

MONITOUCH

Connection Manual [3]

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Record of Revisions

Reference numbers are shown at the bottom left corner on the back cover of each manual.

Printing Date	Reference No.	Revised Contents
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Preface

Thank you for selecting the MONITOUCH V9 series.

For correct set-up of the V9 series, you are requested to read through this manual to understand more about the product. For more information about the V9 series, refer to the following related manuals.

Manual Name	Contents	Reference No.	
V9 Series Connection Manual [1]	The connection and communication parameters for the V9 series and controllers are explained in detail. Included Makers ALLEN BRADLEY, Automationdirect, Azbil, Baumuller, BECKHOFF, CHINO, CIMON, DELTA, DELTA TAU DATA SYSTEMS, EATON Cutler-Hammer, EMERSON, FANUC, Fatek Automation, FUFENG, Fuji Electric, Gammaflux, GE Fanuc, Hitachi, Hitachi Industrial Equipment Systems	2210NE	
V9 Series Connection Manual [2]	The connection and communication parameters for the V9 series and controllers are explained in detail. Included Makers IAI, IDEC, JTEKT, KEYENCE, KOGANEI, KOYO ELECTRONICS, LS, MITSUBISHI ELECTRIC, MODICON, MOELLER, M-SYSTEM, OMRON, Oriental Motor, Panasonic, RKC, RS Automation	2211NE	
V9 Series Connection Manual [3]	The connection and communication parameters for the V9 series and controllers are explained in detail. Included Makers SAIA, SAMSUNG, SanRex, SANMEI, SHARP, SHIMADEN, SHINKO TECHNOS, Siemens, SINFONIA TECHNOLOGY, TECO, Telemecanique, TOHO, TOSHIBA, TOSHIBA MACHINE, TURCK, UNIPULSE, UNITRONICS, VIGOR, WAGO, XINJE, YAMAHA, Yaskawa Electric, Yokogawa Electric, MODBUS, Barcode Reader, Slave Communication Function, Universal Serial Communication	2212NE	
V9 Series Reference Manual [1]	The functions and instructions of the V9 series are explained.	1065NE	
V9 Series Reference Manual [2]		1066NE	
V9 Series Troubleshooting/Maintenance Manual	Errors and operation procedures of the V9 series are explained.	1068NE	
V9 Series Hardware Specifications	Notes on usage and hardware specifications for the V9 series are explained.	2023NE	
V9 Series Macro Reference	An overview of macros of V-SFT version 6 as well as macro editor operations and macro command descriptions are explained.	1071NE	

For further details about PLCs, inverters, or temperature controllers, refer to the manual attached to each controller.

Notes:

- 1. This manual may not, in whole or in part, be printed or reproduced without the prior written consent of Hakko Electronics Co., Ltd.
- 2. The information in this manual is subject to change without prior notice.
- 3. Windows and Excel are registered trademarks of Microsoft Corporation in the United States and other countries.
- 4. All other company names or product names are trademarks or registered trademarks of their respective holders.
- 5. This manual is intended to give accurate information about MONITOUCH hardware. If you have any questions, please contact your local distributor.

Notes on Safe Usage of MONITOUCH

In this manual, you will find various notes categorized under the following two levels with the signal words "Danger" and "Caution."



Indicates an imminently hazardous situation which, if not avoided, will result in death or serious injury.



Indicates a <u>potentially hazardous situation which</u>, if not avoided, may result in minor or moderate injury and <u>could cause property damage</u>.

Note that there is a possibility that an item listed under **CAUTION** may have serious ramifications.

MDANGER

- Never use the output signal of the V9 series for operations that may threaten human life or damage the system, such as signals used in case of emergency. Please design the system so that it can cope with the malfunctions of a touch switch. A malfunction of a touch switch may result in machine accident or damage.
- Turn off the power supply when you set up the unit, connect new cables, or perform maintenance or inspections. Otherwise, electrical shock or damage may occur.
- Never touch any terminals while the power is on. Otherwise, electric shock may occur.
- Put a cover on the terminals on the unit before turning the power on starting operation. Otherwise, electric shock may occur.
- The liquid crystal in the LCD panel is a hazardous substance. If the LCD panel is damaged, do not ingest the leaked liquid crystal. If the liquid crystal contacts skin or clothing, use soap and wash off thoroughly.
- Never disassemble, recharge, deform by pressure, short-circuit, reverse the polarity of the lithium battery, nor dispose of the lithium battery in fire. Failure to follow these conditions will lead to explosion or fire.
- Never use a lithium battery that is deformed, leaks, or shows any other signs of abnormality. Failure to follow these conditions may lead to explosion or fire.
- The power lamp flashes when the backlight is at the end of life or is faulty. However, the switches on the screen are operable at this time. Do not touch the screen when the screen becomes dark and the power lamp flashes. Otherwise, a malfunction may occur and result in machine accident or damage.

CAUTION

- Check the appearance of MONITOUCH when unpacked. Do not use it if any damage or deformation is found. Failure to do so may lead to fire, damage or malfunction.
- For use in a facility or for a system related to nuclear energy, aerospace, medical, traffic equipment, or mobile installations, please consult your local distributor.
- Operate (or store) the V9 series under the conditions indicated in this manual and related manuals. Failure to do so could cause fire, malfunction, physical damage or deterioration.
- Understand the following environmental limits for use and storage of MONITOUCH. Otherwise, fire or damage to the unit may
 result.
 - Avoid locations where there is a possibility that water, corrosive gas, flammable gas, solvents, grinding fluids or cutting oil can come into contact with the unit.
 - Avoid high temperature, condensation, and outside weather conditions, such as wind, rain or direct sunlight.
 - Avoid locations where excessive dust, salt, and metallic particles are present.
 - Avoid installing the unit in a location where vibration or physical shock may be transmitted.
- Equipment must be correctly mounted so that the main terminal of the V9 series will not be touched inadvertently. Otherwise, an accident or electric shock may occur.
- Tighten the fixtures of the V9 series evenly to a torque of 0.6 N·m.

 Excessive tightening may distort the panel surface. Loose tightening may cause MONITOUCH to come off, malfunction or be short-circuited
- Check periodically that terminal screws on the power supply terminal block and fixtures are firmly tightened. Loosened screws may result in fire or malfunction.
- Tighten terminal screws on the power supply terminal block equally to a torque of 7.1 to 8.8 inch-lbf (0.8 to 1.0 N·m). Improper tightening of screws may result in fire, malfunction, or other trouble.
- The V9 series has a glass screen. Do not drop or give physical shock to the unit. Otherwise, the screen may be damaged.
- Connect the cables correctly to the terminals of the V9 series in accordance with the specified voltage and wattage. Over-voltage, over-wattage, or incorrect cable connection could cause fire, malfunction or damage to the unit.
- Be sure to establish a ground of the V9 series. The FG terminal must be used exclusively for the unit with the level of grounding resistance less than 100Ω Otherwise, electric shock or fire may occur.
- Prevent any conductive particles from entering into the V9 series. Failure to do so may lead to fire, damage, or malfunction.
- After wiring is finished, remove the paper used as a dust cover before starting to operate the V9 series. Operation with the cover attached may result in an accident, fire, malfunction, or trouble.
- Do not attempt to repair the V9 series at your site. Ask Hakko Electronics or the designated contractor for repairs.



- Do not repair, disassemble or modify the V9 series. Hakko Electronics Co., Ltd. is not responsible for any damages resulting from repair, disassembly or modification of a unit that was performed by an unauthorized person.
- Do not use a sharp-pointed tool when pressing a touch switch. Doing so may damage the screen.
- Only experts are authorized to set up the unit, connect the cables or perform maintenance and inspection.
- Lithium batteries contain combustible material such as lithium or organic solvents. Mishandling may cause heat, explosion or ignition resulting in fire or injury. Read related manuals carefully and handle the lithium battery correctly as instructed.
- Do not press two or more positions on the screen at the same time. If two or more positions are pressed at the same time, the switch located between the pressed positions activates.
- Take safety precautions during operations such as changing settings during running, forced output, start, and stop. Any
 misoperation may cause unexpected machine motions, resulting in machine accident or damage.
- In facilities where a failure of the V9 series could lead to accidents threatening human life or other serious damage, be sure that the facilities are equipped with adequate safeguards.
- At the time of disposal, the V9 series must be treated as industrial waste.
- Before touching the V9 series, discharge static electricity from your body by touching grounded metal. Excessive static electricity may cause malfunction or trouble.
- Insert an SD card into the unit in the same orientation as pictured on the unit. Failure to do so may damage the SD card or the slot on the unit.
- The SD card access LED flashes red when the SD card is being accessed. Never remove the SD card or turn off power to the unit while the LED is flashing. Doing so may destroy the data on the SD card. Check that the LED has turned off before removing the SD card or turning off the power to the unit.

[General Notes]

- Never bundle control cables or input/output cables with high-voltage and large-current carrying cables such as power supply cables.
 Keep these cables at least 200 mm away from the high-voltage and large-current carrying cables. Otherwise, malfunction may occur due to noise.
- When using the V9 series in an environment where a source of high-frequency noise is present, it is recommended that the FG shielded cable (communication cable) be grounded at each end. However, when communication is unstable, select between grounding one or both ends, as permitted by the usage environment.
- Be sure to plug connectors or sockets of the V9 series in the correct orientation. Failure to do so may lead to damage or malfunction.
- If a LAN cable is inserted into the MJ1 or MJ2 connector on the V9 series, the counterpart device may be damaged. Check the indication on the unit and insert a cable into the correct position.
- Do not use thinners for cleaning because they may discolor the V9 series surface. Use commercially available alcohol.
- If a data receive error occurs when the V9 series and the counterpart (PLC, temperature controller, etc.) are started at the same time, read the manual for the counterpart unit and remove the error correctly.
- Avoid discharging static electricity on the mounting panel of the V9 series. Discharging static electricity on the mounting panel may cause malfunction due to noise.
- Avoid prolonged display of any fixed pattern. Due to the characteristic of liquid crystal displays, an afterimage may occur. If prolonged display of a fixed pattern is expected, use the backlight's auto OFF function.
- The V9 series is identified as a class-A product in industrial environments. In the case of use in a domestic environment, the unit is likely to cause electromagnetic interference. Preventive measures should thereby be taken appropriately.

[Notes on the LCD]

Note that the following conditions may occur under normal circumstances.

- The response time, brightness and colors of the V9 series may be affected by the ambient temperature.
- Tiny spots (dark or luminescent) may appear on the display due to the characteristics of liquid crystal.
- There are variations in brightness and colors between units.

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Connection Compatibility List

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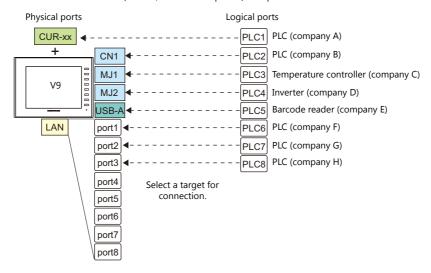
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1.1 System Configuration

1.1.1 Overview

The V9 series is equipped with seven physical ports consisting of three serial ports, one LAN port, one USB-A port, one USB mini-B port, and one network communication port *1 . The LAN port can open eight ports simultaneously. You can use the physical ports to connect a maximum of eight different models of devices and allow the V9 series to communicate with them at the same time. This is called 8-way communication.

*1 A communication interface unit (CUR-xx, under development) is required to enable network communication.



Physical Ports			No. of	Applicable Devices		
	1 Hysical Forts			8-way Communication	Other than 8-way	
	CN1 (RS-232C/RS-422/485)		1	PLC, temperature controller, servo, inverter, barcode reader	-	
Serial	MJ1 (RS-232C/R connection)	S-485, 2-wire	1	PLC, temperature controller, servo, inverter, barcode reader, V-Link,	Computer (screen program	
	MJ2 (RS-232C/R connection)	S-485, 2-wire	1	slave communication (Modbus RTU)	transfer, MJ1) Serial printer	
Ethernet	LAN		8	PLC, slave communication (Modbus TCP/IP)	Computer (screen program transfer)	
USB	USB-A		1	Barcode reader	Printer (EPSON ESC/P-R compatible), USB flash drive, USB-CFREC-2 (under development), keyboard, mouse, USB hub	
	USB mini-B		1	-	Printer (PictBridge), computer (screen program transfer)	
	OPCN-1	CUR-00 (under development)				
	T-Link	CUR-01 (under development)				
	CC-LINK	CUR-02 (under development)		PLC		
Network	Ethernet	CUR-03 (under development)	1			
Network	PROFIBUS-DP	CUR-04 under development)		PLC	-	
	SX BUS	CUR-06 (under development)				
	DeviceNet	CUR-07 (under development)				
	FL-Net	CUR-08 (under development)				

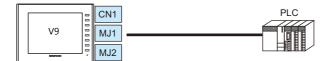
- Only the logical port PLC1 can be selected for the following devices and functions. Thus, they cannot be connected at the same time.
 - Devices
 - Network connection (CUR-xx, under development), without PLC connection, Mitsubishi Electric A-Link + Net10, AB Control Logix, Siemens S7-200PPI, Siemens S7-300/400 MPI connection
 - Functions
 Multi-link2, Multi-link, ladder transfer, ladder monitor, MICREX SX variable name cooperation function

1.1.2 System Composition

Serial Communication

• 1:1 Connection

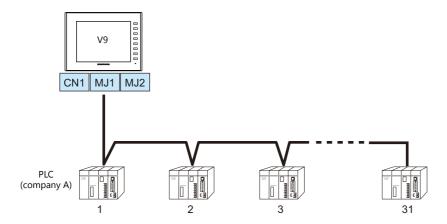
A communication port is selectable from CN1, MJ1, and MJ2. For more information, refer to "1:1 Connection" (page 1-8) in "1.3 Connection Methods".



• 1: n Connection

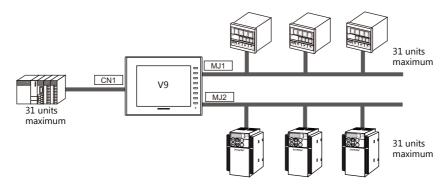
A communication port is selectable from CN1, MJ1, and MJ2. A maximum of 31 units of the same model can be connected to each port.

For more information, refer to "1: n Connection (Multi-drop)" (page 1-14) in "1.3 Connection Methods".



• 3-way Connection

The V9 series is allowed to communicate with three different models of devices at the same time via three serial ports. A maximum of 31 units of the same model can be connected to each port. The connection method is the same as those for 1:1 and 1:n.



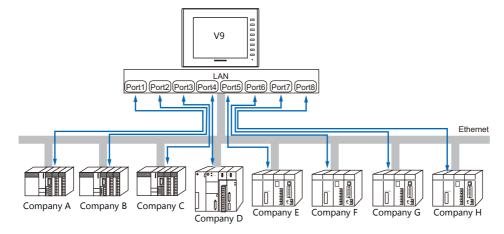
• n:1 Connection (Under development)

Multiple V9 units can be connected to one PLC or temperature controller. For more information, refer to "n:1 Connection (Multi-link2) (Under Development)" (page 1-17), "n:1 Connection (Multi-link2 (Ethernet)) (Under Development)" (page 1-25), "n:1 Connection (Multi-link) (Under Development)" (page 1-31) in "1.3 Connection Methods".

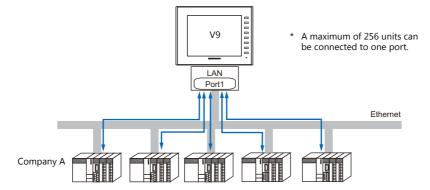
n:n Connection (Under development)
 Multiple V9 units can be connected to multiple PLCs.
 For more information, refer to "n:n Connection (1:n Multi-link2 (Ethernet)) (Under Development)" (page 1-28) in "1.3 Connection Methods".

Ethernet Communication

Because eight communication ports can be opened, the V9series is allowed to communicate with eight models of PLCs at the same time.



When there are two or more PLCs of the same model, the V9 series is allowed to carry out 1: n communication via one port.

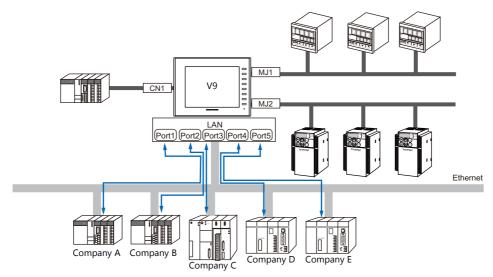


* For more information, refer to "1.3.2 Ethernet Communication" (page 1-36) in "1.3 Connection Methods".

Mixed Serial-Ethernet Communication

In the case of mixed serial-Ethernet communication, the V9 series is allowed to communicate with eight different models of devices at the same time.

• Connection of 3 models for serial communication and 5 models for Ethernet communication



* For the connection method, refer to "1.3.1 Serial Communication" and "1.3.2 Ethernet Communication".

1.2 Physical Ports

1.2.1 CN1

The CN1 port supports communication via RS-232C, RS-422 (4-wire system), and RS-485 (2-wire system). The signal level can be changed between RS-232C and RS-422/485 under [Communication Setting] of the editor.

* The signal level can be changed between RS-232C and RS-422/485 in the Local mode on the V9 unit as well. For details, refer to the separate V9 Series Hardware Specifications manual.



When executing communication via RS-232C, set the DIP switches 5 and 7 to OFF. For more information on the DIP switch, refer to "1.2.6 DIP Switch (DIPSW) Settings" (page 1-7).

Pin Arrangement

CN1	No.		RS-232C	RS-422/RS-485	
Dsub 9pin, Female	INO.	Name	Contents	Name	Contents
	1	NC	Not used	+RD	Receive data (+)
	2	RD	Receive data	-RD	Receive data (–)
	3	SD	Send data	–SD	Send data (–)
	4	NC	Not used	+SD	Send data (+)
9 110 0115	5	0V	Signal ground	0V	Signal ground
6 	6	NC	Not used	+RS	RS send data (+)
	7	RS	RS request to send	-RS	RS send data (–)
	8	CS	CS clear to send	NC	Not used
	9	NC	Not used	+5V	Terminating resistance

Recommended Connector for Communication Cable

Recommended Connector		
DDK's 17JE-23090-02(D8C)-CG	D-sub 9-pin, male, inch screw thread, with hood, RoHS compliant	

Applicable Devices

	Applicable Devices
PLC, temperature controller, inverter, servo, barcode reader	

1.2.2 MJ1/MJ2

The MJ1 and MJ2 ports support communication via RS-232C and RS-485 (2-wire system). MJ1 is also usable as a screen program transfer port.



- MJ1 and MJ2 use the same type RJ-45 connector as the LAN connector.
 To prevent damage to the device from an external power supply of the MJ, check the indication on the unit and insert a cable in the correct position.
- MJ1 and MJ2 are not usable for connection via RS-422 (4-wire system). Use the CN1 port instead or a commercially available RS-232C-to-RS-422 converter.

Pin Arrangement

MJ1/MJ2

MJ1/MJ2 RJ-45 8pin	No.	Signal	Contents
	1	+SD/RD	RS-485 + data
	2	-SD/RD	RS-485 – data
12345678	3	+5V	Externally supplied +5 V [*]
	4		
	5	SG	Signal ground
	6	30	Signal ground
	7	RD	RS-232C receive data
	8	SD	RS-232C send data

^{*} For MJ1, MJ2 and USBA, the maximum allowable current is 150 mA in total (only when the installation angle of MONITOUCH is within 60° to 120°).

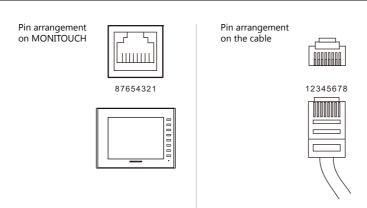
Recommended Cable

Recommended Cable
Hakko Electronics' cable "V6-TMP" 3, 5, 10 m

Notes on Configuring a Cable



Pins No. 3 and 4 are provided for external power supply. To prevent damage to the device due to wrong connection, check the pin numbers and connect wires correctly.



Applicable Devices

	Port	Applicable Devices
MJ1 Computer (screen program transfer) PLC, temperature controller, inverter, servo, barcode reader, V-Link, slave communication		Computer (screen program transfer)
		PLC, temperature controller, inverter, servo, barcode reader, V-Link, slave communication (Modbus RTU), serial printer
	MJ2	PLC, temperature controller, inverter, servo, barcode reader, V-Link, slave communication (Modbus RTU), serial printer

1.2.3 LAN

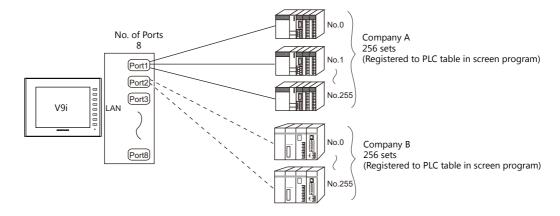


The LAN connector uses the same type RJ-45 connector as MJ1 and MJ2. Check the indication on the unit and insert a cable into the correct position.

LAN Port Specifications

Ikana	Specifications			
Item	100BASE-TX (IEEE802.3u)	10BASE-T (IEEE802.3)		
Baud Rate	100 Mbps	10 Mbps		
Transmission method	Base	band		
Maximum segment length	100 m (between the	node and the hub)		
Connecting cable	100 Ω, UTP cab	ole, category 5		
Protocol	UDP/IP,	TCP/IP		
Port	Auto-MDIX, Auto-Negotia	tion functions compatible		
Number of concurrently opened ports	8 pc	orts		
Maximum number of connectable devices	256 sets each via one s	ingle port PLC1 - PLC8		

Maximum number of connectable devices



Pin Arrangement

LAN RJ-45	No.	Name	Contents
	1	TX+	Send signal +
12345678	2	TX-	Send signal –
	3	RX+	Receive signal +
	4	4 NC	Not used
	5	INC	Not used
	6	RX-	Receive signal –
	7	NC	Not used
	8	INC	ivot used

Applicable Devices

Applicable Devices
PLC, slave communication (Modbus TCP/IP), computer (screen program transfer, V-Server, etc.)

1.2.4 Network Communication Port (Under Development)

An optional communication interface unit "CUR-xx" (under development) is required to perform network communication. For more information, refer to the specifications for each unit.

1.2.5 USB

USB Port Specifications

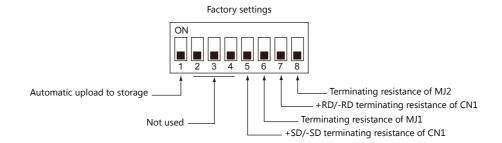
Item		Specifications
USB-A	Applicable standards	USB versions 2.0
USB mini-B	Baud Rate	High-speed 480 Mbps

Applicable Devices

Port	Applicable Devices
USB-A	Printer (EPSON ESC/P-R compatible), barcode reader, USB flash drive, USB-CFREC-2 (under development), numeric keypad, keyboard, mouse, USB hub
USB mini-B	Printer (PictBridge), computer (screen program transfer)

1.2.6 DIP Switch (DIPSW) Settings

The V9 series is equipped with DIP switches 1 to 8. When setting the DIP switch, turn the power off.



DIPSW1* (Automatic upload to storage)

Set the DIPSW1 to ON when automatically uploading screen programs from storage such as an SD card or USB flash drive. For details, refer to the separate V9 Series Hardware Specifications manual.

* Be sure to set the DIPSW1 to OFF when automatic upload is not performed.

DIPSW5, 6, 7, 8 (Terminating resistance setting)

- When connecting a controller to CN1 via RS-422/485 (2-wire connection), set the DIPSW7 to ON.
- When connecting a controller to CN1 via RS-422/485 (4-wire connection), set the DIPSW5 and DIPSW7 to ON.
- When connecting a controller at MJ1 via RS-422/485 (2-wire connection), set the DIPSW6 to ON.
- When connecting a controller at MJ2 via RS-422/485 (2-wire connection), set the DIPSW8 to ON.



When executing communication via RS-232C at CN1, set the DIP switches 5 and 7 to OFF.

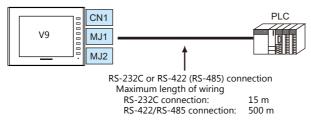
1.3 Connection Methods

1.3.1 Serial Communication

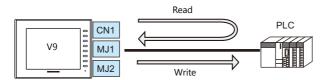
1:1 Connection

Overview

- One set of the V9 is connected to one PLC (1:1 connection).
- You can make settings for 1:1 communication in [Communication Setting] for the logical ports PLC1 PLC8. A communication port is selectable from CN1, MJ1, and MJ2.



- * The maximum length of wiring varies depending on the connected device. Check the specifications for each device.
- The V9 (master station) communicates with a PLC under the PLC's protocol. Therefore, there is no need to prepare a communication program for the PLC (slave station).
- The V9 reads from the PLC device memory for screen display. It is also possible to write switch data or numerical data entered through the keypad directly to the PLC device memory.

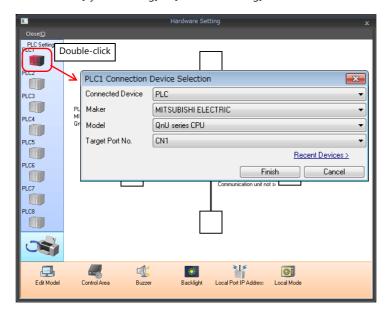


V-SFT Ver. 6 Settings

Hardware Settings

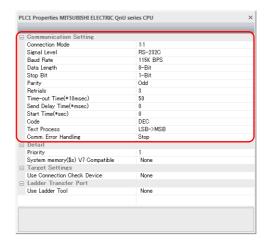
Selecting a device to be connected

Select the device for connection from [System Setting] \rightarrow [Hardware Setting].



PLC properties

Configure [Communication Setting] on the [PLC Properties] window.



Item	Contents
Connection Mode	1:1
Signal Level	
Baud Rate	
Data Length	
Stop Bit	Configure according to the connected device.
Parity	
Target Port No.	
Transmission Mode	

For settings other than the above, see "1.4 Hardware Settings" (page 1-43).

Settings of a Connected Device

Refer to the chapter of the respective manufacturer. For descriptions of connecting PLCs, refer to the manual for each PLC.

Wiring

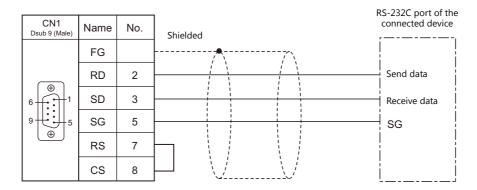


Be sure to turn off the power before connecting cables. Otherwise, electrical shock or damage may occur.

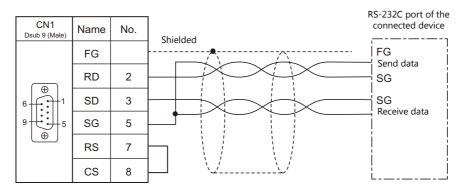
CN1

RS-232C connection

- Prepare a communication cable on your side. Twisted pairs of 0.3 mm sq. or above are recommended.
- The maximum length for wiring is 15 m.
 - * The maximum length varies depending on the connected device. Check the specifications for each device.
- Connect a shielded cable to either the V9 series or the connected device. The connection diagram shows the case where
 the shielded cable is connected on the V9 series side. Connect the cable to the FG terminal on the backside of
 MONITOUCH.

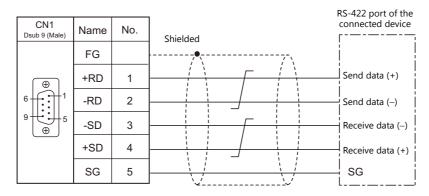


• If noise disturbs communications, establish connections between SD and SG and between RD and SG as pairs respectively, and connect a shielded cable to both the V9 series and the connected device.

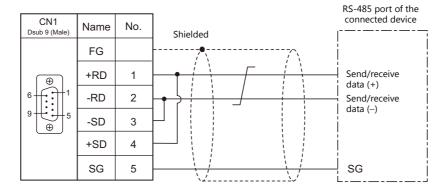


RS-422/RS-485 connection

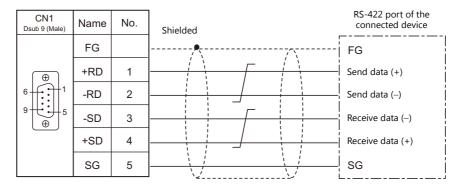
- Prepare a communication cable on your side. Twisted pairs of 0.3 mm sq. or above are recommended.
- The maximum length of wiring is 500 m.
 - * The maximum length varies depending on the connected device. Check the specifications for each device.
- Connect twisted pairs between +SD and -SD, and between +RD and -RD.
- If the PLC has a signal ground (SG) terminal, connect it.
- To use a terminal block for connection, use Hakko Electronics' optionally available "TC-D9".
- The DIP switch on the back of the V9 unit is used to set the terminating resistance. For more information on DIP switches, refer to "1.2.6 DIP Switch (DIPSW) Settings" (page 1-7).
- Connect a shielded cable to either the V9 series or the connected device. The connection diagram shows the case where
 the shielded cable is connected on the V9 series side. Connect the cable to the FG terminal on the backside of
 MONITOUCH.
 - RS-422 (4-wire system)



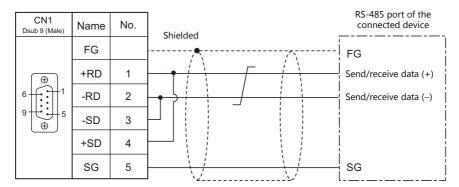
- RS-485 (2-wire system)



- If noise disturbs communications, connect a shielded cable to both the V9 series and the connected device.
 - RS-422 (4-wire system)



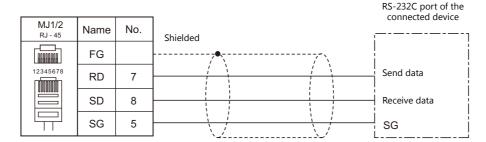
- RS-485 (2-wire system)



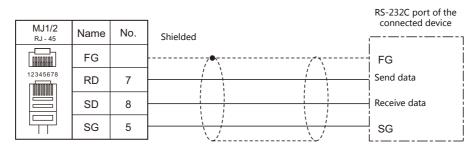
MJ1/MJ2

RS-232C connection

- Use Hakko Electronics' cable "V6-TMP" (3, 5, 10 m) as a communication cable.
- The maximum length of wiring is 15 m.
 - * The maximum length varies depending on the connected device. Check the specifications for each device.
- Connect a shielded cable to either the V9 series or the connected device. Connect the cable to the FG terminal on the backside of MONITOUCH.



• If noise disturbs communications, connect a shielded cable to both the V9 series and the connected device.

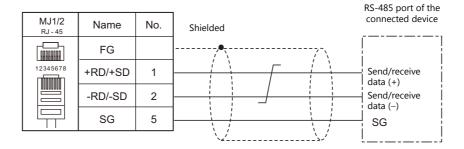


RS-485 (2-wire system) connection

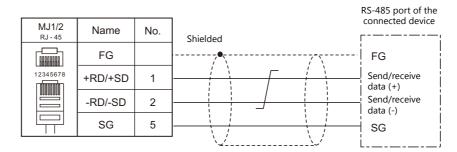


The MJ1 and MJ2 are not usable for connection via RS-422 (4-wire system). Use the CN1 port instead or a commercially available RS-232C-to-RS-422 converter.

- Use Hakko Electronics' cable "V6-TMP" (3, 5, 10 m) as a communication cable.
- The maximum length of wiring is 500 m.
 - * The maximum length varies depending on the connected device. Check the specifications for each device.
- If the PLC has a signal ground (SG) terminal, connect it.
- The DIP switch on the back of the V9 unit is used to set the terminating resistance. For more information, see "1.2.6 DIP Switch (DIPSW) Settings" (page 1-7).
- Connect a shielded cable to either the V9 series or the connected device. Connect the cable to the FG terminal on the backside of MONITOUCH.



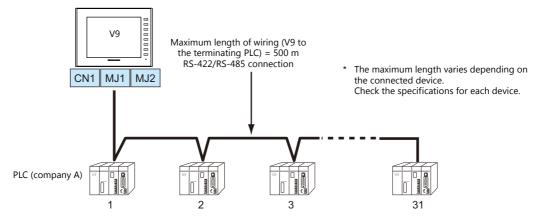
• If noise disturbs communications, connect a shielded cable to both the V9 series and the connected device.



1: n Connection (Multi-drop)

Overview

- Multi-drop connection connects one V9 unit to multiple PLCs of the same model as a 1: n connection. (Maximum connectable units: 31)
- You can make settings for 1: n communication in [Communication Setting] for the logical ports PLC1 PLC8. A communication port is selectable from CN1, MJ1, and MJ2.



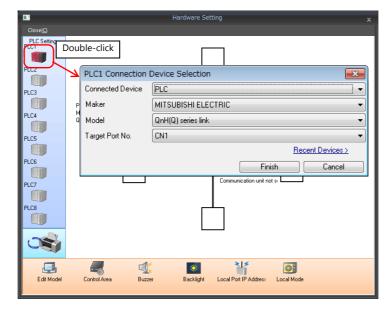
- The ladder transfer function is not available for a 1: n connection.
- For models that support multi-drop connection, refer to the Connection Compatibility List provided at the end of this manual or the chapters on individual manufacturers.

V-SFT Ver. 6 Settings

Hardware Settings

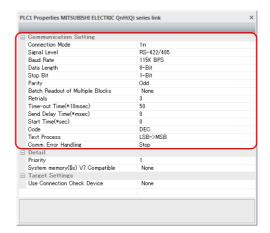
Selecting a device to be connected

Select the device for connection from [System Setting] \rightarrow [Hardware Setting].



PLC properties

Configure [Communication Setting] on the [PLC Properties] window.



Item	Contents	
Connection Mode	1:n	
Signal Level	RS-422/485	
Baud Rate		
Data Length		
Stop Bit	Configure according to the comparted device	
Parity	Configure according to the connected device.	
Target Port No.		
Transmission Mode		

For settings other than the above, see "1.4 Hardware Settings" (page 1-43).

Settings of a Connected Device

Refer to the chapter of the respective manufacturer. For descriptions of connecting PLCs, refer to the manual for each PLC.

Wiring



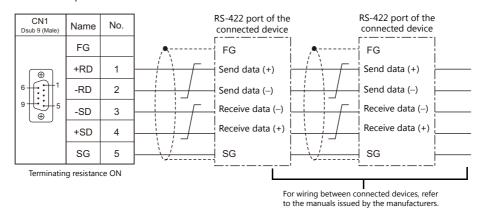
Be sure to turn off the power before connecting cables. Otherwise, electrical shock or damage may occur.

CN1

The wiring between a V9 and a connected device is the same as that for 1:1 communication. For description of wiring between connected devices, refer to the manuals issued by the manufacturers.

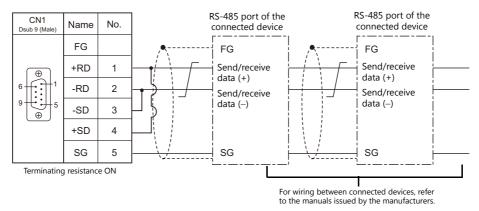
RS-422 (4-wire system) connection

· Connection example



RS-485 (2-wire system) connection

• Connection example

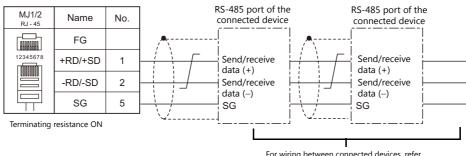


MJ1/MJ2

The wiring between a V9 and a connected device is the same as that for 1:1 communication. For description of wiring between connected devices, refer to the manuals issued by the manufacturers.

RS-485 (2-wire system) connection

• Connection example

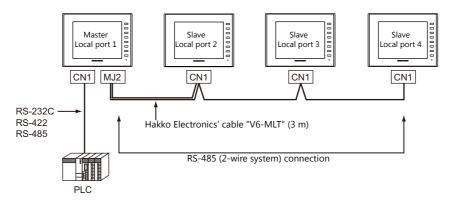


For wiring between connected devices, refer to the manuals issued by the manufacturers.

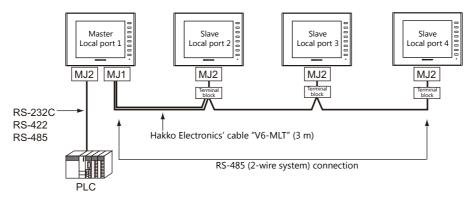
n: 1 Connection (Multi-link2) (Under Development)

Overview

- One PLC is connected to a maximum of four V9 units. The V8, V7, and V6 series can be used together.
- Multi-link2 enables you to establish an original network consisting of a master V9 of local port No. 1 and slave V9 units of local port Nos. 2, 3, and 4. The master V9 communicates with the PLC directly, and the slave V9 units communicate with the PLC through the master.
 - Connection example 1:



- Connection example 2:



- You can make settings for multi-link2 in [Communication Setting] for PLC1. Therefore, multi-link2 connection is not
 possible concurrently with a network connection that uses a "CUR-xx" communication interface unit (under
 development).
- Multi-link2 enables sharing of data stored in PLC1 device memory among the V9 units. However, sharing data in PLC2 PLC8 is not possible.
- The communication speed between the master and the PLC depends on the setting made on the PLC. The maximum communication speed between V9 units is 115 kbps, which is higher than the one available with multi-link connection described in "n:1 Connection (Multi-link) (Under Development)".
- For PLCs that support multi-link2 connection, see Connection Compatibility List provided at the end of this manual.
 The connection between the master and the PLC is the same as the one for 1:1 connection.

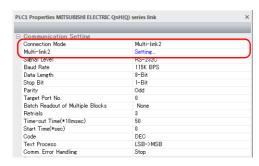
 RS-485 (2-wire system) connection is adopted to connect a master with slaves. At this time, use Hakko Electronics' cable "V6-MLT" for the multi-link2 master.
- When connecting the V6 series together with the V9 series, note the following points:
 - When V609E, V606e, V606, or V606i is connected as a master, only V609E, V606e, V606, or V606i can be connected as a slave.
 - The V9 series cannot be used as a slave in this case.
 - Multi-link2 cannot be used for the V6 series with which temperature control network/PLC2Way is used.
 - Multi-link2 may not be used on the V6 series depending on its hardware version.
 For more information, refer to the V6 Series Hardware Specifications manual.
- If the master station becomes faulty (communication error), the master and slave stations do not work, and as a result, "Communication Error Time-Out" is displayed. If a slave station becomes faulty, "Data Loading..." is displayed due to a communication error only on the faulty station.
- The ladder transfer function is not available for a multi-link2 connection.

V-SFT Ver. 6 Settings

Make settings on [Hardware Setting] \rightarrow [PLC Properties]. The differences with respect to a 1:1 connection and the points where caution is required are explained here.

For details on other settings, refer to Hardware Settings in "1:1 Connection" (page 1-8).

PLC Properties



Item		Contents
	Connection Mode	Multi-link2
Communication Setting	Multi-link2	Click [Setting] to display the [Multi-link] dialog, then make the necessary settings in this dialog. For more information on settings, see " Multi-link2" (page 1-18).

Multi-link2

For a master, set all of the items. For a slave, set only those items marked "♦".

Master





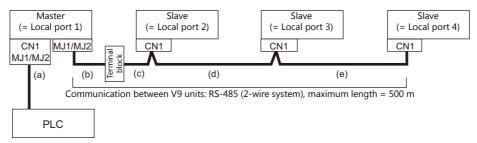


Local Port No.◆	1 to 4 Specify a port number of the V9. For the master set "1", and for the slaves set "2" to "4". Note that if the port number specified is the same as that already set for another V9 unit, the system will not operate correctly.	
Send Delay Time	Specify a delay time that elapses before V9 sends the next command after receiving data from the PLC. Normally use the default setting (0).	
	PLC MONITOUCH Send delay time "t"	
Total ◆	2 to 4 Set the total number of V9 units connected in the multi-link2 connection. The setting must be the same as other V9 series on the same communication line.	
Retry Cycle	Set the number of cycles before the master sends an inquiry for restoration to a slave that has a communication problem (= system down). When a slave has a problem, it is temporarily removed from the communication targets, and the master sends an inquiry for restoration every number of cycles specified for [Retry Cycle]. This setting does not affect the communication speed if no problem is occurring on the slave; however, if there is any problem, it does affect the communication speed. When the setting value is small: Restoration will not take long. When the setting value is large: Restoration will take a longer time.	
Multi-Link Baud Rate◆	4800/9600/19200/38400/57600/115 Kbps Set the baud rate for between V9 series units. The setting must be the same as other V9 series on the same communication line.	
Connect Port	CN1/MJ1/MJ2 Set the port to be connected to slaves.	

System Configurations and Wiring Diagrams

Connection Method 1

Connecting the MJ1/MJ2 of the master to CN1 connectors of the slaves



- (a) Connection between master and PLC
 - Select the port for connection from among CN1, MJ1 and MJ2.

The communication settings and connection method are the same as those for 1:1 connection.

(b), (c) Connection between master and slave

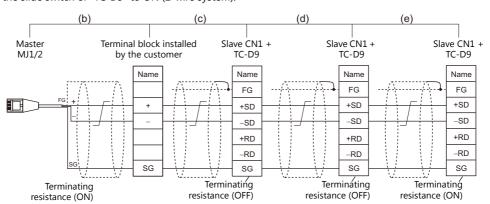
Choose the connecting port of the master between MJ1 and MJ2.

The connecting port of the slave should be CN1. It is convenient to install the optional terminal converter "TC-D9". Use the "V6-MLT" cable (3 m). If the distance is greater than 3 meters the customer should prepare a terminal block and extension cable (c), and should make the connection through that terminal block.

- (d), (e) Connection between slaves
 - Use the RS-485 (2-wire system) connection. It is convenient to install the optional terminal converter "TC-D9". Use twisted-pair cables of 0.3 mm sq or greater.
- (b), (c), (d), (e) The maximum length of the wiring among the master and slave is 500 m.

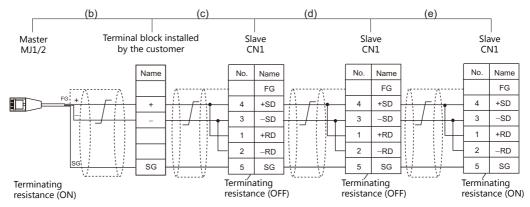
Wiring diagrams

When a TC-D9 is used:
 Set the slide switch of "TC-D9" to ON (2-wire system).



- As a measure against noise, connect the frame ground terminal of each V9 series at one side only. The frame ground of V6-MLT must be connected to the V9 series.
- When no TC-D9 is used:

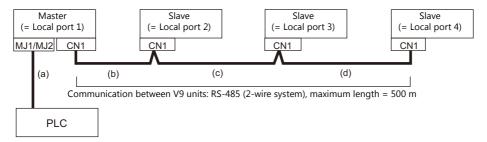
Install jumpers between +SD and +RD as well as -SD and -RD.



 As a measure against noise, connect the frame ground terminal of each V9 series at one side only. The frame ground of V6-MLT must be connected to the V9 series.

Connection Method 2

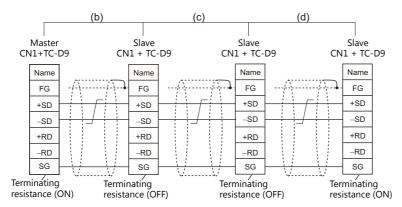
Connecting the CN1 of the master to the CN1s of the slaves



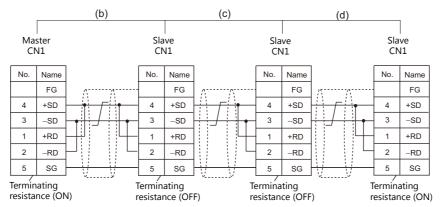
- (a) Connection between master and PLC
 - Choose the connection port between MJ1 and MJ2.
 - The communication settings and connection method are the same as those for 1:1 connection.
- (b), (c), (d) Connection between master and slave
 Use the RS-485 (2-wire system) connection. It is convenient to install the optional terminal converter "TC-D9". Use twisted-pair cables of 0.3 mm sq or greater. The maximum length of the wiring is 500 m.

Wiring diagrams

When a TC-D9 is used:
 Set the slide switch of "TC-D9" to ON (2-wire system).



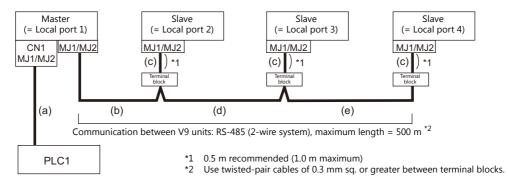
- * As a measure against noise, connect the frame ground terminal of each V9 series at one side only.
- When no TC-D9 is used: Install jumpers between +SD and +RD as well as -SD and -RD.



* As a measure against noise, connect the frame ground terminal of each V9 series at one side only.

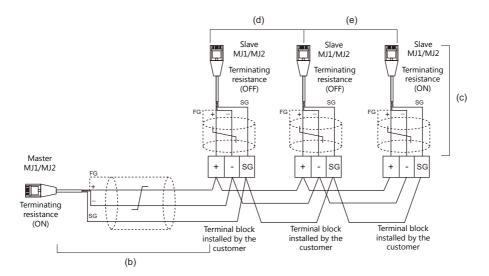
Connection Method 3

Connecting the MJ1/MJ2 of the master to the MJ1/MJ2 ports of the slaves



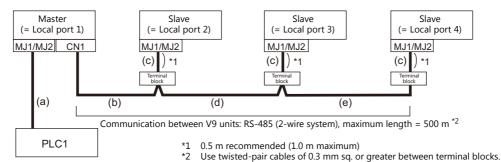
- (a) Connection between master and PLCSelect the port for connection from among CN1, MJ1 and MJ2.The communication settings and connection method are the same as those for 1:1 connection.
- (b) Connection between master and terminal blockChoose the connecting port of the master between MJ1 and MJ2.For the cable, use "V6-MLT" (3 m). Connect the terminals of this cable to a terminal block prepared by the customer.
- (c) Connection between terminal block and slave Choose the connecting port of the slave between MJ1 and MJ2. Use the "V6-MLT" cable (3 m).
- (d) Connection between terminal blocks
 Use the RS-485 (2-wire system) connection. Use twisted-pair cables of 0.3 mm sq or greater.
- (b), (c), (d) The maximum length of the wiring among the master and slave is 500 m.

Wiring diagrams



Connection Method 4

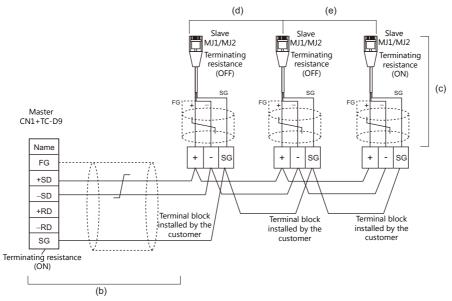
Connecting the CN1 of the master to the MJ1/MJ2 of the slaves



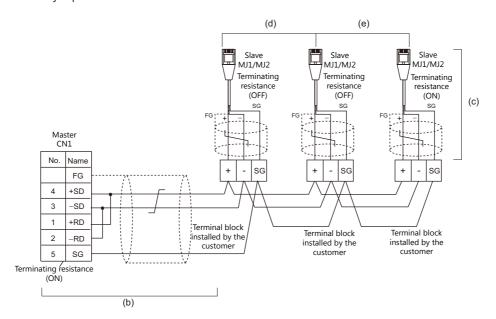
- (a) Connection between master and PLCChoose the connection port between MJ1 and MJ2.The communication settings and connection method are the same as those for 1:1 connection.
- (b), (d), (e) Connection between master and terminal blockFor the connecting port of the master, choose CN1. For the slave, choose between MJ1 and MJ2.Use the RS-485 (2-wire system) connection. Use twisted-pair cables of 0.3 mm sq or greater. The maximum length of the wiring is 500 m.
- (c) Connection between terminal block and slave The connecting port of the slave should be MJ1 or MJ2. Use the "V6-MLT" cable (3 m).

Wiring diagrams

 When a TC-D9 is used: Set the slide switch of "TC-D9" to ON (2-wire system).

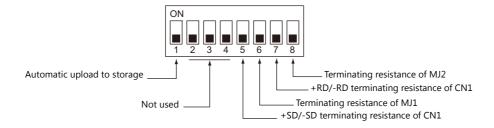


 When no TC-D9 is used: Install jumpers between +SD and +RD as well as -SD and -RD.



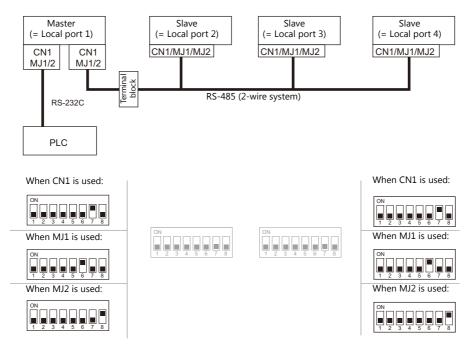
Terminating Resistance Setting

The terminating resistance should be set on the DIP switch.



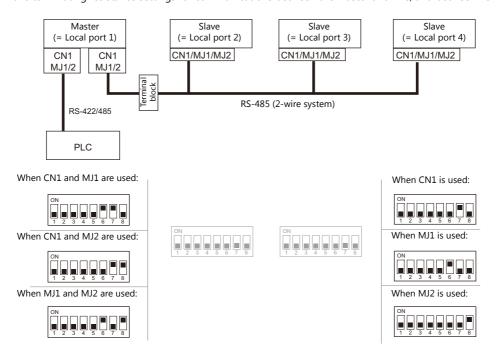
When the PLC is connected to the master via RS-232C:

There is no terminating resistance setting for communications between the master and the PLC. Set terminating resistances for connections between V9 units.



When the PLC is connected to the master via RS-422/485:

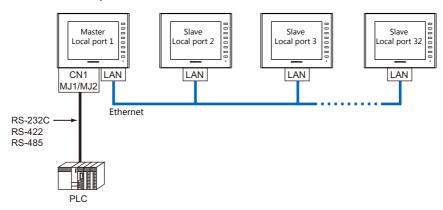
Make terminating resistance settings for communications between the master and PLC, and between V9 units.



n: 1 Connection (Multi-link2 (Ethernet)) (Under Development)

Overview

- One PLC is connected to a maximum of 32 V9 units. The V8 series can be used together.
- Multi-link2 (Ethernet) enables you to establish an original network consisting of a master V9 of local port No. 1 and slave V9 units of local port Nos. 2 to 32. The master V9 communicates with the PLC directly, and the slave V9 units communicate with the PLC through the master.
 - Connection example



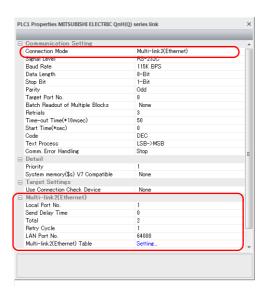
- You can make settings for multi-link2 (Ethernet) in [Communication Setting] for PLC1. Therefore, multi-link2 connection is not possible concurrently with a network connection that uses a "CUR-xx" communication interface unit.
- Multi-link2 (Ethernet) enables sharing of data stored in PLC1 device memory among the V9 units. However, sharing data in PLC2 PLC8 is not possible.
- The V7 and V6 series cannot be used together.
- The communication speed between the master station and the PLC depends on the setting made on the PLC; however, communication among V9 units is performed via Ethernet, thus, high-speed communication is possible among them.
- For PLCs that support multi-link2 (Ethernet) connection, see Connection Compatibility List provided at the end of this
 manual.
 - The connection between the master and the PLC is the same as the one for 1:1 connection. Ethernet connection is adopted to connect a master with slaves.
- If the master station becomes faulty (communication error), the master and slave stations do not work, and as a result, "Communication Error Time-Out" is displayed. If a slave station becomes faulty, "Data Loading..." is displayed due to a communication error only on the faulty station.
- The ladder transfer function is not available for a multi-link2 (Ethernet) connection.

V-SFT Ver. 6 Settings

Make settings on [Hardware Setting] \rightarrow [PLC Properties]. The differences with respect to a 1:1 connection and the points where caution is required are explained here.

For details on other settings, refer to Hardware Settings in " 1:1 Connection" (page 1-8).

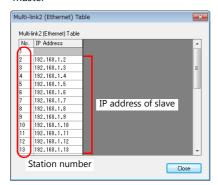
PLC Properties



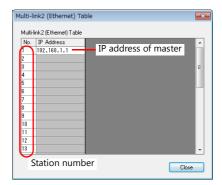
Item		Contents		
Communication Setting	Connection Mode	Multi-link2 (Ethernet)		
	Local Port No.	Master to 32: Slave Note that if the port number specified is the same as that already set for another V9 unit, the system will not operate correctly.		
	Send Delay Time	Specify a delay time that elapses before V9 sends the next command after receiving data from the PLC. Normally use the default setting (0). PLC MONITOUCH Send delay time "t"		
Multi-link2	Total	2 to 32 Set the total number of V9 units connected in the multi-link2 (Ethernet) connection. The setting must be the same as other V9 series on the same communication line.		
(Ethernet)	Retry Cycle	Valid only when the local port is "1" (master). Set the number of cycles before the master sends an inquiry for restoration to a slave that has a communication problem (= system down). When a slave has a problem, it is temporarily removed from the communication targets, and the master sends an inquiry for restoration every number of cycles specified for [Retry Cycle]. This setting does not affect the communication speed if no problem is occurring on the slave; however, if there is any problem, it does affect the communication speed. When the setting value is small: Restoration will not take long. When the setting value is large: Restoration will take a longer time.		
	LAN Port No.	Set a value in the range from 1024 to 65535 (excluding 8001 and 8020). Default: 64000 * Set the same port number for all master and slave stations.		
Multi-link2 (Ethernet) Table Click [Setting] to display the [Multi-link2 (Ethernet) Table] window. For details on settings, refer to the next section.				

Multi-link2 (Ethernet) table

Master



• Slave



Item	Item Contents	
Multi-link2 (Ethernet) Table	 For local port 1 (master) Set the IP addresses of all V9 units used as slave to respective local port numbers. For local port 2 to 32 (slave) Set the IP address of the master V9 for No. 1. 	

Wiring

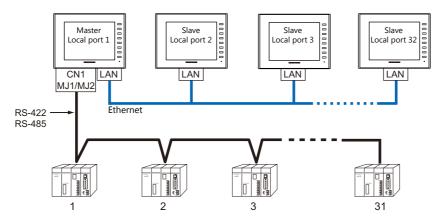
The connection between the master and the PLC is the same as the one for 1:1 connection. Refer to "Wiring" (page 1-10) in "1:1 Connection".

Use a LAN cable to connect a master with slaves.

n: n Connection (1: n Multi-link2 (Ethernet)) (Under Development)

Overview

- A maximum of 32 units of V9 series can be connected to a maximum of 31 units of PLCs.
- Multi-link2 (Ethernet) enables you to establish an original network consisting of a master V9 of local port No. 1 and slave V9 units of local port Nos. 2 to 32. The master V9 communicates with the PLC directly, and the slave V9 units communicate with the PLC through the master.



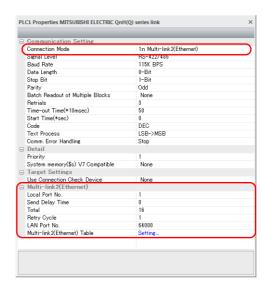
- You can make settings for 1: n multi-link2 (Ethernet) in [Communication Setting] for PLC1. Therefore, multi-link2 connection is not possible concurrently with a network connection that uses a "CUR-xx" communication interface unit.
- 1: n multi-link2 (Ethernet) enables sharing of data stored in PLC1 device memory among the V9 units. However, sharing data in PLC2 PLC8 is not possible.
- The V7 and V6 series cannot be used together.
- The communication speed between the master station and the PLC depends on the setting made on the PLC; however, communication among V9 units is performed via Ethernet, thus, high-speed communication is possible among them.
- For PLCs that support 1: n multi-link2 (Ethernet) connection, see Connection Compatibility List provided at the end of this manual.
 - The connection between the master and the PLC is the same as the one for $\bf 1$: n connection. Ethernet connection is adopted to connect a master with slaves.
- If the master station becomes faulty (communication error), the master and slave stations do not work, and as a result, "Communication Error Time-Out" is displayed. If a slave station becomes faulty, "Data Loading..." is displayed due to a communication error only on the faulty station.
- The ladder transfer function is not available for a 1: n multi-link2 (Ethernet) connection.

V-SFT Ver. 6 Settings

Make settings on [Hardware Setting] \rightarrow [PLC Properties]. The differences with respect to a 1: n connection and the points where care is required are explained here.

For details on other settings, refer to "Hardware Settings" (page 1-14) in "1:n Connection (Multi-drop)".

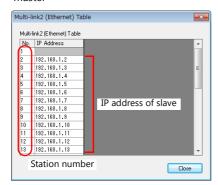
PLC Properties



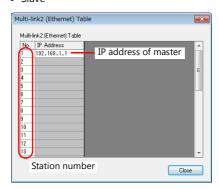
Item		Contents		
Communication Setting	Connection Mode	1 : n Multi-link2 (Ethernet)		
	Local Port No.	Master to 32: Slave Note that if the port number specified is the same as that already set for another V9 unit, the system will not operate correctly.		
		Specify a delay time that elapses before V9 sends the next command after receiving data from the PLC. Normally use the default setting (0).		
	Send Delay Time	PLC MONITOUCH Send delay time "t"		
Multi-link2	Total	2 to 32 Set the total number of V9 units connected in the multi-link2 (Ethernet) connection. The setting must be the same as other V9 series on the same communication line.		
Retry Cycle When the setting		Valid only when the local port is "1" (master). Set the number of cycles before the master sends an inquiry for restoration to a slave that has a communication problem (= system down). When a slave has a problem, it is temporarily removed from the communication targets, and the master sends an inquiry for restoration every number of cycles specified for [Retry Cycle]. This setting does not affect the communication speed if no problem is occurring on the slave; however, if there is any problem, it does affect the communication speed. When the setting value is small: Restoration will not take long. When the setting value is large: Restoration will take a longer time.		
	LAN Port No.	Set a value in the range from 1024 to 65535 (excluding 8001 and 8020). Default: 64000		
* Set the same port number for all master and slave stations. Multi-link2 (Ethernet) Table * Set the same port number for all master and slave stations. Click [Setting] to display the [Multi-link2 (Ethernet) Table] window. For details on settings, refer to the next section.				

Multi-link2 (Ethernet) table

Master



• Slave



Item	Contents
Multi-link2 (Ethernet) Table	 For local port 1 (master) Set the IP addresses of all V9 units used as slave to respective local port numbers. For local port 2 to 32 (slave) Set the IP address of the master V9 for No. 1.

Wiring

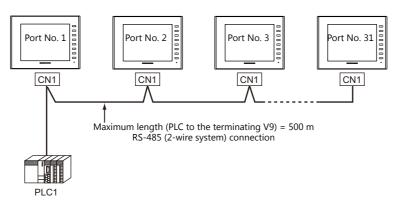
The connection between the master and the PLC is the same as the one for 1: n connection. Refer to "Wiring" (page 1-15) in "1: n Connection (Multi-drop)".

Use a LAN cable to connect a master with slaves.

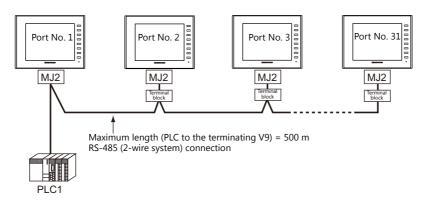
n: 1 Connection (Multi-link) (Under Development)

Overview

- One PLC is connected to a maximum of 31 V9 units. The V8, V7, and V6 series can be used together.
 - Connection example 1:



- Connection example 2:



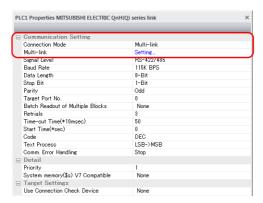
- You can make settings for multi-link at the PLC1. For the V9 and V8 series, a physical port is selectable from CN1, MJ1, and MJ2. For the V7 or V6 series, however, use CN1 only.
- Only a PLC [Signal Level: RS422/RS485] and with a port number set. RS-485 (2-wire system) connection is adopted to connect a V-series unit and a PLC. For available models, see Connection Compatibility List provided at the end of this manual.
- Use twisted-pair cables of 0.3 mm sq. or greater between terminal blocks.
- The ladder transfer function is not available for a multi-link connection.

V-SFT Ver. 6 Settings

Make settings on [Hardware Setting] \rightarrow [PLC Properties]. The differences with respect to a 1:1 connection and the points where care is required are explained here.

For details on other settings, refer to Hardware Settings in "1:1 Connection" (page 1-8).

PLC Properties



Item		Contents
	Connection Mode	Multi-link
Communication Setting	Multi-link	Display the [Multi-link] dialog by pressing the [Setting] button, then make the necessary settings in this dialog. For more information on settings, see " Multi-link" (page 1-32).

Multi-link



Item	Contents	
Local Port No.	1 to 32 Specify a port number of the V9. * Note that if the port number specified is the same as that already set for another V9 unit, the system will not operate correctly.	
Send Delay Time *1	0 to 255 msec (Default setting: 20 msec) Specify a delay time that elapses before V9 sends the next command after receiving data from the PLC. PLC MONITOUCH Send delay time "t"	
Total *1	2 to 32 Set the maximum number of V series units to be connected in multi-link connection. *2	
Retry Cycle *1	1 to 100 (× 10) When the V9 series has a problem, it is temporarily removed from the communication targets, and the master sends an inquiry for restoration every number of cycles specified for [Retry Cycle]. This setting does not affect the communication speed if no problem is occurring; however, if there is any problem, it does affect the communication speed. When the setting value is small: When the setting value is large: Restoration will not take long. Restoration will take a longer time.	
Set Local Port No. in Main Menu	Unchecked Set the local port number on the screen program. Checked Set the local port number on MONITOUCH (see page 1-33).	

- *1 For [Send Delay Time], [Total] and [Retry Cycle], the same values must be set on all the V9 series that are connected in the same communication line.
- *2 When connecting three units with the local port numbers 1, 2 and 10, specify "10" for [Total].

MONITOUCH Setting

Local port setting (Local mode)

When [Set Local Port No. in Main Menu] is checked in the [Multi-link] window, the local port number must be set in Local mode on the V9 series.

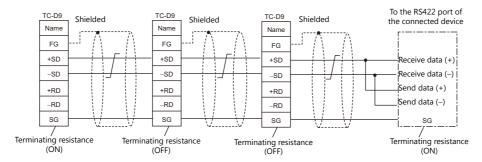
- 1. Transfer the screen program.
- 2. Switch to Local mode on MONITOUCH.
- 3. Press the [Communication Setting] switch and display the Communication Setting screen.
- 4. Set the [Local Port No] on the [Individual Parameter] tab window.
- 5. Press the [Apply] switch.

Wiring

When Connected at CN1

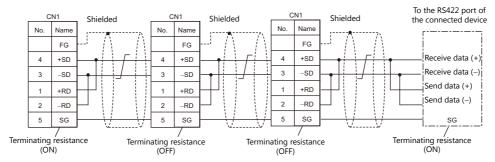
This shows the situation when a multi-link connection is made at CN1. It is convenient to use the Hakko Electronics' optional terminal converter "TC-D9".

When a TC-D9 is used:
 Set the slide switch of "TC-D9" to ON (2-wire system).



Use shielded twist-pair cables.

- Jumpers may not be necessary, depending on the connected device.
- When no TC-D9 is used: Install jumpers between +SD and +RD as well as -SD and -RD.



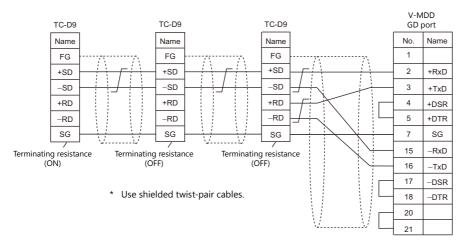
* Use shielded twist-pair cables.

Jumpers may not be necessary, depending on the connected device.

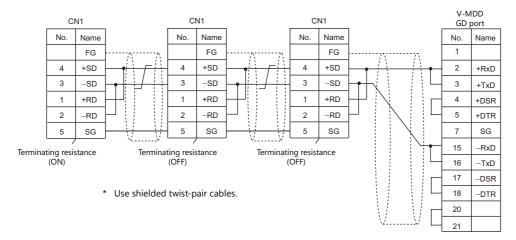
When connecting to Mitsubishi Electric's QnA CPU:

Use the GD port of Hakko Electronics' optional dual port interface V-MDD for the PLC CPU port.

When a TC-D9 is used:
 Set the slide switch of "TC-D9" to ON (2-wire system).

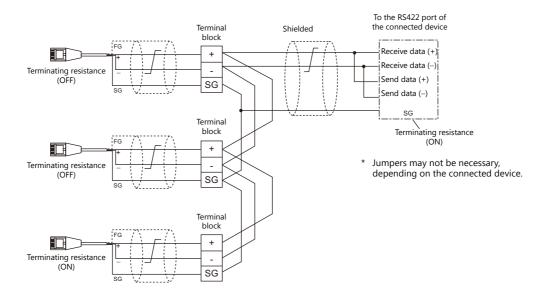


 When no TC-D9 is used: Install jumpers between +SD and +RD as well as -SD and -RD.



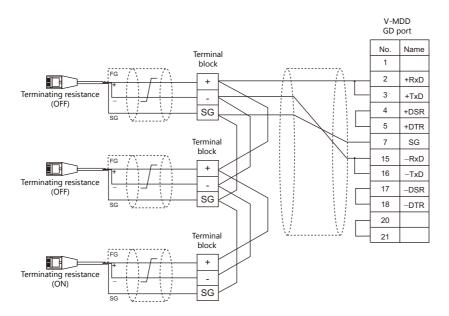
When Connected at MJ1/MJ2:

This shows the situation when a multi-link connection is made at MJ1 or MJ2.



