold status 0: OFF, 1: ON | |
| Trigger input | 1 - 8 (PLC1 - 8) | n | Station number | 2 |
| | | n + 1 | Command: 3 | |
| | | n + 2 | Display type 0: Normal display 1: Over display 2: Peak hold display 3: Valley hold display 4: Peak valley hold display | |
| | | n + 3 | Measurement value | |
| | | n + 4 | Comparison result 0: OFF 1: HI 2: GO 3: LO | |
| Hold remote control cancel | 1 - 8 (PLC1 - 8) | n | Station number | 2 |
| | | n + 1 | Command: 4 | |
| Peak hold remote control response | 1 - 8 (PLC1 - 8) | n | Station number | 2 |
| | | n + 1 | Command: 5 | |
| | | n + 2 | Peak hold type 0: Peak hold 1: Valley hold 2: Peak valley hold | |
| | | n + 3 | Peak hold status 0: OFF, 1: ON | |
| Peak hold terminal response | 1 - 8 (PLC1 - 8) | n | Station number | 2 |
| | | n + 1 | Command: 6 | |
| | | n + 2 | Peak hold status 0: OFF, 1: ON | |
| Peak hold type setting | 1 - 8 (PLC1 - 8) | n | Station number | 3 |
| | | n + 1 | Command: 7 | |
| | | n + 2 | Peak hold type 0: Peak hold 1: Valley hold 2: Peak valley hold | |
| Peak hold remote control | 1 - 8 (PLC1 - 8) | n | Station number | 3 |
| | | n + 1 | Command: 8 | |
| | | n + 2 | Peak hold remote 0: OFF, 1: ON | |
| Peak hold value response | 1 - 8 (PLC1 - 8) | n | Station number | 2 |
| | | n + 1 | Command: 9 | |
| | | n + 2 | Peak hold value | |
| | | n + 3 | Valley hold value | |
| Peak hold value clear | 1 - 8 (PLC1 - 8) | n | Station number | 3 |
| | | n + 1 | Command: 10 | |
| | | n + 2 | Peak hold type 0: Peak hold 1: Valley hold 2: Peak valley hold | |
| Peak hold remote control cancel | 1 - 8 (PLC1 - 8) | n | Station number | 2 |
| | | n + 1 | Command: 11 | |
| Digital zero remote control response | 1 - 8 (PLC1 - 8) | n | Station number | 2 |
| | | n + 1 | Command: 12 | |
| | | n + 2 | Digital zero 0: OFF, 1: ON | |
| | | n + 3 | Displayed value | |

| Contents | F0 | F1 (= \$u n) | | F2 |
|--|---------------------|--------------|--|----|
| Digital zero terminal response | 1 - 8 (PLC1 - 8) | n | Station number | 2 |
| | | n + 1 | Command: 13 | |
| | | n + 2 | Digital zero 0: OFF, 1: ON | |
| Digital zero remote control | 1 - 8 (PLC1 - 8) | n | Station number | 4 |
| | | n + 1 | Command: 14 | |
| | | n + 2 | Digital zero 0: OFF, 1: ON, 2: ON when the value reaches the set value | |
| | | n + 3 | Setting value | |
| Digital zero remote control cancel | 1 - 8 (PLC1 - 8) | n | Station number | 2 |
| | | n + 1 | Command: 15 | |
| Comparison output remote control response | 1 - 8 (PLC1 - 8) | n | Station number | 2 |
| | | n + 1 | Command: 16 | |
| | | n + 2 | Status 0: OFF 1: Set (ON) HI 2: Set (ON) GO 3: Set (ON) LO | |
| Comparison output remote control | 1 - 8 (PLC1 - 8) | n | Station number | 3 |
| | | n + 1 | Command: 17 | |
| | | n + 2 | Status 0: OFF 1: Set (ON) HI 2: Set (ON) GO 3: Set (ON) LO | |
| Comparison output remote control cancel | 1 - 8 (PLC1 - 8) | n | Station number | 2 |
| | | n + 1 | Command: 18 | |
| Remote control response | 1 - 8 (PLC1 - 8) | n | Station number | 2 |
| | | n + 1 | Command: 19 | |
| | | n + 2 | Remote control status  | |
| | | | * No remote control is performed when all bits are reset (OFF). | |
| Maximum / minimum / (maximum - minimum) response | 1 - 8 (PLC1 - 8) | n | Station number | 2 |
| | | n + 1 | Command: 20 | |
| | | n + 2 | Maximum | |
| | | n + 3 | Minimum | |
| | | n + 4 | (Maximum - minimum) | |
| Maximum / minimum / (maximum - minimum) clear | 1 - 8 (PLC1 - 8) | n | Station number | 3 |
| | | n + 1 | Command: 21 | |
| | | n + 2 | Maximum / minimum / (maximum - minimum) clear 0: Maximum 1: Minimum 2: Maximum - minimum | |
| Range response | 1 - 8 (PLC1 - 8) | n | Station number | 2 |
| | | n + 1 | Command: 22 | |
| | | n + 2 | Range 0: No designation 12: J 1: Range 11 13: T 2: Range 12 14: R 3: Range 13 15: S 4: Range 14 16: B 5: Range 15 17: PA 6: Range 23 18: Pb 7: Range 24 19: JPA 8: Range 25 20: JPb 9: Range 26 21: 1V 10: KA 22: 2A 11: KB | |

| Contents | F0 | F1 (= \$u n) | | F2 |
|--|---------------------|--------------|--|----|
| Range setting | 1 - 8 (PLC1 - 8) | n | Station number | 3 |
| | | n + 1 | Command: 23 | |
| | | n + 2 | Range 1: Range 11 12: J 2: Range 12 13: T 3: Range 13 14: R 4: Range 14 15: S 5: Range 15 16: B 6: Range 23 17: PA 7: Range 24 18: Pb 8: Range 25 19: JPA 9: Range 26 20: JPb 10: KA 21: 1V 11: KB 22: 2A | |
| Average number of responses | 1 - 8 (PLC1 - 8) | n | Station number | 2 |
| | | n + 1 | Command: 24 | |
| | | n + 2 | Average number of times 1 / 2 / 4 / 8 / 10 / 20 / 40 / 80 (times) | |
| Setting for average number of times | 1 - 8 (PLC1 - 8) | n | Station number | 3 |
| | | n + 1 | Command: 25 | |
| | | n + 2 | Average number of times 1 / 2 / 4 / 8 / 10 / 20 / 40 / 80 (times) | |
| Average number of movement times | 1 - 8 (PLC1 - 8) | n | Station number | 2 |
| | | n + 1 | Command: 26 | |
| | | n + 2 | Average number of movement times 0 (OFF) / 2 / 4 / 8 / 16 / 32 (times) | |
| Setting for average number of movement times | 1 - 8 (PLC1 - 8) | n | Station number | 3 |
| | | n + 1 | Command: 27 | |
| | | n + 2 | Average number of movement times 0 (OFF) / 2 / 4 / 8 / 16 / 32 (times) | |
| Step-wide response | 1 - 8 (PLC1 - 8) | n | Station number | 2 |
| | | n + 1 | Command: 28 | |
| | | n + 2 | Step wide 1:1, 2:2, 5:5, 0:10 (digit) | |
| Step-wide setting | 1 - 8 (PLC1 - 8) | n | Station number | 3 |
| | | n + 1 | Command: 29 | |
| | | n + 2 | Step wide 1:1, 2:2, 5:5, 0:10 (digit) | |
| Communication function parameter response | 1 - 8 (PLC1 - 8) | n | Station number | 2 |
| | | n + 1 | Command: 30 | |
| | | n + 2 | Baud rate 0: 2400, 1: 4800, 2: 9600, 3: 19200, 4: 38400 | |
| | | n + 3 | Data length 0: 7 bits, 1: 8 bits | |
| | | n + 4 | Parity 0: none, 1: odd, 2: even | |
| | | n + 5 | Stop bit 0: 1 bit, 1: 2 bits | |
| | | n + 6 | Delimiter 0: CR/LF, 1: CR | |
| Communication function parameter setting | 1 - 8 (PLC1 - 8) | n | Station number | 7 |
| | | n + 1 | Command: 31 | |
| | | n + 2 | Baud rate 0: 2400, 1: 4800, 2: 9600, 3: 19200, 4: 38400 | |
| | | n + 3 | Data length 0: 7 bits, 1: 8 bits | |
| | | n + 4 | Parity 0: none, 1: odd, 2: even | |
| | | n + 5 | Stop bit 0: 1 bit, 1: 2 bits | |
| | | n + 6 | Delimiter 0: CR/LF, 1: CR | |
| Unit ID response | 1 - 8 (PLC1 - 8) | n | Station number | 2 |
| | | n + 1 | Command: 32 | |
| | | n + 2 | Unit ID 1 to 99 | |
| Unit ID setting | 1 - 8 (PLC1 - 8) | n | Station number | 3 |
| | | n + 1 | Command: 33 | |
| | | n + 2 | Unit ID 1 to 99 | |

| Contents | F0 | F1 (= \$u n) | | F2 |
|-------------------------------------|---------------------|--------------|--|----|
| Analog output type response | 1 - 8 (PLC1 - 8) | n | Station number | 2 |
| | | n + 1 | Command: 34 | |
| | | n + 2 | Analog output type 0: Not provided 1: OFF 2: 0 - 1 (V) 3: 0 - 10 (V) 4: 1 - 5 (V) 5: 0 - 20 (mA) 6: 4 - 20 (mA) | |
| Analog output type setting | 1 - 8 (PLC1 - 8) | n | Station number | 3 |
| | | n + 1 | Command: 35 | |
| | | n + 2 | Analog output type 1: OFF 2: 0 - 1 (V) 3: 0 - 10 (V) 4: 1 - 5 (V) 5: 0 - 20 (mA) 6: 4 - 20 (mA) | |
| Digital zero backup status response | 1 - 8 (PLC1 - 8) | n | Station number | 2 |
| | | n + 1 | Command: 36 | |
| | | n + 2 | Digital zero backup status 0: OFF 1: ON | |
| Digital zero backup control | 1 - 8 (PLC1 - 8) | n | Station number | 3 |
| | | n + 1 | Command: 37 | |
| | | n + 2 | Digital zero backup status 0: OFF 1: ON | |
| Digital zero data save command | 1 - 8 (PLC1 - 8) | n | Station number | 2 |
| | | n + 1 | Command: 38 | |
| Input change response | 1 - 8 (PLC1 - 8) | n | Station number | 2 |
| | | n + 1 | Command: 39 | |
| | | n + 2 | Input change 0: Not provided 1: Open collector 2: Logic 3: Magnetic | |
| Input change setting | 1 - 8 (PLC1 - 8) | n | Station number | 3 |
| | | n + 1 | Command: 40 | |
| | | n + 2 | Input change 1: Open collector 2: Logic 3: Magnetic | |
| Tracking zero response | 1 - 8 (PLC1 - 8) | n | Station number | 2 |
| | | n + 1 | Command: 41 | |
| | | n + 2 | Tracking zero time 0 (OFF) / 1 to 99 | |
| Tracking zero time setting | 1 - 8 (PLC1 - 8) | n | Station number | 3 |
| | | n + 1 | Command: 42 | |
| | | n + 2 | Tracking zero time 0 (OFF) / 1 to 99 | |
| Tracking zero width setting | 1 - 8 (PLC1 - 8) | n | Station number | 3 |
| | | n + 1 | Command: 43 | |
| | | n + 2 | Tracking zero width 0 (OFF) / 1 to 99 | |
| Sensor power response | 1 - 8 (PLC1 - 8) | n | Station number | 2 |
| | | n + 1 | Command: 44 | |
| | | n + 2 | Sensor power 0: 5 V 1: 10 V | |
| Sensor power setting | 1 - 8 (PLC1 - 8) | n | Station number | 3 |
| | | n + 1 | Command: 45 | |
| | | n + 2 | Sensor power 0: 5 V 1: 10 V | |
| Power-on delay time response | 1 - 8 (PLC1 - 8) | n | Station number | 2 |
| | | n + 1 | Command: 46 | |
| | | n + 2 | Power-on delay time 0 (OFF) / 1 to 30 | |

| Contents | F0 | F1 (= \$u n) | | F2 |
|---|---------------------|--------------|---|----|
| Power-on delay time setting | 1 - 8 (PLC1 - 8) | n | Station number | 3 |
| | | n + 1 | Command: 47 | |
| | | n + 2 | Power-on delay time 0 (OFF) / 1 to 30 | |
| Protection response | 1 - 8 (PLC1 - 8) | n | Station number | 2 |
| | | n + 1 | Command: 48 | |
| | | n + 2 | Protect 0: OFF 1: ON | |
| Protection setting | 1 - 8 (PLC1 - 8) | n | Station number | 3 |
| | | n + 1 | Command: 49 | |
| | | n + 2 | Protect 0: OFF 1: ON | |
| Unit No. response | 1 - 8 (PLC1 - 8) | n | Station number | 2 |
| | | n + 1 | Command: 50 | |
| | | n + 2 | Input unit number 1 to 18 | |
| | | n + 3 | Output unit number 0 to 7 | |
| Response to prohibition of key operations | 1 - 8 (PLC1 - 8) | n | Station number | 2 |
| | | n + 1 | Command: 51 | |
| | | n + 2 | Prohibition of key operations 0: OFF 1: ON | |
| Prohibition of key operations setting | 1 - 8 (PLC1 - 8) | n | Station number | 3 |
| | | n + 1 | Command: 52 | |
| | | n + 2 | Prohibition of key operations 0: OFF 1: ON | |
| Response to linearizing function status | 1 - 8 (PLC1 - 8) | n | Station number | 2 |
| | | n + 1 | Command: 53 | |
| | | n + 2 | Linearizing function 0: OFF 1: ON 2: CLR | |
| Linearizing function status setting | 1 - 8 (PLC1 - 8) | n | Station number | 3 |
| | | n + 1 | Command: 54 | |
| | | n + 2 | Linearizing function 0: OFF 1: ON 2: CLR | |
| Response to the number of linearization correction data | 1 - 8 (PLC1 - 8) | n | Station number | 2 |
| | | n + 1 | Command: 55 | |
| | | n + 2 | Linearization correction data 0 (clear) to 16 | |
| The number of linearization correction data setting | 1 - 8 (PLC1 - 8) | n | Station number | 3 |
| | | n + 1 | Command: 56 | |
| | | n + 2 | Linearization correction data 1 to 16 | |

| Contents | F0 | F1 (= \$u n) | | F2 |
|--------------------------------|---|--------------|---|----|
| Response to linearization data | 1 - 8 (PLC1 - 8) | n | Station number | 4 |
| | | n + 1 | Command: 57 | |
| | | n + 2 | Read start number 1 to 16 | |
| | | n + 3 | The number of read data 1 to 16 | |
| | | n + 4 | Linearization data input value (start number + 0) | |
| | | n + 5 | Linearization data output value (start number + 0) | |
| | | n + 6 | Linearization data input value (start number + 1) | |
| | | n + 7 | Linearization data output value (start number + 1) | |
| | | n + 8 | Linearization data input value (start number + 2) | |
| | | n + 9 | Linearization data output value (start number + 2) | |
| | | n + 10 | Linearization data input value (start number + 3) | |
| | | n + 11 | Linearization data output value (start number + 3) | |
| | | n + 12 | Linearization data input value (start number + 4) | |
| | | n + 13 | Linearization data output value (start number + 4) | |
| | | n + 14 | Linearization data input value (start number + 5) | |
| | | n + 15 | Linearization data output value (start number + 5) | |
| | | n + 16 | Linearization data input value (start number + 6) | |
| | | n + 17 | Linearization data output value (start number + 6) | |
| | | n + 18 | Linearization data input value (start number + 7) | |
| | | n + 19 | Linearization data output value (start number + 7) | |
| | | n + 20 | Linearization data input value (start number + 8) | |
| | | n + 21 | Linearization data output value (start number + 8) | |
| | | n + 22 | Linearization data input value (start number + 9) | |
| | | n + 23 | Linearization data output value (start number + 9) | |
| | | n + 24 | Linearization data input value (start number + 10) | |
| | | n + 25 | Linearization data output value (start number + 10) | |
| | | n + 26 | Linearization data input value (start number + 11) | |
| | | n + 27 | Linearization data output value (start number + 11) | |
| | | n + 28 | Linearization data input value (start number + 12) | |
| | | n + 29 | Linearization data output value (start number + 12) | |
| | | n + 30 | Linearization data input value (start number + 13) | |
| | | n + 31 | Linearization data output value (start number + 13) | |
| | | n + 32 | Linearization data input value (start number + 14) | |
| | | n + 33 | Linearization data output value (start number + 14) | 4 |
| | | n + 34 | Linearization data input value (start number + 15) | |
| n + 35 | Linearization data output value (start number + 15) | | | |

| Contents | F0 | F1 (= \$u n) | | F2 |
|----------------------------|---|--------------|---|--------------|
| Linearization data setting | 1 - 8 (PLC1 - 8) | n | Station number | 6 , 36 |
| | | n + 1 | Command: 58 | |
| | | n + 2 | Read start number 1 to 16 | |
| | | n + 3 | The number of read data 1 to 16 | |
| | | n + 4 | Linearization data input value (start number + 0) | |
| | | n + 5 | Linearization data output value (start number + 0) | |
| | | n + 6 | Linearization data input value (start number + 1) | |
| | | n + 7 | Linearization data output value (start number + 1) | |
| | | n + 8 | Linearization data input value (start number + 2) | |
| | | n + 9 | Linearization data output value (start number + 2) | |
| | | n + 10 | Linearization data input value (start number + 3) | |
| | | n + 11 | Linearization data output value (start number + 3) | |
| | | n + 12 | Linearization data input value (start number + 4) | |
| | | n + 13 | Linearization data output value (start number + 4) | |
| | | n + 14 | Linearization data input value (start number + 5) | |
| | | n + 15 | Linearization data output value (start number + 5) | |
| | | n + 16 | Linearization data input value (start number + 6) | |
| | | n + 17 | Linearization data output value (start number + 6) | |
| | | n + 18 | Linearization data input value (start number + 7) | |
| | | n + 19 | Linearization data output value (start number + 7) | |
| | | n + 20 | Linearization data input value (start number + 8) | |
| | | n + 21 | Linearization data output value (start number + 8) | |
| | | n + 22 | Linearization data input value (start number + 9) | |
| | | n + 23 | Linearization data output value (start number + 9) | |
| | | n + 24 | Linearization data input value (start number + 10) | |
| | | n + 25 | Linearization data output value (start number + 10) | |
| | | n + 26 | Linearization data input value (start number + 11) | |
| | | n + 27 | Linearization data output value (start number + 11) | |
| | | n + 28 | Linearization data input value (start number + 12) | |
| | | n + 29 | Linearization data output value (start number + 12) | |
| | | n + 30 | Linearization data input value (start number + 13) | |
| | | n + 31 | Linearization data output value (start number + 13) | |
| | | n + 32 | Linearization data input value (start number + 14) | |
| | | n + 33 | Linearization data output value (start number + 14) | |
| | | n + 34 | Linearization data input value (start number + 15) | |
| n + 35 | Linearization data output value (start number + 15) | | | |

Return data: Data stored from the panel meter to the V9

16.2.28 APR-N (MODBUS RTU)

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|--|---------|
| Connection Mode | 1 : 1 / <u>1:n</u> / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet) | |
| Signal Level | RS-422/485 | |
| Baud Rate | 4800 / <u>9600</u> / 19200 / 38400 bps | |
| Data Length | 8 bits | |
| Stop Bit | <u>1</u> / 2 bits | |
| Parity | None / Even / <u>Odd</u> | |
| Target Port No. | <u>1</u> to 31 | |

AC Power Regulator

The communication parameter can be set using keys attached to the front of the AC power regulator. Be sure to match the settings to those made under [Communication Setting] of the editor.

(Underlined setting: default)

| Function Code | Item | Setting | Example |
|---------------|-----------------------------------|--|---------|
| 6.o02 | Setting device selection* | <u>APd: Setting indicator</u> nEt: Network device APr: APR main unit | nEt |
| 7.n01 | Communication protocol selection* | <u>m-S: Master / slave parallel operation</u> nEt: MODBUS RTU | nEt |
| 7.n02 | Station address | A000: 0 , A031: 31 (default: A001: 1) | A001 |
| 7.n04 | Baud rate selection | 4800: 4800 bps <u>9600: 9600 bps</u> 1.920: 19200 bps 3.840: 38400 bps | 9600 |
| 7.n05 | Parity bit + Stop bit selection | P0: Without parity, Stop bit 2 bits P1: Even parity, Stop bit 1 bits <u>P2: Odd parity, Stop bit 1 bits</u> P3: Without parity, Stop bit 1 bits | P2 |

*1 For communication with V9, select "Network device" for the setting device selection and "MODBUS RTU" for the communication protocol selection on this regulator.

*2 The communication parameter (data length) is fixed to 8 bits.

Available Device Memory

The available setting range of device memory varies depending on the model. Be sure to set within the range available for the model to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|---------------|------|--------------|
| --- | 02H | Byte address |

Indirect Device Memory Designation

- For word designation, specify the device memory No. (address) in even address.
Example: To make the setting of "output setting" for the function code 1.b01;
Specify "2" in the device memory No. (address).
- For bit designation, it is possible to specify the device memory No. (address) in both even and odd address.
Specify "00H" for the extensional code because the setting range for the bit address is 0 to 7.
Example: To make the setting of "gradient setting selection" for the function code 1.b09;
Specify "1" in the device memory No. (address), "00H" for the extensional code, and "00" or "01" in the bit No..

16.2.29 ALPHA5 (MODBUS RTU)

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|---|---------|
| Connection Mode | <u>1</u> : 1 / <u>1:n</u> / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet) | |
| Signal Level | RS-422/485 | |
| Baud Rate | 9600 / 19200 / <u>38400</u> bps | |
| Data Length | 8 bits | |
| Stop Bit | <u>1</u> / 2 bits | |
| Parity | None / <u>Even</u> / Odd | |
| Target Port No. | <u>1</u> to 31 | |

Servo Amplifier

Set communication parameters.

Be sure to match the settings to those made under [Communication Setting] of the editor.

(Underlined setting: default)

| Parameter | Item | Setting | Example |
|--|-----------------|-----------------------------------|---|
| PA2 Extensional Function Setting | PA2_72 (No. 72) | Station number | <u>1</u> to 31 |
| | PA2_73 (No. 73) | Baud rate | <u>0</u> : 38400 bps 1: 19200 bps 2: 9600 bps |
| | PA2_93 (No. 93) | Parity bit / Stop bit selection | <u>0</u> : <u>Even parity, Stop bit 1 bits</u> 1: Odd parity, Stop bit 1 bits 2: Without parity, Stop bit 1 bits 3: Even parity, Stop bit 2 bits 4: Odd parity, Stop bit 2 bits 5: Without parity, Stop bit 2 bits |
| | PA2_97 (No. 97) | Communication protocol selection* | <u>0</u> : PC Loader protocol 1: MODBUS RTU |

*1 For communication with V9, select "MODBUS RTU" for the communication protocol selection on the servo amplifier.

*2 The communication parameter (data length) is fixed to 8 bits.

Available Device Memory

The available setting range of device memory varies depending on the model. Be sure to set within the range available for the model to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|---------------------------------------|------|------------------------|
| 00 (communication CONT / OUT signals) | 00H | Double-word* |
| 01 (monitor) | 01H | Double-word, read only |
| 02 (sequence monitor) | 02H | Double-word, read only |
| 03 (various commands) | 03H | Double-word |
| 04 (parameter) | 04H | Double-word |
| 05 (immediate value data) | 05H | Double-word |

* Communication OUT signal is read only.

PLC_CTL

| Contents | F0 | F1 (= \$u n) | | F2 | |
|--------------------------|--------------------------|--------------|--|-------|---|
| Positioning data reading | 1 - 8 (PLC1 - 8) | n | Station number | 4 | |
| | | n+1 | Command: 03 (HEX) | | |
| | | n+2 | Reading device memory address | | |
| | | n+3 | Reading positioning data count: m (1 to 9) | | |
| | | n+4 | Positioning data m = 1 | | Positioning status and M code Bit 15 to 8 7 6 5 4 3 2 1 0 M code output timing Not used M code valid/invalid Step mode Command mode |
| | | n+5 | | | Stop timer |
| | | n+6 to n+7 | | | Stop position |
| | | n+8 to n+9 | | | Rotation speed |
| | | n+10 to n+11 | | | Acceleration time |
| | | n+12 to n+13 | | | Deceleration time |
| n+14 to n+(3+10m) | Positioning data (m = 2) | | | | |
| Positioning data writing | 1 - 8 (PLC1 - 8) | n | Station number *1 | 4+10m | |
| | | n+1 | Command: 10 (HEX) | | |
| | | n+2 | Writing device memory address | | |
| | | n+3 | Writing positioning data count: m (1 to 9) | | |
| | | n+4 | Positioning data m = 1 | | Positioning status and M code Bit 15 to 8 7 6 5 4 3 2 1 0 M code output timing Not used M code valid/invalid Step mode Command mode |
| | | n+5 | | | Stop timer |
| | | n+6 to n+7 | | | Stop position |
| | | n+8 to n+9 | | | Rotation speed |
| | | n+10 to n+11 | | | Acceleration time |
| | | n+12 to n+13 | | | Deceleration time |
| n+14 to n+(3+10m) | Positioning data (m = 2) | | | | |

*1 Select station No. 0 for broadcast commands.

Return data: Data stored from the servo amplifier to the V9

16.2.30 ALPHA5 Smart (MODBUS RTU)

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|--|---------|
| Connection Mode | 1 : 1 / <u>1:n</u> / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet) | |
| Signal Level | RS-422/485 | |
| Baud Rate | 9600 / 19200 / <u>38400</u> / 115K bps | |
| Data Length | 8 bits | |
| Stop Bit | <u>1</u> / 2 bits | |
| Parity | None / <u>Even</u> / Odd | |
| Target Port No. | <u>1</u> to 31 | |

Servo Amplifier

Set communication parameters.

Be sure to match the settings to those made under [Communication Setting] of the editor.

(Underlined setting: default)

| Parameter | Item | Setting | Example |
|-------------------------------------|-----------------|---------------------------------------|--|
| PA2 Extended function setting | PA2_72 (No. 72) | Station number | <u>1</u> to 31 |
| | PA2_73 (No. 73) | Baud rate | <u>0</u> : 38400 bps 1: 19200 bps 2: 9600 bps 3: 115200 bps |
| | PA2_93 (No. 93) | Parity bit and stop bit selection | <u>0</u> : Even parity, stop bit 1 1: Odd parity, stop bit 1 2: Without parity, stop bit 1 3: Even parity, stop bit 2 4: Odd parity, stop bit 2 5: Without parity, stop bit 2 |
| | PA2_97 (No. 97) | Communication protocol selection*1 | <u>0</u> : PC loader protocol 1: MODBUS RTU |

*1 For communication with a V9, select "MODBUS RTU" for the communication protocol.

*2 The communication parameter (data length) is fixed to 8 bits.

Available Device Memory

The available setting range of device memory varies depending on the model. Be sure to set within the range available for the model to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|------------------------------------|------|------------------------|
| 00 (communication CONT/OUT signal) | 00H | Double-word *1 |
| 01 (monitor) | 01H | Double-word, read only |
| 02 (sequence monitor) | 02H | Double-word, read only |
| 03 (various commands) | 03H | Double-word |
| 04 (parameter) | 04H | Double-word |
| 05 (immediate data) | 05H | Double-word |

*1 Communication OUT signal: Read only

PLC_CTL

| Contents | F0 | F1 (= \$u n) | | F2 | | | | | | | | | | |
|-----------------------------|--------------------------|--------------|---|-------|---|--------|---|---|---|---|---|---|---|---|
| Reading of positioning data | 1 - 8 (PLC1 - 8) | n | Station number | 4 | | | | | | | | | | |
| | | n+1 | Command: 03 (HEX) | | | | | | | | | | | |
| | | n+2 | Reading address | | | | | | | | | | | |
| | | n+3 | Number of positioning data to read: m (1 to 9) | | | | | | | | | | | |
| | | n+4 | Positioning data m = 1 | | Positioning status & M code Bit <table border="1" style="display: inline-table; vertical-align: middle;"> <tr> <td>15 - 8</td> <td>7</td> <td>6</td> <td>5</td> <td>4</td> <td>3</td> <td>2</td> <td>1</td> <td>0</td> </tr> </table> M code (bits 15-8) Not used (bits 7-6) Command method / Step mode (bits 5-4) Not used (bits 3-2) M code Valid/invalid (bits 1-0) M code output timing (bits 1-0) | 15 - 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | | 15 - 8 | | | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | | |
| | | n+5 | | | Stop timer | | | | | | | | | |
| | | n+6 to n+7 | | | Stop position | | | | | | | | | |
| | | n+8 to n+9 | | | Rotation speed | | | | | | | | | |
| | | n+10 to n+11 | | | Acceleration time | | | | | | | | | |
| n+12 to n+13 | Deceleration time | | | | | | | | | | | | | |
| n+14 to n+(3+10m) | Positioning data (m = 2) | | | | | | | | | | | | | |
| Writing of positioning data | 1 - 8 (PLC1 - 8) | n | Station number *1 | 4+10m | | | | | | | | | | |
| | | n+1 | Command: 10 (HEX) | | | | | | | | | | | |
| | | n+2 | Writing address | | | | | | | | | | | |
| | | n+3 | Number of positioning data to write: m (1 to 9) | | | | | | | | | | | |
| | | n+4 | Positioning data m = 1 | | Positioning status & M code Bit <table border="1" style="display: inline-table; vertical-align: middle;"> <tr> <td>15 - 8</td> <td>7</td> <td>6</td> <td>5</td> <td>4</td> <td>3</td> <td>2</td> <td>1</td> <td>0</td> </tr> </table> M code (bits 15-8) Not used (bits 7-6) Command method / Step mode (bits 5-4) Not used (bits 3-2) M code Valid/invalid (bits 1-0) M code output timing (bits 1-0) | 15 - 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | | 15 - 8 | | | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | | |
| | | n+5 | | | Stop timer | | | | | | | | | |
| | | n+6 to n+7 | | | Stop position | | | | | | | | | |
| | | n+8 to n+9 | | | Rotation speed | | | | | | | | | |
| | | n+10 to n+11 | | | Acceleration time | | | | | | | | | |
| n+12 to n+13 | Deceleration time | | | | | | | | | | | | | |
| n+14 to n+(3+10m) | Positioning data (m = 2) | | | | | | | | | | | | | |

*1 Select station No. 0 for broadcast commands.

Return data: Data stored from servo amplifier to V9 series

16.2.31 WE1MA (Ver. A) (MODBUS RTU)

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|--|--------------|
| Connection Mode | 1 : <u>1:n</u> / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet) | |
| Signal Level | RS-422/485 | |
| Baud Rate | 4800 / <u>9600</u> / 19200 / 38400 bps | |
| Data Length | 8 bits | |
| Stop Bit | <u>1</u> / 2 bits | |
| Parity | None / <u>Even</u> / Odd | |
| Target Port No. | 0 to 247 | 0: Broadcast |

Electronic Multimeter

The communication parameter can be set using keys attached to the front of the electronic multimeter. Be sure to match the settings to those made under [Communication Setting] of the editor.

(Underlined setting: default)

| Setting Component | Setting No. | Item | Setting | Example |
|-------------------|-------------|------------------|--|---------|
| Adr | 231C | Station address | <u>1</u> to 247 | 1 |
| bPS | 232C | Baud rate | 4800 / <u>9600</u> / 19200 / 38400 bps | 9600 |
| PAr | 233C | Parity bit | <u>E</u> : Even o: Odd -: None | E |
| StoP | 234C | Stop bit | <u>1</u> / 2 bits | 1 |
| WEr | 235C | Protocol version | A: Version A | A |

* The communication parameter (data length) is fixed to 8 bits.