When connecting to Mitsubishi Electric's QnA CPU:

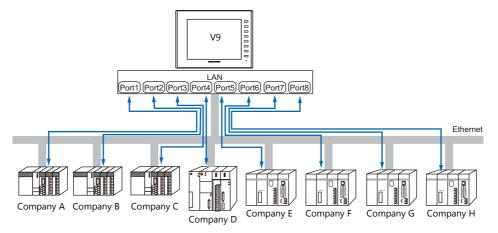
Use the GD port of Hakko Electronics' optional dual port interface V-MDD for the PLC CPU port.



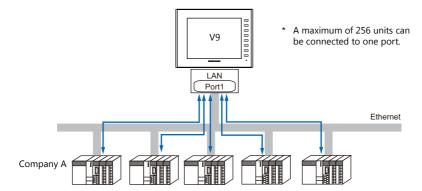
1.3.2 Ethernet Communication

Overview

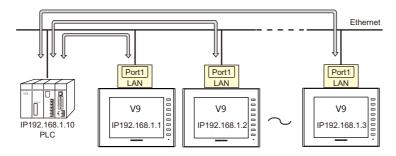
• Because eight communication ports can be opened, the V9 series is allowed to communicate with eight models of PLCs at the same time.



• When there are two or more PLCs of the same model, the V9 series is allowed to carry out 1:n communication via one single port.



• If multiple V9 units are connected to one single PLC, the maximum permissible number of these units depends on the PLC specifications. Refer to the PLC manual issued by the manufacturer.



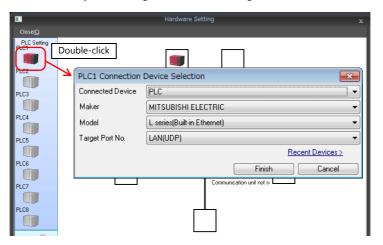
• You can make settings for Ethernet communication in [Communication Setting] for the logical ports PLC1 - PLC8.

V-SFT Ver. 6 Settings

Hardware Settings

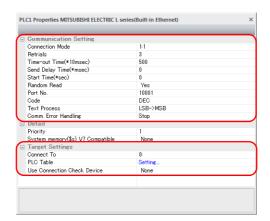
Selecting a device to be connected

Select the device for connection from [System Setting] \rightarrow [Hardware Setting].

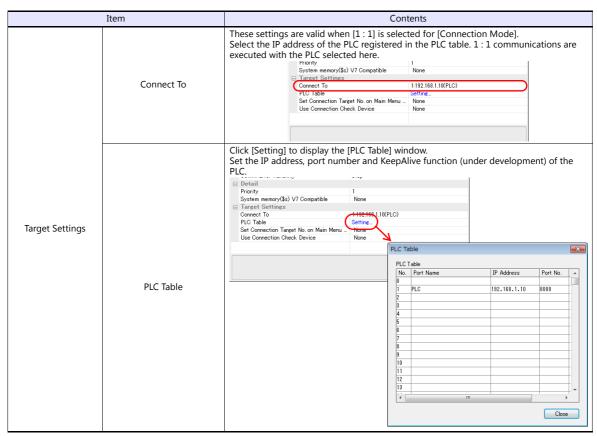


PLC properties

Configure the [PLC Properties].



Item		Contents	
	Connection Mode	1:1/1:n Set the number of PLCs that are to be communicated with.	
	Port No.	Set the port number of the V9 series to be used for communications with the PLCs.	
Communication Setting	KeepAlive (Under development)	This setting is used when using the "KeepAlive" function. The "KeepAlive" function is used for periodically checking the connection with devices on the network. This function enables a prompt detection of a communication error, thus, significantly shortens the time to wait until a "disconnect" process takes place after an occurrence of the time-out error. * When using this function, select [Disconnect] for [Comm. Error Handling]. • [Use KeepAlive] Select [Yes] when using the "KeepAlive" function. The following settings will take effect. - [Retrials] Specify the number of retrials. If a timeout persists even after as many retrials as specified, an error handling routine will take place. 0 to 255 Default: 0 - [Time-out Time] Specify a period of time allowed for V9 to monitor a response from its connected device. If no response is given within the specified time, retrial will be made. 1 to 999 (x 10 msec) Default: 30 (x 10 msec) - [Checking Cycle]	
		Set the cycle time of "KeepAlive" communication. 1 to 999 (× 10 msec) Default: 10 (× 10 msec)	



^{*} For settings other than the above, see "1.4 Hardware Settings" (page 1-43).

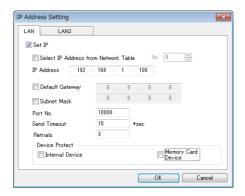
IP Address Setting of the V9 Series

An IP address must be set for the V9 to connect to devices via Ethernet. Set the IP address either on the V9 unit or for the screen program using the V-SFT editor.

Setting Using the V-SFT Editor

Set the IP address at [System Setting] \rightarrow [Hardware Setting] \rightarrow [Local Port IP Address].

Local port IP address setting



Item	Contents	
Select IP Address from Network Table	This is valid when the IP address of the V9 has been registered in the network table. Select a network table number from 0 to 255 to set the IP address.	
Network lable	* For more information on the network table, refer to "Network table" (page 1-50).	
IP Address *1	Set the IP address for the V9.	
Default Gateway *1	Set the default gateway.	
Subnet Mask *1	Set the subnet mask. When this box is not checked, the subnet mask is automatically assigned based on the byte at the extreme left of the IP address. Example: When IP address is "172.16.200.185", "255.255.0.0" is set. When IP address is "192.168.1.185", "255.255.255.0" is set.	
Port No. *1	Set a port number from 1024 to 65535. (Excluding 8001 and 8020)	

Item	Contents	
Send Timeout	Specify the timeout time to send the EREAD/EWRITE/SEND/MES command.	
Retrials	0 to 255 Set the number of retrials to be performed when a time-out occurs.	
Device Protect Internal Device Memory Card Device	Check either check box to write-protect the device memory from computers or other stations.	

^{*1} For more information on each setting item, see "Basics of ethernet settings" (page 1-51).

Settings in Local Mode on the V9 Unit

Set the IP address in Local mode on the V9 unit.

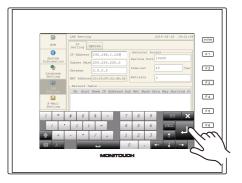
If IP address setting has been performed on the V-SFT editor, this setting will be taken as the valid one.

- 1. Press the [SYSTEM] switch on MONITOUCH to display the system menu.
- 2. Press the [Local] switch. The display switches to Local mode.
- 3. Press the [LAN Setting] switch and display the LAN Setting screen.



4. Set each item.





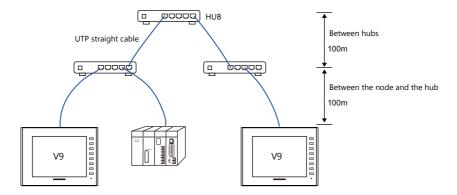
5. Press the [Apply] switch to determine the setting.



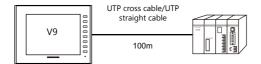
 * Press the [Return to Screen Data Setting] to return to the settings made on the V-SFT editor.

Connection Example

With hub



Without hub

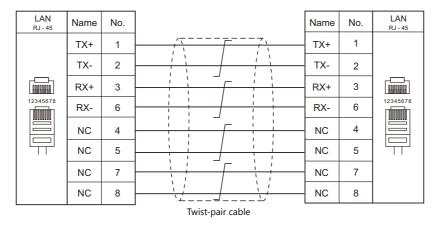


Wiring

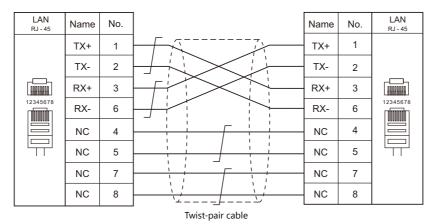


- Use a commercially available cable. Using a self-made cable may cause an error in network connection.
- If the use of a cross cable cannot stabilize communication, use a hub.

• Straight cable



• Cross cable



1.3.3 Network Communication (Under Development)

Overview

• The optional communication interface unit "CUR-xx" is required to enable a network communication listed below.

Communication Interface Unit	Network		Available Models	Remarks
CUR-00	OPCN-1	Mitsubishi Electric OMRON Fuji Electric	A series (OPCN-1) SYSMAC C (OPCN-1) MICREX-SX (OPCN-1)	Under development
CUR-01	T-Link	Fuji Electric Fuji Electric	MICREX-F (T-LINK) MICREX SX (T-LINK)	Under development
CUR-02	CC-LINK Ver.2.0	Mitsubishi Electric Mitsubishi Electric Mitsubishi Electric	A series (CC-LINK) QnA series (CC-LINK) QnH (Q) series (CC-LINK)	Under development
CUR-03	Ethernet *1	Various PLCs	Ethernet UDP/IP communication	Under development
CUR-04	PROFIBUS-DP	Siemens Universal PROFIBUS-	S7 PROFIBUS-DP -DP	Under development
CUR-06	SX BUS	Fuji Electric	MICREX-SX (SX BUS)	Under development
CUR-07	DeviceNet		-	Under development
CUR-08	FL-Net	Universal FL-Net		Under development

^{*1} In addition to UDP/IP communication with a PLC, screen program transfer, the MES interface function, and TELLUS & V-Server connection can be enabled by connecting a PC. Use the built-in LAN port for TCP/IP communication.

V-SFT Ver. 6 Settings

For more information, refer to the communication unit specifications provided for each network.

Wiring

For more information, refer to the communication unit specifications provided for each network.

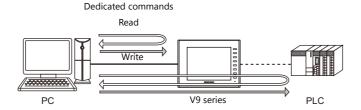
[•] You can make settings for network communication in [Communication Setting] for the logical port PLC1. Thus, devices available with only PLC1, as those used for multi-link or multi-link2, cannot be connected concurrently for network communication.

1.3.4 Slave Communication

Connecting via V-Link, Modbus RTU, or Modbus TCP/IP is applicable to slave communication using the V9. V-Link and Modbus RTU are used for serial communication, and Modbus TCP/IP is used for Ethernet (TCP/IP) communication.

V-Link

• "V-Link" is the network where the PC reads from and writes to the internal device memory of the V9 series, memory card device memory, or PLC1 to 8 device memory using a dedicated protocol.



- You can make settings for V-Link communication in [Communication Setting] for the logical ports PLC2 PLC8.
 A communication port is selectable from CN1, MJ1, and MJ2.
- For more information, refer to "V-Link" in book 3 of the V9 Series Connection Manual.

MODBUS RTU

- The V9 series is connected to a Modbus RTU master via serial connection.
- The device memory table for Modbus slave communication is prepared for the V9. The master is allowed to gain access to the device memory table and read/write the PLC data.
- · For more information, refer to the Modbus Slave Communication Specifications manual separately provided.

MODBUS TCP/IP

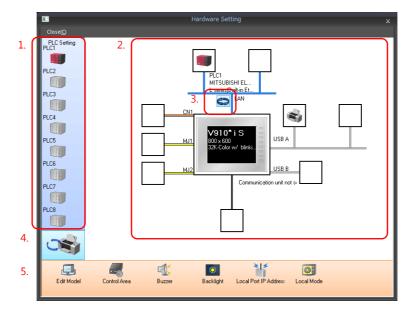
- The V9 is connected to a Modbus TCP/IP master via Ethernet communication.
- The device memory table for Modbus slave communication is prepared for the V9. The master is allowed to gain access to the device memory table and read/write the PLC data.
- For more information, refer to the Modbus Slave Communication Specifications manual separately provided.

1.3.5 Other Connections

For connection to a serial printer that is not in 8-way communication, serial ports of MJ1 and MJ2 are used.

1.4 Hardware Settings

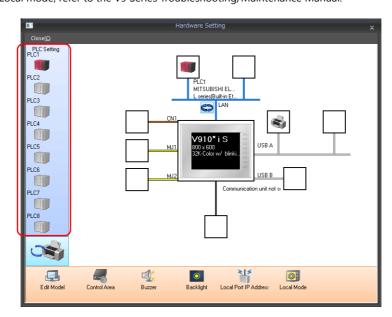
Select and set the devices to connect to the V9 series on the Hardware Setting screen.



	Item	Contents
1.	PLC Setting	Set the devices (PLC, temperature controller, servo, inverter, barcode reader etc.) to connect to PLC1 to PLC8.
2.	Connection Diagram	The devices which are set for connection are displayed. Devices as well as communication settings can be changed.
3.	Built-in LAN / Ethernet unit switch	Select the Ethernet connection port on the V9 series from the internal LAN communication unit. The icon changes each time it is clicked.
4.	PLC Setting / Other Setting switch	Switch between PLC settings and other settings. The icon changes each time it is clicked.
5.	MONITOUCH Settings	Make MONITOUCH settings on the V9 series.

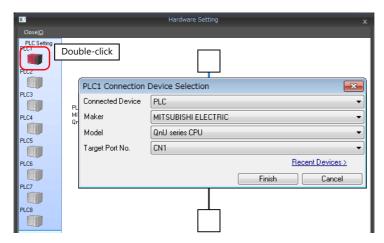
1.4.1 PLC Settings

To enable communication with a PLC, a temperature controller, an inverter, etc., the following settings are required to be set on the editor. You can see the contents of these settings in the V9 Local mode. For information on Local mode, refer to the V9 Series Troubleshooting/Maintenance Manual.



Selecting a Device to be Connected

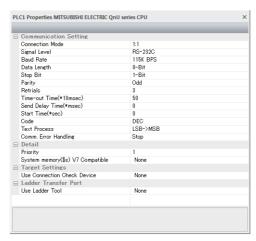
Double-click on a PLC icon in the [Hardware Setting] window to display the window shown below.



Item	Contents
Connected Device	Select the device to connect.
Maker	Select the maker of the device.
Model	Select the model of the device to connect. Refer to the respective chapter of each maker and select the appropriate model.
Target Port No.	Select the port to which the device connects to on the V9 series.

PLC Properties

Click on the PLC icon in [Hardware Setting] to display the window shown below.



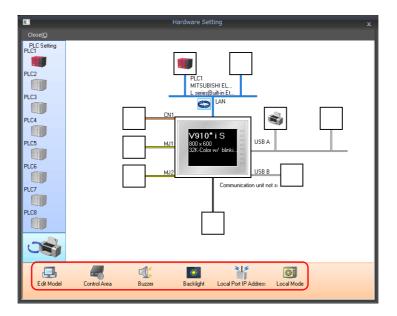
Item		Contents
	Connection Mode	Select a connection mode. $1:1/1:n$ / Multi-link / Multi-link2 (Ethernet) / $1:n$ Multi-link2 (Ethernet) Available options vary, depending on which device is connected. For details, see Connection Compatibility List provided at the end of this manual.
	Signal Level ^{*1}	Select a signal level. RS-232C/RS-422/485
Communication Setting	Baud Rate*1	Select a baud rate. 4800/9600/19200/38400/57600/76800/115K/187.5K* bps * Available only when connecting via Siemens S7-200PPI or S7-300/400MPI and CN1.
	Data Length ^{*1}	Select a data length. 7 / 8 bits
	Stop Bit*1	Select a stop bit. 1 / 2 bits
	Parity*1	Select an option for parity bit. None / Odd / Even
	Target Port No.*1	Specify a port number of the connected device. 0 to 31 (Modbus RTU: 1 to 255)

Item			Contents
	Transmission Mode*1		Select a transmission mode for the connected device. This setting is required if a device of Mitsubishi, Omron, Hitachi Industrial Equipment Systems, Yokogawa, JTEKT, or Yaskawa is in use.
	Retrials		Specify the number of retrials to be allowed in the event of a timeout during communication. If a timeout persists even after as many retrials as specified, an error handing routine will take place. 1 to 255
	Time-out Time		Specify a period of time allowed for V9 to monitor a response from its connected device. If no response is given within the specified time, retrial will be made. 0 to 999 (×10 msec)
	Send Delay Time		Specify a delay time that elapses before V9 sends the next command after receiving a response from its connected device. Normally use the default setting. 0 to 255 (×1 msec) PLC MONITOUCH Send delay time "t"
	Start Time		Specify a delay time that elapses before V9 starts to send commands upon power-up. If V9 and its connected device are turned on at the same time and the device is slower to start up, set [Start Time]. 0 to 255 (×1 sec)
	Code		Select a code for the connected device. The selected option is reflected through the data displayed on graphs or trending sampling parts. DEC/BCD
Communication Setting	Text Process		Specify a byte order in text data. This setting is valid for macro commands that handle text. $LSB \rightarrow MSB/MSB \rightarrow LSB$ $\begin{bmatrix} LSB \rightarrow MSB \end{bmatrix} \qquad \begin{bmatrix} MSB & LSB \\ 2nd byte & 1st byte \end{bmatrix}$ $\begin{bmatrix} MSB \rightarrow LSB \end{bmatrix}$ $\begin{bmatrix} MSB \rightarrow LSB \end{bmatrix}$ $\begin{bmatrix} 15 & 0 \\ 15t byte & 2nd byte \end{bmatrix}$
	Comm. Error Handling		Select an action to be taken in the event of a communication error. • [Stop] Communication will be stopped entirely and the communication error screen will be displayed. The [RETRY] switch is available for attempting reestablishment of communication. • [Continue] The communication error message will be displayed at the center of the screen. The same communication will continue until restoration, and screen operation is not allowed then. When communication has been returned to a normal state, the message disappears and screen operation is allowed. • [Disconnect] No error message will appear and communication will proceed to the next one.* However, communication with the device, in which a timeout was detected, will be disconnected. When a timeout is detected, ⚠ will be displayed for the part that is monitoring the address of the timeout device. * The communication status is displayed on the status bar. For information, refer to the V9 Series Troubleshooting/Maintenance Manual.
		Use Recovery Time	This setting is valid when [Disconnect] is selected for [Comm. Error Handling].
	Recovery Condition	Recovery Time	Return Time 1 to 255 (×10 sec) When the specified time has elapsed, V9 checks the recovery of the device which discontinued communicating.
		Auto-restoration upon screen switch-over	When the screen is switched, V9 checks the recovery of the device which discontinued communicating.

	Item	Contents	
	Priority	[1] (higher priority) - [8] (lower priority) Specify the priority taken during 8-way communication. If interrupts from two or more devices occur at the same time, communication with these devices will take place in order of priority.	
	System device (\$s) V7 Compatible (PLC1)	This is set to [Yes] if the V7-series screen program (including temperature control network/PLC2Way settings) has been converted to data for the V9 series. System information relevant to 8-way communication will be stored in device memory addresses \$P1 and \$s.	
		* For more information, see "1.5.1 \$Pn (For 8-way Communication)" (page 1-55).	
Detail	System device (\$s) V7 Compatible (PLC2)	This is set to [Yes] if the V7-series screen program (including temperature control network/PLC2Way settings) has been converted to data for the V9 series. • [None] \$P2:493/494/495 is used as the transfer table control device memory. • [Yes] \$s762/763/764 is used as the transfer table control device memory. * For more information, see "1.5.1 \$Pn (For 8-way Communication)" (page	
	Device Memory Map Control Device	1-55). Specify the device memory for controlling device memory maps of PLC1 - PLC8. The device memory specified here is the same as [Control Device] in [Device Memory Map Setting] ([System Setting] → [Device Memory Map] → [Device Memory Map Edit] window → [Device Memory Map Setting]). * For more information, refer to the V9 Series Reference Manual.	
	Connect To	Set this for Ethernet communication. For more information, see "1.3.2 Ethernet	
	PLC Table	Communication" (page 1-36).	
Target Settings	Use Connection Check Device	Select [Yes] for connection confirmation using a desired device memory address at the start of communication.	
	Connection Check Device	Specify a desired device memory address used for connection confirmation.	
	Use Ladder Tool	This setting is used when using the ladder transfer tool. * For more information, refer to the V9 Series Reference Manual.	
Ladder Transfer Port	Connection target		
FOIT	Ladder Communication in Local Mode		

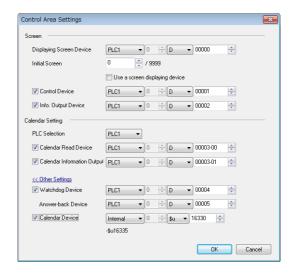
^{*1} Be sure to match the settings to those made on the connected device.

1.4.2 MONITOUCH Settings



Select Edit Model

Control Area

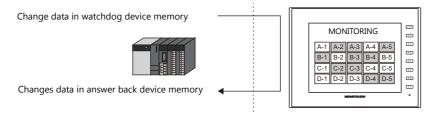


Item		Contents		
	Displaying Screen Device	This device memory is used for switching the screen by an external command. When a screen number is specified in a device memory, the screen is displayed. When the screen is switched by an internal switch, the currently displayed screen number is stored in this device memory.		
Screen	Initial Screen	* When recovering from a communication error, the screen number which was set for the screen displaying device memory is displayed.		
	Use a screen displaying device	When this is checked, the screen number which was set for the screen displaying device memory is displayed as the initial screen.		
	Control Device	For more information, refer to the V9 Series Reference Manual.		
	Info. Output Device	For more information, refer to the v9 Series Reference Manual.		
	PLC Selection	This setting is valid when the V9 s built-in clock is not used. The setting allows the calendar data to be read from device memory via the selected port at PLC1 - PLC8.		
		This setting is valid when the V9 s built-in clock is not used. This bit should be used differently depending on whether the connected PLC is equipped with the calendar function. When MONITOUCH is connected to a PLC with calendar function: When calendar data in the PLC is updated, it can forcibly be read by setting this bit (at the leading edge of [0 — 1]). In addition to calendar data update using this bit, calendar		
Calendar Setting	Calendar Read Device	data in the PLC is automatically read and updated when: - The power is turned on. - STOP → RUN - The date changes (AM 00:00:00). • When MONITOUCH is connected to a PLC without calendar function: A virtual calendar area can be provided by setting [Calendar Device] in [Other Settings]. Setting this bit (ON) will set the data stored in the calendar device memory as calendar data for MONITOUCH.		
	Calendar Information Output Device	The status of the calendar read device memory is stored.		
	Watchdog Device	When data is saved in this area, the same data is written to [Answer-back Device] after the		
Other Settings	Answer-back Device	screen has been displayed. Utilizing this operation, these device memory can be used for watchdog monitoring *1 or display scanning *2.		
	Calendar Device	Use this device memory when the connected device is not equipped with the calendar function and the V9 series built-in clock is not used.		

*1 Watchdog

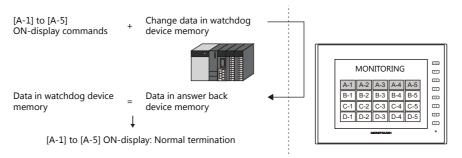
When the PLC is communicating with MONITOUCH, there is no means for the PLC to know whether or not MONITOUCH is doing operations correctly.

To solve this one-way communication, forcibly change data in the watchdog device memory and check that the same data is saved in the answer back device memory. This proves that the V series is correctly doing operations through communications with the PLC. This verification is called "watchdog".



*2 Display scanning

This operation can be utilized for display scanning. Forcibly change data in the watchdog device memory when giving a graphic change command and check that the same data is saved in the answer back device memory. This can prove that the graphic change command is received and executed correctly.



Calendar device memory

Follow the steps below to set the calendar.

- 1. Specify the desired device memory address for [Calendar Device]. Six words are occupied consecutively.
- 2. Save calendar data in the calendar device memory address specified in step 1 in BCD notation. The address allocation of calendar device memory is shown below.

Device Memory	Contents
n	Year (BCD 0 to 99)
n + 1	Month (BCD 1 to 12)
n + 2	Day (BCD 1 to 31)
n + 3	Hour (BCD 0 to 23)
n + 4	Minute(s) (BCD 0 to 59)
n + 5	Second(s) (BCD 0 to 59)

The day of the week is automatically recognized from the above data. It is not necessary to input any data.

- 3. Set the calendar read device memory to ON. At the leading edge of this bit (0 → 1), data in the calendar device memory is set for calendar data on MONITOUCH.
- *1 Calendar data is cleared when the power is turned off. When the power is turned on, set calendar data according to the procedure mentioned above.
- *2 When using the calendar device memory, automatic reading of calendar data at the time of PLC connection as well as once-a-day automatic correction is not performed. Consequently, some errors may be introduced. Perform the procedure described above at regular intervals.

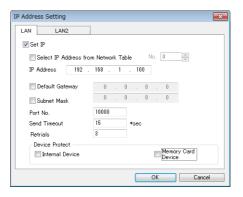
Buzzer

Make settings for the buzzer. For more information, refer to the V9 Series Reference Manual.

Backlight

Make settings for the backlight. For more information, refer to the V9 Series Reference Manual.

Local IP Address



Item	Contents
Select IP Address from Network Table	This is valid when the IP address of the V9 has been registered in the network table. Select a network table number from 0 to 255 to set the IP address.
Network lable	* For more information on the network table, refer to "Network table" (page 1-50).
IP Address*1	Set the IP address for the V9.
Default Gateway*1	Set the default gateway.
Subnet Mask*1	Set the subnet mask. When this box is not checked, the subnet mask is automatically assigned based on the byte at the extreme left of the IP address. Example: When IP address is "172.16.200.185", "255.255.0.0" is set. When IP address is "192.168.1.185", "255.255.255.0" is set.
Port No.*1	Set a port number from 1024 to 65535. Other than 8001.
Send Timeout	Specify the timeout time to send the EREAD/EWRITE/SEND/MES command.
Retrials	0 to 255 Set the number of retrials to be performed when a time-out occurs.
Device Protect Internal Device Memory Card Device	Check either check box to write-protect the device memory from computers or other stations.

 $^{^{\}star}1$ For more information on each setting item, see "Basics of ethernet settings" (page 1-51).

Network table

This is an area for registering IP addresses of the MONITOUCH, PC and other devices.

 $\mathsf{Select}\; [\mathsf{System}\; \mathsf{Setting}] \to [\mathsf{Ethernet}\; \mathsf{Communication}] \to [\mathsf{Network}\; \mathsf{Table}] \; \mathsf{and} \; \mathsf{register}.$



Double-click a number in the No. column to display the [Network Table Setting] dialog. An IP address and other items can be registered.





Network table number

Item	Contents
Port Name	Set the name of the V9 or the computer.
IP Address*1	Set the IP address of the V9 or the computer.
Send Timeout*2	Specify the timeout time to send the EREAD/EWRITE/SEND/MES command.
Port No.*1	Set the port number of the V9 or the computer.
Retrials*2	0 to 255 Set the number of retrials to be performed when a time-out occurs.
Device Protect ^{*2} Internal Device Memory Card Device	Check either check box to write-protect the device memory from computers or other stations.
Default Gateway*1 *2	Set the default gateway.
Subnet Mask*1 *2	Set the subnet mask.

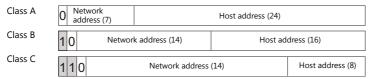
- For more information on each setting item, see "Basics of ethernet settings" (page 1-51). Invalid if V9 units or PCs at other ports are registered. Only valid when set as the local port IP of the V9 unit.

Basics of ethernet settings

IP address

This is an address that is used for recognizing each node on the Ethernet and should be unique.

The IP address is 32-bit data which consists of the network address and the host address and can be classified into classes A to C depending on the network size.



<Notation>

A string of 32-bit data is divided into four, and each segment delimited with a period is in decimal notation. Example: The IP address in class C shown below is represented as "192.128.1.50".

11000000 10000000 00000001 00110010

<Unusable IP addresses>

• "0" is specified for one byte at the extreme left.

• "127" is specified for one byte at the extreme left (loop back address).

• "224" or more is specified for one byte at the extreme left (for multi-cast or experiment).

• The host address consists of only "0" or "255" (broadcast address).

Example: 0.x.x.x

Example: 127.x.x.x Example: 224.x.x.x

Example: 128.0.255.255, 192.168.1.0

Port No.

Multiple applications are running on each node, and communications are carried out for each application between the nodes. Consequently, it is necessary to have a means to identify the application that data should be transferred to. The port number works as this identifier. Each port number is 16-bit data (from 0 to 65535).

The V9 series uses the port for screen program transfer (8001), PLC communication (as desired), and the simulator (8020). Set a unique number in the range of 1024 to 65535. For a PLC or a computer, set the port number in the range of 256 to 65535. It is recommended to set a greater number.

Default gateway

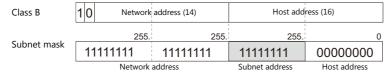
A gateway and a router are used for communication between different networks.

The IP address of the gateway (router) should be set to communicate with the node(s) on other networks.

Subnet mask

A subnet mask is used for dividing one network address into multiple networks (subnet).

The subnet is assigned by specifying a part of the host address in the IP address as a subnet address.



<Unusable subnet masks>

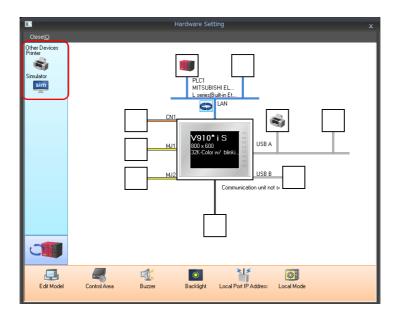
- All bits are set to "0"..... 0.0.0.0
- All bits are set to "1"...... 255.255.255.255

Local Mode Screen

Make prohibition settings for Local mode.

For more information, refer to the V9 Series Reference Manual.

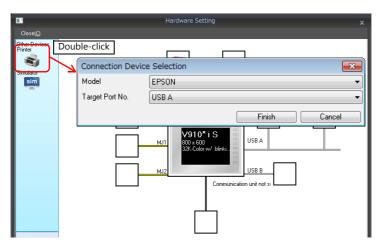
1.4.3 Other Equipment



Printer

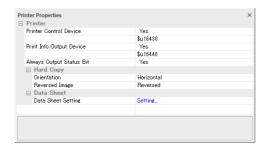
Configure these settings when connecting a printer.

Selecting the printer model



Item	Contents
Model	Select the model of the printer to connect.
Target Port No.	Select the port to connect the printer cable to. USB A: Select when connecting an EPSON, ESC/P-R compatible printer. Also use this setting when connecting a parallel printer using a commercially available parallel-to-USB cable. USB B: Select when connecting a PictBridge-compatible printer. MJ1/MJ2: Select when connecting with the serial interface of a printer. Also select whether to use MJ1 or MJ2 of the V9 series.

Printer properties



Item		Contents		
		When this setting is enabled and the bit is set to ON (0 \rightarrow 1), screen images and data sheets can be printed out.		
		MSB LSB		
Printer Control Device		15 14 13 12 11 10 09 08 07 06 05 04 03 02 01 00		
Timer cor	Itioi Device	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0		
		$0 \rightarrow 1$: Screen image output		
		$0 \rightarrow 1$: Data sheet output		
		When this setting is enabled, the status of the printer is stored in the specified address.		
		MSB LSB		
		15 14 13 12 11 10 09 08 07 06 05 04 03 02 01 00		
Printer Info C	Output Device	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0		
		0: End (standby)		
		1: Transferring print data 0: Not busy status —		
		1: Busy status		
		The V9 series outputs $[0 \rightarrow 1]$ when starting to transfer data upon receiving a print command, and outputs $[1 \rightarrow 0]$ upon finishing transfer. However, these signals may not be output if the		
		print data is small.		
		Select [Yes] to output a signal regardless of the data size.		
		The output area is as follows:		
		 Bit 1 of the device memory for printer information output Bit 0 of internal device memory \$s16 		
Always Outp	out Status Bit	\$s16		
		MSB LSB		
		15 14 13 12 11 10 09 08 07 06 05 04 03 02 01 00		
		0 0 0 0 0 0 0 0 0 0 0 0 0 0		
		0: End (standby)		
		1: Transferring print data		
		Specify the printing orientation of the screen on paper.		
		In vertical output, the screen is rotated 90° clockwise with respect to the printing paper and printed out.		
		Printing examples of hard copies:		
		Horizontal Vertical		
	Orientation			
Hard Copy		A		
<u>.</u>	Reversed Image	Reversed: Screens are printed with black and white inverted. Normal: Screens are printed as they are displayed on MONITOUCH.		
Data Sheet	Data Sheet Setting	Make settings for printing data sheets. For more information, refer to the V9 Series Reference Manual.		
		Make this setting when using a PictBridge-compatible printer.		
Use PictBridge only on USB-B port.		Select [Yes] when starting up the USB-B port as the connection port for a PictBridge printer in		
	,	the RUN mode. When transferring screen programs via the USB-B port, switch to Local mode.		
		, , , , , , , , , , , , , , , , , , , ,		

Item		Contents
Serial Port	Baud Rate	Set the communication baud rate. 4800/9600/19200/38400/57600/76800/115K BPS
	Parity	Select an option for parity bit. None / Odd / Even
	Data Length	Select a data length. 7 bits / 8 bits
	Stop Bit	Select a stop bit. 1 bit / 2 bits

^{*} For details on printing, refer to the V9 Series Reference Manual.

Touch Switch (CH5)

Configure this setting when emulating touch switches on the RGB input screen. The optional unit "GUR-01/GUR-10/GUR-11" (under development) is required for RGB input display. For details on touch switch emulation, refer to the V9 Series Reference Manual.

Simulator

Configure this setting when saving a simulator communication program to a storage device (SD card or USB flash drive) in addition to screen program data using the storage manager.

1.5 System Device Memory for Communication Confirmation

The V9 series has addresses \$s and \$Pn as system device memory.

\$Pn

This is the system device memory for 8-way communications, and 512 words are allocated for each logical port. For more information, see "1.5.1 \$Pn (For 8-way Communication)".

\$s518

This is the system device memory for confirming the Ethernet status. For more information, see "1.5.2 \$s518 (Ethernet Status Confirmation)".

For the device memory address \$s, \$s0 to 2047 (2 K words) are assigned and data can be read from written to this area. For more information on addresses other than \$s518, refer to the V9 Series Reference Manual.

1.5.1 \$Pn (For 8-way Communication)

This is the system device memory for 8-way communications, and 512 words are assigned for each logical port. Refer to the next section for more information.

\$P1: 0000 :	PLC1 area
\$P1: 0511	
\$P2: 0000	
:	PLC2 area
\$P2: 0511	
\$P3: 0000	
:	PLC3 area
\$P3: 0511	
\$P4: 0000	
:	PLC4 area
\$P4: 0511	
\$P5: 0000	
:	PLC5 area
\$P5: 0511	
\$P6: 0000	
:	PLC6 area
\$P6: 0511	
\$P7: 0000	
:	PLC7 area
\$P7: 0511	
\$P8: 0000	
:	PLC8 area
\$P8: 0511	

\$Pn List

The \$Pn list is presented below. Part of the information of logical ports PLC1/PLC2 can also be stored in $\$s.^{*1}$

\$Pn (n = 1 to 8)	\$s*1	Contents	Device Type
000	111 (PLC1)	V9 local port number Stores the local port number of the V9 series. (Universal serial communication, slave communication, etc.)	←V
:	-	:	
004	130 (PLC1) ^{*2}	Modbus TCP/IP Sub Station communications Relay station No. designated device memory When a relay station number is set with a MOV macro command, the error information of the sub station number that is connected to that relay station is stored in \$Pn010 to 025.	→V
:	-	:	
010	128 (PLC1)	Link down information (station No. 0 - 15) 0: Normal 1: Down	
011	129 (PLC1)	Link down information (station No. 16 - 31) 0: Normal 1: Down	
012	114 (PLC1)	Link down information (station No. 32 - 47) 0: Normal 1: Down	
013	115 (PLC1)	Link down information (station No. 48 - 63) 0: Normal 1: Down	
014	116 (PLC1)	Link down information (station No. 64 - 79) 0: Normal 1: Down	
015	117 (PLC1)	Link down information (station No. 80 - 95) 0: Normal 1: Down	
016	118 (PLC1)	Link down information (station No. 96 - 111) 0: Normal 1: Down	
017	119 (PLC1)	Link down information (station No. 112 - 127) 0: Normal 1: Down	←V
018	120 (PLC1)	Link down information (station No. 128 - 143) 0: Normal 1: Down	← V
019	121 (PLC1)	Link down information (station No. 144 - 159) 0: Normal 1: Down	
020	122 (PLC1)	Link down information (station No. 160 - 175) 0: Normal 1: Down	
021	123 (PLC1)	Link down information (station No. 176 - 191) 0: Normal 1: Down	
022	124 (PLC1)	Link down information (station No. 192 - 207) 0: Normal 1: Down	
023	125 (PLC1)	Link down information (station No. 208 - 223) 0: Normal 1: Down	
024	126 (PLC1)	Link down information (station No. 224 - 239) 0: Normal 1: Down	
025	127 (PLC1)	Link down information (station No. 240 - 255) 0: Normal 1: Down	
:	-	:	
099	-	Error information hold (page 1-59) Setting for the update timing of the \$Pn: 0: Other than 0: 010 to 025 link down information Always updated with the latest information Only updated when a communication error occurs	→V
100	730 (PLC2)	Error status Station No. 00 status (page 1-60)	
101	731 (PLC2)	Error status Station No. 01 status (page 1-60)	
102	732 (PLC2)	Error status Station No. 02 status (page 1-60)	
103	733 (PLC2)	Error status Station No. 03 status (page 1-60)	
104	734 (PLC2)	Error status Station No. 04 status (page 1-60)	, M
105	735 (PLC2)	Error status Station No. 05 status (page 1-60)	- ←V
106	736 (PLC2)	Error status Station No. 06 status (page 1-60)	
107	737 (PLC2)	Error status Station No. 07 status (page 1-60)	
108	738 (PLC2)	Error status Station No. 08 status (page 1-60)	
109	739 (PLC2)	Error status Station No. 09 status (page 1-60)	

\$Pn	\$s*1	Contents	Device
(n = 1 to 8)	740		Type
110	(PLC2)	Error status Station No. 10 status (page 1-60)	
:	:	:	
120	750	Error status Station No. 20 status (page 1-60)	
	(PLC2)		1
:	760	;	-
130	(PLC2)	Error status Station No. 30 status (page 1-60)	
131	761	Error status Station No. 31 status (page 1-60)	
131	(PLC2)	Enol status station No. 51 status (page 1 00)	
132	820 (PLC2)	Error status Station No. 32 status (page 1-60)	
133	821 (PLC2)	Error status Station No. 33 status (page 1-60)	
:	:	:	
	828		
140	(PLC2)	Error status Station No. 40 status (page 1-60)	
:	:	:	
150	838 (DLC3)	Error status Station No. 50 status (page 1-60)	
:	(PLC2)	:	←V
	848		~ ∨
160	(PLC2)	Error status Station No. 60 status (page 1-60)	
:	:	:]
170	858 (BLG3)	Error status Station No. 70 status (page 1-60)	
	(PLC2)		
:	:	;	
180	868 (PLC2)	Error status Station No. 80 status (page 1-60)	
:	:	:	
190	878	Error status Station No. 90 status (page 1-60)	
190	(PLC2)	Endi status Station No. 50 status (page 1-00)	
:	:	:	
199	887 (PLC2)	Error status Station No. 99 status (page 1-60)	
200	-	Error status Station No. 100 status (page 1-60)	-
:	:	:	
350	-	Error status Station No. 250 status (page 1-60)	-
:	:	:	
355	-	Error status Station No. 255 status (page 1-60)	
356	-	Device memory map 0 Status	
357	-	Device memory map 0 Error code 1	
358	-	Device memory map 0 Error code 2	
359-361	-	Device memory map 1 Status, error code	_
362-364	-	Device memory map 2 Status, error code	-
365-367	-	Device memory map 3 Status, error code	-
368-370	-	Device memory map 4 Status, error code	-
371-373 374-376	-	Device memory map 5 Status, error code	_
374-376 377-379	-	Device memory map 6 Status, error code Device memory map 7 Status, error code	_
380-382	-	Device memory map 8 Status, error code	+
383-385	-	Device memory map 9 Status, error code	← V
386-388	-	Device memory map 10 Status, error code	+
389-391	-	Device memory map 11 Status, error code	=
392-394	-	Device memory map 12 Status, error code	1
395-397	-	Device memory map 13 Status, error code	
398-400	-	Device memory map 14 Status, error code]
401-403	-	Device memory map 15 Status, error code	
404-406	-	Device memory map 16 Status, error code	
407-409	-	Device memory map 17 Status, error code	
410-412	-	Device memory map 18 Status, error code	
413-415	-	Device memory map 19 Status, error code	_
416-418	-	Device memory map 20 Status, error code	

\$Pn (n = 1 to 8)	\$s*1	Contents	Device Type
419-421	-	Device memory map 21 Status, error code	
422-424	-	Device memory map 22 Status, error code	
425-427	-	Device memory map 23 Status, error code	
428-430	-	Device memory map 24 Status, error code	
431-433	-	Device memory map 25 Status, error code	
434-436	-	Device memory map 26 Status, error code	
437-439	-	Device memory map 27 Status, error code	←V
440-442	-	Device memory map 28 Status, error code	
443-445	-	Device memory map 29 Status, error code	
446-448	-	Device memory map 30 Status, error code	
449	-	Device memory map 31 Status	
450	-	Device memory map 31 Error code 1	
451	-	Device memory map 31 Error code 2	
:	:	:	
493	762 (PLC2) ^{*3}	Device memory map reading prohibited flag (refer to the V9 Series Reference Manual). 0: Periodical reading/synchronized reading executed Other than 0: Periodical reading/synchronized reading stopped	
494	763 (PLC2) ^{*3}	Forced execution of the device memory map TRL_READ/TBL_WRITE macro Setting for macro operation when there is a station with a communication error 0: The macro is not executed in relation to any of the stations. Other than 0: The macro is executed in relation to connected stations.	→V
495	764 (PLC2) ^{*3}	Device memory map writing prohibited flag (refer to the V9 Series Reference Manual). 0: Periodical writing/synchronized writing executed Other than 0: Periodical writing/synchronized writing stopped	
:	-	:	
500	800 (PLC3)		
501	801 (PLC3)	Device memory for Modbus slave communications	
502	802 (PLC3)	Used for setting the number of the reference device memory map and the device memory for referring free area 31.Used for setting the number of the reference device memory map and the device memory for referring free area 31.	→V
503	803 (PLC3)	\$Pn500 to 505 are exclusively used for monitoring: \$s800 to 805 are used for writing from the Modbus master.	,,
504	804 (PLC3)	Refer to the Modbus Slave Communication Specifications.	
505	805 (PLC3)		
:	:	i i	
508	765 (PLC2)		
509	766 (PLC2)	Error response code (page 1-62) If "800BH" (error code received) is stored for the error status (\$Pn100 to 355), it is possible to	←V
510	767 (PLC2)	check the error code.	~ν
511	768 (PLC2)		

 ^{*1} For PLC1, select [Yes] for [System memory (\$s) V7 Compatible] under [Detail] on the [PLC Properties] window. The same information is stored in the \$P1 and \$s.
 *2 If designating the relay station number using \$s130, select [Yes] for [System memory (\$s) V7 Compatible] under [Detail] on the [PLC Properties] window for PLC1. \$P1: 004 cannot be used in this case.
 *3 If executing device memory map control using \$s762, \$s763 and \$s764, select yes for [System memory (\$s) V7 Compatible] under [Detail] on the [PLC Properties] window for PLC2. Note that \$P2: 493/494/495 cannot be used in this case.

Details

\$Pn:99

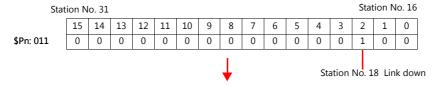
The update timing for the link down information stored in \$Pn:010 to 025 is set here.

0: Always updated with the latest information

Other than 0: Only updated when a communication error occurs

• Example:

An error has occurred at station No. 18. 2nd bit of \$Pn: 011 is set (ON).



After resetting communications

- If \$Pn: 99 = 0, the link down information is updated.



- If \$Pn: 99 = other than 0, the link down information is not updated.

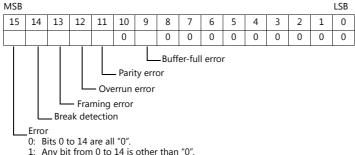
Stat	ion N	o. 31												Stat	ion N	lo. 16	
	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	
\$Pn: 011	0	0	0	0	0	0	0	0	0	0	0	0	0	1	0	0	
												Sta	ation	No. 1	8 Lin	k dov	vn

\$Pn: 100 to 355

The results of communication with each station are stored here. The status codes are shown below.

Code (HEX)	Contents
0000H	Normal
FFFFH	Time-out
8001H	Check code error
8002H	Data error
800BH	Receives the error code from the connected device

Errors other than the above are stored as shown below.



Τ.	\neg iiy	DIL	110111	U	ω	T-4	13	Other	tilaii	U	•

Error	Details	Solution	
Time-out	Although a request to send is given, no answer is returned within the specified time.	Implement solutions 1, 2, and 3.	
Check code	The check code of the response is incorrect.	Implement solutions 1 and 3.	
Data error	The code of the received data is invalid.	Implement solutions 1, 2, and 3.	
Error code received	An error occurred on the connected device.	Refer to the instruction manual for the PLC.	
Buffer full	The V9 buffer is full.	Contact your local distributor.	
Parity	An error occurred in parity check.	Implement solutions 2 and 3.	
Overrun	After receiving one character, the next character was received before internal processing was completed.	Implement solutions 1 and 3.	
Framing	Although the stop bit must be "1", it was detected as "0".	Implement solutions 1, 2, and 3.	
Break detection	The connected device's SD is remaining at the low level.	g at the low Examine the connection with the connected device SD and RD.	

Solution

- 1) Check if the communication settings of the V9 series and the connected device are matched.
- 2) Check the cable connection.
- 3) Data may be disrupted because of noise. Fix noise.

If you still cannot solve the error even after following the solutions above, contact your local distributor.

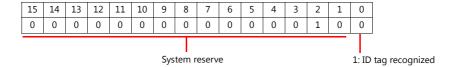
\$Pn: 356 to 451

This device memory is valid when an Omron ID controller (V600/620/680) is connected with [Guarantee synchronism of the data] checked on the [Device Memory Map Setting] dialog.

• Status (\$Pn 356, 359, ...)

The execution status of the device memory map is stored here.

The bit is set (ON) when reading or writing of the first data in the device memory map is correctly finished. When the control device memory (command bit) is set (ON), the bit is reset.

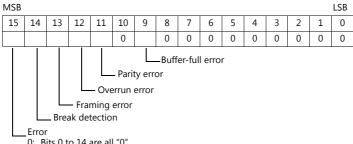


• Error code 1 (\$Pn 357, 360, ...)

An error code is stored when an error occurs in the reading or writing of data in the device memory map. If multiple errors occur in the device memory map, the last error code is stored. When the control device memory (command bit) is set (ON), the bit is reset.

Code (HEX)	Contents
FFFFH	Time-out
8001H	Check code error
8002H	Data error
800BH	Receives the error code from the connected device

Errors other than the above are stored as shown below.



0: Bits 0 to 14 are all "0".

- 1: Any bit from 0 to 14 is other than "0".
- Error code 2 (\$Pn 358, 361, ...)

The exit code is stored here when "800BH" of error code 1 is stored.

Exit Code (HEX)	Contents			
10		Parity error		
11	F	Framing error		
12	Host communication error	Overrun error		
13	Host communication error	FCS error		
14		Format error, execution status error		
18		Frame length error		
70		Tag communication error		
71	Slave communication error	Inconsistency error		
72		Tag absence error		
76		Copy error		
7A		Address error		
7C		Antenna disconnection error		
7D		Write protect error		
75	Tag device memory	Data check command Exit code stored when the writing count management command has been successfully processed (without any error)		
76	warning	Data check command Exit code stored when the writing count management command has abnormally been processed (comparison error, excessive writing counts)		
92	System error	Abnormal mains voltage at antenna		
93	System enoi	Internal device memory error		

\$Pn: 508 to 511

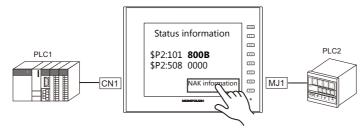
If "800BH" is stored for the error status information (\$Pn: 100 to 355), on transferring the data of that station number to any internal device memory address, the reception code will be obtained at \$Pn: 508 to 511.

Notes on use

- Use \$u/\$T as the target internal device memory.
- Use the macro command MOV (W). MOV (D) cannot be used.
- "0" is stored to device memory addresses that have no expansion error code.
- Example PLC2: Fuji Electric PXR station No. 1
 - 1) On receipt of an error code at station No. 1 of PLC2, "800BH" is stored in \$P2:101.



2) The data of \$P2: 101 is transferred to \$u1000 by a MOV command. \$u1000 = \$P2: 101 (W)



3) The reception code is stored in \$P2: 508. \$P2:508 = 0002H



4) The PXR manual shows that code 002H means "device memory address range exceeded". Amend the screen program address designation.

1.5.2 \$s518 (Ethernet Status Confirmation)

Stores the current status of the Ethernet.

Address	Contents	Stored Value
\$s518	Ethernet status (for built-in LAN port)	[0]: Normal [Other than 0]: Error For details on errors, refer to the next section.

Error details

No.	Built-in LAN	Contents	Solution
201	0	Send error	Check that the setting on the target station is consistent with the network table setting.
203	0	TCP socket creation error	The TCP socket cannot be created. Turn the power off and back on again, or check the communication line status, e.g., if the port number is duplicated.
204	0	TCP connection over	The number of connections reaches the maximum (256), and no more connection is possible. Check the communication lines.
205	0	CP connection error Connection cannot be established. Check the communication lines, or turn the power off and back	
207	0	TCP send error	TCP communication has failed. Check the communication lines.
208	0	TCP connection interruption notification from the connected device	Check the connected device and communication lines.
261	0	Send processing full error	Sending process is disabled. Check the communication lines.
350	0	Send buffer full	The line is busy. Consult the network administrator of your company. The communication unit is of an old version or is faulty.
801	0	Link down error	Check the HUB or the link confirmation LED on the communication unit. If the LED is not on, check cable connection and the port setting on the network table.
1202	0	MAC address error	The MAC address is not registered. Repair is necessary.
2001	0	Undefined error	Turn the power off and back on again. If the problem persists, the unit may be faulty. Contact your local distributor.

MEMO
Please use this page freely.

2. SAIA

2.1 PLC Connection

2.1 **PLC Connection**

Serial Connection

PLC Selection on the CPU		Unit/Port	Signal Level	Conn	Ladder	
Editor	Editor		Signal Level	CN1	MJ1/MJ2	Transfer *1
	PCD1.M120 PCD1.M130	PGU port	RS-232C	Wiring diagram 1 - C2	Wiring diagram 1 - M2	
PCD	PCD2.M120 PCD2.M130	PCD7.F120	RS-232C	Wiring diagram 2 - C2	Wiring diagram 2 - M2	×
	PCD2.M170 PCD2.M480	PCD7.F110	RS-422	Wiring diagram 1 - C4	Wiring diagram 1 - M4	

^{*1} For the ladder transfer function, see the V9 Series Reference Manual.

Ethernet Connection

PLC Selection on the Editor	CPU	Unit	TCP/IP	UDP/IP	Port No.	Keep Alive ^{*1}	Ladder Transfer *2
PCD S-BUS (Ethernet)	PCD.M3120 PCD.M3330 PCD.M5340 PCD.M5540 PCD.M6340 PCD.M6540	CPU with built-in Ethernet	×	0	5050 fixed	0	×

^{*1} For KeepAlive functions, see "1.3.2 Ethernet Communication".
*2 For the ladder transfer function, see the V9 Series Reference Manual.

2.1.1 PCD

Communication Setting

Editor

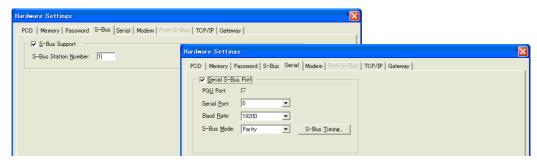
Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1:1/1:n / Multi-link2 / Multi-link2 (Ethernet) / $1:n$ Multi-link2 (Ethernet)	
Signal Level	<u>RS-232C</u> / RS-422/485	
Baud Rate	9600 / <u>19200</u> / 38400 / 57600 / 115K bps	
Data Length	8 bits	
Stop Bit	1 bits	
Target Port No.	1	

PLC

PCD



Item	Setting	Remarks
S-Bus Station Number	1	
Serial Port	0: PGU Port 1: PCD7.F120 / F110	
Baud Rate	19200 bps	
S-Bus Mode	Parity	

Available Device Memory

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

	Device Memory	TYPE	Remarks
R	(register)	00H	Double-word
Rfp	(register/floating point)	01H	Double-word
Т	(timer)	02H	Double-word
С	(counter)	03H	Double-word
I	(input)	04H	Read only
0	(output)	05H	
F	(flag)	06H	

2.1.2 PCD S-BUS (Ethernet)

Communication Setting

Editor

Make the following settings on the editor. For more information, see "1.3.2 Ethernet Communication".

- IP address for the V9 unit
 - When specified on the screen program:
 [System Setting] → [Hardware Setting] → [Local Port IP Address]
 - When specified on the V9 unit: Local mode → [LAN Setting]
- Port number for the V9 unit (for communication with PLC)
 [System Setting] → [Hardware Setting] → [PLC Properties] → [Communication Setting]
- IP address and port number of the PLC
 Register on the [PLC Table] in [System Setting] → [Hardware Setting] → [PLC Properties] → [Target Settings].

PLC

PCD S-BUS (Ethernet)



Item	Setting	Remarks
IP Node	Make settings in accordance with the network environment.	
IP Address	PLC's IP address	For more information, refer to the
Subnet Mask	PLC's subnet mask	manual of the PLC.
Default Router	Make settings in accordance with the network environment.	

Available Device Memory

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

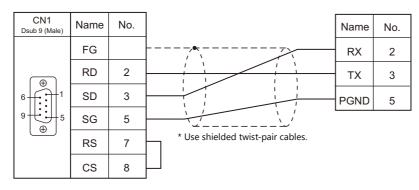
	Device Memory	TYPE	Remarks
R	(register)	00H	Double-word
Rfp	(register/floating point)	01H	Double-word
T	(timer)	02H	Double-word
С	(counter)	03H	Double-word
I	(input)	04H	Read only
0	(output)	05H	
F	(flag)	06H	

2.1.3 Wiring Diagrams

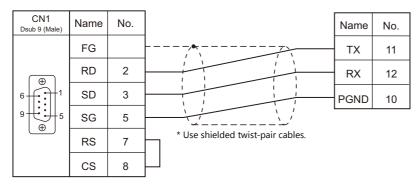
When Connected at CN1:

RS-232C

Wiring diagram 1 - C2

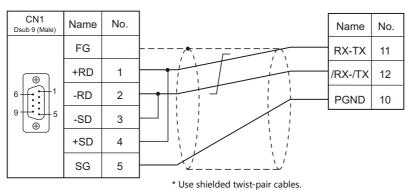


Wiring diagram 2 - C2



RS-422/RS-485

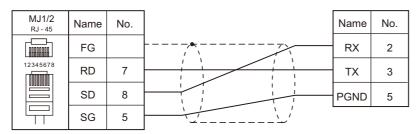
Wiring diagram 1 - C4



When Connected at MJ1/MJ2:

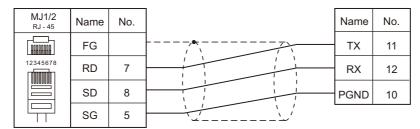
RS-232C

Wiring diagram 1 - M2



* Use shielded twist-pair cables.

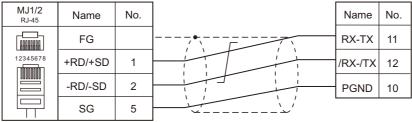
Wiring diagram 2 - M2



* Use shielded twist-pair cables.

RS-422/RS-485

Wiring diagram 1 - M4



^{*} Use shielded twist-pair cables.

MEMO	
	Please use this page freely.

3. SAMSUNG

3.1 PLC Connection

3.1 PLC Connection

Serial Connection

PLC Selection		CPU	Linit/Dort	Cianal Laval	Conn	ection	Ladder	
on the Editor		CPU	Unit/Port	Signal Level	CN1	MJ1/MJ2	Transfer *1	
	N70 plus	CPL9215A CPL9216A	COM1/COM2					
	N700 plus	CPL7215A		RS-232C	Wiring diagram 1 - C2	Wiring diagram 1 - M2	i	
		NX70-CPU70p1	COM port					
N_plus	NX70 plus		NX70-CCU+(CCU)				×	
	,	NX70-CPU70p2	COM1/COM2	_				
			NX70-CCU+(CCU)	RS-485	Wiring diagram 1 - C4	Wiring diagram 1 - M4		
	NX700 plus	NX-CPU700p	COM1/COM2	_				
		-	NX-CCU+(CCU)	20000				
			COM port	RS-232C	Wiring diagram 2 - C2	Wiring diagram 2 - M2	×	
	N70	CPL9211A		RS-422	Wiring diagram 2 - C4	×	0	
			CPL9462(CCU)	RS-232C	Wiring diagram 3 - C2	Wiring diagram 3 - M2	×	
	Ν70α	CPL9210A	COM port	RS-232C	Wiring diagram 4 - C2	Wiring diagram 4 - M2	0	
	N70α CPL9210A		CPL9462(CCU)	RS-232C	Wiring diagram 3 - C2	Wiring diagram 3 - M2	×	
		CPL7210A CPL7211A	COM port	RS-232C	Wiring diagram 2 - C2	Wiring diagram 2 - M2	×	
	N700		CON POR	RS-422	Wiring diagram 2 - C4	×	0	
		CPL7462(CCU)	RS-232C	Wiring diagram 3 - C2	Wiring diagram 3 - M2	×		
	Ν700α		TOOL port	RS-232C	Wiring diagram 3 - C2	Wiring diagram 3 - M2	0	
		CPL6210A CPL6210B	COM port	RS-232C	Wiring diagram 5 - C2	Wiring diagram 5 - M2	×	
		C1 20210B	CPL7462(CCU)	RS-232C	Wiring diagram 3 - C2	Wiring diagram 3 - M2	×	
				RS-232C	Wiring diagram 2 - C2	Wiring diagram 2 - M2	×	
	N7000	OOO CPL5221B CPL5231	COM port	RS-422	Wiring diagram 2 - C4	×	0	
SECNET		C1 L3231	CPL5462(CCU)	RS-232C	Wiring diagram 3 - C2	Wiring diagram 3 - M2	×	
			COM1	RS-422	Wiring diagram 2 - C4	×	0	
	Ν7000α	CPL4210 CPL4211	COM2	RS-232C	Wiring diagram 5 - C2	Wiring diagram 5 - M2	×	
		C1 L4211	CPL5462(CCU)	RS-232C	Wiring diagram 3 - C2	Wiring diagram 3 - M2	×	
			TOOL port	RS-232C	Wiring diagram 1 - C2	Wiring diagram 1 - M2	0	
		NX70-CPU70	NX70-CCU(CCU)	RS-232C	Wiring diagram 6 - C2	Wiring diagram 6 - M2	×	
	NX70		TOOL port	RS-232C	Wiring diagram 1 - C2	Wiring diagram 1 - M2	0	
		NX70-CPU750	COM port	RS-232C	Wiring diagram 6 - C2	Wiring diagram 6 - M2		
			NX70-CCU(CCU)	RS-232C	Wiring diagram 6 - C2	Wiring diagram 6 - M2	×	
		NX-CPU750A	TOOL port	RS-232C	Wiring diagram 1 - C2	Wiring diagram 1 - M2	0	
		NX-CPU750B NX-CPU750C	COM port	RS-232C	Wiring diagram 6 - C2	Wiring diagram 6 - M2		
	NX700	NX-CPU750D	NX-CCU(CCU)	RS-232C	Wiring diagram 6 - C2	Wiring diagram 6 - M2	×	
		NIV CRUZOO	TOOL port	RS-232C	Wiring diagram 1 - C2	Wiring diagram 1 - M2	0	
		NX-CPU700	NX-CCU(CCU)	RS-232C	Wiring diagram 6 - C2	Wiring diagram 6 - M2	×	

^{*1} For the ladder transfer function, see the V9 Series Reference Manual.

3.1.1 N_plus

Communication Setting

Editor

Communication setting

(Underlined setting: default)

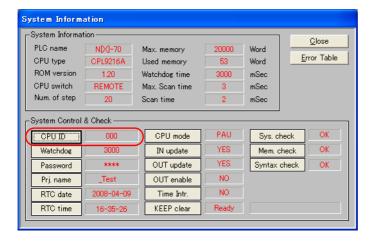
Item	Setting	Remarks
Connection Mode	1:1/1: n / Multi-link / Multi-link2 / Multi-link2 (Ethernet) / 1: n Multi-link2 (Ethernet)	
Signal Level	<u>RS-232C</u> / RS-422/485	For RS-485 connection, set the transmission delay time to 3 msec or longer.
Baud Rate	4800 / <u>9600</u> / 19200 / 38400 bps	
Data Length	8 bits	
Stop Bit	1 bit	
Parity	None	
Target Port No.	<u>0</u> to 31	

PLC

Be sure to match the settings to those made under [Communication Setting] of the editor.

System information

Set a station number for the PLC using the PLC software "WINGPC". For more information, refer to the PLC manual issued by the manufacturer.



Setting Item	Setting	Remarks
CPU ID	0 to 223, 255	

CPL9215A

DIP switches 1

DIPSW1		Contents		Setting		
	SW1	Program write target		ON: EEPRO OFF: RAM		
ON OFF	SW2	RS-232C / RS-485 selection	ON: RS-485 OFF: RS-232C			
2 3	SW3			SW3 OFF	SW4 OFF	Baud Rate 9600bps
4		Baud rate selection		ON OFF	OFF ON	38400bps 19200bps
	SW4			ON	ON	4800bps

CPL9216A

DIP switches 1

DIPSW1		Contents	Setting			
	SW1		SW1 OFF	SW2 OFF	Baud Rate 9600bps	
ON OFF	SW2	Baud rate selection (COM1)	ON OFF ON	OFF ON ON	19200bps 38400bps 4800bps	
1 2 3 3 4	SW3		SW3 OFF	SW4 OFF	Baud Rate 9600bps	
5 6	SW4	Baud rate selection (COM2)	ON OFF ON	OFF ON ON	19200bps 38400bps 4800bps	
7 8	SW5	RS-232C / RS-485 selection (COM1)	ON: RS-485 OFF: RS-232C			
	SW6	RS-232C / RS-485 selection (COM2)	ON: RS-485 OFF: RS-232C OFF			
	SW7	Not used				
	SW8	Program write target	ON: EEPROM OFF: RAM			

DIP switches 2

DIPSW2		Contents	Setting		
ON OFF	SW1	COM1 terminating resistance	SW1	SW2	Terminating Resistance
1		(for RS-485 connection)	OFF	OFF	Invalid
2	SW2		ON	ON	Valid
3					
4	SW3	COM2 terminating resistance (for RS-485 connection)	SW3	SW4	Terminating Resistance
			OFF	OFF	Invalid
	SW4		ON	ON	Valid

CPL7215A

DIP switches 1

DIPSW1		Contents		Setting		
	SW1	Baud rate selection (COM1)		ON: 19200bps OFF: 9600bps		
	SW2			SW2	SW3	Baud Rate
				OFF	OFF	9600bps
<u> </u>		Baud rate selection (COM2)		ON	OFF	19200bps
Δ.	SW3			OFF	ON	38400bps
4	3003		ON	ON	4800bps	
2 3	SW4	Program write target	-	ON: EEPROM OFF: RAM		
→ ON	SW5	COM2 terminating resistance		SW5	SW6	Terminating Resistance
		(for RS-485 connection)		OFF	OFF	Invalid
	SW6			ON	ON	Valid

NX70-CPU70p1 (COM Port)

DIP switches

DIPSW		Contents		Setting		
	SW1	Terminating resistance		SW1	SW2	Terminating Resistance
	SW2	(for RS-485 connection)		OFF ON	OFF ON	Invalid Valid
5 4	SW3	Program write target	_	ON: EEPROM OFF: RAM		
ω ω ν μ μ μ μ μ μ μ μ μ μ μ μ μ μ μ μ μ	SW4	RS-232C / RS-485 selection		N: RS-485 FF: RS-232C		
ON	SW5			SW5	SW6 OFF	Baud Rate 9600bps
	SW6	Baud rate selection		ON OFF ON	OFF ON ON	38400bps 19200bps 4800bps

NX70-CPU70p2 (COM Port) / NX-CPU700p (COM Port)

DIP switches 1

DIPSW1		Contents		Setting		
	SW1	COM1 terminating resistance	SW1	SW2	Terminating Resistance	
4		(for RS-485 connection)	OFF	OFF	Invalid	
ω ω ν	SW2		ON	ON	Valid	
ON	SW3		CITA	CIAVA	Terminating	
		COM2 terminating resistance	SW3	SW4	Resistance	
		(for RS-485 connection)	OFF	OFF	Invalid	
	SW4		ON	ON	Valid	
					<u> </u>	

DIP switches 2

DIPSW2		Contents		S	etting		
	SW1	Program write target	ON: EEPROM OFF: RAM				
	SW2	Not used	OFF				
	SW3	RS-232C / RS-485 selection (COM2)	ON: RS-48 OFF: RS-2				
	SW4	RS-232C / RS-485 selection (COM1)	ON: RS-48 OFF: RS-2				
8 7 6	SW5	Baud rate selection (COM1)	SW5 OFF	SW6	Baud Rate 9600bps		
5 1 4			ON	OFF	38400bps		
ω	SW6		OFF	ON	19200bps		
2	3000		ON	ON	4800bps		
<u> </u>							
ON	SW7		SW7	SW8	Baud Rate		
			OFF	OFF	9600bps		
	SW8	Baud rate selection (COM2)	ON	OFF	38400bps		
			OFF	ON	19200bps		
	3110		ON	ON	4800bps		

NX-CCU+(CCU) / NX70-CCU+(CCU)

DIP switches

DIPSW		Contents		Setting				
	SW1			SW1	SW2	SW3	Baud Rate	
				OFF	OFF	OFF	38400bps	
	SW2	Baud rate selection		ON	OFF	OFF	19200bps	
N				OFF	ON	OFF	9600bps	
4	SW3			ON	ON	OFF	4800bps	
σ Ι	63474	B	_					
o ■	SW4	Data length	U	ON: 8 bits OFF: None				
7	SW5	Parity check	_					
<u>∞</u>	SW6	ranty check	٦	OFF: None				
ON	SW7	Stop bit	О	FF: 1 bit				
	SW8	Reserved	0	FF				

Available Device Memory

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

	Device Memory	TYPE	Remarks
R	(input/output)	00H	
L	(link relay)	01H	
М	(internal relay)	02H	
K	(keep relay)	03H	
F	(special relay)	04H	
W	(word register)	05H	

3.1.2 SECNET

Communication Setting

Editor

Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1:1/1:n/Multi-link/Multi-link2/ Multi-link2 (Ethernet)/1:n Multi-link2 (Ethernet)	
Signal Level	RS-232C / RS-422/485	
Baud Rate	4800 / <u>9600</u> / 19200 / 38400 / 57600 / 76800 / 115K bps	
Data Length	7 / <u>8</u> bits	
Stop Bit	<u>1</u> / 2 bits	
Parity	None / <u>Odd</u> / Even	
Target Port No.	0 to 31	Only port No. 31 is valid, depending on the CPU model. For connection with a CCU module, select port No. 1.
Header	<u>% (Header)</u> / < (Extension Header)	Models on which "< (Expansion Header)" is available: NX-CPU750A / NX-CPU750B / NX-CPU750C / NX-CPU750D / NX70-CPU750
Monitor Registration	Unchecked / <u>Checked</u>	One V9 unit can be registered as a monitor for one PLC. When multi-link connection (n : 1) is selected, do not check this box for multiple V9 units.

PLC

Be sure to match the settings to those made under [Communication Setting] of the editor.

Available Device Memory

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

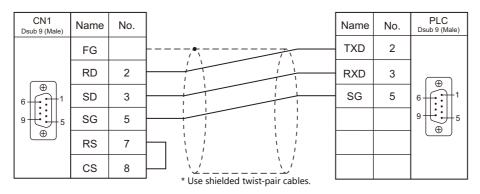
	Device Memory	TYPE	Remarks
DT	(data register)	00H	
Х	(external input)	01H	WX as word device, read only
Υ	(external output)	02H	WY as word device
R	(internal relay)	03H	WR as word device
L	(link relay)	04H	WL as word device
LD	(link register)	05H	
FL	(file register)	06H	
SV	(timer, counter/set value)	07H	
EV	(timer, counter/elapsed time)	08H	
T	(timer/contact)	09H	Read only
С	(counter/contact)	0AH	Read only

3.1.3 Wiring Diagrams

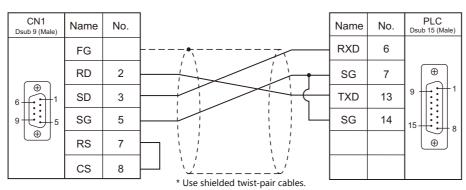
When Connected at CN1:

RS-232C

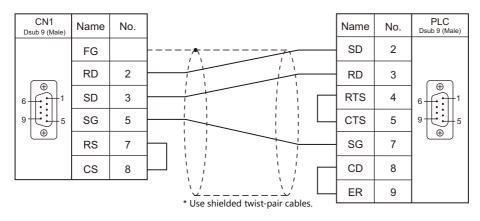
Wiring diagram 1 - C2



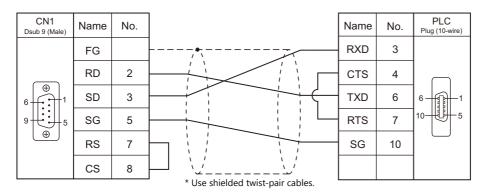
Wiring diagram 2 - C2



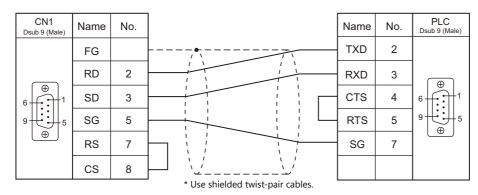
Wiring diagram 3 - C2



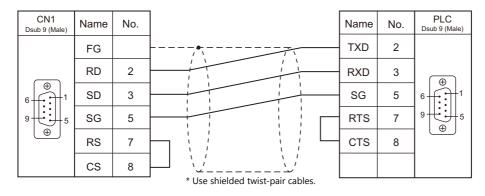
Wiring diagram 4 - C2



Wiring diagram 5 - C2

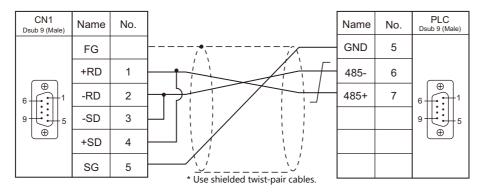


Wiring diagram 6 - C2

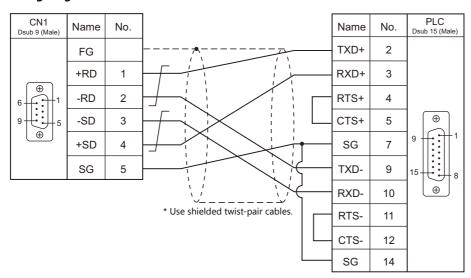


RS-422/RS-485

Wiring diagram 1 - C4



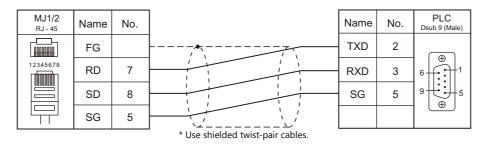
Wiring diagram 2 - C4



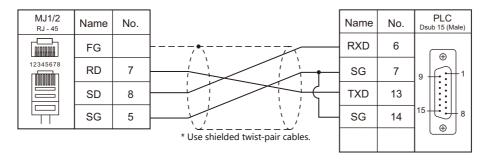
When Connected at MJ1/MJ2:

RS-232C

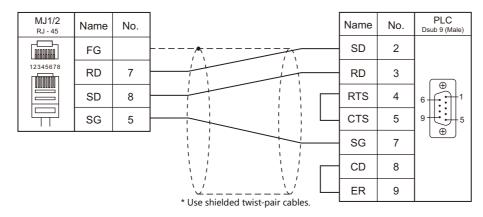
Wiring diagram 1 - M2



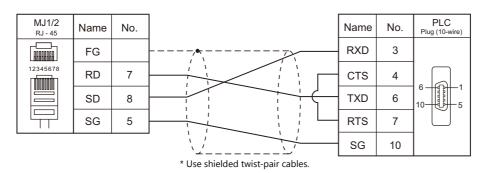
Wiring diagram 2 - M2



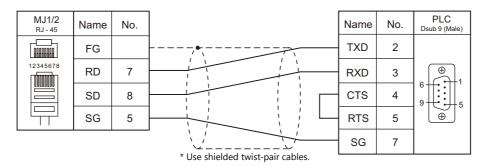
Wiring diagram 3 - M2



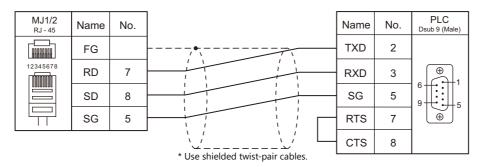
Wiring diagram 4 - M2



Wiring diagram 5 - M2

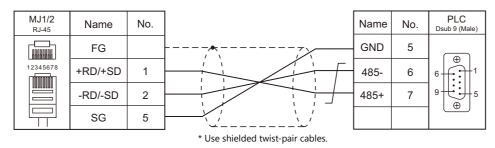


Wiring diagram 6 - M2



RS-422/RS-485

Wiring diagram 1 - M4



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4. SanRex

4.1 Temperature Controller / Servo / Inverter Connection

4.1 Temperature Controller / Servo / Inverter Connection

Serial Connection

DC Power Supply Unit

PLC Selection on the	Model	Port Signal Level -		Conne	Lst File	
Editor	Wodel	FOIL	Signal Level	CN1	MJ1/MJ2	LSCFIIE
DC AUTO (HKD type)	Type HKD B	Terminal block	RS-422	Wiring diagram 1 - C4	×	HKD.Lst

4.1.1 DC AUTO (HKD type)

Communication Setting

Editor

Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1 : 1 / <u>1 : n</u> / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet)	
Signal Level	RS-422/485	
Baud Rate	9600 bps	
Parity	Even	
Data Length	8 bits	
Stop Bit	1 bit	
Target Port No.	<u>1</u> to 31	

DC AUTO (Type HKD B)

Item	Setting	Remarks
Communication address	1 to 31	
Baud rate	9600 BPS	
Transmission mode	8E1	
REMOTE/PANEL key	REMOTE	Remote control mode *1

^{*1} This setting is not provided, depending on the model.

Available Device Memory

The available setting range of device memory varies depending on the model. Be sure to set within the range available for the model to be used. Use [TYPE] when assigning indirect device memory for macro programs.

Device Memory		TYPE	Remarks
М	(monitor data)	00H	Read only
MD	(monitor data (4 bytes))	01H	Double-word, read only
S	(setting data)	02H	*1
SD	(setting data (4 bytes))	03H	Double-word

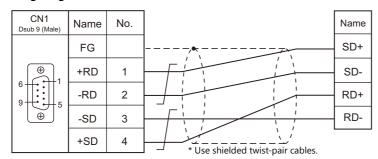
^{*1} When changing the data setting, press the REMOTE/PANEL key to select the remote mode.

4.1.2 Wiring Diagrams

When Connected at CN1:

RS-422/RS-485

Wiring diagram 1 - C4



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5. SANMEI

5.1 Temperature Controller/Servo/Inverter Connection

5.1 Temperature Controller/Servo/Inverter Connection

AC Servo Driver

PLC Selection on the Editor	Model	Port	Signal Level	Connection		Lst File
				CN1	MJ1/MJ2	LSt File
Cuty Axis	QT-0xxAX CN4	CNA	RS-232C	Wiring diagram 1 - C2	Wiring diagram 1 - M2	SanOT.Lst
		CIN4	RS-422	Wiring diagram 1 - C4	×	SanQ1.LSt

5.1.1 Cuty Axis

Communication Setting

Editor

Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1:1/ <u>1:n</u> /Multi-link2/ Multi-link2 (Ethernet)/ 1:n Multi-link2 (Ethernet)	
Signal Level	<u>RS-232C</u> / RS-422/485	
Baud Rate	9600 bps (fixed)	
Data Length	8 bits (fixed)	
Stop Bit	1 bit (fixed)	
Parity	Even (fixed)	
Target Port No.	<u>0</u> to 9	Set the same number as the axis number of the AC servo driver.

AC Servo Driver

The communication parameters can be set using the MODE key on the built-in digital operator attached to the front of the AC servo driver.

They can also be set by using the software "Cuty Wave" or the ladder program.

For settings using the software or ladder program, refer to the AC servo driver manual issued by the manufacturer.

(Underlined setting: default)

Mode	Parameter No.	Item	Setting	Remarks
Parameter mode (P-)	27	Axis number	<u>0</u> to 9	Invalid during RS-232C communication

The following settings are fixed; baud rate: 9600 bps, data length: 8 bits, stop bit: 1 bit, and parity: even.

Available Device Memory

The available setting range of device memory varies depending on the model. Be sure to set within the range available for the model to be used. Use [TYPE] when assigning indirect device memory for macro programs.

	Device Memory	TYPE	Remarks
PRM	(parameter) *1	00H	Double-word
TBL	(point table) *2	01H	Double-word
OPE	(basic operation)	02H	Double-word
MON	(value monitor) *1	03H	Double-word, read only
IO	(I/O monitor) *1	04H	Double-word, read only
ALM	(alarm status) *1	05H	Double-word, read only
S	(servo status)	06H	Double-word, read only
VV	(internal monitor)	07H	Double-word, read only

- *1 When using the parameter, value monitor, I/O monitor or alarm status device memory, set the address with the number of digits shown below. For other types of device memory, see "Device Memory Types" described later.
 - Parameter, value monitor, I/O monitor: 8 digits
 - Alarm status: 4 digits
- *2 Address denotations

On the signal name reference list, every point number is designated as "00". To access any point number other than "00", manually input the desired number.

aabb

Point number (00H to 07H)
Address

Device Memory Types

Туре	Address	Name	Digits
	0	Absolute/relative value	2
	1	Distance of movement	8
	2	Speed	4
	3 Acceleration/deceleration time constant		4
TBL	4	Wait time	4
(Point table)	5	Continuous motion	2
	6	Branch target point number	2
	7	Acceleration/deceleration ON/OFF at S	2
	8	Expansion (1)	2
	9	Expansion (2)	4
	0	Write into EEPROM	1
	1	Servo ON	1
	2	Servo OFF	1
	3	Emergency stop ON	1
	4	Emergency stop OFF	1
	5	Alarm reset	1
	6	Start ON	1
	7	Start OFF	1
	8	Zero start ON	1
	9	Zero start OFF	1
	Α	Zero deceleration ON	1
	В	Zero deceleration OFF	1
OPE	С	Pause ON	1
	D	Pause OFF	1
(Basic operation)	E	Single block ON	1
орегинопу	F	Single block OFF	1
	10	Point No. designation	2
	11	Log clear	1
	12	Torque peak reset	1
	13	Machine zero point change	8
	14	Reset	1
	15	Normal JOG	1
	16	Reverse JOG	1
	17	JOG stop	1
	18	General-purpose output setting	2
	19	General-purpose output	
	1A	Smoothing setting	8

Туре	Address	Name	Digits
1	0	Servo status	8
	1	Command point	2
·	2	Motor type	2
S	3 ROM version		4
(Servo status)	4	System data 1	4
	5	System data 2	4
	6	System data 3	
	7	System data 4	2
	0	System data 1	2
	1	System data 2	2
	2	System data 3	2
•	3	System data 4	2
	4	System data 5	2
	5	System data 6	2
•	6	System data 7	2
•	7	System data 8	2
Internal	8	Speed [rpm]	8
monitor	9	Torque [%]	8
0.00	Α	Torque (+-) peak [%]	8
(VV)	В	Current position [pulse]	8
•	С	Position command [pulse]	8
	D	Position deviation [pulse]	8
	E	Servo status	8
	F	I/O status	8
	10	System data 9	4
	11	11 System data 10	
	12	12 System data 11	
	13	Point being executed	2

PLC_CTL

Macro command "PLC_CTL F0 F1 F2"

Contents	F0		F1 (= \$u n)	F2
	1 - 8	n	n Command: 7FH *1	
Data write of all axes (PRM, OPE) (I		n + 1	Device number 00H: Parameter (PRM) 02H: Basic operation (OPE)	5
	(PLC1 - 8)	n + 2	Address	
		n + 3	Data (lower)	
		n + 4	Data (higher)	
		n	Command: 7FH *1	
		n + 1	Device number 01H: Point table (TBL)	
		n + 2	Point number: 0000H to 0007H	
		n + 3 to n + 4	Absolute/relative value: 0 to 1	
		n + 5 to n + 6	Distance of movement: -9999999 to 9999999	
Data write of all axes *2	1 - 8	n + 7 to n + 8	Speed: 1 to 5000	22*3
(TBL)	(PLC1 - 8)	n + 9 to n + 10	Acceleration/deceleration time constant: 1 to 9999	23*3
		n + 11 to n + 12	Wait time: 0 to 9999	
		n + 13 to n + 14	Continuous motion: 0 to 1	
		n + 15 to n + 16	Branch target point number: 0 to 107	
		n + 17 to n + 18	S-shaped motion ON/OFF: 0 to 1	
		n + 19 to n + 20	Expansion 1 *3	
		n + 21 to n + 22	Expansion 2 *3	
	1 - 8 (PLC1 - 8)	n	Station number: 0100H to 0109H	
Data write of each axis		n + 1	Device number 00H: Parameter (PRM) 02H: Basic operation (OPE)	5
(PRM, OPE)		n + 2	Address	
		n + 3	Data (lower)	
		n + 4	Data (higher)	
	1 - 8 (PLC1 - 8)	n	Station number: 0100H to 0109H	
		n + 1	Device number 01H: Point table (TBL)	
		n + 2	Point number: 0000H to 0007H	
		n + 3 to n + 4	Absolute/relative value: 0 to 1	
		n + 5 to n + 6	Distance of movement: -99999999 to 99999999	
Data write of each axis (TBL)		n + 7 to n + 8	Speed: 1 to 5000	23*3
		n + 9 to n + 10	Acceleration/deceleration time constant: 1 to 9999	25
		n + 11 to n + 12	Wait time: 0 to 9999	
		n + 13 to n + 14	Continuous motion: 0 to 1	
		n + 15 to n + 16	Branch target point number: 0 to 107	
		n + 17 to n + 18	S-shaped motion ON/OFF: 0 to 1	
		n + 19 to n + 20	Expansion 1 *3	
		n + 21 to n + 22	Expansion 2 *3	
Teaching	1 - 8 (PLC1 - 8)	n	Station number: 00H to 09H	
		n + 1	Command: 0000H	2
		n + 2	Data (lower)	
		n + 3	Data (higher)	

Contents	F0	F1 (= \$u n)						
		n	Station number: 00H to 09H					
	1 - 8 (PLC1 - 8)	n + 1	Command: 0001H					
T waveform monitor sampling		n + 2	Control code Bit - 7 6 5 4 3 2 1 0 Trigger target 0: Speed 1: Torque 2: Servo status 3: Manual Trigger edge 0: Leading edge in normal turn 1: Trailing edge in normal turn 2: Leading edge in reverse turn 3: Trailing edge in reverse turn 0: 2 ms (50 ms/div) 1: 4 ms (100 ms/div) 2: 8 ms (200 ms/div) 2: 8 ms (200 ms/div) 3: 20 ms (500 ms/div) Operation command 0: Stop 1: Run	5				
		n + 3	Trigger position 00H to 1EH (0FH: Center) Servo status bit Bit - 7 6 5 4 3 2 1 0 Positioning					
		n + 5	Servo status					
		n + 6	Torque					
		n + 7	Speed	ļ				
		n + 8	Servo status					
		:	:					
		n + 51	Torque					
		n + 52	Speed					
		n	Station number: 00H to 09H					
		n + 1	Command: 0002H					
		n + 2 to n + 3	Servo status					
		n + 4 to n + 5	Command point					
	1 0	n + 6 to n + 7	Motor type					
Servo status acquisition	1 - 8 (PLC1 - 8)	n + 8 to n + 9	ROM version	2				
	(. 201 0)							
		n + 10 to n + 11	System data					
		n + 12 to n + 13	System data					
		n + 14 to n + 15	System data					
		n + 16 to n + 17	System data					

Contents	F0		F1 (= \$u n)				
		n	Station number: 00H to 09H				
		n + 1	Command: 0003H				
		n + 2 to n + 3	System data				
		n + 4 to n + 5	System data				
		n + 6 to n + 7	System data				
		n + 8 to n + 9	System data				
		n + 10 to n + 11	System data				
		n + 12 to n + 13	System data	•			
		n + 14 to n + 15	System data				
	1 - 8 (PLC1 - 8)	n + 16 to n + 17	System data				
Internal monitor		n + 18 to n + 19	Speed [rpm]	2			
Internal monitor		n + 20 to n + 21	Torque [%]				
		n + 22 to n + 23	Torque (+) peak [%]				
		n + 24 to n + 25	Current position [pulse]				
		n + 26 to n + 27	Position command [pulse]				
		n + 28 to n + 29	Position deviation [pulse]				
		n + 30 to n + 31	Servo status				
		n + 32 to n + 33	I/O status				
		n + 34 to n + 35	System data				
		n + 36 to n + 37	System data				
		n + 38 to n + 39	System data				
		n + 40 to n + 41	Point being executed				

Return data: Data stored from AC servo to V series

- *1 "FFH" can be set for the command (n) when Cuty Axis of version 2.50 and later is used.
- *2 When "01H: point table" is set for the device number (n + 1) of the "data write of all axes" command, the version of all connected Cuty Axis units must be unified into earlier than 2.50 or 2.50 and later.
- *3 "Expansion 1" and "expansion 2" settings are valid when Cuty Axis of version 2.50 and later is used.

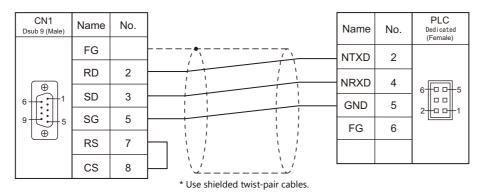
Function	Expansion 1	Expansion 2
None	00	0000
Jump setting for input condition	01	Jump destination Point number: 0000 to 0007
Loop setting	Number of loops: 02 to 64	Operation end: 0063 Point number (single block function): 0064 to 0071
Torque setting	FF	Torque setting value [%]: 0001 to 0120
Loop counter clear	7F	Counter number to be cleared: 0000 to 0007

5.1.2 Wiring Diagrams

When Connected at CN1:

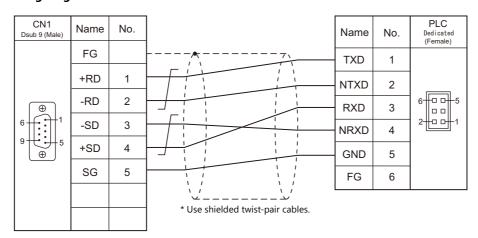
RS-232C

Wiring diagram 1 - C2



RS-422/RS-485

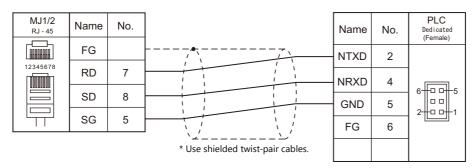
Wiring diagram 1 - C4



When Connected at MJ1/MJ2:

RS-232C

Wiring diagram 1 - M2



6. SHARP

- 6.1 PLC Connection
- 6.2 Temperature Controller/Servo/Inverter Connection

6.1 PLC Connection

Serial Connection

PLC Selection	CPU		Unit/Port	Signal Level	Conn	ection	Ladder
on the Editor		CFU	Unit/Purt	Signal Level	CN1	MJ1/MJ2	Transfer *1
	W70H, W100H JW50, JW70, JW100 JW50H, JW70H, JW100H JW-50CU		JW-10CM ZW-10CM	RS-422	Wiring diagram 1 - C4	Wiring diagram 1 - M4	
	JW20, JW2	0H, JW30H	JW-21CM	RS-422	Wiring diagram 1 - C4	Wiring diagram 1 - M4	
		JW-1324K	MMI port	RS-422	Wiring diagram 2 - C4	×	
JW series	JW10	JW-1342K JW-1424K JW-1442K JW-1624K JW-1642K	Communication port	RS-422	Wiring diagram 3 - C4	Wiring diagram 1 - M4	
		JW-32CUH	PG/COMM1 port	RS-422	Wiring diagram 4 - C4	×	
ı		JW-32CUH1 JW-32CUM1		RS-232C	Wiring diagram 1 - C2	Wiring diagram 1 - M2	
	JW30H JW- JW- JW-	JW-33CUH JW-33CUH1 JW-33CUH2 JW-33CUH3	PG/COMM2 port	RS-422	Wiring diagram 4 - C4	×	
	J-board	Z-331J Z-332J	Host communication port T1	RS-422	Wiring diagram 3 - C4	Wiring diagram 1 - M4	
	JW70	JW-70CU	Communication port	RS-232C	Wiring diagram 2 - C2	Wiring diagram 2 - M2	
JW100/70H	JW100	JW-100CU	Communication port	RS-422	Wiring diagram 5 - C4	×	
COM port	JW70H	JW-70CUH	- Communication port	RS-232C	Wiring diagram 2 - C2	Wiring diagram 2 - M2	
	JW100H	JW-100CUH	Communication port	RS-422	Wiring diagram 6 - C4	×	×
	JW20H	JW-22CU	Communication port	RS-232C	Wiring diagram 2 - C2	Wiring diagram 2 - M2	
	JVVZUH	JVV-22C0	Communication port	RS-422	Wiring diagram 5 - C4	×	
		Z-311J	Host communication port CN3	RS-232C	Wiring diagram 3 - C2	Wiring diagram 3 - M2	
JW20 COM port	J-board	Z-312J	Host communication port TC1	RS-422	Wiring diagram 7 - C4	×	
	J-board	Z-511J	PG/COMM1 port PG/COMM2 port	- RS-422	Wiring diagram 4 - C4	×	
		Z-512J	PG/COMM1 port PG/COMM2 port	113-422	Willing diagram 4 - C4		
			PG/COMM1 port	RS-232C	Wiring diagram 4 - C2	Wiring diagram 4 - M2	
		JW-311CU JW-312CU	FG/COMMIT PORT	RS-422	Wiring diagram 4 - C4	×	
			JW-21CM *2	RS-422	Wiring diagram 1 - C4	Wiring diagram 1 - M4	
		JW-321CU	DC (COMMA) a set	RS-232C	Wiring diagram 4 - C2	Wiring diagram 4 - M2	
JW300 series	JW300	JW-322CU JW-331CU	PG/COMM1 port	RS-422	Wiring diagram 4 - C4	×	
		JW-332CU	DC/COMM2 port	RS-232C	Wiring diagram 1 - C2	Wiring diagram 1 - M2	1
		JW-341CU JW-342CU	PG/COMM2 port	RS-422	Wiring diagram 4 - C4	×	
			JW-21CM *2	RS-422	Wiring diagram 1 - C4	Wiring diagram 1 - M4	

^{*1} For the ladder transfer function, see the V9 Series Reference Manual.

^{*2} When using this unit with JW300, be sure to use one of the JW300-compatible type. The JW300-compatible unit has a 300 mark on its

Ethernet Connection

PLC Selection on the Editor	CPU		Unit	TCP/IP	UDP/IP	Port No.	Keep Alive *1	Ladder Transfer *2
	JW20H		JW-255CM					
	JW30H		JW-25TCM					
JW series (Ethernet) JW50H JW70H JW100H		JW-50CM JW-51CM						
	J-board		Z-339J					
JW311/312/321/322 series		JW-311CU	JW-255CM *3	×	0	1001 to 65534	0	×
(Ethernet)	JW300	JW-312CU JW-321CU JW-322CU	JW-25TCM *3	^				
		JW-331CU JW-332CU	JW-255CM *3					
JW331/332/341/342/352/362 series (Ethernet)	JW-332CU JW-341CU JW-342CU JW-352CU JW-362CU		JW-25TCM *3					

For KeepAlive functions, see "1.3.2 Ethernet Communication".
 For the ladder transfer function, see the V9 Series Reference Manual.
 When using with JW300, be sure to use a JW300-compatible type. A JW300-compatible unit has a 300 mark on its front.

6.1.1 **JW Series**

Communication Setting

Editor

Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1:1/1:n/Multi-link2/Multi-link2(Ethernet)/ 1:n Multi-link2(Ethernet)	
Signal Level	RS-232C / <u>RS-422/485</u>	
Baud Rate	4800 / 9600 / <u>19200</u> / 38400 / 57600 / 115K bps	
Data Length	<u>7</u> / 8 bits	
Stop Bit	<u>1</u> / 2 bits	
Parity	None / Odd / <u>Even</u>	
Target Port No.	0 to 31	

For JW10 series with MMI port or communication port, turn off the terminating resistances of the V series.
 The following switches must be turned off.
 CN1: DIP switches 5 and 7
 MJ1: DIP switch 6
 MJ2: DIP switch 8

PLC

Be sure to match the settings to those made under [Communication Setting] of the editor.

JW-10CM, ZW-10CM, JW-21CM Unit

Switch setting

Swit	ch	Setting			
SW	0	Computer link (command mode)	4		
SW	1	Station address	1		
SW	2	Set the number from 01 to 37 in octal notation. SW1 denotes the lower-order digit, and SW2 denotes the higher-order digit.* * Do not set 00, 08, 09, 18, 19, 28, 29 and 40 or greater. When any of these numbers is set, an error will occur.	0		
	1	Not used	OFF		
SW3	2	Communication system (ON: 4-wire system, OFF: 2-wire system)	ON		
3003	3	Not used	OFF		
	4	ON			
SW	4	Baud rate 0:19200, 1: 9600, 2: 4800	0		
SW	7	Terminating resistance (ON: provided, OFF: not provided)	ON		

^{*} The following settings are fixed; data length: 7 bits, and stop bit: 2 bits.

Z-331J, Z-332J

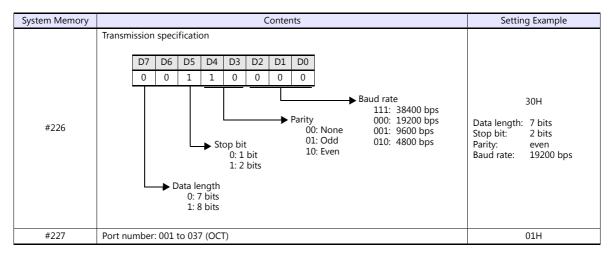
Swit	Switch Contents						
SW	0	Command mode	4				
SW	1	Station address	1				
SW	2	Set the number from 01 to 37 in octal notation. SW1 denotes the lower-order digit, and SW2 denotes the higher-order digit.* * Do not set 00, 08, 09, 18, 19, 28, 29 and 40 or greater. When any of these numbers is set, an error will occur.	0				
	1	Not used	OFF				
SW3	2	Communication system (ON: 4-wire system, OFF: 2-wire system)	OFF				
3003	3	Not used	OFF				
	4	ON					
SW	4	Baud rate 0: 19200, 1: 9600, 2: 4800	0				
SW	7	Terminating resistance (ON: provided, OFF: not provided)	ON				

^{*} The following settings are fixed; data length: 7 bits, and stop bit: 2 bits.

JW-10

The settings for communications with the V9 series should be made at the system memory as shown below.

MMI port



^{*} With the MMI port, only 1:1 or multi-link2 communication is available.

Communication port

System Memory						C	Conte	nts		Settin	g Example	
#234	Communio	Communication mode: computer link mode									00H	
	_	Transmission specification										
	D'	7 D6	D5	D4	D3	D2	D1	D0				
	0	0	1	1	0	0	0	0				
#236		—• □			op bit 0: 1 1: 2	bit	→	01	Baud rate 111: 38400 bps 000: 19200 bps 1: None 1: Odd 10: 4800 bps 1: Even	Data length: Stop bit: Parity: Baud rate:	30H 7 bits 2 bits even 19200 bps	
#237	Port numb	er: 001	to 037	7 (OC	Γ)						01H	

JW-30H

PG/COMM1 port

System Memory	Contents	Setting Example
#234	Transmission specification D7	30H Data length: 7 bits (fixed) Stop bit: 2 bits Parity: even Baud rate: 19200 bps
#235	Port number: 001 to 037 (OCT)	01H

^{*1} Not available for JW-32CUH and JW-33CUH

PG/COMM2 port

System Memory					C	onter	nts		Settin	g Example
	Transmission spe	cificatio	on							
	D7 D6	D5	D4	D3	D2	D1	D0			
	0 0	1	1	0	0	0	0			2011
#236			→ Sto	op bit 0: 1 1: 2	bit	→	01	110: 57600 bps*1		7 bits (fixed) 2 bits even 19200 bps
#237	Port number: 001	. to 037	7 (OC	Γ)						01H

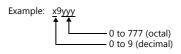
^{*1} Not available for JW-32CUH and JW-33CUH

Available Device Memory

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

	Device Memory	TYPE	Remarks
R	(register)	00H	*1, *2
Relay	(relay)	01H	☐ for word device *1
Е	(self diagnosis)	02H	*1
b	(timer, counter/current value)	03H	*1
Fn	(file register)	07H	*1, *3

- *1 The addresses are expressed in "bytes". For word designation, specify an even-numbered address.
- *2 The assigned device memory is expressed as shown on the right when editing the



*3 The file number is required in addition to the device type and address. The assigned device memory is expressed as shown on the right when editing the screen.



Indirect Device Memory Designation

• For R device memory "x9yyy":

Specify the value "x" (0 to 9: decimal) for higher bytes (bit 15 to 8). Specify a value obtained by dividing "yyy" (000 to 777: octal) by 2 for lower bytes (bit 7 to 0).

Example: With indirect device memory designation, "086D" (H) is assigned for "R89332".

89 (ignoring the lower digit of "9") \rightarrow 8 (DEC) \rightarrow 08 (HEX) 332 (OCT) \rightarrow 218 (DEC) / 2 = 109 (DEC) \rightarrow 6D (HEX)

• For Fn device memory :

Specify the file number in the expansion code.

• For a device memory other than "R" or "Fn":

Example: With indirect device memory designation, "01BF" (H) is assigned for " 1576".

1576 (OCT) \rightarrow 894 (DEC) / 2 = 447 (DEC) \rightarrow 01BF (HEX)

6.1.2 JW100/70H COM Port

Communication Setting

Editor

Communication setting

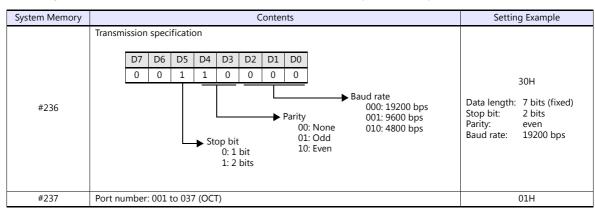
Item	Setting	Remarks
Connection Mode	1:1/1:n/Multi-link2/Multi-link2(Ethernet)/ 1:n Multi-link2(Ethernet)	
Signal Level	RS-232C / <u>RS-422/485</u>	
Baud Rate	4800 / 9600 / <u>19200</u> bps	
Data Length	7 bits	
Stop Bit	1 / <u>2</u> bits	
Parity	None / Odd / Even	
Target Port No.	0 to 31	

PLC

Be sure to match the settings to those made under [Communication Setting] of the editor.

JW-70CU/JW-100CU, JW-70CUH/JW-100CUH

The settings for communications with the V9 series should be made at the system memory as shown below.

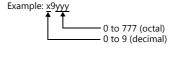


Available Device Memory

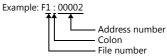
The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

	Device Memory	TYPE	Remarks
R	(register)	00H	*1, *2
Relay	(relay)	01H	☐ for word device *1
E	(self diagnosis)	02H	*1
b	(timer, counter/current value)	03H	*1
Fn	(file register)	07H	*1, *3

- *1 The addresses are expressed in "bytes". For word designation, specify an even-numbered address.
- *2 The assigned device memory is expressed as shown on the right when editing the



*3 The file number is required in addition to the device type and address. The assigned device memory is expressed as shown on the right when editing the screen.



Indirect Device Memory Designation

• For R device memory "x9yyy": Specify the value "x" (0 to 9: decimal) for higher bytes (bit 15 to 8). Specify a value obtained by dividing "yyy" (000 to 777: octal) by 2 for lower bytes (bit 7 to 0).

Example: With indirect device memory designation, "086D" is assigned for "R89332".

89 (ignoring the lower digit of "9") \rightarrow 8 (DEC) \rightarrow 08 (HEX) 332 (OCT) \rightarrow 218 (DEC) / 2 = 109 (DEC) \rightarrow 6D (HEX)

• For Fn device memory : Specify the file number in the expansion code.

• For a device memory other than "R" or "Fn":

Example: With indirect device memory designation, "01BF" is assigned for "\$\square\$ 1576".

1576 (OCT) \rightarrow 894 (DEC) / 2 = 447 (DEC) \rightarrow 01BF (HEX)

6.1.3 JW20 COM Port

Communication Setting

Editor

Communication setting

Item	Setting	Remarks
Connection Mode	1:1/1:n/Multi-link2/Multi-link2(Ethernet)/ 1:n Multi-link2(Ethernet)	
Signal Level	RS-232C / <u>RS-422/485</u>	
Baud Rate	4800 / 9600 / <u>19200</u> bps	
Data Length	7 bits	
Stop Bit	1 / <u>2</u> bits	
Parity	None / Odd / <u>Even</u>	
Target Port No.	0 to 31	

PLC

Be sure to match the settings to those made under [Communication Setting] of the editor.

JW-22CU, Z-311J, Z-312J

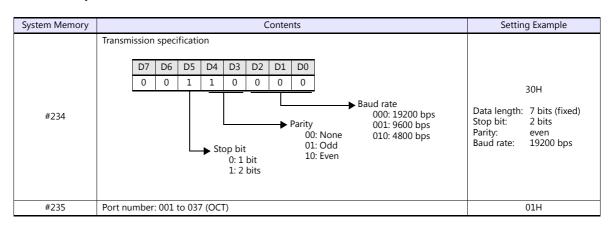
The settings for communications with the V9 series should be made at the system memory as shown below.

System Memory			Settin	g Example							
#236	Transmissio D7 0	D6	D5	D4 1	D3 0	D2 0	D1 0	D0 0	—— → Baud rate 000: 19200 bps 001: 9600 bps	Data length: Stop bit:	30H 7 bits (fixed) 2 bits
#227	Do et avendo	w 001	10.03		op bit 0: 1 1: 2	bit		01	: None 010: 4800 bps : Odd : Even	Parity: Baud rate:	even 19200 bps
#237	Port numbe	r: 001	to 03.	/ (UC	I)						01H

^{*} The terminating resistance switch (SW1) is provided at the back of the JW-22CU board. Turn this switch off for RS-232C connection.

Z-511J, Z-512J

PG/COMM1 port



PG/COMM2 port

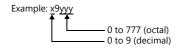
System Memory			Settin	g Example						
#236	Transmission spe		D4 1	D3 0 op bit 0: 1	D2 0	D1 0	D0 0 Parity 00 01	Baud rate 000: 19200 bps 001: 9600 bps 1 None 010: 4800 bps 1 Odd 1 Even		30H 7 bits (fixed) 2 bits even 19200 bps
#237	1: 2 bits #237 Port number: 001 to 037 (OCT)							01H		

Available Device Memory

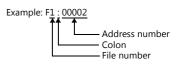
The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

	Device Memory	TYPE	Remarks
R	(register)	00H	*1, *2
Relay	(relay)	01H	☐ for word device *1
E	(self diagnosis)	02H	*1
b	(timer, counter/current value)	03H	*1
Fn	(file register)	07H	*1, *3

- *1 The addresses are expressed in "bytes". For word designation, specify an even-numbered address.
- *2 The assigned device memory is expressed as shown on the right when editing the screen.



*3 The file number is required in addition to the device type and address. The assigned device memory is expressed as shown on the right when editing the screen.



Indirect Device Memory Designation

• For R device memory "x9yyy": Specify the value "x" (0 to 9: decimal) for higher bytes (bit 15 to 8). Specify a value obtained by dividing "yyy" (000 to 777: octal) by 2 for lower bytes (bit 7 to 0).

Example: With indirect device memory designation, "086D" is assigned for "R89332". 89 (ignoring the lower digit of "9") \rightarrow 8 (DEC) \rightarrow 08 (HEX)

332 (OCT) \rightarrow 218 (DEC) / 2 = 109 (DEC) \rightarrow 6D (HEX)

- For Fn device memory: Specify the file number in the expansion code.
- For a device memory other than "R" or "Fn":
 Example: With indirect device memory designation, "01BF" is assigned for "☐ 1576".
 1576 (OCT) → 894 (DEC) / 2 = 447 (DEC) → 01BF (HEX)

6.1.4 JW300 Series

Communication Setting

Editor

Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1:1/1:n/Multi-link2/Multi-link2(Ethernet)/ 1:n/Multi-link2(Ethernet)	
Signal Level	RS-232C / <u>RS-422/485</u>	
Baud Rate	4800 / 9600 / 19200 / 38400 / <u>115K</u> bps	
Data Length	<u>7</u> / 8 bits	
Stop Bit	1 / <u>2</u> bits	
Parity	None / <u>Odd</u> / Even	
Target Port No.	0 to 31	
Transmission Mode	<u>2-wire</u> / 4-wire	Multi-link connection is not available in the 4-wire mode.

PLC

Be sure to match the settings to those made under [Communication Setting] of the editor.

PG/COMM 1 Port, PG/COMM 2 Port

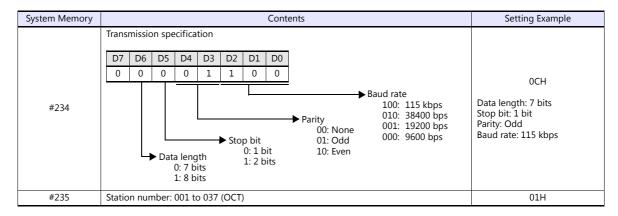
Make PLC communication settings by using the application software "JW300SP" or writing the setting values directly into the system memory. For more information, refer to the PLC manual issued by the manufacturer.

JW300SP

	Item	Setting	Remarks
	Baud Rate		
	Parity	None / Odd / Even	
Port 1 Port 2	Stop Bit	1/2	
	Station number	0 to 37 (OCT)	
	Data Length	7 bits / 8 bits	

System memory

PG/COMM 1 port



PG/COMM 2 port

System Memory				Setting Example					
#236	Transmiss D7 D6 0 0		D4 0	D3 1		D1 0 p bit 0: 1 b 1: 2 b		■ Baud rate 100: 115 kbps 010: 38400 bps 00: None 01: Odd 10: Even ■ Baud rate 100: 115 kbps 010: 38400 bps 001: 9600 bps	OCH Data length: 7 bits Stop bit: 1 bit Parity: Odd Baud rate: 115 kbps
#237	Station nu	ımber:	0: 7 b 1: 8 b	01H					

JW-21CM Unit

Switch setting

Sw	itch	Contents	Setting
SI	W 0	Computer link (command mode)	4
SI	W1	Station address	1
S\	N2	Set the number from 01 to 37 in octal notation. SW1 denotes the lower-order digit, and SW2 denotes the higher-order digit. Do not set 00, 08, 09, 18, 19, 28, 29 and 40 or greater. When any of these number is set, an error occurs.	0
	1	Not used	OFF
SW3	2	Communication system (ON: 4-wire / OFF: 2-wire)	ON
3003	3	Not used	OFF
	4	Parity (ON: Even / OFF: Odd)	ON
SI	N4	Baud rate 0: 19200, 1: 9600, 2: 4800	0
SI	N7	Terminating resistance (ON: Provided / OFF: Not provided)	ON

^{*} The following settings are fixed; data length: 7 bits, and stop bit: 2 bits.

Available Device Memory

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

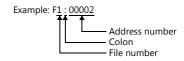
	Device Memory	TYPE	Remarks
R	(register)	00H	*1, *2
Relay	(relay)	01H	☐ for word device *1
Е	(self diagnosis)	02H	*1
b	(timer, counter/current value)	03H	*1
Fn	(file register)	07H	*1, *3

*1 The addresses are expressed in "bytes". For word designation, specify an even-numbered address.

*2 The assigned device memory is expressed as shown on the right when editing the screen.

Example: xx9yyy 0 to 777 (octal) 0 to 38 (decimal)

*3 The file number is required in addition to the device type and address. The assigned device memory is expressed as shown on the right when editing the screen.



Indirect Device Memory Designation

• For R device memory "xx9yyy":

Specify the value "xx" (00 to 38: decimal) for higher bytes (bit 15 to 8). Specify a value obtained by dividing "yyy" (000 to 777: octal) by 2 for lower bytes (bit 7 to 0).

Example: With indirect device memory designation, "086D" is assigned for "R89332".

089 (ignoring the lower digit of "9") \to 08 (DEC) \to 08 (HEX) 332 (OCT) \to 218 (DEC) / 2 = 109 (DEC) \to 6D (HEX)

• For Fn device memory: Specify the file number in the expansion code.

• For a device memory other than "R" or "Fn":

Example: With indirect device memory designation, "01BF" is assigned for " 1576".

1576 (OCT) \rightarrow 894 (DEC) / 2 = 447 (DEC) \rightarrow 01BF (HEX)

6.1.5 JW Series (Ethernet)

Communication Setting

Editor

Make the following settings on the editor. For more information, see "1.3.2 Ethernet Communication".

- IP address for the V9 unit
 - When specified on the screen program:
 - $[\mathsf{System}\ \mathsf{Setting}] \to [\mathsf{Hardware}\ \mathsf{Setting}] \to [\mathsf{Local}\ \mathsf{Port}\ \mathsf{IP}\ \mathsf{Address}]$
 - When specified on the V9 unit: Local mode → [LAN Setting]
- Port number for the V9 unit (for communication with PLC)
 [System Setting] → [Hardware Setting] → [PLC Properties] → [Communication Setting]
- IP address and port number of the PLC
 Register on the [PLC Table] in [System Setting] → [Hardware Setting] → [PLC Properties] → [Target Settings].

PLC

JW-255CM, JW-25TCM

Make PLC communication settings by using the application software or entering the setting values directly into the network parameter.

For more information, refer to the PLC manual issued by the manufacturer.

JW300SP (JW25TCM/255CM parameter settings)

	Item	Setting	Remarks
IP Address Setting		Set the IP address of the PLC.	
IF Address Setting	Subnet Mask	Set the subnet mask of the PLC.	
Connection Setting	Open Method	UDP	
Connection Setting	Local Port No.	Set the port number of the PLC.	

Network parameter

Parameter Address	Contents	Setting Example
0000 to 0003	IP address at local port (DEC)	IP address: 192.168.1.1 0000: 192 0001: 168 0002: 1 0003: 1
0004 to 0007	Subnet mask (DEC)	Subnet mask: 255.255.255.0 0004: 255 0005: 255 0006: 255 0007: 0
0100 to 0103	Connection 0 setting 0100: Open method 01: UDP 0101: Fixed to 0 0102: Local port number (lower byte (HEX)) 0103: Local port number (higher byte (HEX))	UDP connection, port number 3000 (= BB8H) 0100: 01H 0101: 00H 0102: B8H 0103: 0BH
0104 to 0107	Connection 1 setting (same as connection 0)	
0110 to 0113	Connection 2 setting (same as connection 0)	
0114 to 0117	Connection 3 setting (same as connection 0)	
0120 to 0123	Connection 4 setting (same as connection 0)	
0124 to 0127	Connection 5 setting (same as connection 0)	
0130 to 0133	Connection 6 setting (same as connection 0)	
0134 to 0137	Connection 7 setting (same as connection 0)	
3777 *	Communication start switch 00H: Communication stop 01H: Parameter check, BCC check, communication start 81H: Parameter check, BCC creation, writing into EEPROM, communication start (changed to 01H after the start of communication)	

^{*} Communication must be stopped before entering values into the network parameter to make the communication setting. Specify 00H at parameter address 3777 at first, and set the IP address, etc. After settings are made, specify 81H at parameter address 3777. Then settings will be written into EEPROM and communication will start.

JW-50CM, JW-51CM

Make PLC communication settings by using the application software or entering the setting values directly into the network parameter.

For more information, refer to the PLC manual issued by the manufacturer.

JW300SP (parameter settings)

Item		Setting	Remarks
IP Address Setting	IP Address	Set the IP address of the PLC.	
ir Address Setting	Subnet Mask	Set the subnet mask of the PLC.	
Connection Setting	Open Method	UDP	
Connection Setting	Local Port No.	Set the port number of the PLC.	

Network parameter

Parameter Address	Contents	Setting Example
0000 to 0003	IP address at local port (DEC)	IP address: 192.168.1.1 0000: 192 0001: 168 0002: 1 0003: 1
0004 to 0007	Subnet mask (DEC)	Subnet mask: 255.255.255.0 0004: 255 0005: 255 0006: 255 0007: 0
0100 to 0103	Connection 0 setting 0100: Open method 01: UDP 0101: Fixed to 0 0102: Local port number (lower byte (HEX)) 0103: Local port number (higher byte (HEX))	UDP connection, port number 3000 (= BB8H) 0100: 01H 0101: 00H 0102: B8H 0103: 0BH
0104 to 0107	Connection 1 setting (same as connection 0)	
0110 to 0113	Connection 2 setting (same as connection 0)	
0114 to 0117	Connection 3 setting (same as connection 0)	
0120 to 0123	Connection 4 setting (same as connection 0)	
0124 to 0127	Connection 5 setting (same as connection 0)	
0130 to 0133	Connection 6 setting (same as connection 0)	
0134 to 0137	Connection 7 setting (same as connection 0)	
3777 *	Communication start switch 00H: Communication stop 01H: Parameter check, BCC check, communication start 81H: Parameter check, BCC creation, writing into EEPROM, communication start (changed to 01H after the start of communication)	

^{*} Communication must be stopped before entering values into the network parameter to make the communication setting. Specify 00H at parameter address 3777 at first, and set the IP address, etc. After settings are made, specify 81H at parameter address 3777. Then settings will be written into EEPROM and communication will start.

Z-339J

12-VDC Power Input

10BASE5 or 10BASE-T is selected according to the input status of the 12-VDC power supply.

Item		Contents		
12-VDC power input	Provided	10BASE5 communication		
12-VDC power input	Not provided	10BASE-T communication		

Network parameter

Parameter Address	Contents	Setting Example
0000 to 0003	IP address at local port (DEC)	IP address: 192.168.1.1 0000: 192 0001: 168 0002: 1 0003: 1
0004 to 0007	Subnet mask (DEC)	Subnet mask: 255.255.255.0 0004: 255 0005: 255 0006: 255 0007: 0
0100 to 0103	Connection 0 setting 0100: Open method 01: UDP 0101: Fixed to 0 0102: Local port number (lower byte (HEX)) 0103: Local port number (higher byte (HEX))	UDP connection, port number 3000 (= BB8H) 0100: 01H 0101: 00H 0102: B8H 0103: 0BH
0104 to 0107	Connection 1 setting (same as connection 0)	
0110 to 0113	Connection 2 setting (same as connection 0)	
0114 to 0117	Connection 3 setting (same as connection 0)	
0120 to 0123	Connection 4 setting (same as connection 0)	
0124 to 0127	Connection 5 setting (same as connection 0)	
0130 to 0133	Connection 6 setting (same as connection 0)	
0134 to 0137	Connection 7 setting (same as connection 0)	
3777 *	Communication start switch 00H: Communication stop 01H: Parameter check, BCC check, communication start 81H: Parameter check, BCC creation, writing into EEPROM, communication start (changed to 01H after the start of communication)	

* Communication must be stopped before entering values into the network parameter to make the communication setting. Specify 00H at parameter address 3777 at first, and set the IP address, etc.

After settings are made, specify 81H at parameter address 3777. Then settings will be written into EEPROM and communication will start.

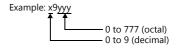
Available Device Memory

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

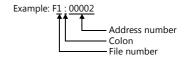
	Device Memory	TYPE	Remarks
R	(register)	00H	*1, *2
Relay	(relay)	01H	☐ for word device *1
E	(self diagnosis)	02H	*1
b	(timer, counter/current value)	03H	*1
Fn	(file register)	07H	*1, *3

*1 The addresses are expressed in "bytes". For word designation, specify an even-numbered address.

2 The assigned device memory is expressed as shown on the right when editing the screen.



*3 The file number is required in addition to the device type and address. The assigned device memory is expressed as shown on the right when editing the screen.



Indirect Device Memory Designation

• For R device memory "x9yyy":

Specify the value "x" (0 to 9: decimal) for higher bytes (bit 15 to 8). Specify a value obtained by dividing "yyy" (000 to 777: octal) by 2 for lower bytes (bit 7 to 0).

Example: With indirect device memory designation, "086D" is assigned for "R89332".

89 (ignoring the lower digit of "9") \rightarrow 8 (DEC) \rightarrow 08 (HEX) 332 (OCT) \rightarrow 218 (DEC) / 2 = 109 (DEC) \rightarrow 6D (HEX)

• For Fn device memory: Specify the file number in the expansion code.

• For a device memory other than "R" or "Fn":

Example: With indirect device memory designation, "01BF" is assigned for " 1576".

1576 (OCT) \rightarrow 894 (DEC) / 2 = 447 (DEC) \rightarrow 01BF (HEX)

6.1.6 JW311/312/321/322 Series (Ethernet)

Communication Setting

Editor

Make the following settings on the editor. For more information, see "1.3.2 Ethernet Communication".

- IP address for the V9 unit
 - When specified on the screen program:
 [System Setting] → [Hardware Setting] → [Local Port IP Address]
 - When specified on the V9 unit: Local mode → [LAN Setting]
- Port number for the V9 unit (for communication with PLC)
 [System Setting] → [Hardware Setting] → [PLC Properties] → [Communication Setting]
- IP address and port number of the PLC
 Register on the [PLC Table] in [System Setting] → [Hardware Setting] → [PLC Properties] → [Target Settings].

PLC

JW-255CM, JW-25TCM

Make PLC communication settings by using the application software or entering the setting values directly into the network parameter.

For more information, refer to the PLC manual issued by the manufacturer.

JW300SP (JW25TCM/255CM parameter settings)

Item		Setting	Remarks
IP Address Setting	IP Address	Set the IP address of the PLC.	
ir Address Setting	Subnet Mask	Set the subnet mask of the PLC.	
Connection Setting	Open Method	UDP	
Connection Setting	Local Port No.	Set the port number of the PLC.	

Network parameter

Parameter Address	Contents	Setting Example
0000 to 0003	IP address at local port (DEC)	IP address: 192.168.1.1 0000: 192 0001: 168 0002: 1 0003: 1
0004 to 0007	Subnet mask (DEC)	Subnet mask: 255.255.255.0 0004: 255 0005: 255 0006: 255 0007: 0
0100 to 0103	Connection 0 setting 0100: Open method 01: UDP 0101: Fixed to 0 0102: Local port number (lower byte (HEX)) 0103: Local port number (higher byte (HEX))	UDP connection, port number 3000 (= BB8H) 0100: 01H 0101: 00H 0102: B8H 0103: 0BH
0104 to 0107	Connection 1 setting (same as connection 0)	
0110 to 0113	Connection 2 setting (same as connection 0)	
0114 to 0117	Connection 3 setting (same as connection 0)	
0120 to 0123	Connection 4 setting (same as connection 0)	
0124 to 0127	Connection 5 setting (same as connection 0)	
0130 to 0133	Connection 6 setting (same as connection 0)	
0134 to 0137	Connection 7 setting (same as connection 0)	
3777 *	Communication start switch 00H: Communication stop 01H: Parameter check, BCC check, communication start 81H: Parameter check, BCC creation, writing into EEPROM, communication start (changed to 01H after the start of communication)	

^{*} Communication must be stopped before entering values into the network parameter to make the communication setting. Specify 00H at parameter address 3777 at first, and set the IP address, etc. After settings are made, specify 81H at parameter address 3777. Then settings will be written into EEPROM and communication will start.

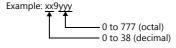
Available Device Memory

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

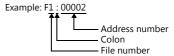
	Device Memory	TYPE	Remarks
R	(register)	00H	*1, *2
Relay	(relay)	01H	☐ for word device *1
E	(self diagnosis)	02H	*1
b	(timer, counter/current value)	03H	*1
Fn	(file register)	07H	*1, *3

*1 The addresses are expressed in "bytes". For word designation, specify an even-numbered address.

*2 The assigned device memory is expressed as shown on the right when editing the



*3 The file number is required in addition to the device type and address. The assigned device memory is expressed as shown on the right when editing the screen.



Indirect Device Memory Designation

• For R device memory "xx9yyy":

Specify the value "xx" (0 to 38: decimal) for higher bytes (bit 15 to 8). Specify a value obtained by dividing "yyy" (000 to 777: octal) by 2 for lower bytes (bit 7 to 0).

Example: With indirect device memory designation, "086D" is assigned for "R89332".

089 (ignoring the lower digit of "9") \to 08 (DEC) \to 08 (HEX) 332 (OCT) \to 218 (DEC) / 2 = 109 (DEC) \to 6D (HEX)

• For Fn device memory:

Specify the file number in the expansion code.

• For a device memory other than "R" or "Fn":

Example: With indirect device memory designation, "01BF" is assigned for "\$\square\$ 1576".

1576 (OCT) \rightarrow 894 (DEC) / 2 = 447 (DEC) \rightarrow 01BF (HEX)

6.1.7 JW331/332/341/342/352/362 Series (Ethernet)

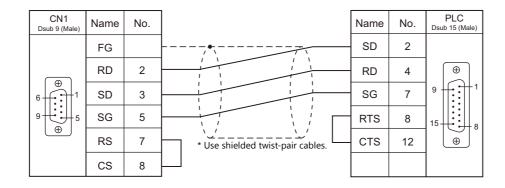
Settings are the same as those described in "6.1.6 JW311/312/321/322 Series (Ethernet)".

6.1.8 Wiring Diagrams

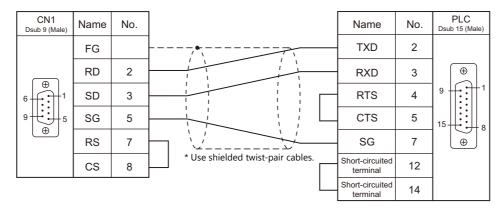
When Connected at CN1:

RS-232C

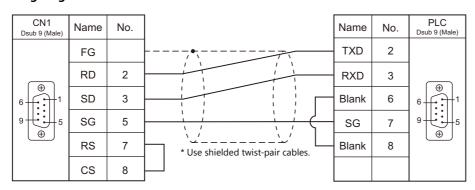
Wiring diagram 1 - C2



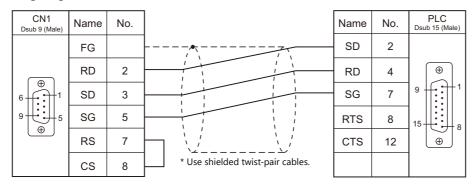
Wiring diagram 2 - C2



Wiring diagram 3 - C2

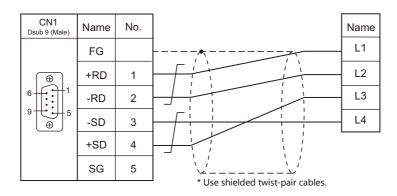


Wiring diagram 4 - C2

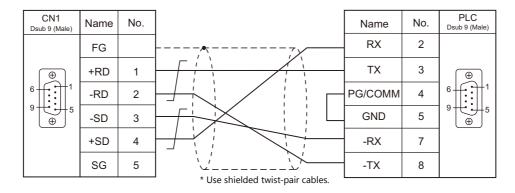


RS-422/RS-485

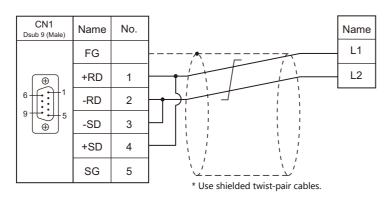
Wiring diagram 1 - C4



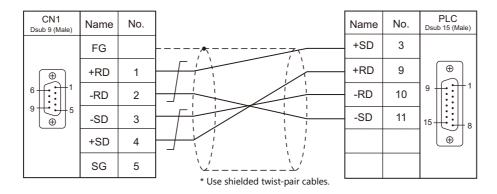
Wiring diagram 2 - C4



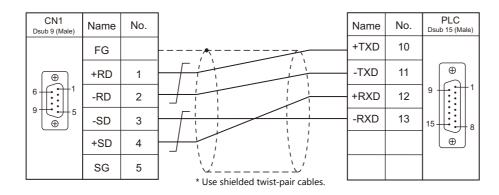
Wiring diagram 3 - C4



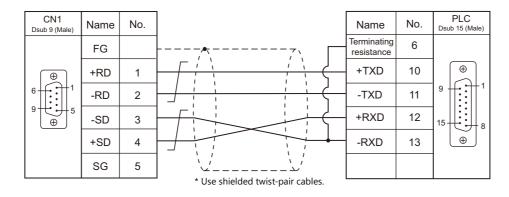
Wiring diagram 4 - C4



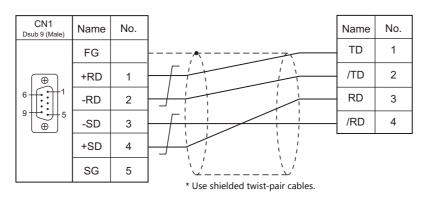
Wiring diagram 5 - C4



Wiring diagram 6 - C4



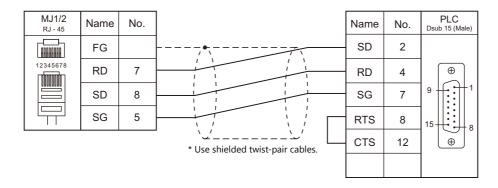
Wiring diagram 7 - C4



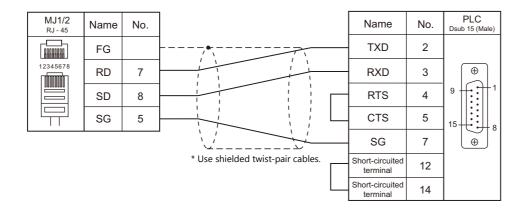
When Connected at MJ1/MJ2:

RS-232C

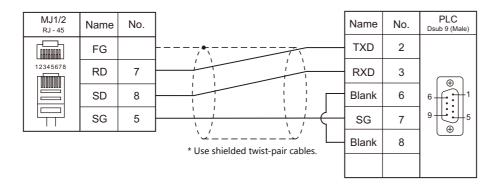
Wiring diagram 1 - M2



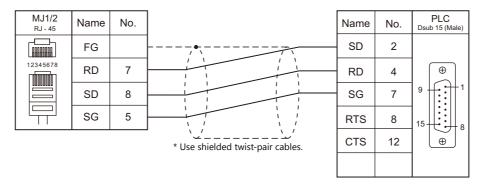
Wiring diagram 2 - M2



Wiring diagram 3 - M2

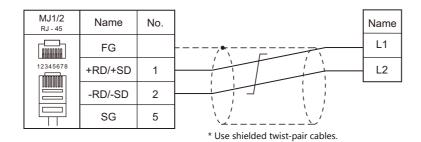


Wiring diagram 4 - M2



RS-422/RS-485

Wiring diagram 1 - M4



6.2 Temperature Controller/Servo/Inverter Connection

ID Controller

PLC Selection on the	Model	Port	Signal Level	Conn	Lst File	
Editor	iviouei	Port Signal Level		CN1		MJ1/MJ2
		Terminal block	RS-232C	Wiring diagram 1 - C2	Wiring diagram 1 - M2	
		Terrifical block	RS-422	Wiring diagram 1 - C4	Wiring diagram 1 - M4	
DS-30D	DS-30D	DS-30D Connector for host/peripheral equipment	RS-232C	Wiring diagram 2 - C2	Wiring diagram 2 - M2	SH-DS30D.Lst
			RS-422	Wiring diagram 2 - C4	×	
		Host communication port 1	RS-232C	Wiring diagram 1 - C2	Wiring diagram 1 - M2	
DS-32D	DS-32D Host communication port 2	RS-422	Wiring diagram 1 - C4	Wiring diagram 1 - M4	SH-DS32D.Lst	
		MMI port	RS-232C	Wiring diagram 2 - C2	Wiring diagram 2 - M2	

6.2.1 DS-30D

Communication Setting

Editor

Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1:1/1:n/Multi-link2/Multi-link2(Ethernet)/ 1:n Multi-link2(Ethernet)	
Signal Level	RS-232C / RS-422/485	
Baud Rate	4800 / <u>9600</u> / 19200 bps	
Data Length	<u>7</u> / 8 bits	
Stop Bit	<u>1</u> / 2 bits	
Parity	None / Odd / Even	
Target Port No.	<u>0</u> to 15	

RFID System

Switch Setting

(Underlined setting: default)

Communication setting

SW1	Function	OFF		ON		Setting Example
1	Data length	7		8		
2	Parity	<u>None</u>		Provided		
3	Failty	<u>Even</u>		Odd		0(1)1
4	Stop bit	<u>1</u>			2	F 2
5	Connector type	Using the host only		Using the host and hand-held programmer (e.g. JW-12PG) at one time		3 4 5
6	Communication	RS-232C	RS-232C RS-4 (4-wire s		RS-485 (2-wire system)	6
7	system (wiring type)	<u>OFF</u>	10	N	OFF	OFF←→ON
		<u>OFF</u> OFF		F	ON	
8	Mode	High speed			Standard	

Station number setting

SW2	Contents	Setting Example
OF O TOP A	<u>Q</u> to F (H) (0 to 15)	0

Baud rate

SW3	Setting	Baud Rate	Setting Example
, o ,	4	4800 bps	
	<u>5</u>	<u>9600 bps</u>	5
- S 4	6	19200 bps	

Terminating resistance

SW4		Setting Example			
0 1	RS-232C	RS-422 (4-wire system)	RS-485 (2-wire system)		1: OFF
F 1 2	OFF	ON	OFF		2: OFF
OFF←→ON	OFF	OFF	ON		
	•				

Communication Mode Setting

Set a communication mode at the system memory. The selected mode becomes effective when the power is turned off and on again.

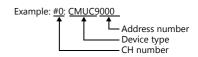
Address	Contents	Setting		
A008	Communication start method	0: At any time required		
A00A	Response transmission method	0: Automatic		

Available Device Memory

The available setting range of device memory varies depending on the model. Be sure to set within the range available for the model to be used. Use [TYPE] when assigning indirect device memory for macro programs.

	Device Memory	TYPE	Remarks
CMUC	(controller memory 1-byte data)	00H	
CMS	(controller memory 2-byte data)	01H	
CMUT	(controller memory 3-byte data)	02H	
CML	(controller memory 4-byte data)	03H	
IMUC	(ID memory 1-byte data)	04H	
IMS	(ID memory 2-byte data)	05H	
IMUT	(ID memory 3-byte data)	06H	
IML	(ID memory 4-byte data)	07H	
ID	(ID code)	08H	Double-word
TM	(time)	09H	

^{*1} The CH number is required in addition to the device type and address. The assigned device memory is expressed as shown on the right when editing the screen.



Indirect Device Memory Designation

Specify the CH number in the expansion code.