Available Device Memory

The available setting range of device memory varies depending on the model. Be sure to set within the range available for the model to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|----------------------|------|-----------|
| 1 (input relay) | 01H | Read only |
| 4 (holding register) | 02H | |
| 3 (input register) | 03H | Read only |

16.2.32 WE1MA (Ver. B) (MODBUS RTU)

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|--|--------------|
| Connection Mode | 1 : 1 / <u>1:n</u> / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet) | |
| Signal Level | RS-422/485 | |
| Baud Rate | 4800 / <u>9600</u> / 19200 / 38400 bps | |
| Data Length | 8 bits | |
| Stop Bit | <u>1</u> / 2 bits | |
| Parity | None / <u>Even</u> / Odd | |
| Target Port No. | 0 to 247 | 0: Broadcast |

Electronic Multimeter

Communication parameters can be set by operating the front-mounted keys of the electronic multimeter. Be sure to match the settings to those made under [Communication Setting] of the editor.

(Underlined setting: default)

| Setting Component | Setting No. | Item | Setting | Example |
|-------------------|-------------|------------------|--|---------|
| Adr | 231C | Address | <u>1</u> to 247 | 1 |
| bPS | 232C | Baud rate | 4800 / <u>9600</u> / 19200 / 38400 bps | 9600 |
| PAr | 233C | Parity | <u>E</u> : Even o: Odd -: None | E |
| StoP | 234C | Stop bit | <u>1</u> / 2 bits | 1 |
| WEr | 235C | Protocol version | B : Version B | B |

* The communication parameter (data length) is fixed to 8 bits.

Available Device Memory

The available setting range of device memory varies depending on the model. Be sure to set within the range available for the model to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|----------------------|------|-----------|
| 4 (holding register) | 02H | |
| 3 (input register) | 03H | Read only |

16.2.33 WSZ Series

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|--|---------|
| Connection Mode | <u>1 : 1</u> / 1 : n / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet) | |
| Signal Level | <u>RS-232C</u> / RS-422/485 | |
| Baud Rate | 4800 / <u>9600</u> / 19200 / 38400 / 57600 / 76800 / 115k bps | |
| Data Length | <u>7</u> / 8 bits | |
| Stop Bit | <u>1</u> / 2 bits | |
| Parity | None / <u>Even</u> / Odd | |
| Target Port No. | <u>1</u> to 254 | |

WSZ Series

Make settings for the controller by using the software "WinProladder". For more information, refer to the instruction manual of the controller issued by the manufacturer.

Station Number

(Underlined setting: default)

| Setting Items | Setting | Remarks |
|----------------|-----------------|---------|
| Station Number | <u>1</u> to 254 | |

PORT 0

Comm. Parameters Setting - Port 0

(Underlined setting: default)

| Setting Items | Setting | Remarks |
|---------------|--|--|
| Baud Rate | <u>9600</u> / 19200 / 38400 / 57600 / 115200 | The baud rate can also be set by specifying a value for the designated address. For more information, refer to the instruction manual of the controller issued by the manufacturer. |

* The following settings are fixed; data length: 7, stop bit: 1, parity: even, and protocol: Fatek Communication protocol.

WSZ-CB25 (PORT 1 / PORT 2)

Comm. Parameters Setting - Port 1 / Port 2

(Underlined setting: default)

| Setting Items | Setting | Remarks |
|---------------|---|--|
| Baud Rate | 4800 / <u>9600</u> / 19200 / 38400 / 57600 / 76800 / 115200 | The baud rate can also be set by specifying a value for the designated address. For more information, refer to the instruction manual of the controller issued by the manufacturer. |
| Parity | None / <u>Even</u> / Odd | |
| Data Bit | <u>7</u> / 8 | |
| Stop Bit | <u>1</u> / 2 | |
| Protocol | Fatek Communication protocol | |

DIPSW

| Setting Items | Setting | Remarks |
|---|--|--|
| Terminating resistance  | ON: With terminating resistance OFF: Without terminating resistance | This setting must be the same for both switches. |

Calendar

This model is equipped with a calendar function; however, the calendar data cannot be written from the V series. Thus, time correction must be performed on the controller side.

Available Device Memory

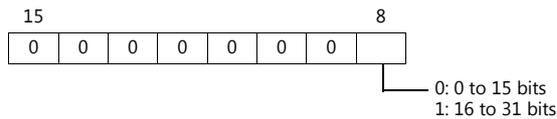
The available setting range of device memory varies depending on the model. Be sure to set within the range available for the model to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|-------------------------------------|------|-------------------|
| R (data register) | 00H | |
| D (data register) | 01H | |
| X (input relay) | 02H | WX as word device |
| Y (output relay) | 03H | WY as word device |
| M (internal relay) | 04H | WM as word device |
| S (step relay) | 05H | WS as word device |
| T (timer/contact) | 06H | WT as word device |
| C (counter/contact) | 07H | WC as word device |
| TR (timer/current value) | 08H | |
| CR (counter/current value) | 09H | |
| 32CR (32-bit counter/current value) | 0AH | Double-word |

Indirect Device Memory Designation

| | | | | |
|-------|------------------|---|-----------------|---|
| | 15 | 8 | 7 | 0 |
| n + 0 | Model | | Device type | |
| n + 1 | Address No. | | | |
| n + 2 | Expansion code * | | Bit designation | |
| n + 3 | 00 | | Station number | |

* In the expansion code, set which word, higher or lower, is to be read when a double-word address is specified.

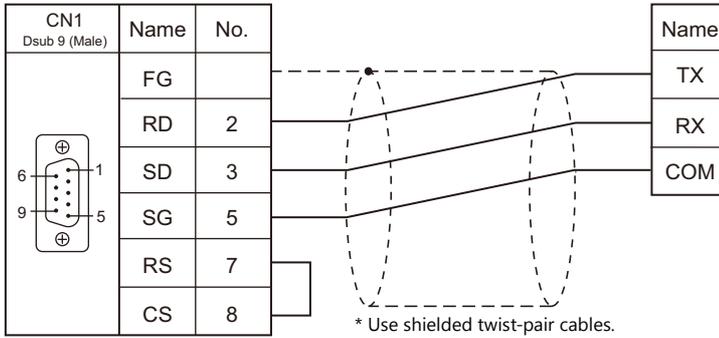


16.2.34 Wiring Diagrams

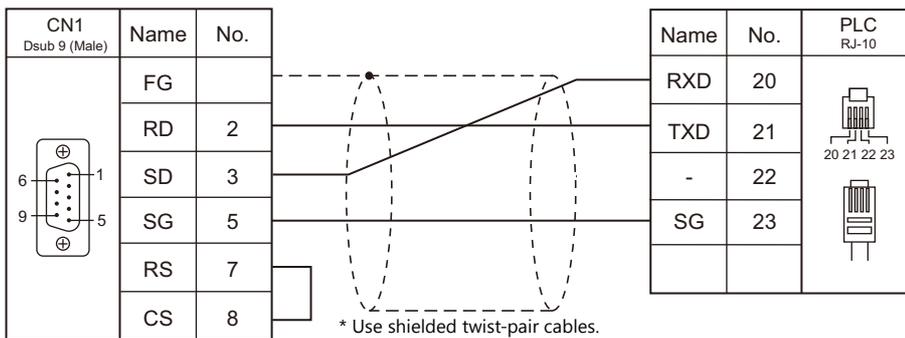
When Connected at CN1:

RS-232C

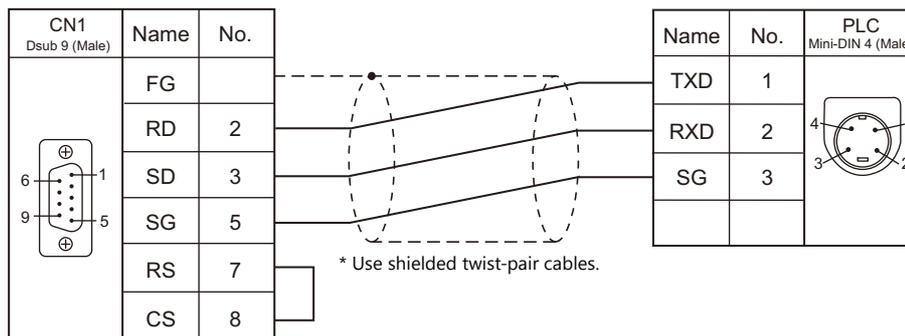
Wiring diagram 1 - C2



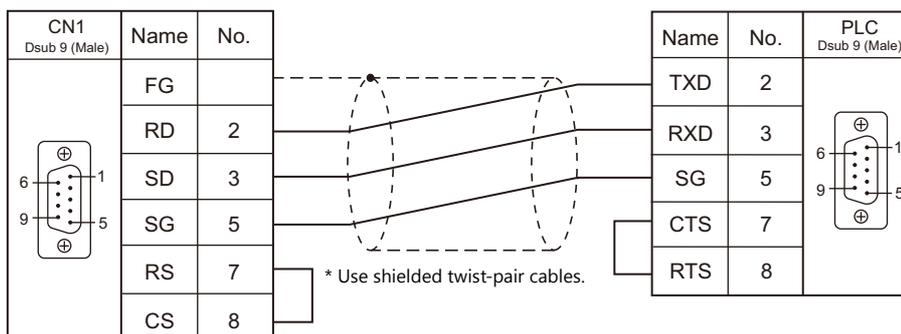
Wiring diagram 2 - C2



Wiring diagram 3 - C2

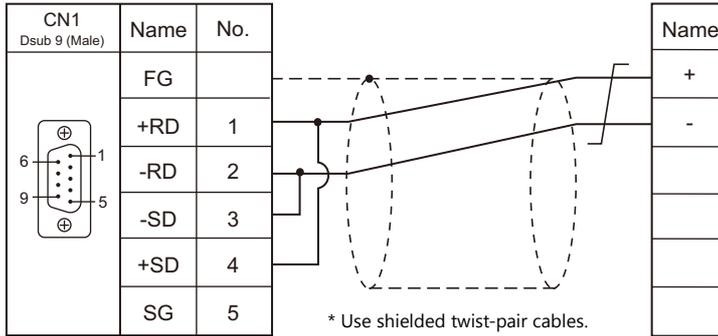


Wiring diagram 4 - C2

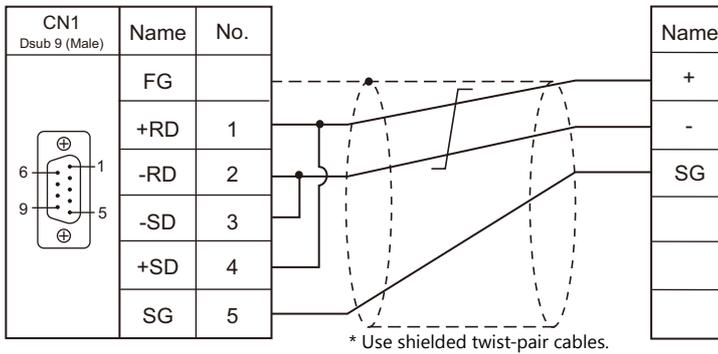


RS-422/RS-485

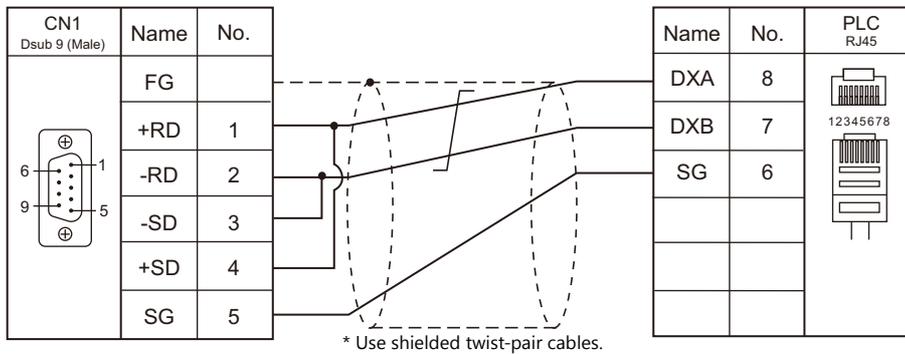
Wiring diagram 1 - C4



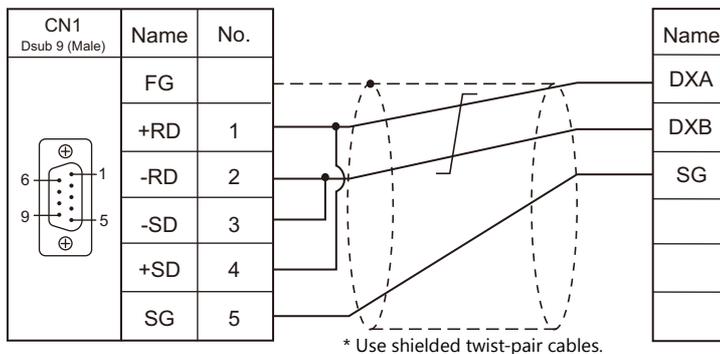
Wiring diagram 2 - C4



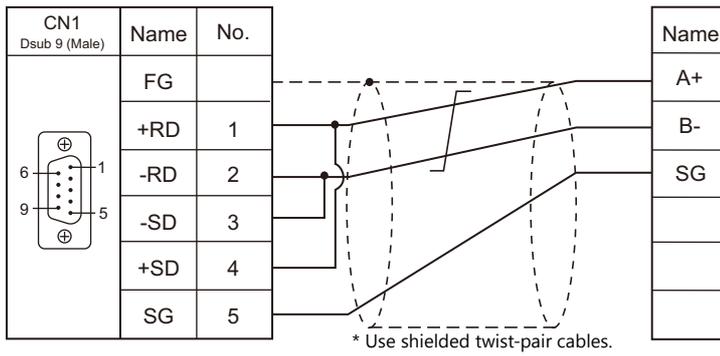
Wiring diagram 3 - C4



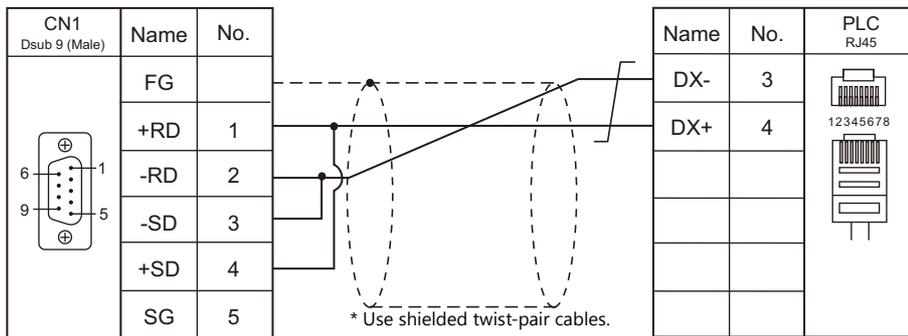
Wiring diagram 4 - C4



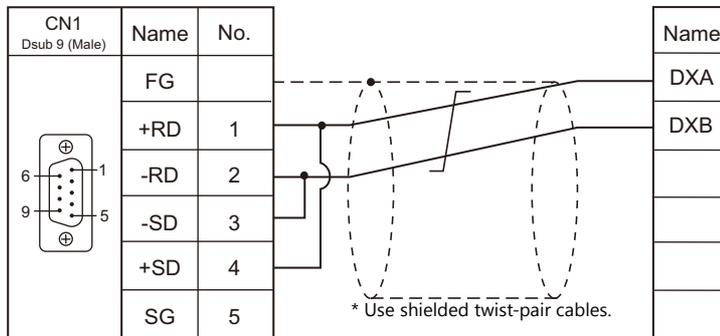
Wiring diagram 5 - C4



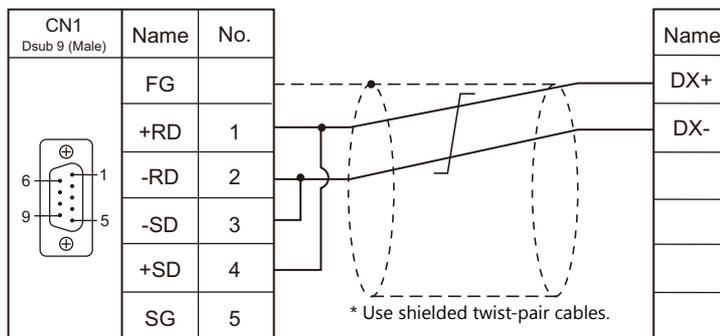
Wiring diagram 6 - C4



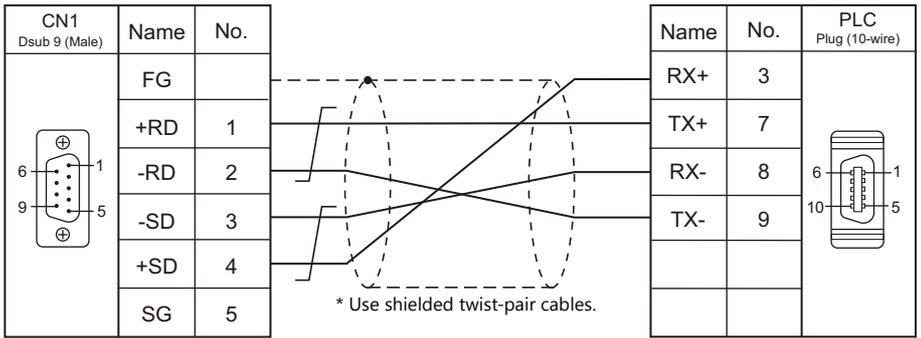
Wiring diagram 7 - C4



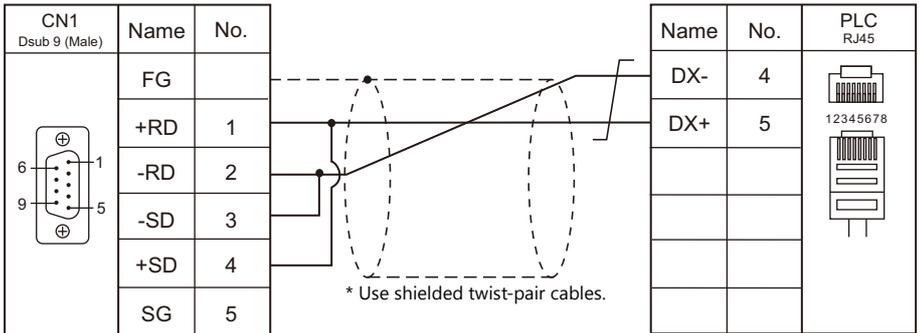
Wiring diagram 8 - C4



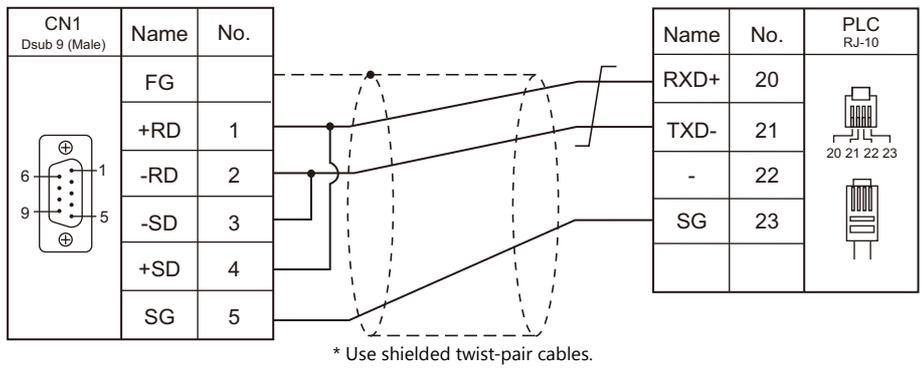
Wiring diagram 9 - C4



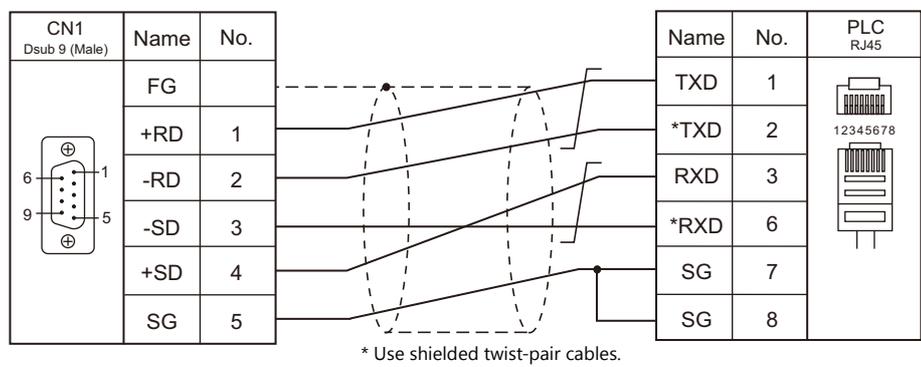
Wiring diagram 10 - C4



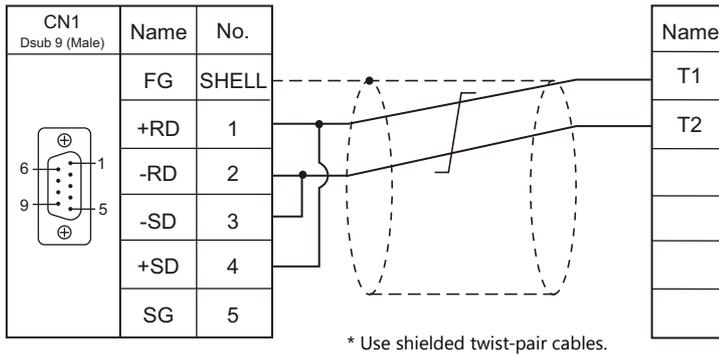
Wiring diagram 11 - C4



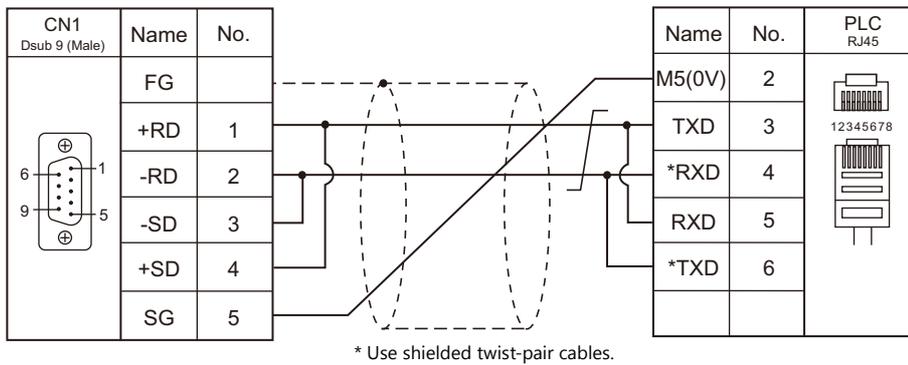
Wiring diagram 12 - C4



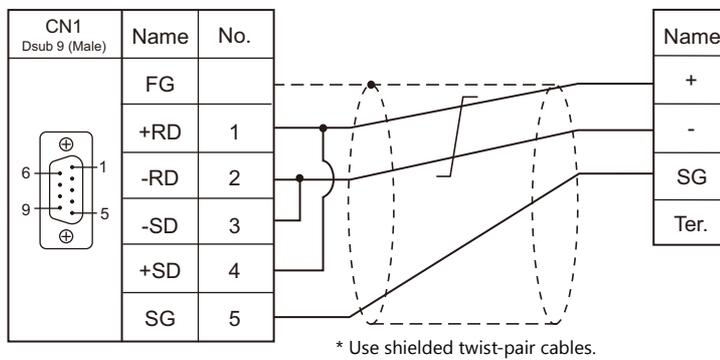
Wiring diagram 13 - C4



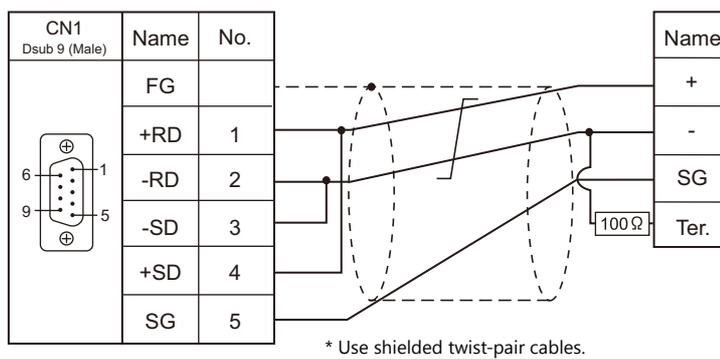
Wiring diagram 14 - C4



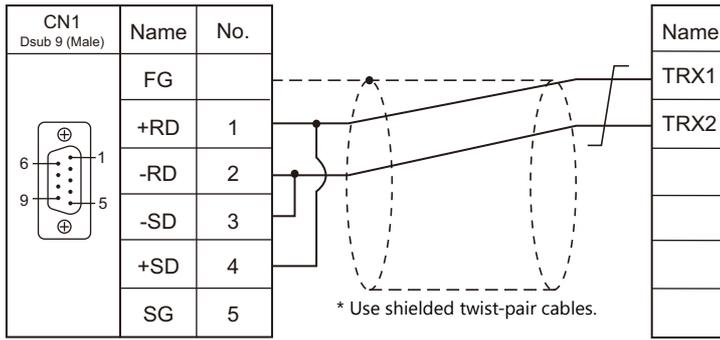
Wiring diagram 15 - C4



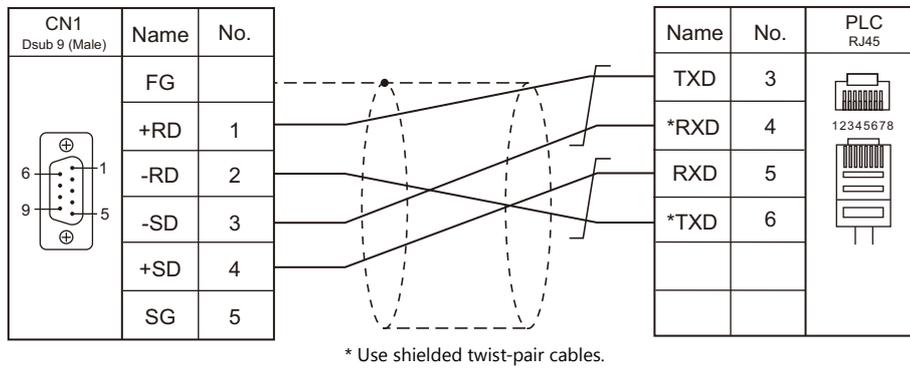
With an electronic multimeter connected at the terminal



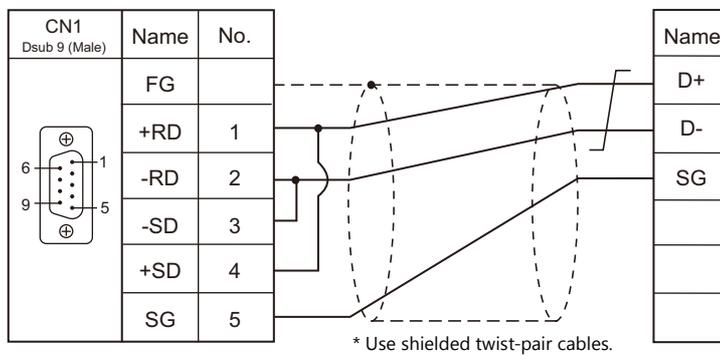
Wiring diagram 16 - C4



Wiring diagram 17 - C4



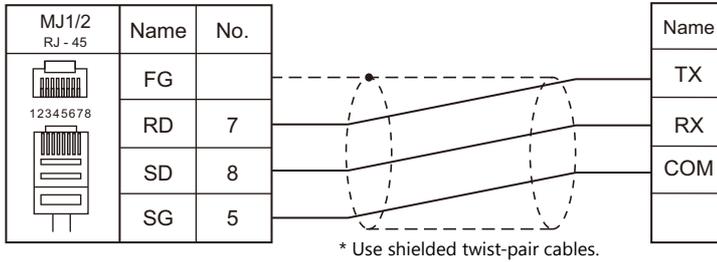
Wiring diagram 18 - C4



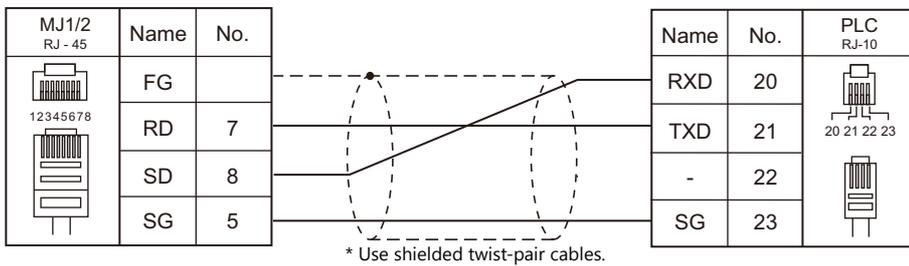
When Connected at MJ1/MJ2:

RS-232C

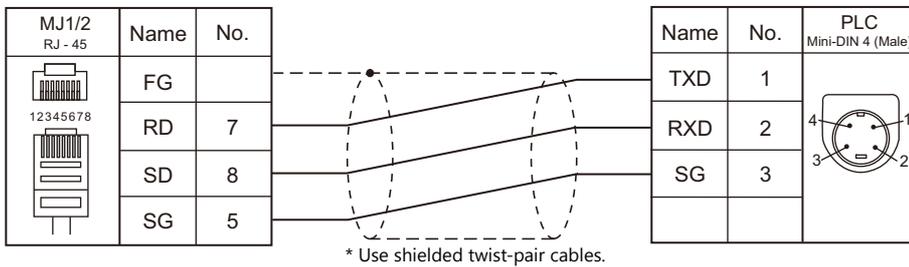
Wiring diagram 1 - M2



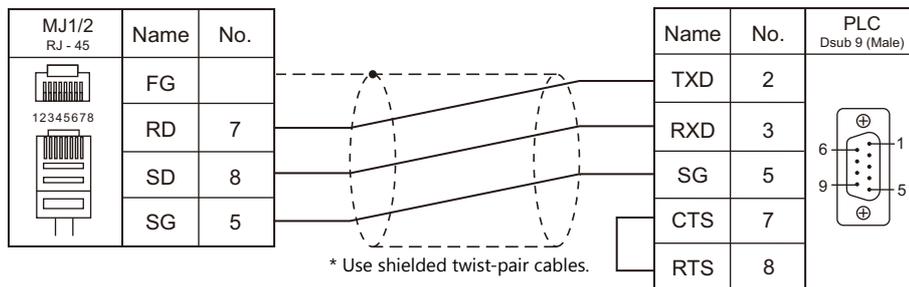
Wiring diagram 2 - M2



Wiring diagram 3 - M2

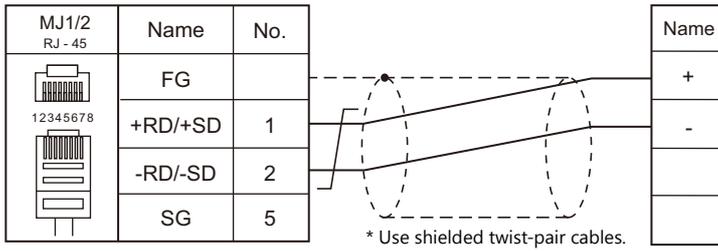


Wiring diagram 4 - M2

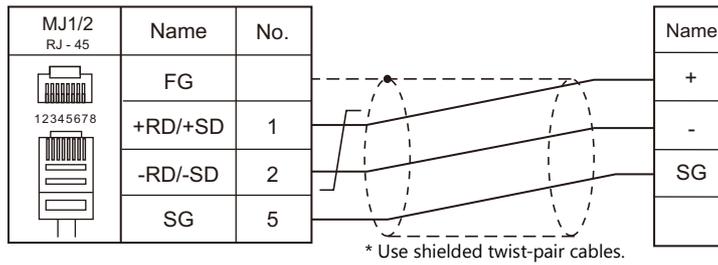


RS-422/RS-485

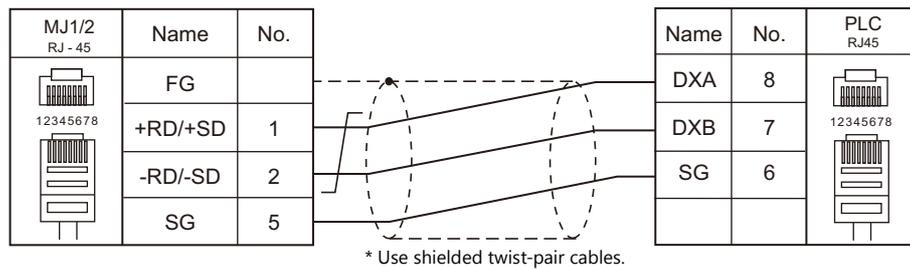
Wiring diagram 1 - M4



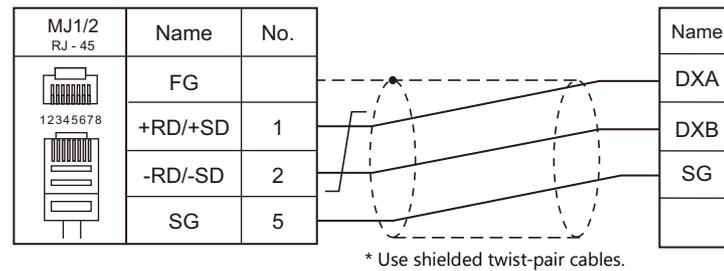
Wiring diagram 2 - M4



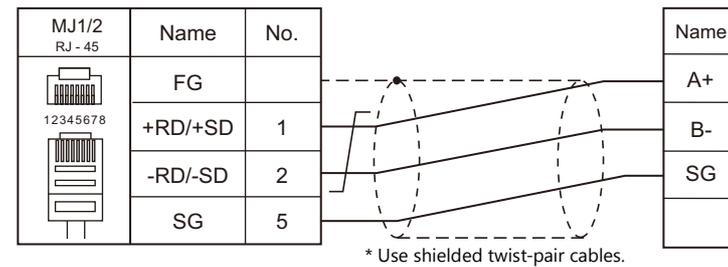
Wiring diagram 3 - M4



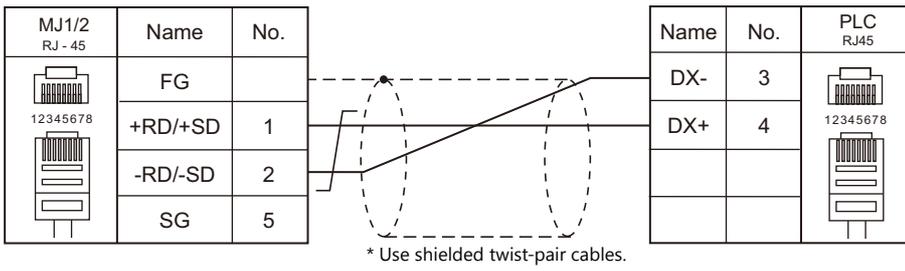
Wiring diagram 4 - M4



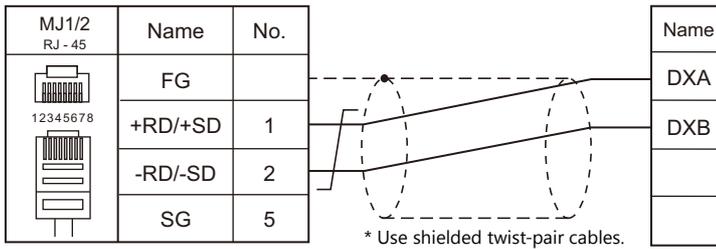
Wiring diagram 5 - M4



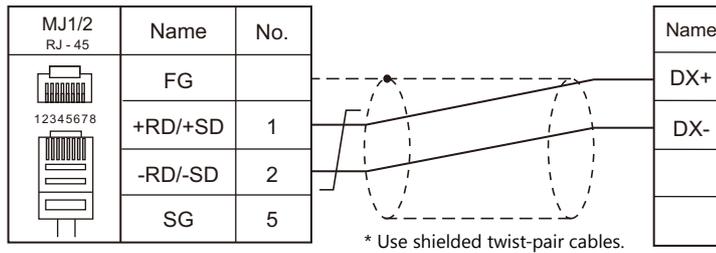
Wiring diagram 6 - M4



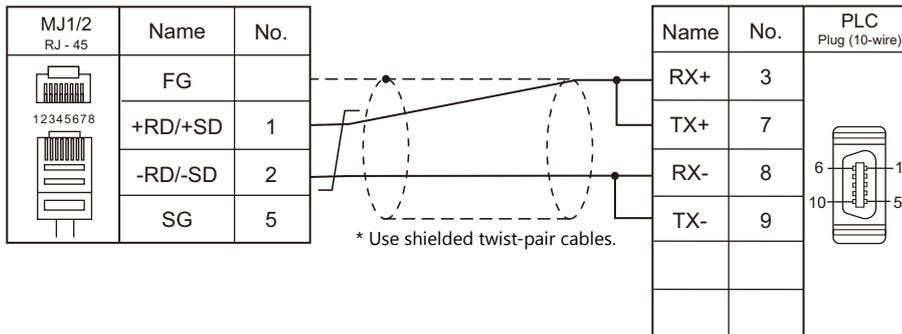
Wiring diagram 7 - M4



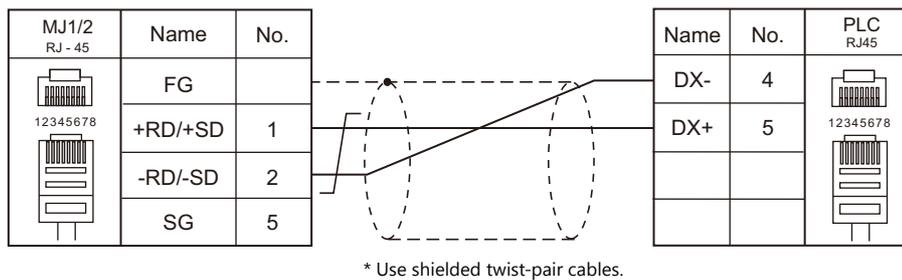
Wiring diagram 8 - M4



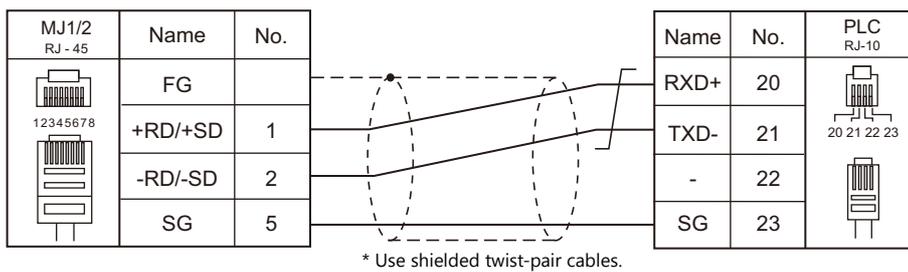
Wiring diagram 9 - M4



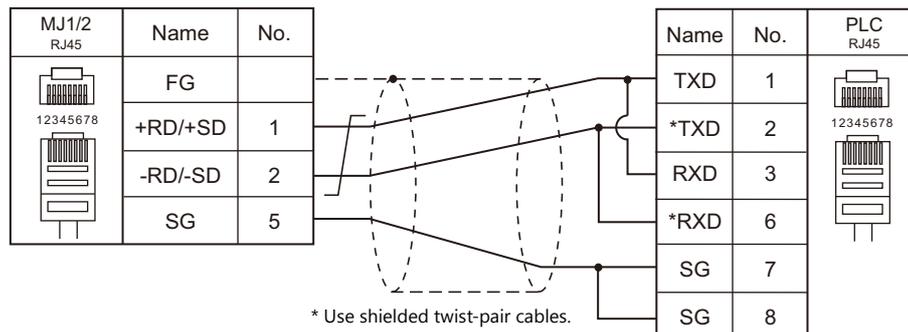
Wiring diagram 10 - M4



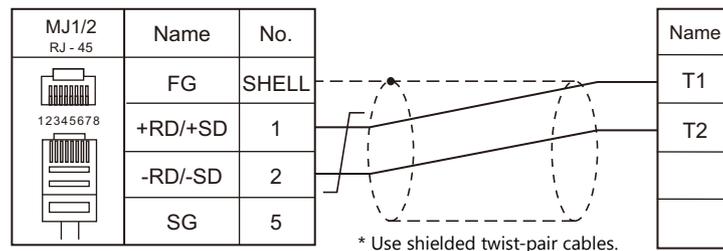
Wiring diagram 11 - M4



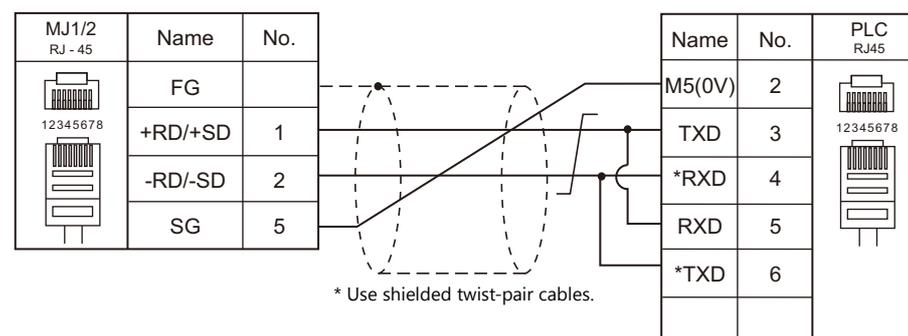
Wiring diagram 12 - M4



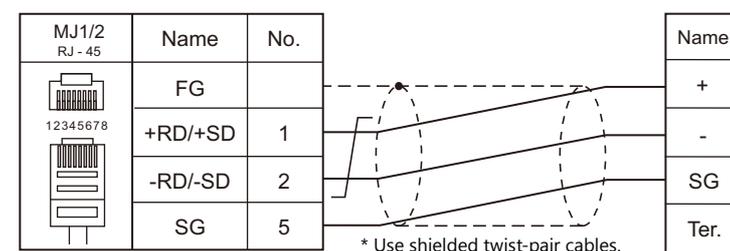
Wiring diagram 13 - M4



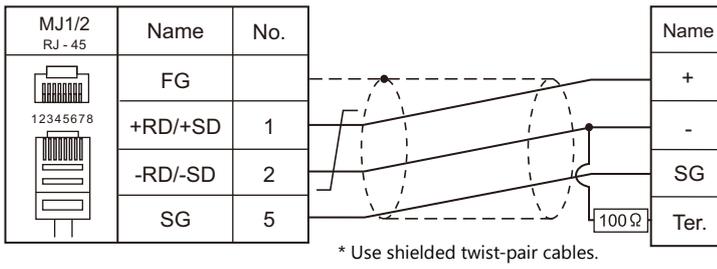
Wiring diagram 14 - M4



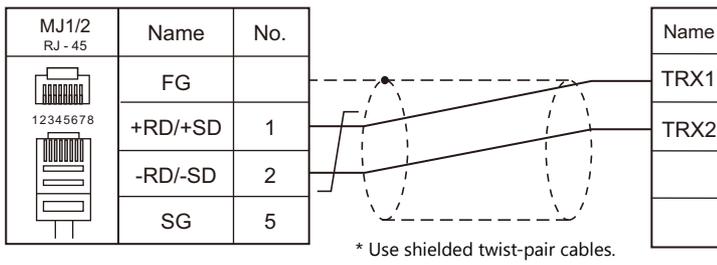
Wiring diagram 15 - M4



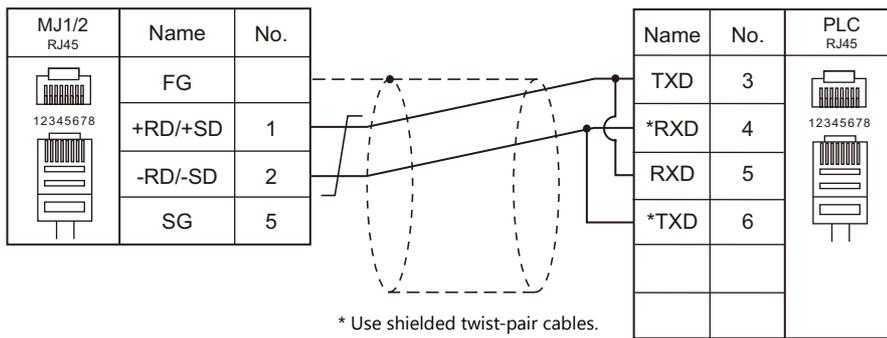
With an electronic multimeter connected at the end



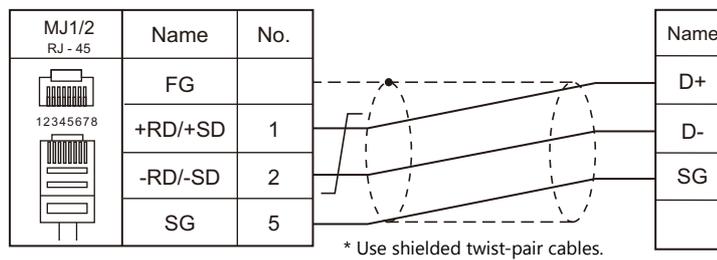
Wiring diagram 16 - M4



Wiring diagram 17 - M4



Wiring diagram 18 - M4



MEMO

Please use this page freely.

17. Gammaflux

17.1 Temperature Controller / Servo / Inverter

17.1 Temperature Controller / Servo / Inverter

Serial Connection

| PLC Selection on the Editor | Model | Port | Signal Level | Wiring Diagrams | | Lst File |
|-----------------------------|-------------------------------------|------|--------------|----------------------|-----------------------|-----------------|
| | | | | CN1 | MJ1/MJ2 | |
| TTC2100 | TTC2100-1 TTC2100-2 TTC2200-1 | COM2 | RS-485 | Wiring diagram1 - C4 | Wiring diagram 1 - M4 | TTC2100. Lst |

17.1.1 TTC2100

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|---|---------|
| Connection Mode | 1 : 1 / <u>1:n</u> / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet) | |
| Signal Level | RS-232C / <u>RS-422/485</u> | |
| Baud Rate | 57600 bps | |
| Data Length | 8 bits | |
| Stop Bit | 1 bit | |
| Parity | Not provided | |
| Target Port No. | 0 to 31 | |

Temperature Controller

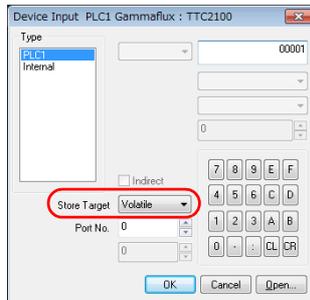
Be sure to match the settings to those made under [Communication Setting] of the editor.

Available Device Memory

The available setting range of device memory varies depending on the model. Be sure to set within the range available for the model to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|-----------------------|------|---------------------|
| TD (temperature data) | 00H | Read only |
| ZC (zone commands) | 01H | Partially read only |
| ZD (zone commands2) | 02H | Partially read only |

Specify the storage device memory.



Address denotations are as follows.

- For the TD:

Example: 0 : #0 : TD0000A

0 : Station number
 # : Command No. (HEX)
 00 : ZONE No. 00 - 3FH (1 - 64)
 0000 : Storage device memory
 0 : Volatile
 1 : Nonvolatile
 A : Station number

- For ZC, ZD:

Example: 0 : #1 : ZC000A0

0 : Station number
 # : Data No. (HEX)
 00 : Command No. (HEX)
 00 : ZONE No. 00 - 3FH (1 - 64)
 000 : Storage device memory
 0 : Volatile
 1 : Nonvolatile
 A : Station number

Indirect Device Memory Designation

| | | | | |
|-------|--------------------|---|-----------------|---|
| | 15 | 8 | 7 | 0 |
| n + 0 | Model | | Device type | |
| n + 1 | Lower address No. | | | |
| n + 2 | Higher address No. | | | |
| n + 3 | Expansion code * | | Bit designation | |
| n + 4 | 00 | | Station number | |

- Specify the ZONE number, command number, and the data number for the address number.

Example: When specifying TD1000A
 Store "1000A" as the address number.
 Lower address No. = 000A (HEX)
 Higher address No. = 0001 (HEX)

Example: When specifying ZC100A0
 Store "100A0" as the address number.
 Lower address No. = 00A0 (HEX)
 Higher address No. = 0001 (HEX)

- Specify the storage device memory address with the expansion code.
 00H: Volatile
 01H: Nonvolatile

PLC_CTL

Macro command "PLC_CTL F0 F1 F2"

| Contents | F0 | F1 (= \$u n) | F2 | | | | | | | | | |
|--|---|--------------|--|----|----|----|----|---|---|---|---|---|
| External Standby Group | 1 - 8 (PLC1 - 8) | n | Station number | | | | | | | | | |
| | | n + 1 | ZONE No.: Fixed to 0 | | | | | | | | | |
| | | n + 2 | ZONE COMMAND 008CH (Storage device memory: Volatile) 808CH (Storage device memory: Nonvolatile) | | | | | | | | | |
| | | n + 3 | Bit <table border="1" style="margin-left: 20px;"> <tr> <td>15</td><td>14</td><td style="text-align: center;">-</td><td style="text-align: center;">2</td><td style="text-align: center;">1</td><td style="text-align: center;">0</td> </tr> </table> Zone16 Zone1 | 15 | 14 | - | 2 | 1 | 0 | | | |
| | | 15 | 14 | - | 2 | 1 | 0 | | | | | |
| | | n + 4 | Bit <table border="1" style="margin-left: 20px;"> <tr> <td>15</td><td>14</td><td style="text-align: center;">-</td><td style="text-align: center;">2</td><td style="text-align: center;">1</td><td style="text-align: center;">0</td> </tr> </table> Zone32 Zone17 | 15 | 14 | - | 2 | 1 | 0 | | | |
| | | 15 | 14 | - | 2 | 1 | 0 | | | | | |
| n + 5 | Bit <table border="1" style="margin-left: 20px;"> <tr> <td>15</td><td>14</td><td style="text-align: center;">-</td><td style="text-align: center;">2</td><td style="text-align: center;">1</td><td style="text-align: center;">0</td> </tr> </table> Zone48 Zone33 | 15 | 14 | - | 2 | 1 | 0 | | | | | |
| 15 | 14 | - | 2 | 1 | 0 | | | | | | | |
| n + 6 | Bit <table border="1" style="margin-left: 20px;"> <tr> <td>15</td><td>14</td><td style="text-align: center;">-</td><td style="text-align: center;">2</td><td style="text-align: center;">1</td><td style="text-align: center;">0</td> </tr> </table> Zone64 Zone49 | 15 | 14 | - | 2 | 1 | 0 | | | | | |
| 15 | 14 | - | 2 | 1 | 0 | | | | | | | |
| Data Concentrator Resettable Alarm Relays | 1 - 8 (PLC1 - 8) | n | Station number | | | | | | | | | |
| | | n + 1 | ZONE No.: Fixed to 0 | | | | | | | | | |
| | | n + 2 | ZONE COMMAND: 91H | | | | | | | | | |
| | | n + 3 | Bit <table border="1" style="margin-left: 20px;"> <tr> <td>-</td><td>12</td><td>11</td><td>10</td><td>9</td><td>8</td><td>-</td><td>3</td><td>2</td><td>1</td><td>0</td> </tr> </table> Not used Clear Output3 Clear Output4 (Alarm Bar) Clear Overtemp Occurred Clear1, Resettable Alarm Clear2, Non-resettable Alarm Set Output3 Set Output4 (Alarm Bar) Set Output2, Non-resettable Alarm Set Output1, Resettable Alarm | - | 12 | 11 | 10 | 9 | 8 | - | 3 | 2 |
| - | 12 | 11 | 10 | 9 | 8 | - | 3 | 2 | 1 | 0 | | |

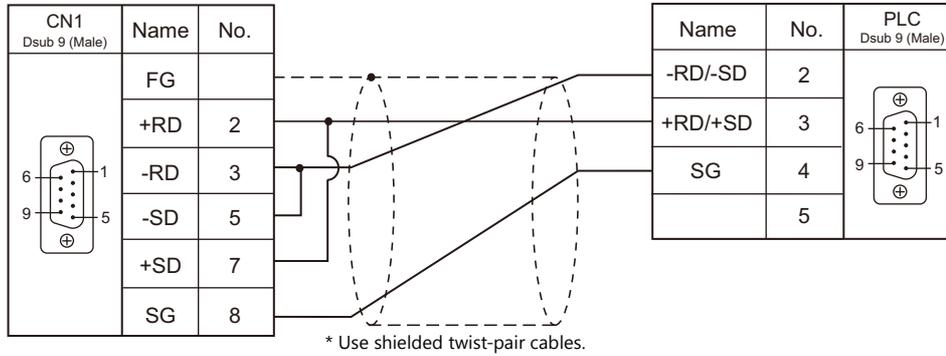
| Contents | F0 | F1 (= \$u n) | F2 | | | | | | | |
|----------------------------|---|--------------|---|---|----|----|---|---|---|---|
| Turn All Zones On/Off | 1 - 8 (PLC1 - 8) | n | Station number | 7 | | | | | | |
| | | n + 1 | ZONE No.: Fixed to 0 | | | | | | | |
| | | n + 2 | ZONE COMMAND 0099H (Storage device memory: Volatile) 8099H (Storage device memory: Nonvolatile) | | | | | | | |
| | | n + 3 | Bit <table border="1" style="margin-left: 20px;"> <tr> <td style="width: 20px;">15</td> <td style="width: 20px;">14</td> <td style="width: 40px;">-</td> <td style="width: 20px;">2</td> <td style="width: 20px;">1</td> <td style="width: 20px;">0</td> </tr> </table> <div style="margin-left: 20px;"> Zone16 Zone1 </div> | | 15 | 14 | - | 2 | 1 | 0 |
| | | 15 | 14 | | - | 2 | 1 | 0 | | |
| | | n + 4 | Bit <table border="1" style="margin-left: 20px;"> <tr> <td style="width: 20px;">15</td> <td style="width: 20px;">14</td> <td style="width: 40px;">-</td> <td style="width: 20px;">2</td> <td style="width: 20px;">1</td> <td style="width: 20px;">0</td> </tr> </table> <div style="margin-left: 20px;"> Zone32 Zone17 </div> | | 15 | 14 | - | 2 | 1 | 0 |
| | | 15 | 14 | | - | 2 | 1 | 0 | | |
| n + 5 | Bit <table border="1" style="margin-left: 20px;"> <tr> <td style="width: 20px;">15</td> <td style="width: 20px;">14</td> <td style="width: 40px;">-</td> <td style="width: 20px;">2</td> <td style="width: 20px;">1</td> <td style="width: 20px;">0</td> </tr> </table> <div style="margin-left: 20px;"> Zone48 Zone33 </div> | 15 | 14 | - | 2 | 1 | 0 | | | |
| 15 | 14 | - | 2 | 1 | 0 | | | | | |
| n + 6 | Bit <table border="1" style="margin-left: 20px;"> <tr> <td style="width: 20px;">15</td> <td style="width: 20px;">14</td> <td style="width: 40px;">-</td> <td style="width: 20px;">2</td> <td style="width: 20px;">1</td> <td style="width: 20px;">0</td> </tr> </table> <div style="margin-left: 20px;"> Zone64 Zone49 </div> | 15 | 14 | - | 2 | 1 | 0 | | | |
| 15 | 14 | - | 2 | 1 | 0 | | | | | |
| Zones Temporarily in Group | 1 - 8 (PLC1 - 8) | n | Station number | 7 | | | | | | |
| | | n + 1 | ZONE No.: Fixed to 0 | | | | | | | |
| | | n + 2 | ZONE COMMAND 009AH (Storage device memory: Volatile) 809AH (Storage device memory: Nonvolatile) | | | | | | | |
| | | n + 3 | Bit <table border="1" style="margin-left: 20px;"> <tr> <td style="width: 20px;">15</td> <td style="width: 20px;">14</td> <td style="width: 40px;">-</td> <td style="width: 20px;">2</td> <td style="width: 20px;">1</td> <td style="width: 20px;">0</td> </tr> </table> <div style="margin-left: 20px;"> Zone16 Zone1 </div> | | 15 | 14 | - | 2 | 1 | 0 |
| | | 15 | 14 | | - | 2 | 1 | 0 | | |
| | | n + 4 | Bit <table border="1" style="margin-left: 20px;"> <tr> <td style="width: 20px;">15</td> <td style="width: 20px;">14</td> <td style="width: 40px;">-</td> <td style="width: 20px;">2</td> <td style="width: 20px;">1</td> <td style="width: 20px;">0</td> </tr> </table> <div style="margin-left: 20px;"> Zone32 Zone17 </div> | | 15 | 14 | - | 2 | 1 | 0 |
| | | 15 | 14 | | - | 2 | 1 | 0 | | |
| n + 5 | Bit <table border="1" style="margin-left: 20px;"> <tr> <td style="width: 20px;">15</td> <td style="width: 20px;">14</td> <td style="width: 40px;">-</td> <td style="width: 20px;">2</td> <td style="width: 20px;">1</td> <td style="width: 20px;">0</td> </tr> </table> <div style="margin-left: 20px;"> Zone48 Zone33 </div> | 15 | 14 | - | 2 | 1 | 0 | | | |
| 15 | 14 | - | 2 | 1 | 0 | | | | | |
| n + 6 | Bit <table border="1" style="margin-left: 20px;"> <tr> <td style="width: 20px;">15</td> <td style="width: 20px;">14</td> <td style="width: 40px;">-</td> <td style="width: 20px;">2</td> <td style="width: 20px;">1</td> <td style="width: 20px;">0</td> </tr> </table> <div style="margin-left: 20px;"> Zone64 Zone49 </div> | 15 | 14 | - | 2 | 1 | 0 | | | |
| 15 | 14 | - | 2 | 1 | 0 | | | | | |

17.1.2 Wiring Diagrams

When Connected at CN1:

RS-422/RS-485

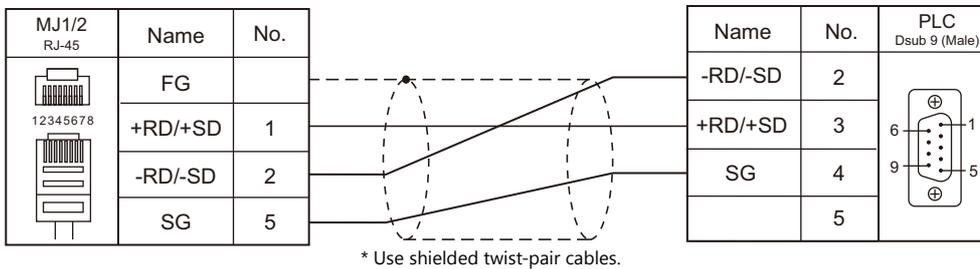
Wiring diagram1 - C4



When Connected at MJ1/MJ2:

RS-422/RS-485

Wiring diagram 1 - M4



MEMO

Please use this page freely.

18. GE Fanuc

18.1 PLC Connection

18.1 PLC Connection

Serial Connection

| PLC Selection on the Editor | CPU | | Unit/Port | | Signal Level | Connection | | Ladder Transfer *1 |
|-----------------------------|--|---|----------------------------|---|----------------------------|-----------------------|---------|-----------------------|
| | | | | | | CN1 | MJ1/MJ2 | |
| 90 series | IC693CPU331 IC693CPU340 IC693CPU341 IC693CPU350 IC693CPU351 IC693CPU352 IC693CPU360 IC693CPU363 IC693CPU364 IC693CPU366 IC693CPU367 IC693CPU370 IC693CPU372 IC693CPU374 | IC693CMM311 | Port 1 | RS-232C | Wiring diagram 1 - C2 | Wiring diagram 1 - M2 | × | |
| | | | Port 2 | RS-232C | Wiring diagram 2 - C2 | Wiring diagram 2 - M2 | | |
| | | | | RS-422 | Wiring diagram 2 - C4 | Wiring diagram 1 - M4 | | |
| 90 series (SNP-X) | IC698CPE010 IC698CPE020 IC698CRE020 IC697CPU731 IC697CPX772 IC697CPX782 IC697CPX928 IC697CPX935 IC697CPU780 IC697CGR772 IC697CGR935 IC697CPU789 IC697CPM790 | IC697CMM711 | | RS-422 | Wiring diagram 2 - C4 | Wiring diagram 1 - M4 | × | |
| | | | | | | | | |
| | IC693CPU350 IC693CPU360 IC693CPU363 IC693CPU364 IC693CPU366 IC693CPU367 IC693CPU374 | COM port of the CPU | | RS-422 | Wiring diagram 1 - C4 | × | | |
| 90 series (SNP) | 90-30 series | IC693CPU311 IC693CPU313 IC693CPU323 IC693CPU331 IC693CPU340 IC693CPU341 IC693CPU350 IC693CPU360 IC693CPU364 IC693CPU366 IC693CPU367 IC693CPU370 IC693CPU374 PLUS | Serial port (power supply) | RS-422 | Wiring diagram 1 - C4 | Wiring diagram 2 - M4 | × | |
| | | | IC693CMM311 | Port 1 | RS-232C | Wiring diagram 1 - C2 | | Wiring diagram 1 - M2 |
| | | | | Port 2 | RS-232C | Wiring diagram 2 - C2 | | Wiring diagram 2 - M2 |
| | | | Port 2 | | RS-422 | Wiring diagram 2 - C4 | | Wiring diagram 1 - M4 |
| | | | | IC693CPU351 IC693CPU352 IC693CPU363 | Serial port (power supply) | RS-422 | | Wiring diagram 1 - C4 |
| | | | PORT1 | | RS-232C | Wiring diagram 3 - C2 | | Wiring diagram 3 - M2 |
| | | PORT2 | RS-422 | | Wiring diagram 1 - C4 | Wiring diagram 2 - M4 | | |
| | | IC693CMM311 | Port 1 | | RS-232C | Wiring diagram 1 - C2 | | Wiring diagram 1 - M2 |
| | | | Port 2 | RS-232C | Wiring diagram 2 - C2 | Wiring diagram 2 - M2 | | |
| | | | | Port 2 | RS-422 | Wiring diagram 2 - C4 | | Wiring diagram 1 - M4 |

| PLC Selection on the Editor | CPU | | Unit/Port | | Signal Level | Connection | | Ladder Transfer ^{*1} |
|-----------------------------|-----------------------|---|--|-------------------|-----------------------|---|---|-------------------------------|
| | | | | | | CN1 | MJ1/MJ2 | |
| 90 series (SNP) | 90-70 series | IC697CPU731 IC697CPU780 IC697CPU789 IC697CPM790 | Serial Port | | RS-422 | Wiring diagram 1 - C4 | Wiring diagram 2 - M4 | × |
| | | | IC697CMM711 | Port 1/ Port 2 | RS-232C | Wiring diagram 1 - C2 | Wiring diagram 1 - M2 | |
| | | | | | RS-422 | Wiring diagram 2 - C4 | Wiring diagram 1 - M4 | |
| | | IC697CPX772 IC697CPX782 IC697CPX928 IC697CPX935 IC697CGR772 IC697CGR935 | Serial Port1 | | RS-232C | Wiring diagram 3 - C2 | Wiring diagram 3 - M2 | |
| | | | Serial Port2 Serial Port3 | | RS-422 | Wiring diagram 1 - C4 | Wiring diagram 2 - M4 | |
| | | | IC697CMM711 | Port 1/ Port 2 | RS-232C | Wiring diagram 1 - C2 | Wiring diagram 1 - M2 | |
| | | RS-422 | | | Wiring diagram 2 - C4 | Wiring diagram 1 - M4 | | |
| | | PACSystems RX3i | IC695CPU310 IC695CPU315 IC695CPU320 IC695CMU310 IC695CRU320 IC695CPE310 | COM1 | | RS-232C | Wiring diagram 4 - C2 | |
| | COM2 | | | RS-422 | Wiring diagram 1 - C4 | Wiring diagram 2 - M4 | | |
| | IC695CPE305 | | COM1 | | RS-232C | Wiring diagram 4 - C2 + GE Fanuc IC963CBL316 | Wiring diagram 4 - M2 + GE Fanuc IC963CBL316 | |
| | PACSystems RX7i | IC698CPE010 IC698CPE020 IC698CPE030 IC698CPE040 IC698CRE020 IC698CRE030 IC698CRE040 | COM1 | | RS-232C | Wiring diagram 4 - C2 | Wiring diagram 4 - M2 | |
| | | | COM2 | | RS-422 | Wiring diagram 1 - C4 | Wiring diagram 2 - M4 | |
| | | | IC697CMM711 | Port 1/ Port 2 | RS-232C | Wiring diagram 1 - C2 | Wiring diagram 1 - M2 | |
| | | | | | RS-422 | Wiring diagram 2 - C4 | Wiring diagram 1 - M4 | |
| | VersaMax | IC200CPU001 IC200CPU002 IC200CPU005 IC200CPUE05 | PORT1 | | RS-232C | Wiring diagram 4 - C2 | Wiring diagram 4 - M2 | |
| | | | PORT2 | | RS-422 | Wiring diagram 1 - C4 | Wiring diagram 2 - M4 | |
| | VersaMax Micro & Nano | Nano 10 PLCs Micro 14 PLCs | Serial Port | | RS-232C | Wiring diagram 5 - C2 | Wiring diagram 5 - M2 | |
| | | | Micro 23 PLCs Micro 28 PLCs | Serial Port 1 | | RS-232C | Wiring diagram 5 - C2 | |
| | | Serial Port 2 | | RS-422 | Wiring diagram 1 - C4 | Wiring diagram 2 - M4 | | |
| | | Micro 20 PLCs Micro 40 PLCs Micro 64 PLCs | Serial Port | | RS-232C | Wiring diagram 5 - C2 | Wiring diagram 5 - M2 | |
| | | | IC200USB001 | | RS-232C | Wiring diagram 5 - C2 | Wiring diagram 5 - M2 | |
| | | IC200USB002 | | | | RS-422 | Wiring diagram 3 - C4 | |

*1 For the ladder transfer function, see the V9 Series Reference Manual.

Ethernet Connection

| PLC Selection on the Editor | CPU | | Unit | TCP/IP | UDP/IP | Port No. | Keep Alive ^{*1} | Ladder Transfer ^{*2} |
|-----------------------------|-----------------|-------------|------------------------|--------|--------|-------------|--------------------------|-------------------------------|
| 90 series (Ethernet TCP/IP) | Series 90-70 | | IC697CMM742 (Type 2) | ○ | × | 18245 fixed | ○ | × |
| | Series 90-30 | | IC693CMM321 | ○ | × | | | |
| | | | CPU with built-in port | | | | | |
| RX3i (Ethernet TCP/IP) | PACSystems RX3i | IC695CPU310 | ETM001 | ○ | × | 18245 fixed | | × |

*1 For KeepAlive functions, see "1.3.2 Ethernet Communication".

*2 For the ladder transfer function, see the V9 Series Reference Manual.

18.1.1 90 Series

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|--|---------|
| Connection Mode | <u>1:1</u> / 1:n / Multi-link2 / Multi-link2 (Ethernet) / 1:n Multi-link2 (Ethernet) | |
| Signal Level | <u>RS-232C</u> / RS-422/485 | |
| Baud Rate | 4800 / 9600 / <u>19200</u> bps | |
| Data Length | 8 bits | |
| Stop Bit | 1 bit | |
| Parity | None / <u>Odd</u> | |
| Target Port No. | 1 to 31 | |

PLC

Be sure to match the settings to those made under [Communication Setting] of the editor.

PCM

(Underlined setting: default)

| Item | Setting | Remarks | |
|--------------------|---------------------------------------|---------------------------------------|--|
| Configuration Mode | CCM ONLY, BAS/CCM, PROG/CCM, CCM/PROG | | |
| Port 1 | CCM Enable | YES | |
| | CCM Mode | SLAVE | |
| | Interface | RS-232 | |
| | Date Rate | 4800 / 9600 / <u>19200</u> bps | |
| | Flow Control | NONE | |
| | Parity | NONE / <u>ODD</u> | |
| | Retry Count | <u>NORMAL</u> / SHORT | |
| | Timeout | <u>LONG</u> / MEDIUM / SHORT / NONE | |
| | Turnaround Delay | <u>NONE</u> / 10 ms / 100 ms / 500 ms | |
| | CPU ID | 1 to 31 | |
| Port 2 | CCM Enable | YES | |
| | CCM Mode | SLAVE | |
| | Interface | <u>RS-232</u> / RS-485 | Only RS-485 is available with IC693PCM300. |
| | Date Rate | 4800 / 9600 / <u>19200</u> bps | |
| | Flow Control | NONE | |
| | Parity | NONE / <u>ODD</u> | |
| | Retry Count | <u>NORMAL</u> / SHORT | |
| | Timeout | <u>LONG</u> / MEDIUM / SHORT / NONE | |
| | Turnaround Delay | <u>NONE</u> / 10 ms / 100 ms / 500 ms | |
| | CPU ID | 1 to 31 | |

Calendar

This model is not equipped with the calendar function. Use the built-in clock of the V series.

IC693CMM311

(Underlined setting: default)

| Item | Setting | Remarks |
|--------------------|--|---------------------------------------|
| Configuration Mode | CCM ONLY, CCM/RTU, RTU/CCM, SNP/CCM, CCM/SNP | |
| Port 1 | CCM Enable | YES |
| | CCM Mode | SLAVE |
| | Interface | RS-232 |
| | Date Rate | 4800 / 9600 / <u>19200</u> bps |
| | Flow Control | NONE |
| | Parity | NONE / <u>ODD</u> |
| | Retry Count | <u>NORMAL</u> / SHORT |
| | Timeout | <u>LONG</u> / MEDIUM / SHORT / NONE |
| | Turnaround Delay | <u>NONE</u> / 10 ms / 100 ms / 500 ms |
| | CCM CPU ID | 1 to 31 |
| Port 2 | CCM Enable | YES |
| | CCM Mode | SLAVE |
| | Interface | <u>RS-232</u> / RS-485 |
| | Date Rate | 4800 / 9600 / <u>19200</u> bps |
| | Flow Control | NONE |
| | Parity | NONE / <u>ODD</u> |
| | Retry Count | <u>NORMAL</u> / SHORT |
| | Timeout | <u>LONG</u> / MEDIUM / SHORT / NONE |
| | Turnaround Delay | <u>NONE</u> / 10 ms / 100 ms / 500 ms |
| | CCM CPU ID | 1 to 31 |

Calendar

This model is not equipped with the calendar function. Use the built-in clock of the V series.

Available Device Memory

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|---------------|------|---------|
| R (register) | 00H | |
| I (input) | 01H | |
| Q (output) | 02H | |

Indirect Device Memory Designation

For the device memory address number, specify the value obtained by subtracting "1" from the actual address.

18.1.2 90 Series (SNP-X)

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|--|---------|
| Connection Mode | <u>1</u> :1 / Multi-link2 / Multi-link2 (Ethernet) | |
| Signal Level | RS-232C / <u>RS-422/485</u> | |
| Baud Rate | 4800 / 9600 / <u>19200</u> bps | |
| Data Length | 8 bits | |
| Stop Bit | <u>1</u> / 2 bits | |
| Parity | None / <u>Odd</u> / Even | |

PLC

Be sure to match the settings to those made under [Communication Setting] of the editor.

90 series (SNP-X)

| Item | Setting | Remarks |
|-------------------|-------------|---------|
| Baud Rate | 19200 bps | |
| Parity | Odd | |
| Transmission code | Data Length | 8 bits |
| | Stop Bit | 1 bit |
| Function | SNP-X | |

Calendar

This model is not equipped with the calendar function. Use the built-in clock of the V series.

Available Device Memory

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|----------------------------|------|-----------|
| R (register) | 00H | |
| I (input) | 01H | |
| Q (output) | 02H | |
| M (internal relay) | 03H | |
| G (global relay) | 04H | |
| AI (analog input) | 05H | |
| AQ (analog output) | 06H | |
| T (temporary memory relay) | 07H | |
| S (system status) | 08H | Read only |
| SA (system status) | 09H | |
| SB (system status) | 0AH | |
| SC (system status) | 0BH | |

Indirect Device Memory Designation

For the device memory address number, specify the value obtained by subtracting "1" from the actual address.

18.1.3 90 Series (SNP)

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|---|---------|
| Connection Mode | <u>1:1</u> / Multi-link2 / Multi-link2 (Ethernet) | |
| Signal Level | <u>RS-232C</u> / RS-422/485 | |
| Baud Rate | 4800 / 9600 / <u>19200</u> / 38400 / 57600 / 115K bps | |
| Data Length | <u>8 bits</u> | |
| Stop Bit | <u>1</u> / 2 bits | |
| Parity | None / <u>Odd</u> / Even | |

PLC

Be sure to match the settings to those made under [Communication Setting] of the editor.

IC693CMM311 / IC697CMM711

(Underlined setting: default)

| Item | Setting | Remarks | |
|--------------------|--|---------------------------------------|--------------------------------------|
| Configuration Mode | SNP ONLY, SNP/CCM, CCM/SNP, SNP/RTU, RTU/SNP | | |
| Port 1 | SNP Enable | YES | |
| | SNP Mode | SLAVE | |
| | Interface | <u>RS485</u> / RS232 | Only RS232C supported by IC693CMM311 |
| | Date Rate | 4800 / 9600 / <u>19200</u> bps | |
| | Flow Control | NONE | |
| | Parity | <u>ODD</u> / EVEN / NONE | |
| | Stop Bits | <u>1</u> / 2 | |
| | Timeout | <u>LONG</u> / MEDIUM / SHORT / NONE | |
| | Modem Turnaround Delay | <u>NONE</u> / 10 ms / 100 ms / 500 ms | |
| Port 2 | SNP Enable | YES | |
| | SNP Mode | SLAVE | |
| | Interface | <u>RS485</u> / RS232 | |
| | Date Rate | 4800 / 9600 / <u>19200</u> bps | |
| | Flow Control | NONE | |
| | Parity | <u>ODD</u> / EVEN / NONE | |
| | Stop Bits | <u>1</u> / 2 | |
| | Timeout | <u>LONG</u> / MEDIUM / SHORT / NONE | |
| | Modem Turnaround Delay | <u>NONE</u> / 10 ms / 100 ms / 500 ms | |

90-30 Series / 90-70 Series

(Underlined setting: default)

| Parameter | Setting | Remarks |
|--------------------|--------------------------------|----------------------|
| Port Mode | SNP Slave | |
| Data Rate | 4800 / 9600 / <u>19200</u> bps | |
| Parity | <u>ODD</u> / EVEN / NONE | |
| Stop Bits | <u>1</u> / 2 | |
| Physical Interface | 2-wire / <u>4-wire</u> | Both valid for RS232 |

PAC Systems

(Underlined setting: default)

| Parameter | Setting | Remarks |
|--------------------|---|----------------------|
| Port Mode | SNP Slave | |
| Data Rate | 4800 / 9600 / <u>19200</u> / 38400 / 57600 / 115200 bps | |
| Parity | <u>ODD</u> / EVEN / NONE | |
| Stop Bits | 1 | |
| Physical Interface | 2-wire / <u>4-wire</u> | Both valid for RS232 |

VersaMax / VersaMax Micro & Nano / IC200USB001 / IC200USB002

(Underlined setting: default)

| Parameter | Setting | Remarks |
|--------------------|--|----------------------|
| Port Mode | SNP | |
| Port Type | Slave | |
| Data Rate | 4800 / 9600 / <u>19200</u> / 38400 bps | |
| Parity | <u>ODD</u> / EVEN / NONE | |
| Stop Bits | <u>1</u> / 2 | |
| Physical Interface | 2-wire / <u>4-wire</u> | Both valid for RS232 |

Calendar

This model is not equipped with the calendar function. Use the built-in clock of the V series.

Available Device Memory

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|----------------------------|------|-------------------|
| R (register) | 00H | |
| I (input) | 01H | |
| Q (output) | 02H | |
| M (internal relay) | 03H | |
| G (global relay) | 04H | |
| AI (analog input) | 05H | |
| AQ (analog output) | 06H | |
| T (temporary memory relay) | 07H | |
| S (system status) | 08H | Read only |
| SA (system status) | 09H | |
| SB (system status) | 0AH | |
| SC (system status) | 0BH | |
| P (local subblock data) | 0CH | 90-70 series only |
| L (program block data) | 0DH | 90-70 series only |

Indirect Device Memory Designation

For the device memory address number, specify the value obtained by subtracting "1" from the actual address.

18.1.4 90 Series (Ethernet TCP/IP)

Communication Setting

Editor

Make the following settings on the editor. For more information, see "1.3.2 Ethernet Communication".

- IP address for the V9 unit
 - When specified on the screen program:
[System Setting] → [Hardware Setting] → [Local Port IP Address]
 - When specified on the V9 unit:
Local mode → [LAN Setting]
- Port number for the V9 unit (for communication with PLC)
[System Setting] → [Hardware Setting] → [PLC Properties] → [Communication Setting]
- IP address and port number (No. 18245) of the PLC
Register on the [PLC Table] in [System Setting] → [Hardware Setting] → [PLC Properties] → [Target Settings].

PLC

Parameters

| Parameters | Values |
|--------------------------------------|---------------|
| Configuration Mode: | TCP/IP |
| Adapter Name: | 0.1 |
| IP Address: | 10.91.131.229 |
| Subnet Mask: | 255.255.255.0 |
| Gateway IP Address: | 10.91.131.1 |
| Status Address: | %I00001 |
| Status Length: | 80 |
| Network Time Sync: | Sntp |
| Max number of Web Server Connection: | 1 |
| Max number of FTP Server Connection: | 2 |

| Item | Setting | Remarks |
|--------------------|---|---------|
| IP Address | Set the IP address of the PLC. | |
| Subnet Mask | Set the subnet mask of the PLC. | |
| Gateway IP Address | Make settings in accordance with the network environment. | |

Calendar

This model is not equipped with the calendar function. Use the built-in clock of the V series.

Available Device Memory

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|----------------------------|------|-----------|
| R (register) | 00H | |
| I (input) | 01H | |
| Q (output) | 02H | |
| M (internal relay) | 03H | |
| G (global relay) | 04H | |
| AI (analog input) | 05H | |
| AQ (analog output) | 06H | |
| T (temporary memory relay) | 07H | |
| S (system status) | 08H | Read only |
| SA (system status) | 09H | |
| SB (system status) | 0AH | |
| SC (system status) | 0BH | |

Indirect Device Memory Designation

For the device memory address number, specify the value obtained by subtracting "1" from the actual address.

18.1.5 RX3i (Ethernet TCP/IP)

Communication Setting

Editor

Make the following settings on the editor. For more information, see "1.3.2 Ethernet Communication".

- IP address for the V9 unit
 - When specified on the screen program:
[System Setting] → [Hardware Setting] → [Local Port IP Address]
 - When specified on the V9 unit:
Local mode → [LAN Setting]
- Port number for the V9 unit (for communication with PLC)
[System Setting] → [Hardware Setting] → [PLC Properties] → [Communication Setting]
- IP address and port number (No. 18245) of the PLC
Register on the [PLC Table] in [System Setting] → [Hardware Setting] → [PLC Properties] → [Target Settings].

PLC

Parameters

| Item | Setting | Remarks |
|--------------------|---------------------------------------|---------|
| IP Address | Set the IP address of the PLC. | |
| Subnet Mask | Set the subnet mask of the PLC. | |
| Gateway IP Address | Specify according to the environment. | |

Calendar

This model is not equipped with the calendar function. Use the built-in clock of the V series.

Available Device Memory

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|----------------------------|------|-----------|
| R (register) | 00H | |
| I (input) | 01H | |
| Q (output) | 02H | |
| M (internal relay) | 03H | |
| G (global relay) | 04H | |
| AI (analog input) | 05H | |
| AQ (analog output) | 06H | |
| T (temporary memory relay) | 07H | |
| S (system status) | 08H | Read only |
| SA (system status) | 09H | |
| SB (system status) | 0AH | |
| SC (system status) | 0BH | |

Indirect Device Memory Designation

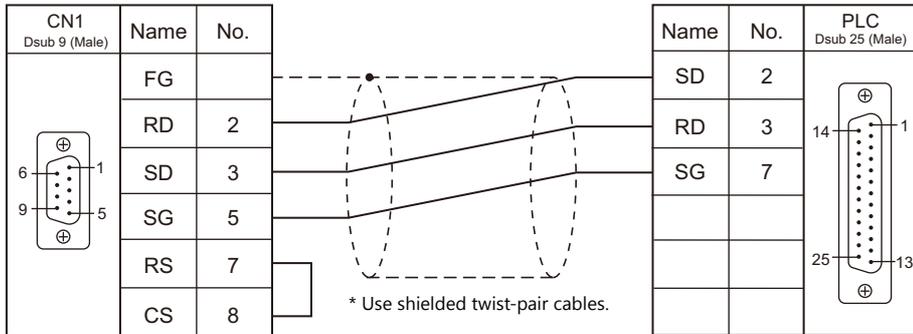
For the device memory address number, specify the value obtained by subtracting "1" from the actual address.

18.1.6 Wiring Diagrams

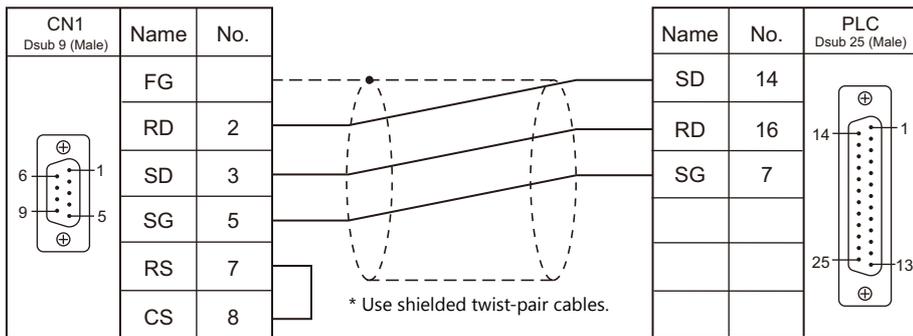
When Connected at CN1:

RS-232C

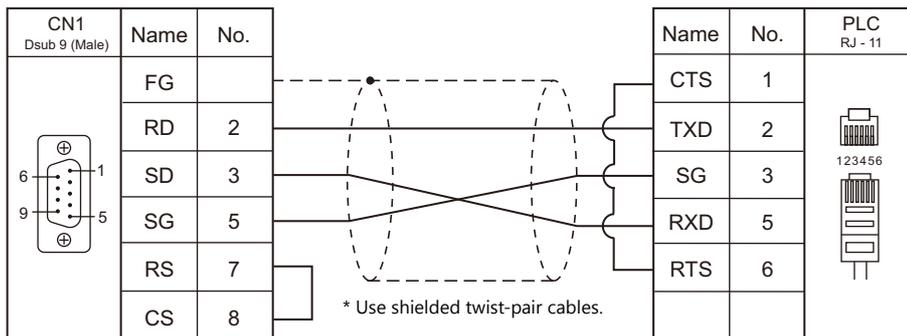
Wiring diagram 1 - C2



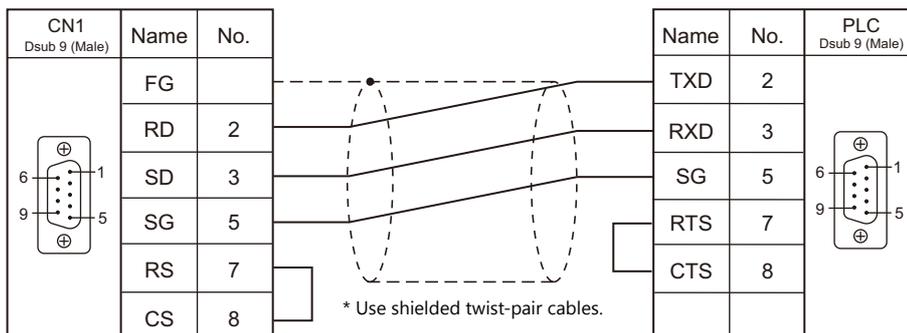
Wiring diagram 2 - C2



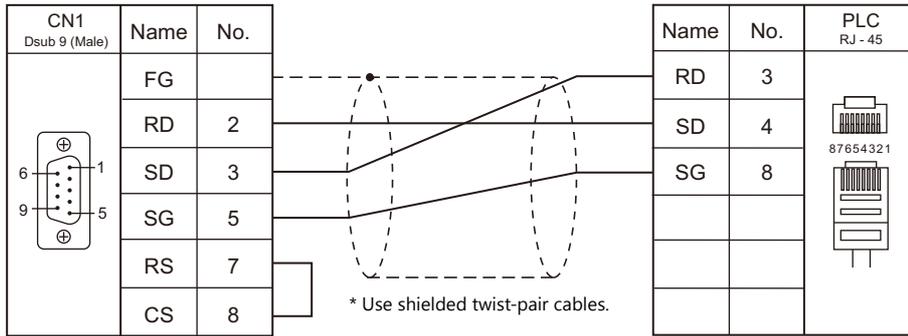
Wiring diagram 3 - C2



Wiring diagram 4 - C2

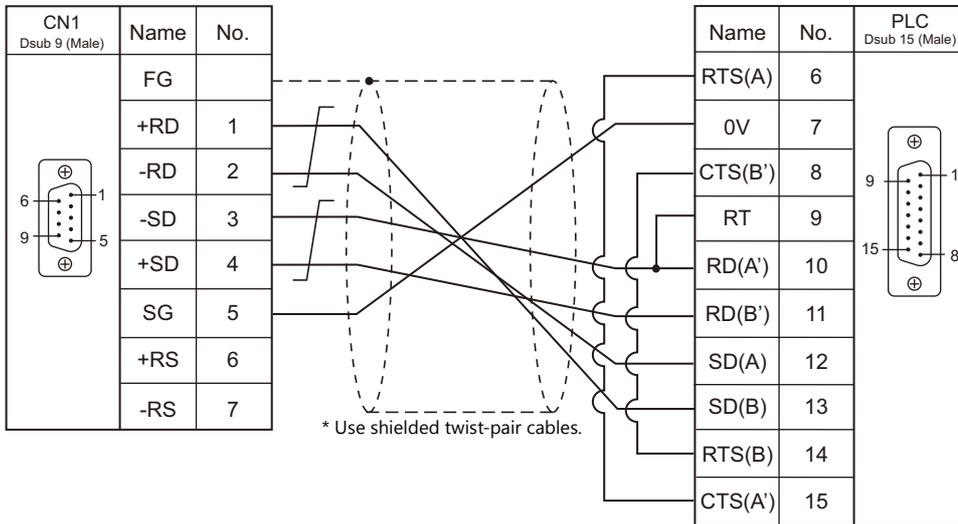


Wiring diagram 5 - C2

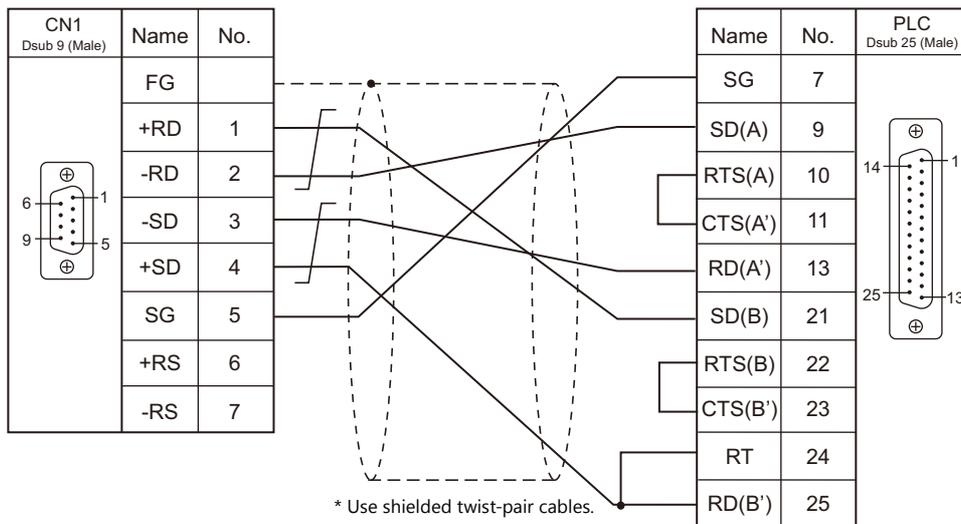


RS-422/RS-485

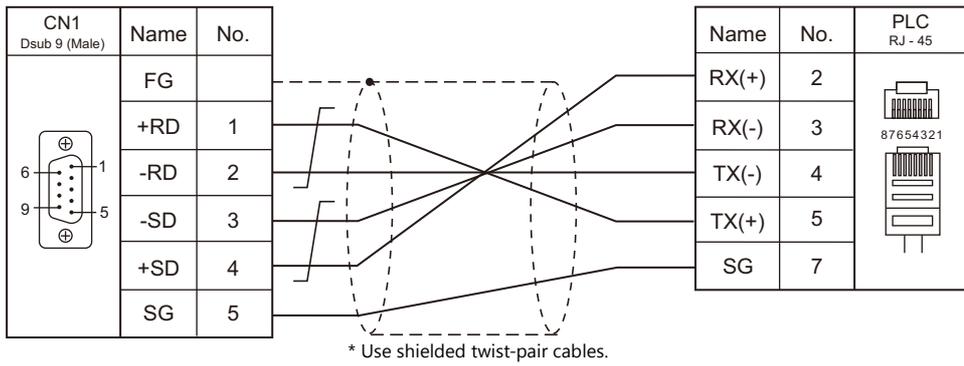
Wiring diagram 1 - C4



Wiring diagram 2 - C4



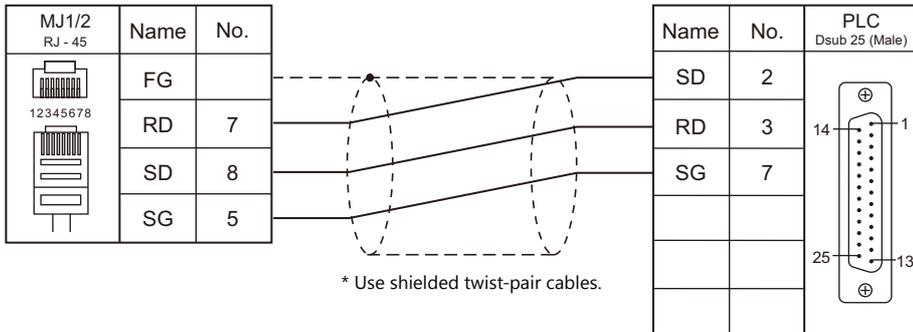
Wiring diagram 3 - C4



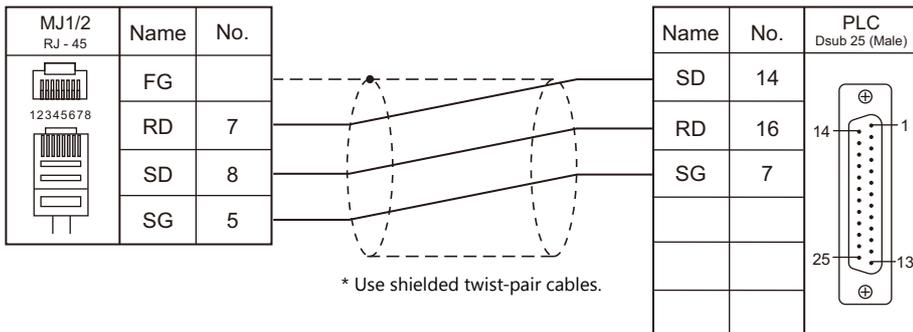
When Connected at MJ1/MJ2:

RS-232C

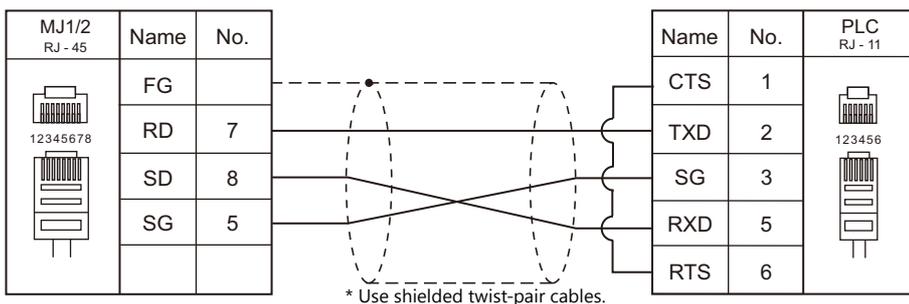
Wiring diagram 1 - M2



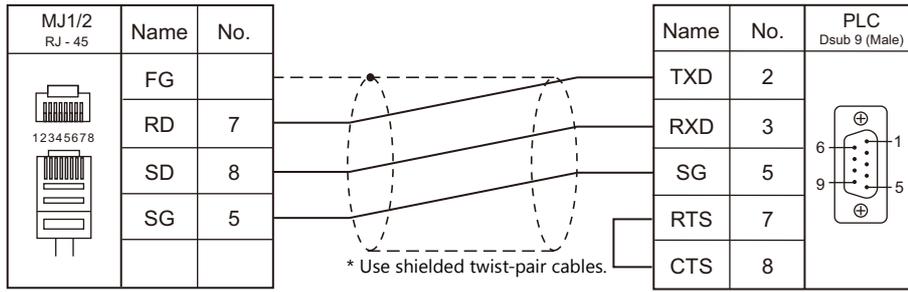
Wiring diagram 2 - M2



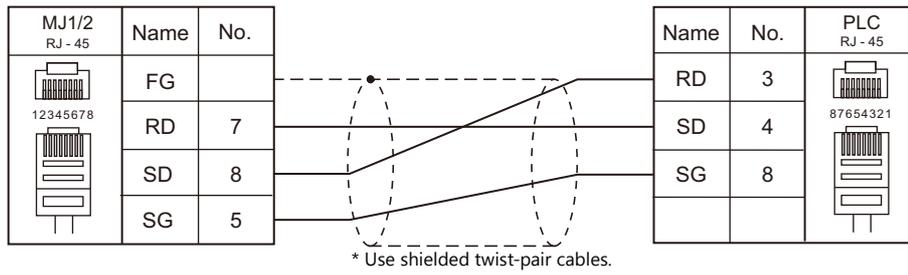
Wiring diagram 3 - M2



Wiring diagram 4 - M2

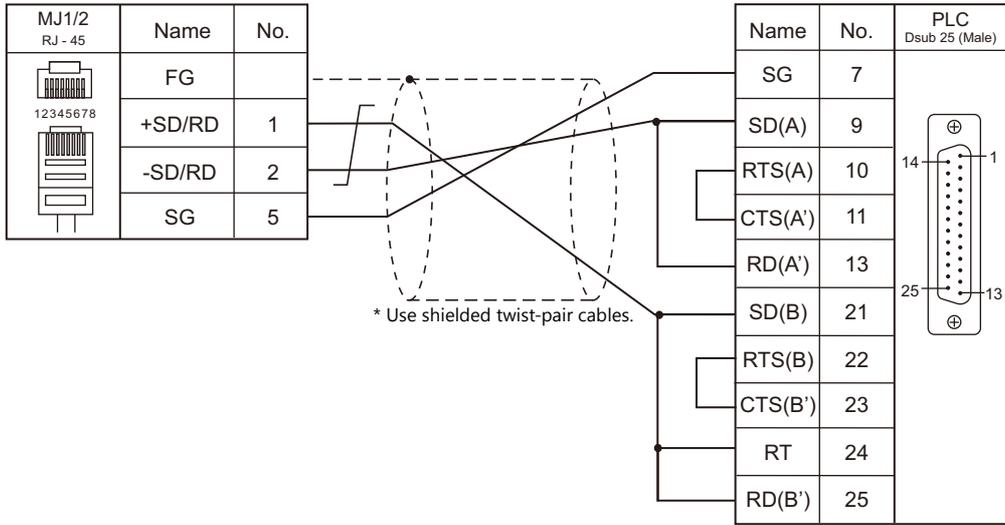


Wiring diagram 5 - M2

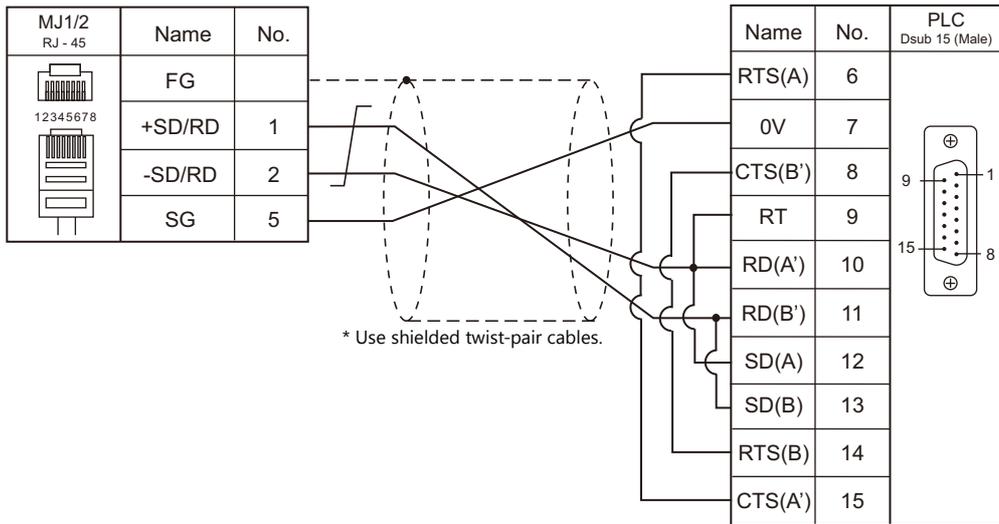


RS-422/RS-485

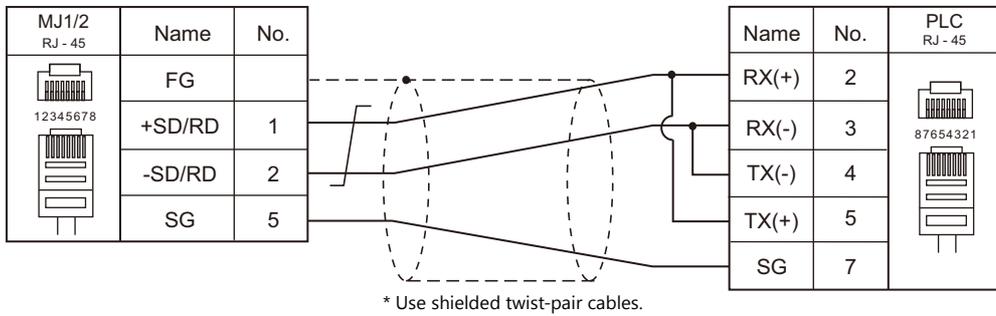
Wiring diagram 1 - M4



Wiring diagram 2 - M4



Wiring diagram 3 - M4



19. Hitachi

19.1 PLC Connection

19.1 PLC Connection

Serial Connection

| PLC Selection on the Editor | CPU | Unit/Port | Signal Level | Connection | | Ladder Transfer ^{*1} |
|--------------------------------|--------------------------------------|-----------------------------------|--------------|-----------------------|-----------------------|-------------------------------|
| | | | | CN1 | MJ1/MJ2 | |
| HIDIC-S10/2 α , S10mini | S10 2 α | Interface on the CPU unit | RS-422 | Wiring diagram 1 - C4 | × | × |
| | LQP000 LQP010 LQP011 LQP120 | RS-232C connector on the CPU unit | RS-232C | Wiring diagram 1 - C2 | Wiring diagram 1 - M2 | |
| | | LQE060 (CN1, CN2) | RS-232C | Wiring diagram 2 - C2 | Wiring diagram 2 - M2 | |
| | | LQE160 (CN1, CN2) | | | | |
| | | LQE560 (CN1, CN2) | | | | |
| | | LQE165 (CN1, CN2) | RS-422 | Wiring diagram 2 - C4 | × | |
| LQE565 (CN1, CN2) | | | | | | |
| HIDIC-S10/4 α | S10 4 α | LWE805 | RS-422 | Wiring diagram 1 - C4 | × | |
| HIDIC-S10V | LQP510 | UP LINK | RS-422 | Wiring diagram 2 - C4 | × | |
| | | LQE560 (CN1, CN2) | RS-232C | Wiring diagram 2 - C2 | Wiring diagram 2 - M2 | |
| | | LQE565 (CN1, CN2) | RS-422 | Wiring diagram 2 - C4 | × | |

*1 For the ladder transfer function, see the V9 Series Reference Manual.

Ethernet Connection

| PLC Selection on the Editor | CPU | Unit | TCP/IP | UDP/IP | Port No. | Keep Alive ^{*1} | Ladder Transfer ^{*2} |
|---|---------|--------|--------|-----------------------|---------------------|--------------------------|-------------------------------|
| HIDIC-S10/2 α , S10mini (Ethernet) | S10mini | LQE020 | ○ | × | 4301 (max. 4 units) | ○ | × |
| | | LQE520 | | | | | |
| HIDIC-S10V (Ethernet) | LQP510 | LQE520 | | | | | |
| | | LQP520 | | | 4302 (max. 4 units) | | |
| | | | | 4302 to 4305 (1 each) | | | |

*1 For KeepAlive functions, see "1.3.2 Ethernet Communication".

*2 For the ladder transfer function, see the V9 Series Reference Manual.

19.1.1 HIDIC-S10/2 α , S10mini

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|--|---------|
| Connection Mode | <u>1:1</u> / Multi-link2 / Multi-link2 (Ethernet) | |
| Signal Level | RS-232C / <u>RS-422/485</u> | |
| Baud Rate | 4800 / 9600 / <u>19200</u> / 38400 / 57600 / 115k bps | |
| Data Length | 8 bits | |
| Stop Bit | 1 bit | |
| Parity | Odd | |

PLC

All PLC parameters are fixed to the following settings:

Baud rate: 19200 bps, data length: 8 bits, stop bit: 1 bit, parity: odd

However, when the optional RS-232C/RS-422 module is used, the channel and the protocol must be set using the channel No./protocol setting switch.

Channel No./Protocol Setting Switch

A maximum of two RS-232C/RS-422 modules (four channels) can be attached to one CPU. When using multiple channels, set a unique channel number (#1 to #4) for each.

LQE060

| MODU NO | Communication Mode | Channel No. |
|---------|--------------------|-------------|
| 8 | H-7338 protocol | #0 |
| 9 | | #1 |

LQE160 / LQE165 / LQE560 / LQE565

| MODU NO | Communication Mode | Channel No. |
|---------|--------------------|-------------|
| 8 | H-7338 protocol | #0 |
| 9 | | #1 |
| A | | #2 |
| E | | #3 |

Available Device Memory

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|---------------------------------------|------|-------------------|
| FW (work register) | 00H | |
| X (input) | 01H | XW as word device |
| Y (output) | 02H | YW as word device |
| R (internal relay) | 03H | RW as word device |
| G (global link relay) | 04H | GW as word device |
| K (keep relay) | 05H | KW as word device |
| T (on-delay timer/contact) | 06H | TW as word device |
| U (one-shot timer/contact) | 07H | UW as word device |
| C (up/down counter/contact) | 08H | CW as word device |
| TS (on-delay timer/set value) | 09H | |
| TC (on-delay timer/enumerated value) | 0AH | |
| US (one-shot timer/set value) | 0BH | |
| UC (one-shot timer/enumerated value) | 0CH | |
| CS (up/down counter/set value) | 0DH | |
| CC (up/down counter/enumerated value) | 0EH | |
| DW (data register) | 0FH | |
| E (event register) | 10H | EW as word device |
| S (system register) | 11H | SW as word device |
| J (transfer register) | 12H | JW as word device |
| Q (receive register) | 13H | QW as word device |
| M (extensional internal register) | 14H | MW as word device |

19.1.2 HIDIC-S10/2 α , S10mini (Ethernet)

Communication Setting

Editor

Make the following settings on the editor. For more information, see "1.3.2 Ethernet Communication".

- IP address for the V9 unit
 - When specified on the screen program:
[System Setting] → [Hardware Setting] → [Local Port IP Address]
 - When specified on the V9 unit:
Local mode → [LAN Setting]
- Port number for the V9 unit (for communication with PLC)
[System Setting] → [Hardware Setting] → [PLC Properties] → [Communication Setting]
- IP address and port number of the PLC
Register on the [PLC Table] in [System Setting] → [Hardware Setting] → [PLC Properties] → [Target Settings].

PLC

LQE020

Module No. setting switch

| MODU NO | Contents | |
|---------|----------------------------|--|
| 0 | Communication via 10BASE-5 | |
| 2 | Communication via 10BASE-T | |

ET. NET system

Specify the IP address and the subnet mask.

LQE520

Module No. setting switch

| MODU NO | Contents | |
|---------|----------------------------|--|
| 0 | Communication via 10BASE-5 | |
| 2 | Communication via 10BASE-T | |

S10V ET.NET system

Specify the IP address and the subnet mask.

Available Device Memory

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|---------------------------------------|------|-------------------|
| FW (work register) | 00H | |
| X (input) | 01H | XW as word device |
| Y (output) | 02H | YW as word device |
| R (internal relay) | 03H | RW as word device |
| G (global link relay) | 04H | GW as word device |
| K (keep relay) | 05H | KW as word device |
| T (on-delay timer/contact) | 06H | TW as word device |
| U (one-shot timer/contact) | 07H | UW as word device |
| C (up/down counter/contact) | 08H | CW as word device |
| TS (on-delay timer/set value) | 09H | |
| TC (on-delay timer/enumerated value) | 0AH | |
| US (one-shot timer/set value) | 0BH | |
| UC (one-shot timer/enumerated value) | 0CH | |
| CS (up/down counter/set value) | 0DH | |
| CC (up/down counter/enumerated value) | 0EH | |
| DW (data register) | 0FH | |
| E (event register) | 10H | EW as word device |
| S (system register) | 11H | SW as word device |
| J (transfer register) | 12H | JW as word device |
| Q (receive register) | 13H | QW as word device |
| M (extensional internal register) | 14H | MW as word device |

19.1.3 HIDIC-S10/4 α

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|---|---------|
| Connection Mode | <u>1:1</u> / Multi-link2 / Multi-link2 (Ethernet) | |
| Signal Level | RS-232C / <u>RS-422/485</u> | |
| Baud Rate | 19200 bps | |
| Data Length | 8 bits | |
| Stop Bit | 1 bit | |
| Parity | Odd | |

PLC

All PLC parameters are fixed to the following settings:

Baud rate: 19200 bps, data length: 8 bits, stop bit: 1 bit, parity: odd

Only RS-422 (4-wire) connection can be used. For RS-232C or RS-485 (2-wire) connection, a commercially available converter must be used.

Available Device Memory

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|---------------------------------------|------|-------------------|
| FW (work register) | 00H | |
| X (input) | 01H | XW as word device |
| Y (output) | 02H | YW as word device |
| R (internal relay) | 03H | RW as word device |
| G (global link relay) | 04H | GW as word device |
| K (keep relay) | 05H | KW as word device |
| T (on-delay timer/contact) | 06H | TW as word device |
| U (one-shot timer/contact) | 07H | UW as word device |
| C (up/down counter/contact) | 08H | CW as word device |
| TS (on-delay timer/set value) | 09H | |
| TC (on-delay timer/enumerated value) | 0AH | |
| US (one-shot timer/set value) | 0BH | |
| UC (one-shot timer/enumerated value) | 0CH | |
| CS (up/down counter/set value) | 0DH | |
| CC (up/down counter/enumerated value) | 0EH | |
| DW (data register) | 0FH | |
| E (event register) | 10H | EW as word device |
| S (system register) | 11H | SW as word device |
| J (transfer register) | 12H | JW as word device |
| Q (receive register) | 13H | QW as word device |
| M (extensional internal register) | 14H | MW as word device |

19.1.4 HIDIC-S10V

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|---|---------|
| Connection Mode | <u>1:1</u> / Multi-link2 / Multi-link2 (Ethernet) | |
| Signal Level | RS-232C / <u>RS-422/485</u> | |
| Baud Rate | 4800 / 9600 / <u>19200</u> / 38400 / 57600 / 115K bps | |
| Data Length | 8 bits | |
| Stop Bit | 1 bit | |
| Parity | Odd | |

PLC

All PLC parameters are fixed to the following settings:

Baud rate: 19200 bps, data length: 8 bits, stop bit: 1 bit, parity: odd

However, when the optional RS-232C/RS-422 module is used, the channel and the protocol must be set using the channel No./protocol setting switch.

Channel No./Protocol Setting Switch

A maximum of two RS-232C/RS-422 modules (four channels) can be attached to one CPU. When using multiple channels, set a unique channel number (#1 to #4) for each.

LQE560 / LQE565

| MODU NO | Communication Mode | Channel No. |
|---------|--------------------|-------------|
| 8 | H-7338 protocol | #0 |
| 9 | | #1 |
| A | | #2 |
| E | | #3 |

Available Device Memory

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|--|------|--------------------|
| FW (work register) | 00H | |
| X (input) | 01H | XW as word device |
| Y (output) | 02H | YW as word device |
| R (internal relay) | 03H | RW as word device |
| G (global link relay) | 04H | GW as word device |
| K (keep relay) | 05H | KW as word device |
| T (on-delay timer/contact) | 06H | TW as word device |
| U (one-shot timer/contact) | 07H | UW as word device |
| C (up/down counter/contact) | 08H | CW as word device |
| TS (on-delay timer/set value) | 09H | |
| TC (on-delay timer/enumerated value) | 0AH | |
| US (one-shot timer/set value) | 0BH | |
| UC (one-shot timer/enumerated value) | 0CH | |
| CS (up/down counter/set value) | 0DH | |
| CC (up/down counter/enumerated value) | 0EH | |
| DW (data register) | 0FH | |
| E (event register) | 10H | EW as word device |
| S (system register) | 11H | SW as word device |
| J (transfer register) | 12H | JW as word device |
| Q (receive register) | 13H | QW as word device |
| M (extensional internal register) | 14H | MW as word device |
| LB (work register) | 15H | LBW as word device |
| LR (work register 1 for ladder converter) | 16H | LRW as word device |
| LV (work register 2 for ladder converter) | 17H | LVW as word device |
| LLL (long-word work register) | 18H | Double-word |
| LFF (floating-point work register) | 19H | |
| LWW (word work register) | 1AH | |
| LML (long-word work register) backup area | 1BH | Double-word |
| LGF (floating-point work register) backup area | 1CH | |
| LXW (word work register) backup area | 1DH | |

19.1.5 HIDIC-S10V (Ethernet)

Communication Setting

Editor

Make the following settings on the editor. For more information, see "1.3.2 Ethernet Communication".

- IP address for the V9 unit
 - When specified on the screen program:
[System Setting] → [Hardware Setting] → [Local Port IP Address]
 - When specified on the V9 unit:
Local mode → [LAN Setting]
- Port number for the V9 unit (for communication with PLC)
[System Setting] → [Hardware Setting] → [PLC Properties] → [Communication Setting]
- IP address and port number of the PLC
Register on the [PLC Table] in [System Setting] → [Hardware Setting] → [PLC Properties] → [Target Settings].

PLC

LQE520

Module No. setting switch

| MODU NO | Contents | Remarks |
|---------|----------------------------|---------|
| 0 | Communication via 10BASE-5 | |
| 2 | Communication via 10BASE-T | |

S10V ET.NET

Specify the IP address and the subnet mask.

LQP520

Station No. setting switch

| S/T NO | Setting | Contents |
|--------|---------|--------------------------|
| U L | 0 0 | Set IP address is valid. |
| | F F | 192.192.192.1 is valid. |

Standard system tool

Specify the IP address and the subnet mask.

Available Device Memory

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

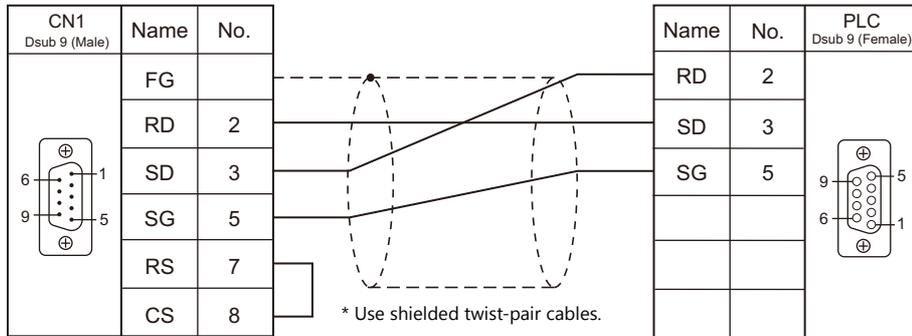
| Device Memory | TYPE | Remarks |
|--|------|--------------------|
| FW (work register) | 00H | |
| X (input) | 01H | XW as word device |
| Y (output) | 02H | YW as word device |
| R (internal relay) | 03H | RW as word device |
| G (global link relay) | 04H | GW as word device |
| K (keep relay) | 05H | KW as word device |
| T (on-delay timer/contact) | 06H | TW as word device |
| U (one-shot timer/contact) | 07H | UW as word device |
| C (up/down counter/contact) | 08H | CW as word device |
| TS (on-delay timer/set value) | 09H | |
| TC (on-delay timer/enumerated value) | 0AH | |
| US (one-shot timer/set value) | 0BH | |
| UC (one-shot timer/enumerated value) | 0CH | |
| CS (up/down counter/set value) | 0DH | |
| CC (up/down counter/enumerated value) | 0EH | |
| DW (data register) | 0FH | |
| E (event register) | 10H | EW as word device |
| S (system register) | 11H | SW as word device |
| J (transfer register) | 12H | JW as word device |
| Q (receive register) | 13H | QW as word device |
| M (extensional internal register) | 14H | MW as word device |
| LB (work register) | 15H | LBW as word device |
| LR (work register 1 for ladder converter) | 16H | LRW as word device |
| LV (work register 2 for ladder converter) | 17H | LVW as word device |
| LLL (long-word work register) | 18H | Double-word |
| LFF (floating-point work register) | 19H | |
| LWW (word work register) | 1AH | |
| LML (long-word work register) backup area | 1BH | Double-word |
| LGF (floating-point work register) backup area | 1CH | |
| LXW (word work register) backup area | 1DH | |
| A (extensional internal register) | 1EH | AW as word device |
| N (nesting coil) | 1FH | NW as word device |
| P (process coil) | 20H | PW as word device |
| V (edge contact) | 21H | VW as word device |
| Z (Z register) | 22H | ZW as word device |
| IW (extensional input) | 23H | |
| OW (extensional output) | 24H | |
| BD (special internal register) | 25H | |

19.1.6 Wiring Diagrams

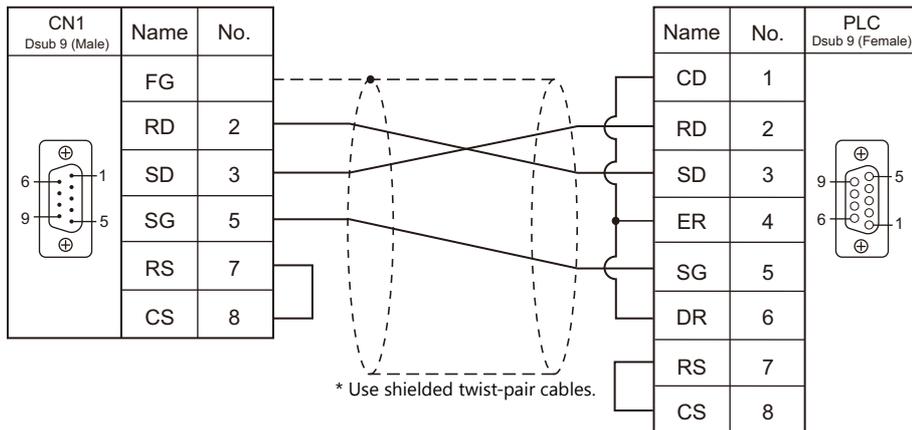
When Connected at CN1:

RS-232C

Wiring diagram 1 - C2



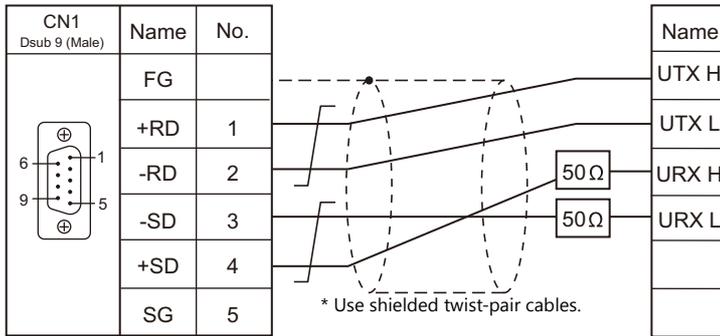
Wiring diagram 2 - C2



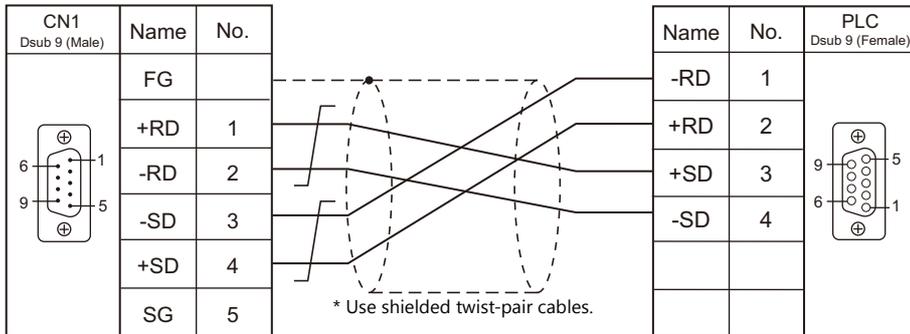
RS-422/RS-485

Wiring diagram 1 - C4

When connecting to the S10xα series, place a resistor of 50Ω (1/2 W) as shown below.



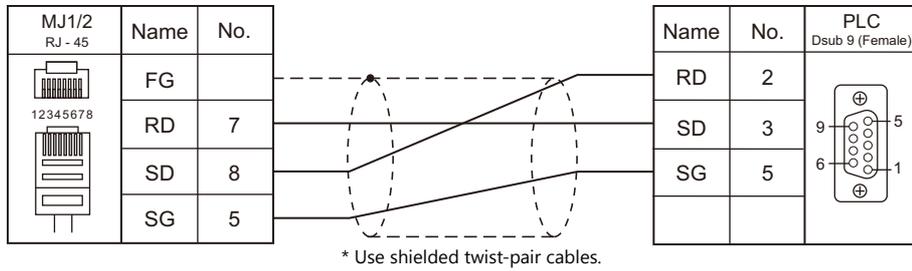
Wiring diagram 2 - C4



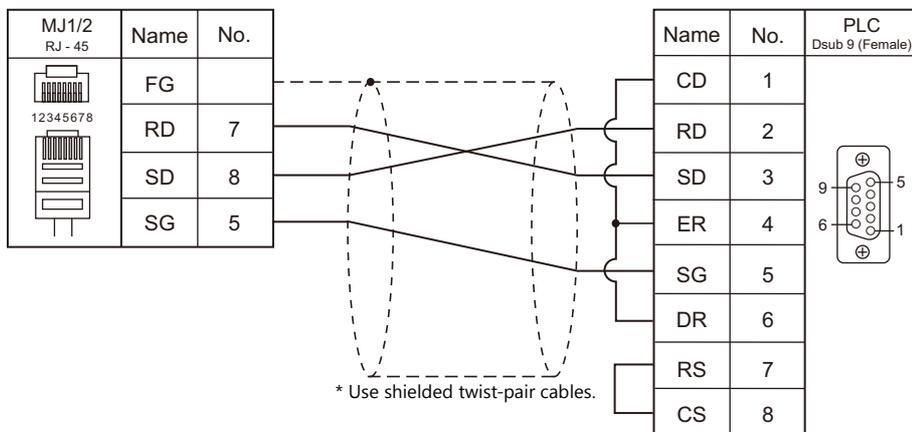
When Connected at MJ1/MJ2:

RS-232C

Wiring diagram 1 - M2



Wiring diagram 2 - M2



MEMO

Please use this page freely.

20. Hitachi Industrial Equipment Systems

20.1 PLC Connection

20.2 Temperature Controller/Servo/Inverter Connection

20.1 PLC Connection

Serial Connection

| PLC Selection on the Editor | CPU | Unit/Port | | Signal Level | Connection | | Ladder Transfer ^{*4} | |
|-----------------------------|----------------|----------------------|-------------|--|--|-------------------------------------|-------------------------------|-------------------------------------|
| | | | | | CN1 | MJ1/MJ2 | | |
| HIDIC-H | H series | COMM-2H | | RS-232C | Hakko Electronics' cable "D9-HI2-H-5M" or Wiring diagram 1 - C2 | Wiring diagram 1 - M2 | X | |
| | | | | RS-422 | Wiring diagram 1 - C4 | X | | |
| | | PERIPHERAL on CPU | | RS-232C | Hakko Electronics' cable "D9-HI2-H-5M" or Wiring diagram 1 - C2 | X | | |
| | | H252C CPU | PERIPHERAL1 | RS-232C | Hakko Electronics' cable "D9-HI2-H-5M" or Wiring diagram 1 - C2 | X | | |
| | PERIPHERAL2 | | RS-232C | Hakko Electronics' cable "D9-HI2-H-5M" + Hitachi's "CNCOM-05" or Wiring diagram 1 - C2 + Hitachi's "CNCOM-05" | X | | | |
| | EH-150 | On CPU | PORT1 | RS-232C | Wiring diagram 2 - C2 ^{*2} | Wiring diagram 2 - M2 | | |
| | | | | RS-422 | Wiring diagram 2 - C4 | Wiring diagram 1 - M4 ^{*3} | | |
| | | EH-SIO ^{*1} | PORT2 | RS-232C | Wiring diagram 2 - C2 ^{*2} | Wiring diagram 2 - M2 ^{*3} | | |
| | | | | RS-422 | Wiring diagram 2 - C2 ^{*2} | Wiring diagram 2 - M2 | | |
| | MICRO-EH | On CPU | PORT1 | RS-232C | Wiring diagram 2 - C2 ^{*2} | Wiring diagram 2 - M2 | | |
| | | | | RS-422 | Wiring diagram 4 - C4 | Wiring diagram 3 - M4 ^{*3} | | |
| | | EH-OB232 | PORT2 | RS-232C | Wiring diagram 2 - C2 ^{*2} | Wiring diagram 2 - M2 | | |
| | Web controller | EH-WD10DR | SERIAL | RS-232C | Wiring diagram 3 - C2 | Wiring diagram 3 - M2 | | |
| | | | | EH-WA23DR | RS-422 | Wiring diagram 5 - C4 | | Wiring diagram 4 - M4 ^{*3} |
| | HIDIC-EHV | EH-150 EHV | EHV-CPU128 | SERIAL | RS-232C | Wiring diagram 2 - C2 ^{*2} | | Wiring diagram 2 - M2 |
| | | | | | RS-422 | Wiring diagram 5 - C4 | | Wiring diagram 4 - M4 ^{*3} |
| EH-SIO ^{*1} | | | PORT1 | RS-232C | Wiring diagram 2 - C2 | Wiring diagram 2 - M2 | | |
| | | | PORT2 | RS-422 | Wiring diagram 3 - C4 | Wiring diagram 2 - M4 ^{*3} | | |

*1 For the EH-SIO unit, EH-CPU548 (version E402 or later) and EH-CPU516 (version E202 or later) can only be used.

*2 Communication is also available using the Hitachi's "EH-RS05" cable with the cable used for the wiring diagram 1-C2.

*3 Communication cannot be established when "transmission control protocol 1, without port" is set. Set "transmission control protocol 2, without port". Note that some CPUs do not support "transmission control protocol 2, without port". For more information, refer to the PLC manual issued by the manufacturer.

*4 For the ladder transfer function, see the V9 Series Reference Manual.

Ethernet Connection

| PLC Selection on the Editor | CPU | Unit/Port | TCP/IP | UDP/IP | Port No. | Keep Alive ^{*1} | Ladder Transfer ^{*2} |
|-----------------------------|----------------|-----------|--------|--------|-----------------------|--------------------------|-------------------------------|
| HIDIC-H (Ethernet) | H series | LAN-ETH2 | X | O | 3004 to 3005 (1 each) | O | X |
| | EH-150 | EH-ETH | | | 3004 to 3007 (1 each) | | |
| | Web controller | ETHERNET | | | | | |
| HIDIC-EHV (Ethernet) | EHV-CPU128 | ETHERNET | | | | | |

*1 For KeepAlive functions, see "1.3.2 Ethernet Communication".

*2 For the ladder transfer function, see the V9 Series Reference Manual.

20.1.1 HIDIC-H

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-------------------|---|---|
| Connection Mode | 1 : 1 / <u>1 : n</u> / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet) | |
| Baud Rate | 4800 / 9600 / <u>19200</u> / 38400 / 57600 / 115K bps | |
| Parity | None / Odd / <u>Even</u> | |
| Signal Level | <u>RS-232C</u> / RS-422/485 | |
| Data Length | <u>7</u> / 8 bits | |
| Stop Bit | <u>1</u> / 2 bits | |
| Target Port No. | 0 to 31 | |
| Transmission Mode | <u>Protocol 2 with port</u> Protocol 1 without port Protocol 2 without port Protocol 1 with port | Protocol 2 achieves higher communication speed, compared to protocol 1. |

COMM-2H

ST No. switch

| ST No. | Setting | Remarks |
|-----------------------------------|---------|--|
| 10 ¹ , 10 ⁰ | 0 to 31 | If a value greater than 31 is set, the unit works as the station No. 31. |

MODE switch

| MODE | RS-232C | RS-422 |
|------|--|---|
| 0 | Transmission control protocol 1 with port | - |
| 2 | Transmission control protocol 1 without port | Transmission control protocol 1 with port |
| 7 | Transmission control protocol 2 with port | - |
| 9 | Transmission control protocol 2 without port | Transmission control protocol 2 with port |

* When connecting to both RS-232C and RS-422, set MODE switch to 9.