PLC_CTL

Macro command "PLC_CTL F0 F1 F2"

Contents	F0		F1 (= \$	u n)	F2	
		n	Station number			
		n + 1	Command: 0			
		n + 2	CH No.			
		n + 3	Attribute (0, 3, A, D)	Attribute (1, 2, 4, 5, B, C, E, F)		
Plate clear	1 - 8 (PLC1 - 8)	n + 4	Address	Address	7/9	
		n + 5	Bytes	Bytes		
		n + 6	Clear data	Designated ID and		
		n + 7	-	Designated ID code		
		n + 8	-	Clear data		
		n	Station number			
		n + 1	Command: 1			
Plate initialize	1 - 8	n + 2	CH No.		4/6	
Flate illitialize	(PLC1 - 8)	n + 3	Attribute (0, 3, A, D)	Attribute (1, 2, 4, 5, B, C, E, F)	4/0	
		n + 4	-	Designated ID code		
		n + 5	-	Designated ID code		
		n	Station number			
		n + 1	Command: 2			
DS-30D clear	1 - 8	n + 2	CH No.		6	
D3-30D Cleal	(PLC1 - 8)	n + 3	Address			
		n + 4	Bytes			
		n + 5	Clear data			
		n	Station number			
DS-30D initialize 1 - 8 (PLC1 - 8)		n + 1	Command: 3		3	
	(1201-0)	n + 2	CH No.			
	1 - 8 (PLC1 - 8)	n	Station number			
		n + 1	Command: 4			
Log clear (communication time,		n + 2	CH No.		4	
number of retrials, error log)		n + 3	Area 0: Communication time log 1: Retry count log 2: Error log	3	4	
		n	Station number			
		n + 1	Command: 5			
		n + 2	CH No.		1	
		n + 3	Attribute (0, 3, A, D)	Attribute (1, 2, 4, 5, B, C, E, F)		
Plate self diagnosis	1 - 8 (PLC1 - 8)	n + 4	Address	Address	6/8	
_	(PLCI - 0)	n + 5	Bytes	Bytes		
		n + 6	Battery use rate	2		
		n + 7	-	Designated ID code		
		n + 8	-	Battery use rate		
		n	Station number			
		n + 1	Command: 6			
2014	1 - 8	n + 2	CH No.			
ROM check	(PLC1 - 8)	n + 3	Attribute (0, 3, A, D)	Attribute (1, 2, 4, 5, B, C, E, F)	4/6	
		n + 4	-			
		n + 5	-	ID code		
		n	Station number	1		
		n + 1	Command: 7		1	
		n + 2	CH No.		1	
BANA 1 1	1 - 8	n + 3	Attribute (0, 3, A, D)	Attribute (1, 2, 4, 5, B, C, E, F)	+	
RAM check	(PLC1 - 8)	n + 4	Address	Address	6/8	
			1	Purtos	1	
		n + 5	Bytes	Bytes		
		n + 5 n + 6	Bytes -	Designated ID code		

	F0		F1 (= \$u	n)	F2
		n	Station number		
		n + 1	Command: 8		
		n + 2	CH No.		
Plate battery service life check	1 - 8 (PLC1 - 8)	n + 3	Attribute (0, 3, A, D)	Attribute (1, 2, 4, 5, B, C, E, F)	4/6
CHECK	(1202 0)	n + 4	Battery use rate	Designated ID code	
		n + 5	-	Designated ID code	
		n + 6	-	Battery use rate	
DS-30D self diagnosis	1 - 8	n	Station number		2
23 302 3cm diagnosis	(PLC1 - 8)	n + 1	Command: 9		_
		n	Station number		
		n + 1	Command: 10		
		n + 2	CH No.		
Block check	1 - 8	n + 3	Attribute (0, 3, A, D)	Attribute (1, 2, 4, 5, B, C, E, F)	6/8
	(PLC1 - 8)	n + 4	Address	Address	., .
		n + 5	Bytes	Bytes	
		n + 6	-	— Designated ID code	
		n + 7	-	3	
		n	Station number		
	1 - 8	n + 1	Command: 11		
Reset	(PLC1 - 8)	n + 2	CH No. 0: CH No. 0 1: CH No. 1 2: Both		3
		n	Station number		
	1 - 8 (PLC1 - 8)	n + 1	Command: 12		
		n + 2	CH No.		
Output command		n + 3	Output 0		
	(1201 0)	n + 4	Output 1		
		n + 5	Output 2		
		n + 6	Output 3		
		n	Station number		
Status read out	1 - 8	n + 1	Command: 13		3
Status read out	(PLC1 - 8)	n + 2	CH No.		3
		n + 3	Status		
		n	Station number		
		n + 1	Command: 14		
DS-30D read out	1 - 8	n + 2	CH No.		6
D3-30D Tead Out	(PLC1 - 8)	n + 3	Address		0
		n + 4	Bytes		
		n + 5	Internal device memory add	ress *1	
		n	Station number		
		n + 1	Command: 15		
DS-30D write	1 - 8	n + 2	CH No.		6
שווופ חוספ-פים wille	(PLC1 - 8)	n + 3	Address		U
		n + 4	Bytes		
		n + 5	Internal device memory add	ress *2	
		n	Station number		
		n + 1	Command: 16		
		n + 2	CH No.		
		n + 3	Attribute (0, 3, A, D)	Attribute (1, 2, 4, 5, B, C, E, F)	
	1 - 8 (PLC1 - 8)	n + 4	Address	Address	
			Bytes	Bytes	7/9
ID memory read out	1 - 8 (PLC1 - 8)	n + 5	Dytes	,	
ID memory read out		n + 5 n + 6	Internal device memory address *1	Designated ID code	
ID memory read out			Internal device memory		

Contents	F0		F1 (= \$u	n)	F2	
		n	Station number			
		n + 1	Command: 17			
		n + 2	CH No.]	
	1 - 8	n + 3	Attribute (0, 3, A, D)	Attribute (1, 2, 4, 5, B, C, E, F)		
		n + 4	Address	Address	7/9	
ID memory write	(PLC1 - 8)	n + 5	Bytes	Bytes		
		n + 6	Internal device memory address *2	Designated ID code		
		n + 7	-			
		n + 8	-	Internal device memory address		
		n	Station number			
		n + 1	Command: 18			
		n + 2	CH No.			
ID code read out	1 - 8	n + 3	Attribute (0, 3, A, D)	Attribute (1, 2, 4, 5, B, C, E, F)	4/6	
ID code read out	(PLC1 - 8)	n + 4	ID code	Designated ID code	4,0	
		n + 5	ID code	Designated ID code		
		n + 6	-	ID code		
		n + 7	-	15 code	<u> </u>	
		n	Station number			
	1 - 8 (PLC1 - 8)	n + 1	Command: 19			
		n + 2	CH No.			
ID code write		n + 3	Attribute (0, 3, A, D)	Attribute (1, 2, 4, 5, B, C, E, F)	6/8	
ID code write		n + 4	n + 4 ID code	Designated ID code		
		n + 5		Designated ID code		
		n + 6	-	ID code		
		n + 7	-	1D Code		
		n	Station number			
		n + 1	Command: 20			
		n + 2	CH No.			
		n + 3	Year		3	
Time read out	1 - 8	n + 4	Month			
Time read out	(PLC1 - 8)	n + 5	Day			
		n + 6	Hour			
		n + 7	Minute			
		n + 8	Second			
		n + 9	A day of the week			
		n	Station number			
		n + 1	Command: 21		-	
		n + 2	CH No.			
		n + 3	Year			
Time correction	1 - 8	n + 4	Month			
	(PLC1 - 8)	n + 5	Day			
		n + 6	Hour			
		n + 7	Minute			
		n + 8	Second			
		n + 9	A day of the week			

Return data: Data stored from servo to V series

 ^{*1} Specify the top address of the internal device memory (\$u) at which the read data is to be stored.
 *2 Specify the top address of the internal device memory (\$u) at which data to be written is stored.

6.2.2 DS-32D

Communication Setting

Editor

Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1:1/1:n/Multi-link2/Multi-link2(Ethernet)/ 1:n Multi-link2(Ethernet)	
Signal Level <u>RS-232C</u> / RS-422/485		
Baud Rate	4800 / 9600 / 19200 / 38400 / 57600 / 76800 / <u>115K</u> bps	
Data Length	7 / <u>8</u> bits	
Stop Bit	<u>1</u> / 2 bits	
Parity	None / Odd / Even	
Target Port No.	<u>0</u> to 15	

^{*1} When RS-422 connection is used via the MMI port, the following settings are fixed; baud rate: 115 kbps, data length: 8 bits, stop bit: 1 bit, and parity: even.

RFID System

Switch Setting

(Underlined setting: default)

Station number setting

SW1	Contents	Setting Example
	<u>0</u> to F (H) (0 to 15)	0

Baud rate

SW2	Setting	Baud Rate	Setting Example
	4	4800 bps	
•	5	9600 bps	
SEF 0 123	6	19200 bps	0
8 1 0 5	7	38400 bps	9
	8	57600 bps	
	9	<u>115 kbps</u>	

Terminating resistance

SW3		Setting Example			
0 1	RS-232C	RS-422 (4-wire system)	RS-485 (2-wire system)		1: OFF
F 2	<u>OFF</u>	ON	OFF		2: OFF
OFF←→ON	<u>OFF</u>	ON	ON		

Communication setting

SW4	Function	OFF		ON	Setting Example
1	Data length 7			<u>8</u>	
2	Parity	None		<u>Provided</u>	- <u>-</u>
3	Parity	<u>Even</u>		Odd	
4	Stop bit	1		2	ω
5		4			
6					σ I
7	Communication system (wiring type)	RS-232C	RS-422 (4-wire system)	RS-485 (2-wire system)	o I
		<u>OFF</u>	ON	OFF	7
		<u>OFF</u>	OFF	ON	8 1 9
8		OFF ←→ ON			
9	Fixed to OFF				

Communication Mode Setting

Set a communication mode at the system memory. The selected mode becomes effective when the power is turned off and on again.

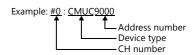
Address	Contents	Setting	
A008	Communication start method	0: At any time required	
A00A	Response transmission method	0: Automatic	
A00F Trigger setting		0: Triggering invalid	

Available Device Memory

The available setting range of device memory varies depending on the model. Be sure to set within the range available for the model to be used. Use [TYPE] when assigning indirect device memory for macro programs.

Device Memory		TYPE	Remarks
CMUC	(controller memory 1-byte data)	00H	
CMS	(controller memory 2-byte data)	01H	
CMUT	(controller memory 3-byte data)	02H	
CML	(controller memory 4-byte data)	03H	
IMUC	(ID memory 1-byte data)	04H	
IMS	(ID memory 2-byte data)	05H	
IMUT	(ID memory 3-byte data)	06H	
IML	(ID memory 4-byte data)	07H	
ID	(ID code)	08H	Double-word
TM	(time)	09H	
RWUC	(reader/writer memory 1-byte data)	0AH	
RWS	(reader/writer memory 2-byte data)	0BH	
RWUT	(reader/writer memory 3-byte data)	0CH	
RWL	(reader/writer memory 4-byte data)	0DH	

^{*1} The CH number is required in addition to the device type and address. The assigned device memory is expressed as shown on the right when editing the screen.



Indirect Device Memory Designation

Specify the CH number in the expansion code.

PLC_CTL

Macro command "PLC_CTL F0 F1 F2"

Contents	F0		F1 (= \$u r	1)	F2
		n	Station number		
		n + 1	Command: 0		
		n + 2	CH No.		
		n + 3	Attribute (0, 8)	Attribute (1, 2, 9, A)	
		n + 4	Address	Address	
Tag memory clear	1 - 8 (PLC1 - 8)	n + 5	Bytes	Bytes	7/11
	(ILCI O)	n + 6	Clear data	LIID (1)	
		n + 7	-	UID (lower)	
		n + 8	-	LITD (1: 1)	
		n + 9	-	— UID (higher)	
		n + 10	-	Clear data	
		n	Station number		
		n + 1	Command: 1		
	1 - 8	n + 2	CH No.		
Controller clear	(PLC1 - 8)	n + 3	Address		6
		n + 4	Bytes		
		n + 5	Clear data		
		n	Station number		
Controller initialize	1 - 8	n + 1	Command: 2		3
	(PLC1 - 8)	n + 2	CH No.		
		n	Station number		
		n + 1	Command: 3		
Error log clear (communication time,	1 - 8	n + 2	CH No.		4
number of retrials)	(PLC1 - 8)		Area		4
,		n + 3	0: Communication time log 1: Retry count log		
		n	Station number		
		n + 1	Command: 4		
		n + 2	CH No.		
		n + 3	Attribute (0, 8)	Attribute (1, 9)	
Reader/writer memory clear	1 - 8 (PLC1 - 8)	n + 4	Address	Address	7/9
	(ILCI O)	n + 5	Bytes	Bytes	
		n + 6	Clear data		
		n + 7	-	Identification sign	
		n + 8	-	Clear data	
		n	Station number		
Controller self diagnosis	1 - 8	n + 1	Command: 5		3
3	(PLC1 - 8)	n + 2	CH No.		
		n	Station number		
		n + 1	Command: 6		
	1 - 8	n + 2	CH No.		
Reader/writer self diagnosis	(PLC1 - 8)	n + 3	Attribute (0, 8)	Attribute (1, 9)	4/6
	•	n + 4	-		
		n + 5	_	Identification sign	
		n	Station number		
		n + 1	Command: 7		
Error reset	1 - 8 (PLC1 - 8)		CH No.		3
	(1202 0)	n + 2	0: CH No. 0		
			1: CH No. 1		
		n	Station number		
		n + 1	Command: 8		
		n + 2	CH No.		
Output command	1 - 8 (PLC1 - 8)	n + 3	OUT0 0: OFF 1: ON		5
		n + 4	OUT1 0: OFF 1: ON		
		n	Station number		
Status read out	1 - 8 (PLC1 - 8)	n + 1	Command: 9		3
	(I LCI - 0)	n + 2	CH No.		
		n + 3	Status		

Contents	F0		F1 (= \$u r	1)	F2
		n	Station number		
		n + 1	Command: 10		
D 1 (')	1 - 8	n + 2	CH No.		4.16
Reader/writer reset	(PLC1 - 8)	n + 3	Attribute (0, 8)	Attribute (1, 9)	4/6
		n + 4	-		
		n + 5	-	Identification sign	
		n	Station number		
		n + 1	Command: 11		
Reader/writer radio wave	1 - 8	n + 2	CH No.		
stop	(PLC1 - 8)	11 + 2	Command to reader/writer		4
		n + 3	0: Radio wave stop 1: Radio wave emit		
		n	Station number		
	4 0	n + 1	Command: 12		
Input check	1 - 8 (PLC1 - 8)	n + 2	CH No.		3
	(1202 0)	n + 3	IN0		
		n + 4	IN1		
		n	Station number		
		n + 1	Command: 13		
	1 0	n + 2	CH No.		
Controller read out	1 - 8 (PLC1 - 8)	n + 3	Address		6
	(-222 3)	n + 4	Bytes		
			,	. *1	
		n + 5	Internal device memory add	aress +	
	1 - 8 (PLC1 - 8)	n	Station number		
Controller write		n + 1	Command: 14		
		n + 2	CH No.		6
		n + 3	Address		
		n + 4	Bytes		
		n + 5	Internal device memory address *2		
		n	Station number		
		n + 1	Command: 15		
		n + 2	CH No.		1
		n + 3	Attribute (0, 3, 4, 8, B, C)	Attribute (1, 2, 5, 6, 9, A, D, E)	
		n + 4	Address	Address	
		n + 5	Bytes	Bytes	
Tag read out	1 - 8 (PLC1 - 8)	n + 6	Internal device memory address *1	UID (lower)	7/11
		n + 7	-		
		n + 8	_		
		n + 9	_	— UID (higher)	1
		n + 10	-	Internal device memory address *1	
	+	n	Station number	address	
		n + 1	Command: 16		
			CH No.		4
		n + 2		Attailbute (1.2.5.0.0.4.5.5)	
		n + 3	Attribute (0, 3, 4, 8, B, C)	Attribute (1, 2, 5, 6, 9, A, D, E)	
		n + 4	Address	Address	
To a vivile	1 - 8	n + 5	Bytes	Bytes	7/11
Tag write	(PLC1 - 8)	n + 6	Internal device memory address *2	UID (lower)	7/11
		n + 7	-		
		n + 8	-	UID (higher)	
		n + 9	-	515 (gci)	
		n + 10	-	Internal device memory address *2	
		n	Station number		
			The state of the s		1
		n + 1	Command: 17		
Tag UID code read out	1 - 8	n + 1 n + 2	Command: 17 CH No.		5
Tag UID code read out	1 - 8 (PLC1 - 8)				5

Contents	F0	F1 (= \$u n)			F2
		n	Station number		
		n + 1	Command: 18		
		n + 2	CH No.		
		n + 3	Year	Year	
T'	1 - 8	n + 4	Month		
Time read out	(PLC1 - 8)	n + 5	Day		3
		n + 6	Hour		
		n + 7	Minute		
		n + 8	Second		
		n + 9	A day of the week		
		n	Station number		
		n + 1	Command: 19		
		n + 2	CH No.		
		n + 3	Year		
Time setting	1 - 8	n + 4	Month		10
Time setting	(PLC1 - 8)	n + 5	Day		10
		n + 6	Hour		
		n + 7	Minute		
		n + 8	Second		
		n + 9	A day of the week		
	1-8	n	Station number		
		n + 1	Command: 20		
		n + 2	CH No.		
		n + 3	Attribute (0, 8)	Attribute (1, 9)	
		n + 4	Address	Address	
Reader/writer read out	(PLC1 - 8)	n + 5	Bytes	Bytes	7/9
		n + 6	Internal device memory address *1	Identification sign	
		n + 7	-		
		n + 8	-	Internal device memory address *1	
		n	Station number		
Reader/writer write		n + 1	Command: 21		
		n + 2	CH No.		
		n + 3	Attribute (0, 8)	Attribute (1, 9)	
	1 - 8	n + 4	Address	Address	
	(PLC1 - 8)	n + 5	Bytes	Bytes	7/9
	(. 202 0)	n + 6	Internal device memory address *2	Identification sign	
		n + 7	-		
		n + 8	-	Internal device memory address *2	

Return data: Data stored from servo to V series

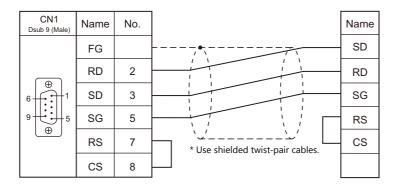
^{*1} Specify the top address of the internal device memory (\$u) at which the read data is to be stored.
*2 Specify the top address of the internal device memory (\$u) at which data to be written is stored.

6.2.3 Wiring Diagrams

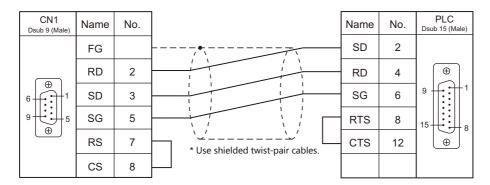
When Connected at CN1:

RS-232C

Wiring diagram 1 - C2

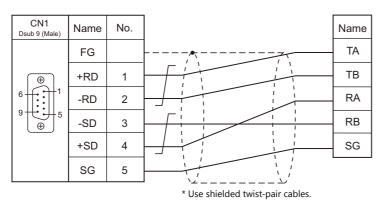


Wiring diagram 2 - C2

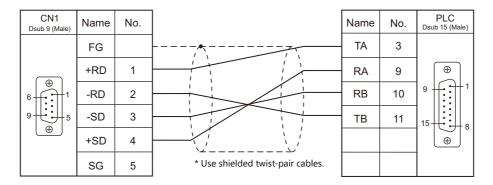


RS-422/RS-485

Wiring diagram 1 - C4



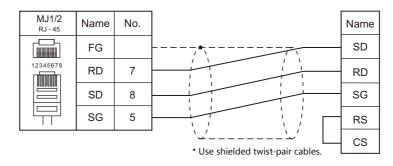
Wiring diagram 2 - C4



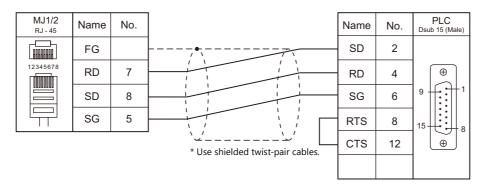
When Connected at MJ1/MJ2:

RS-232C

Wiring diagram 1 - M2

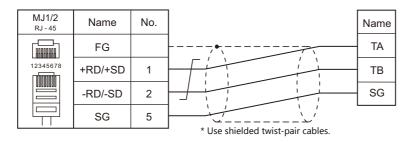


Wiring diagram 2 - M2



RS-422/RS-485

Wiring diagram 1 - M4



7. SHIMADEN

7.1 Temperature Controller / Servo / Inverter Connection

7.1 Temperature Controller / Servo / Inverter Connection

Controller / Indicator / Servo Controller

PLC Selection on the	Model	Port	Ciamal Lavial	Conn	ection	Lst File
Editor	Model	Port	Signal Level	CN1	MJ1/MJ2	LSt File
	SR82-xx-N-xx-xxxx5xx SR83-xx-x-xx-xxxx5xx SR84-xx-x-xx-xxxx5xx SR91-xx-xx-x5x SR92-xx-x-xx-x05x SR93-xx-x-xx-x05x SR94-xx-x-xx-x05x SR23-xxxx-xxxxxx5x FP93-xx-xx-x5x MR13-xx1-xxxx15x SD16-xxx-xx5x EM70-xx-xxx5x	Terminal block	RS-485	Wiring diagram 1 - C4	Wiring diagram 1 - M4	
SHIMADEN standard protocol	SR82-xx-N-xx-xxxx7xx SR83-xx-x-xx-xxxx7xx SR84-xx-x-xx-xxx7xx SR92-xx-x-xx-xx7x SR93-xx-x-xx-x07x SR94-xx-x-xx-x07x SR93-xx-x-xxxxxx7x FP3-xx-xx-xxxxxxxxxxxxxxxxxxxxxxxxxxxxxx	Terminal block	RS-232C	Wiring diagram 1 - C2	Wiring diagram 1 - M2	Shimaden. List
	SR253-xx-x-xxxxxx5x	Communication port	RS-485	Wiring diagram 2 - C4	Wiring diagram 2 - M4	
	SR253-xx-x-xxxxxx6x	Communication port	RS-422	Wiring diagram 3 - C4	×	
	SR253-xx-x-xxxxxx7x	Communication port	RS-232C	Wiring diagram 2 - C2	Wiring diagram 2 - M2	
	FP23-xxxx-xxxxx5x	Terminal block	RS-485	Wiring diagram 1 - C4	Wiring diagram 1 - M4	ShimadenF
	FP23-xxxx-xxxxx7x	Terminal block	RS-232C	Wiring diagram 1 - C2	Wiring diagram 1 - M2	P23.List

7.1.1 SHIMADEN Standard Protocol

Communication Setting

Editor

Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1:1/1:n/Multi-link2/Multi-link2 (Ethernet)/ 1:n Multi-link2 (Ethernet)	
Signal Level	<u>RS-232C</u> / RS-422/485	
Baud Rate	4800 / 9600 / <u>19200</u> bps	
Data Length	<u>7</u> / 8 bits	
Stop Bit	<u>1</u> / 2 bits	
Parity	None / Odd / Even	
Target Port No.	<u>1</u> to 31	
Sum Check	Add/ Complement for Adding 2 / Exclusive OR / None	
CR/LF	<u>CR</u> / CR/LF	Only CR supported by the SR90/FP93/SD16 series
Write Data Count Setting	1 to 10	

Controller / Indicator / Servo Controller

Communication parameters can be set by operating the keys on the front of the controller. Be sure to match the settings to those made under [Communication Setting] of the editor.

SR80 Series / EM70 Series

Parameter Display	Item	Setting	Example
Comm	Communication mode *1	LOC: Read only COM: Read/write	СОМ
AdrS	Communication address	1 to 99	1
bPS	Baud rate	4800 / 9600 / 19200 bps	19200
dAtA	Communication data format	7E1: 7 bits / even parity / 1 bit 7E2: 7 bits / even parity / 2 bits 7N1: 7 bits / none / 1 bit 7N2: 7 bits / none / 2 bits 8E1: 8 bits / even parity / 1 bit 8E2: 8 bits / even parity / 2 bits 8N1: 8 bits / none / 1 bit 8N2: 8 bits / none / 2 bits	7E1
CtrL	Communication control code	1: STX_ETX_CR 2: STX_ETX_CRLF	1
bcc	Communication BCC check	1: ADD (addition) 2: ADD_two's cmp (addition + 2's complement number) 3: XOR (exclusive OR) 4: None	1

^{*1} The front-mounted key works for switching COM \rightarrow LOC only. When writing from the V9, place "1" (= communication mode: COM) at address "018Cxx (H)". (xx: Subaddress)

SR90 Series

(Underlined setting: default)

Parameter Display	Item	Setting	Example
Comm	Communication mode *1	LOC: Read only COM: Read/write	СОМ
Prot	Communication protocol	Shim: SHIMADEN protocol	Shim
bcc	BCC calculation	1: ADD (addition) 2: ADD_two's cmp (addition + 2's complement number) 3: XOR (exclusive OR) 4: None	1
bPS	Baud rate	4800 / 9600 / 19200 bps	19200
Addr	Communication address	<u>1</u> to 255	1
dAtA	Communication data format	7E1: 7 bits / even parity / 1 bit 7E2: 7 bits / even parity / 2 bits 7N1: 7 bits / none / 1 bit 7N2: 7 bits / none / 2 bits 8E1: 8 bits / even parity / 1 bit 8E2: 8 bits / even parity / 2 bits 8N1: 8 bits / none / 1 bit 8N2: 8 bits / none / 2 bits	7E1
SchA	Start character	STX	STX

The front-mounted key works for switching COM \rightarrow LOC only. When writing from the V9, place "1" (= communication mode: COM) at address "018Cxx (H)". (xx: Subaddress)

SR253 Series

Group	Display	Item	Setting	Example
Group 1-2	Operation	Communication mode *1	LOCAL: Read only COMM: Read/write	СОММ
	Add	Machine address	<u>01</u> to 99	01
	BPS	Baud rate	4800 / 9600 / 19200 bps	19200
Group 5-5A	DATA	Communication data format	7E1: 7 bits / even parity / 1 bit 7E2: 7 bits / even parity / 2 bits 7N1: 7 bits / none / 1 bit 7N2: 7 bits / none / 2 bits 8E1: 8 bits / even parity / 1 bit 8E2: 8 bits / even parity / 2 bits 8N1: 8 bits / none / 1 bit 8N2: 8 bits / none / 2 bits	7E1
	Mode	Communication protocol mode	Standard: Standard protocol	Standard
	MEM	Communication memory mode	EEP: EEPROM RAM: RAM	EEP
	CTRL	Control code	STX_ETX_CR STX_ETX_CRLF	STX_ETX_CR
Group 5-5B	ВСС	Checksum	ADD (addition) ADD_two's cmp (addition + 2's complement number) XOR (exclusive OR) None	ADD
	DELY	Delay time	0 to 99 ms	40

^{*1} The front-mounted key works for switching COMM → LOCAL only.

When writing from the V9, place "1" (= communication mode: COM) at address "018Cxx (H)". (xx: Subaddress)

SR23 Series / FP23 Series

(Underlined setting: default)

Parameter Display	Item	Setting	Example
СОМ	Communication mode *1	LOCAL: Read only COM: Read/write	СОМ
PORT	Communication protocol mode	SHIMADEN: SHIMADEN protocol	SHIMADEN
ADDR	Device address	1 to 98	1
BPS	Baud rate	4800 / 9600 / 19200 bps	19200
MEM	Communication memory mode	EEP: EEPROM RAM: RAM R_E: RAM/EPPROM *2	EEP
DATA	Data length	7/8	7
PARI	Parity	EVEN / ODD / NONE	EVEN
STOP	Stop bit	1/2	1
DELY	Communication delay time	1 to 50 ms	10
CTRL	Communication control code	STX_ETX_CR STX_ETX_CRLF	STX_ETX_CR
ВСС	Communication BCC data calculation	ADD (addition) ADD_two's cmp (addition + 2's complement number) XOR (exclusive OR) None	ADD

- *1
- The front-mounted key works for switching COM \rightarrow LOC only. When writing from the V9, place "1" (= communication mode: COM) at address "018Cxx (H)". (xx: Subaddress) Data in SV, OUT, and COM modes will be written to RAM. Other data will be written to EPPROM.

FP93 Series

Parameter Display	Item	Setting	Example
Comm	Communication mode *1	LOC: Read only COM: Read/write	СОМ
Addr	Communication address	<u>1</u> to 255	1
bPS	Baud Rate	4800 / 9600 / 19200 bps	19200
dAtA	Communication data format	7E1: 7 bits / even parity / 1 bit 8N1: 8 bits / none / 1 bit	7E1
Stx	Start character	STX	STX
bCC	Communication calculation	1: Addition 2: Addition + 2's complement number 3: XOR 4: None	1

^{*1} The front-mounted key works for switching COM \rightarrow LOC only. When writing from the V9, place "1" (= communication mode: COM) at address "018Cxx (H)". (xx: Subaddress)

MR13 Series

(Underlined setting: default)

Parameter Display	Item	Setting	Example
Com	Communication mode *1	LOC: Read only COM: Read/write	СОМ
Addr	Communication address	<u>1</u> to 99	1
bPS	Baud rate	4800 / 9600 / 19200 bps	19200
dAtA	Communication data format	7E1: 7 bits / even parity / 1 bit 7E2: 7 bits / even parity / 2 bits 7N1: 7 bits / none / 1 bit 7N2: 7 bits / none / 2 bits 8E1: 8 bits / even parity / 1 bit 8E2: 8 bits / even parity / 2 bits 8N1: 8 bits / none / 1 bit 8N2: 8 bits / none / 2 bits	7E1
mEm	Communication memory mode	EEP: EEPROM RAM: RAM	EEP
CtrL	Communication control code	1: STX_ETX_CR 2: STX_ETX_CRLF	1
ьсс	Communication checksum	1: ADD (addition) 2: ADD_two's cmp (addition + 2's complement number) 3: XOR (exclusive OR) 4: None	1

¹ The front-mounted key works for switching COM \rightarrow LOC only. When writing from the V9, place "1" (= communication mode: COM) at address "018Cxx (H)". (xx: Subaddress)

SD16 Series

Parameter Display	Item	Setting	Example
Comm	Communication mode *1	LOC: Read only COM: Read/write	СОМ
Prot	Communication protocol mode	SHIM: SHIMADEN standard protocol	SHIM
Addr	Communication address	<u>1</u> to 100	1
dAtA	Communication data format	7E1: 7 bits / even parity / 1 bit 7E2: 7 bits / even parity / 2 bits 7N1: 7 bits / none / 1 bit 7N2: 7 bits / none / 2 bits 8E1: 8 bits / even parity / 1 bit 8E2: 8 bits / even parity / 2 bits 8N1: 8 bits / none / 1 bit 8N2: 8 bits / none / 2 bits	7E1
SchA	Communication start character	STX	STX
bcc	BCC calculation	1: ADD (addition) 2: ADD_two's cmp (addition + 2's complement number) 3: XOR 4: None	1
bPS	Baud rate	4800 / <u>9600</u> / 19200 bps	19200

^{*1} The front-mounted key works for switching COM → LOC only.

When writing from the V9, place "1" (= communication mode: COM) at address "018Cxx (H)". (xx: Subaddress)

Available Device Memory

The available setting range of device memory varies depending on the model. Be sure to set within the range available for the model to be used. Use [TYPE] when assigning indirect device memory for macro programs.

Device Memory	TYPE	Remarks
	00H	

Address denotations

The assigned device memory is expressed as shown below when editing the screen.

* Specify a channel as a subaddress.

 SR23 series / FP23 series
 : 01 to 02

 MR13 series
 : 01 to 03

 Other models
 : 01 (fixed)

Indirect Device Memory Designation

15	5 8	7 0
n+0	Model	Device type
n+1	Address (lower)	Subaddress
n+2	00	Address (higher)
n+3	00	Bit designation
n+4	00	Station number

PLC_CTL

Macro command "PLC_CTL F0 F1 F2"

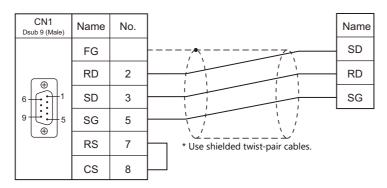
Contents	F0	F1 (=\$u n)		F2		
		n	Station number: 0 (fixed)			
Broadcast	1 to 8	n+1	Address (lower) + subaddress	4		
Dioducast	(PLC1 to 8)	n+2	Address (higher)	4		
		n+3		Write data		

7.1.2 Wiring Diagrams

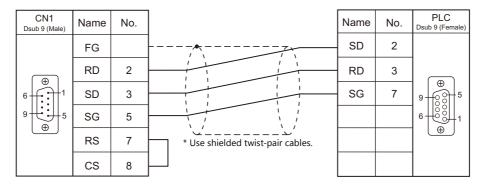
When Connected at CN1:

RS-232C

Wiring diagram 1 - C2

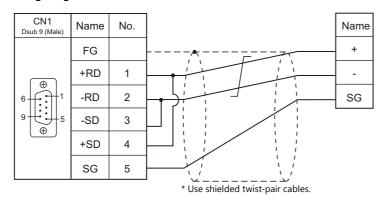


Wiring diagram 2 - C2

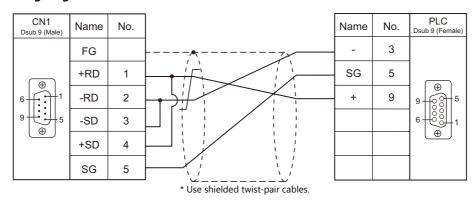


RS-422/RS-485

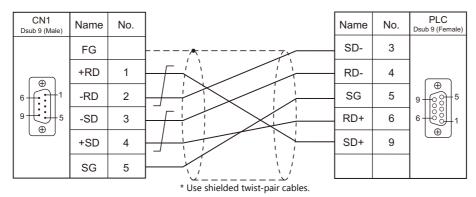
Wiring diagram 1 - C4



Wiring diagram 2 - C4



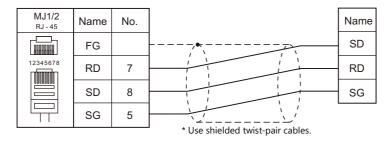
Wiring diagram 3 - C4



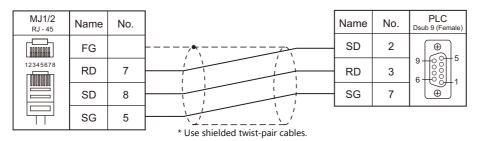
When Connected at MJ1/MJ2:

RS-232C

Wiring diagram 1 - M2

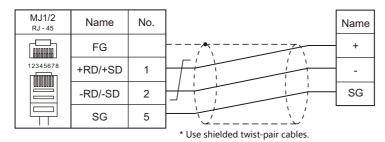


Wiring diagram 2 - M2

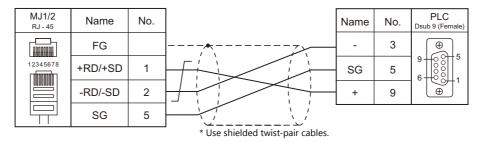


RS-422/RS-485

Wiring diagram 1 - M4



Wiring diagram 2 - M4



MEMO	
Please use this pa	ge freely.

8. SHINKO TECHNOS

8.1 Temperature Controller/Servo/Inverter Connection

8.1 Temperature Controller/Servo/Inverter Connection

Serial Connection

Multi-point Temperature Control System

PLC Selection	Model	Port	Signal Level	Conne	Lst File	
on the Editor	Wodel	FOIL	Signal Level	CN1	MJ1/MJ2	LSCFIIE
C series	CPT-20A	Power source host link unit	RS-485	Wiring diagram 3 - C4	Wiring diagram 3 - M4	S-C.Lst

Digital Indicating Controller

PLC Selection	Model	Dowt	Ciamal Laval	Conn	ection	Lst File
on the Editor	Model	Port	Signal Level	CN1	MJ1/MJ2	LSt File
	FCS-23A (C5, C)*1					
FC series FCR-2	FCR-13A (C5, C)*1 FCR-23A (C5, C)*1 FCR-15A (C5, C)*1	Terminal block	RS-232C	Wiring diagram 1 - C2	Wiring diagram 1 - M2	S-FC.Lst
	FCD-13A (C5, C) ^{*1} FCD-15A (C5, C) ^{*1}		RS-485	Wiring diagram 1 - C4	Wiring diagram 1 - M4	
GC series	GCS-33x-x/x, C5	Terminal block	RS-485	Wiring diagram 1 - C4	Wiring diagram 1 - M4	S-GC.Lst
JCx-300 series	JCS-33A-x/xx, C5 JCR-33A-x/xx, C5 JCD-33A-x/xx, C5	Terminal block	RS-485	Wiring diagram 1 - C4	Wiring diagram 1 - M4	S-JC.Lst
ACS-13A	ACS-13A-x/Mx, C5	Terminal block	RS-485	Wiring diagram 1 - C4	Wiring diagram 1 - M4	S-ACS13A.Lst
	ACD-13A-x/Mx, (C5, C)*1 ACR-13A-x/Mx, (C5, C)*1		RS-232C	Wiring diagram 1 - C2	Wiring diagram 1 - M2	
ACD/ACR series	ACR-15A-x/Mx, (C5, C)*1 ACD-15A-R/Mx, (C5, C)*1 ACR-15A-R/Mx, (C5, C)*1	Terminal block	RS-485	Wiring diagram 1 - C4	Wiring diagram 1 - M4	S-ACDR.Lst
WCL-13A	WCL-13A-xx/xxx, C5	RS-485	RS-485	Wiring diagram 2 - C4	Wiring diagram 2 - M4	S-WCL.Lst

^{*} Select a model with option C5 (serial communication RS-485) or C (serial communication RS-232C).

DIN-Rail-Mounted Indicating Controller

,	PLC Selection	Model	Port	Signal Level	Conne	Lst File	
	on the Editor	Wodei	FOIL	Signal Level	CN1	MJ1/MJ2	LSCFIIE
,	DCL-33A	DCL-33A-x/xx, C5	RS-485	RS-485	Wiring diagram 2 - C4	Wiring diagram 2 - M4	S-DCL.Lst

Program Controller

PLC Selection	Model	Port Signal Level		Conne	Lst File	
on the Editor	Model	POIL	Signal Level	CN1	MJ1/MJ2	LSCFIIE
PCD-33A	PCD-33A-x/Mx, C5	Terminal block	RS-485	Wiring diagram 1 - C4	Wiring diagram 1 - M4	S-PCD33A.Lst
PC-900	DC 00F 0/M /CF C)*1	Torminal black	RS-232C	Wiring diagram 1 - C2	Wiring diagram 1 - M2	S-PC900.Lst
PC-900	PC-9x5-x/M, (C5, C)*1	, C) ^{*1} Terminal block	RS-485	Wiring diagram 1 - C4	Wiring diagram 1 - M4	3-PC900.LSt

^{*1} Select a model with option C5 (serial communication RS-485) or C (serial communication RS-232C).

8.1.1 C Series

Communication Setting

Editor

Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1 : 1 / <u>1 : n</u> / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet)	
Signal Level	RS-232C / <u>RS-422/485</u>	
Baud Rate	<u>9600</u> / 19200 bps	
Data Length	Z/8 bits	
Stop Bit	<u>1</u> / 2 bits	
Parity	None / Odd / <u>Even</u>	
Target Port No.	0 to 15	

C Series

Device number setting

STATION No.	Setting	Setting Example
\$\frac{1}{2}\frac{1}{2	0 to F (H) (0 to 15)	0

Communication setting DIP switch

Switch	Contents	OFF			ON	Setting Example	
1	Baud rate	<u>9600 bps</u>			19200 bps		
2	Terminating resistance	With	out termir	nating resistance	With terminating resistance		
3							
4	Communication			OFF: Shinko sta	andard protocol		
5	format			<u>011</u> . 31111110 310	OFF: Shinko standard protocol		
6							
		7	8		Contents	3 4	
7		<u>OFF</u>	<u>OFF</u>	Turning ON/OFF by co	ommunication command *1	5	
		ON	OFF	DO1: warning 1, DO2: warning	warning 2, DO3: heater disconnection	6 ■ 7 ■ 8 ■	
	Digital output setting		ON	DO1: warning 1, DO2:	warning 2, DO3: abnormal loop warning		
	Setting	ON	ON	DO1: warning 1, DO2: abnormal loop warnir	heater disconnection warning, DO3:		
8		CPT-	20A. For n		e address (digital output [0041xx]) on o the instruction manual for the temperature		

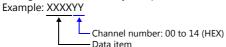
Available Device Memory

The available setting range of device memory varies depending on the controller model. Be sure to set within the range available for the controller to be used. Use [TYPE] when assigning indirect device memory for macro programs.

	Device Memory	TYPE	Remarks
ſ		00H	

Address denotations

• The assigned device memory is expressed as shown below when editing the screen.



• On the signal name reference list, every channel number is designated as "00". To access any channel number other than "00", manually input the desired number.

8.1.2 FC Series

Communication Setting

Editor

Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1 : 1 / <u>1 : n</u> / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet)	
Signal Level	RS-232C / <u>RS-422/485</u>	
Baud Rate	4800 / <u>9600</u> / 19200 bps	
Data Length	7 bits	
Stop Bit	1 bit	
Parity	Even	
Target Port No.	0 to 95	"95" is used for broadcasting.

FC Series

Auxiliary function setting mode 1

When the [MODE] key is held down for three seconds together with the $[\Psi]$ key in the PV/SV display mode, the controller enters in "auxiliary function setting mode 1".

(Underlined setting: default)

Item	Setting	Remarks
Communication protocol selection	Shinko standard	Available only with FCS-23A, FCR-13A, FCR-23A and FCD-13A
Device number setting	<u>0</u> to 94	
Baud rate selection	4800 / <u>9600</u> / 19200 bps	

^{*} The following settings are fixed; data length 7, stop bit 1 and even parity.

Available Device Memory

The available setting range of device memory varies depending on the controller model. Be sure to set within the range available for the controller to be used. Use [TYPE] when assigning indirect device memory for macro programs.

Device Memory	TYPE	Remarks
	00H	

Address denotations

The assigned device memory is expressed as shown below when editing the screen.
 Example: XXXXYY



• On the signal name reference list, every sub address is designated as "00". To access any sub address other than "00", manually input the desired address.

8.1.3 GC Series

Communication Setting

Editor

Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1 : 1 / <u>1 : n</u> / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet)	
Signal Level	RS-232C / <u>RS-422/485</u>	
Baud Rate	4800 / <u>9600</u> / 19200 bps	
Data Length	7 bits	
Stop Bit	1 bit	
Parity	Even	
Target Port No.	0 to 95	"95" is used for broadcasting.

GC Series

Auxiliary function setting mode 1

When the [MODE] key is held down for three seconds together with the $[\Psi]$ key in the PV/SV display mode, the controller enters in "auxiliary function setting mode 1".

(Underlined setting: default)

Item	Setting	Remarks
Device number setting	<u>0</u> to 94	
Baud rate selection	4800 / 9600 / 19200 bps	

^{*} The following settings are fixed; data length 7, stop bit 1, even parity.

Available Device Memory

The available setting range of device memory varies depending on the controller model. Be sure to set within the range available for the controller to be used. Use [TYPE] when assigning indirect device memory for macro programs.

Device Memory	TYPE	Remarks
	00H	

Address denotations

The assigned device memory is expressed as shown below when editing the screen.
 Example: XXXXYY

Channel number: 00 (fixed)

8.1.4 JCx-300 Series

Communication Setting

Editor

Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1:1/ <u>1:n</u> /Multi-link2/ Multi-link2 (Ethernet)/ 1:n Multi-link2 (Ethernet)	
Signal Level	RS-232C / <u>RS-422/485</u>	
Baud Rate	4800 / <u>9600</u> / 19200 bps	
Data Length	7 bits	
Stop Bit	1 bit	
Parity	Even	
Target Port No.	0 to 95	"95" is used for broadcasting.

JCx-300 Series

Auxiliary function setting mode 1

When the [MODE] key is held down for three seconds together with the $[\P]$ key in the PV/SV display mode, the controller enters in "auxiliary function setting mode 1".

(Underlined setting: default)

Item	Setting	Remarks
Communication protocol selection	Shinko standard	
Communication device number setting	<u>0</u> to 94	
Baud rate selection	4800 / <u>9600</u> / 19200 bps	
Parity selection	Even	Cannot be changed when the Shinko standard protocol
Stop bit selection	1 bit	is selected.

^{*} The data length setting is fixed to "7".

Available Device Memory

Device Memory	TYPE	Remarks
	00H	

8.1.5 ACS-13A

Communication Setting

Editor

Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1 : 1 / <u>1 : n</u> / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet)	
Signal Level	RS-232C / <u>RS-422/485</u>	
Baud Rate	4800 / <u>9600</u> / 19200 bps	
Data Length	7 bits	
Stop Bit	1 bit	
Parity	Even	
Target Port No.	0 to 95	"95" is used for broadcasting.

ACS-13A

Auxiliary function setting mode

When the [MODE] key is held down for three seconds together with the $[\P]$ key in the PV/SV display mode, the controller enters in "auxiliary function setting mode".

(Underlined setting: default)

Item	Setting	Remarks
Communication protocol selection	Shinko standard	
Device number setting	<u>0</u> to 94	
Baud rate selection	4800 / <u>9600</u> / 19200 bps	
Data bit / parity selection	7 bits / even	
Stop bit selection	1 bit	

Available Device Memory

Device Memory	TYPE	Remarks
	00H	

8.1.6 ACD/ACR Series

Communication Setting

Editor

Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1:1/ <u>1:n</u> /Multi-link2/ Multi-link2 (Ethernet)/ 1:n Multi-link2 (Ethernet)	
Signal Level	RS-232C / <u>RS-422/485</u>	
Baud Rate	9600 / 19200 / 38400 bps	
Data Length	Z / 8 bits	
Stop Bit	<u>1</u> / 2 bits	
Parity	None / Odd / <u>Even</u>	
Target Port No.	0 to 95	"95" is used for broadcasting.

ACD/ACR Series

Communication parameter setting group

When the [SET] key is pressed four times and the [MODE] key is pressed in the PV/SV display mode, the controller enters in "input parameter group".

In this state, press the [SET] key several times again. The controller enters in "communication parameter setting group".

(Underlined setting: default)

Item	Setting	Remarks
Communication protocol selection	Shinko standard	
Device number setting	<u>0</u> to 94	
Baud rate selection	9600 / 19200 / 38400 bps	
Data bit / parity selection	8 bits / no parity 7 bits / no parity 8 bits / even 7 bits / even 8 bits / odd 7 bits / odd	
Stop bit selection	1 bit 2 bits	

Available Device Memory

Device Memory	TYPE	Remarks
	00H	

8.1.7 WCL-13A

Communication Setting

Editor

Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1:1/ <u>1:n</u> /Multi-link2/ Multi-link2 (Ethernet)/ 1:n Multi-link2 (Ethernet)	
Signal Level	RS-232C / <u>RS-422/485</u>	
Baud Rate	9600 / 19200 / 38400 bps	
Data Length	7 bits	
Stop Bit	1 bit	
Parity	Even	
Target Port No.	0 to 95	"95" is used for broadcasting.

WCL-13A

Specific function setting group

When the [MODE] key is pressed several times in the PV/SV display mode, the controller enters in "specific function setting group".

(Underlined setting: default)

Item	Setting	Remarks
Communication protocol selection	Shinko standard	
Device number setting	<u>0</u> to 94	
Baud rate selection	9600 / 19200 / 38400 bps	
Data bit / parity selection	7 bits / even	
Stop bit selection	1 bit	

Available Device Memory

Device Memory	TYPE	Remarks
	00H	

8.1.8 DCL-33A

Communication Setting

Editor

Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1 : 1 / <u>1 : n</u> / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet)	
Signal Level	RS-422/485	
Baud Rate	4800 / <u>9600</u> / 19200 bps	
Data Length	7 bits	
Stop Bit	1 bit	
Parity	Even	
Target Port No.	0 to 31	

DCL-33A

Auxiliary function setting mode 1

When the [MODE] key is held down for three seconds together with the $[\P]$ key in the PV/SV display mode, the controller enters in the "auxiliary function setting" mode.

(Underlined setting: default)

Item	Setting	Remarks
Communication protocol selection	Shinko standard	
Communication device number setting	<u>0</u> to 31	
Baud rate selection	4800 / <u>9600</u> / 19200 bps	
Parity selection	Even	Cannot be changed when the Shinko standard protocol
Stop bit selection	1 bit	is selected.

^{*} The data length setting is fixed to "7".

Available Device Memory

Device Memory	TYPE	Remarks
	00H	

8.1.9 PCD-33A

Communication Setting

Editor

Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1:1/ <u>1:n</u> /Multi-link2/ Multi-link2 (Ethernet)/ 1:n Multi-link2 (Ethernet)	
Signal Level	RS-232C / <u>RS-422/485</u>	
Baud Rate	4800 / <u>9600</u> / 19200 bps	
Data Length	7 bits	
Stop Bit	1 bit	
Parity	Even	
Target Port No.	0 to 95	"95" is used for broadcasting.

PCD-33A

Auxiliary function setting mode 1

When the [MODE] key is held down for three seconds together with the $[\P]$ key in the PV/SV display mode, the controller enters in "auxiliary function setting mode 1".

(Underlined setting: default)

Item	Setting	Remarks
Communication protocol selection	Shinko standard	
Device number setting	<u>0</u> to 94	
Baud rate selection	9600 / 19200 / 38400 bps	
Parity selection	<u>Even</u>	Cannot be changed when the Shinko standard protocol
Stop bit selection	1 bit	is selected.

^{*} The data length setting is fixed to "7".

Available Device Memory

Device Memory	TYPE	Remarks
	00H	

8.1.10 PC-900

Communication Setting

Editor

Communication setting

(Underlined setting: default)

Item	Setting	Remarks		
Connection Mode	1 : 1 / <u>1 : n</u> / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet)			
Signal Level	RS-232C / <u>RS-422/485</u>			
Baud Rate	4800 / <u>9600</u> / 19200 bps			
Data Length	7 bits			
Stop Bit	1 bit			
Parity	Even			
Target Port No.	0 to 95	"95" is used for broadcasting.		

PC-900

Communication parameter

Press the [SET/RST] key in the standby mode or program control execution mode, press the [STOP/MODE] key four times, and then press the [HOLD/ENT] key to select "auxiliary function setting mode". In this state, press the [STOP/MODE] key five times and then press the [HOLD/ENT] key to select "communication parameter". For more information, refer to the instruction manual for the PC-900.

(Underlined setting: default)

Item	Setting	Remarks
Baud rate selection	4800 / <u>9600</u> / 19200 bps	
Device number setting	<u>0</u> to 94	
Communication mode selection	Serial communication	

^{*} The following settings are fixed; data length 7, stop bit 1, even parity.

Available Device Memory

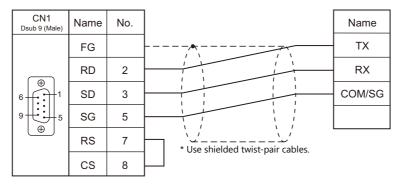
Device Memory	TYPE	Remarks
	00H	

8.1.11 Wiring Diagrams

When Connected at CN1:

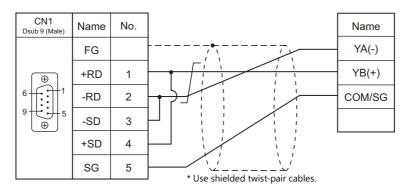
RS-232C

Wiring diagram 1 - C2

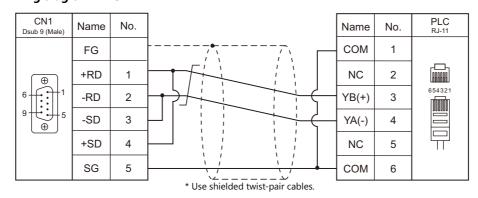


RS-422/RS-485

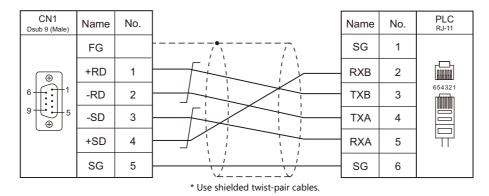
Wiring diagram 1 - C4



Wiring diagram 2 - C4



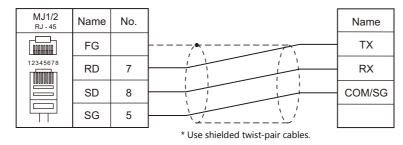
Wiring diagram 3 - C4



When Connected at MJ1/MJ2:

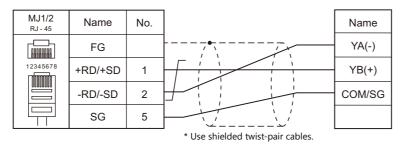
RS-232C

Wiring diagram 1 - M2

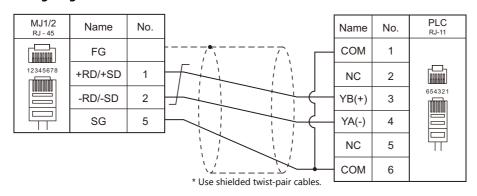


RS-422/RS-485

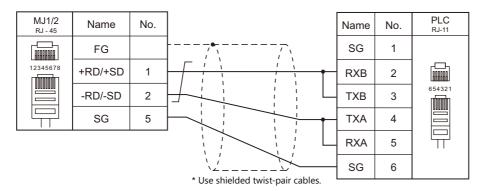
Wiring diagram 1 - M4



Wiring diagram 2 - M4



Wiring diagram 3 - M4



MEMO
Please use this page freely.

9. Siemens

9.1 PLC Connection

9.1 PLC Connection

Serial Connection

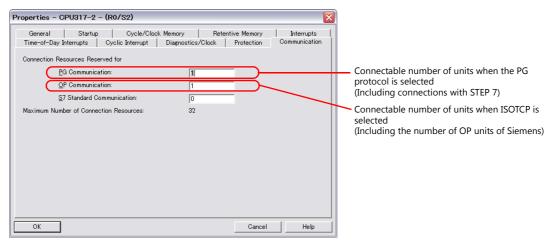
PLC Selection on the Editor	CPU	Unit/Port	Ciamal Laura	Conn	Ladder Transfer ^{*1}		
			Signal Level	CN1			
S5 (PG port)	S5-90U S5-95U S5-95F S5-100U S5-115U S5-115H S5-115F	Programming port of CPU	RS-232C	Siemens 6ES5 734-1BD20 + Wiring diagram 2 - C2	Siemens 6ES5 734-1BD20 + Wiring diagram 2 - M2	×	
	67, 200	CP-341 (3964R/RK512)	RS-232C	Wiring diagram 1 - C2	Wiring diagram 1 - M2	×	
S7	S7-300		RS-422	Wiring diagram 1 - C4	×		
	S7-400	CP-441	RS-232C	Wiring diagram 1 - C2	Wiring diagram 1 - M2		
	37-400	(3964R/RK512)	RS-422	Wiring diagram 1 - C4	×		
S7-200PPI	CPU 226 CPU 224 CPU 222 CPU 221 CPU 216 CPU 215 CPU 214 CPU 212	PPI	RS-485	Wiring diagram 2 - C4	Wiring diagram 1 - M4	×	
S7-300/400MPI	CPU 312 CPU 312C CPU 313C CPU 313C-2 DP CPU 314 CPU 314C-2 DP CPU 315-2 DP CPU 315-2 DP CPU 315-2 DP CPU 317-2 DP CPU 317-2 DP CPU 317-2 DP CPU 317-2 DP CPU 317-3 DP CPU 412-1 CPU 412-2 CPU 414-3 CPU 416-3 CPU 417-4	MPI (MPI/DP)	RS-485	Wiring diagram 2 - C4	Wiring diagram 1 - M4	×	
TI.500/505 T. series T.	TI545-1103	Port2	RS-232C	Wiring diagram 3 - C2	Wiring diagram 3 - M2		
	TI545-1101 TI545-1102 TI545-1104 TI545-1111 TI555-1101 TI555-1102 TI555-1103 TI555-1104 TI555-1105 TI555-1106	Port?	RS-232C	Wiring diagram 4 - C2	Wiring diagram 4 - M2		
		. 5.12	RS-422	Wiring diagram 3 - C4	Wiring diagram 2 - M4	×	
	TI575-2104	Port1	RS-232C	Wiring diagram 5 - C2	Wiring diagram 5 - M2		
	TI575-2105 TI575-2106	Port3	RS-422	Wiring diagram 4 - C4	×		

^{*1} For the ladder transfer function, see the V9 Series Reference Manual.

Ethernet Connection

PLC Selection on the Editor	CPU	Unit	TCP/IP	UDP/IP	Port No.	Keep Alive *1	Ladder Transfer ^{*2}
S7-200 (Ethernet ISOTCP)	CPU222, CPU224 CPU224XP, CPU226	CP243-1 CP243-1 IT	0	×	102 fixed (Max. 8 units)	0	×
S7-300/400 (Ethernet ISOTCP)	CPU312, CPU312C CPU313, CPU313C-2 DP CPU314, CPU314C-2 DP CPU315-2 DP CPU315-2 PN/DP CPU315F-2 DP CPU317-2 DP CPU317-2 PN/DP CPU317-2 PN/DP CPU317F-2 DP	CP343-1 Lean	0	×	102 (fixed) *3	0	×
	CPU315-2 PN/DP CPU317-2 PN/DP CPU319-3 PN/DP	-					
	CPU412-1, CPU412-2 CPU414-2, CPU414-3 CPU416-2, CPU416-3 CPU417-4	CP443-1					
S7-300/400 (Ethernet TCP/IP PG protocol)	CPU312, CPU312C CPU313, CPU313C-2 DP CPU314, CPU314C-2 DP CPU315-2 DP CPU315-2 PN/DP CPU315F-2 DP CPU317-2 DP CPU317-2 PN/DP CPU317-2 PN/DP CPU317F-2 DP	CP343-1 Lean	0	×	102 (fixed) * ³	0	×
	CPU315-2 PN/DP CPU317-2 PN/DP CPU319-3 PN/DP	-					
	CPU412-1, CPU412-2 CPU414-2, CPU414-3 CPU416-2, CPU416-3 CPU417-4	CP443-1					
S7-1200 (Ethernet ISOTCP)	CPU1211C CPU1212C CPU1214C	-	0	×	102 (fixed) (Max. 3 units)	0	×

- For KeepAlive functions, see "1.3.2 Ethernet Communication". For the ladder transfer function, see the V9 Series Reference Manual. In n:1 connection, the connectable number of V9 units varies depending on the system resource capacity of the PLC. Check the capacity on [Communication] which is displayed by selecting [STEP7 HW configuration] \rightarrow [CPU] \rightarrow [Object Properties].



9.1.1 S5 (PG Port)

Communication Setting

Editor

Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1:1/1: n / Multi-link2 / Multi-link2 (Ethernet) / 1: n Multi-link2 (Ethernet)	
Signal Level	RS-232C	
Baud Rate	<u>9600</u> bps	
Data Length	8 bits	
Stop Bit	1 bit	
Parity	Even	
Target Port No.	0 to 31	

S5

No particular setting is necessary on S5.

Calendar

This model is not equipped with the calendar function. Use the built-in clock of the V series.

Available Device Memory

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

	Device Memory	TYPE	Remarks
DB	(Data Block)	00H	*1
I	(input)	01H	IW as word device
Q	(output)	02H	QW as word device
F	(flag/internal relay)	03H	FW as word device
Т	(timer/current value)	04H	
С	(counter/current value)	05H	
AS	(absolute address)	06H	

*1 When these device memory are used, registration is required at the PLC. For more information, refer to the PLC manual issued by the manufacturer. The assigned device memory is expressed as shown on the right when editing the screen.

Example: DB001000

Address No. (0 to 255)

Block No. (0 to 255)

Addresses that can be set on MONITOUCH range from DB000000 to DB255255.

Indirect Device Memory Designation

	15 8	7 0
n+0	Model	Device type
n+1	Address No. (wo	ord designation)
n+2	00	Bit designation
n+3	00	Station number

 Designation of addresses for byte devices (I, Q, F, AS): Specify an address number divided by "2" for "n+1".

Example: Indirect device memory designation of "IW00010"

$$n+1 = 10 (DEC) \div 2 = 5 (DEC)$$

- Bit designation of addresses for byte devices (I, Q, F, AS):
 - An even address number

Specify a byte address number divided by "2" for "n+1" and specify a bit number for "n+2".

Example: Indirect device memory designation of "I000105"

$$n + 1 = 10 \div 2 = 5$$
 (DEC)

$$n + 2 = 5$$
 (DEC)

- An odd address number

Specify a byte address number minus "1", divided by "2", for "n+1". Specify a bit number plus "8" for "n+2".

Example: Indirect device memory designation of "I000115"

$$n + 1 = (11 - 1) \div 2 = 5$$
 (DEC)

$$n + 2 = 5 + 8 = 13$$
 (DEC)

• For DB device memory:

Specify a block number for the higher-order bytes "n + 1". Specify an address number for the lower-order bytes.

9.1.2 S7

Communication Setting

Editor

Communication setting

(Underlined setting: default)

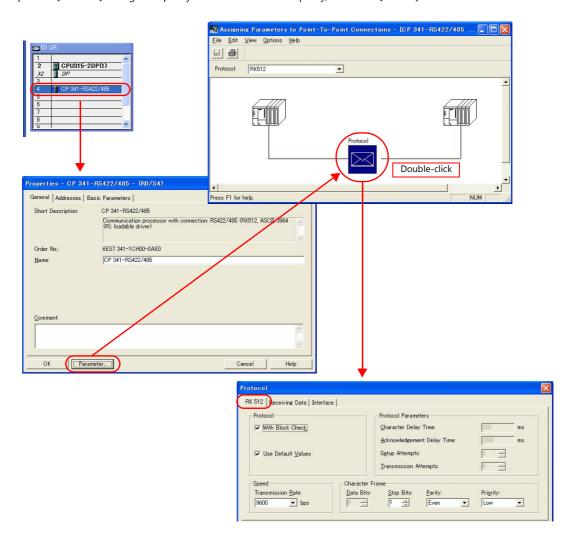
Item	Setting	Remarks
Connection Mode	1:1 / Multi-link2 / Multi-link2 (Ethernet)	
Signal Level	RS-232C / RS-422/485	
Baud Rate	4800 / <u>9600</u> / 19200 /38400 / 57600 / 76800 / 115K bps	
Data Length	7 / <u>8</u> bits	
Stop Bit	<u>1</u> / 2 bit	
Parity	None / Odd / <u>Even</u>	

S7

Make the setting for communication using the ladder tool "SIMATIC Manager". For more information, refer to the PLC manual issued by the manufacturer.

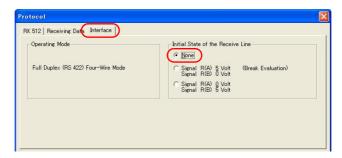
Hardware Configuration ([RK 512] tab window)

Open the [Protocol] dialog and specify the baud rate and the parity, etc. in the [RK 512] tab window.



Hardware Configuration ([Interface] tab window)

Specify "None" for the initial state of the receive line in the [Interface] tab window.



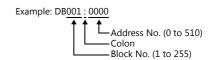
Available Device Memory

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

	Device Memory	TYPE	Remarks
DB	(data block)	00H	*1
I	(input)	01H	IW as word device
Q	(output)	02H	QW as word device
М	(memory word)	03H	MW as word device
T	(timer/current value)	04H	
С	(counter/current value)	05H	

*1 When this device memory is used, a registration is required for the PLC. For more information, refer to the PLC manual issued by the manufacturer. The assigned device memory is expressed as shown on the right when editing the screen.

The address range available on MONITOUCH is DB255:0000 to DB255:0510.



S7-200PPI 9.1.3

Communication Setting

* Only the logical port PLC1 can be selected for S7-200PPI.

Editor

Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1:1/1:n/Multi-link2	
Signal Level	RS-422/485	
Baud Rate	<u>9600</u> / 19200 / 187.5k ^{*1} bps	187.5 kbps can be specified when CN1 is selected for PLC1.
Data Length	8 bits	
Stop Bit	1 bit	
Parity	Even	
Target Port No.	1 to 31 (<u>2</u>)	

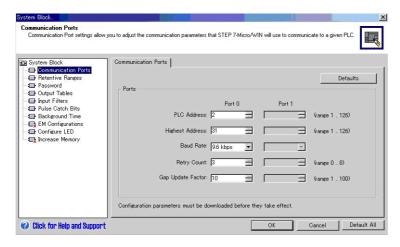
- *1 Notes on communication at the baud rate of 187.5 kbps:
 - The sound play function cannot be used.
 - When performing slave communication via RS-485, set the send delay time of 5 msec or longer.
 - When performing serial communication with another device at PLC2 to PLC8, if only one port is used, 115-kbps communication is available.

When two ports are used at the same time, the maximum baud rate available is 57600 bps for each port.

S7-200

Make the setting for communication using the ladder tool "STEP 7 MicroWIN".

System block



(Underlined setting: default)

Item	Setting	Remarks
PLC Address	1 to 31 (<u>2</u>)	Numbers from 1 to 126 can be specified, however,
Highest Address	1 to <u>31</u>	communication with V9 cannot be established when a number from 32 to 126 is specified.
Baud Rate	<u>9.6k</u> / 19.2k / 187.5 kbps	

The following settings are fixed; data length: 8 bits, stop bit: 1 bit and parity: even.

Available Device Memory

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

	Device Memory	TYPE	Remarks
V	(data memory)	00H	VW as word device
I	(input)	01H	IW as word device, possible to write to the unused area
Q	(output)	02H	QW as word device
М	(bit memory/internal relay)	03H	MW as word device
Т	(timer/current value)	04H	
С	(counter/current value)	05H	
HC	(high-speed counter/current value)	08H	Double-word usable
AIW	(analog input)	09H	
AQW	(analog output)	0AH	
SM	(special memory/special relay)	0BH	SMW as word device
S	(stage)	0CH	SW as word device

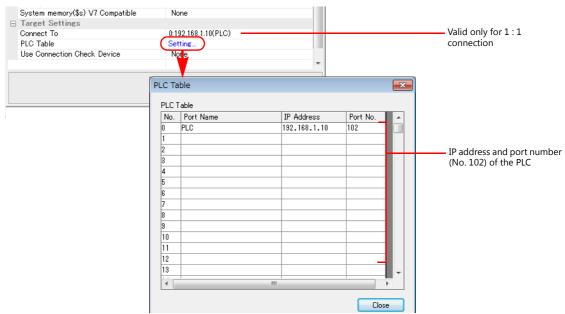
9.1.4 S7-200(Ethernet ISOTCP)

Communication Setting

Editor

Make the following settings on the editor. For more information, see "1.3.2 Ethernet Communication".

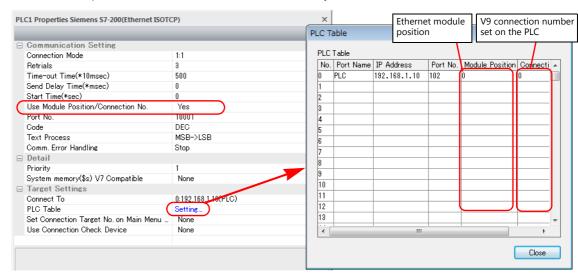
- IP address for the V9 unit
 - When specified on the screen program:
 [System Setting] → [Hardware Setting] → [Local Port IP Address]
 - When specified on the V9 unit: Local mode → [LAN Setting]
- Port number for the V9 unit (for communication with PLC)
 [System Setting] → [Hardware Setting] → [PLC Properties] → [Communication Setting]
- IP address and port number (No. 102) of the PLC
 Register on the [PLC Table] in [System Setting] → [Hardware Setting] → [PLC Properties] → [Target Settings].



Others

 $[System \ Setting] \rightarrow [Hardware \ Setting] \rightarrow [PLC \ Properties] \rightarrow [Communication \ Setting] \rightarrow [Use \ Module \ Position/Connection \ No.]$

- [Yes] (default)
 - Specify the module position and connection number at the [PLC Table] under [Target Settings] on the [PLC Properties] window ([System Setting] \rightarrow [Hardware Setting]).
- Setting range: [Module Position] 0 to 6, [Connection No.] 0 to 7
- [None]
 - The module position and connection number will automatically be retrieved.



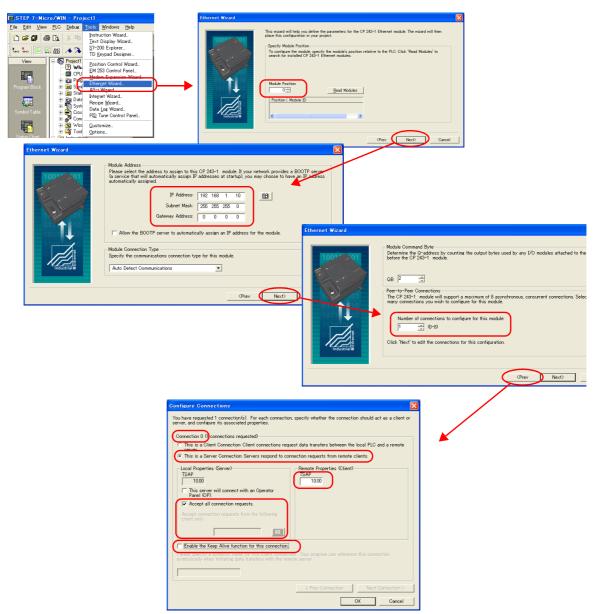
S7-200

Make the following settings in the ladder tool "STEP 7-Micro/WIN".

"ETHO_CTRL" must be executed in the ladder program at each time of scan. For more information, refer to the PLC manual issued by the manufacturer.

Ethernet Wizard

Set the following items including module position, V9 connection number, IP address, and subnet mask according to the instructions in Ethernet Wizard.



	Item	Setting	Remarks
Module Position		0 to 6	Set this value for [Module Position] in V-SFT.
IP Address		Set the IP address of the PLC.	
Subnet Mask		Specify according to the	
Gateway Addre	ess	environment.	
Number of cor	nnections to configure for this module	0 to 8	Number of connecting units
	Connection No.	0 to 7	Automatically displayed according to [Number of connections to configure for this module. Set this value for [Connection No.] in V-SFT.
	This is a Server Connection	Checked	
Configure Connections	Accept all connection requests	Checked	Unchecked: Specify the IP address of V9 for [Accept connection requests from the following client only].
	Enable the Keep Alive function for this connection.	Unchecked	
	Remote Properties (Client) TSAP	10.00	

Calendar

The V series cannot read the calendar data from this PLC. Use the built-in clock of the V series.

Available Device Memory

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

	Device Memory	TYPE	Remarks
V	(data memory)	00H	VW as word device
I	(input)	01H	IW as word device
Q	(output)	02H	QW as word device
М	(bit memory/internal relay)	03H	MW as word device
Т	(timer/current value)	04H	
С	(counter/current value)	05H	

9.1.5 S7-300/400MPI

Communication Setting

* Only the logical port PLC1 can be selected for S7-300/400MPI.

Editor

Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	<u>1:1</u> /1:n	A maximum of four MPI-capable units can be connected.
Signal Level	RS-422/485	
Baud Rate	<u>19200</u> / 187.5k ^{*1} bps	V815/V812/V810/V808: 187.5 kbps can be specified when CN1 is selected for PLC1. V806: 187.5 kbps can be specified when MJ2 is selected for PLC1.
Data Length	8 bits	
Stop Bit	1 bit	
Parity	Even	
Target Port No.	0 to 31 (2)	Specify the MPI station number of S7-300/400.

- *1 Notes on communication at the baud rate of 187.5 kbps:
 - The sound play function cannot be used.
 - When performing slave communication via RS-485, set the send delay time of 5 msec or longer.
 - When performing serial communication with another device at PLC2 to PLC8, if only one port is used, 115-kbps communication is available.

When two ports are used at the same time, the maximum baud rate available is 57600 bps for each port.

MPI setting

(Underlined setting: default)

Item	Setting	Remarks
Highest MPI Address	<u>15</u> / 31 / 63 / 126	Specify the highest address in the MPI network.
Local Port No.	0 to 126 (<u>3</u>)	Specify the port number of V9. It must be a unique number.

S7-300/400MPI

Specify the MPI address and the baud rate using "SIMATIC Manager". For more information, refer to the PLC manual issued by the manufacturer.

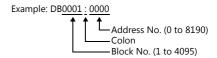
Available Device Memory

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

	Device Memory	TYPE	Remarks
DB	(data block)	00H	*1
I	(input)	01H	IW as word device
Q	(output)	02H	QW as word device
М	(memory word)	03H	MW as word device
T	(timer/current value)	04H	
С	(counter/current value)	05H	

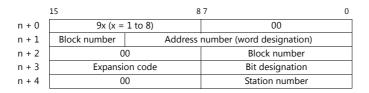
^{*1} When this device memory is used, a registration is required for the PLC. For more information, refer to the PLC manual issued by the manufacturer. The assigned device memory is expressed as shown on the right when editing the screen.

The address range available on MONITOUCH is DB0001:0000 to DB4095:8190.



Indirect Device Memory Designation

• DB device memory



9.1.6 S7-300/400 (Ethernet ISOTCP)

Communication Setting

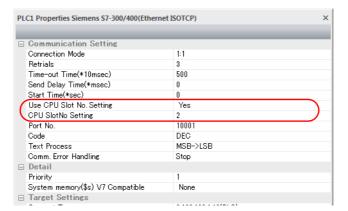
Editor

Make the following settings on the editor. For more information, see "1.3.2 Ethernet Communication".

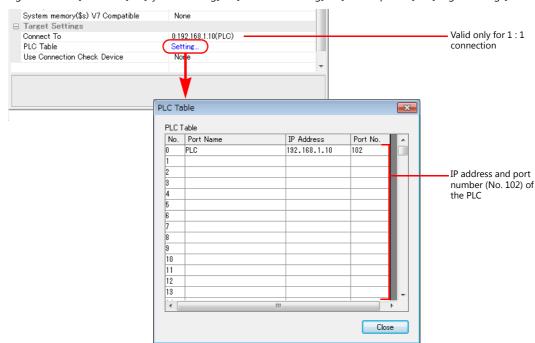
- IP address for the V9 unit
 - When specified on the screen program:
 [System Setting] → [Hardware Setting] → [Local Port IP Address]
 - When specified on the V9 unit: Local mode → [LAN Setting]
- Port number for the V9 unit (for communication with PLC)
 [System Setting] → [Hardware Setting] → [PLC Properties] → [Communication Setting]
- Others
 [System Setting] → [Hardware Setting]

 $[\text{System Setting}] \rightarrow [\text{Hardware Setting}] \rightarrow [\text{PLC Properties}] \rightarrow [\text{Communication Setting}] \rightarrow [\text{Use CPU Slot No. Setting}]$

- Set the slot number. Setting range: 2 to 18
- [None]
 The slot number is automatically retrieved.



IP address and port number (No. 102) of the PLC
 Register on the [PLC Table] in [System Setting] → [Hardware Setting] → [PLC Properties] → [Target Settings].



S7-300/400

Make the communication settings using "SIMATIC Manager". For more information, refer to the PLC manual issued by the manufacturer

Hardware configuration

Specify the IP address on the Ethernet interface PN-IO screen.

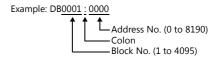
Available Device Memory

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

	Device Memory	TYPE	Remarks
DB	(data block)	00H	*1
I	(input)	01H	IW as word device
Q	(output)	02H	QW as word device
М	(memory word)	03H	MW as word device
Т	(timer/current value)	04H	
С	(counter/current value)	05H	

*1 When this device memory is used, a registration is required for the PLC. For more information, refer to the PLC manual issued by the manufacturer. The assigned device memory is expressed as shown on the right when editing the screen.

The address range available on MONITOUCH is DB0001:0000 to DB4095:8190.



Indirect Device Memory Designation

• DB device memory

	15	8 7			
n + 0	9x (x =	1 to 8)	00		
n + 1	Block number (Lower 4 bits)	Address number (word designation)			
n + 2	0	0	Block number (higher 8 bits)		
n + 3	Expansi	on code	Bit designation		
n + 4	0	0	Station number		

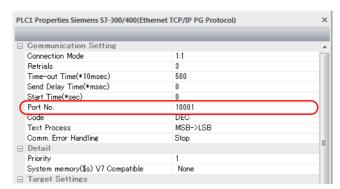
9.1.7 S7-300/400 (Ethernet TCP/IP PG Protocol)

Communication Setting

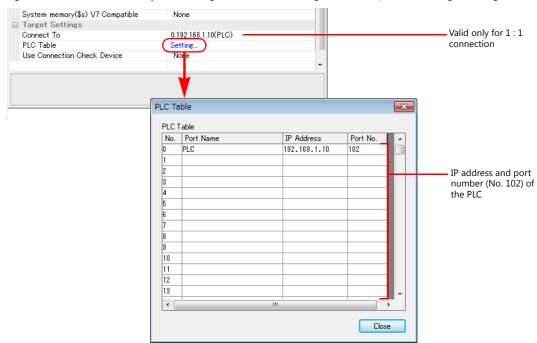
Editor

Make the following settings on the editor. For more information, see "1.3.2 Ethernet Communication".

- IP address for the V9 unit
 - When specified on the screen program:
 [System Setting] → [Hardware Setting] → [Local Port IP Address]
 - When specified on the V9 unit: Local mode → [LAN Setting]
- Port number for the V9 unit (for communication with PLC)
 [System Setting] → [Hardware Setting] → [PLC Properties] → [Communication Setting]



IP address and port number (No. 102) of the PLC
 Register on the [PLC Table] in [System Setting] → [Hardware Setting] → [PLC Properties] → [Target Settings].



Others
 [System Setting] → [Hardware Setting] → [PLC Properties] → [Communication Setting] → [Protection]
 If the protection function is used on STEP7, set a password. Otherwise, a communication error will occur.



S7-300/400

Make the communication settings using "SIMATIC Manager". For more information, refer to the PLC manual issued by the manufacturer

Hardware configuration

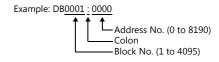
Specify the IP address on the Ethernet interface PN-IO screen.

Available Device Memory

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

	Device Memory	TYPE	Remarks
DB	(data block)	00H	*1
I	(input)	01H	IW as word device
Q	(output)	02H	QW as word device
М	(memory word)	03H	MW as word device
T	(timer/current value)	04H	
С	(counter/current value)	05H	

When this device memory is used, a registration is required for the PLC. For more information, refer to the PLC manual issued by the manufacturer. The assigned device memory is expressed as shown on the right when editing the screen.



The address range available on MONITOUCH is DB0001:0000 to DB4095:8190.

Indirect Device Memory Designation

• DB device memory

	15 8		7 0
n + 0	9x (x = 1 to 8)		00
n + 1	Block number (Lower 4 bits)	Add	ress number (word designation)
n + 2	00		Block number (higher 8 bits)
n + 3	Expansion code		Bit designation
n + 4	00		Station number

9.1.8 **S7-1200** (Ethernet ISOTCP)

Communication Setting

Editor

Make the following settings on the editor. For more information, see "1.3.2 Ethernet Communication".

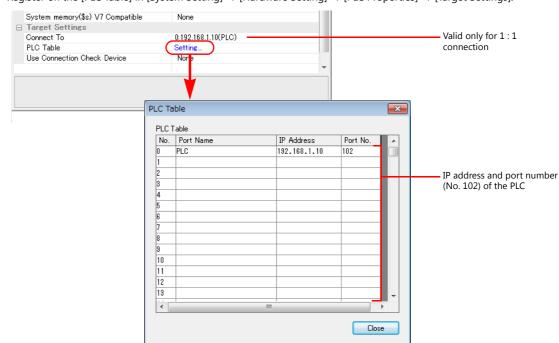
- IP address for the V9 unit
 - When specified on the screen program:
 [System Setting] → [Hardware Setting] → [Local Port IP Address]
 - When specified on the V9 unit: Local mode → [LAN Setting]
- Port number for the V9 unit (for communication with PLC)
 [System Setting] → [Hardware Setting] → [PLC Properties] → [Communication Setting]
- Others

 $[\text{System Setting}] \rightarrow [\text{Hardware Setting}] \rightarrow [\text{PLC Properties}] \rightarrow [\text{Communication Setting}] \rightarrow [\text{Use CPU Slot No. Setting}]$

- [Yes]
 Set the slot number. Setting range: 2 to 18
- [None]
 The slot number is automatically retrieved.

□ Communication Setting Connection Mode Retrials Time-out Time(*10msec) 500 Send Delay Time(*msec) Start Time(*sec)
Use CPU Slot No. Setting Yes CPU SlotNo Setting Port No. 10001 Code DEC Text Process MSB->LSB Comm. Error Handling Stop ■ Detail Priority System memory(\$s) V7 Compatible None ■ Target Settings

• IP address and port number (No. 102) of the PLC
Register on the [PLC Table] in [System Setting] → [Hardware Setting] → [PLC Properties] → [Target Settings].

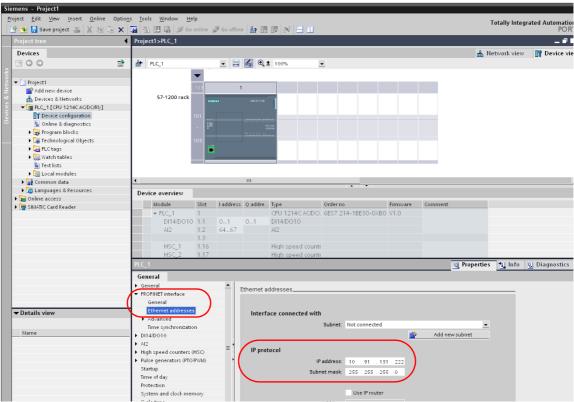


S7-1200

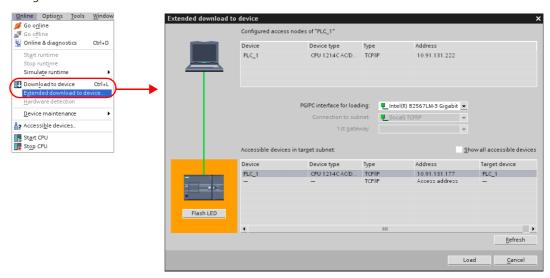
Make the settings using "Totally Integrated Automation Portal V10" dedicated to S7-1200. For more information, refer to the PLC manual issued by the manufacturer.

IP address setting

- 1. Select "PLC_1" in [Network view] or [Device view] in the project.
- 2. Set the IP address in [Ethernet addresses] ([Properties] → [PROFINET interface]).

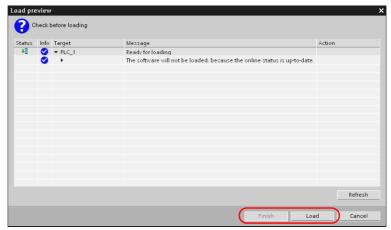


3. Click [Online] → [Download to device] or [Extended Download to device] to display the [Extended download to device] dialog.



4. Select [Access Address] and click [Load].

5. The [Load preview] screen is displayed. Click [Load].

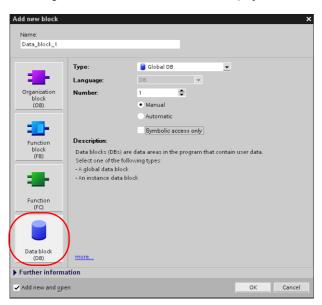


6. Click [Finish]. The IP address setting has been completed.

DB area setting

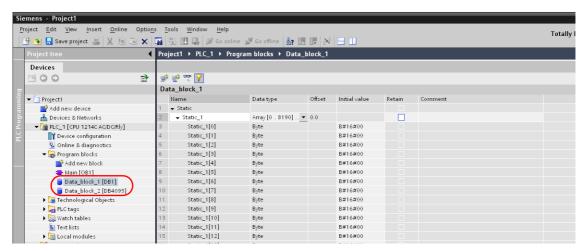
The following settings are required to use the DB device memory.

1. Select [Program blocks] \rightarrow [Add new block] in the project, and make the following settings.



Item		Setting	
	Number	Set the block number in the range from 1 to 4095.	
Data block	Manual / Automatic	Manual	
	Symbolic access only	Unchecked	

2. The newly created data block is added under [Program blocks] in the project.



• When specifying the byte address in the array format:Select "Array [lo..hi] of type" for "Data type" and enter "lo", "hi" and "type" (byte).

Range of "lo" and "hi": 0 to 8190

Example: Array [0..1024] of type

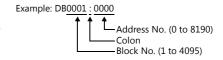
3. From the right-click menu of [Project tree], select [Download to device] \rightarrow [software] to write the settings into the PLC.

Available Device Memory

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

	Device Memory	TYPE	Remarks
DB	(data block)	00H	*1
I	(input)	01H	IW as word device
Q	(output)	02H	QW as word device
М	(memory word)	03H	MW as word device

*1 When this device memory is used, a registration is required for the PLC. For more information, refer to the PLC manual issued by the manufacturer. The assigned device memory is expressed as shown on the right when editing the screen. The address range available on MONITOUCH is DB0001:0000 to DB4095:8190.



Indirect Device Memory Designation

• DB device memory

	15	8	7 0			
n + 0	9x (x =	1 to 8)	00			
n + 1	Block No. (lower 4 bits)	Address No. (word designation)				
n + 2	0	0	Block No. (higher 8 bits)			
n + 3	Expansi	on code	Bit designation			
n + 4	00		Station number			

9.1.9 TI500 / 505 Series

Communication Setting

Editor

Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode 1:1/1:n/Multi-link2/ Multi-link2 (Ethernet)/ 1:n Multi-link2 (Ethernet)		
Signal Level <u>RS-232C</u> / RS-422/485		
Baud Rate 9600 / <u>19200</u> / 38400 / 57600 / 115200 bps		
Data Length 7 / 8 bits		
Stop Bit 1 / 2 bits		
Parity None / Odd / Even		
Target Port No.	0 to 31	

PLC

TI545/TI555

Item	No.						Remarks
ON ← OFF	1	Port 2 signal level	ON: RS-232C / RS-422 OFF: RS-485			Only RS-232C supported by 555-1103CPU	
1	6		Baud Rate	6	7	0	1
ω 💶	_			-	/	8	
4		115200 *	ON	ON	OFF		
σ =			57600 *	ON	OFF	ON	*Supported by
6 1		Port 2 Baud rate	38400	ON	OFF	OFF	555-1105CPU and 555-1106CPU only
∞ 🔳	8		19200	ON	ON	ON]
9 🔳	9 10		9600	OFF	ON	ON	
				•			_

TI575

Item	Setting	Remarks
Baud rate	9600	
Data length	7 bits	
Parity	Odd	
Stop bit	1 bit	

Available Device Memory

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

	Device Memory	TYPE	Remarks
V	(variable memory)	00H	
WX	(word input)	01H	
WY	(word output)	02H	
Χ	(discrete input)	03H	
Υ	(discrete output)	04H	
CR	(control relay)	05H	
TCP	(timer, counter/set value)	06H	
TCC	(timer, counter/current value)	07H	
DCP	(drum count/set value)	08H	
DCC	(drum count/current value)	09H	Read only
DSP	(drum step/set value)	0AH	
DSC	(drum step/current value)	0BH	
K	(constant memory)	0CH	
STW	(system status)	0DH	

Indirect Device Memory Designation

	15 8	7 0
n+0	Model	Device type
n+1	Address No. (wo	ord designation)
n+2	Expansion code	Bit designation
n+3	00	Station number

- For the device memory address number, specify the value obtained by subtracting "1" from the actual address.
- For the designation of a DCC device memory, specify a drum step number minus "1" for the expansion code.

9.1.10 Wiring Diagrams

We recommend the following cable and the connectors for cable configuration. For more information, refer to related documents issued by Siemens.

• Recommended cable

Manufacturer	Model
Siemens	6XV1 830-0EH10

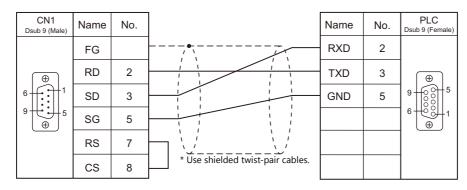
• Recommended connector

Manufacturer	Model	Remarks		
	6ES7 972-0BA50-0XA0		For vertical wiring	Without PG I/F
	6ES7 972-0BB50-0XA0	Fast Connect	90-degree angle of outgoing cable	With PG I/F
Siemens	6ES7 972-0BA60-0XA0		For vertical wiring	Without PG I/F
	6ES7 972-0BB60-0XA0		35-degree angle of outgoing cable	With PG I/F
	6GK1 500-0FC00		For horizontal wiring	-

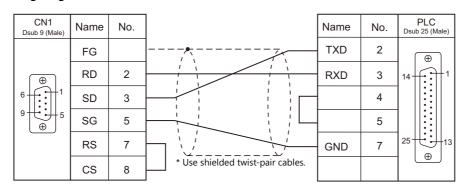
When Connected at CN1:

RS-232C

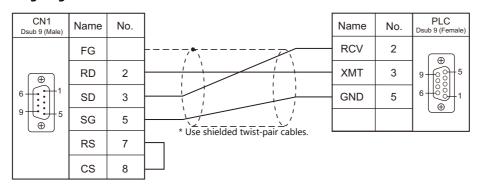
Wiring diagram 1 - C2



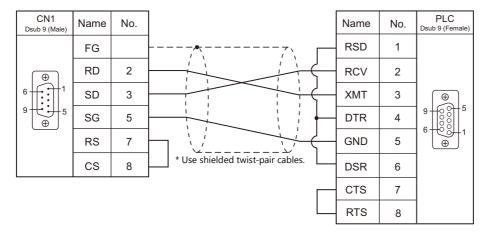
Wiring diagram 2 - C2



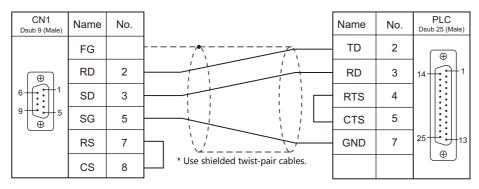
Wiring diagram 3 - C2



Wiring diagram 4 - C2

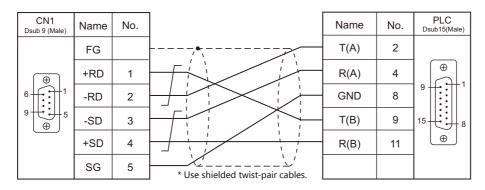


Wiring diagram 5 - C2



RS-422/RS-485

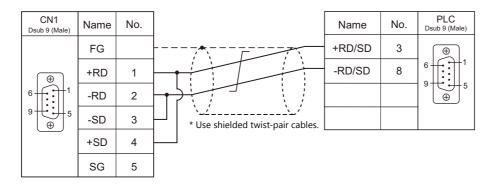
Wiring diagram 1 - C4



Wiring diagram 2 - C4

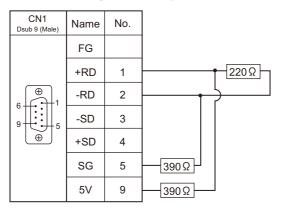
Terminating resistance

Set DIP switches 5 and 7^{*1} of the V9 unit to the OFF position, and set the terminating resistance by referring to "Terminating resistance setting" described below.

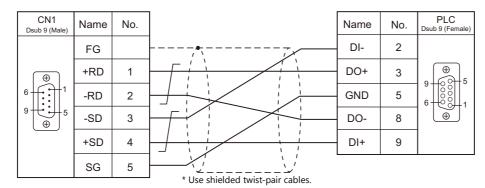


Terminating resistance setting

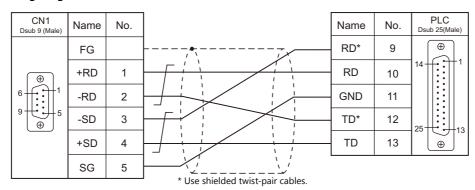
Set the DIP switch of the V9 unit to the OFF position and connect the terminating resistance to CN1 as shown below. The absence of terminating resistance may result in communication failure.



Wiring diagram 3 - C4



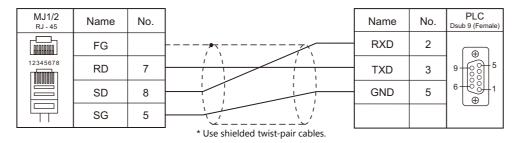
Wiring diagram 4 - C4



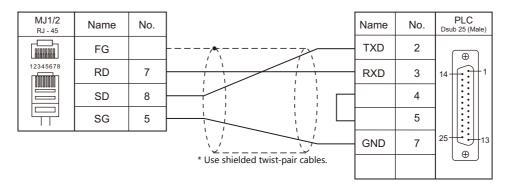
When Connected at MJ1/MJ2:

RS-232C

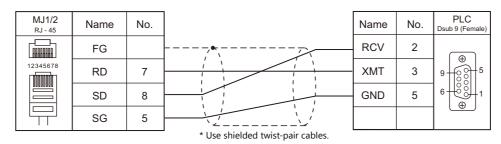
Wiring diagram 1 - M2



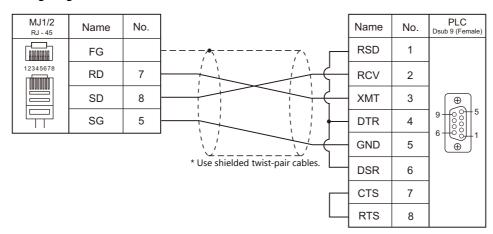
Wiring diagram 2 - M2



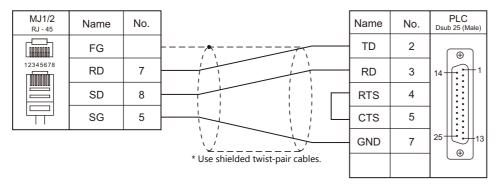
Wiring diagram 3 - M2



Wiring diagram 4 - M2



Wiring diagram 5 - M2



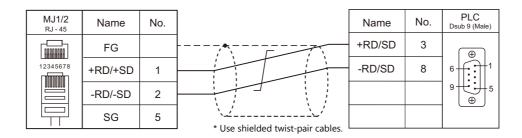
RS-422/RS-485

Wiring diagram 1 - M4

Terminating resistance

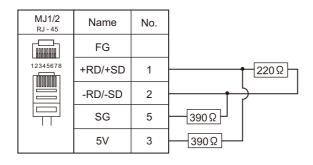
Set the DIP switch of the V9 unit to the OFF position, and set the terminating resistance by referring to "Terminating resistance setting" described below.

- MJ1: DIP switch 6
- MJ2: DIP switch 8

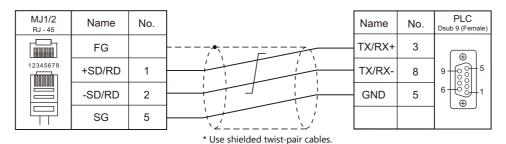


Terminating resistance setting

Set the DIP switch of the V-series unit to the OFF position and connect the terminating resistance to MJ as shown below. The absence of terminating resistance may result in communication failure.



Wiring diagram 2 - M4



10. SINFONIA TECHNOLOGY

10.1 PLC Connection

10.1 PLC Connection

Serial Connection

PLC Selection on the	СРИ	Unit/Port Signal Le	Signal Loyal	Conne	ection	Ladder
Editor			Signal Level	CN1	MJ1/MJ2	Transfer*1
SELMART	SELMART-100 and later	01M2-UCI-6x 01M2-UCI-Ax	RS-232C	Wiring diagram 1 - C2	Wiring diagram 1 - M2	×

^{*1} For the ladder transfer function, see the V9 Series Reference Manual.

10.1.1 SELMART

Communication Setting

Editor

Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1:1/1:n/Multi-link/Multi-link2/ Multi-link2 (Ethernet)/1:n Multi-link2 (Ethernet)	
Signal Level	<u>RS-232C</u> / RS-422/485	
Baud Rate	4800 / 9600 / <u>19200</u> bps	
Data Length <u>7</u> bits		
Stop Bit	<u>1</u> bit	
Parity	<u>Even</u>	
Target Port No.	1 to 8	Set the same number as the one set by the DEV. NO. switch on the PLC.

PLC

An application program is necessary on the PLC to communicate with the V series. For more information, refer to the specifications sheet of the PLC.

01M2-UCI-6x

DEV. NO. switch

SW	Setting	Remarks
DEV. NO.	1 to 8	

SELMART SUPPORT SYSTEM

Set desired values for internal addresses in the PLC. For more information, refer to the specifications sheet of the PLC.

Ado	dress	Item	Setting	Remarks
C4096 to C4111		Card usage status	X22X (HEX) 1 to 8: DEV. NO. 0: Used 1 to F: Not used	The standard entry table is used. When using an expanded entry table, refer to the specifications sheet of the PLC.
DEV. NO. 1	C4333	Baud rate	4800 / 9600 / 19200	
DEV. NO. 1	C4334	Communication mode	0: GD-80	
DEV. NO. 2	C4341	Baud rate	4800 / 9600 / 19200	
DEV. NO. 2	C4342	Communication mode	0: GD-80	
DEV/ NO. 3	C4349	Baud rate	4800 / 9600 / 19200	
DEV. NO. 3	C4350	Communication mode	0: GD-80	The standard entry table is used.
DEV. NO. 4	C4357	Baud rate	4800 / 9600 / 19200	When using an expanded entry table,
DEV. NO. 4	C4358	Communication mode	0: GD-80	refer to the specifications sheet of the
DEV. NO. 5	C4365	Baud rate	4800 / 9600 / 19200	PLC.
DEV. NO. 5	C4366	Communication mode	0: GD-80	Set the address set by the DEV. NO.
DEV/ NO. 6	C4373	Baud rate	4800 / 9600 / 19200	switch.
DEV. NO. 6	C4374	Communication mode	0: GD-80	
DEL / NO. 7	C4381	Baud rate	4800 / 9600 / 19200	
DEV. NO. 7	C4382	Communication mode	0: GD-80	
DEV. NO. 8	C4389	Baud rate	4800 / 9600 / 19200	
DEV. NO. 8	C4390	Communication mode	0: GD-80	

The following settings are fixed; data length: 7 bits, stop bit: 1 bit and parity: even. Changes take effect when the power is turned off and on again.

* Be sure to set "mode 0" for the CPU card operation mode.

Calendar

This model is equipped with the calendar function; however, the calendar data cannot be written from the V series. Thus, time correction must be performed on the PLC side.

01M2-UCI-Ax

DEV. NO. switch (station number)

SW	Setting	Remarks
DEV. NO.	1 to 8	

UC1-HL switch (unit communication function setting)

SW	Setting	Remarks
Н	6	UC1-6X (communication for touch panel)
L	0, 1 / 2 / F	OCI-OX (COMMUNICATION TO LOUCH Panel)

SELMART SUPPORT SYSTEM

Set desired values for internal addresses in the PLC. For more information, refer to the specifications sheet of the PLC.

Ad	dress	Item	Setting	Remarks
C4096 to C4111		Card usage status	X22X (HEX) 1 to 8: DEV. NO. 0: Used 1 to F: Not used	The standard entry table is used. When using an expanded entry table, refer to the specifications sheet of the PLC.
DEV. NO. 1	C4333	Baud rate	4800 / 9600 / 19200	
DEV. NO. 1	C4334	Communication mode	0: GD-80	
DEV. NO. 2	C4341	Baud rate	4800 / 9600 / 19200	
DEV. NO. 2	C4342	Communication mode	0: GD-80	
DEV. NO. 3	C4349	Baud rate	4800 / 9600 / 19200	
DEV. NO. 3	C4350	Communication mode	0: GD-80	The standard entry table is used.
DEV. NO. 4	C4357	Baud rate	4800 / 9600 / 19200	When using an expanded entry table,
DEV. NO. 4	C4358	Communication mode	0: GD-80	refer to the specifications sheet of the
DEV. NO. 5	C4365	Baud rate	4800 / 9600 / 19200	PLC.
DEV. NO. 5	C4366	Communication mode	0: GD-80	Set the address set by the DEV. NO.
DEV. NO. 6	C4373	Baud rate	4800 / 9600 / 19200	switch.
DEV. NO. 6	C4374	Communication mode	0: GD-80	
DEV. NO. 7	C4381	Baud rate	4800 / 9600 / 19200	
DEV. NO. /	C4382	Communication mode	0: GD-80	
DEV NO 9	C4389	Baud rate	4800 / 9600 / 19200	
DEV. NO. 8	C4390	Communication mode	0: GD-80	

The following settings are fixed; data length: 7 bits, stop bit: 1 bit and parity: even. Changes take effect when the power is turned off and on again.

Calendar

This model is equipped with a calendar function; however, the calendar data cannot be written from the V series. Thus, time correction must be performed on the PLC side.

Available Device Memory

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

	Device Memory		Remarks
ſ	D (data register)	00H	D0 to D1023

^{*} Addresses other than D0 to D1023 can be set on the editor; however it cannot be used actually. If such a address is set, an error code "06" occurs. Do not specify any addresses other than D0 to D1023.

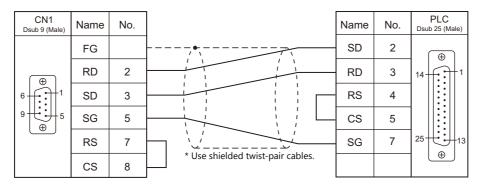
^{*} Be sure to set "mode 0" for the CPU card operation mode.

10.1.2 Wiring Diagrams

When Connected at CN1:

RS-232C

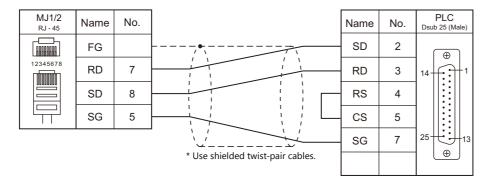
Wiring diagram 1 - C2



When Connected at MJ1/MJ2:

RS-232C

Wiring diagram 1 - M2



11. TECO

11.1 PLC Connection

11.1 PLC Connection

Serial Connection

PLC Selection on the	CPU	Unit/Port	Signal Level	Conne	ection	Ladder	
Editor	CPU	Unit/Port	Signal Level	CN1	MJ1/MJ2	Transfer *1	
	TP03-xxSx-x TP03-xxMx-x	PC / PDA port	RS-232C	TECO TP-302PC + Gender changer ^{*2}	TECO TP-302PC + Wiring diagram 1 - M2		
	1		RS-422	Wiring diagram 2 - C4	×		
TP03		Expansion card	RS-485	Wiring diagram 1 - C4	Wiring diagram 1 - M4		
(MODBUS RTU)	TP03-xxHx-x	PC/PDA port	RS-232C	TECO TP-302PC + Gender changer ^{*2}	TECO TP-302PC + Wiring diagram 1 - M2	×	
			RS-422	Wiring diagram 2 - C4	×		
			RS-485 port Expansion card	RS-485	Wiring diagram 1 - C4	Wiring diagram 1 - M4	

^{*1} For the ladder transfer function, see the V9 Series Reference Manual.
*2 Use a D-sub gender changer (9-pin, female-to-male) commercially available.

Manufacturer	Model
BLACK BOX	FA440-R2
MISUMI	DGC-9PP

11.1.1 TP03 (MODBUS RTU)

Communication Setting

Editor

Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1:1/1:n/Multi-link2/Multi-link2(Ethernet)/ 1:n Multi-link2(Ethernet)	
Signal Level	RS-232C / RS-422/485	
Baud Rate	4800 / 9600 / <u>19200</u> / 38400 / 57600 76800 bps	
Data Length	8 bits	
Stop Bit	1 / <u>2</u> bits	
Parity	Odd / Even /None	
Target Port No.	<u>1</u> to 31	

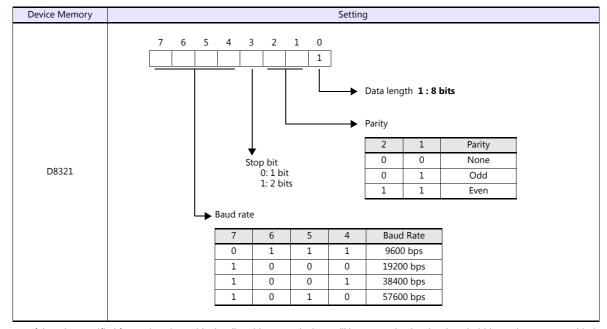
PLC

Be sure to match the settings to those made under [Communication Setting] of the editor.

Set a port number in the communication software. For more information, refer to the PLC manual issued by the manufacturer.

PC/PDA Port

Use bits 0 to 7 at D8321 for the following settings.



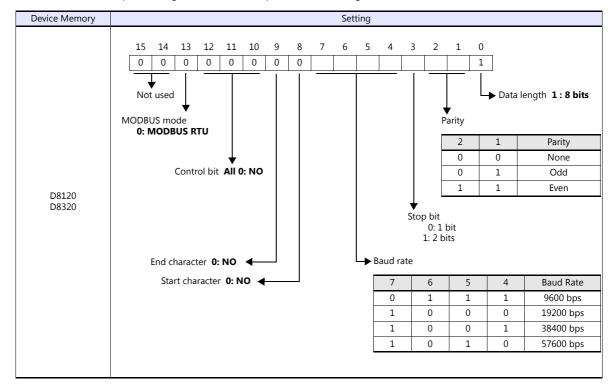
If the value specified for any item is outside the allowable range, the item will be assumed to be: data length: 8 bits, parity: none, stop bit: 2 bits, or baud rate: 19200 bps.

Calendar

This model is not equipped with the calendar function. Use the built-in clock of the V series.

RS-485 Port / Expansion Card

Use D8120 for RS-485 port settings and D8320 for expansion card settings.



Calendar

This model is not equipped with the calendar function. Use the built-in clock of the V series.

Available Device Memory

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

	Device Memory	TYPE	Remarks
D	(Data register)	00H	
Х	(Digital I relay)	01H	
Υ	(Digital O relay)	02H	
М	(Auxiliary relay)	03H	
CC	(Counter [Coil])	04H	
TC	(Timer [Coil])	05H	
С	(Counter [Current value])	06H	
Т	(Timer [Current value])	07H	
CP	(Counter [Preset value])	08H	
TP	(Timer [Preset value])	09H	

Indirect Device Memory Designation

15	5 8	7 0		
n+0	Model	Device type		
n+1	Addre	Address No.		
n+2	Expansion code	Bit designation		
n+3	00	Station number		

• For X/Y device memory

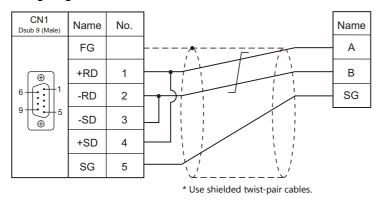
Assign an actual address number (OCT) converted to HEX as the address number.

11.1.2 Wiring Diagrams

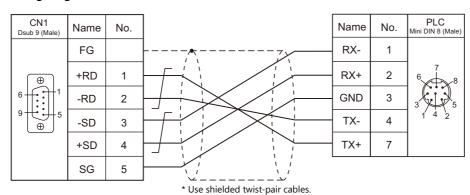
When Connected at CN1:

RS-422/RS-485

Wiring diagram 1 - C4



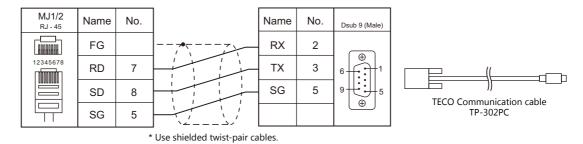
Wiring diagram 2 - C4



When Connected at MJ1/MJ2:

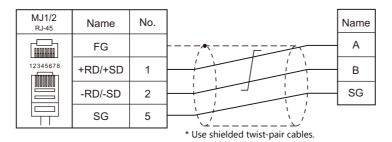
RS-232C

Wiring diagram 1 - M2



RS-422/RS-485

Wiring diagram 1 - M4



MEMO	
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12. Telemecanique

12.1 PLC Connection

12.1 PLC Connection

Serial Connection

PLC Selection on the	CPU	Unit/Port	Signal Level	Cianal Laval	Signal Loyal	Signal Lovel	Connection Connection		Ladder
Editor	CFU	Offit/Fort	Signal Level	CN1	MJ1/MJ2	Transfer *1			
TSX Micro	TSX37-xx TSX57-xx	TER AUX	RS-485	Wiring diagram 1 - C4	Wiring diagram 1 - M4	×			

^{*1} For the ladder transfer function, see the V9 Series Reference Manual.

12.1.1 TSX Micro

Communication Setting

Editor

Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	Multi-link	PLC1 to PLC8 valid Local port Nos. 1 to 8 valid (4 as default)
Signal Level	RS-422/485	
Baud Rate	9600 bps	
Data Length	<u>8</u> bits	
Stop Bit	<u>1</u> bit	
Parity	None / <u>Odd</u> / Even	

PLC

TER / AUX Port

Make PLC settings using the application software "PL7 Junior". For more information, refer to the PLC manual issued by the manufacturer.

Item	Setting	Remarks
CHANNEL 0:	UNI-TELWAY LINK	
Transmission speed	9600 bits/s	
Parity	Even / Odd / None	

Available Device Memory

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

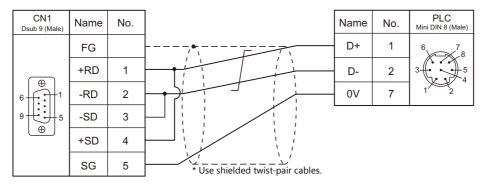
	Device Memory	TYPE	Remarks
MW	(Memory Word)	00H	
KW	(Constant Word)	01H	Read only
М	(Bit Memory)	02H	

12.1.2 Wiring Diagrams

When Connected at CN1:

RS-422/RS-485

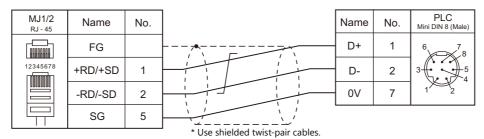
Wiring diagram 1 - C4



When Connected at MJ1/MJ2:

RS-232C

Wiring diagram 1 - M4



MEMO
Please use this page freely.
Please use this page freely.

13. TOHO

13.1 Temperature Controller/Servo/Inverter Connection

13.1 Temperature Controller/Servo/Inverter Connection

Digital Temperature Controller

PLC Selection on the	Mandal	Downt	Cianal Laure	Connection		Lst File	
Editor	Model	Port	Signal Level	CN1	MJ1/MJ2	LSt File	
	TTM-002-x-x-AM		al block RS-485	Wiring diagram 5 - C4	Wiring diagram 5 - M4		
	TTM-004-x-x-AM TTM-004S-x-x-AX TTM-X04-x-x-AM TTM-X04S-x-x-AX			Wiring diagram 6 - C4	Wiring diagram 6 - M4	TTM-000.Lst	
TTM-000	TTM-005-x-x-AM TTM-005S-x-x-AX TTM-006-x-x-AM TTM-006S-x-x-AX TTM-009-x-x-AM TTM-009S-x-X-AX	Terminal block		Wiring diagram 2 - C4	Wiring diagram 2 - M4		
	TTM-007-x-x-AM TTM-007S-x-x-AX			Wiring diagram 7 - C4	Wiring diagram 7 - M4		
TTM-00BT	TTM-00BT-0-R-M1 TTM-00BT-1-R-M1	TB3	RS-485	Wiring diagram 1 - C4	Wiring diagram 1 - M4	TTM-00BT.Lst	
11101-0001	TTM-00BT-0-R-M2 TTM-00BT-1-R-M2	0-R-M2	RS-232C	Wiring diagram 1 - C2	Wiring diagram 1 - M2	TTIVI-OODI.EST	
	TTM-204			Wiring diagram 2 - C4	Wiring diagram 2 - M4		
TTM-200 (MODBUS RTU)	TTM-205 TTM-209	Terminal block	RS-485	ninal block RS-485	Wiring diagram 3 - C4	Wiring diagram 3 - M4	TD_TTM200.Lst
	TTM-207			Wiring diagram 4 - C4	Wiring diagram 4 - M4		

13.1.1 TTM-000

Communication Setting

Editor

Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1 : 1 / <u>1 : n</u> / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet)	
Signal Level	RS-422/485	
Baud Rate	4800 / <u>9600</u> / 19200 bps	
Data Length	7 / <u>8</u> bits	
Stop Bit	1 / <u>2</u> bits	
Parity	None / Odd / Even	
Target Port No.	1 to 32	
BCC Check	Without BCC / With BCC	

Digital Temperature Controller

Communication setting

Make the communication settings in the communication setting mode (SET6) that is selected by the key on the front of the digital temperature controller.

(Underlined setting: default)

Communication Setting	Item	Contents	Setting Example
_P-E	Communication protocol	0: TOHO communication protocol * Not necessary for TTM-xxx-x-x-AxxM	0
_EaN	Communication parameter	1: Stop bit 1 2: Stop bit 2 n: No parity o: Odd parity E: Even parity 7: Data length 7 bits 8: Data length 8 bits n: Without BCC check b: With BCC check	b8n2
_ <i>6</i> 25	Communication setting	4.8: 4800 bps 9.6: 9600 bps 19.2: 19200 bps	9.6
_Rdr	Communication address	<u>1</u> to 32	1
_88E	Response delay time	<u>0</u> to 255 (ms)	0
_Nod	Communication mode selection	ro: Read only rw: Read/write	rw

Available Device Memory

The available setting range of device memory varies depending on the model. Be sure to set within the range available for the model to be used. Use [TYPE] when assigning indirect device memory for macro programs.

	Device Memory	TYPE	Remarks
MW	(monitor data)	00H	
SW	(setting data)	01H	Always set "0" for SW00137 (communication protocol setting).
ST	(character string data)	02H	6-byte character string data

Read-only device memory

The following types of device memory are read-only.

Device Memory	Name	Remarks
MW00000	Measurement value (PV)	When the measurement value exceeds the upper limit, "32767" is displayed. When it falls below the lower limit, "-32768" is displayed.
MW00003	Output status monitoring	
MW00005	DI status monitoring	
SW00041	Input monitoring for event output 1CT	
SW00050	Input monitoring for event output 2CT	
SW00064	Monitoring for remaining time on timer	
ST00000	Measurement value (PV1)	

Write-only device memory

The following type of device memory is write-only.

Device Memory	Name	Remarks
MW00002	Timer start / stop	

Indirect Device Memory Designation

Specify the value obtained by subtracting "1" from the actual station number.

PLC_CTL

Macro command "PLC_CTL F0 F1 F2"

Contents	F0		F1 (= \$u n)		
Data save	1 - 8	n	Station numbers 0 to 31*	2	
Data save	(PLC1 - 8)	n + 1	Command: 0	2	

^{*} Specify the value obtained by subtracting "1" from the actual station number.

13.1.2 TTM-00BT

Communication Setting

Editor

Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1:1/1:n/Multi-link2/Multi-link2(Ethernet)/ 1:n Multi-link2(Ethernet)	
Signal Level	RS-232C / RS-422/485	
Baud Rate	4800 / <u>9600</u> / 19200 / 38400 bps	
Data Length	8 bits	
Stop Bit	2 bits	
Parity	None	
Target Port No.	0 to 15	

Digital Temperature Controller

Settings related to communications can be made using switches on the controller. Before changing a setting, be sure to turn off the power to the digital temperature controller.

Unit number (station number)

(Underlined setting: default)

SW1	Contents	Setting Example
1,3 4 5 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 to F (H) (0 to 15)	0

Baud rate

(Underlined setting: default)

SW2	Contents						Setting Example
ON ON	DIP Switch	4800 bps	9600 bps	19200 bps	38400 bps		1: ON 2: OFF
	1	OFF	<u>ON</u>	OFF	ON		3: OFF 4: OFF
1 2 3 4	2	OFF	<u>OFF</u>	ON	ON		
1 2 3 4	3		OFF (N	ot used)			Baud rate: 9600 bps
	4		OFF (N	ot used)			bada rate. 5000 bps

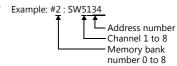
The following settings are fixed; data length: 8 bits, stop bit: 2 bits, and parity: none.

Available Device Memory

The available setting range of device memory varies depending on the model. Be sure to set within the range available for the model to be used. Use [TYPE] when assigning indirect device memory for macro programs.

	Device Memory	TYPE	Remarks
MW	(monitor data)	00H	
SW	(setting data)	01H	

The memory bank number (0 to 8) and channel number (1 to 8) are required in addition to the device type and address. The assigned device memory is expressed as shown on the right when editing the screen.



Address denotations

- To specify the memory bank currently in use, set "0" for the memory bank number. When specifying other memory banks, set the corresponding numbers.
- On the signal name reference list, every channel is designated as "0". Manually input the number (1 to 8) of the channel to

Read-only device memory

The following types of device memory are read-only.

Device Memory	Name	Remarks
MW000	Measurement value (PV1)	*1
MW003	Control output monitor (OM1)	
SW041	CT measurement value 1 (CM1)	*2
SW050	CT measurement value 2 (CM2)	*2
SW083	CT measurement value 3 (CM3)	*2
SW092	CT measurement value 4 (CM4)	*2
SW101	CT measurement value 5 (CM5)	*2
SW110	CT measurement value 6 (CM6)	*2
SW119	CT measurement value 7 (CM7)	*2
SW130	DI monitor (DIM)	
SW131	Event output monitor 1 to 5 (EMI)	
SW132	Event output monitor 6 to 8 (EM2)	
SW133	Alarm monitor (ALM)	

- When the measurement value exceeds the upper limit, "32767" is displayed. When it falls below the lower limit, "-32768" is displayed. When the measurement value exceeds the upper limit, "32767" is displayed. When it falls below the lower limit or measurement is impossible, "-32768" is displayed.

Indirect Device Memory Designation

15	8	7 0
n + 0	Model	Device type
n + 1	Addre	ess No.
n + 2	Bank No.	Bit designation
n + 3	00	Station number

 Specify the channel number (1 to 8) and address for the device memory number (address). Channel 5, address 134: Example:

Specify "5134" (DEC) for the device memory number (address).

PLC_CTL

Macro command "PLC_CTL F0 F1 F2"

Contents	F0		F2	
Data save	1 - 8 (PLC1 - 8)	n	Station number	
		n + 1	Command: 0	3
		n + 2	Channel (1 - 8)	

13.1.3 TTM-200 (MODBUS RTU)

Communication Setting

Editor

Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1:1/1:n/Multi-link2/Multi-link2(Ethernet)/ 1:n Multi-link2(Ethernet)	
Signal Level	RS-422/485	
Baud Rate	4800 / <u>9600</u> / 19200 / 38400 bps	
Data Length	8 bits	
Stop Bit	1 / <u>2</u> bits	
Parity	None / Odd / Even	
Target Port No.	1 to 31	

Digital Temperature Controller

Communication setting

Make the communication settings in the communication setting mode (SET17) that is selected by the key on the front of the digital temperature controller.

(Underlined setting: default)

Communication Setting	Item	Contents	Setting Example
PRŁ	Communication protocol *1	1: MODBUS RTU	1
[oM	Communication parameter	8N1: data length 8, without parity, stop bit 1 8N2: data length 8, without parity, stop bit 2 801: data length 8, odd parity, stop bit 1 802: data length 8, odd parity, stop bit 2 8E1: data length 8, even parity, stop bit 1 8E2: data length 8, even parity, stop bit 2	8N2
ЬPS	Communication setting	4.8: 4800 bps <u>9.6: 9600 bps</u> 19.2: 19200 bps 38.4: 38400 bps	9.6
RdR	Communication address	1 to 31	1
RWF	Communication response delay time	<u>0</u> to 255 (ms)	0
Mod	Communication switching	O: Writing prohibited 1: Writing enabled 2: Master of simultaneous rise in temperature 3: Slave of simultaneous rise in temperature	1

^{*1} Select "Modbus RTU" for the communication protocol on the digital temperature controller when connecting with the V9.

Available Device Memory

The available setting range of device memory varies depending on the model. Be sure to set within the range available for the model to be used. Use [TYPE] when assigning indirect device memory for macro programs.

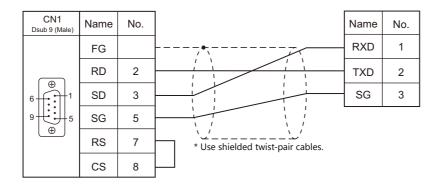
	Device Memory	TYPE	Remarks
4	(holding register)	00H	No address of even-numbered digits can be specified.

13.1.4 Wiring Diagrams

When Connected at CN1:

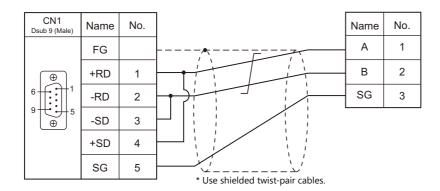
RS-232C

Wiring diagram 1 - C2

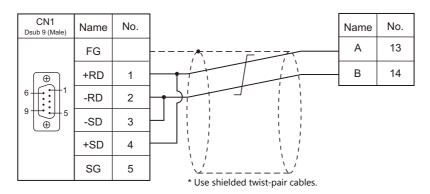


RS-422/RS-485

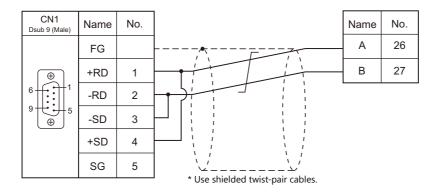
Wiring diagram 1 - C4



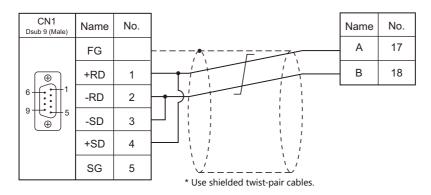
Wiring diagram 2 - C4



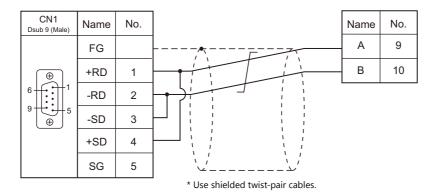
Wiring diagram 3 - C4



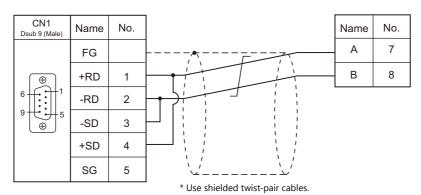
Wiring diagram 4 - C4



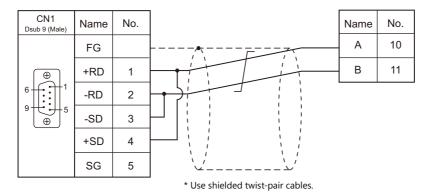
Wiring diagram 5 - C4



Wiring diagram 6 - C4



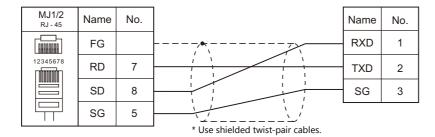
Wiring diagram 7 - C4



When Connected at MJ1/MJ2:

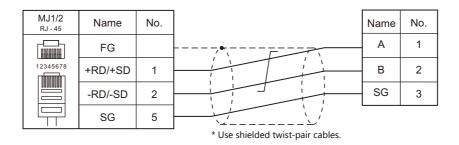
RS-232C

Wiring diagram 1 - M2

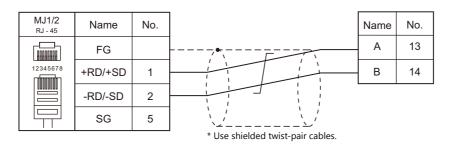


RS-422/RS-485

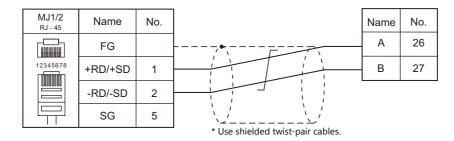
Wiring diagram 1 - M4



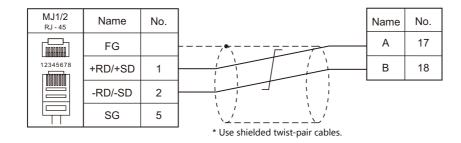
Wiring diagram 2 - M4



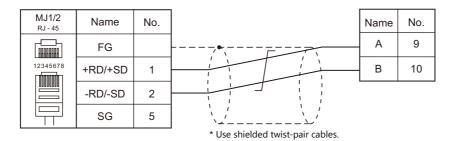
Wiring diagram 3 - M4



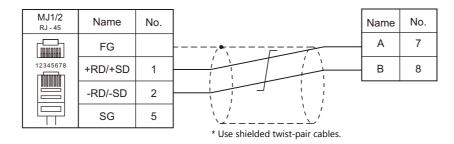
Wiring diagram 4 - M4



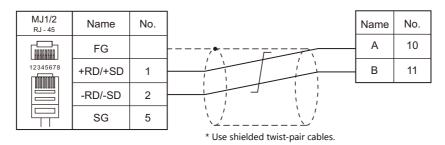
Wiring diagram 5 - M4



Wiring diagram 6 - M4



Wiring diagram 7 - M4



14. TOSHIBA

- 14.1 PLC Connection
- 14.2 Temperature Controller/Servo/Inverter Connection

14.1 PLC Connection

Serial Connection

PLC Selection		DI C (CI	N. I	Linit (Dont	Ciamal Laurel	Conn	ection	Ladder
on the Editor		PLC/CF	0	Unit/Port	Signal Level	CN1	MJ1/MJ2	Transfer *1
			T1-16	Programmer port	RS-232C	Wiring diagram 1 - C2	Wiring diagram 1 - M2	
		T1	T1-28 T1-40 T1-40S	CU111	RS-485	Wiring diagram 1 - C4	×	
		T1S	T1-40S	LINK port			^	
		T2	PU224	LINK port	RS-485	Wiring diagram 2 - C4		
				Programmer port	- RS-232C	Wiring diagram 2 - C2	Wiring diagram 2 - M2	
		T2E	PU234E	CM232E		Willing diagram 2 - C2	Willing diagram 2 - Wiz	
	T series			CM231E	RS-485	Wiring diagram 1 - C4	×	
			PU215N	Programmer port	RS-232C	Wising dispuses 2 C2	Minima dia ana 2 M2	
		T2N	PU235N		RS-232C	Wiring diagram 2 - C2	Wiring diagram 2 - M2	
			PU245N	LINK port	RS-485	Wiring diagram 3 - C4	×	
T series / V series		Т3	PU315 PU325	LINK port RS-485	DC 10E	Wiring diagram 2 - C4	×	×
(T compatible)		ТЗН	PU325H PU326H		Willing diagram 2 - C4			
		S2T	PU672T PU662T	Programmer port	RS-232C	Wiring diagram 2 - C2	Wiring diagram 2 - M2	_
				LINK port	RS-485	Wiring diagram 1 - C4	×	
		V series model 2000	DUC10E	Programmer port	RS-232C	Wiring diagram 2 - C2	Wiring diagram 2 - M2	
			S2E PU612E	LINK port	RS-485	Wiring diagram 1 - C4	×	
	V series		S2PU22A S2PU32A S2PU72A S2PU72D S2PU82	LINK port	RS-485	Wiring diagram 1 - C4	×	
		model 3000	S3PU21 S3PU45A S3PU55A S3PU65A	·		Wiring diagram 2 - C4		
	EX100	MPU12	A	COMP. LINK				
EX series	EX250 EX500			CMP6236A	RS-485	Wiring diagram 1 - C4	×	×
	EX2000	MPU-6620		COMP. LINK				

^{*1} For the ladder transfer function, see the V9 Series Reference Manual.

14.1.1 T Series / V Series (T Compatible)

Communication Setting

Editor

Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1:1/1:n/Multi-link/Multi-link2/ Multi-link2 (Ethernet)/ 1:n Multi-link2 (Ethernet)	
Signal Level	RS-232C / <u>RS-422/485</u>	
Baud Rate	4800 / <u>9600</u> / 19200 / 38400 bps	
Parity	None / <u>Odd</u> / Even	
Data Length	7 / <u>8</u> bits	
Stop Bit	<u>1</u> / 2 bits	
Target Port No.	<u>1</u> to 31	

PLC

T1/T1S (Programmer Port)/CU111

System information

(Underlined setting: default)

Item	Setting	Remarks
Operation Mode	Computer link (ASCII)	
Signal Level	Programmer port: RS-232C CU111: RS-485	
Baud Rate	9600 bps (fixed)	
Parity	None / <u>Odd</u>	
Data Length	8 bits (fixed)	
Stop Bit	1 bit (fixed)	
Station No.	<u>1</u> to 31	

T1S (Link Port)

Special register (SW056), system information

(Underlined setting: default)

Item	Link Port	Remarks
Operation Mode	Computer link (ASCII)	Special register SW056 = 0 The setting takes effect when the EEPROM write command is executed and the power is turned off and back on again.
Signal Level	RS-485	
Baud Rate	4800 / 9600 / 19200 bps	
Parity	None / <u>Odd</u> / Even	
Data Length	7 / <u>8</u> bits	
Stop Bit	<u>1</u> / 2 bits	
Station No.	<u>1</u> to 31	

T2E/T2N (Programmer Port)

Operation mode setting switch

Swi	tch	Contents	Setting	Remarks
P 1	SW6: COM	Programmer port parity setting	OFF: Odd parity ON: Without parity	The setting takes effect when the power is turned off and back on again.

The following settings are fixed; baud rate: 9600 bps, data length: 8 bits, and stop bit: 1 bit.

T2E (Option Card CM231E/CM232E)

Operation mode setting switch

The settings are made by the DIP switch on the front of the CPU module (PU234E).

Swi	tch	Contents	Setting	Remarks
	SW4: CM0		OFF	
P 1	SW5: CM1	Option communication mode setting Function: computer link	OFF	The settings take effect when the power is turned off and back on again.

Transmission parameter setting

Transmission parameters are set on the system information area of T2E.

(Underlined setting: default)

Item	Setting	Remarks
Signal Level	CM231E: RS-485 CM232E: RS-232C	
Baud Rate	4800 / 9600 / 19200 bps	The settings take effect when the EEPROM write
Parity	None / <u>Odd</u> / Even	command is executed and the power is turned off and
Data Length	7 / <u>8</u> bits	back on again.
Stop Bit	<u>1</u> / 2 bits	
Station No.	<u>1</u> to 31	

T2N (LINK Port)

Operation mode setting switch

Į	Swi	tch	Contents	Setting	Remarks
ĺ		SW4: CM0		OFF	
	OFF	SW5: CM1	Communication mode setting Function: computer link	OFF	The settings take effect when the power is turned off and back on again.

Communication port select switch

Switch	า	Contents	Setting	Remarks
ON 1 2	W1	Signal Level	OFF: RS-485 ON: RS-232C	

The following settings are fixed; baud rate: 9600 bps, data length: 8 bits, and stop bit: 1 bit.

Transmission parameter setting

Transmission parameters are set on the system information area of T2N.

(Underlined setting: default)

Item	Setting	Remarks
Signal Level	CM231E: RS-485 CM232E: RS-232C	
Baud Rate	4800 / 9600 / 19200 bps	The settings take effect when the EEPROM write
Parity	None / <u>Odd</u> / Even	command is executed and the power is turned off and
Data Length	7 / <u>8</u> bits	back on again.
Stop Bit	<u>1</u> / 2 bits	
Station No.	<u>1</u> to 31	

T3/T3H (LINK Port)

Transmission parameter setting

 $\label{transmission} \mbox{Transmission parameters are set on the system information area.}$

(Underlined setting: default)

Item	Setting	Remarks
Signal Level	RS-485	
Baud Rate	4800 / 9600 / 19200 bps	
Parity	None / <u>Odd</u> / Even	The settings take effect when the EEPROM write command is executed and the power is turned off and
Data Length	7 / <u>8</u> bits	back on again.
Stop Bit	<u>1</u> / 2 bits	
Station No.	<u>1</u> to 31	

S2E/S2T (Programmer Port)

Operation mode setting switch

Switch	Contents	OFF	ON	Remarks
3:P	Programmer port parity setting	Odd parity	Without parity	

The following settings are fixed; baud rate: 9600 bps, data length: 8 bits, and stop bit: 1 bit.