DIP switch

| Switch | Setting | Contents |
|--------|---------|----------------|
| 1 | OFF | Bit length 7 |
| 2 | OFF | 19200 bps |
| 3 | ON | |
| 4 | ON | With parity |
| 5 | ON | |
| 6 | ON | Even |
| 7 | OFF | Stop bit 1 |
| 8 | ON | With sum check |

PERIPHERAL Port

No particular setting is necessary on the PLC. The PLC always operates using the parameter shown below. Set the following parameter on V9.

| Item | Setting | Remarks |
|-------------------|-------------------------|---------|
| Signal Level | RS-232C | |
| Baud Rate | 19200 bps | |
| Data Length | 7 bits | ASCII |
| Stop Bit | 1 bit | |
| Parity | Even | |
| Transmission Mode | Protocol 1 without port | |
| Sum Check | Provided | |
| Port Operation | Dedicated port | |

EH-150 CPU

PORT1

Set the signal level and the communication protocol as shown below for PORT1 (dedicated port). Other parameters (7 bits, 1 bit, even) are fixed.

| Signal Level | Communication Protocol | CPU Model |
|--------------|---|--|
| RS-232C | Transmission control protocol 1 | EH-CPU104/104A/208/208A/308/308A/316/316A/448/448A/516/548 |
| | Transmission control protocol 2 | EH-CPU104A/208A/308A/316A/448/448A/516/548 |
| RS-422 | Transmission control protocol 1 | EH-CPU308A/316A/448/448A/516/548 |
| | Transmission control protocol 2 | |
| | Transmission control protocol 1 with port | |
| | Transmission control protocol 2 with port | |
| RS-485 | Transmission control protocol 1 with port | |
| | Transmission control protocol 2 with port | |

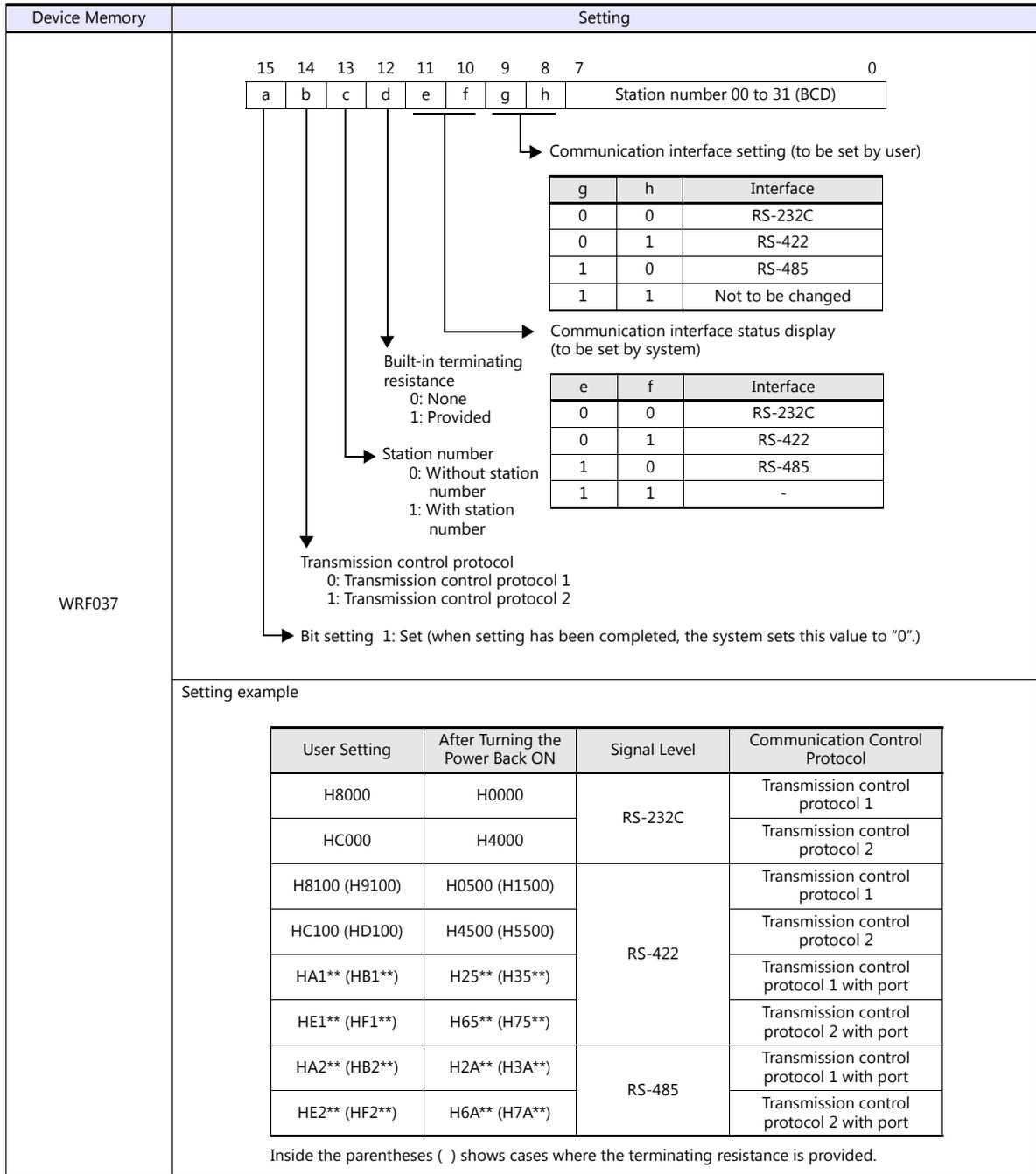
Procedure

1. Turn the PLC off and set the " Mode setting switch" (page 20-3).
2. Turn the power on and check the value for " Special internal output: WRF037" (page 20-4).
3. When the signal level and the communication control protocol have correctly been selected, setting is completed. If they are wrong, set a correct value and turn the power off and back on again.
4. Check the value set for WRF037.

Mode setting switch

| SW3 | SW4 | SW5 | Contents |
|-----|-----|-----|----------------------------|
| ON | ON | ON | Dedicated port, 4,800 bps |
| OFF | ON | | Dedicated port, 9,600 bps |
| ON | OFF | | Dedicated port, 19,200 bps |
| OFF | OFF | | Dedicated port, 38,400 bps |

Special internal output: WRF037



* If the setting is undefined upon power-up, the default setting (transmission control protocol 1, without port, RS-232C) is applied.

PORT2

PORT2 settings are defined as "dedicated port, RS-232C, transmission control protocol 1, 7 bits, 1 bit, even", regardless of the CPU model.

Mode setting switch, PHL switch

| SW6 | PHL Switch | Baud Rate | Remarks |
|-----|------------|-----------|----------------------------------|
| OFF | OFF (Low) | 4800 bps | PHL signal (pin 4 at PORT2) Low |
| ON | OFF (Low) | 9600 bps | |
| OFF | ON (High) | 19200 bps | PHL signal (pin 4 at PORT2) High |
| ON | ON (High) | 38400 bps | |

EH-SIO

PORT1/PORT2

The following table shows the signal level and the communication protocol for each port. Other parameters (7 bits, 1 bit, even) are fixed.

| Port | Signal Level | Communication Protocol | EH-SIO Version |
|-------|--------------|---|-----------------------|
| PORT1 | RS-232C | Transmission control protocol 1 | Version 2.0 and later |
| | | Transmission control protocol 2 | Version 2.1 and later |
| PORT2 | RS-232C | Transmission control protocol 1 | Version 2.0 and later |
| | | Transmission control protocol 2 | Version 2.1 and later |
| | RS-422 | Transmission control protocol 1 | Version 2.0 and later |
| | | Transmission control protocol 2 | Version 2.1 and later |
| | | Transmission control protocol 1 with port | Version 2.0 and later |
| | | Transmission control protocol 2 with port | Version 2.1 and later |
| | RS-485 | Transmission control protocol 2 | Version 2.1 and later |
| | | Transmission control protocol 1 with port | Version 2.0 and later |
| | | Transmission control protocol 2 with port | Version 2.1 and later |

DIP switch 1/2

Set the baud rate for PORT1/2 using the DIPSW1/2 attached to the side of EH-SIO. For more information, refer to the PLC manual issued by the manufacturer.

Ladder program

Make initial settings for the transmission control protocol and the station number. For more information, refer to the PLC manual issued by the manufacturer.

MICRO EH

The following table shows the signal level and the communication protocol for each port. Other parameters (7 bits, 1 bit, even) are fixed.

| CPU Model | Port | Signal Level | Communication Protocol |
|--|-------|--------------|---|
| EH-D10 EH-D14 / EH-A14 EH-D20 / EH-A20 EH-D23 / EH-A23 EH-D28 / EH-A28 EH-D40 / EH-A40 EH-D64 / EH-A64 | PORT1 | RS-232C | Transmission control protocol 1 |
| | | | Transmission control protocol 2 |
| EH-D23 / EH-A23 EH-D28 / EH-A28 | PORT2 | RS-422 | Transmission control protocol 1 |
| | | | Transmission control protocol 2 |
| | | | Transmission control protocol 1 with port |
| | | | Transmission control protocol 2 with port |
| EH-x64xxx + EH-OB232 | PORT2 | RS-232C | Transmission control protocol 1 |
| | | | Transmission control protocol 2 |
| EH-x64xxx + EH-OB485 | PORT2 | RS-422 | Transmission control protocol 1 |
| | | | Transmission control protocol 2 |
| | | | Transmission control protocol 1 with port |
| | | | Transmission control protocol 2 with port |

PORT1

Procedure

1. Turn the PLC off and set the baud rate using the DIPSW.
2. Turn the power on and check the value set for " Special internal output: WRF01A".
3. When the transmission control protocol has correctly been selected, setting is completed. If it is wrong, set a correct value.
4. Set the bit "R7F6" (setting write request) to save the setting in the flash memory.

* It is not necessary to make the setting again upon next power-up once the setting has been saved in the flash memory. Note that the ladder tool cannot be connected when the setting has been saved using the transmission control protocol 2.

DIPSW

| SW1 | SW2 | SW3 | SW4 | Baud Rate |
|-----|-----|-----|-----|-----------|
| ON | OFF | ON | OFF | 38.4 kbps |
| ON | OFF | OFF | OFF | 19.2 kbps |
| OFF | OFF | ON | OFF | 9600 bps |
| OFF | OFF | OFF | OFF | 4800 bps |

Special internal output: WRF01A

| Device Memory | Setting | Contents |
|---------------|---------|---------------------------------|
| WRF01A | H0000 | Transmission control protocol 1 |
| | H8000 | Transmission control protocol 2 |

PORT2

Procedure

1. Check the value set for special internal output "WRF03D".
2. When the setting, such as transmission control protocol or baud rate, has correctly been defined, the setting is completed. If it is wrong, set a correct value. See "User Setting" described in " Special internal output: WRF03D".
3. Check that the value set for WRF03D has been changed to the one shown in the "System Setting" column.
4. Set the bit "R7F6" (setting write request) to save the setting in the flash memory.

* It is not necessary to make the setting again upon next power-up once the setting has been saved in the flash memory.

Special internal output: WRF03D

| Device Memory | Setting | | | | | | | | | | | | | | | | | |
|-----------------|--|---|----------------|-----------|-----------|-------|----------|---------------------------------|-----------|-------|-----------|---------------------------------|-------|-------|---|-------|-------|---|
| WRF03D | <table border="1" style="margin-left: 20px;"> <thead> <tr> <th>d</th> <th>Baud Rate</th> </tr> </thead> <tbody> <tr> <td>00000</td> <td>4800 bps</td> </tr> <tr> <td>00001</td> <td>9600 bps</td> </tr> <tr> <td>00010</td> <td>19.2 kbps</td> </tr> <tr> <td>00011</td> <td>38.4 kbps</td> </tr> </tbody> </table> <p>Station number 0: Without station number 1: With station number</p> <p>Transmission control protocol 0: Transmission control protocol 1 1: Transmission control protocol 2</p> <p>Bit setting 1: Set (when setting completed, the system sets this value to "0".)</p> | d | Baud Rate | 00000 | 4800 bps | 00001 | 9600 bps | 00010 | 19.2 kbps | 00011 | 38.4 kbps | | | | | | | |
| | d | Baud Rate | | | | | | | | | | | | | | | | |
| 00000 | 4800 bps | | | | | | | | | | | | | | | | | |
| 00001 | 9600 bps | | | | | | | | | | | | | | | | | |
| 00010 | 19.2 kbps | | | | | | | | | | | | | | | | | |
| 00011 | 38.4 kbps | | | | | | | | | | | | | | | | | |
| Setting example | <table border="1" style="width: 100%;"> <thead> <tr> <th>User Setting</th> <th>System Setting</th> <th>Interface</th> <th>Baud Rate</th> </tr> </thead> <tbody> <tr> <td>H8300</td> <td>H0300</td> <td>Transmission control protocol 1</td> <td rowspan="4" style="text-align: center; vertical-align: middle;">38.4 kbps</td> </tr> <tr> <td>HC300</td> <td>H4300</td> <td>Transmission control protocol 2</td> </tr> <tr> <td>HA300</td> <td>H2300</td> <td>Transmission control protocol 1 with port</td> </tr> <tr> <td>HE300</td> <td>H6300</td> <td>Transmission control protocol 2 with port</td> </tr> </tbody> </table> | User Setting | System Setting | Interface | Baud Rate | H8300 | H0300 | Transmission control protocol 1 | 38.4 kbps | HC300 | H4300 | Transmission control protocol 2 | HA300 | H2300 | Transmission control protocol 1 with port | HE300 | H6300 | Transmission control protocol 2 with port |
| User Setting | System Setting | Interface | Baud Rate | | | | | | | | | | | | | | | |
| H8300 | H0300 | Transmission control protocol 1 | 38.4 kbps | | | | | | | | | | | | | | | |
| HC300 | H4300 | Transmission control protocol 2 | | | | | | | | | | | | | | | | |
| HA300 | H2300 | Transmission control protocol 1 with port | | | | | | | | | | | | | | | | |
| HE300 | H6300 | Transmission control protocol 2 with port | | | | | | | | | | | | | | | | |

Web Controller

The following table shows the signal level and the communication protocol for each PLC. Other parameters (7 bits, 1 bit, even) are fixed.

| PLC | Port | Signal Level | Communication Protocol |
|-----------|---|--------------|---|
| EH-WD10DR | SERIAL | RS-232C | Transmission control protocol 1 |
| | | | Transmission control protocol 2 |
| EH-WA23DR | PORT1 | RS-232C | Transmission control protocol 1 |
| | | | Transmission control protocol 2 |
| | | RS-422 | Transmission control protocol 1 |
| | | | Transmission control protocol 2 |
| | | | Transmission control protocol 1 with port |
| | | | Transmission control protocol 2 with port |
| | | RS-485 | Transmission control protocol 2 |
| | | | Transmission control protocol 1 with port |
| | Transmission control protocol 2 with port | | |

Procedure

Connect the computer (PC) to the web controller and make the setting for the PLC with the web browser. For more information, refer to the PLC manual issued by the manufacturer.

System configuration (RS-232C protocol/serial protocol → passive HI protocol)

Make settings for "Interface Type", "Transmission Control Procedure", "Transmission Speed".

Available Device Memory

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|----------------------------------|------|-------------------|
| WR (internal output/word) | 00H | |
| X (external input) | 01H | WX as word device |
| Y (external output) | 02H | WY as word device |
| L (CPU link area) | 03H | WL as word device |
| M (data area) | 04H | WM as word device |
| TC (timer, counter/elapsed time) | 05H | |
| R (internal output/bit) | 06H | |
| TD (timer, counter/contact) | 07H | |
| WN (network input/output) | 08H | |

20.1.2 HIDIC-H (Ethernet)

Communication Setting

Editor

Make the following settings on the editor. For more information, see "1.3.2 Ethernet Communication".

- IP address for the V9 unit
 - When specified on the screen program:
[System Setting] → [Hardware Setting] → [Local Port IP Address]
 - When specified on the V9 unit:
Local mode → [LAN Setting]
- Port number for the V9 unit (for communication with PLC)
[System Setting] → [Hardware Setting] → [PLC Properties] → [Communication Setting]
- IP address and port number of the PLC
Register on the [PLC Table] in [System Setting] → [Hardware Setting] → [PLC Properties] → [Target Settings].

LAN-ETH2 (H Series)

The IP address setting tool can be downloaded from the Hitachi Industrial Equipment Systems website.

Connect the computer (PC) to the RS-232C port of PORT1 and specify the IP address and the task port. For more information, refer to the PLC manual issued by the manufacturer.

EH-ETH (EH-150)

Make settings using the web server function incorporated in EH-ETH. For more information, refer to the PLC manual issued by the manufacturer.

IP address information setup

Set the IP address and the subnet mask.

Task code information setup

Select [UDP/IP] for [Protocol] and specify the port number.

Web Controller

Connect the computer (PC) to the web controller and make the setting for the PLC with the web browser. For more information, refer to the PLC manual issued by the manufacturer.

System configuration (IP address)

Specify the IP address and the subnet mask.

System configuration (ethernet protocol → passive HI protocol)

Select [UDP/IP] for [Task code port] and specify the port number.

Available Device Memory

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|----------------------------------|------|-------------------|
| WR (internal output/word) | 00H | |
| X (external input) | 01H | WX as word device |
| Y (external output) | 02H | WY as word device |
| L (CPU link area) | 03H | WL as word device |
| M (data area) | 04H | WM as word device |
| TC (timer, counter/elapsed time) | 05H | |
| R (internal output/bit) | 06H | |
| TD (timer, counter/contact) | 07H | |
| WN (network input/output) | 08H | |

20.1.3 HIDIC-EHV

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-------------------|---|---|
| Connection Mode | 1 : 1 / <u>1 : n</u> / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet) | |
| Signal Level | <u>RS-232C</u> / RS-422/485 | |
| Baud Rate | 4800 / 9600 / 19200 / <u>38400</u> / 57600 bps | |
| Data Length | 7 bits | |
| Stop Bit | 1 bit | |
| Parity | Even | |
| Target Port No. | 0 to 31 | |
| Transmission Mode | <u>Protocol 2 with port</u> Protocol 1 without port Protocol 2 without port Protocol 1 with port | Protocol 2 achieves higher communication speed, compared to protocol 1. |

EHV-CPU

CPU communication setting on control editor

| Item | Setting | | | | | | | | | | | | | | |
|------------------------------|--|-----------|------------------------|---------|---|---|--------|---|---|---|---|--------|---|---|---|
| Serial communication setting | Dedicated | | | | | | | | | | | | | | |
| Port type | RS-232C/RS-422/RS-485 The following table shows the combination of port type and communication protocols available. <table border="1" style="margin-left: 20px;"> <thead> <tr> <th>Port Type</th> <th>Communication Protocol</th> </tr> </thead> <tbody> <tr> <td rowspan="2">RS-232C</td> <td>Transmission control protocol 1 (1 : 1)</td> </tr> <tr> <td>Transmission control protocol 2 (1 : 1)</td> </tr> <tr> <td rowspan="4">RS-422</td> <td>Transmission control protocol 1 (1 : 1)</td> </tr> <tr> <td>Transmission control protocol 2 (1 : 1)</td> </tr> <tr> <td>Transmission control protocol 1 (1 : n)</td> </tr> <tr> <td>Transmission control protocol 2 (1 : n)</td> </tr> <tr> <td rowspan="3">RS-485</td> <td>Transmission control protocol 2 (1 : 1)</td> </tr> <tr> <td>Transmission control protocol 1 (1 : n)</td> </tr> <tr> <td>Transmission control protocol 2 (1 : n)</td> </tr> </tbody> </table> | Port Type | Communication Protocol | RS-232C | Transmission control protocol 1 (1 : 1) | Transmission control protocol 2 (1 : 1) | RS-422 | Transmission control protocol 1 (1 : 1) | Transmission control protocol 2 (1 : 1) | Transmission control protocol 1 (1 : n) | Transmission control protocol 2 (1 : n) | RS-485 | Transmission control protocol 2 (1 : 1) | Transmission control protocol 1 (1 : n) | Transmission control protocol 2 (1 : n) |
| Port Type | Communication Protocol | | | | | | | | | | | | | | |
| RS-232C | Transmission control protocol 1 (1 : 1) | | | | | | | | | | | | | | |
| | Transmission control protocol 2 (1 : 1) | | | | | | | | | | | | | | |
| RS-422 | Transmission control protocol 1 (1 : 1) | | | | | | | | | | | | | | |
| | Transmission control protocol 2 (1 : 1) | | | | | | | | | | | | | | |
| | Transmission control protocol 1 (1 : n) | | | | | | | | | | | | | | |
| | Transmission control protocol 2 (1 : n) | | | | | | | | | | | | | | |
| RS-485 | Transmission control protocol 2 (1 : 1) | | | | | | | | | | | | | | |
| | Transmission control protocol 1 (1 : n) | | | | | | | | | | | | | | |
| | Transmission control protocol 2 (1 : n) | | | | | | | | | | | | | | |
| Baud rate | 4800 / 9600 / 19200 / <u>38400</u> / 57600 bps | | | | | | | | | | | | | | |
| Communication protocol | See "Port Type" shown above. | | | | | | | | | | | | | | |
| Station number | 0 to 31 (to be specified when "with port" is selected) | | | | | | | | | | | | | | |

EH-SIO

PORT1/PORT2

The following table shows the signal level and the communication protocol for each port. Other parameters (7 bits, 1 bit, even) are fixed.

| Port | Signal Level | Communication Protocol | EH-SIO Version |
|-------|--------------|---|-----------------------|
| PORT1 | RS-232C | Transmission control protocol 1 | Version 2.0 and later |
| | | Transmission control protocol 2 | Version 2.1 and later |
| PORT2 | RS-232C | Transmission control protocol 1 | Version 2.0 and later |
| | | Transmission control protocol 2 | Version 2.1 and later |
| | RS-422 | Transmission control protocol 1 | Version 2.0 and later |
| | | Transmission control protocol 2 | Version 2.1 and later |
| | | Transmission control protocol 1 with port | Version 2.0 and later |
| | | Transmission control protocol 2 with port | Version 2.1 and later |
| | RS-485 | Transmission control protocol 2 | Version 2.1 and later |
| | | Transmission control protocol 1 with port | Version 2.0 and later |
| | | Transmission control protocol 2 with port | Version 2.1 and later |
| | | Transmission control protocol 2 with port | Version 2.1 and later |

DIP switch 1/2

Set the baud rate for PORT1/2 using the DIPSW1/2 attached to the side of EH-SIO. For more information, refer to the PLC manual issued by the manufacturer.

Ladder program

Make initial settings for the transmission control protocol and the station number. For more information, refer to the PLC manual issued by the manufacturer.

Available Device Memory

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|----------------------------------|------|--------------------|
| WR (internal output/word) | 00H | |
| X (external input) | 01H | WX as word device |
| Y (external output) | 02H | WY as word device |
| L (CPU link area) | 03H | WL as word device |
| M (data area) | 04H | WM as word device |
| TC (timer, counter/elapsed time) | 05H | |
| R (internal output/bit) | 06H | |
| TD (timer, counter/contact) | 07H | |
| WN (network input/output) | 08H | |
| CL (counter clear) | 09H | |
| EX (extensional external input) | 0BH | WEX as word device |
| EY (extensional external output) | 0CH | WEY as word device |

20.1.4 HIDIC-EHV (Ethernet)

Communication Setting

Editor

Make the following settings on the editor. For more information, see "1.3.2 Ethernet Communication".

- IP address for the V9 unit
 - When specified on the screen program:
[System Setting] → [Hardware Setting] → [Local Port IP Address]
 - When specified on the V9 unit:
Local mode → [LAN Setting]
- Port number for the V9 unit (for communication with PLC)
[System Setting] → [Hardware Setting] → [PLC Properties] → [Communication Setting]
- IP address and port number of the PLC
Register on the [PLC Table] in [System Setting] → [Hardware Setting] → [PLC Properties] → [Target Settings].

PLC

Control Editor

IP address setting

| Item | Contents | |
|-----------------|---------------------------------------|--|
| IP address | Specify the IP address for the PLC. | |
| Subnet mask | Specify the subnet mask for the PLC. | |
| Default gateway | Specify according to the environment. | |

Ethernet communication (task code) setting

| Item | Contents | |
|----------|--|--|
| Valid | Select a port to which the V9 unit is connected and make the port enabled. | |
| Port No. | Set the port number of the PLC. | |
| Protocol | UDP/IP | |

Available Device Memory

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

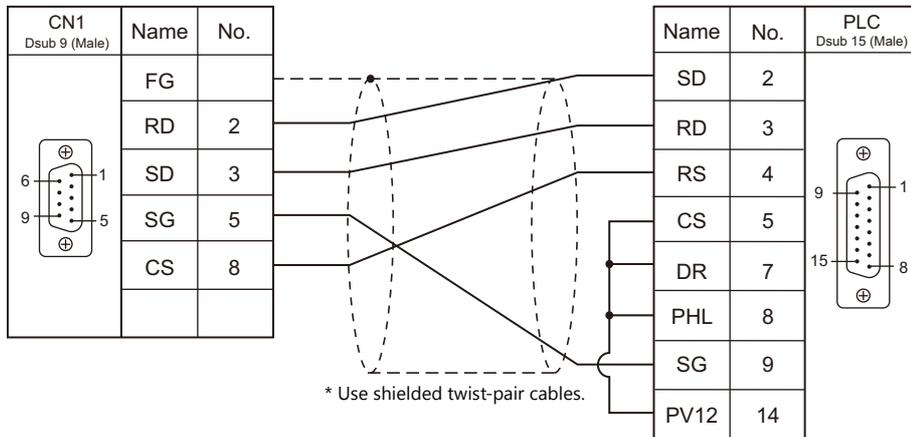
| Device Memory | TYPE | Remarks |
|----------------------------------|------|--------------------|
| WR (internal output/word) | 00H | |
| X (external input) | 01H | WX as word device |
| Y (external output) | 02H | WY as word device |
| L (CPU link area) | 03H | WL as word device |
| M (data area) | 04H | WM as word device |
| TC (timer, counter/elapsed time) | 05H | |
| R (internal output/bit) | 06H | |
| TD (timer, counter/contact) | 07H | |
| WN (network input/output) | 08H | |
| CL (counter clear) | 09H | |
| EX (extensional external input) | 0BH | WEX as word device |
| EY (extensional external output) | 0CH | WEY as word device |

20.1.5 Wiring Diagrams

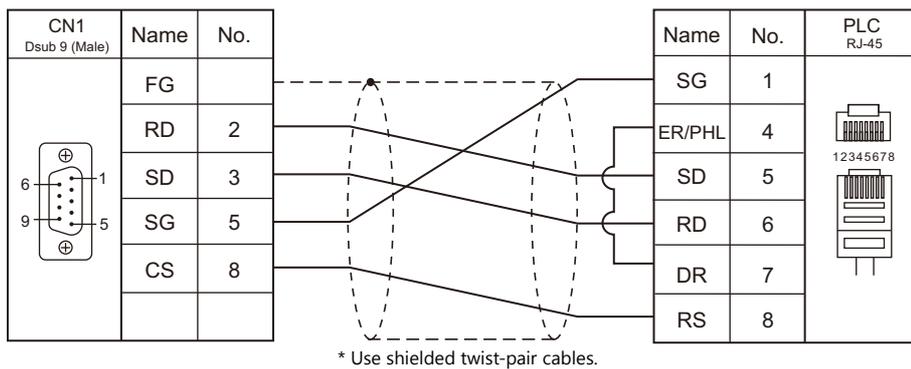
When Connected at CN1:

RS-232C

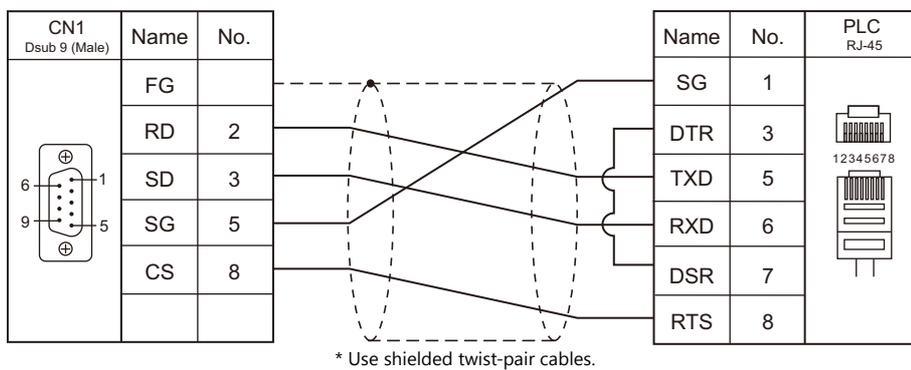
Wiring diagram 1 - C2



Wiring diagram 2 - C2

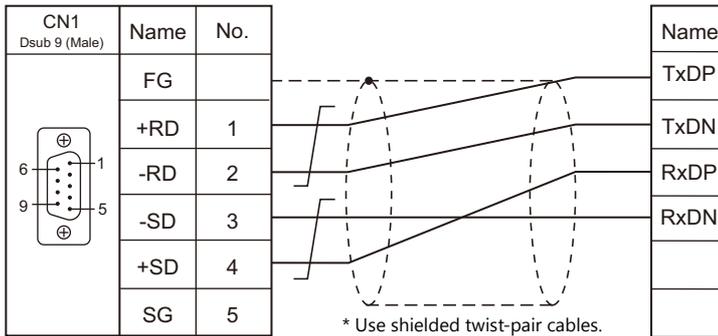


Wiring diagram 3 - C2

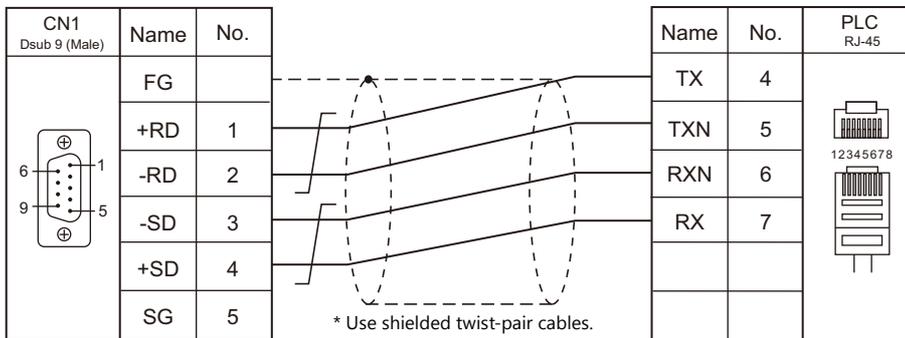


RS-422/RS-485

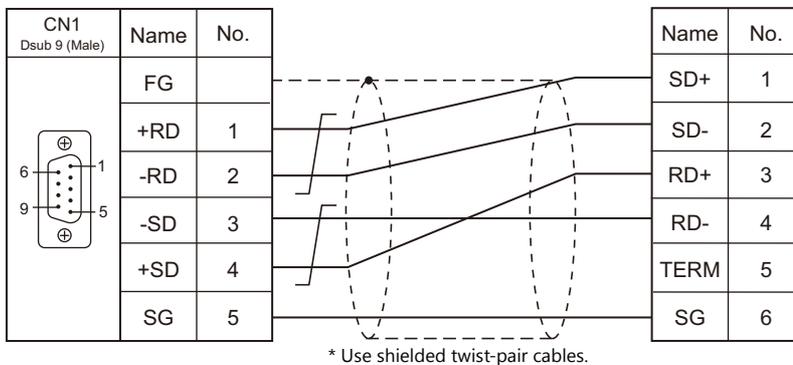
Wiring diagram 1 - C4



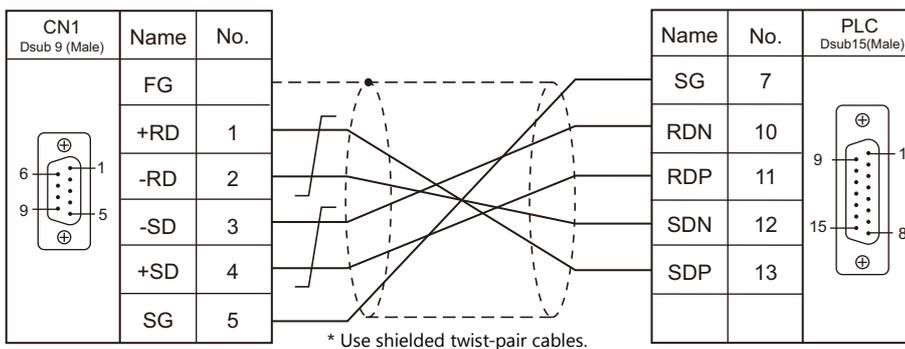
Wiring diagram 2 - C4



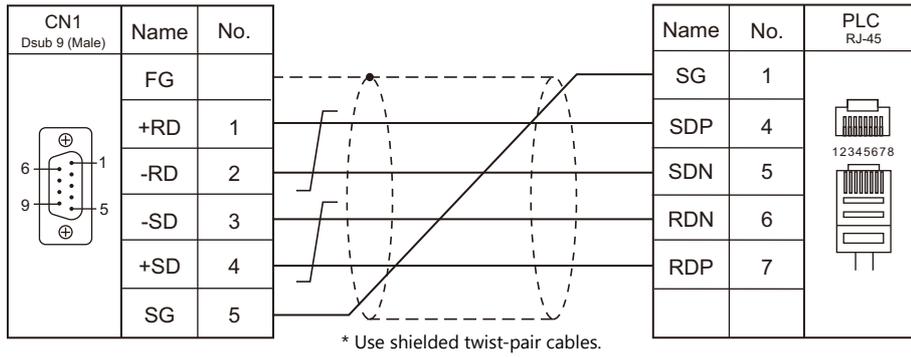
Wiring diagram 3 - C4



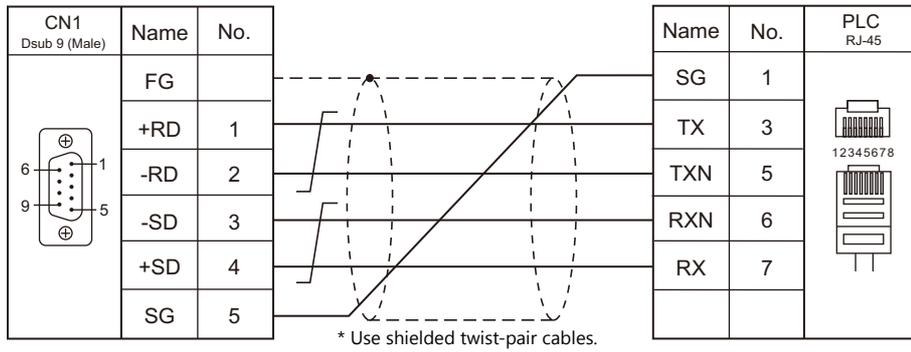
Wiring diagram 4 - C4



Wiring diagram 5 - C4



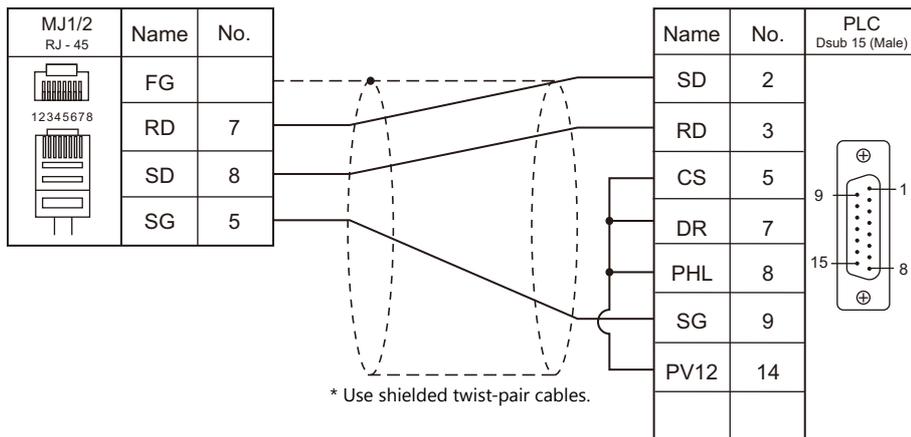
Wiring diagram 6 - C4



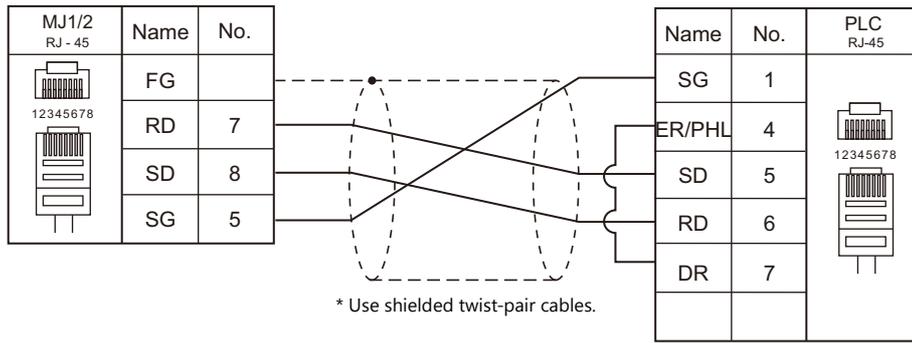
When Connected at MJ1/MJ2:

RS-232C

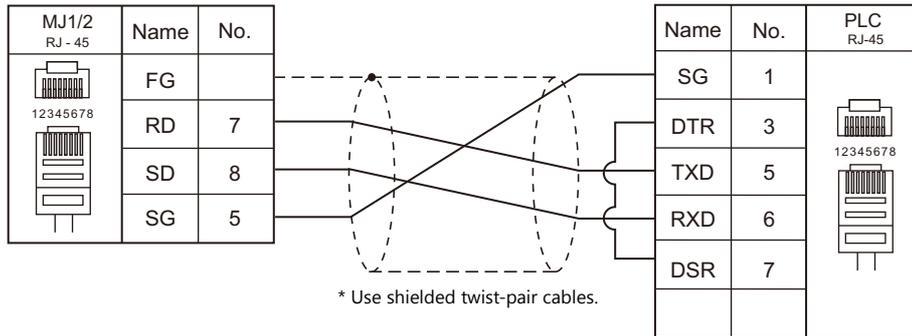
Wiring diagram 1 - M2



Wiring diagram 2 - M2

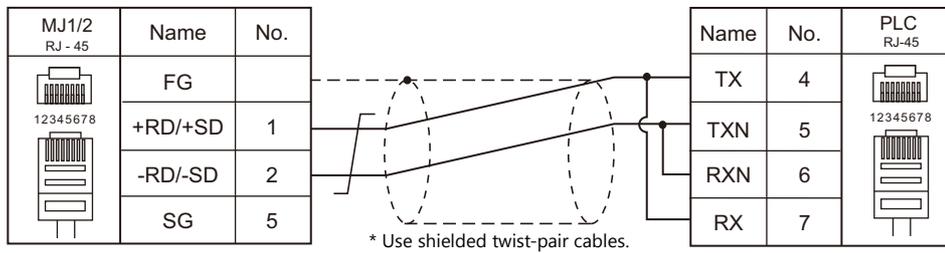


Wiring diagram 3 - M2

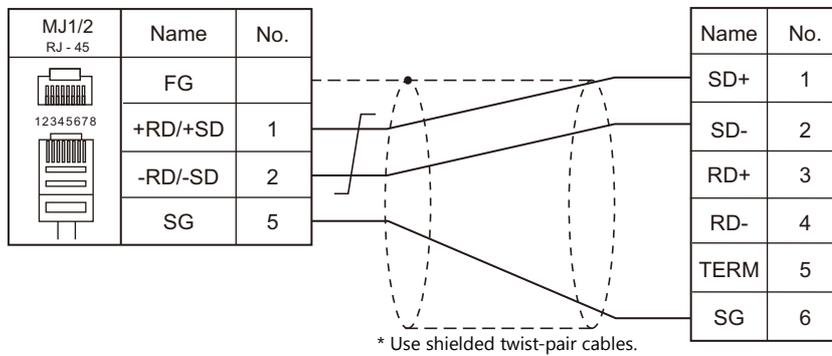


RS-422/RS-485

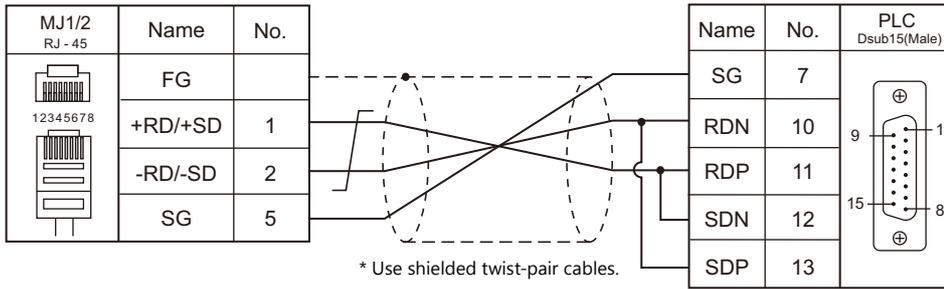
Wiring diagram 1 - M4



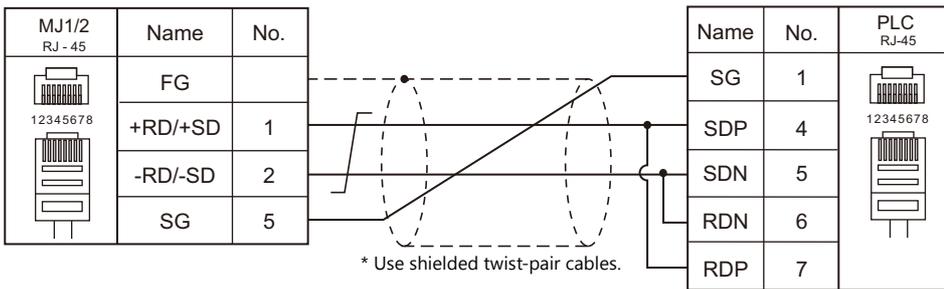
Wiring diagram 2 - M4



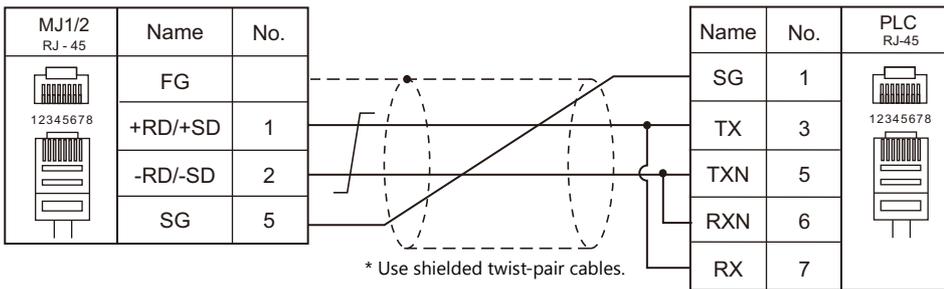
Wiring diagram 3 - M4



Wiring diagram 4 - M4



Wiring diagram 5 - M4



20.2 Temperature Controller/Servo/Inverter Connection

Inverter

| PLC Selection on the Editor | Model | Port | Signal Level | Connection | | Lst File |
|-----------------------------|------------------|------|--------------|-----------------------|-----------------------|-------------|
| | | | | CN1 | MJ1/MJ2 | |
| SJ300 series | SJ300 SJH300 | TM2 | RS-485 | Wiring diagram 1 - C4 | Wiring diagram 1 - M4 | H_SJ300.Lst |
| SJ700 series | SJ700 SJ700-2 | TM2 | RS-485 | Wiring diagram 1 - C4 | Wiring diagram 1 - M4 | H_SJ700.Lst |

20.2.1 SJ300 Series

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|---|---------|
| Connection Mode | <u>1</u> : 1 / <u>1:n</u> / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet) | |
| Signal Level | RS-232C / <u>RS-422/485</u> | |
| Baud Rate | <u>4800</u> / 9600 / 19200 bps | |
| Data Length | <u>7</u> / 8 bits | |
| Stop Bit | <u>1</u> / 2 bits | |
| Parity | <u>None</u> / Odd / Even | |
| Target Port No. | <u>1</u> to 32 | |

Inverter

Parameter

The communication parameters can be set using keys attached to the inverter.

Be sure to match the settings to those made under [Communication Setting] of the editor.

(Underlined setting: default)

| Function Code | Function Name | Setting | Remarks | |
|-----------------------------------|---------------|--|---|--|
| Basic setting | A001 | Frequency command selection | 03: RS-485 | To give the frequency command from V9, always select "03". |
| | A002 | Operation command selection | 03: RS-485 | To give the operation command from V9, always select "03". |
| Communication function adjustment | C070 | Data command selection | 03: RS-485 | |
| | C071 | Baud rate selection | <u>04: 4800 bps</u> 05: 9600 bps 06: 19200 bps | |
| | C072 | Communication station number selection | <u>1</u> to 32. | |
| | C073 | Communication bit length selection | <u>7: 7 bits</u> 8: 8 bits | |
| | C074 | Communication parity selection | <u>00: No parity</u> 01: Even parity 02: Odd parity | |
| | C075 | Communication stop bit selection | <u>1: 1 bit</u> 2: 2 bits | |
| | C078 | Communication latency | <u>0</u> to 1000. (msec) | |

Terminating resistance

Short-circuit RP-SN (control terminal block) on the terminal inverter.

Available Device Memory

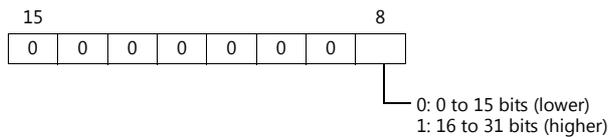
The available setting range of device memory varies depending on the model. Be sure to set within the range available for the model to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|------------------|------|------------------------|
| d | 00H | Double-word, read only |
| F | 01H | Double-word |
| A | 02H | Double-word |
| b | 03H | Double-word |
| C | 04H | Double-word |
| H | 05H | Double-word |
| P | 06H | Double-word |
| T (trip history) | 07H | Double-word, read only |

Indirect Device Memory Designation

| | 15 | 8 7 | 0 |
|-------|-------------------|-----------------|---|
| n + 0 | Models (11 to 18) | Device type | |
| n + 1 | Address No. | | |
| n + 2 | Expansion code * | Bit designation | |
| n + 3 | 00 | Station number | |

* In the expansion code, set which word, higher or lower, is to be read when a double-word address is specified.



PLC_CTL

Macro command "PLC_CTL F0 F1 F2"

| Contents | F0 | F1 (= \$u n) | | F2 |
|---|---------------------|--------------|--|----|
| Normal turn, reverse turn or stop command | 1 - 8 (PLC1 - 8) | n | Station number | 3 |
| | | n + 1 | Command: 0 | |
| | | n + 2 | 0: Stop command 1: Normal turn command 2: Reverse turn command | |
| Frequency command setting | 1 - 8 (PLC1 - 8) | n | Station number | 3 |
| | | n + 1 | Command: 1 | |
| | | n + 2 | Frequency (0 to 400 Hz) | |

| Contents | F0 | F1 (= \$u n) | F2 | | | | | | | | | | | | | | | |
|-------------------------------------|--|---|---|----|----|----|----|----|----|---|---|---|---|---|---|---|---|---|
| Intelligent terminal status setting | 1 - 8 (PLC1 - 8) | n | Station number | | | | | | | | | | | | | | | |
| | | n + 1 | Command: 2 | | | | | | | | | | | | | | | |
| | | n + 2 | Data (HH) | | | | | | | | | | | | | | | |
| | | | <table border="1"> <tr> <td>15</td><td>14</td><td>13</td><td>12</td><td>11</td><td>10</td><td>9</td><td>8</td><td>7</td><td>6</td><td>5</td><td>4</td><td>3</td><td>2</td><td>1</td><td>0</td> </tr> </table> Bit 0: "STAT" Pulse train input enabled | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 |
| | | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | |
| n + 3 | Data (HL) | | | | | | | | | | | | | | | | | |
| | <table border="1"> <tr> <td>15</td><td>14</td><td>13</td><td>12</td><td>11</td><td>10</td><td>9</td><td>8</td><td>7</td><td>6</td><td>5</td><td>4</td><td>3</td><td>2</td><td>1</td><td>0</td> </tr> </table> Bit 0: "SF1" Multistep speed (bit operation) Bit 1: "SF2" Multistep speed (bit operation) Bit 2: "SF3" Multistep speed (bit operation) Bit 3: "SF4" Multistep speed (bit operation) Bit 4: "SF5" Multistep speed (bit operation) Bit 5: "SF6" Multistep speed (bit operation) Bit 6: "SF7" Multistep speed (bit operation) Bit 7: "OLR" Overload limitation selection Bit 8: "TL" Torque limitation valid/invalid Bit 9: "TRQ1" Torque limit selection 1 Bit 10: "TRQ2" Torque limit selection 2 Bit 11: "PPI" P/PI selection Bit 12: "BOK" Brake check Bit 13: "ORT" Orientation Bit 14: "LAC" LAD cancel Bit 15: "PCLR" Positioning deviation clear | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | |
| 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | | | |
| n + 4 | Data (LH) | | | | | | | | | | | | | | | | | |
| | <table border="1"> <tr> <td>15</td><td>14</td><td>13</td><td>12</td><td>11</td><td>10</td><td>9</td><td>8</td><td>7</td><td>6</td><td>5</td><td>4</td><td>3</td><td>2</td><td>1</td><td>0</td> </tr> </table> Bit 0: "AT" Analog input selection Bit 1: "SET3" 3rd control Bit 2: "RS" Reset Bit 3: -- Bit 4: "STA" 3-wire start Bit 5: "STP" 3-wire retain Bit 6: "F/R" 3-wire normal/reverse turn Bit 7: "PID" PID selection (valid/invalid) Bit 8: "PIDC" PID integral reset Bit 9: -- Bit 10: "CAS" Control gain selection Bit 11: "UP" Remote control acceleration Bit 12: "DWN" Remote control deceleration Bit 13: "UDC" Remote control data clear Bit 14: -- Bit 15: "OPE" Forced operation | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | |
| 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | | | |
| n + 5 | Data (LL) | | | | | | | | | | | | | | | | | |
| | | <table border="1"> <tr> <td>15</td><td>14</td><td>13</td><td>12</td><td>11</td><td>10</td><td>9</td><td>8</td><td>7</td><td>6</td><td>5</td><td>4</td><td>3</td><td>2</td><td>1</td><td>0</td> </tr> </table> Bit 0: "FW" Normal turn command Bit 1: "RV" Reverse turn command Bit 2: "CF1" Multistep speed 1 (binary operation) Bit 3: "CF2" Multistep speed 2 (binary operation) Bit 4: "CF3" Multistep speed 3 (binary operation) Bit 5: "CF4" Multistep speed 4 (binary operation) Bit 6: "JG" Jogging (inching operation) Bit 7: "DB" External DC braking Bit 8: "SET" 2nd control Bit 9: "2CH" 2-step acceleration/deceleration Bit 10: -- Bit 11: "FRS" Free-run stop Bit 12: "EXP" External trip Bit 13: "USP" Unattended start protection function Bit 14: "CS" Commercial switching Bit 15: "SFT" Soft lock (control terminal block) | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | | | |

| Contents | F0 | F1 (= \$u n) | | F2 |
|---|---------------------|--------------|--|----|
| Inverter status readout | 1 - 8 (PLC1 - 8) | n | Station number | 2 |
| | | n + 1 | Command: 4 | |
| | | n + 2 | Status A (BCD) 00: Initial status 01: Waiting for Vdc establishment 02: Stopping 03: Running 04: FRS in progress 05: JG in progress 06: DB in progress 07: F acquisition in progress 08: Retry in progress 09: UV in progress 10: Tripping 11: Waiting for reset | |
| | | n + 3 | Status B (BCD) 00: Stopping 01: Running 02: Tripping | |
| | | n + 4 | Status C (BCD) 00: -- 01: Stop 02: Deceleration 03: Constant speed 04: Acceleration 05: Normal turn 06: Reverse turn 07: Normal to reverse turn 08: Reverse to normal turn 09: Normal turn start 10: Reverse turn start | |
| Resetting of setting value to default * | 1 - 8 (PLC1 - 8) | n | Station number | 2 |
| | | n + 1 | Command: 8 | |
| Check for EEPROM availability | 1 - 8 (PLC1 - 8) | n | Station number | 2 |
| | | n + 1 | Command: 9 | |
| | | n + 2 | 01: Allowed | |
| Storing of setting values in EEPROM | 1 - 8 (PLC1 - 8) | n | Station number | 2 |
| | | n + 1 | Command: 10 | |
| Re-calculation of internal constant | 1 - 8 (PLC1 - 8) | n | Station number | 2 |
| | | n + 1 | Command: 11 | |

 Return data: Data stored from inverter to V series

* When the initialize parameter of "b084" is set to "00", only trip history is cleared.

20.2.2 SJ700 Series

Communication Setting

Editor

Communication setting

(Underlined setting: default)

| Item | Setting | Remarks |
|-----------------|--|---------|
| Connection Mode | 1 : 1 / <u>1:n</u> / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet) | |
| Signal Level | RS-232C / <u>RS-422/485</u> | |
| Baud Rate | <u>4800</u> / 9600 / 19200 bps | |
| Data Length | <u>7</u> / 8 bits | |
| Stop Bit | <u>1</u> / 2 bits | |
| Parity | <u>None</u> / Odd / Even | |
| Target Port No. | <u>1</u> to 32 | |

Inverter

Parameter

The communication parameters can be set using keys attached to the inverter.

Be sure to match the settings to those made under [Communication Setting] of the editor.

(Underlined setting: default)

| Function Code | Function Name | Setting | Remarks | |
|-----------------------------------|------------------------------|--|---|--|
| Basic setting | A001 | Frequency command selection | 03: RS-485 | To give the frequency command from V9, always select "03". |
| | A002 | Operation command selection | 03: RS-485 | To give the operation command from V9, always select "03". |
| Communication function adjustment | C071 | Baud rate selection | <u>04: 4800 bps</u> 05: 9600 bps 06: 19200 bps | |
| | C072 | Communication station number selection | <u>1</u> to 32. | |
| | C073 | Communication bit length selection | <u>7: 7 bits</u> 8: 8 bits | |
| | C074 | Communication parity selection | <u>00: No parity</u> 01: Even parity 02: Odd parity | |
| | C075 | Communication stop bit selection | <u>1: 1 bit</u> 2: 2 bits | |
| | C076 | Communication error selection | 02: Ignored | |
| | C077 | Communication trip time | <u>0.00</u> - 99.99 (s) | |
| | C078 | Communication latency | <u>0</u> - 1000. (ms) | |
| C079 | Communication mode selection | 00: ASCII | | |

Terminating resistance

Short-circuit RP-SN (control terminal block) on the terminal inverter.

Available Device Memory

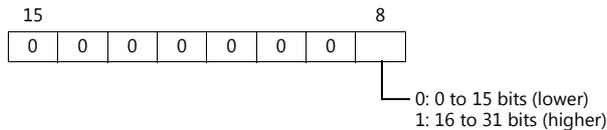
The available setting range of device memory varies depending on the model. Be sure to set within the range available for the model to be used. Use [TYPE] when assigning indirect device memory for macro programs.

| Device Memory | TYPE | Remarks |
|------------------|------|------------------------|
| d | 00H | Double-word, read only |
| F | 01H | Double-word |
| A | 02H | Double-word |
| b | 03H | Double-word |
| C | 04H | Double-word |
| H | 05H | Double-word |
| P | 06H | Double-word |
| T (trip history) | 07H | Double-word, read only |

Indirect Device Memory Designation

| | 15 | 8 7 | 0 |
|-------|-------------------|-----|-----------------|
| n + 0 | Models (11 to 18) | | Device type |
| n + 1 | Address No. | | |
| n + 2 | Expansion code * | | Bit designation |
| n + 3 | 00 | | Station number |

* In the expansion code, set which word, higher or lower, is to be read when a double-word address is specified.



PLC_CTL

Macro command "PLC_CTL F0 F1 F2"

| Contents | F0 | F1 (= \$u n) | | F2 |
|---|---------------------|--------------|--|----|
| Normal turn, reverse turn or stop command | 1 - 8 (PLC1 - 8) | n | Station number | 3 |
| | | n + 1 | Command: 0 | |
| | | n + 2 | 0: Stop command 1: Normal turn command 2: Reverse turn command | |
| Frequency command setting | 1 - 8 (PLC1 - 8) | n | Station number | 3 |
| | | n + 1 | Command: 1 | |
| | | n + 2 | Frequency (0 to 400 Hz) | |

| Contents | F0 | F1 (= \$u n) | F2 | | | | | | | | | | | | | | | |
|-------------------------------------|---|--|---|----|----|----|----|----|----|---|---|---|---|---|---|---|---|---|
| Intelligent terminal status setting | 1 - 8 (PLC1 - 8) | n | Station number | | | | | | | | | | | | | | | |
| | | n + 1 | Command: 2 | | | | | | | | | | | | | | | |
| | | n + 2 | Data (HH) | | | | | | | | | | | | | | | |
| | | | <table border="1"> <tr> <td>15</td><td>14</td><td>13</td><td>12</td><td>11</td><td>10</td><td>9</td><td>8</td><td>7</td><td>6</td><td>5</td><td>4</td><td>3</td><td>2</td><td>1</td><td>0</td> </tr> </table> <p>Bit 0: "STAT" Pulse train position command enabled Bit 1: -- Bit 2: "ADD" Set frequency addition Bit 3: "F-TM": Forced terminal Bit 4: "ATR" Torque command input enabled Bit 5: "KHC" Integral power clear Bit 6: "SON" Servo ON Bit 7: "FOC" Pre-excitation Bit 8: "MI1" General-purpose input 1 Bit 9: "MI2" General-purpose input 2 Bit 10: "MI3" General-purpose input 3 Bit 11: "MI4" General-purpose input 4 Bit 12: "MI5" General-purpose input 5 Bit 13: "MI6" General-purpose input 6 Bit 14: "MI7" General-purpose input 7 Bit 15: "MI8" General-purpose input 8</p> | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 |
| | | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | |
| n + 3 | Data (HL) | | | | | | | | | | | | | | | | | |
| | <table border="1"> <tr> <td>15</td><td>14</td><td>13</td><td>12</td><td>11</td><td>10</td><td>9</td><td>8</td><td>7</td><td>6</td><td>5</td><td>4</td><td>3</td><td>2</td><td>1</td><td>0</td> </tr> </table> <p>Bit 0: "SF1" Multistep speed (bit operation) Bit 1: "SF2" Multistep speed (bit operation) Bit 2: "SF3" Multistep speed (bit operation) Bit 3: "SF4" Multistep speed (bit operation) Bit 4: "SF5" Multistep speed (bit operation) Bit 5: "SF6" Multistep speed (bit operation) Bit 6: "SF7" Multistep speed (bit operation) Bit 7: "OLR" Overload limitation selection Bit 8: "TL" Torque limitation valid/invalid Bit 9: "TRQ1" Torque limit selection 1 Bit 10: "TRQ2" Torque limit selection 2 Bit 11: "PPI" P/PI selection Bit 12: "BOK" Brake check Bit 13: "ORT" Orientation Bit 14: "LAC" LAD cancel Bit 15: "PCLR" Positioning deviation clear</p> | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | |
| 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | | | |
| n + 4 | Data (LH) | | | | | | | | | | | | | | | | | |
| | <table border="1"> <tr> <td>15</td><td>14</td><td>13</td><td>12</td><td>11</td><td>10</td><td>9</td><td>8</td><td>7</td><td>6</td><td>5</td><td>4</td><td>3</td><td>2</td><td>1</td><td>0</td> </tr> </table> <p>Bit 0: "AT" Analog input selection Bit 1: -- Bit 2: "RS" Reset Bit 3: -- Bit 4: "STA" 3-wire start Bit 5: "STP" 3-wire retain Bit 6: "F/R" 3-wire normal/reverse turn Bit 7: "PID" PID selection (valid/invalid) Bit 8: "PIDC" PID integral reset Bit 9: -- Bit 10: -- Bit 11: "UP" Remote control acceleration Bit 12: "DWN" Remote control deceleration Bit 13: "UDC" Remote control data clear Bit 14: -- Bit 15: "OPE" Forced operation</p> | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | |
| 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | | | |
| n + 5 | Data (LL) | | | | | | | | | | | | | | | | | |
| | | <table border="1"> <tr> <td>15</td><td>14</td><td>13</td><td>12</td><td>11</td><td>10</td><td>9</td><td>8</td><td>7</td><td>6</td><td>5</td><td>4</td><td>3</td><td>2</td><td>1</td><td>0</td> </tr> </table> <p>Bit 0: "FW" Normal turn command Bit 1: "RV" Reverse turn command Bit 2: "CF1" Multistep speed 1 (binary operation) Bit 3: "CF2" Multistep speed 2 (binary operation) Bit 4: "CF3" Multistep speed 3 (binary operation) Bit 5: "CF4" Multistep speed 4 (binary operation) Bit 6: "JG" Jogging (inching operation) Bit 7: "DB" External DC braking Bit 8: "SET" 2nd control Bit 9: "2CH" 2-step acceleration/deceleration Bit 10: -- Bit 11: "FRS" Free-run stop Bit 12: "EXP" External trip Bit 13: "USP" Unattended start protection function Bit 14: "CS" Commercial switching Bit 15: "SFT" Soft lock (control terminal block)</p> | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | | | |

| Contents | F0 | F1 (= \$u n) | | F2 |
|---|---------------------|--------------|--|----|
| Inverter status readout | 1 - 8 (PLC1 - 8) | n | Station number | 2 |
| | | n + 1 | Command: 4 | |
| | | n + 2 | Status A (BCD) 00: Initial status 01: Waiting for Vdc establishment 02: Stopping 03: Running 04: FRS in progress 05: JG in progress 06: DB in progress 07: F acquisition in progress 08: Retry in progress 09: UV in progress 10: Tripping 11: Waiting for reset | |
| | | n + 3 | Status B (BCD) 00: Stopping 01: Running 02: Tripping | |
| | | n + 4 | Status C (BCD) 00: -- 01: Stop 02: Deceleration 03: Constant speed 04: Acceleration 05: Normal turn 06: Reverse turn 07: Normal to reverse turn 08: Reverse to normal turn 09: Normal turn start 10: Reverse turn start | |
| Resetting of setting value to default * | 1 - 8 (PLC1 - 8) | n | Station number | 2 |
| | | n + 1 | Command: 8 | |
| Check for EEPROM availability | 1 - 8 (PLC1 - 8) | n | Station number | 2 |
| | | n + 1 | Command: 9 | |
| | | n + 2 | 01: Allowed | |
| Storing of setting values in EEPROM | 1 - 8 (PLC1 - 8) | n | Station number | 2 |
| | | n + 1 | Command: 10 | |
| Re-calculation of internal constant | 1 - 8 (PLC1 - 8) | n | Station number | 2 |
| | | n + 1 | Command: 11 | |

Return data: Data stored from inverter to V series

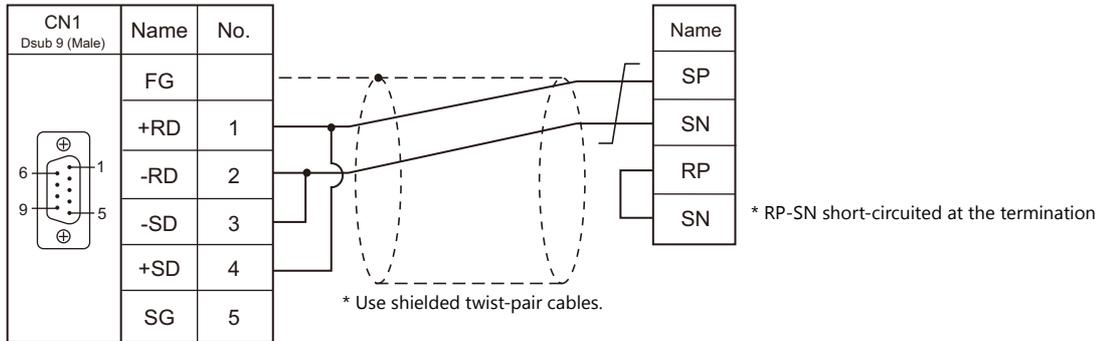
* When the initialize parameter of "b084" is set to "00", only trip history is cleared.