S2E/S2T (LINK Port)

Set special registers and system information using the engineering tool.

After making settings, execute the ROM write command and turn the power off and back it on again to determine the settings.

Operation mode

Special Register	Setting	Remarks
SW069	0: Computer link (ASCII)	

System information

(Underlined setting: default)

Item		Setting	Remarks
Computer Link Setting Station No.		<u>1</u> to 31	
	Baud Rate	4800 / <u>9600</u> / 19200 bps	
Connection Mode	Parity	None / Odd / Even	
	Data Length	7 / <u>8</u> bits	
	Stop Bit	1/2 bits	

model2000/3000

Set module parameters using the engineering tool.

Module parameter

(Underlined setting: default)

Item	Setting	Remarks
RS-485 Station No.	<u>1</u> to 31	
RS-485 Baud Rate (bit/s)	4800 / <u>9600</u> / 19200 / 38400 bps	
RS-485 Parity Setting	None / Odd / Even	
RS-485 Data Length	7 / <u>8</u> bits	
RS-485 Stop Bit	1 / 2 bits	

Available Device Memory

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

	Device Memory	TYPE	Remarks
D	(data register)	00H	
Χ	(input)	01H	XW as word device
Υ	(output)	02H	YW as word device
R	(auxiliary relay)	05H	RW as word device
L	(link relay)	06H	LW as word device, not available with model2000 and model3000.
W	(link register)	07H	Not available with model2000 and model3000
F	(file register)	08H	
TN	(timer/current value)	09H	Read only, not available with model2000 and model3000
CN	(counter/current value)	0AH	Read only, not available with model2000 and model3000
TS	(timer/contact)	0BH	Read only, not available with model2000 and model3000
CS	(counter/contact)	0CH	Read only, not available with model2000 and model3000

14.1.2 EX Series

Communication Setting

Editor

Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1:1/1:n/Multi-link2/Multi-link2(Ethernet)/ 1:n Multi-link2(Ethernet)	
Signal Level	RS-232C / <u>RS-422/485</u>	
Baud Rate	4800 / <u>9600</u> bps	
Parity	None / <u>Odd</u> / Even	
Data Length	7 / <u>8</u> bits	
Stop Bit	1 / 2 bits	
Target Port No.	0 to 15	For EX200/500: 0 to 7

PLC

EX100

Make settings by using the switches on the CPU module. The following settings are fixed; data length: 8 bits, and stop bit: 1 bit.

Switch

Switch		Setting	Remarks
Communication switch	PROGMR	LINK: computer link	
Station No.	STATION	0 to F (= 0 to 15)	The settings take effect when the power is turned off and back on again.
Baud Rate	BR BR2	9600 bps (BR2: OFF, BR1: OFF) 4800 bps (BR2: OFF, BR1: ON)	
Parity	BR1 PEN PR □ □ → ON	Odd (PEN: ON, PR: OFF) Even (PEN: ON, PR: ON) None (PEN: OFF, PR: OFF/ON)	

EX250/EX500

Make settings by using the switches on the CPU module. The following settings are fixed; data length: 8 bits, and stop bit: 1 bit.

Switch

	Switch		Setting	Remarks
Write enable switch	ON OFF		ON: Write enabled	
Station No.	STATION		0 to 7	
		SP0	0: EX control command enabled	
	0 1	SP1	0: Block write command enabled	
	SP0 ■ ∞ SP1 ■ ト	SP2	1: ASCII mode	
DNT8	BR2 ■ 0 8 BR BR BR BR	BR	9600 bps (BR0: 1, BR1: 0, BR2: 0) 4800 bps (BR0: 0, BR1: 1, BR2: 0)	
	PEN S C	PEN EVN	Odd (PEN: 0, EVN: 1) Even (PEN: 0, EVN: 0) None (PEN: 1, EVN: 0/1)	

EX2000

Make settings for system information (16. COMPUTER LINK) by using the graphic programmer.

System information

(Underlined setting: default)

Item	Setting	Remarks
STATION No.	<u>1</u> to 31	
BAUD RATE	4800 / 9600 bps	
PARITY	0: None 1: Odd 2: Even	
DATA LENGTH	8 bits (fixed)	
STOP BIT	1.0: 1 bits 2.0: 2 bits	

Available Device Memory

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

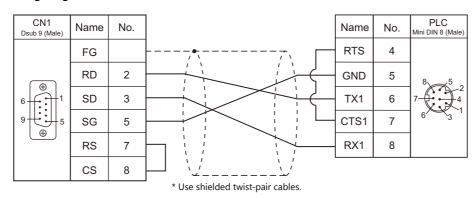
	Device Memory	TYPE	Remarks
D	(data register)	00H	
Х	(input)	01H	XW as word device
Υ	(output)	02H	YW as word device
R	(auxiliary relay)	03H	RW as word device
Z	(link relay)	04H	ZW as word device
TN	(timer/current value)	05H	Read only
CN	(counter/current value)	06H	Read only

14.1.3 Wiring Diagrams

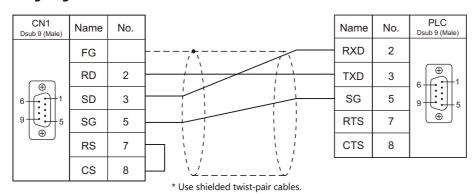
When Connected at CN1:

RS-232C

Wiring diagram 1 - C2

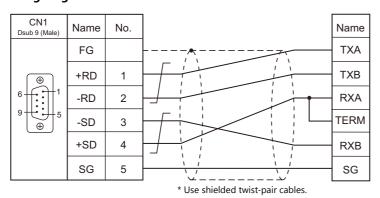


Wiring diagram 2 - C2



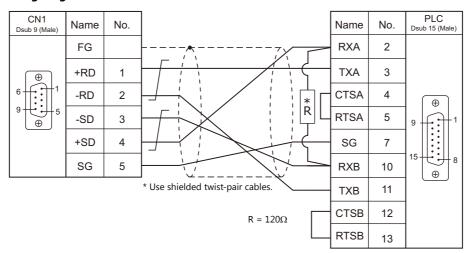
RS-422/RS-485

Wiring diagram 1 - C4

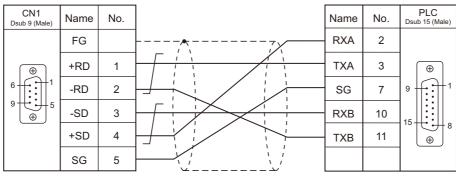


For 1 : 1 connection: Terminating resistance: 120 $\!\Omega$ with RXA and TERM short-circuited

Wiring diagram 2 - C4



Wiring diagram 3 - C4

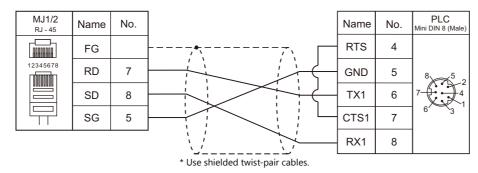


* Use shielded twist-pair cables.

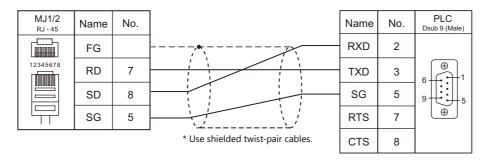
When Connected at MJ1/MJ2:

RS-232C

Wiring diagram 1 - M2



Wiring diagram 2 - M2



14.2 Temperature Controller/Servo/Inverter Connection

Inverter

PLC Selection	Model	Down	Cianal Laurel	Conn	ection	1 . 69	
on the Editor	Model	Port	Signal Level	CN1	MJ1/MJ2	Lst File	
VF-S7	VF-S7	RS2001Z	RS-232C	Wiring diagram 1 - C2	Wiring diagram 1 - M2	VFS7.Lst	
VF-3/	VF-37	RS4001Z	RS-485	Wiring diagram 1 - C4	Wiring diagram 1 - M4	VF37.LSt	
VF-S9	VF-S9	RS2001Z	RS-232C	Wiring diagram 1 - C2	Wiring diagram 1 - M2	VFS9.Lst	
VF-39	VF-39	RS4001Z	RS-485	Wiring diagram 1 - C4	Wiring diagram 1 - M4	VF39.LSt	
		RS2001Z	RS-232C	Wiring diagram 1 - C2	Wiring diagram 1 - M2		
		RS20035	KS-232C	Wiring diagram 2 - C2	Wiring diagram 2 - M2		
VF-S11	VF-S11	RS4001Z				VFS11.Lst	
		RS4002Z	RS-485	Wiring diagram 1 - C4	Wiring diagram 1 - M4		
		RS4003Z					
		RS2001Z	RS-232C	Wiring diagram 1 - C2	Wiring diagram 1 - M2		
VF-A7	VF-A7	RS4001Z	RS-485	Wiring diagram 1 - C4	Wiring diagram 1 - M4	VFA7.Lst	
		RS-485 connector	RS-485	Wiring diagram 2 - C4	Wiring diagram 2 - M4		
VF-AS1	VF-AS1	2-wire RS-485 connector	RS-485	Wiring diagram 3 - C4	Wiring diagram 3 - M4	VFAS1.Lst	
VF-ASI	VF-ASI	4-wire RS-485 connector	K3-403	Wiring diagram 2 - C4	Wiring diagram 2 - M4		
		RS2001Z	RS-232C	Wiring diagram 1 - C2	Wiring diagram 1 - M2		
VF-P7	VF-P7	RS4001Z	RS-485	Wiring diagram 1 - C4	Wiring diagram 1 - M4	VFP7.Lst	
		RS-485 connector	RS-485	Wiring diagram 2 - C4	Wiring diagram 2 - M4		
VF-PS1	VF-PS1	2-wire RS-485 connector	RS-485	Wiring diagram 3 - C4	Wiring diagram 3 - M4	VFPS1.Lst	
VF-PS1 VF-PS1		4-wire RS-485 connector	KS-485	Wiring diagram 2 - C4	Wiring diagram 2 - M4	VFPSI.LSI	
VF-FS1	VF-FS1	Communication connector	RS-485	Wiring diagram 3 - C4	Wiring diagram 3 - M4	VFFS1.Lst	
		RS2001Z	RS-232C	Wiring diagram 1 - C2	Wiring diagram 1 - M2		
VF-nC1	VF-nC1	RS4001Z	RS-485	Wiring diagram 1 C4	Wiring diagram 1 MA	VFnC1.Lst	
		RS4002Z	K3-483	Wiring diagram 1 - C4	Wiring diagram 1 - M4		

14.2.1 VF-S7

Communication Setting

Editor

Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1:1/ <u>1:n</u> /Multi-link2/Multi-link2 (Ethernet)/ 1:n Multi-link2 (Ethernet)	
Signal Level	RS-232C / <u>RS-422/485</u>	
Baud Rate	4800 / <u>9600</u> bps	
Data Length	<u>8</u> bits	
Stop Bit	<u>1</u> / 2 bits	
Parity	None / Odd / <u>Even</u>	
Target Port No.	<u>0</u> to 31	

Inverter

Communication parameter (group No. 08)

The communication parameters can be set using keys attached to the inverter. Be sure to match the settings to those made under [Communication Setting] of the editor.

(Underlined setting: default)

Parameter	Indication	Item	Setting	Default
	F800	Baud rate	2: 4800 bps 3: 9600 bps	3
Communication	F801	Parity	0: None 1: Even 2: Odd	1
	F802	Inverter number (station number)	<u>0</u> to 31	0
	F803	Communication error trip time	0: Inactive 1 to 100 seconds	0

The data length is fixed to "8 bits".

Changes to parameters take effect when the power is turned off and on again.

RS4001Z: baud rate and terminating resistance setting switch

Switch	Contents	Setting			Setting Example
1, 2	Baud rate *	4800 9600 SW1 OFF ON SW2 ON ON		ON	Baud rate: 9600 bps Terminating resistance: Provided
3	Terminating resistance on the receiving side	ON: Prov	ided provided		ON 1 2 3 4
4	Terminating resistance on the sending side	ON: Prov OFF: Not	rided provided		

^{*} Set the same baud rate as the one set for the communication parameter "F800" of the inverter.

Available Device Memory

The available setting range of device memory varies depending on the model. Be sure to set within the range available for the model to be used. Use [TYPE] when assigning indirect device memory for macro programs.

Device Memory	TYPE	Remarks
	00H	

Specify the storage device memory address on the [Device Input] dialog.

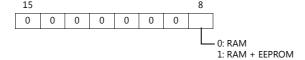
RAM: Store in RAM

EEPROM: Store in RAM + EEPROM

Indirect Device Memory Designation

15	8	7 0
n + 0	Model (11 to 18)	Device type
n + 1	Addre	ess No.
n + 2	Expansion code *	Bit designation
n + 3	00	Station number

* Specify the storage device memory address in the expansion code.



14.2.2 VF-S9

Communication Setting

Editor

Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode		
Signal Level	RS-232C / <u>RS-422/485</u>	
Baud Rate	4800 / <u>9600</u> / 19200 bps	
Data Length	<u>8</u> bits	
Stop Bit	<u>1</u> / 2 bits	
Parity	None / Odd / <u>Even</u>	
Target Port No.	<u>0</u> to 31	

Inverter

Communication parameter (group No. 08)

The communication parameters can be set using keys attached to the inverter. Be sure to match the settings to those made under [Communication Setting] of the editor.

(Underlined setting: default)

Parameter	Indication	Item	Setting	Default
	F800	Baud rate	2: 4800 bps 3: 9600 bps 4: 19200 bps	3
Communication	F801 Parity	Parity	0: None 1: Even 2: Odd	1
	F802	Inverter number (station number)	<u>0</u> to 31	0
	F803	Communication error trip time	0: Inactive 1 to 100 seconds	0
	F805	Transmission latency setting *	0.00: Normal communication 0.01 to 2.00 seconds	0.00

^{*} Necessary for the CPU version V110 and later

The data length is fixed to "8 bits".

Changes to parameters take effect when the power is turned off and on again.

RS4001Z: baud rate and terminating resistance setting switch

Switch	Contents	Setting)	Setting Example
1, 2	Baud rate *	4800 SW1 OFF SW2 ON	9600 ON ON	Baud rate: 9600 bps Terminating resistance: Provided
3	Terminating resistance on the receiving side	ON: Provided OFF: Not provided		ON 1 2 3 4
4	Terminating resistance on the sending side	ON: Provided OFF: Not provided		

^{*} Set the same baud rate as the one set for the communication parameter "F800" of the inverter.

Available Device Memory

The available setting range of device memory varies depending on the model. Be sure to set within the range available for the model to be used. Use [TYPE] when assigning indirect device memory for macro programs.

Device Memory	TYPE	Remarks
	00H	

Specify the storage device memory address on the [Device Input] dialog.

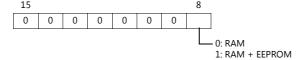
RAM: Store in RAM

EEPROM: Store in RAM + EEPROM

Indirect Device Memory Designation

15	8	7 0
n + 0	Model (11 to 18)	Device type
n + 1	Addre	ess No.
n + 2	Expansion code *	Bit designation
n + 3	00	Station number

* Specify the storage device memory address in the expansion code.



14.2.3 VF-S11

Communication Setting

Editor

Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode		
Signal Level	RS-232C / <u>RS-422/485</u>	
Baud Rate	4800 / <u>9600</u> / 19200 bps	
Data Length	<u>8</u> bits	
Stop Bit	<u>1</u> / 2 bits	
Parity	None / Odd / <u>Even</u>	
Target Port No.	<u>0</u> to 31	

Inverter

Communication parameter

The communication parameters can be set using keys attached to the inverter. Be sure to match the settings to those made under [Communication Setting] of the editor.

(Underlined setting: default)

Parameter	Indication	Item	Setting	Default
	F800	Baud rate	2: 4800 bps 3: 9600 bps 4: 19200 bps	3
	F801 Parity		0: None 1: Even 2: Odd	1
Communication	ommunication F802 Inverter number (station number)		<u>0</u> to 31	0
	F803 Communication error trip time	0: Inactive 1 to 100 seconds	0	
	F805	Transmission latency setting	0.00: Normal communication 0.01 to 2.00 seconds	0.00
	F829	Communication protocol selection	0: Toshiba inverter protocol 1: MODBUS-RTU protocol	0

The data length is fixed to "8 bits".

Changes to parameters take effect when the power is turned off and on again.

RS4001Z: baud rate and terminating resistance setting switch

Switch	Contents		Setting		Se	etting Example
1, 2	Baud rate *	SW1 SW2	4800 OFF ON	9600 ON ON		Baud rate: 9600 bps Terminating resistance: Provided
3	Terminating resistance on the receiving side	ON: Prov OFF: Not	ided provided		ON 1 2 3 4	icinimuting resistance. Frended
4	Terminating resistance on the sending side	ON: Prov OFF: Not	ided provided			

 $^{^{\}star}~$ Set the same baud rate as the one set for the communication parameter "F800" of the inverter.

RS4002Z: baud rate and bit length setting (SW1)

Switch	Contents		Se	etting		Setting Example
1 to 3	Baud rate ^{*1}	SW1 SW2 SW3	4800 OFF ON OFF	9600 ON ON OFF	19200 OFF OFF ON	ON Baud rate: 9600 bps Bit length: 12 bits
4	Bit length *2	ON: 11 bi				

- *1 Set the same baud rate as the one set for the communication parameter "F800" of the inverter.
 *2 When the parity is provided, set 12 bits.

RS4002Z: wiring system and terminating resistance setting (SW2)

Switch	Contents		Setting		Se	etting Example
1, 2	Wiring system	SW1 SW2	4-wire system OFF	2-wire system ON	ON	Wiring: 4-wire system
3	Terminating resistance on the receiving side	ON: Provide OFF: Not pr				Terminating resistance: Provided
4	Terminating resistance on the sending side	ON: Provide OFF: Not pr				

RS4003Z: wiring system (SW1), terminating resistance (SW2), and inverter number (SW5) setting

Switch	Contents		Setting	Setting Example	
SW1	Wiring system *1		2: 2-wire system 4: 4-wire system	2 4	Wiring: 4-wire system
SW2	R	Terminating resistance on the receiving side	S: Terminating resistance provided O: Terminating resistance not provided	R T	Terminating resistance: Provided
	Т	Terminating resistance on the sending side	S: Terminating resistance provided O: Terminating resistance not provided	0	terminating resistance. Provided
SW5	Inverter number *2		0 to 15		Inverter number: 0

- *1 Set the both setting switches in the same positions.
 *2 When "0" is selected, the setting of the inverter's communication parameter "F802" takes effect.

Available Device Memory

The available setting range of device memory varies depending on the model. Be sure to set within the range available for the model to be used. Use [TYPE] when assigning indirect device memory for macro programs.

Device Memory	TYPE	Remarks
	00H	

Specify the storage device memory address on the [Device Input] dialog.

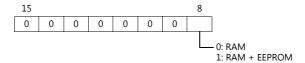
Store in RAM

RAM: EEPROM: Store in RAM + EEPROM

Indirect Device Memory Designation

15	5 8	7 0
n + 0	Model (11 to 18)	Device type
n + 1	Addre	ess No.
n + 2	Expansion code *	Bit designation
n + 3	00	Station number

 $^{\star}\,$ Specify the storage device memory address in the expansion code.



14.2.4 VF-A7

Communication Setting

Editor

Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1 : 1 / <u>1 : n</u> / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet)	
Signal Level	RS-232C / <u>RS-422/485</u>	
Baud Rate	4800 / <u>9600</u> / 19200 / 38400 bps	
Data Length	<u>8</u> bits	
Stop Bit	<u>1</u> / 2 bits	Fixed to "1" when 2-wire RS-485 connection is selected and the CPU version is V100 to V305
Parity	None / Odd / <u>Even</u>	
Target Port No.	<u>0</u> to 31	

Inverter

RS-485 Communication Port

Communication parameter

The communication parameters can be set using keys attached to the inverter. Be sure to match the settings to those made under [Communication Setting] of the editor.

(Underlined setting: default)

Parameter	Indication	Item	Setting	Default
	F801	Parity	0: None <u>1: Even</u> 2: Odd	1
	F802	Inverter number (station number)	<u>0</u> to 31	0
	F803	Communication timeout time	0: OFF 1 to 100 seconds	0
Communication	F805	Transmission latency setting *1	0.00: Normal communication 0.01 to 2.00 seconds	0.00
Communication	F820	Baud rate (RS-485 communication port)	2: 4800 bps 3: 9600 bps 4: 19200 bps 5: 38400 bps	3
	F821	Wiring system	0: 2-wire system *2 1: 4-wire system	1
	F825	Transmission latency setting *1	0.00: Normal communication 0.01 to 2.00 seconds	0.00

^{*1} When the CPU version is V100, make a setting for F805. For any version other than V100, make a setting for F825.
*2 Not available with the CPU version of V300 or earlier. Use a 4-wire system for connection.

The data length is fixed to "8 bits".

Changes to parameters take effect when the power is turned off and on again.

Common Serial Communication Port (RS2001Z / RS4001Z)

When the common serial communication port is used, the communication conversion unit "RS2001Z" or "RS4001Z" is necessary.

Communication parameter

The communication parameters can be set using keys attached to the inverter.

Be sure to match the settings to those made under [Communication Setting] of the editor.

(Underlined setting: default)

Parameter	Indication	Item	Setting	Default
	F800	Baud rate (Common serial)	2: 4800 bps 3: 9600 bps	3
	F801	Parity	0: None <u>1: Even</u> 2: Odd	1
Communication	F802	Inverter number (station number)	<u>0</u> to 31	0
	F803	Communication timeout time	0: OFF 1 to 100 seconds	0
	F805	Transmission latency setting	0.00: Normal communication 0.01 to 2.00 seconds	0.00

The data length is fixed to "8 bits".

Changes to parameters take effect when the power is turned off and on again.

RS4001Z: baud rate and terminating resistance setting switch

Switch	Contents	Setting			Se	etting Example
1, 2	Baud rate *	SW1 SW2	4800 OFF ON	9600 ON ON		Baud rate: 9600 bps Terminating resistance: Provided
3	Terminating resistance on the receiving side	ON: Provided OFF: Not provided			ON 1 2 3 4	icinimuting resistance. Frended
4	Terminating resistance on the sending side	ON: Prov OFF: Not	ided provided			

^{*} Set the same baud rate as the one set for the communication parameter "F800" of the inverter.

Available Device Memory

The available setting range of device memory varies depending on the model. Be sure to set within the range available for the model to be used. Use [TYPE] when assigning indirect device memory for macro programs.

Device Memory	TYPE	Remarks
	00H	

Specify the storage device memory address on the [Device Input] dialog.

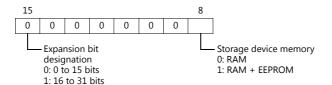
Store in RAM EEPROM:

Store in RAM + EEPROM

Indirect Device Memory Designation

15	5 8	7 0
n + 0	Model (11 to 18)	Device type
n + 1	Addre	ess No.
n + 2	Expansion code *	Bit designation
n + 3	00	Station number

In the expansion code, specify the storage device memory address, and set which word, higher or lower, is to be read when 2-word address is specified (expansion bit designation).



14.2.5 VF-AS1

Communication Setting

Editor

Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1:1/1:n/Multi-link2/Multi-link2(Ethernet)/ 1:n/Multi-link2(Ethernet)	
Signal Level	RS-422/485	
Baud Rate	9600 / <u>19200</u> / 38400 bps	
Data Length	<u>8</u> bits	
Stop Bit	<u>1</u> / 2 bits	
Parity	None / Odd / Even	
Target Port No.	<u>0</u> to 31	

Inverter

2-wire RS-485 Communication Port

Communication parameter

The communication parameters can be set using keys attached to the inverter. Be sure to match the settings to those made under [Communication Setting] of the editor.

(Underlined setting: default)

Parameter	Indication	Item	Setting	Default
	F800	Baud rate (2-wire RS-485)	0: 9600 bps 1: 19200 bps 2: 38400 bps	1
	F801 Parity (Common to 2-wire and 4-wire)		0: None 1: Even 2: Odd	1
Communication	F802	Inverter number (station number)	<u>Q</u> to 31	0
Communication	F803	Communication timeout time (Common to 2-wire and 4-wire)	0: OFE 1 to 100 seconds	0
	F805	Transmission latency setting (2-wire RS-485)	0.00: Normal communication 0.01 to 2.00 seconds	0.00
	F807	Communication protocol selection (2-wire RS-485)	0: Toshiba inverter protocol 1: MODBUS-RTU protocol	0

The data length is fixed to "8 bits".

Changes to parameters take effect when the power is turned off and on again.

4-wire RS-485 Communication Port

Communication parameter

The communication parameters can be set using keys attached to the inverter. Be sure to match the settings to those made under [Communication Setting] of the editor. (Underlined setting: default)

RS4001Z: baud rate and terminating resistance setting switch

Parameter	Indication	Item	Setting	Default
	F801	Parity (Common to 2-wire and 4-wire)	0: None 1: Even 2: Odd	1
	F802	Inverter number (station number)	<u>0</u> to 31	0
Communication	F803	Communication timeout time (Common to 2-wire and 4-wire)	0: OFF 1 to 100 seconds	0
Communication	F820	Baud rate (4-wire RS-485)	0: 9600 bps 1: 19200 bps 2: 38400 bps	1
	F825	Transmission latency setting (4-wire RS-485)	0.00: Normal communication 0.01 to 2.00 seconds	0.00
	F829	Communication protocol selection (4-wire RS-485)	0: Toshiba inverter protocol 1: MODBUS-RTU protocol	0

The data length is fixed to "8 bits".

Changes to parameters take effect when the power is turned off and on again.

Available Device Memory

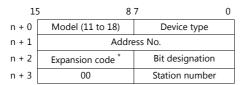
The available setting range of device memory varies depending on the model. Be sure to set within the range available for the model to be used. Use [TYPE] when assigning indirect device memory for macro programs.

Device Memory	TYPE	Remarks
	00H	

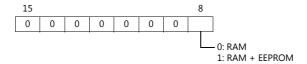
Specify the storage device memory address on the [Device Input] dialog.

RAM: Store in RAM
EEPROM: Store in RAM + EEPROM

Indirect Device Memory Designation



* Specify the storage device memory address in the expansion code.



14.2.6 VF-P7

Settings are the same as those described in "14.2.4 VF-A7".

14.2.7 VF-PS1

Settings are the same as those described in "14.2.5 VF-AS1".

14.2.8 VF-FS1

Communication Setting

Editor

Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1:1/1:n/Multi-link2/Multi-link2(Ethernet)/ 1:n Multi-link2(Ethernet)	
Signal Level	RS-422/485	
Baud Rate	9600 / <u>19200</u> bps	
Data Length	<u>8</u> bits	
Stop Bit	<u>1</u> / 2 bits	
Parity	None / Odd / Even	
Target Port No.	<u>0</u> to 31	

Inverter

Communication parameter

The communication parameters can be set using keys attached to the inverter. Be sure to match the settings to those made under [Communication Setting] of the editor.

(Underlined setting: default)

Parameter	Indication	Item	Setting	Default
	F800	Baud rate	0: 9600 bps 1: 19200 bps	1
	F801	Parity	0: None 1: Even 2: Odd	1
Communication	F802	Inverter number (station number)	<u>0</u> to 31	0
Communication	F803	Communication timeout time	0: OFF 1 to 100 seconds	0
	F805	Transmission latency setting	0.00: Normal communication 0.01 to 2.00 seconds	0.00
	F829	Communication protocol selection	0: Toshiba inverter protocol 1: MODBUS-RTU protocol	0

The data length is fixed to "8 bits".

Changes to parameters take effect when the power is turned off and on again.

Available Device Memory

The available setting range of device memory varies depending on the model. Be sure to set within the range available for the model to be used. Use [TYPE] when assigning indirect device memory for macro programs.

Device Memory	TYPE	Remarks
	00H	

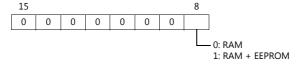
Specify the storage device memory address on the [Device Input] dialog. RAM: Store in RAM

EEPROM: Store in RAM + EEPROM

Indirect Device Memory Designation

15	5 8	7	0			
n + 0	Model (11 to 18)	Device type				
n + 1	Addre	Address No.				
n + 2	Expansion code *	Bit designation				
n + 3	00	Station number				

* Specify the storage device memory address in the expansion code.



14.2.9 VF-nC1

Communication Setting

Editor

Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1:1/1:n/Multi-link2/Multi-link2(Ethernet)/ 1:n Multi-link2(Ethernet)	
Signal Level	RS-232C / <u>RS-422/485</u>	
Baud Rate	4800 / <u>9600</u> / 19200 bps	
Data Length	<u>8</u> bits	
Stop Bit	<u>1</u> / 2 bits	
Parity	None / Odd / <u>Even</u>	
Target Port No.	<u>0</u> to 31	

Inverter

Communication parameter

The communication parameters can be set using keys attached to the inverter. Be sure to match the settings to those made under [Communication Setting] of the editor.

(Underlined setting: default)

Parameter	Indication	Item	Setting	Default
	F800	Baud rate	2: 4800 bps 3: 9600 bps 4: 19200 bps	3
Communication	F801	Parity	0: None 1: Even 2: Odd	1
	F802	Inverter number (station number)	<u>0</u> to 31	0
	F803	Communication timeout time	0: OFF 1 to 100 seconds	0

The data length is fixed to "8 bits".

Changes to parameters take effect when the power is turned off and on again.

RS4001Z: baud rate and terminating resistance setting switch

Switch	Contents	Setting			Se	etting Example
1, 2	Baud rate *	SW1 SW2	4800 OFF ON	9600 ON ON		Baud rate: 9600 bps Terminating resistance: Provided
3	Terminating resistance on the receiving side	ON: Provided OFF: Not provided			ON 1 2 3 4	reminuting resistance. The race
4	Terminating resistance on the sending side	ON: Provi OFF: Not				

^{*} Set the same baud rate as the one set for the communication parameter "F800" of the inverter.

RS4002Z: baud rate and bit length setting switch

Switch	Contents		Se	etting		Setting Example
		SW1	4800 OFF	9600 ON	19200 OFF	
1 to 3	Baud rate ^{*1}	-				ON Baud rate: 9600 bps
		SW2	ON	ON	OFF	Bit length: 12 bits
		SW3	OFF	OFF	ON	1 2 3 4 Sittlengtii. 12 Sits
4	Bit length *2	ON: 11 b OFF: 12 b				

^{*1} Set the same baud rate as the one set for the communication parameter "F800" of the inverter.
*2 When the parity is provided, set 12 bits.

RS4002Z: wiring system and terminating resistance setting switch

Switch	Contents	Setting		Se	etting Example
1, 2	Wiring system	4-wire system SW1 OFF SW2 OFF	2-wire system ON	ON DE D	Wiring: 4-wire system Terminating resistance: Provided
3	Terminating resistance on the receiving side	ON: Provided OFF: Not provided		1 2 3 4	
4	Terminating resistance on the sending side	ON: Provided OFF: Not provided			

Available Device Memory

The available setting range of device memory varies depending on the model. Be sure to set within the range available for the model to be used. Use [TYPE] when assigning indirect device memory for macro programs.

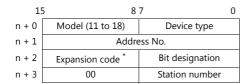
Device Memory	TYPE	Remarks
	00H	

Specify the storage device memory address on the [Device Input] dialog.

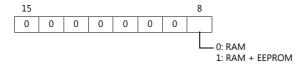
RAM: Store in RAM

EEPROM: Store in RAM + EEPROM

Indirect Device Memory Designation



* Specify the storage device memory address in the expansion code.

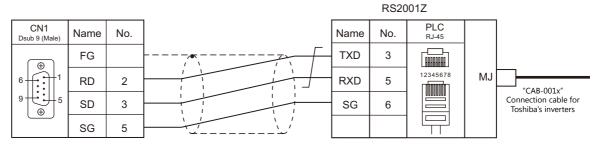


14.2.10 Wiring Diagrams

When Connected at CN1:

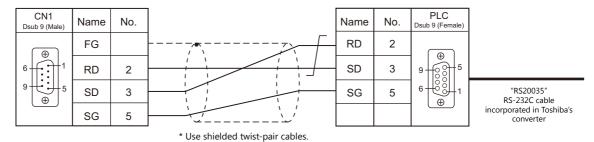
RS-232C

Wiring diagram 1 - C2



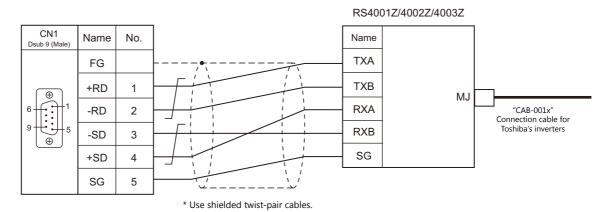
^{*} Use shielded twist-pair cables.

Wiring diagram 2 - C2

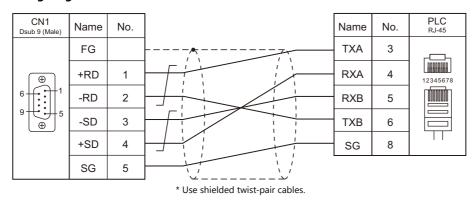


RS-422/RS-485

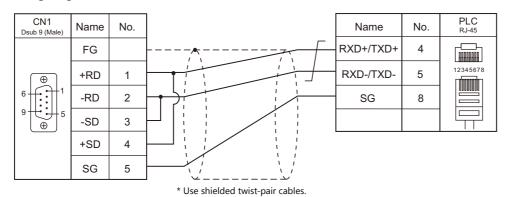
Wiring diagram 1 - C4



Wiring diagram 2 - C4



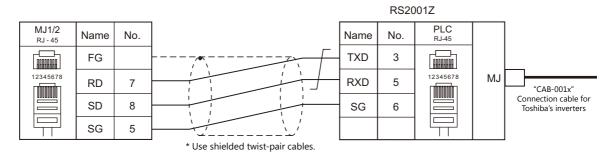
Wiring diagram 3 - C4



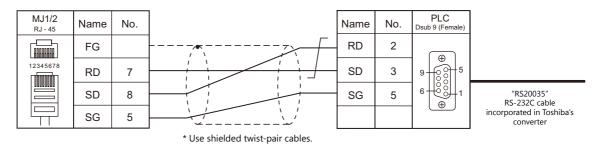
When Connected at MJ1/MJ2:

RS-232C

Wiring diagram 1 - M2

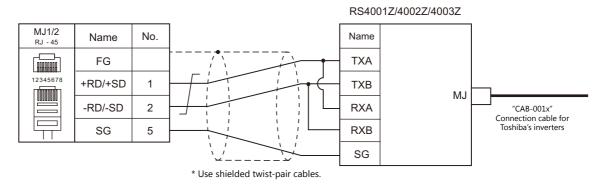


Wiring diagram 2 - M2

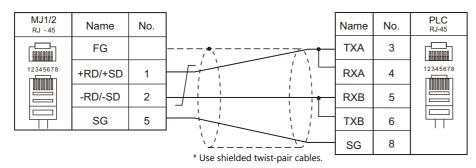


RS-422/RS-485

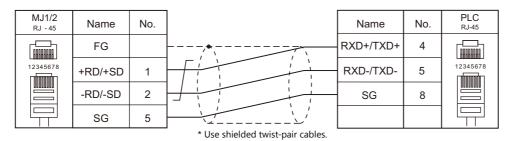
Wiring diagram 1 - M4



Wiring diagram 2 - M4



Wiring diagram 3 - M4



15. TOSHIBA MACHINE

- 15.1 PLC Connection
- 15.2 Temperature Controller/Servo/Inverter Connection

15.1 PLC Connection

Serial Connection

PLC Selection		CPU	Hn	Unit/Port		Conn	ection	Ladder
on the Editor		CPU	Un	II/POIT	Signal Level	CN1	MJ1/MJ2	Transfer*4
		тссин	Port of the CPU					
		ІССОН	TCCMW TCCMO					
	TC200	TCCUHS	Port of the CPU	RS-232C port	RS-232C	Wiring diagram 1 - C2	Wiring diagram 1 - M2	
		TCCUHSC TCCUHSAC	TCCMWA TCCMWS TCCMOA TC232CA					
			CN16		RS-232C	Wiring diagram 1 - C2	Wiring diagram 1 - M2	
		TC3-01	CN17A CN17B		RS-485 *1	Wiring diagram 1 - C4	Wiring diagram 1 - M4	
TC200			CN18		RS-232C	Wiring diagram 1 - C2	Wiring diagram 1 - M2	×
		TC3-02	CN20A CN20B		RS-485 *2	Wiring diagram 2 - C4	Wiring diagram 2 - M4	
			CN18		RS-232C	Wiring diagram 1 - C2	Wiring diagram 1 - M2	
	TCmini	TC5-02	CN24A CN24B		RS-485	Wiring diagram 3 - C4	Wiring diagram 3 - M4	
			CN13		RS-232C	Wiring diagram 1 - C2	Wiring diagram 1 - M2	Ī
		TC5-03	CN14 CN18		RS-485	Wiring diagram 2 - C4	Wiring diagram 2 - M4	
		700.00	CN13	CN13		Wiring diagram 1 - C2	Wiring diagram 1 - M2	
		TC8-00	CN11		RS-485 ^{*3}	Wiring diagram 4 - C4	Wiring diagram 4 - M4	
		TC9-00	CN11		RS-485	Wiring diagram 3 - C4	Wiring diagram 3 - M4	Ī

^{*1} CPUs version LT3CU01-D0 or later support RS-485. Check the CPU version.
*2 CPUs version LT3CU02-F0 or later support RS-485. Check the CPU version.
*3 CPUs version LT8CU00-A0 or later support RS-485. Check the CPU version.
*4 For the ladder transfer function, see the V9 Series Reference Manual.

15.1.1 TC200

Communication Setting

Editor

Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1:1/1:n/Multi-link2/Multi-link2(Ethernet)/ 1:n Multi-link2(Ethernet)	
Signal Level	<u>RS-232C</u> / RS-422/485	*1
Baud Rate	9600 / 19200 / 38400 / 57600 / 115200 bps	
Parity	<u>None</u>	
Data Length	<u>8</u> bits	
Stop Bit	<u>2</u> bits	

^{*1} For RS-422/485 communications, set a transmission delay time to 4 msec or longer.

TC200

TCCUH

Make the setting for communication using the ladder tool.

(Underlined setting: default)

Item	Setting	Remarks
Baud Rate	<u>9600</u> / 19200 bps	Set the baud rate in the system flag "A00F" OFF: 9600 bps ON: 19200 bps
Parity	None	
Data Length	8 bits	
Stop Bit	2 bit	
Station Number	1	

TCCMW / TCCMO

No particular setting is necessary on the PLC. The PLC always performs communication functions using the following parameters. Be sure to match the settings to those made under [Communication Setting] of the editor.

Item	Setting	Remarks
Baud Rate	9600 bps	
Parity	None	
Data Length	8 bits	
Stop Bit	2 bit	
Station Number	1	

Function setting switch (MODE)

Switch		Setting	Remarks
3	ON	Link master station	When this switch is OFF, communications between V8 and PLC are not possible.
4	OFF	Link slave station	
5	OFF	Remote master station	
6	OFF	Remote slave station	

TCCUHS / TCCUHSC / TCCUHSAC

Set the communication format in the application software.

(Underlined setting: default)

Item	Setting		Remarks				
		System Flag					
		A00F	A154	A155	Baud Rate (bps)		
Baud rate	9600 / 19200 / 38400 / 57600 / 1 0 0 0 1 1 0 0 1 1 0 1 1 0 1 1 1 1	0	0	0	9600		
		19200					
		'		1	0	38400	
							-
			1	1	115200		

Parity: none, data length: 8 bits, stop bit: 2 bits, station No. 1 (fixed)

TCCMWA / TCCMWS / TCCMOA / TC232CA

Be sure to match the settings to those made under [Communication Setting] of the editor.

Item	Setting	Remarks
Baud rate	9600 / 19200 / 38400 / 57600 bps	57600 bps not supported by TC232CA

Parity: none, data length: 8 bits, stop bit: 2 bits, station No. 1 (fixed)

Function setting switches (MODE)

Switch	ON/OFF	Setting	Remarks
3	ON	Link master station	Communication disabled with this switch set to OFF
4	OFF	Link slave station	
5	OFF	Remote master station	
6	OFF	Remote slave station	

TCmini

TC3-01

CN16

Parity: none, data length: 8 bits, stop bit: 2 bits, station No. 1 (fixed)
Because of the baud rate auto-detection feature (4800/9600/19200/38400 bps), no baud rate setting is needed on the PLC.

CN17A/CN17B

Parity: none, data length: 8 bits, stop bit: 2 bits, station No. 1 (fixed)
Because of the baud rate auto-detection feature (4800/9600/19200/38400 bps), no baud rate setting is needed on the PLC.

Setting Item	Register	Contents	Setting	Remarks
Software setting	D11F	Mode setting	4: Host communication mode	Setting changes take effect when the power is turned off and on again.

Setting Item	Jumper	Item	Setting	
	JP2	Terminating resistance	With terminating resistance	JP2: Jumper
Hardware setting	JP3 JP4 JP15	Half duplex / full duplex selection	Half duplex	JP3: Jumper JP4: Jumper Jumper across pins 2 and 3 of JP15

TC3-02

CN18

Parity: none, data length: 8 bits, stop bit: 2 bits, station No. 1 (fixed)

Because of the baud rate auto-detection feature (4800/9600/19200/38400 bps), no baud rate setting is needed on the PLC.

CN20A/CN20B

Parity: none, data length: 8 bits, stop bit: 2 bits, station No. 1 (fixed)

Because of the baud rate auto-detection feature (4800/9600/19200/38400 bps), no baud rate setting is needed on the PLC.

Setting Item	Register	Contents	Setting	Remarks
Software setting	D26F	Mode setting	4: Host communication mode	Setting changes take effect when the power is turned off and on again.

Setting Item	DIP Switch (SW2)		Contents			Set	ting		
Hardware setting	ON	SW2-1 SW2-2 SW2-3 SW2-4 SW2-7	Half duplex / full duplex selection	Half duplex	SW2-1 OFF	SW2-2	SW2-3	SW2-4	SW2-7
		SW2-6	Terminating resistance	ON: Provided					

TC5-02

CN18

Parity: none, data length: 8 bits, stop bit: 2 bits, station No. 1 (fixed)
Because of the baud rate auto-detection feature (9600/19200/38400 bps), no baud rate setting is needed on the PLC.

CN24A/CN24B

Setting Item	Register	Contents	Setting	Remarks
Software setting	D37E	Baud rate setting	0: 9600 bps 1: 19200 bps 2: 38400 bps	Setting changes take effect when the power is turned off and on again.
	D37F	Mode setting	3: Host communication mode	

Parity: none, data length: 8 bits, stop bit: 2 bits, station No. 1 (fixed)

Setting Item	DIP Switch (SW2)		Contents	Setting
Hardware setting	ON 1 2 3 4 5 6 7 8	SW2-7	Terminating resistance	ON: Provided

TC5-03

CN13

Parity: none, data length: 8 bits, stop bit: 2 bits, station No. 1 (fixed)

Because of the baud rate auto-detection feature (9600/19200/38400 bps), no baud rate setting is needed on the PLC.

CN14/CN18

Setting Item	Register	Contents	Setting	Remarks
Software setting	D37E	Baud rate setting	0: 9600 bps 1: 19200 bps 2: 38400 bps	Setting changes take effect when the power is turned off and on again.
	D37F	Mode setting	3: Host communication mode	

Parity: none, data length: 8 bits, stop bit: 2 bits, station No. 1 (fixed)

Setting Item	DIP Switch (SW1)		Contents			Set	ting		
		SW1-1 SW1-2	Half duplex /		SW1-1	SW1-2	SW1-3	SW1-4	SW1-7
Hardware setting		SW1-3 SW1-4 SW1-7	full duplex selection	Half duplex	OFF	ON	ON	ON	OFF
	1 2 3 4 5 6 7 8	SW1-6	Terminating resistance	ON: Provi	ded				

TC8-00

CN13

Parity: none, data length: 8 bits, stop bit: 2 bits, station No. 1 (fixed)
Because of the baud rate auto-detection feature (9600/19200/38400 bps), no baud rate setting is needed on the PLC.

CN11

Parity: none, data length: 8 bits, stop bit: 2 bits, station No. 1 (fixed)
Because of the baud rate auto-detection feature (9600/19200/38400 bps), no baud rate setting is needed on the PLC.

Setting Item	Register	Contents	Setting	Remarks
Software setting	D37F	Mode setting	8004H: Host communication mode	Setting changes take effect when the power is turned off and on again.

Setting Item	DIP Switch (SW5)		Contents				Sett	ting		
	ON	SW5-1 SW5-2	Half duplex /			SW5-1	SW5-2	SW5-3	SW5-4	SW5-5
Hardware setting		SW5-3 SW5-4 SW5-5	full duplex selection		Half duplex	OFF	OFF	ON	ON	ON
Setting	1 2 3 4 5 6 7 8			Ľ						
		SW5-7	Terminating resistance	c	ON: Provi	ded				

TC9-00

CN11

Setting Item	Register	Contents	Setting	Remarks
Software setting	D12E	Baud rate setting	0: 9600 bps 1: 19200 bps 2: 38400 bps	Setting changes take effect when the power is turned off and on again.
	D12F	Mode setting	0: Host communication mode	

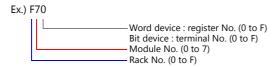
Parity: none, data length: 8 bits, stop bit: 2 bits, station No. 1 (fixed)

Available Device Memory

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

	Device Memory	TYPE	Remarks
D	(universal register 1)	00H	
В	(universal register 2)	01H	
Х	(input relay)	02H	XW as word device
Υ	(output relay)	03H	YW as word device
R	(internal relay)	04H	RW as word device
G	(extension internal relay 1)	05H	GW as word device
Н	(extension internal relay 2)	06H	HW as word device
L	(latch relay)	07H	LW as word device
S	(shift register)	08H	SW as word device
E	(edge relay)	09H	EW as word device
Р	(timer counter register 1/current value)	0AH	
٧	(timer counter register 2/set value)	0BH	
Т	(timer/contact)	0CH	TW as word device
С	(counter/contact)	0DH	CW as word device
Α	(special auxiliary relay)	0EH	AW as word device
U	(universal register 3)	0FH	TCCMWA / TCCMWS / TCCMOA / TC232CA only
М	(universal register 4)	10H	TCCMWA / TCCMWS / TCCMOA / TC232CA only
Q	(universal register 5)	11H	TCCMWA / TCCMWS / TCCMOA / TC232CA only
I	(input relay 2)	12H	IW as word device; supported by TCCMWA / TCCMWS / TCCMOA / TC232CA only
0	(output relay 2)	13H	OW as word device; supported by TCCMWA / TCCMWS/ TCCMOA / TC232CA only
J	(extension internal relay 3)	14H	JW as word device; supported by TCCMWA / TCCMWS / TCCMOA / TC232CA only
K	(extension internal relay 4)	15H	KW as word device; supported by TCCMWA / TCCMWS / TCCMOA / TC232CA only

Address denotations



Indirect Device Memory Designation

	15 8	7 0)
n+0	Models	Device Type	
n+1	Address No. (wo	ord designation)	
n+2	00	Bit designation	
n+3	00	Station number	

Address No. (n+1)

• Word device (D, B, V, P, U, M, Q)

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
Not used					Rack	No.		Мо	dule 1	No.	Resister No.				

Ex.) D 052F (Rack No. 5, Module No. 2, Resister No. F) n+1 = 0000 0010 1010 1111(BIN) = 02AF(HEX)

• Bit device (X, Y, R, G, H, L, S, E, T, C, A, I, O, J, K)

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
Not used								Rack	No.		Мо	dule N	Ю.		

Ex.) R 0F1A (Rack No. F, Module No. 1, Terminal No. A) n+1 = 0000 0000 0111 1001(BIN) = 0079(HEX)

Bit designation (n+2)

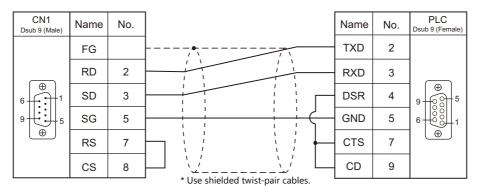
When you use the command of BSET/BCLR/BINV, set the terminal No.
 Ex.) R 0F1A (Rack No. F, Module No. 1, terminal No. A)
 n+2 = 000A(HEX)

15.1.2 Wiring Diagrams

When Connected at CN1:

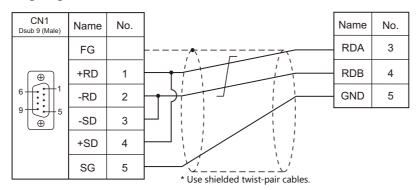
RS-232C

Wiring diagram 1 - C2

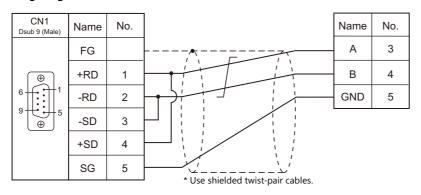


RS-422/RS-485

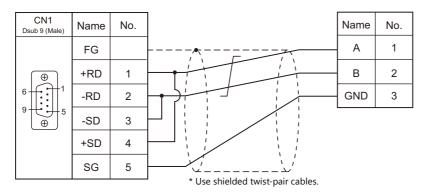
Wiring diagram 1 - C4



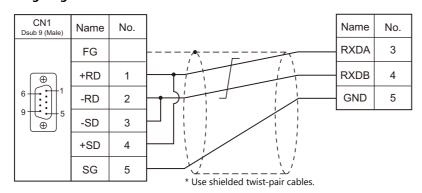
Wiring diagram 2 - C4



Wiring diagram 3 - C4



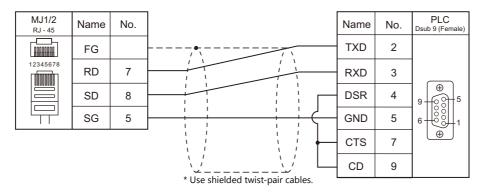
Wiring diagram 4 - C4



When Connected at MJ1/MJ2:

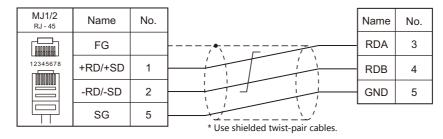
RS-232C

Wiring diagram 1 - M2

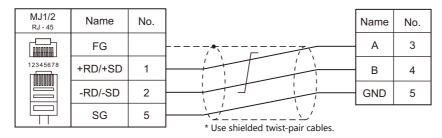


RS-422/RS-485

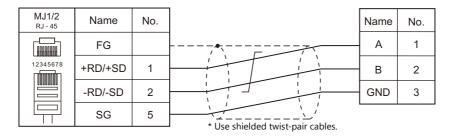
Wiring diagram 1 - M4



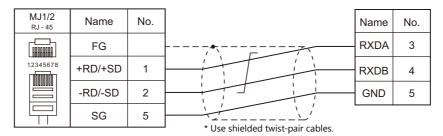
Wiring diagram 2 - M4



Wiring diagram 3 - M4



Wiring diagram 4 - M4



15.2 Temperature Controller/Servo/Inverter Connection

The controller models shown below can be connected.

Servo Amplifier

	PLC Selection on	Model		Port	Signal Level	Conne	Lst File	
	the Editor			POIL	Signal Level	CN1	MJ1/MJ2	LSt File
Ī	VELCONIC series	NCBOY-80	VLPSX-xxxPx-xRx	CN14	RS-485	Wiring diagram 1 - C4	Wiring diagram 1 - M4	_

15.2.1 VELCONIC Series

Communication Setting

Editor

Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1:n	
Signal Level	RS-422/485	
Baud Rate	4800 / 9600 / 19200 / 38400 / 57600 / 115K bps	
Parity	None / Odd / Even	
Data Length	7 / <u>8</u> bits	
Stop Bit	<u>1</u> / 2 bits	

Servo Amplifier

Parameter

The communication parameters can be set using keys attached to the servo amplifier. Set the following parameters under [Communication Setting] of the editor.

Parameter	Item	Setting	Remarks
A.n-	Axis number	0 to 63	
PP45	Baud rate setting	0: 4800 bps 1: 9600 bps 2: 19.2k bps 3: 38.4k bps 4: 57.6k bps 6: 115.2k bps	
PP48	RS-485 setting	0 0 Parity	The setting takes effect when the power is turned off and back on again.
UP01	Control mode	23: RS-485 (VLBus-A)	

Terminating resistance setting (SW1)

SW1	Item	Setting		
SW1-1	Touris discount de la constant		When one unit is connected	When multiple units are connected
■	Terminating resistance	SW1-1	OFF	ON
		SW1-2	ON	ON

Available Device Memory

The macro commands "PLC_CTL" is used for reading and writing data. For more information on the macro command, see " PLC_CTL" (page 15-13).

PLC_CTL

Macro command "PLC_CTL F0 F1 F2"

Contents	F0		F1 (= \$u n)	F2					
		n	Station number: 0000 to 003F (H)						
		n + 1	Command: 000C (H)						
			Data to write (D1/D0)						
			D1 D0						
			15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0						
		n + 2	Bit 0: IN58 : MPGM0 (MPG/step scale factor) Bit 1: IN59 : MPGM1 (MPG/step scale factor) Bit 2: IN5A : CCD0 (4-step electric current limitation select) Bit 3: IN5B : CCD1 (4-step electric current limitation select) Bit 4: IN5C : ACSEL0 (4-step acceleration/deceleration time select) Bit 5: IN5D : ACSEL1 (4-step acceleration/deceleration time select) Bit 6: IN5E : RPAMOD (parameter change mode) Bit 7: IN5F : RPASTB (parameter change strobe) Bit 8 to 14: IN50 to IN56 : PNCMD0 to PNCMD6 (point command) Bit 15: IN57 : —						
			Data to write (D3/D2)						
			D3 D2						
			15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0						
		n + 3	Bit 0 to 5, 8 to 15: IN40 to IN4D : OVR0 to OVR13 (override)						
Device			Bit 6: IN4E : — Bit 7: IN4F : DCNT (start signal confirm)						
memory information	1 - 8 (PLC1 - 8)		Data to write (D7/D6/D5/D4)	7					
designation		n + 4 to	n + 4 to	D7 D6 D5 D4					
		n + 5							
			Bit 0 to 31: IN20 to IN3F : PCMD0 to PCMD31 (position command)						
			Data to write (D9/D8)						
			D9 D8						
			15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0						
		n + 6	Bit 0: IN18 : TEACH (teaching) Bit 1: IN19 : MODE0 (operation mode) Bit 2: IN1A : MODE1 (operation mode) Bit 3: IN1B : CSEL0 (command select) Bit 4: IN1C : CSEL1 (command select) Bit 5: IN1D : FSEL0 (speed select) Bit 6: IN1E : FSEL1 (speed select) Bit 7: IN1F : PCLR (current value clear) Bit 8: IN10 : RUN (running) Bit 9: IN11 : RESET (reset) Bit 10: IN12 : START (start) Bit 11: IN13 : JOGP (jog +) Bit 12: IN14 : JOGM (jog -) Bit 13: IN15 : FSTP (temporary stop) Bit 14: IN16 : LSSEL (LS positioning select) Bit 15: IN17 : ECLR (deviation counter clear)						

Contents	F0		F1 (= \$u n)	F2			
		n + 7	Data to read (D1'/D0') * D1'				
		n + 8	Data to read (D3'/D2') * D3'				
Device memory information designation	1 - 8 (PLC1 - 8)	n + 9 to n + 10	Data to read (D7'/D6'/D5'/D4') * D7' D6' D5' D4' 31 to 24 23 to 16 15 to 8 7 to 0 Bit 0 to 31: OUT20 to OUT3F : POSI0 to POSI31 (current value)	7			
designation		Data to read (D9'/D8') * D9' D8' 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 Bit 0: OUT18: LSALM (LS error) Bit 1: OUT19: TENBL (teaching enabled) Bit 2: OUT1A: BLV (battery voltage drop) Bit 3: OUT1B: WARN (warning) Bit 4: OUT1C: POK (positioning OK) Bit 5: OUT1D: MFEED (rotation monitor) Bit 6: OUT1E: MCURR (current monitor) Bit 7: OUT1F: SSTP (stopped due to error) Bit 8: OUT10: ST (servo normal output) Bit 9: OUT11: SRDY (servo ready) Bit 10: OUT12: GRUN (servo locked) Bit 11: OUT13: MZM (home position memorize in progress) Bit 12: OUT14: HOME (stopped at home position) Bit 13: OUT15: DEN (operation finish) Bit 14: OUT16: INP (in position) Bit 15: OUT17: AFSTP / CLA (temporarily stopped/current control in progress)					

Return data: Data stored from servo amplifier to V series

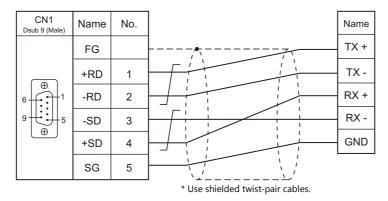
^{*} Data must be written before executing reading of data. Specify control values of the servo amplifier for the device memory address of data to write (n + 2 to n + 6). Then data is stored in the device memory address of data to read (n + 7 to n + 11).

15.2.2 Wiring Diagrams

When Connected at CN1:

RS-422/RS-485

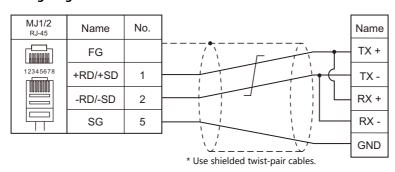
Wiring diagram 1 - C4



When Connected at MJ1/MJ2:

RS-422/RS-485

Wiring diagram 1 - M4



MEMO
Please use this page freely.

16.TURCK

16.1 PLC Connection

16.1 PLC Connection

Ethernet Connection

PLC Selection on the Editor	СРИ	LAN Port	TCP/IP	UDP/IP	Port No.	Keep Alive ^{*1}	Ladder Transfer ^{*2}	Lst File
BL Series Distributed I/O	BL20-GW-EN BL20-PG-EN	10/100 MBit	0	~	502	0		BL Mod Eth. Lst
(MODBUS TCP/IP)	BL67-GW-EN BL67-PG-EN	ETHERNET	0	×	(Max. 10 units)	O	^	BL_IVIOU_EUI. LSU

^{*1} For KeepAlive functions, see "1.3.2 Ethernet Communication".
*2 For the ladder transfer function, see the V9 Series Reference Manual.

16.1.1 BL Series Distributed I/O (MODBUS TCP/IP)

Communication Setting

Editor

Communication setting

Make the following settings on the editor. For more information, see "1.3.2 Ethernet Communication".

- IP address for the V9 unit
 - When specified on the screen program: [System Setting] → [Hardware Setting] → [Local Port IP Address]
 - When specified on the V9 unit: Local mode → [LAN Setting]
- Port number for the V9 unit (for communication with PLC)
 [System Setting] → [Hardware Setting] → [PLC Properties] → [Communication Setting]
- IP address and port number of the PLC
 Register on the [PLC Table] in [System Setting] → [Hardware Setting] → [PLC Properties] → [Target Settings].

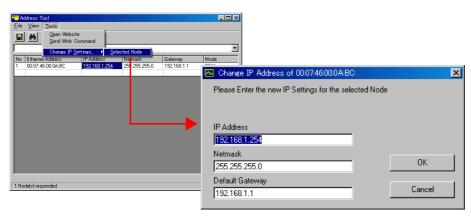
PLC

Configure the IP address using the rotary switch and "I/O Assistant" ladder software.

Rotary switch

SW	Setting	Remarks	
IP Address Setting			
$ \begin{bmatrix} 8 & 0 & 1 & 2 \\ 7 & 0 & 5 & 4 \\ X & 100 \end{bmatrix} \begin{bmatrix} 8 & 0 & 1 & 2 \\ 7 & 0 & 5 & 4 \\ X & 100 \end{bmatrix} \begin{bmatrix} 8 & 0 & 1 & 2 \\ 7 & 0 & 5 & 4 \\ X & 10 \end{bmatrix} \begin{bmatrix} 8 & 0 & 1 & 2 \\ 7 & 0 & 5 & 4 \\ X & 10 \end{bmatrix} $	000: 192.168.1.254 1 to 254: Specify the least significant byte of the IP address. 500: Specify using I/O Assistant	For 1 to 254, the three high-order bytes enable I/O Assistant settings.	

Address tool (I/O Assistant)



Item	Setting	Remarks
IP Address	Set the IP address of the PLC.	
Netmask	Set the subnet mask of the PLC.	
Default Gateway	Specify according to the environment.	

Available Device Memory

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

Device Memory		Remarks
	02H	

17. UNIPULSE

17.1 Temperature Controller/Servo/Inverter Connection

17.1 Temperature Controller/Servo/Inverter Connection

Digital Indicator

PLC Selection	Model	Port	Signal Level	Conn	ection	Lst File
on the Editor	Model	POIL	Signal Level	CN1	MJ1/MJ2	LST FIIE
F340A	F340A	Option RS-232C interface	RS-232C	Wiring diagram 1 - C2	Wiring diagram 1 - M2	UP_F340A.Lst
F371	F371	Built-in RS-232C interface	RS-232C	Wiring diagram 2 - C2	Wiring diagram 2 - M2	UP F371.Lst
F3/1	F3/1	Option RS-485 interface	RS-485	Wiring diagram 1 - C4	Wiring diagram 1 - M4	OF_F3/1.LSt

Load Cell Indicator

PLC Selection	Model	Port	Signal Level	Conne	ection	Lst File
on the Editor	Model	FOIL	Signal Level	CN1	MJ1/MJ2	LSCFIIE
F800	F800	Option RS-232C interface	RS-232C	Wiring diagram 1 - C2	Wiring diagram 2 - M2	UP F800.Lst
1800	F800 F800	Ontion RS-485	RS-485	Wiring diagram 1 - C4	Wiring diagram 1 - M4	OF_F800.LSt
F805A	F805A	RS-232C interface	RS-232C	Wiring diagram 1 - C2	Wiring diagram 2 - M2	UP F805A.Lst
FOUSA	FBUSA	Option RS-485 interface	RS-485	Wiring diagram 1 - C4	×	OF_F803A.LSt

Weighing Controller

PLC Selection	Model	Model Port Signal Level		Conne	ection	Lst File
on the Editor	Model	FOIL	Signal Level	CN1	MJ1/MJ2	LSCFIIE
F720A	F720A	Built-in RS-232C interface	RS-232C	Wiring diagram 3 - C2	Wiring diagram 3 - M2	UP F720A.Lst
F720A	F720A	Option RS-485 interface	RS-485	Wiring diagram 1 - C4	Wiring diagram 1 - M4	OF_F720A.LSt

17.1.1 F340A

Communication Setting

Editor

Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1:1/ <u>1:n</u> /Multi-link2/Multi-link2(Ethernet)/ 1:n Multi-link2(Ethernet)	
Signal Level	RS-232C / RS-422/485	
Baud Rate	4800 / <u>9600</u> bps	
Data Length	<u>7</u> / 8 bits	
Stop Bit	<u>1</u> / 2 bits	
Parity	None / <u>Odd</u> / Even	
Target Port No.	0 to 31	

Digital Indicator

The communication parameters can be set using keys attached to the digital indicator. Be sure to match the settings to those made under [Communication Setting] of the editor.

Setting mode 4

(Underlined setting: default)

Parameter	Item	Setting	Setting Example	
Mode 4 / RS-232C	Communication mode	0: Communication mode 0 *		
● HI ○ OK ○ LOW ● PEAK ○ HOLD	Baud rate	2: 4800 bps 3: 9600 bps	02000 Communication mode:0 Baud rate: 9600 bps	
● Blink ○Off	Character length	0: 7 bits 1: 8 bits		
-	Parity bit	0: None 1: Odd 2: Even	Character length: 7 bits Parity bit: Odd Stop bit: 1 bit	
	Stop bit	0: 1 bit 1: 2 bits		

^{*} When establishing a communication with the V series, be sure to select "communication mode 0".

Available Device Memory

The available setting range of device memory varies depending on the model. Be sure to set within the range available for the model to be used. Use [TYPE] when assigning indirect device memory for macro programs.

	Device Memory	TYPE	Remarks	
R	(specified value, status read out)	00H	Double-word, read only	
W	(setting value)	01H	Double-word, W24 and W34: read only	

R (Specified Value, Status Read Out)

Address	Name	Remarks
0	Specified value read out	Read only
10	Status read out Bit	Read only

W (Setting Value)

Address	Name	Remarks
01	Upper limit	*1
02	Lower limit	*1
03	Comparison between upper limit and lower limit	*1
04	Hysteresis	*1
05	Digital offset	*1
06	Close to zero	*1
11	Digital filter	*1
12	Analog filter	*1
13	MD (stabilized time)	*1
14	MD (stabilized width)	*1
15	Zero tracking (time)	*1
16	Zero tracking (width)	*1
17	Hold mode	*1
18	Automatic print	*1
19	Hold value print	*1
21	LOCK	
22	Minimum scale	*2
23	Display count	*2
24	Applied voltage	Read only
31	BCD data update rate	*1
32	RS-232C	*1
33	D/A zero setting	*1
34	D/A full scale setting	Read only

PLC_CTL

Macro command "PLC_CTL F0 F1 F2"

Contents	F0		F2	
Hold	1 - 8	n	Station number	2
Hold	(PLC1 - 8)	n + 1	Command: 0	
Hold reset	1 - 8	n	Station number	2
noid reset	(PLC1 - 8)	n + 1	Command: 1	2
Digital zero *1	1 - 8 (PLC1 - 8)	n	Station number	2
Digital Zelo		n + 1	Command: 2	
Digital zero reset *1	1 - 8	n	Station number	2
Digital zero reset	(PLC1 - 8)	n + 1	Command: 3	2
Print command *2	1 - 8	n	Station number	- 2
Fillit Collinatio	(PLC1 - 8)	n + 1	Command: 4	2

^{*1} Valid only when "1" is set for the calibration value "LOCK". The calibration value "LOCK" is specified in "setting mode 3" of F340A.
*2 Outputs a print command to SIF.

^{*1} Writing is prohibited when the setting value is "LOCK". The setting value "LOCK" is specified in "setting mode 3" of F340A.
*2 Writing is prohibited when the calibration value is "LOCK". The calibration value "LOCK" is specified in "setting mode 3" of F340A.

17.1.2 F371

Communication Setting

Editor

Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1:1/1:n/Multi-link2/Multi-link2(Ethernet)/ 1:n Multi-link2(Ethernet)	
Signal Level	<u>RS-232C</u> / RS-422/485	
Baud Rate	4800 / <u>9600</u> / 19200 bps	
Data Length	<u>7</u> / 8 bits	
Stop Bit	<u>1</u> / 2 bits	
Parity	None / Odd / Even	
Target Port No.	0 to 31	
CR/LF	CR/LF / <u>CR</u>	

Digital Indicator

The communication parameters can be set using keys attached to the digital indicator. Be sure to match the settings to those made under [Communication Setting] of the editor.

Built-in RS-232C Interface

Communication setting

(Underlined setting: default)

Item	Setting	Setting Example
Communication Mode	Communication mode 0 *	Communication mode 0
Baud Rate	4800 / <u>9600</u> / 19200 bps	9600 bps
Character Length	7 / <u>8</u> bits	7 bits
Stop Bit	<u>1</u> / 2 bits	1 bit
Parity Bit	None / Odd / Even	None
Terminator	<u>CR</u> / CR + LF	CR

^{*} When establishing a communication with the V series, be sure to select "communication mode 0".

RS-485 Communication Interface (Option)

Option setting

(Underlined setting: default)

Item	Setting	Setting Example
Communication Mode	Communication mode 0 *	Communication mode 0
Baud Rate	4800 / <u>9600</u> / 19200 bps	9600 bps
Character Length	7 / <u>8</u> bits	7 bits
Stop Bit	1 / 2 bits	1 bit
Parity Bit	None / Odd / Even	None
Terminator	<u>CR</u> / CR + LF	CR
ID	<u>0000</u> to 9999	0000
Terminating Resistance	With terminating resistance / Without terminating resistance	With terminating resistance
Communication Mode	2-wire / <u>4-wire</u>	2-wire

 $^{^{\}star}$ $\,$ When establishing a communication with the V series, be sure to select "communication mode 0".

Available Device Memory

The available setting range of device memory varies depending on the model. Be sure to set within the range available for the model to be used. Use [TYPE] when assigning indirect device memory for macro programs.

	Device Memory	TYPE	Remarks
R	(specified value, status read out)	00H	Double-word, read only
W	(setting value)	01H	Double-word
RG	(waveform data read out)	02H	Double-word, read only

R (Specified Value, Status Read Out)

Address	Name	Remarks
0	Specified value read out	Read only
10	Status read out Bit	Read only
11	Status read out Bit	Read only

W (Setting Value)

Address	Name	Remarks
11	Higher-higher limit	*1
12	Higher limit	*1
13	Lower limit	*1
14	Lower-lower limit	*1
15	Hysteresis	*1
48	Digital offset setting	*2
16	Close to zero	*1
21	Hold mode	
81	Hold range setting	
22	Hold time	*1
23	Auto start level	*1
24	Minimum count	
25	Local maximum value detection level	
26	Inflection point judgment value	
27	Detection time A	
28	Detection time B	
31	Graph mode	
32	Interval time	
33	Trigger level	*1
34	Level detection mode	*1
1F	Setting CH	
44	Calibration value select	*2
29	Hold point shift amount	

- *1 Writing is prohibited when the setting value is "LOCK". The setting value "LOCK" is specified for "motion setting" of F371.
 *2 Writing is prohibited when the calibration value is "LOCK". The calibration value "LOCK" is specified for "motion setting" of F371.

RG (Waveform Data Read Out)

Address	Name	Remarks
0	Waveform data 0	Read only
1	Waveform data 1	Read only
:	:	:
199	Waveform data 199	Read only

PLC_CTL

Macro command "PLC_CTL F0 F1 F2"

Contents	F0	F1 (= \$u n)		F2
Digital zero	1 - 8	n	Station number	- 2
Digital Zelo	(PLC1 - 8)	n + 1	Command: 2	
Digital zero reset	1 - 8	n	Station number	2
Digital Zelo leset	(PLC1 - 8)	n + 1	Command: 3	
Print command *1	1 - 8	n	Station number	- 2
Print Command	(PLC1 - 8)	n + 1	Command: 4	2
		n	Station number	
Waveform hold point data	1 - 8	n + 1	Command: 5	2
read out *2	ad out *2 (PLC1 - 8)		Data No.	2
		n + 3 to n + 4	Data	1

Return data: Data stored from controller to V series

^{*1} Outputs a print command to SIF.
*2 Return data is given when "HOLD" is set to ON on the hold screen of F371 and "START" is selected on the graph screen.

17.1.3 F800

Communication Setting

Editor

Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1:1/1:n/Multi-link2/Multi-link2(Ethernet)/ 1:n Multi-link2(Ethernet)	
Signal Level	<u>RS-232C</u> / RS-422/485	
Baud Rate	4800 / <u>9600</u> / 19200 / 38400 bps	
Data Length	<u>7</u> / 8 bits	
Stop Bit	<u>1</u> / 2 bits	
Parity	None / <u>Odd</u> / Even	
Target Port No.	0 to 31	
CR/LF	<u>CR/LF</u> / CR	

Load Cell Indicator

The communication parameters can be set using keys attached to the load cell indicator. Be sure to match the settings to those made under [Communication Setting] of the editor.

Setting mode 2

(Underlined setting: default)

Parameter	Item	Setting	Setting	j Example
RS-232C/485 I/F setting	Baud rate	2: 4800 bps 3: 9600 bps 4: 19200 bps 6: 38400 bps		
	Character length	0: 7 bits 1: 8 bits	30101 Baud rate: 9600 bps Character length: 7 bits Parity bit: Odd Stop bit: 1 bit	
	Parity bit	0: None 1: Odd 2: Even		7 bits Odd 1 bit
	Stop bit	0: 1 bit 1: 2 bits	Terminator:	CR + LF
	Terminator	0: CR 1: CR + LF		

Setting mode 3 (only for RS-485 communication)

(Underlined setting: default)

Parameter	Item	Setting	Setting Example
ID number			
3 9	ID*	<u>0000</u> to 9999	0001

^{*} When multiple units of F800 are connected, the ID number must be set to a value other than "0000".

Available Device Memory

The available setting range of device memory varies depending on the model. Be sure to set within the range available for the model to be used. Use [TYPE] when assigning indirect device memory for macro programs.

	Device Memory	TYPE	Remarks
R	(specified value, status read out)	00H	Double-word, read only
W	(setting value)	01H	Double-word

R (Specified Value, Status Read Out)

Address	Name	Remarks
0000	Total weight read out	Read only
0001	Net weight read out	Read only
0002	Tare read out	Read only
0010	Status read out 1 HOLD	Read only
0011	Status read out 1 Zero error	Read only
0012	Status read out 1 Stabilized	Read only
0013	Status read out 1 Taring	Read only
0014	Status read out 1 Total weight display / net weight display	Read only
0015	Status read out 1 LOCK / terminal at rear	Read only
0020	Status read out 2 Bulk supply	Read only
0021	Status read out 2 Medium supply	Read only
0022	Status read out 2 Fine supply	Read only
0023	Status read out 2 Insufficient	Read only
0024	Status read out 2 Correct amount	Read only
0025	Status read out 2 Excessive amount	Read only
0026	Status read out 2 Finish	Read only
0030	Status read out 3 Close to zero	Read only
0031	Status read out 3 Lower limit	Read only
0032	Status read out 3 Upper limit	Read only
0033	Status read out 3 Discharge	Read only
0040	Status read out 4 Weight error	Read only
0041	Status read out 4 Error	Read only
0042	Status read out 4 Operation mode	Read only
0043	Status read out 4 Weight value overflow	Read only
0044	Status read out 4 Calibration error	Read only
0045	Status read out 4 Sequence error	Read only
0050	Cumulative count read out	Read only
0051	Cumulative value read out	Read only

W (Setting Value)

Address	Name	Remarks
00	Code No.	
10	Bulk supply	*1
11	Below the preset amount	*1
12	Preset amount	*1
13	Excessive amount	*1
14	Insufficient	*1
15	Gap	*1
16	Automatic gap control value	*1, *2
17	Offset supply time	*1, *2
20	Timer	*2
21	Comparison prohibit time	*2
22	Upper limit	*2
23	Lower limit	*2
24	Close to zero	
25	Taring setting	
26	AZ count	*2
27	Judgment count	*2
28	Discharge time	*2
29	Weighing start time	

Address	Name	Remarks
30	Sequence mode	*2
31	Weighing function 1	*2
32	Weighing function 2	*2
33	Weighing function 3	*2
34	Function key prohibited	*2
35	Filter	*2
36	Motion detection	*2
37	Zero tracking	*2
40	Weight value	*2
41	Maximum weighing value	*2
42	Minimum scale	*2
43	Net weight excessive	*2
44	Total weight excessive	*2
45	Function select	*2
46	Gravitational acceleration offset	*2
50	Maximum weight	*1, read only
51	Minimum weight	*1, read only
52	Maximum - minimum	*1, read only
53	Average weight	*1, read only
54	Population standard deviation	*1, read only
55	Sample standard deviation	*1, read only

PLC_CTL

Macro command "PLC_CTL F0 F1 F2"

Contents	F0	F1 (= \$u n)			
		n	Station number		
7 I'l +! ^1	1 - 8 (PLC1 - 8)	n + 1	Command: 0	2	
	(I LCI O)	n + 2	Error result		
		n	Station number		
Span calibration *1	1 - 8 (PLC1 - 8)	n + 1	Command: 1	2	
	(I LCI O)	n + 2	Error result		
Switching to total	1 - 8	n	Station number	2	
weight display *2	(PLC1 - 8)	n + 1	Command: 2	2	
Switching to net weight	1 - 8	n	Station number	2	
display *2	(PLC1 - 8)	n + 1	Command: 3	2	
Taring	1 - 8	n	Station number	2	
lamig	(PLC1 - 8)	n + 1	Command: 4	2	
Taring reset	1 - 8	n	Station number	2	
laning reset	(PLC1 - 8)	n + 1	Command: 5	2	
Digital zero	1 - 8 (PLC1 - 8)	n	Station number	2	
Digital Zelo		n + 1	Command: 6	2	
Digital zero reset	1 - 8	n	Station number	2	
Digital Zelo leset	(PLC1 - 8)	n + 1	Command: 7	2	
Totalize command	1 - 8	n	Station number	2	
Totalize communa	(PLC1 - 8)		Command: 8	2	
Cumulative data clear	ivo data clear 1 - 8		Station number	2	
Cumulative data cicar	(PLC1 - 8)	n + 1	Command: 9	2	
Cumulative data all	1 - 8	n	Station number	2	
clear	(PLC1 - 8)	n + 1	Command: 10	2	
		n	Station number		
Cumulative data read out	1 - 8	n + 1	Command: 11	2	
	(PLC1 - 8)	n + 2	Code No.	2	
		n + 3 - n + 4	Weighing value		
		n	Station number	2	
Weighing data read out	1 - 8	n + 1	Command: 12		
vveigning data read out	(PLC1 - 8)	n + 2	Code No.		
		n + 3 - n + 4	Weighing value		

^{*1} Set for each code.
*2 Writing is prohibited when "LOCK" is set.
"LOCK" can be set by short-circuiting the LOCK terminal on the terminal block at the rear of F800. For more information, refer to the instruction manual of F800.

Contents	F0	F1 (= \$u n)		F2
Time-out change *3 1 - 8 (PLC1 - 8)		n	Station number	
		n + 1	Command: 13	3
	(1202 0)	n + 2	Time-out value (ms)	

Return data: Data stored from controller to V series

- *1 Calibration is performed based on the value at W40, W41 and W42. Since a response is given after completion of the calibration on F800, it takes time before the receipt of a response after the calibration
- since a response is given after completion of the calibration on F800, it takes time before the receipt of a response after the calibration command is executed. Before executing the calibration command, execute the time-out change command.
 The display cannot be changed when "1: external input mode" is set for "total weight/net weight display change" of extended function 1 in setting mode 4 of F800.
 Used to change the time-out time of V9 to apply when the PLC_CTL command is used. It takes time before a response is sent back after the calibration command is executed. Set a time-out time according to your use environment. The default value is "0", and the time set for [Time-out Time] under [Communication Setting] in the [PLC Properties] dialog is applied.

17.1.4 F805A

Communication Setting

Editor

Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1 : 1 / <u>1 : n</u> / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet)	
Signal Level	<u>RS-232C</u> / RS-422/485	
Baud Rate	4800 / <u>9600</u> / 19200 bps	
Data Length	<u>Z</u> / 8 bits	
Stop Bit	<u>1</u> / 2 bits	
Parity	None / <u>Odd</u> / Even	
Target Port No.	0 to 31	
CR/LF	<u>CR/LF</u> / CR	

Load Cell Indicator

The communication parameters can be set using keys attached to the load cell indicator. Be sure to match the settings to those made under [Communication Setting] of the editor.

Built-in RS-232C Interface

Communication setting

(Underlined setting: default)

Setting Items	Setting Remarks		
Baud rate selection	4800 / <u>9600</u> / 19200 bps		
Character length	Z / 8 bits		
Parity bit	None / <u>Odd</u> / Even		
Stop bit	<u>1</u> /2 bits		
Terminator	CR / CR + LF		

RS-485 Communication Interface (Option)

Setting mode 4

(Underlined setting: default)

Item	Setting Remarks		
Baud rate	4800 / <u>9600</u> / 19200 bps		
Character length	/ 8 bits		
Parity bit	None / <u>Odd</u> / Even		
Stop bit	<u>1</u> / 2 bits		
Terminator	CR / CR + LF		
ID *	<u>0</u> - 99		

 $^{^{\}star}~$ When multiple units of F805A are connected, the ID number must be set to a value other than "0".

Rt switch

Rt switch	OFF	ON	Remarks
Rt OFF	Terminating resistance OFF	Terminating resistance ON	

Available Device Memory

The available setting range of device memory varies depending on the model. Be sure to set within the range available for the model to be used. Use [TYPE] when assigning indirect device memory for macro programs.

	Device Memory	TYPE	Remarks
R	(specified value / status read out)	00H	Double-word, read only
W	(setting value)	01H	Double-word

R (Specified Value / Status Read Out)

Address	Name	Remarks
0000	Total weight read out	Read only
0001	Net weight read out	Read only
0002	Tare read out	Read only
0010	Status read out 1 Hold	Read only
0011	Status read out 1 Zero error	Read only
0012	Status read out 1 Stabilized	Read only
0013	Status read out 1 Taring	Read only
0014	Status read out 1 Weight display	Read only
0015	Status read out 1 LOCK / terminal at rear	Read only
0016	Status read out 1 LOCK (soft)	Read only
0020	Status read out 2 Bulk supply	Read only
0021	Status read out 2 Medium supply	Read only
0022	Status read out 2 Fine supply	Read only
0023	Status read out 2 Insufficient	Read only
0024	Status read out 2 Correct amount	Read only
0025	Status read out 2 Excessive amount	Read only
0026	Status read out 2 Finish	Read only
0030	Status read out 3 Close to zero	Read only
0031	Status read out 3 Lower limit	Read only
0032	Status read out 3 Upper limit	Read only
0033	Status read out 3 Discharge	Read only
0034	Status read out 3 Total final	Read only
0040	Status read out 4 Weight error	Read only
0041	Status read out 4 Error	Read only
0042	Status read out 4 Operation mode	Read only
0043	Status read out 4 Weight value overflow	Read only
0044	Status read out 4 Calibration error	Read only
0045	Status read out 4 Sequence error	Read only
0050	Cumulative count read out	Read only
0051	Cumulative value read out	Read only

W (Setting Value)

Address	Name	Remarks
0000	Code No.	*1
0100	Bulk supply	*1
0110	Below the preset amount	*1
0120	Preset amount	*1
0130	Excessive amount	*1
0140	Insufficient	*1
0150	Gap	*1
0160	Automatic gap control value	*1, *2
0170	Offset supply time	*1, *2
0180	Total comparison selection	*1
0190	Total final	*1
01A0	Total times	*1
0200	With or without upper and lower limit comparison	*2
0210	Comparison between upper limit and lower limit	*2
0220	Upper limit	*2
0230	Lower limit	*2
0240	With or without close to zero comparison	*2

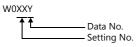
Address	Name	Remarks
0250	Close to zero	*2
0260	With or without comparison between excess and insufficient	*2
0270	Comparison between excess and insufficient mode	*2
0280	Completion signal output mode	*2
0290	Completion output time	*2
02A0	Judgment time	*2
02B0	Comparison prohibit time	*2
02C0	Cut-out control mode	*2
02D0	Automatic gap correction factor	*2
02E0	With or without automatic gap correction	*2
02F0	Average times for automatic gap correction	*2
0300	Display count	*2
0310	Digital filter	*2
0320	Analog filter	*2
0330	Stabilized time filter	*2
0330	MD mode	*2
0340	MD time	*2
0350	MD width	*2
0360	ZT time	*2
0370	ZT width	*2
0380	DZ control value	*2
0400	Sequence mode	*2
0401	Near zero check at start	*2
0402	Weight value check at start	*2
0403	With or without offset supply	*2
0404	Discharge gate control	*2
0410	Judgment count	*2
0420	AZ count	*2
0430	Discharge time	*2
0440	START/STOP key prohibit	*2
0500	Digital taring	*2
0501	G/N display switch	*2
0502	Sign for discharge control	*2
0503	TARE/DZ key prohibit	*2
0504	GROSS/NET key prohibit	*2
0510	Taring setting	*2
0520	Automatic totalize command	*2
0530	Weighing code specification	*2
0540	Setting code specification	*2
0550	Setting per code key prohibit	*2
0600	Weight value	*3
0610	Maximum weighing value	*3
		*3
0620	Minimum scale	*2
0630	Net weight excessive Total weight excessive	*2
0640	3	*3
0650	Decimal place	
0660	Unit setting	*2
0670	1/4 memory	*2
0680	Gravitational acceleration offset	*2
0690	Applied voltage	*3
0700	Graphic mode	*2
0710	Trigger level	*2
0720	X (time) axis end point	*2
0730	Y (weight) axis start point	*2
0740	Z (weight) axis end point	*2
0800	Average weight	Read only
0810	Maximum weight	Read only
0820	Minimum weight	Read only
	Deputation standard deviation	Read only
0830	Population standard deviation	nead only
0830 0840	Sample standard deviation	Read only
0840	Sample standard deviation	Read only

Address	Name	Remarks
0920	System speed	*2
0930	Backlight ON	*2
0940	Backlight OFF	*2
0A00	Totalize command	*2
0A01	One-touch taring	*2
0A02	Taring range	*2
0A03	Taring display	*2
0A04	Digital taring expansion	*2
0A10	SIFII ID	*2
0A20	Overscale display	*2
0B00	D/A output mode	*2
0B10	D/A zero output	*2
0B20	D/A full scale	*2
0B60	Data update rate	*2
0B70	D/A output ch	*2

- *1 Specify for each code.
 *2 Writing is prohibited when "LOCK (soft)" is set.
 *3 Writing is prohibited when "LOCK (soft, hard)" is set.

Address denotations

The address denotation of the device memory W is shown below.



PLC_CTL

Macro command "PLC_CTL F0 F1 F2"

Descriptions	F0		F1 (=\$u n)	F2
		n	Station number	
Zero calibration	1 - 8 (PLC1 - 8)	n + 1	Command: 0	2
	(1201 0)	n + 2	Error result	
		n	Station number	
Span calibration	1 - 8 (PLC1 - 8)	n + 1	Command: 1	2
	(1201 0)	n + 2	Error result	
Display change total weight	1 - 8	n	Station number	2
Display Change total weight	(PLC1 - 8)	n + 1	Command: 2	2
Display change net weight	1 - 8	n	Station number	2
Display change het weight	(PLC1 - 8)	n + 1	Command: 3	2
Taring	1 - 8	n	Station number	2
lating	(PLC1 - 8)	n + 1	Command: 4	2
Taring reset	1 - 8	n	Station number	2
lating reset	(PLC1 - 8)	n + 1	Command: 5	
Digital zero	1 - 8	n	Station number	2
Digital Zelo	(PLC1 - 8)	n + 1	Command: 6	2
Digital zero reset	1 - 8	n	Station number	2
Digital Zelo leset	(PLC1 - 8)	n + 1	Command: 7	2
Totalize command	1 - 8	n	Station number	2
lotalize command	(PLC1 - 8)	n + 1	Command: 8	2
Cumulative data clear	1 - 8	n	Station number	2
Cumulative data clear	(PLC1 - 8)	n + 1	Command: 9	2
Cumulative data all clear	1 - 8	n	Station number	2
Cumulative data all clear	(PLC1 - 8)	n + 1	Command: 10	
		n	Station number	
Cumulative data read out	1 - 8	n + 1	Command: 11	2
Camadave data read out	(PLC1 - 8)	n + 2	Code No.	
		n + 3 - n + 4	Weighing value	

Descriptions	F0	F1 (=\$u n)		F2
		n	Station number	
Weighing data read out	1 - 8	n + 1	Command: 12	2
Weighing data read out	(PLC1 - 8)	n + 2	Code No.	2
		n + 3 - n + 4	Weighing value	
		n	Station number	
Time-out change *1	1 - 8 (PLC1 - 8)	n + 1	Command: 13	3
	(. 202 0)	n + 2	Time-out value (ms)	
Backlight ON	1 - 8	n	Station number	2
bucklight ON	(PLC1 - 8)	n + 1	Command: 14	2

Return data: Data stored from controller to V series

^{*1} Used to change the time-out time of the V9 to apply when the PLC_CTL command is used. It takes time before a response is sent back after the calibration command is executed. Set a time-out time according to your use environment. The default value is "0", and the value varies according to the time set for [Time-out Time] under [Communication Setting] in the [PLC Properties] dialog.

17.1.5 F720A

Communication Setting

Editor

Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1:1/1:n/Multi-link2/Multi-link2(Ethernet)/ 1:n Multi-link2(Ethernet)	
Signal Level	<u>RS-232C</u> / RS-422/485	
Baud Rate	4800 / <u>9600</u> / 19200 / 38400 bps	
Data Length	<u>7</u> / 8 bits	
Stop Bit	<u>1</u> / 2 bits	
Parity	None / <u>Odd</u> / Even	
Target Port No.	0 to 31	
CR/LF	<u>CR/LF</u> / CR	

Weighing Controller

The communication parameters can be set using keys attached to the weighing controller. Be sure to match the settings to those made under [Communication Setting] of the editor.

Built-in RS-232C Interface

Setting mode 4

(Underlined setting: default)

Parameter	Item	Setting	Setting Exa	mple
RS-232C I/F setting	Baud rate	2: 4800 bps 3: 9600 bps 4: 19200 bps 5: 38400 bps	30101	
	Character length	0: 7 bits 1: 8 bits	Baud rate: Character length:	9600 bps 7 bits
	Parity bit	0: None 1: Odd 2: Even	Parity bit: Stop bit: Communication mode:	Odd 1 bit Communication
	Stop bit	0: 1 bit 1: 2 bits		mode 0 (CR + LF)
	Communication mode	0: Communication mode 0 (CR) 1: Communication mode 0 (CR + LF)		

RS-485 Communication Interface (Option)

Setting mode 4

(Underlined setting: default)

Parameter	Item	Setting	Setting Example
RS-485 I/F setting	Baud rate	2: 4800 bps 3: 9600 bps 4: 19200 bps 5: 38400 bps	20101
	Character length	0: 7 bits 1: 8 bits	30101 Baud rate: 9600 bps
	Parity bit	0: None 1: Odd 2: Even	Character length: 7 bits Parity bit: Odd Stop bit: 1 bit
	Stop bit	0: 1 bit 1: 2 bits	Terminator: CR + LF
	Terminator	0: CR 1: CR + LF	
ID setting	ID*	<u>0000</u> to 9999	0001

^{*} When multiple units of F720A are connected, the ID number must be set to a value other than "0000".

Rt switch

Rt switch	OFF	ON	Remarks
ON OFF	Terminating resistance OFF	Terminating resistance ON	

Available Device Memory

The available setting range of device memory varies depending on the model. Be sure to set within the range available for the model to be used. Use [TYPE] when assigning indirect device memory for macro programs.

Device Memory		TYPE	Remarks
R	(specified value, status read out)	00H	Double-word, read only
W	(setting value)	01H	Double-word

R (Specified Value, Status Read Out)

Address	Name	Remarks
0000	Total weight read out	Read only
0001	Net weight read out	Read only
0002	Tare read out	Read only
0010	Status read out 1 Hold	Read only
0011	Status read out 1 Zero error	Read only
0012	Status read out 1 Stabilized	Read only
0013	Status read out 1 Taring	Read only
0014	Status read out 1 Weight display	Read only
0015	Status read out 1 Rear terminal LOCK	Read only
0020	Status read out 2 Bulk supply	Read only
0021	Status read out 2 Medium supply	Read only
0022	Status read out 2 Fine supply	Read only
0023	Status read out 2 Insufficient	Read only
0024	Status read out 2 Correct amount	Read only
0025	Status read out 2 Excessive amount	Read only
0026	Status read out 2 Finish	Read only
0030	Status read out 3 Close to zero	Read only

Address	Name	Remarks
0031	Status read out 3 Lower limit	Read only
0032	Status read out 3 Upper limit	Read only
0040	Status read out 4 Weight error	Read only
0041	Status read out 4 Error	Read only
0042	Status read out 4 Operation mode	Read only
0043	Status read out 4 Weight value overflow	Read only
0044	Status read out 4 Calibration error	Read only
0045	Status read out 4 Sequence error	Read only
0050	Cumulative count read out	Read only
0051	Cumulative value read out	Read only

W (Setting Value)

Address	Name	Remarks
10	Bulk supply	*1
11	Below the preset amount	*1
12	Preset amount	*1
13	Excessive amount	*1
14	Insufficient	*1
15	Gap	*1
16	Automatic gap control value	*2
17	Offset supply time	*2
20	Judgment time	*2
21	Comparison prohibit time	*2
22	Upper limit	*1
23	Lower limit	*1
24	Close to zero	*1
25	Taring setting	*1
26	AZ count	*2
27	Judgment count	*2
28	Completion output time	*2
30	Sequence mode	*2
31	Weighing function 1	*2
32	Weighing function 2	*2
33	Weighing function 3	*2
34	Function key prohibited	*2
35	Analog filter	*2
36	Digital filter	*2
37	Motion detection	*2
38	Zero tracking time	*2
39	Zero tracking width	*2
3A	Setting LOCK	
40	Weight value	*2, *3
41	Maximum weighing value	*2, *3
42	Minimum scale	*2, *3
43	Net weight excessive	*2, *3
44	Total weight excessive	*2, *3
45	Function select	*2
46	Gravitational acceleration offset (area number input)	*2
	DZ control value	*2, *3
47		*2, *3
48	Gravitational acceleration offset (acceleration input) Extended function select 1	*2 *2
50		
51	Taring function limitation	*2
52	D/A output mode	*2
53	D/A zero output setting	*2
54	D/A full scale	*2
55	Input select	*2
56	Output select	*2
80	Average weight	Read only
81	Maximum	Read only
82	Minimum	Read only
83	Population standard deviation	Read only

Address	Name	Remarks
84	Sample standard deviation	Read only
85	Maximum - minimum	Read only
86	Cumulative count	Read only
87	Latest cumulative data	Read only

- Writing is prohibited when LOCK1 is ON. "LOCK1" can be set at "setting value LOCK" in setting mode 4 of F720A. Writing is prohibited when LOCK2 is ON. "LOCK2" can be set at "setting value LOCK" in setting mode 4 of F720A. Writing is prohibited when the LOCK switch is set in the ON position. The LOCK switch is provided at the rear of F720A.

PLC_CTL

Macro command "PLC_CTL F0 F1 F2"

Contents	F0		F1 (= \$u n)	F2			
		n	Station number				
Zero calibration *1	1 - 8 (PLC1 - 8)	n + 1	Command: 0	2			
	(1222 0)	n + 2	Error result				
		n	Station number				
Span calibration *1	1 - 8 (PLC1 - 8)	n + 1	Command: 1	2			
	(1222 0)	n + 2	Error result				
Switching to total	1 - 8	n	Station number	2			
weight display *2	(PLC1 - 8)	n + 1	Command: 2	2			
Switching to net weight	1 - 8	n	Station number	2			
display *2	(PLC1 - 8)	n + 1	Command: 3	2			
Taring	1 - 8	n	Station number	2			
lamig	(PLC1 - 8)	n + 1	Command: 4	2			
Taring reset	1 - 8 (PLC1 - 8)	n	Station number	2			
laning reset		n + 1	Command: 5	_			
Digital zero	1 - 8 (PLC1 - 8)	n	Station number	2			
Digital Zero		n + 1	Command: 6	2			
Digital zero reset	1 - 8	n	Station number	2			
Digital Zelo leset	(PLC1 - 8)	n + 1	Command: 7	2			
Totalize command	1 - 8	n	Station number	2			
Totalize communa	(PLC1 - 8)	n + 1	Command: 8	2			
Cumulative data clear	1 - 8	n	Station number	2			
Carrialative data cicar	(PLC1 - 8)	n + 1	Command: 9	2			
		n	Station number				
Cumulative data read	1 - 8	n + 1	Command: 11	2			
out	(PLC1 - 8)	n + 2	Fixed value 00	2			
		n + 3 - n + 4	Weighing value				
	1 0	n	Station number				
Time-out change *3	1 - 8 (PLC1 - 8)	n + 1	Command: 13	3			
		n + 2	Time-out value (ms)				

Return data: Data stored from controller to V series

^{*1} Calibration is performed based on the value at W40, W41 and W42. Since a response is given after completion of the calibration on F720A, it takes time before the receipt of a response after the calibration command is executed. Before executing the calibration command, execute the time-out change command.

The display cannot be changed when "1: external input mode" is set for "total weight/net weight display change" of extended function 1

in setting mode 4 of F720A.

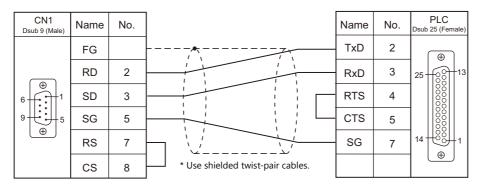
Used to change the time-out time of V9 to apply when the PLC_CTL command is used. It takes time before a response is sent back after the calibration command is executed. Set a time-out time according to your use environment. The default value is "0", and the value varies according to the time set for [Time-out Time] under [Communication Setting] in the [PLC Properties] dialog.

17.1.6 Wiring Diagrams

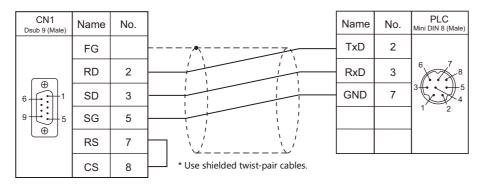
When Connected at CN1:

RS-232C

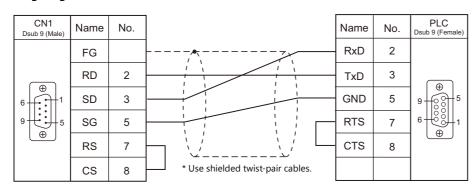
Wiring diagram 1 - C2



Wiring diagram 2 - C2

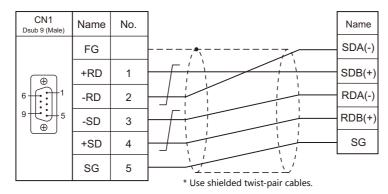


Wiring diagram 3 - C2



RS-485

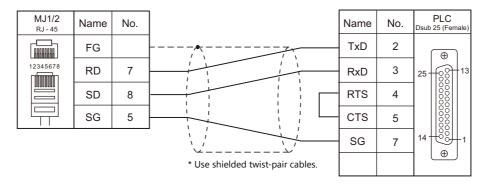
Wiring diagram 1 - C4



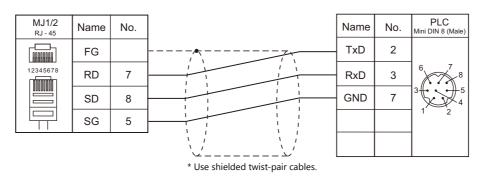
When Connected at MJ1/MJ2:

RS-232C

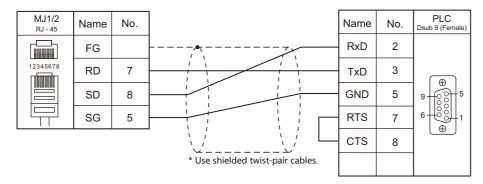
Wiring diagram 1 - M2



Wiring diagram 2 - M2

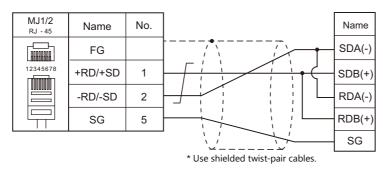


Wiring diagram 3 - M2



RS-485

Wiring diagram 1 - M4



18. UNITRONICS

18.1 PLC Connection

18.1 PLC Connection

Serial Connection

PLC Selection on the	PLC	Port	Port Signal Level		Connection			
Editor	PLC	PORT	Signal Level	CN1	MJ1/MJ2	Transfer *1		
	M90	COM1	RS-232C	Wiring diagram 1 - C2	Wiring diagram 1 - M2			
	M91		RS-232C	Wiring diagram 1 - C2	Wiring diagram 1 - M2			
V3:	V130 V350-35-R2	COM1	RS-485	Wiring diagram 1 - C4	Wiring diagram 1 - M4			
	V230	COM1	RS-232C	Wiring diagram 1 - C2	Wiring diagram 1 - M2			
N 400 (N 401 N // ·	V260 V280 V290 V530	COM2	RS-232C	Wiring diagram 1 - C2	Wiring diagram 1 - M2			
M90/M91/Vision Series (ASCII)			RS-485	Wiring diagram 1 - C4	Wiring diagram 1 - M4	×		
	V120 V290-19-C30BT/40BT V560	COM1/COM2	RS-232C	Wiring diagram 1 - C2	Wiring diagram 1 - M2			
	V570 V1040 V1210	232, 331112	RS-485	Wiring diagram 1 - C4	Wiring diagram 1 - M4			

^{*1} For the ladder transfer function, see the V9 Series Reference Manual.

Ethernet Connection

PLC Selection on the Editor	Model	Unit	TCP/IP	UDP/IP	Port No.	Keep Alive ^{*1}	Ladder Transfer *2
Vision Series (ASCII Ethernet TCP/IP)	V230 V260 V280 V290 V530 V560 V570 V1040 V1210	V200-19-ET1	O ×		0 to 65535 (Default: 20256) (Max. 4 units)	0	×
	V130 V350	V100-17-ET2					
	V1040 V1210	Built-in Ethernet port					

^{*1} For KeepAlive functions, see "1.3.2 Ethernet Communication".
*2 For the ladder transfer function, see the V9 Series Reference Manual.

18.1.1 M90/M91/Vision Series (ASCII)

Communication Setting

Editor

Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1:1 / Multi-link2 / Multi-link2 (Ethernet)	
Signal Level	RS-232C / RS-422/485	
Baud Rate	4800 / 9600 / 19200 / 38400 / <u>57600</u> / 115K bps	
Data Length	7 / <u>8</u> bits	
Stop Bit	1 / 2 bits	
Parity	None / Odd / Even	
Target Port No.	0 to 31	Specify "0" for RS-422/485 communication. On the PLC side, specify a number from "64" to "127".

PLC

Parameter

Parameters must be set in Information Mode or by creating a ladder program using the software "VisiLogic". For more information, refer to the instruction manual issued by UNITORONICS.
When using RS-485 communication, be sure to create the ladder program.

M91

RS232/RS485 Jumper Setting

(Underlined setting: default)

Jumper Sett	Jumper Setting		Setting			Remarks
1 2	No. 1 No. 2	Signal level	RS232 RS485	No. 1 A B	No. 2 A B	
3 4 A B	No. 3 No. 4	RS485 terminating resistance	Provided Not provided	No. 3 A B	No. 4 A B	

V130 / V350-35-R2

RS232 to RS485 Jumper Setting

(Underlined setting: default)

Jumper Setting		Item		Setting	Remarks	
232 - 485 COMM	СОММ	Signal level	RS232 RS485	232 485	232 485	
ON OFF TERM	TERM	RS485 terminating resistance	Provided Not provided	ON OFF	ON OFF	

V230 / V260 / V280 / V290 / V530

RS232/RS485 Jumper Setting

(Underlined setting: default)

Jumper Setting		Setting					
			No. 1	No. 2	No. 3	No. 4	
A No. 1	Signal level/ RS485 terminating	RS232	Α	Α	Α	Α	
B No. 3	RS485 terminating resistance	RS485	В	В	В	В	
1 2 3 4 No. 4	resistance	RS485 With resistance	А	А	В	В	
		,					

V120

RS232/RS485 Jumper Setting

(Underlined setting: default)

Jumper Setti	ng	Item	Setting	Remarks
1 A B 2	No. 1 No. 2	Signal level (COM1)	No. 1 No. 2 RS232 A A RS485 B B	
A B 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4	No. 3 No. 4	RS485 terminating resistance (COM1)	No. 3 No. 4 Provided A A Not provided B B	
5	No. 5 No. 6	Signal level (COM2)	No. 5 No. 6 RS232 A A RS485 B B	
8 B B	No. 7 No. 8	RS485 terminating resistance (COM2)	No. 7 No. 8 Provided A A Not provided B B	

V290-19-C30B/V290-19-T40B/V560/V570/V1040/V1210

RS232/RS485 DIP Switch Settings

(Underlined setting: default)

Dip SW	Item	Setting						Remarks	
			No. 1	No. 2	No. 3	No. 4	No. 5	No. 6	
ON HILL III	Signal level RS485 terminating resistance RS485 With re	RS232	ON	ON	ON	OFF	ON	OFF	These settings are
1 2 3 4 5 6		RS485	OFF	OFF	OFF	ON	OFF	ON	common to both
		RS485 With resistance	ON	ON	OFF	ON	OFF	ON	COM1 and COM2.

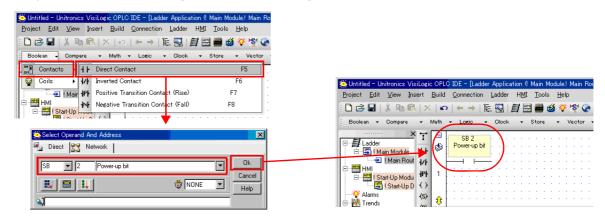
VisiLogic

(Underlined setting: default)

Item		Setting	Remarks	
Direct Contact		SB: 2		
Set PLC Name		Specify a desired name.		
Com Init	Com Port	COM1 / COM2		
	Data Bits	7 / 8	For more information, refer to the	
	Standard	RS232 / RS485	VigiLogic instruction manual.	
	Baud Rate	4800 / 9600 / 19200 / 38400 / 54600 / 115200 bps		
	Parity	NONE / EVEN / ODD		
	Stop Bits	1/2		

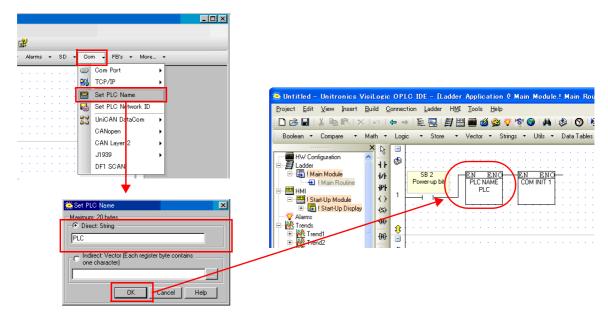
Direct Contact

Specify "2" for the SB address and register it into the ladder program.



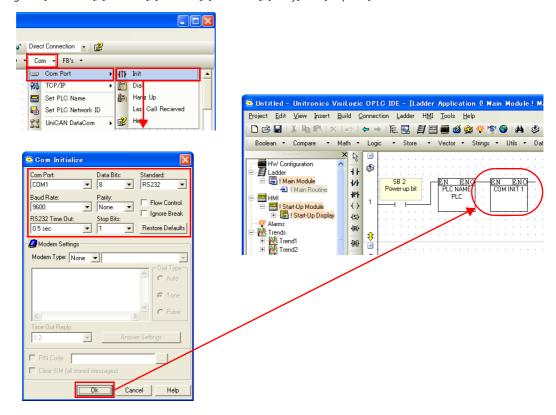
Set PLC Name

Specify a desired PLC name.



Com Init

Make settings for [COM Port], [Data Bits], [Standard], [Baud Rate], [Parity] and [Stop Bits].

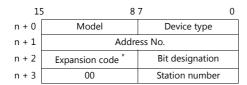


Available Device Memory

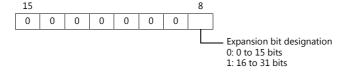
The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

	Device Memory	TYPE	Remarks
МВ	(Memory bit)	00H	
MI	(Memory int)	01H	
ML	(Memory long)	02H	Double-word
MD	(Memory double)	03H	Double-word
MF	(Memory float)	04H	Real number. Bit designation is not possible.
SB	(System bit)	05H	
SI	(System int)	06H	
SL	(System long)	07H	Double-word
SD	(System double)	08H	Double-word
INP	(Input)	09H	Read only
OUT	(Output)	0AH	
TS	(Timer scan bit)	0BH	Read only
TP	(Timer preset)	0CH	Double-word, read only
TC	(Timer current)	0DH	Double-word, read only
CS	(Counter scan bit)	0EH	Read only
СР	(Counter preset)	0FH	Read only
CC	(Counter current)	10H	Read only

Indirect Device Memory Designation



* In the expansion code, set which word, higher or lower, is to be read when a double-word address is specified (expansion bit designation).



PLC_CTL

Macro command "PLC_CTL F0 F1 F2"

Contents	F0	F1 (=\$u n)		F2	
		n	Station number		
		n + 1	Command: 0000H		
PLC operation status setting	1 - 8 (PLC1 - 8)	n + 2	PLC status 0: Run 1: Stop 2: Memory init and reset 3: Reset 4: Switch to BootStrap *1	3	
Conding loss data forms		n	Station number		
Sending key data from remote unit *2	1 - 8 (PLC1 - 8)	n + 1	Command: 0001H	3	
remote unit		n + 2	Key data		
	1 - 8 (PLC1 - 8)	n	Station number		
Unit ID read out		n + 1	Command: 0002H	2	
		n + 2	Unit ID	1	
	1 0	n	Station number		
Unit ID setting	1 - 8 (PLC1 - 8)	n + 1	Command: 0003H	3	
		n + 2	Unit ID		
	1 - 8 (PLC1 - 8)	n	Station number	2	
Version acquisition		n + 1	Command: 0004H		
		n + 2 to n + 29	Version, model type (CHAR data)		

Return data: Data stored from PLC to V series

^{*1} After the setting is made, the PLC must be shut off and restarted.
*2 This command is used when a password is entered into the PLC from the V9 series. Since the password consists of four digits, the command must be executed four times.

Detail of the key data:
40 to 49: "0" to "9"

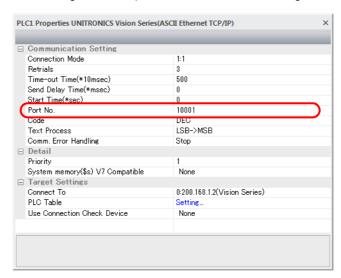
18.1.2 Vision Series (ASCII Ethernet TCP/IP)

Communication Setting

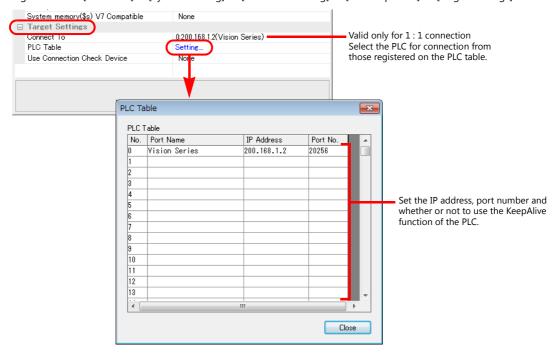
Editor

Make the following settings on the editor. For more information, see "1.3.2 Ethernet Communication".

- IP address for the V9 unit
 - When specified on the screen program:
 [System Setting] → [Hardware Setting] → [Local Port IP Address]
 - When specified on the V9 unit: Local mode → [LAN Setting]
- Port number for the V9 unit (for communication with PLC)
 [System Setting] → [Hardware Setting] → [PLC Properties] → [Communication Setting]



IP address and port number of the PLC
 Register on the [PLC Table] in [System Setting] → [Hardware Setting] → [PLC Properties] → [Target Settings].



PLC

Parameter

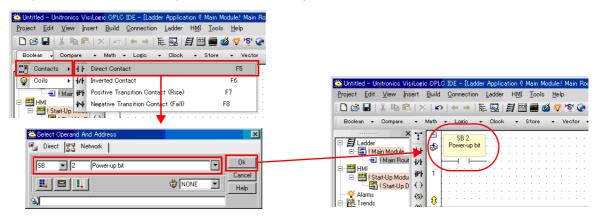
Parameters must be set in Information Mode or by creating a ladder program using the software "VisiLogic". For more information, refer to the instruction manual issued by UNITORONICS.

VisiLogic

Item		Setting	Remarks	
Direct Contact Set PLC Name		SB: 2		
		Specify a desired name.		
Com Init Socket Init	IP Address	IP address of the Vision Series		
	Subnet Mask	Specify according to the environment.		
	Default Gateway	Specify according to the environment.	For more information, refer to the VigiLogic instruction manual.	
	Socket	Socket1		
	Protocol	ТСР		
	Local Port	0 to 65535 (default: 20256)		
	Master/Slave	Slave		

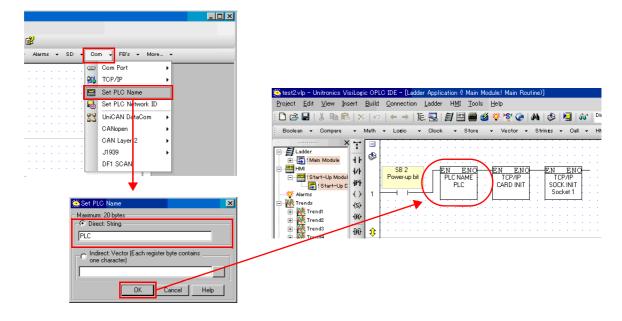
Direct Contact

Specify "2" for the SB address and register it into the ladder program.



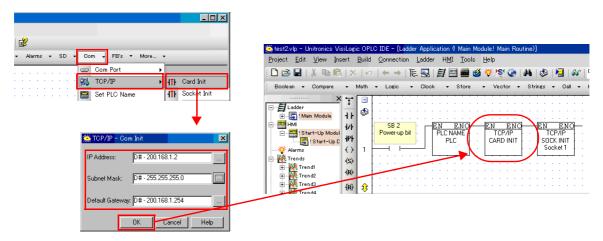
Set PLC Name

Specify a desired PLC name.



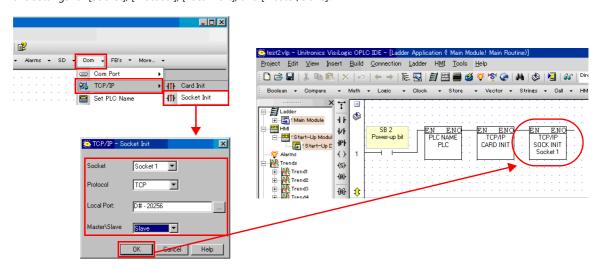
Com Init

Specify the IP address, subnet mask and default gateway.



Socket Init

Make settings for [Socket], [Protocol], [Local Port], and [Master/Slave].



Available Device Memory

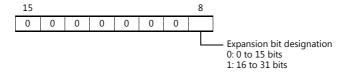
The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

	Device Memory	TYPE	Remarks
МВ	(Memory bit)	00H	
MI	(Memory int)	01H	
ML	(Memory long)	02H	Double-word
MD	(Memory double)	03H	Double-word
MF	(Memory float)	04H	Real number. Bit designation is not possible.
SB	(System bit)	05H	
SI	(System int)	06H	
SL	(System long)	07H	Double-word
SD	(System double)	08H	Double-word
INP	(Input)	09H	Read only
OUT	(Output)	0AH	
TS	(Timer scan bit)	0BH	Read only
TP	(Timer preset)	0CH	Double-word, read only
TC	(Timer current)	0DH	Double-word, read only
CS	(Counter scan bit)	0EH	Read only
СР	(Counter preset)	0FH	Read only
CC	(Counter current)	10H	Read only

Indirect Device Memory Designation

15 8 7		7 0
n + 0	Model	Device type
n + 1	Addre	ess No.
n + 2	Expansion code *	Bit designation
n + 3	00	Station number

* In the expansion code, set which word, higher or lower, is to be read when a double-word address is specified (expansion bit designation).



PLC_CTL

Macro command "PLC_CTL F0 F1 F2"

Contents	F0	F1 (=\$u n)		F2	
		n	Station number		
		n + 1	Command: 0000H		
PLC operation status setting	1 - 8 (PLC1 - 8)	n + 2	PLC status 0: Run 1: Stop 2: Memory init and reset 3: Reset 4: Switch to BootStrap *1	3	
Canding have data from		n	Station number		
Sending key data from remote unit *2	1 - 8 (PLC1 - 8)	n + 1	Command: 0001H	3	
remote unit		n + 2	Key data		
	1 - 8 (PLC1 - 8)	n	Station number	2	
Unit ID read out		n + 1	Command: 0002H		
		n + 2	Unit ID		
		n	Station number		
Unit ID setting	1 - 8 (PLC1 - 8)	n + 1	Command: 0003H	3	
		n + 2	Unit ID		
	1 - 8 (PLC1 - 8)	n	Station number	2	
Version data acquisition		n + 1	Command: 0004H		
		n + 2 to n + 29	Version, model type (CHAR data)		

Return data: Data stored from PLC to V series

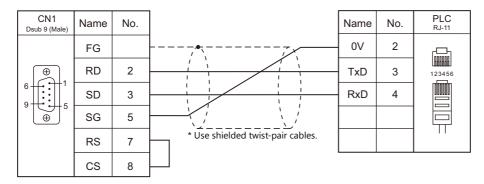
^{*1} After the setting is made, the PLC must be shut off and restarted.
*2 This command is used when a password is entered into the PLC from the V9 series. Since the password consists of four digits, the command must be executed four times.
Detail of the key data:
40 to 49: "0" to "9"

18.1.3 Wiring Diagrams

When Connected at CN1:

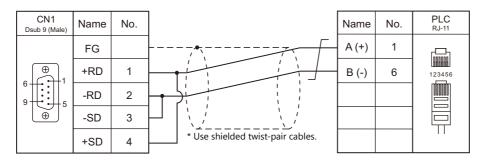
RS-232C

Wiring diagram 1 - C2



RS-422/RS-485

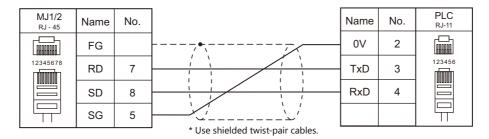
Wiring diagram 1 - C4



When Connected at MJ1/MJ2:

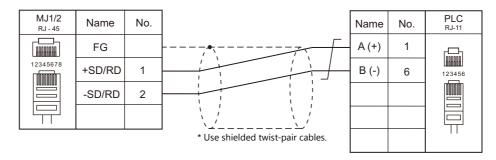
RS-232C

Wiring diagram 1 - M2



RS-422/RS-485

Wiring diagram 1 - M4



MEMO
Please use this page freely.

19. VIGOR

19.1 PLC Connection

19.1 PLC Connection

Serial Connection

PLC Selection on	CPU Unit/F		Port	Signal Level	Conne	Ladder		
the Editor		Only Fort		Signal Level	CN1	MJ1/MJ2	Transfer *1	
M series M1-CPU1	M1-CPU1 COM PORT	COM BORT	M-232R	RS-232C	Wiring diagram 1 - C2	Wiring diagram 1 - M2	\ <u></u>	
	WII-CFUI	COMPORT	M-485R	RS-422/485	Wiring diagram 1 - C4	Wiring diagram 1 - M4	X	

^{*1} For the ladder transfer function, see the V9 Series Reference Manual.

19.1.1 M Series

Communication Setting

Editor

Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1:1/1: n / Multi-link2 / Multi-link2 (Ethernet) / 1: n Multi-link2 (Ethernet)	
Signal Level	<u>RS-232C</u> / RS-422/485	
Baud Rate	4800 / 9600 / <u>19200</u> / 38400bps	
Data Length	7 bits	
Stop Bit	1 bit	
Parity	Even	
Target Port No.	<u>0</u> to 255	

PLC

Make PLC settings using the application software "Ladder Master". For more information, refer to the PLC manual issued by the manufacturer.

M-232R / M-485R

(Underlined setting: default)

Item		Setting	Remarks	
Application		Computer Link		
Computer Link Detail	Station Number	0 to 255		
	Baud Rate	4800 / 9600 / <u>19200</u> / 38400bps	38400 bps supported by M-485R only	

Available Device Memory

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

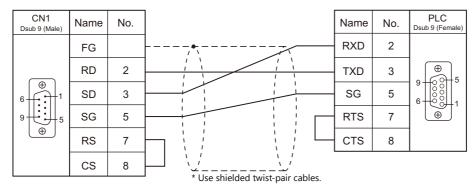
	Device Memory	TYPE	Remarks
D	(Data register / Special register)	00H	D0 to D8191, D9000 to D9255
Х	(Input relay)	01H	
Υ	(Output relay)	02H	
М	(Internal relay / Special relay)	03H	M0 to M5119, M9000 to M9255
S	(Internal relay / Step relay)	04H	
Т	(Timer / Current value)	05H	
С	(Counter / Current value)	06H	
32C	(High-speed counter / Current value)	07H	Double-word
TS	(Timer / Contact)	08H	
CS	(Counter / Contact)	09H	
TC	(Timer / Coil)	0AH	
CC	(Counter / Coil)	0BH	

19.1.2 Wiring Diagrams

When Connected at CN1:

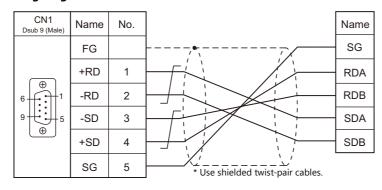
RS-232C

Wiring diagram 1 - C2



RS-422/RS-485

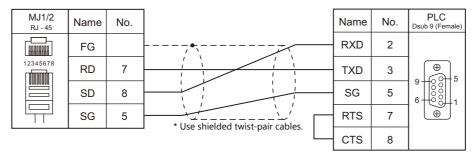
Wiring diagram 1 - C4



When Connected at MJ1/MJ2:

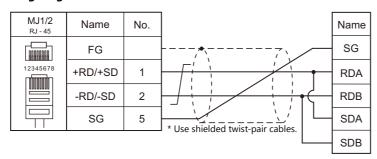
RS-232C

Wiring diagram 1 - M2



RS-422/RS-485

Wiring diagram 1 - M4



20. WAGO

20.1 PLC Connection

20.1 PLC Connection

Serial Connection

PLC Selection on the	CPU	Unit/Port	Signal Level	Conn	Ladder	
Editor	Ci o		Signal Level	CN1	MJ1/MJ2	Transfer *1
750 series	750-314 750-316 750-814 750-816 750-873	Fieldbus connector	RS-232C	Wiring diagram 1 - C2	Wiring diagram 1 - M2	×
(MODBUS RTU)	750-312 750-315 750-812 750-815		RS-422	Wiring diagram 1 - C4	Wiring diagram 1 - M4	

^{*1} For the ladder transfer function, see the V9 Series Reference Manual.

Ethernet Connection

PLC Selection on the Editor	СРИ	Unit	TCP/IP	UDP/IP	Port No.	Keep Alive *1	Ladder Transfer *2
750 series (MODBUS Ethernet)	750-341 750-342 750-841 750-842 750-871 750-873	CPU with built-in Ethernet	0	0	502 (fixed) * ³	0	×

^{*1} For KeepAlive functions, see "1.3.2 Ethernet Communication".
*2 For the ladder transfer function, see the V9 Series Reference Manual.
*3 A maximum of 15 units including the ladder tool can be connected.

20.1.1 750 Series (MODBUS RTU)

Communication Setting

Editor

Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1 : 1 / <u>1 : n</u> / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet)	
Signal Level	<u>RS-232C</u> / RS-422/485	
Baud Rate	4800 / <u>9600</u> / 19200 / 38400 / 57600 / 115K bps	Up to 19200 bps is available on 750-312, 750-314, 750-812 and 750-814. 4800 and 38400 bps are not available on 750-873.
Data Length	8 bits	
Stop Bit	<u>1</u> / 2 bits	
Parity	None / Odd / Even	
Target Port No.	0 to 255	Select station No. 0 for a broadcast command.

Bus Coupler / Bus Controller

750-312 / 750-314 / 750-315 / 750-316

Node address rotary switch

Address	Contents	Setting Example
x1 (2) (3) (4) (4) (5) (5) (4) (5) (6) (6) (7) (7) (7) (7) (7) (7) (7) (7) (7) (7	1 to 99	1

DIP switch FR

(Underlined setting: default)

DIP Switch FR			Conter	nts			Setting Example
		Baud Rate	FR1	FR2	FR3]	
		4800 bps	ON	OFF	ON		
	Ī	9600 bps	<u>OFF</u>	<u>ON</u>	<u>ON</u>		ON — FR1
FR1 FR2	Ī	19200 bps	ON	ON	ON		— FR1
FR3	Ī	38400 bps*	OFF	OFF	OFF		— FR3
	Ī	57600 bps*	ON	OFF	OFF		
	Ī	115 kbps*	OFF	ON	OFF		— FR5
	* Available only on 750-315 and 750-316.						■ — FR6
	Parity	Data Length	Stop Bit	FR4	FR5	FR6	Baud rate: 9600 bps
FR4	<u>None</u>			<u>OFF</u>	<u>OFF</u>	<u>OFF</u>	Parity: None
FR5 FR6	Even	9 hitc	<u> 1 bit</u>	ON	OFF	OFF	Data length: 8 bits Stop bit: 1 bit
	Odd	<u>8 bits</u>		OFF	ON	OFF	
	None	1	2 bits	ON	ON	OFF	
				•	•		

^{*} Before making settings on the DIP switch FR, be sure to turn off the power to the bus coupler.

DIP switch P

(Underlined setting: default)

DIP Switch P	Contents	OFF		ON		Setting Example
		End of Data	P1	P2	P3	
		Three frames	<u>OFF</u>	<u>OFF</u>	<u>OFF</u>	
		100 msec	ON	OFF	OFF	
P1	- 1 6	200 msec	OFF	ON	OFF	ON — P1
P2	End of communication frame data	500 msec	ON	ON	OFF	■ — P2
P3		1 sec.	OFF	OFF	ON	■ - P3
		1 msec	ON	OFF	ON	— P4
		10 msec	OFF	ON	ON	— P5
		50 msec	ON	ON	ON	■ P6
						- P7
P4	Data transfer mode	ASCII mode	e	RTU	<u>mode</u>	■ P8
P5	Error check code	Ignored		<u>Executed</u>		
P6						
P7	Others	<u>OFF</u>		<u>F</u>		
P8						

 $^{^{\}star}$ Before making settings on the DIP switch P, be sure to turn off the power to the bus coupler.

Terminating resistance

Make settings only when 750-312 or 750-315 is used.

• For 2-wire system

• For 4-wire system





750-812 / 750-814 / 750-815 / 750-816

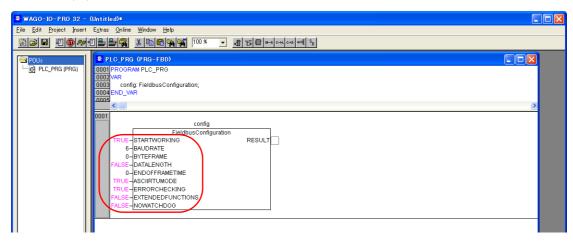
Node address rotary switch

Address	Contents	Setting Example
x1 (\$0 (\$0 (\$0 (\$0 (\$0 (\$0 (\$0 (\$0	1 to 99	1

PLC-PRG (PRG-FBD)

Set communication parameters using the ladder tool "WAGO-I/O-PRO 32" or "WAGO-I/O-PRO CAA". For more information, refer to the PLC manual issued by the manufacturer.

* When setting the communication parameters, set the node address rotary switch to "0" and the operation mode switch in the upper ("run") or center ("stop") position.



(Underlined setting: default)

Setting Items		Contents			Setting
					Example
STARTWORKING		TRUE			TRUE
	Baud rate	Baud rate Value			
	4800 bps		5	1	
	9600 bps		<u>6</u>		
BAUDRATE	19200 bps		7		6
BAUDRATE	38400 bps		0*		б
	57600 bps		1*		
	115 kbps		2*		
	* Available only on	750-815 and 7	50-816.		
	Parity	Stop Bits	Value		
	No		<u>0</u>		
BYTEFRAME	Even	<u>1</u>	1		0
	Odd		2		
	No	2	3		
DATALENGTH		8: FALSE			FALSE
DATALENGTH		_	IALJE		
	End of Frame Tir		Value		
	3 x Frame Time				
	100 ms		1		
	200 ms		2		
ENDOFFRAMETIME	500 ms		3	_	0
	1s		4		
	1 ms		5	_	
	10 ms		6	_	
	50 ms		7		
ASCIIRTUMODE		RTU: TRUE			TRUE
	Error Check		Value		
ERRORCHECKING	ignored		FALSE		TRUE
	being processe	<u>ed</u>	<u>TRUE</u>		
	Extended Functi	ons	Value		
EXTENDEDFUNCTIONS	<u>without</u>		<u>FALSE</u>		FALSE
	available		TRUE		
	Watchdog		Value		
NOWATCHDOG	switched on		FALSE	1	FALSE
	switched off		TRUE	+	

Terminating resistance

Make settings only when 750-812 or 750-815 is used.

- For 2-wire system
- For 4-wire system





750-873

Connect the computer to 750-873 and start the web browser.

Click [Modbus] on the browser menu. The password entry dialog appears. To log on as an administrator, enter "admin" for the user name and "wago" for the password, and click [OK].

Make settings for [Serial Port Settings] and [Modbus RTU Settings] on the screen. For more information, refer to the PLC manual issued by the manufacturer.



Enter the IP address of the bus coupler or bus controller on Internet Explorer, and press the [Enter] key to display the browser menu.

(Underlined setting: default)

			(
Item		Setting	Remarks
Serial Port Settings	Baudrate	9600 / 19200 / 57600 / 115K bps	
Serial Fort Settings	Parity	None / Odd / Even	
Modbus RTU	Slave Device Address	1 to 255	
Settings	Override default fieldbus settings?	Checked	

 $^{^{\}star}$ After settings are made, click [SUBMIT], and turn the power off and back on again.

Available Device Memory

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

Device Memory		TYPE	Remarks
%MX (internal contact point) 00H %MW as word device		%MW as word device	
%IX	(input variable)	01H	%IW as word device
%QX	(output variable)	02H	%QW as word device

20.1.2 750 Series (MODBUS Ethernet)

Communication Setting

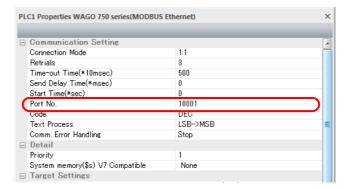
Editor

Make the following settings on the editor. For more information, see "1.3.2 Ethernet Communication".

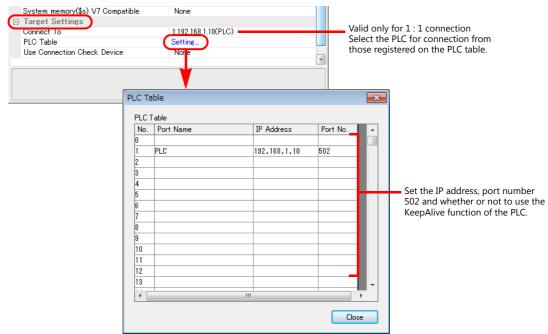
- IP address for the V9 unit
 - When specified on the screen program:
 [System Setting] → [Hardware Setting] → [Local Port IP Address]
 - When specified on the V9 unit: Local mode → [LAN Setting]
- Connection port on the V9 unit:

The [Target Port No.] for the connected device on the [Hardware Setting] window ([System Setting] → [Hardware Setting])

- When using TCP/IP:
- Select [Built-in LAN (TCP)].
- When using UDP/IP:
 Select [Built-in LAN (UDP)].
- Port number for the V9 unit (for communication with PLC)
 [System Setting] → [Hardware Setting] → [PLC Properties] → [Communication Setting]



IP address and port number (No. 502) of the PLC
 Register on the [PLC Table] in [System Setting] → [Hardware Setting] → [PLC Properties] → [Target Settings].

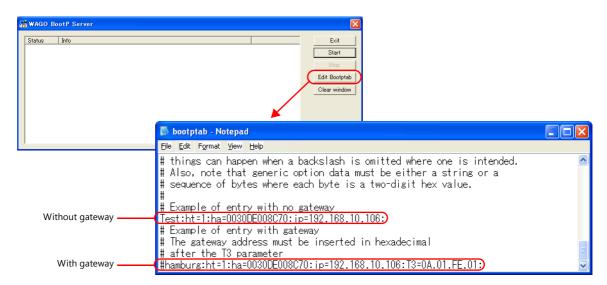


Bus Coupler / Bus Controller

Make PLC settings by using "WAGO BootP Server" or "WAGO Ethernet Settings". For more information, refer to the PLC manual issued by the manufacturer.

* For 750-342 and 750-842, only "WAGO BootP Server" can be used.