20.2.3 Wiring Diagrams

When Connected at CN1:

RS-485

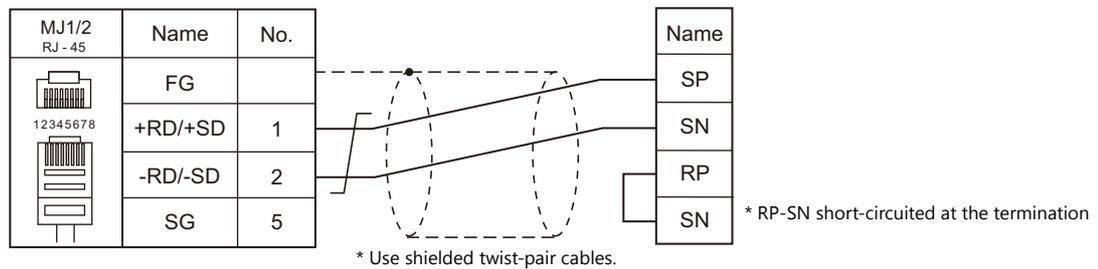
Wiring diagram 1 - C4



When Connected at MJ1/MJ2:

RS-485

Wiring diagram 1 - M4



MEMO

Please use this page freely.

Connection Compatibility List

April, 2014

| Manufacturer | Models | 1 : 1 | 1 : n Multi-drop | n : 1 Multi-link2 | Multi-link2 Ethernet | 1 : n Multi-link2 Ethernet | n : 1 Multi-link |
|-------------------------------|--------------------------------------|-------|---------------------|----------------------|-------------------------|----------------------------------|---------------------|
| Allen-Bradley | PLC-5 | ○ | ○ | ○ | ○ | ○ | ○ |
| | PLC-5 (Ethernet) | ○ | ○ | | | | |
| | Control Logix / Compact Logix | ○ | | ○ | ○ | | |
| | Control Logix (Ethernet) | ○ | ○ | | | | |
| | SLC500 | ○ | ○ | ○ | ○ | ○ | |
| | SLC500 (Ethernet TCP/IP) | ○ | ○ | | | | |
| | NET-ENI (SLC500 Ethernet TCP/IP) | ○ | ○ | | | | |
| | NET-ENI (MicroLogix Ethernet TCP/IP) | ○ | ○ | | | | |
| | Micro Logix | ○ | ○ | ○ | ○ | ○ | |
| Micro Logix (Ethernet TCP/IP) | ○ | ○ | | | | | |
| Automationdirect | Direct LOGIC (K-Sequence) | ○ | | ○ | ○ | | |
| | Direct LOGIC (Ethernet UDP/IP) | ○ | ○ | | | | |
| | Direct LOGIC (MODBUS RTU) | ○ | ○ | ○ | ○ | ○ | |
| Azbil | MX series | ○ | ○ | ○ | ○ | ○ | |
| | SDC10 | ○ | ○ | ○ | ○ | ○ | |
| | SDC20 | ○ | ○ | ○ | ○ | ○ | |
| | SDC21 | ○ | ○ | ○ | ○ | ○ | |
| | SDC30/31 | ○ | ○ | ○ | ○ | ○ | |
| | SDC35/36 | ○ | ○ | ○ | ○ | ○ | |
| | SDC40A | ○ | ○ | ○ | ○ | ○ | |
| | SDC40G | ○ | ○ | ○ | ○ | ○ | |
| | DMC10 | ○ | ○ | ○ | ○ | ○ | |
| | DMC50(COM) | ○ | ○ | ○ | ○ | ○ | |
| | AHC2001 | ○ | ○ | ○ | ○ | ○ | |
| | AHC2001+DCP31/32 | ○ | ○ | ○ | ○ | ○ | |
| | DCP31/32 | ○ | ○ | ○ | ○ | ○ | |
| | NX(CPL) | ○ | ○ | ○ | ○ | ○ | |
| NX(MODBUS RTU) | ○ | ○ | ○ | ○ | ○ | | |
| NX(MODBUS TCP/IP) | ○ | ○ | | | | | |
| Baumuller | BMx-x-PLC | ○ | | ○ | ○ | | |
| BECKHOFF | ADS protocol (Ethernet) | ○ | ○ | | | | |
| CHINO | LT400 Series (MODBUS RTU) | ○ | ○ | ○ | ○ | ○ | |
| | DP1000 | ○ | ○ | ○ | ○ | ○ | |
| | DB100B (MODBUS RTU) | ○ | ○ | ○ | ○ | ○ | |
| | KR2000 (MODBUS RTU) | ○ | ○ | ○ | ○ | ○ | |
| | LT230 (MODBUS RTU) | ○ | ○ | ○ | ○ | ○ | |
| | LT300 (MODBUS RTU) | ○ | ○ | ○ | ○ | ○ | |
| CIMON | BP series | ○ | | ○ | ○ | | |
| | CP series | ○ | | ○ | ○ | | |
| DELTA | DVP series | ○ | ○ | ○ | ○ | ○ | |
| DELTA TAU DATA SYSTEMS | PMAC | ○ | | ○ | ○ | | |
| | PMAC(Ethernet TCP/IP) | ○ | ○ | | | | |
| EATON Cutler-Hammer | ELC | ○ | ○ | ○ | ○ | ○ | |
| EMERSON | EC10/20/20H (MODBUS RTU) | ○ | ○ | ○ | ○ | ○ | |
| FANUC | Power Mate | ○ | | ○ | ○ | | |
| Fatek Automation | FACON FB Series | ○ | ○ | ○ | ○ | ○ | |
| FUFENG | APC Series Controller | ○ | ○ | ○ | ○ | ○ | |
| Fuji Electric | MICREX-F series | ○ | ○ | ○ | ○ | ○ | ○ |
| | MICREX-F series V4-compatible | ○ | ○ | ○ | ○ | ○ | |
| | SPB (N mode) & FLEX-PC series | ○ | ○ | ○ | ○ | ○ | |
| | SPB (N mode) and FLEX-PC CPU | ○ | | ○ | ○ | ○ | |
| | MICREX-SX SPH/SPB series | ○ | | ○ | ○ | | |
| | MICREX-SX SPH/SPB CPU | ○ | | ○ | ○ | | |
| | MICREX-SX (Ethernet) | ○ | ○ | | | | |
| | PYX (MODBUS RTU) | ○ | ○ | ○ | ○ | ○ | |
| | PXR (MODBUS RTU) | ○ | ○ | ○ | ○ | ○ | |
| | PXG (MODBUS RTU) | ○ | ○ | ○ | ○ | ○ | |
| | PXH (MODBUS RTU) | ○ | ○ | ○ | ○ | ○ | |
| | PUM (MODBUS RTU) | ○ | ○ | ○ | ○ | ○ | |
| | F-MPC04P (loader) | ○ | ○ | ○ | ○ | ○ | |
| F-MPC series / FePSU | ○ | ○ | ○ | ○ | ○ | | |

List-2

| Manufacturer | Models | 1 : 1 | 1 : n Multi-drop | n : 1 Multi-link2 | Multi-link2 Ethernet | 1 : n Multi-link2 Ethernet | n : 1 Multi-link |
|--------------------------------------|-----------------------------------|-------|---------------------|----------------------|-------------------------|----------------------------------|---------------------|
| Fuji Electric | FVR-E11S | ○ | ○ | ○ | ○ | ○ | |
| | FVR-E11S (MODBUS RTU) | ○ | ○ | ○ | ○ | ○ | |
| | FVR-C11S (MODBUS RTU) | ○ | ○ | ○ | ○ | ○ | |
| | FRENIC5000 G11S/P11S | ○ | ○ | ○ | ○ | ○ | |
| | FRENIC5000 G11S/P11S (MODBUS RTU) | ○ | ○ | ○ | ○ | ○ | |
| | FRENIC5000 VG7S (MODBUS RTU) | ○ | ○ | ○ | ○ | ○ | |
| | FRENIC-HVAC/AQUA (MODBUS RTU) | ○ | ○ | ○ | ○ | ○ | |
| | FRENIC-Mini (MODBUS RTU) | ○ | ○ | ○ | ○ | ○ | |
| | FRENIC-Eco (MODBUS RTU) | ○ | ○ | ○ | ○ | ○ | |
| | FRENIC-Multi (MODBUS RTU) | ○ | ○ | ○ | ○ | ○ | |
| | FRENIC-MEGA (MODBUS RTU) | ○ | ○ | ○ | ○ | ○ | |
| | FRENIC-MEGA SERVO(MODBUS RTU) | ○ | ○ | ○ | ○ | ○ | |
| | HFR-C9K | ○ | ○ | ○ | ○ | ○ | |
| | HFR-C11K | ○ | ○ | ○ | ○ | ○ | |
| | PPMC (MODBUS RTU) | ○ | ○ | ○ | ○ | ○ | |
| | FALDIC-α series | ○ | ○ | ○ | ○ | ○ | |
| | FALDIC-W series | ○ | ○ | ○ | ○ | ○ | |
| | PH series | ○ | ○ | ○ | ○ | ○ | |
| | PHR (MODBUS RTU) | ○ | ○ | ○ | ○ | ○ | |
| | WA5000 | ○ | ○ | ○ | ○ | ○ | |
| | APR-N (MODBUS RTU) | ○ | ○ | ○ | ○ | ○ | |
| | ALPHA5 (MODBUS RTU) | ○ | ○ | ○ | ○ | ○ | |
| ALPHA5 Smart (MODBUS RTU) | ○ | ○ | ○ | ○ | ○ | | |
| WE1MA (Ver. A)(MODBUS RTU) | ○ | ○ | ○ | ○ | ○ | | |
| WE1MA (Ver. B)(MODBUS RTU) | ○ | ○ | ○ | ○ | ○ | | |
| WSZ series | ○ | ○ | ○ | ○ | ○ | | |
| Gammaflux | TTC2100 | ○ | ○ | ○ | ○ | ○ | |
| GE Fanuc | 90 series | ○ | ○ | ○ | ○ | ○ | |
| | 90 series (SNP-X) | ○ | | ○ | ○ | | |
| | 90 series (SNP) | ○ | ○ | ○ | ○ | ○ | |
| | 90 series (Ethernet TCP/IP) | ○ | ○ | | | | |
| | RX3i (Ethernet TCP/IP) | ○ | ○ | | | | |
| Hitachi | HIDIC-S10/2α, S10mini | ○ | | ○ | ○ | | |
| | HIDIC-S10/2α, S10mini (Ethernet) | ○ | ○ | | | | |
| | HIDIC-S10/4α | ○ | | ○ | ○ | | |
| | HIDIC-S10V | ○ | | ○ | ○ | | |
| | HIDIC-S10V (Ethernet) | ○ | ○ | | | | |
| Hitachi Industrial Equipment Systems | HIDIC-H | ○ | ○ | ○ | ○ | ○ | ○ |
| | HIDIC-H (Ethernet) | ○ | ○ | | | | |
| | HIDIC-EHV | ○ | ○ | ○ | ○ | ○ | ○ |
| | HIDIC-EHV (Ethernet) | ○ | ○ | | | | |
| | SJ300 series | ○ | ○ | ○ | ○ | ○ | |
| | SJ700 series | ○ | ○ | ○ | ○ | ○ | |
| IAI | X-SEL controller | ○ | ○ | ○ | ○ | ○ | |
| | ROBO CYLINDER (RCP2/ERC) | ○ | ○ | ○ | ○ | ○ | |
| | ROBO CYLINDER (RCS/E-CON) | ○ | ○ | ○ | ○ | ○ | |
| | PCON/ACON/SCON (MODBUS RTU) | ○ | ○ | ○ | ○ | ○ | |
| IDEC | MICRO 3 | ○ | ○ | ○ | ○ | ○ | |
| | MICRO Smart | ○ | ○ | ○ | ○ | ○ | |
| | MICRO Smart pentra | ○ | ○ | ○ | ○ | ○ | |
| JTEKT | TOYOPUC | ○ | ○ | ○ | ○ | ○ | ○ |
| | TOYOPUC (Ethernet) | ○ | ○ | | | | |
| | TOYOPUC (Ethernet PC10 mode) | ○ | ○ | | | | |
| KEYENCE | KZ Series Link | ○ | ○ | ○ | ○ | ○ | ○ |
| | KZ-A500 CPU | ○ | | ○ | ○ | | |
| | KV10/24 CPU | ○ | | ○ | ○ | | |
| | KV-700 | ○ | | ○ | ○ | | |
| | KV-700 (Ethernet TCP/IP) | ○ | ○ | | | | |
| | KV-1000 | ○ | | ○ | ○ | | |
| | KV-1000 (Ethernet TCP/IP) | ○ | ○ | | | | |
| | KV-3000/5000 | ○ | | ○ | ○ | | |
| KV-3000/5000 (Ethernet TCP/IP) | ○ | ○ | | | | | |
| KOGANEI | IBFL-TC | ○ | ○ | ○ | ○ | ○ | |
| KOYO ELECTRONICS | SU/SG | ○ | ○ | ○ | ○ | ○ | |
| | SR-T (K protocol) | ○ | | ○ | ○ | | |
| | SU/SG (K-Sequence) | ○ | | ○ | ○ | | |
| | SU/SG (Modbus RTU) | ○ | ○ | ○ | ○ | ○ | |

| Manufacturer | Models | 1 : 1 | 1 : n Multi-drop | n : 1 Multi-link2 | Multi-link2 Ethernet | 1 : n Multi-link2 Ethernet | n : 1 Multi-link |
|---------------------|---|-------|---------------------|----------------------|-------------------------|----------------------------------|---------------------|
| LS | MASTER-KxxxS | ○ | | ○ | ○ | | |
| | MASTER-KxxxS CNET | ○ | ○ | ○ | ○ | ○ | |
| | GLOFA CNET | ○ | ○ | ○ | ○ | ○ | ○ |
| | GLOFA GM7 CNET | ○ | ○ | ○ | ○ | ○ | |
| | GLOFA GM series CPU | ○ | | ○ | ○ | | |
| | XGT/XGK series CNET | ○ | ○ | ○ | ○ | ○ | |
| | XGT/XGK series CPU | ○ | | ○ | ○ | | |
| | XGT/XGK series (Ethernet) | ○ | ○ | | | | |
| | XGT/XGI series CNET | ○ | ○ | ○ | ○ | ○ | |
| | XGT/XGI series CPU | ○ | | ○ | ○ | | |
| | XGT/XGI series (Ethernet) | ○ | ○ | | | | |
| MITSUBISHI ELECTRIC | A series link | ○ | ○ | ○ | ○ | ○ | ○ |
| | A series CPU | ○ | | ○ | ○ | | |
| | QnA series link | ○ | ○ | ○ | ○ | ○ | |
| | QnA series CPU | ○ | | ○ | ○ | | |
| | QnA series (Ethernet) | ○ | ○ | | | | |
| | QnH (Q) series link | ○ | ○ | ○ | ○ | ○ | |
| | QnH (Q) series CPU | ○ | | ○ | ○ | | |
| | QnU series CPU | ○ | | ○ | ○ | | |
| | Q00J/00/01CPU | ○ | | ○ | ○ | | |
| | QnH (Q) series (Ethernet) | ○ | ○ | | | | |
| | QnH (Q) series link (multi CPU) | ○ | ○ | ○ | ○ | ○ | |
| | QnH (Q) series (multi CPU) (Ethernet) | ○ | ○ | | | | |
| | QnH (Q) series CPU (multi CPU) | ○ | | ○ | ○ | | |
| | QnH (Q) series (Ethernet ASCII) | ○ | ○ | | | | |
| | QnH (Q) series (multi CPU) (Ethernet ASCII) | ○ | ○ | | | | |
| | QnU series (built-in Ethernet) | ○ | ○ | | | | |
| | L series link | ○ | ○ | ○ | ○ | ○ | |
| | L series (built-in Ethernet) | ○ | ○ | | | | |
| | FX series CPU | ○ | | ○ | ○ | | |
| | FX2N/1N series CPU | ○ | | ○ | ○ | | |
| | FX1S series CPU | ○ | | ○ | ○ | | |
| | FX series link (A protocol) | ○ | ○ | ○ | ○ | ○ | ○ |
| | FX-3U/3UC/3G series CPU | ○ | | ○ | ○ | | |
| | FX-3U series (Ethernet) | ○ | ○ | | | | |
| | FX3U/3UC/3UG series link (A protocol) | ○ | ○ | ○ | ○ | ○ | ○ |
| | A-Link + Net10 | | ○ | | | | |
| | Q170MCP (multi CPU) | ○ | | ○ | ○ | | |
| | Q170 series (multi CPU) (Ethernet) | ○ | ○ | | | | |
| | FR-*500 | ○ | ○ | ○ | ○ | ○ | |
| | FR-V500 | ○ | ○ | ○ | ○ | ○ | |
| MR-J2S-*A | ○ | ○ | ○ | ○ | ○ | | |
| MR-J3-*A | ○ | ○ | ○ | ○ | ○ | | |
| MR-J3-*T | ○ | ○ | ○ | ○ | ○ | | |
| FR-E700 | ○ | ○ | ○ | ○ | ○ | | |
| MODICON | Modbus RTU | ○ | | ○ | ○ | | |
| MOELLER | PS4 | ○ | | ○ | ○ | | |
| M-SYSTEM | RLM series (MODBUS RTU) | ○ | ○ | ○ | ○ | ○ | |

| Manufacturer | Models | 1 : 1 | 1 : n Multi-drop | n : 1 Multi-link2 | Multi-link2 Ethernet | 1 : n Multi-link2 Ethernet | n : 1 Multi-link |
|--------------------------------|---|-------|---------------------|----------------------|-------------------------|----------------------------------|---------------------|
| OMRON | SYSMAC C | ○ | ○ | ○ | ○ | ○ | ○ |
| | SYSMAC CV | ○ | ○ | ○ | ○ | ○ | ○ |
| | SYSMAC CS1/CJ1 | ○ | ○ | ○ | ○ | ○ | |
| | SYSMAC CS1/CJ1 DNA | ○ | ○ | | | | |
| | SYSMAC CS1/CJ1 (Ethernet) | ○ | ○ | | | | |
| | SYSMAC CS1/CJ1 (Ethernet Auto) | ○ | ○ | | | | |
| | SYSMAC CS1/CJ1 DNA (Ethernet) | ○ | ○ | | | | |
| | E5AK | ○ | ○ | ○ | ○ | ○ | |
| | E5AK-T | ○ | ○ | ○ | ○ | ○ | |
| | E5AN/E5EN/E5CN/E5GN | ○ | ○ | ○ | ○ | ○ | |
| | E5AR/E5ER | ○ | ○ | ○ | ○ | ○ | |
| | E5CK | ○ | ○ | ○ | ○ | ○ | |
| | E5CK-T | ○ | ○ | ○ | ○ | ○ | |
| | E5CN-HT | ○ | ○ | ○ | ○ | ○ | |
| | E5EK | ○ | ○ | ○ | ○ | ○ | |
| | E5ZD | ○ | ○ | ○ | ○ | ○ | |
| | E5ZE | ○ | ○ | ○ | ○ | ○ | |
| | E5ZN | ○ | ○ | ○ | ○ | ○ | |
| | V600/620/680 | ○ | ○ | ○ | ○ | ○ | |
| KM20 | ○ | ○ | ○ | ○ | ○ | | |
| KM100 | ○ | ○ | ○ | ○ | ○ | | |
| Oriental Motor | High-efficiency AR series (MODBUS RTU) | ○ | ○ | ○ | ○ | ○ | |
| | CRK series (MODBUS RTU) | ○ | ○ | ○ | ○ | ○ | |
| Panasonic | FP Series (RS232C/422) | ○ | ○ | ○ | ○ | ○ | ○ |
| | FP Series (TCP/IP) | ○ | ○ | | | | |
| | FP Series (UDP/IP) | ○ | ○ | | | | |
| | FP-X (TCP/IP) | ○ | ○ | | | | |
| | FP7 Series (RS232C/422) | ○ | ○ | ○ | ○ | ○ | |
| | FP7 Series (Ethernet) | ○ | ○ | | | | |
| | LP-400 | ○ | | ○ | ○ | | |
| | KW Series | ○ | ○ | ○ | ○ | ○ | |
| MINAS A4 series | ○ | ○ | ○ | ○ | ○ | | |
| RKC | SR-Mini (MODBUS RTU) | ○ | ○ | ○ | ○ | ○ | |
| | CB100/CB400/CB500/CB700/CB900 (MODBUS RTU) | ○ | ○ | ○ | ○ | ○ | |
| | SR-Mini (Standard Protocol) | ○ | ○ | ○ | ○ | ○ | |
| | REX-F400/F700/F900(Standard Protocol) | ○ | ○ | ○ | ○ | ○ | |
| | SRV (MODBUS RTU) | ○ | ○ | ○ | ○ | ○ | |
| | MA900/MA901 (MODBUS RTU) | ○ | ○ | ○ | ○ | ○ | |
| | SRZ (MODBUS RTU) | ○ | ○ | ○ | ○ | ○ | |
| FB100/FB400/FB900 (MODBUS RTU) | ○ | ○ | ○ | ○ | ○ | | |
| RS Automation | NX7/NX Plus Series (70P/700P/CCU+) | ○ | ○ | ○ | ○ | ○ | ○ |
| | N7/NX Series (70/700/750/CCU) | ○ | ○ | ○ | ○ | ○ | ○ |
| | NX700 Series (Ethernet) | ○ | ○ | | | | |
| | X8 Series | ○ | ○ | ○ | ○ | ○ | |
| | X8 Series (Ethernet) | ○ | ○ | | | | |
| SAIA | PCD | ○ | ○ | ○ | ○ | ○ | |
| | PCD S-BUS (Ethernet) | ○ | ○ | | | | |
| SAMSUNG | N_plus | ○ | ○ | ○ | ○ | ○ | ○ |
| | SECNET | ○ | ○ | ○ | ○ | ○ | ○ |
| SANMEI | Cuty Axis | ○ | ○ | ○ | ○ | ○ | |
| SanRex | DC AUTO (HKD type) | ○ | ○ | ○ | ○ | ○ | |
| SHARP | JW series | ○ | ○ | ○ | ○ | ○ | ○ |
| | JW100/70H COM port | ○ | ○ | ○ | ○ | ○ | ○ |
| | JW20 COM port | ○ | ○ | ○ | ○ | ○ | ○ |
| | JW series (Ethernet) | ○ | ○ | | | | |
| | JW300 series | ○ | ○ | ○ | ○ | ○ | ○ |
| | JW311/312/321/322 series (Ethernet) | ○ | ○ | | | | |
| | JW331/332/341/342/352/362 series (Ethernet) | ○ | ○ | | | | |
| SHIMADEN | SHIMADEN standard protocol | ○ | ○ | ○ | ○ | ○ | |

| Manufacturer | Models | 1 : 1 | 1 : n Multi-drop | n : 1 Multi-link2 | Multi-link2 Ethernet | 1 : n Multi-link2 Ethernet | n : 1 Multi-link |
|---------------------|---|-------|---------------------|----------------------|-------------------------|----------------------------------|---------------------|
| SHINKO TECHNOS | C Series | ○ | ○ | ○ | ○ | ○ | |
| | FC Series | ○ | ○ | ○ | ○ | ○ | |
| | GC Series | ○ | ○ | ○ | ○ | ○ | |
| | DCL-33A | ○ | ○ | ○ | ○ | ○ | |
| | JCx-300 Series | ○ | ○ | ○ | ○ | ○ | |
| | PC-900 | ○ | ○ | ○ | ○ | ○ | |
| | PCD-33A | ○ | ○ | ○ | ○ | ○ | |
| | ACS-13A | ○ | ○ | ○ | ○ | ○ | |
| | ACD/ACR Series | ○ | ○ | ○ | ○ | ○ | |
| WCL-13A | ○ | ○ | ○ | ○ | ○ | | |
| Siemens | S5 PG port | ○ | ○ | ○ | ○ | ○ | |
| | S7 | ○ | | ○ | ○ | | |
| | S7-200 PPI | ○ | ○ | | | | ○ |
| | S7-200 (Ethernet ISOTCP) | ○ | ○ | | | | |
| | S7-300/400 MPI | ○ | ○ | | | | |
| | S7-300/400 (Ethernet ISOTCP) | ○ | ○ | | | | |
| | S7-300/400 (Ethernet TCP/IP PG protocol) | ○ | ○ | | | | |
| | S7-1200 (Ethernet ISOTCP) | ○ | ○ | | | | |
| TI500/505 | ○ | ○ | ○ | ○ | ○ | | |
| SINFONIA TECHNOLOGY | SELMART | ○ | ○ | ○ | ○ | ○ | ○ |
| TECO | TP-03 (MODBUS RTU) | ○ | ○ | ○ | ○ | ○ | |
| Telemecanique | TSX Micro | | | | | | ○ |
| TOHO | TTM-000 | ○ | ○ | ○ | ○ | ○ | |
| | TTM-00BT | ○ | ○ | ○ | ○ | ○ | |
| | TTM-200 | ○ | ○ | ○ | ○ | ○ | |
| TOSHIBA | T series / V series (T compatible) | ○ | ○ | ○ | ○ | ○ | ○ |
| | EX series | ○ | ○ | ○ | ○ | ○ | |
| | VF-S7 | ○ | ○ | ○ | ○ | ○ | |
| | VF-S9 | ○ | ○ | ○ | ○ | ○ | |
| | VF-S11 | ○ | ○ | ○ | ○ | ○ | |
| | VF-A7 | ○ | ○ | ○ | ○ | ○ | |
| | VF-AS1 | ○ | ○ | ○ | ○ | ○ | |
| | VF-P7 | ○ | ○ | ○ | ○ | ○ | |
| | VF-PS1 | ○ | ○ | ○ | ○ | ○ | |
| | VF-FS1 | ○ | ○ | ○ | ○ | ○ | |
| VF-nC1 | ○ | ○ | ○ | ○ | ○ | | |
| TOSHIBA MACHINE | TC200 | ○ | ○ | ○ | ○ | ○ | |
| | VELCONIC series | | ○ | | | | |
| TURCK | BL Series Distributed I/O (MODBUS TCP/IP) | ○ | ○ | | | | |
| UNIPULSE | F340A | ○ | ○ | ○ | ○ | ○ | |
| | F371 | ○ | ○ | ○ | ○ | ○ | |
| | F800 | ○ | ○ | ○ | ○ | ○ | |
| | F805A | ○ | ○ | ○ | ○ | ○ | |
| | F720A | ○ | ○ | ○ | ○ | ○ | |
| UNITRONICS | M90/M91/Vision Series (ASCII) | ○ | ○ | ○ | ○ | ○ | |
| | Vision Series (ASCII Ethernet TCP/IP) | ○ | ○ | | | | |
| VIGOR | M series | ○ | ○ | ○ | ○ | ○ | |
| WAGO | 750 series (MODBUS RTU) | ○ | ○ | ○ | ○ | ○ | |
| | 750 series (MODBUS ETHERNET) | ○ | ○ | | | | |
| XINJE | XC Series (MODBUS RTU) | ○ | ○ | ○ | ○ | ○ | |
| YAMAHA | RCX142 | ○ | | ○ | ○ | | |
| Yaskawa Electric | Memobus | ○ | ○ | ○ | ○ | ○ | |
| | CP9200SH/MP900 | ○ | ○ | ○ | ○ | ○ | |
| | MP2000 series | ○ | ○ | ○ | ○ | ○ | |
| | MP2300 (MODBUS TCP/IP) | ○ | ○ | | | | |
| | CP MP expansion memobus (UDP/IP) | ○ | ○ | | | | |
| | MP2000 series (UDP/IP) | ○ | ○ | | | | |

List-6

| Manufacturer | Models | 1 : 1 | 1 : n Multi-drop | n : 1 Multi-link2 | Multi-link2 Ethernet | 1 : n Multi-link2 Ethernet | n : 1 Multi-link |
|-------------------|--------------------------------------|-----------------------|-----------------------|-----------------------|-------------------------|----------------------------------|-----------------------|
| Yokogawa Electric | FA-M3 | <input type="radio"/> | <input type="radio"/> | <input type="radio"/> | <input type="radio"/> | <input type="radio"/> | <input type="radio"/> |
| | FA-M3R | <input type="radio"/> | <input type="radio"/> | <input type="radio"/> | <input type="radio"/> | <input type="radio"/> | <input type="radio"/> |
| | FA-M3/FA-M3R (Ethernet UDP/IP) | <input type="radio"/> | <input type="radio"/> | | | | |
| | FA-M3/FA-M3R (Ethernet UDP/IP ASCII) | <input type="radio"/> | <input type="radio"/> | | | | |
| | FA-M3/FA-M3R (Ethernet TCP/IP) | <input type="radio"/> | <input type="radio"/> | | | | |
| | FA-M3/FA-M3R (Ethernet TCP/IP ASCII) | <input type="radio"/> | <input type="radio"/> | | | | |
| | FA-M3V | <input type="radio"/> | <input type="radio"/> | <input type="radio"/> | <input type="radio"/> | <input type="radio"/> | <input type="radio"/> |
| | FA-M3V (Ethernet) | <input type="radio"/> | <input type="radio"/> | | | | |
| | FA-M3V(Ethernet ASCII) | <input type="radio"/> | <input type="radio"/> | | | | |
| | UT100 | <input type="radio"/> | <input type="radio"/> | <input type="radio"/> | <input type="radio"/> | <input type="radio"/> | |
| | UT750 | <input type="radio"/> | <input type="radio"/> | <input type="radio"/> | <input type="radio"/> | <input type="radio"/> | |
| | UT550 | <input type="radio"/> | <input type="radio"/> | <input type="radio"/> | <input type="radio"/> | <input type="radio"/> | |
| | UT520 | <input type="radio"/> | <input type="radio"/> | <input type="radio"/> | <input type="radio"/> | <input type="radio"/> | |
| | UT350 | <input type="radio"/> | <input type="radio"/> | <input type="radio"/> | <input type="radio"/> | <input type="radio"/> | |
| | UT320 | <input type="radio"/> | <input type="radio"/> | <input type="radio"/> | <input type="radio"/> | <input type="radio"/> | |
| | UT2400/2800 | <input type="radio"/> | <input type="radio"/> | <input type="radio"/> | <input type="radio"/> | <input type="radio"/> | |
| UT450 | <input type="radio"/> | <input type="radio"/> | <input type="radio"/> | <input type="radio"/> | <input type="radio"/> | | |
| None | Universal Serial | <input type="radio"/> | <input type="radio"/> | | | | |
| | MODBUS RTU | <input type="radio"/> | <input type="radio"/> | <input type="radio"/> | <input type="radio"/> | <input type="radio"/> | |
| | MODBUS RTU EXT Format | <input type="radio"/> | <input type="radio"/> | <input type="radio"/> | <input type="radio"/> | <input type="radio"/> | |
| | MODBUS TCP/IP (Ethernet) | <input type="radio"/> | <input type="radio"/> | | | | |
| | MODBUS TCP/IP (Ethernet) Sub Station | <input type="radio"/> | <input type="radio"/> | | | | |
| | MODBUS TCP/IP (Ethernet) EXT Format | <input type="radio"/> | <input type="radio"/> | | | | |
| MODBUS ASCII | <input type="radio"/> | <input type="radio"/> | <input type="radio"/> | <input type="radio"/> | <input type="radio"/> | | |

Slave Communication

| Manufacturer | Models | Setting | Remarks |
|--------------|-----------------------|-----------------------|---------|
| None | Universal serial | <input type="radio"/> | |
| | V-Link | <input type="radio"/> | |
| | Modbus slave (RTU) | <input type="radio"/> | |
| | Modbus slave (TCP/IP) | <input type="radio"/> | |

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