WAGO BootP Server

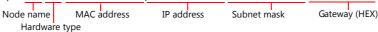


Example: Test:ht=1:ha:0030DE008C70:ip=192.168.10.106:

Node name MAC address IP address

Hardware type

* When setting the subnet mask (sm) and gateway (gw), make settings following the IP address as shown below: Example: Test:ht=1:ha=003-DE000002:ip=192.168.10.106:sm=255.255.255.0:T3=0A:01:FE:01:



Contents	Setting			
Node name	Use one-byte alphanumeric characters.			
Hardware type	ht=1			
MAC address	ha=MAC address (shown on the bus coupler or bus controller)			
IP address table	able ip=IP address of the PLC			
Subnet mask sm=subnet mask				
Gateway T3=gateway address (HEX) * To be set when the bus coupler or bus controller lies beyond the gateway				

- * When making settings for 750-871, set all DIP switches in the OFF positions.
- * The port number is fixed to "502".

Delete either "#" mark at the beginning of "with gateway" or "without gateway" and save the text file. The setting with no "#" mark will take effect.

Notes on setting the IP address using "BootP Server"

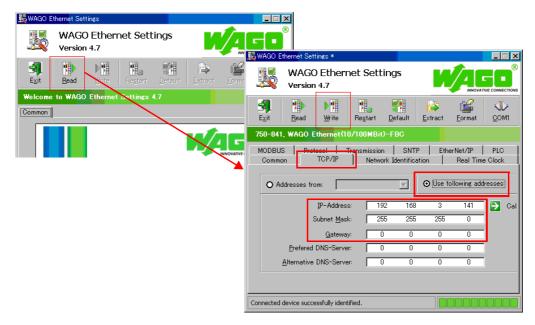
In the initial condition, the IP address set on "BootP Server" is cleared when the power is turned off and back on again. To retain the IP address even when the power has been turned off and back on again, the BootP protocol must be disabled after the IP address is set.

Connect the computer to the bus coupler or bus controller, and start the web browser. Remove the check mark from [BootP] for [Port] on the browser menu.

Click [SUBMIT] and turn the power off and back it on again. The BootP protocol becomes disabled.

* When [Port] is clicked, the password may be required. For more information, see " Enabling Modbus UDP and Modbus TCP protocols" (page 20-8).

WAGO Ethernet Settings ([TCP/IP] tab window)



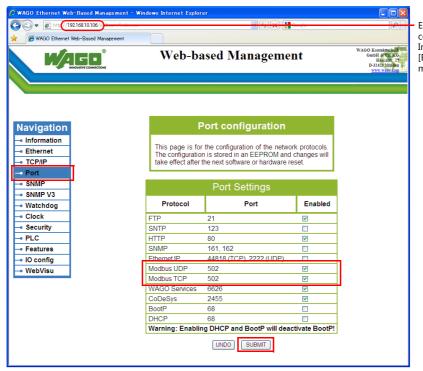
Contents	Setting	Remarks
IP-Address		
Subnet Mask	Make settings in accordance with the network environment.	
Gateway	The control of the co	

- When making settings for 750-871, set all DIP switches in the OFF positions. The port number is fixed to "502".

Enabling Modbus UDP and Modbus TCP protocols

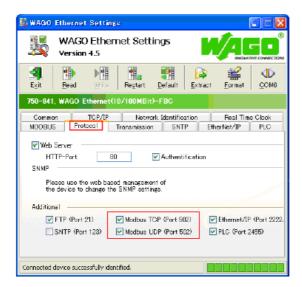
When both Modbus UDP and Modbus TCP protocols are checked (enabled), communication using either protocol becomes possible without selecting a communication protocol on the bus coupler or bus controller. For more information, refer to the PLC manual issued by the manufacturer.

- · Setting on the web browser
 - Connect the computer to the bus coupler or bus controller, and start the web browser.
 - Click [Port] on the browser menu. The password entry dialog appears. To log on as an administrator, enter "admin" for the user name and "wago" for the password, and click [OK].
 - Check both [Modbus UDP] and [Modbus TCP]. Click [SUBMIT], and turn the power off and back on again.
 - * In the initial condition, both Modbus UDP and Modbus TCP are enabled (checked).



Enter the IP address of the bus coupler or bus controller on Internet Explorer, and press the [Enter] key to display the browser menu.

Setting on the [WAGO Ethernet Settings] window ([Protocol] tab window)
 *"WAGO Ethernet Settings" cannot be used with 750-342 or 750-842.
 Check [☐ Modbus TCP (Port 502)] and [☐ Modbus UDP (Port 502)] in the [Protocol] tab window and write the settings into the bus coupler or bus controller.



750-871

The least significant byte of the IP address can be set by the DIP switch.

Note that the IP address must be set on "WAGO BootP Server" or "WAGO Ethernet Settings" in advance.

When any of the DIP switches is set in the ON position upon power-on, the IP address set by the DIP switch will take effect.

DIP Switch	Setting Example	Remarks
ON 1 2 3 4 5 6 7 8	50 [DEC] (00110010 BIN)	Set the least significant byte of the IP address (1 to 254). Switch 1 = LSB, switch 8 = MSB

750-873

Connect the computer to the bus coupler or bus controller, and start the web browser. Be sure to uncheck [Override default fieldbus settings?] for [Modbus RTU Settings] in the [Modbus] browser menu.

- * When [Modbus] is clicked, the password may be required. For more information, see " 750-873" (page 20-5).
- * In the initial condition, [Override default fieldbus settings?] is unchecked.

Available Device Memory

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

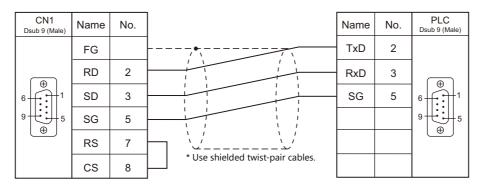
Device Memory		TYPE	Remarks
%MX (internal contact point) 00H %MW as word device		%MW as word device	
%IX	(input variable)	01H	%IW as word device
%QX	(output variable)	02H	%QW as word device

20.1.3 Wiring Diagrams

When Connected at CN1:

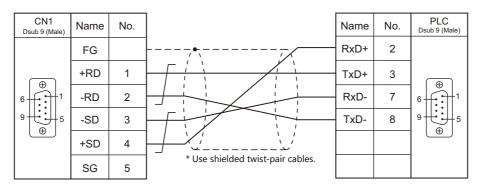
RS-232C

Wiring diagram 1 - C2



RS-422/RS-485

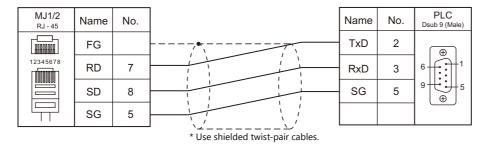
Wiring diagram 1 - C4



When Connected at MJ1/MJ2:

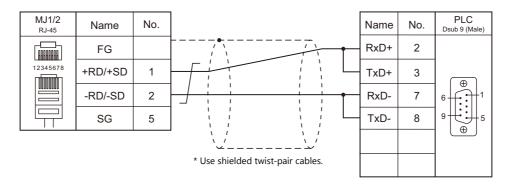
RS-232C

Wiring diagram 1 - M2



RS-422/RS-485

Wiring diagram 1 - M4



MEMO
Please use this page freely.

21.XINJE

21.1 PLC Connection

21.1 PLC Connection

Serial Connection

PLC Selection on the CPU Unit/Port		rt	Signal Level	Wiring Diagrams		Ladder		
Editor	CPU Unit/Port		· C	Signal Level	CN1	MJ1/MJ2	Transfer *1	
		COM1 (Mini-DIN	IN 8-pin) RS-232C Wiring diag	Wiring diagram 1 - C2	1 - C2 Wiring diagram 1 - M2			
va a :	XC3 XC5 XCM	COM2 (Mini-DIN 8-pin)		K3-252C		wiring diagram 1 - C2		
XC Series (MODBUS RTU)			COM2 (Terminal	block)	RS-485	Wiring diagram 1 - C4	Wiring diagram 1 - M4	×
(6556567		XC-COM-BD	сомз	RS-232C	Wiring diagram 2 - C2	Wiring diagram 2 - M2		
		XC-COM-BD CON	COIVIS	RS-485	Wiring diagram 1 - C4	Wiring diagram 1 - M4		

 $^{^{\}star}1$ For the ladder transfer function, see the V9 Series Reference Manual.

21.1.1 XC Series (MODBUS RTU)

Communication Setting

Editor

Communication setting

(Underlined setting: default)

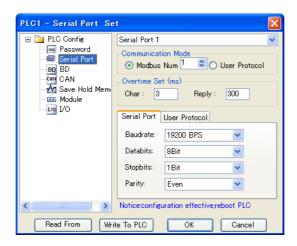
Item	Setting	Remarks
Connection Mode	1:1/1:n/Multi-link2 Multi-link2 (Ethernet)/ 1:n Multi-link2 (Ethernet)	
Signal Level	<u>RS-232C</u> / RS-422/485	
Baud Rate	4800 / 9600 / <u>19200</u> / 38400 / 57600 / 115200 bps	
Data Length	7 / <u>8</u> bits	
Stop Bit	<u>1</u> / 2 bits	
Parity	None / Odd / <u>Even</u>	
Target Port No.	0 to 254	0: Broadcast

PLC

Make communication settings by using the application software "XCPPro" or writing the setting values directly into the FD address

For more information, refer to the PLC manual issued by the manufacturer.

PLC Config



(Underlined setting: default)

	Item		Setting	Remarks	
	Serial Port 1 - 3		Select a COM port to which the V9 is connected.		
	Communication Mode	Modbus Num	<u>1</u> to 254	Changes can be made to the FD address. Of the settings made with the	
Serial Port	Serial Port	Baudrate	4800 / 9600 / <u>19200</u> / 38400 / 57600 / 115200 Bps		
		Databits	7 / <u>8</u> Bits	application software and FD	
		Stopbits	<u>1</u> / 2 Bits	address, the one made last will b used.	
		Parity	None / Odd / <u>Even</u>	assa.	
BD	BD Config		BD Serial Port	This setting is used when using "XC-COM-BD".	

After writing the settings, turn the PLC power off and on again.

FD address

Port	FD	Setting	Remarks
	FD8210	Communication mode: Station number setting	
		Communication format: Baud rate, data length, stop bit, parity settings bit 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0	
COM1	FD8211	Parity Stopbits Databits Baudrate 0: None 0: 2 Bits 0: 8 Bits 4: 4800 BPS 1: Odd 2: 1 Bit 1: 7 Bits 5: 9600 BPS 2: Even 6: 19200 BPS 7: 38400 BPS 8: 57600 BPS 9: 115200 BPS	Changes can be made using the application software. Of the settings made with the application software and FD address, the one made last will be used.
COM2	FD8220	Same as COM1	
	FD8221		
сомз	FD8230	Same as COM1	
CONIS	FD8231	3diffe d3 COM2	

Available Device Memory

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

	Device Memory	TYPE	Remarks
D	(data register)	00H	
М	(auxiliary relays)	01H	
Χ	(input relay)	02H	
Υ	(output relay)	03H	
S	(status relays)	04H	
T	(timer)	05H	
TD	(timer data)	06H	
С	(counter)	07H	
CD	(counter data)	08H	
FD	(flashROM register)	09H	

Indirect Device Memory Designation

15	5 8	7 0
n + 0	Model	Device type
n + 1	Addre	ess No.
n + 2	Expansion code	Bit designation
n + 3	00	Station number

• For X or Y device memory:

Convert the address from octal notation (OCT) to decimal (DEC) and divide by 16. Specify the quotient as the address number. Specify the remainder for bit designation.

Example: Indirect device memory designation of "X31"

31 (OCT) \rightarrow 25 (DEC) \div 16 = 1 remainder 9

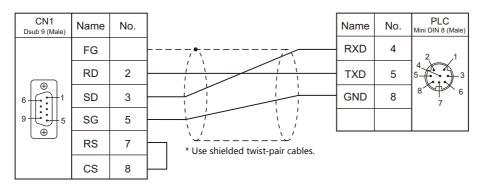
Specify "1" (DEC) for the address number, and "9" (DEC) for the bit designation.

21.1.2 Wiring Diagrams

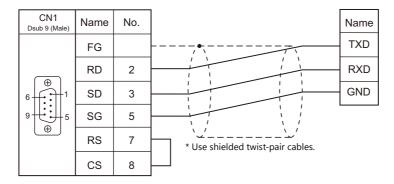
When Connected at CN1:

RS-232C

Wiring diagram 1 - C2

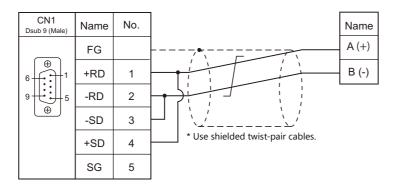


Wiring diagram 2 - C2



RS-422/RS-485

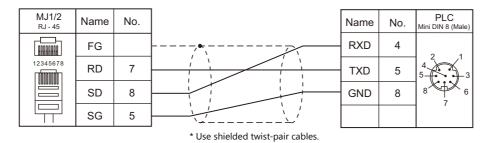
Wiring diagram 1 - C4



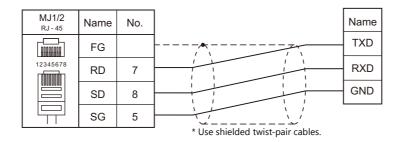
When Connected at MJ1/MJ2:

RS-232C

Wiring diagram 1 - M2

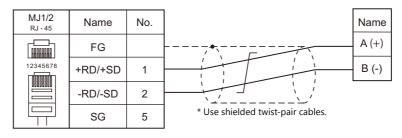


Wiring diagram 2 - M2



RS-422/RS-485

Wiring diagram 1 - M4



MEMO	
	Please use this page freely.

22. YAMAHA

22.1 Temperature Controller/Servo/Inverter Connection

22.1 Temperature Controller/Servo/Inverter Connection

Serial Connection

Robot Controller

PLC Selection on the	Model	Port	Signal Level Connec		Connection	
Editor	iviodei	Port	Signal Level	CN1	MJ1/MJ2	Lst File
	RCX142					
RCX142	RCX222	СОМ	RS-232C	Wiring diagram 1 - C2	Wiring diagram 1 - M2	Y_RCX142.lst
	RCX240					

22.1.1 RCX142

Communication Setting

Editor

Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1:1 / Multi-link2 / Multi-link2 (Ethernet)	
Signal Level	RS-232C	
Baud Rate	4800 / <u>9600</u> / 19200 / 38400 / 57600 bps	
Data Length	7 / <u>8 bits</u>	
Stop Bit	1 bit	
Parity	None / <u>Odd</u> / Even	
CR/LF	<u>CR</u> / CR/LF	

Robot Controller

RCX142/RCX240

Set communication parameters using the MPB programming box (RPB programming box for RCX240). For more information, refer to the instruction manual for the robot controller issued by the manufacturer.

(Underlined setting: default)

Mode	Sub Menu	Item	Setting	Remarks
		1. CMU mode	ONLINE	
		2. Data bits ^{*1}	7 / <u>8 bits</u>	
		3. Baud rate	4800 / <u>9600</u> / 19200 / 38400 / 57600 bps	
CVCTENA	CMIL	4. Stop bit	<u>1</u> /2 bits	
SYSTEM CMI	CMU	5. Parity	NON / <u>ODD</u> / EVEN	
		6. Termination code	CR / CRLF	
		7. XON/XOFF control *2	NO	
		8. RTS/CTS control *2	NO	

 $^{^{*}1}$ If Japanese is selected for the interface language, set the data bit to "8".

RCX222

Set communication parameters using the RPB programming box. For more information, refer to the instruction manual for the robot controller issued by the manufacturer.

(Underlined setting: default)

Mode	Sub Menu	Item	Setting	Remarks
		1. CMU mode	ONLINE	
		2. Data bits*1	7 / <u>8 bits</u>	
		3. Baud rate	4800 / <u>9600</u> / 19200 / 38400 / 57600 bps	
SYSTEM	CMU	4. Stop bit	<u>1</u> / 2 bits	
		5. Parity	NON / <u>ODD</u> / EVEN	
		6. Termination code	CR / CRLF	
		7. Flow control	NO	

 $^{^{*}1}$ If Japanese is selected for the interface language, set the data bit to "8".

Available Device Memory

The available setting range of device memory varies depending on the model. Be sure to set within the range available for the model to be used. Use [TYPE] when assigning indirect device memory for macro programs.

	Device Memory	TYPE	Remarks
LANG	(interface language)	00H	
ACSL	(access level)	01H	
ARM1	(arm status (main robot))	02H	
ARM2	(arm status (sub robot))	03H	
BRKP	(break point)	04H	
EXEL	(execution level)	05H	
MODS	(mode status)	06H	
ORIG	(origin return status)	07H	Read only
ABSR	(absolute reset status)	08H	Double-word, read only
SERV	(servo status)	09H	Double-word, read only
SEQE	(sequence program execution status)	0AH	
UNIT	(point unit coordinate system)	0BH	
VERS	(version)	0CH	Read only
WHR1	(current position in pulse coordinate system (main group))	0DH	Double-word, read only
WHR2	(current position in pulse coordinate system (sub group))	0EH	Double-word, read only
WXY1	(current position in XY coordinate system (main group))	0FH	Double-word, read only
WXY2	(current position in XY coordinate system (sub group))	10H	Double-word, read only
SIFT	(shift status)	11H	Read only
HAND	(hand status)	12H	Read only
MEMR	(remaining memory capacity)	13H	Double-word, read only
EMGS	(emergency stop status)	14H	Read only
SELF	(error status in self-diagnosis)	15H	Read only
OPTS	(option slot status)	16H	Read only
PRGS	(program execution status)	17H	Read only
TSKS	(running or suspended status of task)	18H	Read only
TSKM	(task operation status)	19H	Read only

LANG (interface language)

Address	Name	Setting Range
0	Interface language	0: Japanese 1: English

ACSL (access level)

Address	Name	Setting Range
0	Access level	0 to 3

ARM1 (arm status (main robot))

Address	Name	Setting Range
0		0: Right-hand system 1: Left-hand system
1	Arm setting at the time of program reset	0: Right-hand system 1: Left-hand system

ARM2 (arm status (sub robot))

Address	Name	Setting Range
0	Current arm setting	0: Right-hand system 1: Left-hand system
1	Arm setting at the time of program reset	0: Right-hand system 1: Left-hand system

BRKP (break point)

Address	Name	Setting Range
0	Line number of break point 1	0 to 19999
1	Line number of break point 2	0 to 19999
2	Line number of break point 3	0 to 19999
3	Line number of break point 4	0 to 19999

EXEL (execution level)

Address	Name	Setting Range
0	Execution level	0 to 8

MODS (mode status)

Address	Name	Setting Range
0	Mode status	0: AUTO 1: PROGRAM 2: MANUAL 3: SYSTEM

ORIG (origin return status)

Address	Name	Setting Range
0	Origin return status	0: Completed 1: Not completed

ABSR (absolute reset status)

Address	Name	Setting Range
0	Completed or not completed	0: Completed 1: Not completed
1	Status of each axis (output only when address 0 is set to "1" (absolute reset not completed))	XXXXXXXX Axis 1 0: Not completed : 1: Completed Axis 8 9: Not applicable

SERV (servo status)

Address	Name	Setting Range
0	Motor power ON/OFF status	0: Motor power ON 1: Motor power OFF
1	Status of each axis	XXXXXXXX Axis 1 0: Mechanical brake ON + dynamic brake ON : 1: Servo ON Axis 8 2: Mechanical brake OFF + dynamic brake OFF 9: Not applicable

SEQE (sequence program execution status)

Address	Name	Setting Range
0	Availability	Disabled Enabled Enabled, and output cleared at the time of emergency stop
1	Execution status	0: Stopped 1: In progress

UNIT (point unit coordinate system)

Address	Name	Setting Range
0		Cartesian coordinates in units of pulse Cartesian coordinates in units of mm or deg.

VERS (version)

Address	Name	Setting Range
0	Host version	
1	Host revision	
2	MPB/RPB version	
3	Driver version 1	
4	Driver version 2	
5	Driver version 3	
6	Driver version 4	
7	Driver version 5	
8	Driver version 6	
9	Driver version 7	
10	Driver version 8	
11	Option unit version	

WHR1 (current position in pulse coordinate system (main group))

Address	Name	Setting Range
0	Current position of axis 1 in the pulse coordinate system (main group)	-999999 to 999999
1	Current position of axis 2 in the pulse coordinate system (main group)	-999999 to 999999
2	Current position of axis 3 in the pulse coordinate system (main group)	-999999 to 999999
3	Current position of axis 4 in the pulse coordinate system (main group)	-999999 to 999999
4	Current position of axis 5 in the pulse coordinate system (main group)	-999999 to 999999
5	Current position of axis 6 in the pulse coordinate system (main group)	-999999 to 999999

WHR2 (current position in pulse coordinate system (sub group))

Address	Name	Setting Range
0	Current position of axis 1 in the pulse coordinate system (sub group)	-999999 to 999999
1	Current position of axis 2 in the pulse coordinate system (sub group)	-999999 to 999999
2	Current position of axis 3 in the pulse coordinate system (sub group)	-999999 to 999999
3	Current position of axis 4 in the pulse coordinate system (sub group)	-999999 to 999999
4	Current position of axis 5 in the pulse coordinate system (sub group)	-999999 to 999999
5	Current position of axis 6 in the pulse coordinate system (sub group)	-999999 to 999999

WXY1 (current position in XY coordinate system (main group))

Address	Name	Setting Range
0	Current position of axis 1 in units of "mm" (main group)	-999999 to 999999
1	Current position of axis 2 in units of "mm" (main group)	-999999 to 999999
2	Current position of axis 3 in units of "mm" (main group)	-999999 to 999999
3	Current position of axis 4 in units of "mm" (main group)	-999999 to 999999
4	Current position of axis 5 in units of "mm" (main group)	-999999 to 999999
5	Current position of axis 6 in units of "mm" (main group)	-999999 to 999999

WXY2 (current position in XY coordinate system (sub group))

Address	Name	Setting Range
0	Current position of axis 1 in units of "mm" (sub group)	-999999 to 999999
1	Current position of axis 2 in units of "mm" (sub group)	-999999 to 999999
2	Current position of axis 3 in units of "mm" (sub group)	-999999 to 999999
3	Current position of axis 4 in units of "mm" (sub group)	-999999 to 999999
4	Current position of axis 5 in units of "mm" (sub group)	-999999 to 999999
5	Current position of axis 6 in units of "mm" (sub group)	-999999 to 999999

SIFT (shift status)

Address	Name	Setting Range
0	Shift number selected for main robot	0 to 9
1	Shift number selected for sub robot	0 to 9

HAND (hand status)

Address	Name	Setting Range
0	Hand number selected for main robot	0 to 3
1	Hand number selected for sub robot	4 to 7

MEMR (remaining memory capacity)

Address	Name	Setting Range
0	Remaining source area (unit: byte)	
1	Remaining object area (unit: byte)	

EMGS (emergency stop status)

Address	Name	Setting Range
0	Emergency stop status	0: Normal 1: Emergency stop

SELF (error status in self-diagnosis)

Address	Name	Name Setting Range	
0 to 49	Error status 1		
50 to 99	Error status 2		
100 to 149	Error status 3	[Error group No.] . [Error category No.] : [Error message] (CHAR)	
150 to 199	Error status 4		
200 to 249	Error status 5		

OPTS (option slot status)

Address	Name	Setting Range
0 to 49	Option slot status 1	
50 to 99	Option slot status 2	Option board name (CHAR)
100 to 149	100 to 149 Option slot status 3	
150 to 199	Option slot status 4	

PRGS (program execution status)

Address	Name	Setting Range
0 to 49	Name of currently selected program	Program name (CHAR)
50	Current task number	1 to 8
51	Line number of current program	1 to 9999
52	Priority of current task	17 to 47

TSKS (running or suspended status of task)

Address	Name	Setting Range
0	Number of task currently running or suspended (No. 1)	1 to 8
1	Number of task currently running or suspended (No. 2)	1 to 8
2	Number of task currently running or suspended (No. 3)	1 to 8
3	Number of task currently running or suspended (No. 4)	1 to 8
4	Number of task currently running or suspended (No. 5)	1 to 8
5	Number of task currently running or suspended (No. 6)	1 to 8
6	Number of task currently running or suspended (No. 7)	1 to 8
7	Number of task currently running or suspended (No. 8)	1 to 8

TSKM (task operation status)

Address	Name	Setting Range
0	Number of line being executed in task (No. 1)	1 to 9999
1	Task status (No. 1)	0: In progress 1: Suspended 2: Stopped
2	Priority (No. 1)	17 to 47
3	Number of line being executed in task (No. 2)	1 to 9999
4	Task status (No. 2)	0: In progress 1: Suspended 2: Stopped
5	Priority of task (No. 2)	17 to 47
6	Number of line being executed in task (No. 3)	1 to 9999
7	Task status (No. 3)	0: In progress 1: Suspended 2: Stopped
8	Priority of task (No. 3)	17 to 47
9	Number of line being executed in task (No. 4)	1 to 9999
10	Task status (No. 4)	0: In progress 1: Suspended 2: Stopped
11	Priority of task (No. 4)	17 to 47
12	Number of line being executed in task (No. 5)	1 to 9999
13	Task status (No. 5)	0: In progress 1: Suspended 2: Stopped
14	Priority of task (No. 5)	17 to 47
15	Number of line being executed in task (No. 6)	1 to 9999
16	Task status (No. 6)	0: In progress 1: Suspended 2: Stopped
17	Priority of task (No. 6)	17 to 47
18	Number of line being executed in task (No. 7)	1 to 9999
19	Task status (No. 7)	0: In progress 1: Suspended 2: Stopped
20	Priority of task (No. 7)	17 to 47
21	Number of line being executed in task (No. 8)	1 to 9999
22	Task status (No. 8)	0: In progress 1: Suspended 2: Stopped
23	Priority of task (No. 8)	17 to 47

PLC_CTL

Macro command "PLC_CTL F0 F1 F2"

Contents	F0		F1 (= \$u n)	F2
		n	Station number	
		n + 1	Command: 0	
Program operation	1 - 8 (PLC1 - 8)	n + 2	0: RESET 1: RUN 2: STEP 3: SKIP 4: NEXT 5: STOP	3
	1 - 8	n	Station number	
Switching of execution task	(PLC1 - 8)	n + 1	Command: 1	2
		n	Station number	
		n + 1	Command: 2	
Manual speed change	1 - 8 (PLC1 - 8)	n + 2	0: Main robot 1: Sub robot	4
		n + 3	Manual movement speed: 1 to 100	
		n	Station number	
		n + 1	Command: 3	
		n + 2	0: Main robot	
Moving to absolute reset position	1 - 8 (PLC1 - 8)		1: Sub robot	5
position	(PLC1 - 0)	n + 3	Designated axis: 1 to 6	
		n + 4	Direction of movement 0: Positive direction 1: Negative direction	
		n	Station number	
	1 0	n + 1	Command: 4	
Absolute reset for each axis	1 - 8 (PLC1 - 8)	n + 2	0: Main robot 1: Sub robot	4
		n + 3	Designated axis: 1 to 6	
		n	Station number	
		n + 1	Command: 5	
Memory area initialization	1 - 8 (PLC1 - 8)	n + 2	0: Program data 1: Point data 2: Shift data 3: Hand data 4: Pallet data 5: Point comment data 6: All of above data (program, point, shift, hand, pallet and point comment) 7: Parameter data 8: All data	3
Communication port	1 - 8	n	Station number	2
initialization	(PLC1 - 8)	n + 1	Command: 6	_
Error log initialization	1 - 8	n	Station number	2
- 3	(PLC1 - 8)	n + 1	Command: 7	
Resetting of internal	1 - 8	n	Station number	. 2
emergency stop flag	(PLC1 - 8)	n + 1	Command: 8	
Acquisition of controller	1 - 8	n	Station number	_
configuration status	(PLC1 - 8)	n + 1	Command: 9	2
Acquisition of message line		n + 2 to n + 3	Acquired text	
	1 - 8	n n	Station number	2
information displayed on MPB/RPB	(PLC1 - 8)	n + 1 n + 2 to n + 3	Command: 10	_
	 		Acquired text Station number	
Acquisition of error message		n n + 1		
	1 - 8 (PLC1 - 8)	n + 1	Command: 11	4
		n + 2 n + 3	Top number of acquired data: 1 to 500 Last number of acquired data: 1 to 500	7
		n + 3 - n + 5	Acquired text	
		11 + 4 - 11 + 3	Acquired text	

Contents	F0		F1 (= \$u n)	F2
		n	Station number	
		n + 1	Command: 12	
		n + 2	Setting for automatic movement speed (main group): 1 to 100	
Acquisition of speed setting status	1 - 8 (PLC1 - 8)	n + 3	Setting for manual movement speed (main group): 1 to 100	2
		n + 4	Setting for automatic movement speed (sub group): 1 to 100	
		n + 5	Setting for manual movement speed (sub group): 1 to 100	
Command execution	1 - 8	n	Station number	2
interruption	(PLC1 - 8)	n + 1	Command: 13	2
		n	Station number	1
		n + 1	Command: 14	
		n + 2	Point number: 0 to 9999	
		n + 3	Coordinate system 0: Pulse (integer) 1 or greater: mm (decimal places)	
		n + 4 to n + 5	Point data 1	
Reading of point data	1 - 8	n + 6 to n + 7	Point data 2	3
reading of point data	(PLC1 - 8)	n + 8 to n + 9	Point data 3	J
		n + 10 to n + 11	Point data 4	
		n + 12 to n + 13	Point data 5	
		n + 14 to n + 15	Point data 6	
		n + 16	Extended hand system flag setting 0: No setting 1: Right-hand system 2: Left-hand system	
		n	Station number	
		n + 1	Command: 15	
		n + 2	Point number: 0 to 9999	
		n + 3	Coordinate system 0: Pulse (integer) 1 or greater: mm (decimal places)	
		n + 4 to n + 5	Point data 1	
Writing of point data	1 - 8	n + 6 to n + 7	Point data 2	17
Timeng or point data	(PLC1 - 8)	n + 8 to n + 9	Point data 3	
		n + 10 to n + 11	Point data 4	
		n + 12 to n + 13	Point data 5	
		n + 14 to n + 15	Point data 6	
		n + 16	Extended hand system flag setting 0: No setting 1: Right-hand system 2: Left-hand system	
		n	Station number	
		n + 1	Command: 16	
Dooding of parameter	1 0	n + 2 to n + 4	Parameter label (six alphabetical characters)	
Reading of parameter (controller)	1 - 8 (PLC1 - 8)	n + 5	Type 0: Entire controller	5
		n + 6 to n + 7	Parameter data	
		n + 8 to n + 9	Comment	
		n	Station number	
		n + 1	Command: 16	
		n + 2 to n + 4	Parameter label (six alphabetical characters)	
Reading of parameter (main robot / main robot + sub robot)	1 - 8 (PLC1 - 8)	n + 5	Type 1: Main robot 2: Main robot + sub robot	5
		n + 6 to n + 7	Parameter data (main robot)	
		n + 8 to n + 9	Parameter data (sub robot)	
		n + 10 to n + 11	Comment	

Contents	F0		F1 (= \$u n)	F2
22.76.16	. •	n	Station number	. =
		n + 1	Command: 16	-
		n + 2 to n + 4	Parameter label (six alphabetical characters)	-
		n + 5	Type 3: 4-axis 4: 8-axis	
		n + 6 to n + 7	Parameter data (axis 1)	-
Reading of parameter	1 - 8	n + 8 to n + 9	Parameter data (axis 1)	_
(4-axis/8-axis)	(PLC1 - 8)	n + 10 to n + 11	Parameter data (axis 2)	5
		n + 12 to n + 13	Parameter data (axis 3)	-
		n + 14 to n + 15	Parameter data (axis 5)	-
		n + 16 to n + 17	Parameter data (axis 5)	-
		n + 18 to n + 19	Parameter data (axis 7)	_
		n + 20 to n + 21	Parameter data (axis 8)	-
		n + 22 to n + 23	Comment	-
		n	Station number	
		n + 1	Command: 17	-
		n + 2 to n + 4	Parameter label (six alphabetical characters)	-
Writing of parameter (controller)	1 - 8 (PLC1 - 8)	n + 5	Туре	8 + (m + 1) / 2
			0: Entire controller	-
		n + 6 to n + 7	Parameter data	-
		n + 8 -	Comment: m	
		n	Station number	-
		n + 1	Command: 17	-
and the second second		n + 2 to n + 4	Parameter label (six alphabetical characters)	-
Writing of parameter (main robot / main robot + sub robot)	1 - 8 (PLC1 - 8)	n + 5	Type 1: Main robot 2: Main robot + sub robot	10 + (m + 1) / 2
		n + 6 to n + 7	Parameter data (main robot)	=
		n + 8 to n + 9	Parameter data (sub robot)	=
		n + 10 -	Comment: m	
		n	Station number	
		n + 1	Command: 17	
		n + 2 to n + 4	Parameter label (six alphabetical characters)	
		n + 5	Type 3: 4-axis 4: 8-axis	
		n + 6 to n + 7	Parameter data (axis 1)	=
Writing of parameter	1 - 8	n + 8 to n + 9	Parameter data (axis 2)	22 + (m + 1) /
(4-axis/8-axis)	(PLC1 - 8)	n + 10 to n + 11	Parameter data (axis 3)	2
		n + 12 to n + 13	Parameter data (axis 4)	
		n + 14 to n + 15	Parameter data (axis 5)	
		n + 16 to n + 17	Parameter data (axis 6)	
		n + 18 to n + 19	Parameter data (axis 7)	
		n + 20 to n + 21	Parameter data (axis 8)	
		n + 22 -	Comment: m	
		n	Station number	=
		n + 1	Command: 18	-
		n + 2	Shift coordinate number: 0 to 9	=
		n + 3	Coordinate system 0: Pulse (integer) 1 or greater: mm (decimal places)	
		n + 4 to n + 5	Shift coordinate 1 (S)	1
		n + 6 to n + 7	Shift coordinate 2 (S)	
Reading of shift coordinate	1 - 8	n + 8 to n + 9	Shift coordinate 3 (S)	
reading of shift Coordinate value definition	(PLC1 - 8)	n + 10 to n + 11	Shift coordinate 4 (S)	3
		n + 12 to n + 13	Shift coordinate 1 (SP)	
		n + 14 to n + 15	Shift coordinate 2 (SP)	
		n + 16 to n + 17	Shift coordinate 3 (SP)	
		n + 18 to n + 19	Shift coordinate 4 (SP)	
		n + 20 to n + 21	Shift coordinate 1 (SM)	
		n + 22 to n + 23	Shift coordinate 2 (SM)	
		n + 24 to n + 25	Shift coordinate 3 (SM)	-
		n + 26 to n + 27	Shift coordinate 4 (SM)	

Contents	F0	F1 (= \$u n)		F2
Writing of shift coordinate value definition	1 - 8 (PLC1 - 8)	n	Station number	28
		n + 1	Command: 19	
		n + 2	Shift coordinate number: 0 to 9	
		n + 3	Coordinate system 0: Pulse (integer) 1 or greater: mm (decimal places)	
		n + 4 to n + 5	Shift coordinate 1 (S)	
		n + 6 to n + 7	Shift coordinate 2 (S)	
		n + 8 to n + 9	Shift coordinate 3 (S)	
		n + 10 to n + 11	Shift coordinate 4 (S)	
		n + 12 to n + 13	Shift coordinate 1 (SP)	
		n + 14 to n + 15	Shift coordinate 2 (SP)	
		n + 16 to n + 17	Shift coordinate 3 (SP)	
		n + 18 to n + 19	Shift coordinate 4 (SP)	
		n + 20 to n + 21	Shift coordinate 1 (SM)	
		n + 22 to n + 23	Shift coordinate 2 (SM)	
		n + 24 to n + 25	Shift coordinate 3 (SM)	
		n + 26 to n + 27	Shift coordinate 4 (SM)	
Reading of hand definition	1 - 8 (PLC1 - 8)	n	Station number	3
		n + 1	Command: 20	
		n + 2	Hand number: 0 to 7	
		n + 3	Coordinate system 0: Pulse (integer) 1 or greater: mm (decimal places)	
		n + 4 to n + 5	Hand 1	
		n + 6 to n + 7	Hand 2	
		n + 8 to n + 9	Hand 3	
		n + 10	Hand attachment to R axis 0: None 1: Attached	
Writing of hand definition	1 - 8 (PLC1 - 8)	n	Station number	. 11
		n + 1	Command: 21	
		n + 2	Hand number: 0 to 7	
		n + 3	Coordinate system 0: Pulse (integer) 1 or greater: mm (decimal places)	
		n + 4 to n + 5	Hand 1	
		n + 6 to n + 7	Hand 2	
		n + 8 to n + 9	Hand 3	
		n + 10	Hand attachment to R axis 0: None 1: Attached	

Contents	F0		F1 (= \$u n)	F2
		n	Station number	
		n + 1	Command: 22	
		n + 2	Pallet number: 0 to 19	
		n + 3	NX	
		n + 4	NY	
		n + 5	NZ	
		n + 6	Coordinate system 0: Pulse (integer) 1 or greater: mm (decimal places)	
		n + 7 to n + 8	Coordinate data 1 for P [1]	
		n + 9 to n + 10	Coordinate data 2 for P [1]	
		n + 11 to n + 12	Coordinate data 3 for P [1]	
		n + 13 to n + 14	Coordinate data 4 for P [1]	
		n + 15 to n + 16	Coordinate data 5 for P [1]	
		n + 17 to n + 18	Coordinate data 6 for P [1]	
		n + 19 to n + 20	Coordinate data 1 for P [2]	
		n + 21 to n + 22	Coordinate data 2 for P [2]	
		n + 23 to n + 24	Coordinate data 3 for P [2]	
		n + 25 to n + 26	Coordinate data 4 for P [2]	
Reading of pallet definition	1 - 8	n + 27 to n + 28	Coordinate data 5 for P [2]	3
3 1	(PLC1 - 8)	n + 29 to n + 30	Coordinate data 6 for P [2]	
		n + 31 to n + 32	Coordinate data 1 for P [3]	
		n + 33 to n + 34	Coordinate data 2 for P [3]	
		n + 35 to n + 36	Coordinate data 3 for P [3]	
		n + 37 to n + 38	Coordinate data 4 for P [3]	
		n + 39 to n + 40	Coordinate data 5 for P [3]	
		n + 41 to n + 42	Coordinate data 6 for P [3]	
		n + 43 to n + 44	Coordinate data 1 for P [4]	
		n + 45 to n + 46	Coordinate data 2 for P [4]	
		n + 47 to n + 48	Coordinate data 3 for P [4]	
		n + 49 to n + 50	Coordinate data 4 for P [4]	
		n + 51 to n + 52	Coordinate data 5 for P [4]	
		n + 53 to n + 54	Coordinate data 6 for P [4]	
		n + 55 to n + 56	Coordinate data 1 for P [5]	
		n + 57 to n + 58	Coordinate data 2 for P [5]	
		n + 59 to n + 60	Coordinate data 3 for P [5]	
		n + 61 to n + 62	Coordinate data 4 for P [5]	
		n + 63 to n + 64	Coordinate data 5 for P [5]	
		n + 65 to n + 66	Coordinate data 6 for P [5]	

Contents	F0		F1 (= \$u n)	F2	
		n	Station number		
		n + 1	Command: 23		
		n + 2	Pallet number: 0 to 19		
		n + 3	NX		
		n + 4	NY		
		n + 5	NZ		
		n + 6	Coordinate system 0: Pulse (integer) 1 or greater: mm (decimal places)		
		n + 7 to n + 8	Coordinate data 1 for P [1]	1	
		n + 9 to n + 10	Coordinate data 2 for P [1]		
		n + 11 to n + 12	Coordinate data 3 for P [1]		
		n + 13 to n + 14	Coordinate data 4 for P [1]		
		n + 15 to n + 16	Coordinate data 5 for P [1]		
		n + 17 to n + 18	Coordinate data 6 for P [1]	-	
		n + 19 to n + 20	Coordinate data 1 for P [2]	_	
		n + 21 to n + 22	Coordinate data 2 for P [2]	_	
		n + 23 to n + 24	Coordinate data 2 for P [2]		
		n + 25 to n + 26	Coordinate data 3 for P [2]		
	1 - 8	n + 27 to n + 28	Coordinate data 4 for P [2] Coordinate data 5 for P [2]		
Writing of pallet definition	(PLC1 - 8)	n + 29 to n + 30		67	
			Coordinate data 6 for P [2]	_	
		n + 31 to n + 32	Coordinate data 1 for P [3]		
		n + 33 to n + 34	Coordinate data 2 for P [3]	_	
		n + 35 to n + 36	Coordinate data 3 for P [3]	_	
		n + 37 to n + 38	Coordinate data 4 for P [3]		
		n + 39 to n + 40	Coordinate data 5 for P [3]	_	
		n + 41 to n + 42	Coordinate data 6 for P [3]		
		n + 43 to n + 44	Coordinate data 1 for P [4]		
		n + 45 to n + 46	Coordinate data 2 for P [4]		
		n + 47 to n + 48	Coordinate data 3 for P [4]		
		n + 49 to n + 50	Coordinate data 4 for P [4]		
		n + 51 to n + 52	Coordinate data 5 for P [4]		
		n + 53 to n + 54	Coordinate data 6 for P [4]		
		n + 55 to n + 56	Coordinate data 1 for P [5]		
		n + 57 to n + 58	Coordinate data 2 for P [5]		
		n + 59 to n + 60	Coordinate data 3 for P [5]		
		n + 61 to n + 62	Coordinate data 4 for P [5]		
		n + 63 to n + 64	Coordinate data 5 for P [5]		
		n + 65 to n + 66	Coordinate data 6 for P [5]		
		n	Station number		
		n + 1	Command: 24		
Writing of device port (PLC	1 - 8 (PLC1 - 8)	n + 2	Device port 0: DI port 1: DO port 2: MO port 3: TO port 4: LO port 5: SI port 6: SO port	4	
		n + 3	Port number: 0 to 7, 10 to 17, 20 to 27	-	
		n + 4	Point data	1	
		n	Station number		
		n + 1	Command: 25	1	
	1 - 8 (PLC1 - 8)	n + 2	Device port 1: DO port 2: MO port 3: TO port 4: LO port 6: SO port	5	
		n + 3	Port number: 0 to 7, 10 to 17, 20 to 27		
		n + 4	Point data		

n	Contents	F0		F1 (= \$u n)	F2	
			n	Station number		
Reading of dynamic variable (Data type: lext)			n + 1	Command: 26		
1 - 8			n + 2 to n + 9	Variable name (max. 16 characters)		
N		1 0	n + 10	0: Simple variable 1: One-dimensional array variable 2: Two-dimensional array variable	15	
N + 13 Subscript for three dimensions "3		(PLC1 - 8)	n + 11	Subscript for one dimension *1	13	
			n + 12	Subscript for two dimensions *2	-	
			n + 13	Subscript for three dimensions *3	-	
Reading of dynamic variable (Data type: text)			n + 14	Data type 0: Integer		
N + 1			n + 15 to n + 16	Data		
Reading of dynamic variable (Data type: text)			n	Station number		
Reading of dynamic variable (Data type: text)			n + 1	Command: 26		
Reading of dynamic variable (Data type: text)			n + 2 to n + 9	Variable name (max. 16 characters)		
N + 11 Subscript for one dimension \(^1 \)			n + 10	0: Simple variable 1: One-dimensional array variable 2: Two-dimensional array variable	15	
N + 13 Subscript for three dimensions *3	(Data type: text)	(1 LC1 - 0)	n + 11	Subscript for one dimension *1		
N + 14			n + 12	Subscript for two dimensions *2		
N + 14			n + 13			
Note			n + 14	Data type		
Note			n + 15 -	Data (max. 70 characters)		
Note			n	Station number		
Writing of dynamic variable (Data type: integer/real number) 1 - 8 (PLC1 - 8)			n + 1	Command: 27		
Writing of dynamic variable (Data type: integer/real number) 1 - 8 (PLC1 - 8) n + 10 0: Simple variable 1: One-dimensional array variable 2: Two-dimensional array variable 3: Three-dimensional array variable 3: Three-dimensional array variable 3: Three-dimensional array variable 3: Three-dimensions 1 1 17 In + 11 Subscript for one dimensions 1 2 17 In + 12 Subscript for two dimensions 2 3 1 In + 14 Data type 0: Integer 1: Real number 1:			n + 2 to n + 9	Variable name (max. 16 characters)		
Pict Subscript for one dimension *1			n + 10	0: Simple variable 1: One-dimensional array variable 2: Two-dimensional array variable	17	
N + 13 Subscript for three dimensions *3		(PLC1 - 8)	n + 11	Subscript for one dimension *1	17	
			n + 12	Subscript for two dimensions *2		
N + 14 0: Integer 1: Real number			n + 13	Subscript for three dimensions *3		
Writing of dynamic variable (Data type: text)			n + 14	0: Integer		
Writing of dynamic variable (Data type: text) N + 1			n + 15 to n + 16	Data		
Writing of dynamic variable (Data type: text) Note: The proof of the					_	
Writing of dynamic variable (Data type: text) $ \begin{array}{c} 1 - 8 \\ (PLC1 - 8) \\ \end{array} $ Writing of dynamic variable $ \begin{array}{c} 1 - 8 \\ (PLC1 - 8) \\ \end{array} $ $ \begin{array}{c} 1 - 8 \\ (PLC1 - 8) \\ \end{array} $ $ \begin{array}{c} 1 - 8 \\ (PLC1 - 8) \\ \end{array} $ $ \begin{array}{c} 1 - 8 \\ 0 - 1 \\ \end{array} $ $ \begin{array}{c} 1 - 8 \\ 0 - 1 \\ \end{array} $ $ \begin{array}{c} 1 - 8 \\ 0 - 1 \\ \end{array} $ $ \begin{array}{c} 1 - 8 \\ 0 - 1 \\ \end{array} $ $ \begin{array}{c} 1 - 8 \\ 0 - 1 \\ \end{array} $ $ \begin{array}{c} 1 - 8 \\ 0 - 1 \\ \end{array} $ $ \begin{array}{c} 1 - 8 \\ \end{array} $ $ \begin{array}{c} 1$					-	
Writing of dynamic variable (Data type: text) $ \begin{array}{c} 1 - 8 \\ (Data type: text) \end{array} $ Writing of dynamic variable (Data type: text) $ \begin{array}{c} 1 - 8 \\ (PLC1 - 8) \end{array} $ $ \begin{array}{c} 1 - 8 \\ (PLC1 - 8) \end{array} $ $ \begin{array}{c} 1 - 8 \\ (PLC1 - 8) \end{array} $ $ \begin{array}{c} 1 - 8 \\ (PLC1 - 8) \end{array} $ $ \begin{array}{c} 1 - 8 \\ (PLC1 - 8) \end{array} $ $ \begin{array}{c} 1 - 8 \\ (PLC1 - 8) \end{array} $ $ \begin{array}{c} 1 - 8 \\ (PLC1 - 8) \end{array} $ $ \begin{array}{c} 1 - 8 \\ (PLC1 - 8) \end{array} $ $ \begin{array}{c} 1 - 8 \\ (PLC1 - 8) \end{array} $ $ \begin{array}{c} 0 : Simple variable 1 : One-dimensional array variable 2 : Two-dimensional array variable 3: Three-dimensional array variable 4: Three-dimensional array variable 3: Three-dimensional array variable 4: Three-dimensional array variable 3: Three-dimensional array variable 4: Three-dimensional array variable$			n + 2 to n + 9	· · · · · · · · · · · · · · · · · · ·	-	
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$		1 - 8	n + 10	0: Simple variable 1: One-dimensional array variable 2: Two-dimensional array variable		
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$		(PLC1 - 8)	n + 11	Subscript for one dimension *1		
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$			n + 12		1	
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$,	+	
				Data type		
Robot language execution $\begin{pmatrix} 1-8 \\ (PLC1-8) \end{pmatrix}$ $n+1$ Command: 28 $2 + (m+1)/2$			n + 15 -	Data (max. 70 characters): m		
Robot language execution (PLC1 - 8) n + 1 Command: 28 2 + (m + 1) / 2			n	Station number		
n + 2 - Command text: m	Robot language execution	-	n + 1	Command: 28	2 + (m + 1) / 2	
		(1 LC1 - 0)	n + 2 -	Command text: m	1	

Contents	F0		F1 (= \$u n)	F2
		n	Station number	
		n + 1	Command: 29	
		n + 2	0: Main robot 1: Sub robot	
Inching	1 - 8 (PLC1 - 8)	n + 3	Specified axis 1: X axis 2: Y axis 3: Z axis 4: R axis 5: A axis 6: B axis	5
		n + 4	Direction of movement 0: Positive direction 1: Negative direction	
		n	Station number	
		n + 1	Command: 30	
		n + 2	0: Main robot 1: Sub robot	
JOG	1 - 8 (PLC1 - 8)	n + 3	Specified axis 1: X axis 2: Y axis 3: Z axis 4: R axis 5: A axis 6: B axis	5
		n + 4	Direction of movement 0: Positive direction 1: Negative direction	
		n	Station number	
		n + 1	Command: 31	
		n + 2	0: Main robot 1: Sub robot	
Origin return	1 - 8 (PLC1 - 8)	n + 3	Specified axis 1: X axis 2: Y axis 3: Z axis 4: R axis 5: A axis 6: B axis	4
		n	Station number	
	1 - 8	n + 1	Command: 32	
Teaching	(PLC1 - 8)	n + 2	0: Main robot 1: Sub robot	4
		n + 3	Point number: 0 to 9999	
		n	Station number	
		n + 1	Command: 34	
Reading of static variable Writing of static variable	1 - 8 (PLC1 - 8)	n + 2	Data type 0: Integer (SGI) 1: Real number (SGR)	4
		n + 3	Variable number: 0 to 7	
		n + 4 to n + 5	Data	
		n	Station number	
		n + 1	Command: 35	
	1 - 8 (PLC1 - 8)	n + 2	Data type 0: Integer (SGI) 1: Real number (SGR)	6
		n + 3	Variable number: 0 to 7	
		n + 4 to n + 5	Data	

Return data: Data stored from controller to V series

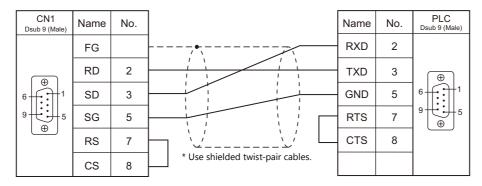
^{*1} Valid in the case where a number other than "0" (simple variable) is specified for the variable type.
*2 Valid in the case where "2" (two-dimensional array variable) or "3" (three-dimensional array variable) is specified for the variable type.
*3 Valid in the case where "3" (three-dimensional array variable) is specified for the variable type.

22.1.2 Wiring Diagrams

When Connected at CN1:

RS-232C

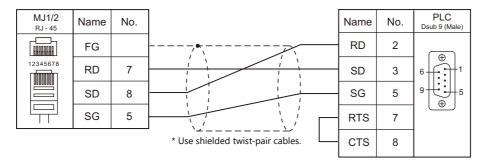
Wiring diagram 1 - C2



When Connected at MJ1/MJ2:

RS-232C

Wiring diagram 1 - M2



23. Yaskawa Electric

23.1 PLC Connection

23.1 PLC Connection

Serial Connection

PLC Selection on the	CPU	Llni	Unit/Port		Conn	Ladder Transfer ^{*1}		
Editor	Editor		Officeror		CN1		MJ1/MJ2	
	GL60 series	JAMSC-IF60 JAMSC-IF61 JAMSC-IF611		RS-232C	Wiring diagram 1 - C2	Wiring diagram 1 - M2		
		JAMSC-IF61 JAMSC-IF61	_	RS-422	Wiring diagram 1 - C4	Wiring diagram 1 - M4		
Memobus	GL120	Memobus p		RS-232C	Wiring diagram 1 - C2	Wiring diagram 1 - M2		
	GL130 series	JAMSC-1201 27100	NOM	RS-422	Wiring diagram 2 - C4	Wiring diagram 2 - M4		
	PROGIC-8	PORT2 on th	ne CPU unit	RS-232C	Wiring diagram 2 - C2	Wiring diagram 2 - M2		
	CP9200SH		CN1	RS-232C	Wiring diagram 1 - C2	Wiring diagram 1 - M2		
		CP-217IF	CN2	K3-252C	Wiring diagram 3 - C2	Wiring diagram 3 - M2		
			CN3	RS-422	Wiring diagram 3 - C4	Wiring diagram 3 - M4		
CP9200SH/		Memobus p		RS-232C	Wiring diagram 1 - C2	Wiring diagram 1 - M2	×	
MP900	1011 520	1011 320	217IF	CN1 CN2	RS-232C	Wiring diagram 1 - C2	Wiring diagram 1 - M2	
			CN3	RS-422	Wiring diagram 4 - C4	Wiring diagram 4 - M4		
	MP2200 MP2300	217IF-01 218IF-01	PORT	RS-232C	Wiring diagram 4 - C2	Wiring diagram 4 - M2		
	MP2300S	217IF-01	RS422/485	RS-422	Wiring diagram 5 - C4	Wiring diagram 5 - M4		
MP2000 series	MP2200 MP2300 MP2300S	217IF-01 218IF-01 218IF-02 260IF-01 261IF-01 215AIF-01	PORT	RS-232C	Wiring diagram 4 - C2	Wiring diagram 4 - M2		
		217IF-01	RS422/485	RS-422	Wiring diagram 5 - C4	Wiring diagram 5 - M4		

^{*1} For the ladder transfer function, see the V9 Series Reference Manual.

Ethernet Connection

To speed up communications, we recommend you to select "CP/MP Expansion Memobus (UDP/IP)".

PLC Selection on the Editor	СРИ	Unit	TCP/IP	UDP/IP	Port No.	Keep Alive ^{*1}	Ladder Transfer *2
MP2300	MP2300S MP2400	218IFA (built-in LAN port)					
(MODBUS TCP/IP)	MP2200 MP2300 MP2300S	218IF-01	0	×	Set the desired number using		×
CP/MP Expansion Memobus	MP2300S MP2400	218IFA (built-in LAN port)			the tool.		^
(UDP/IP)	MP2200 MP2300 MP2300S	218IF-01	×	0			
	MP2200 (CPU-03) MP2310 MP2300S MP2400	218IFA (Built-in LAN port)			Default 9999	0	
MP2000 series (UDP/IP)	MP2200 (CPU-04)	218IFC (Built-in LAN port)	×	0			×
	MP2200 (CPU-01/02/03/04)	218IF-01			Default 10000		
	MP2300 MP2310 MP2300S	218IF-02 263IF-01			Default 9999		

^{*1} For KeepAlive functions, see "1.3.2 Ethernet Communication".
*2 For the ladder transfer function, see the V9 Series Reference Manual.

23.1.1 **Memobus**

Communication Setting

Editor

Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1:1/1:n/Multi-link2/Multi-link2(Ethernet)/ 1:n Multi-link2(Ethernet)	
Signal Level	<u>RS-232C</u> / RS-422/485	
Baud Rate	4800 / 9600 / <u>19200</u> bps	
Data Length	8 bits	
Stop Bit	<u>1</u> / 2 bits	
Parity	None / Odd / Even	
Target Port No.	<u>1</u> to 31	
Transmission Mode	<u>Type 1</u> / Type 2	For GL60 series or PROGIC-8: Type 1: special binary code For GL120/130 series: Type 2: standard binary code

PLC

Be sure to match the settings to those made under [Communication Setting] of the editor. For more information, refer to the PLC manual issued by the manufacturer.

Item	Setting	Remarks
Signal Level	RS-232C / RS-422	
Baud Rate	4800 / 9600 / 19200 bps	
Data Length	8 bits	RTU mode
Stop Bit	1 bit	
Parity	Even	
Station No.	1 to 31	
Error Check	CRC	
Port Delay Timer	0	

Available Device Memory

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

	Device Memory	TYPE	Remarks
4	(holding register)	00H	
3	(input register)	01H	Including constant register, read only
R	(link register)	02H	
Α	(extension register)	03H	
0	(coil)	04H	
D	(link coil)	05H	
1	(input relay)	06H	Read only
7	(constant register)	07H	

23.1.2 CP9200SH/MP900

Communication Setting

Editor

Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1:1/1:n/Multi-link2/Multi-link2 (Ethernet)/ 1:n Multi-link2 (Ethernet)	
Signal Level	<u>RS-232C</u> / RS-422/485	
Baud Rate	4800 / 9600 / <u>19200</u> / 38400 / 57600 / 76800 bps	
Data Length	8 bits	
Stop Bit	<u>1</u> / 2 bits	
Parity	None / Odd / Even	
Target Port No.	<u>1</u> to 31	

PLC

CP-217IF

Be sure to match the settings to those made under [Communication Setting] of the editor. For more information on communication settings, refer to the PLC manual issued by the manufacturer.

Memobus Port on the CPU Module (MP920, MP930) / 217IF

Module configuration

Item	Setting	Remarks
Transmission Protocol	Memobus	
Master/Slave	Slave	
Device Address	1 to 31	
Serial I/F	RS-232	
Transmission Mode	RTU	
Data Length	8 bits	
Parity Bit	Even	
Stop Bit	1 stop	
Baud Rate	19.2K	For connection via RS-422 on "217IF", 76800 bps can also be selected. For more information, refer to the PLC manual issued by the manufacturer.

217IF-01, 218IF-01

Module configuration

Item	Setting	Remarks
Transmission Protocol	Memobus	
Master/Slave	Slave	
Device Address	1	
Serial I/F	RS-232 / RS-485	
Transmission Mode	RTU	
Data Length	8 bits	
Parity Bit	Even	
Stop Bit	1 stop	
Baud Rate	19.2K	The maximum baud rate available is 76.8 kbps.
Automatic Reception	Specified / Not Specified	To speed up communications, select [Not Specified]. When [Not Specified] is selected, the MSG-RCV function is required. For more information, refer to the PLC manual issued by the manufacturer.
Automatic Reception Setting	As desired	Make the setting when [Specified] is selected for [Automatic Reception].

Available Device Memory

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

	Device Memory		Remarks
MW	(holding register)	00H	MB as bit device
IW	(input register)	01H	IB as bit device, read only
MB	(coil)	04H	MW as word device
IB	(input relay)	06H	IW as word device, read only

When setting device memory MB/IB, set the bit numbers in the hexadecimal notation.



23.1.3 MP2300 (MODBUS TCP/IP)

Communication Setting

Editor

Make the following settings on the editor. For more information, see "1.3.2 Ethernet Communication".

- IP address for the V9 unit
 - When specified on the screen program:
 [System Setting] → [Hardware Setting] → [Local Port IP Address]
 - When specified on the V9 unit: Local mode → [LAN Setting]
- Port number for the V9 unit (for communication with PLC)
 [System Setting] → [Hardware Setting] → [PLC Properties] → [Communication Setting]
- IP address and port number of the PLC
 Register on the [PLC Table] in [System Setting] → [Hardware Setting] → [PLC Properties] → [Target Settings].

PLC

218IFA (Built-in LAN Port)

Module configuration

Item	Setting	Remarks
IP Address	Set the IP address of "218IFA".	
Subnet Mask	Set the subnet mask of "218IFA".	
Local Port	256 to 65535	Cannot set the same number as the one set for another connection number.
Target IP Address	000.000.000	Connected in the "Unnective ener" made *
Target Port	0000	Connected in the "Unpassive open" mode *
Connection Type	ТСР	
Protocol Type	MODBUS TCP/IP	
Code	BIN	
Automatic Reception	Valid	When "Valid" is checked, the operation equivalent to the MSG-RCV function is automatically performed.

Gives a response to the connection request issued by the station whose address is within the range specified by the subnet mask regardless of its IP address setting.

218IF-01 (MP2200, MP2300)

Make the settings as shown below and create a program of the MSG-RCV function. For more information, refer to the PLC manual issued by the manufacturer.

Module configuration

Item	Setting	Remarks
IP Address	Set the IP address of "218IF-01".	
Local Port	256 to 65534	Cannot set the same number as the one set for another connection number.
Target IP Address	000.000.000	Connected in the "Honories ones" made t
Target Port 0000		Connected in the "Unpassive open" mode *
Connection Type	ТСР	
Protocol Type	MODBUS TCP/IP	
Code	BIN	

^{*} Gives a response to the connection request issued by the station whose address is within the range specified by the subnet mask regardless of its IP address setting.

Available Device Memory

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

	Device Memory		Remarks
MW	(holding register)	00H	MB as bit device
IW	(input register)	01H	IB as bit device, read only
MB	(coil)	04H	MW as word device
IB	(input relay)	06H	IW as word device, read only

When setting device memory MB/IB, set the bit numbers in the hexadecimal notation.



23.1.4 CP/MP Expansion Memobus (UDP/IP)

Communication Setting

Editor

Make the following settings on the editor. For more information, see "1.3.2 Ethernet Communication".

- IP address for the V9 unit
 - When specified on the screen program: [System Setting] → [Hardware Setting] → [Local Port IP Address]
 - When specified on the V9 unit: Local mode → [LAN Setting]
- Port number for the V9 unit (for communication with PLC)
 [System Setting] → [Hardware Setting] → [PLC Properties] → [Communication Setting]
- IP address and port number of the PLC
 Register on the [PLC Table] in [System Setting] → [Hardware Setting] → [PLC Properties] → [Target Settings].

PLC

218IFA (Built-in LAN Port)

Module configuration

Item	Setting	Remarks
IP Address	Set the IP address of "218IFA".	
Subnet Mask	Set the subnet mask of "218IFA".	
Local Port	256 to 65535	Except 9998 and 10000. Cannot set the same number as the one set for another connection number.
Target IP Address	Set the IP address of the V series.	
Target Port Set the port number of the V series.		
Connection Type UDP		
Protocol Type Extension Memobus		
Code	BIN	
Automatic Reception	Valid	When "Valid" is checked, the operation equivalent to the MSG-RCV function is automatically performed.

218IF-01

Make the settings as shown below and create a program of the MSG-RCV function. For more information, refer to the PLC manual issued by the manufacturer.

Module configuration

Item	Setting	Remarks
IP Address	Set the IP address of "218IF-01".	
Local Port	255 to 65535	Cannot set the same number as the one set for another connection number.
Target IP Address	Set the IP address of the V series.	
Target Port	Set the port number of the V series.	
Connection Type	UDP	
Protocol Type	Extension Memobus	
Code	BIN	

Available Device Memory

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

	Device Memory		Remarks
MW	(holding register)	00H	MB as bit device
IW	(input register)	01H	IB as bit device, read only
МВ	(coil)	04H	MW as word device
IB	(input relay)	06H	IW as word device, read only

When setting device memory MB/IB, set the bit numbers in the hexadecimal notation.



23.1.5 MP2000 Series

Communication Setting

Editor

Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode 1:1/1:n/Multi-link2/Multi-link2(Ethernet)/ 1:n/Multi-link2(Ethernet)		
Signal Level	<u>RS-232C</u> / RS-422/485	
Baud Rate 4800 / 9600 / <u>19200</u> / 38400 / 57600 / 76800 bps		
Data Length	8 bits	
Stop Bit	<u>1</u> / 2 bits	
Parity	None / Odd / <u>Even</u>	
Target Port No.	<u>1</u> to 31	

PLC

217IF-01, 218IF-01, 218IF-02, 260IF-01, 261IF-01, 215AIF-01

Module configuration

Item	Setting	Remarks
Transmission Protocol	Memobus	
Master/Slave	Slave	
Device Address	1	
Serial I/F	RS-232/RS-485	
Transmission Mode	RTU	
Data Length	8Bit	
Parity Bit	even	
Stop Bit	1Stop	
Baud Rate	19.2K	The maximum baud rate available is 76.8 kbps.

Available Device Memory

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

	Device Memory	TYPE	Remarks
MW	(holding register)	00H	MB as bit device
IW	(input register)	01H	IB as bit device
MB	(coil)	04H	MW as word device *1
IB	(input relay)	06H	IW as word device
SW	(system register)	08H	SB as bit device
SB	(system)	09H	SW as word device *1
OW	(output register)	0AH	OB as bit device
ОВ	(output)	0BH	OW as word device

^{*1} When setting device memory MB/SB, set the bit numbers in the hexadecimal notation.



23.1.6 MP2000 Series (UDP/IP)

Communication Setting

Editor

Make the following settings on the editor. For more information, see "1.3.2 Ethernet Communication".

- IP address for the V9 unit
 - When specified on the screen program: [System Setting] → [Hardware Setting] → [Local Port IP Address]
 - When specified on the V9 unit: Local mode → [LAN Setting]
- Port number for the V9 unit (for communication with PLC)
 [System Setting] → [Hardware Setting] → [PLC Properties] → [Communication Setting]
- IP address and port number of the PLC
 Register on the [PLC Table] in [System Setting] → [Hardware Setting] → [PLC Properties] → [Target Settings].

PLC

Module configuration

Item	Setting	Remarks
IP Address	Set the IP address.	
Subnet Mask	Set the subnet mask.	
System Port (engineering port) 256 to 65535		Default 9999: 218IFA / 218IF-02 / 2613IF-01 10000: 218IF-01

Available Device Memory

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

	Device Memory	TYPE	Remarks
MW	(holding register)	00H	MB as bit device
IW	(input register)	01H	IB as bit device
МВ	(coil)	04H	MW as word device *1
IB	(input relay)	06H	IW as word device
SW	(system register)	08H	SB as bit device
SB	(system)	09H	SW as word device *1
OW	(output register)	0AH	OB as bit device
ОВ	(output)	0BH	OW as word device

^{*1} When setting device memory MB/SB, set the bit numbers in the hexadecimal notation.

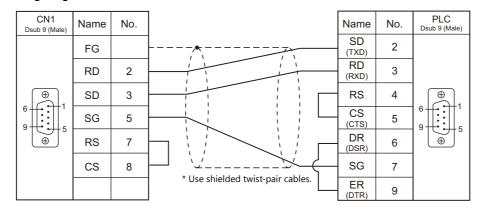


23.1.7 Wiring Diagrams

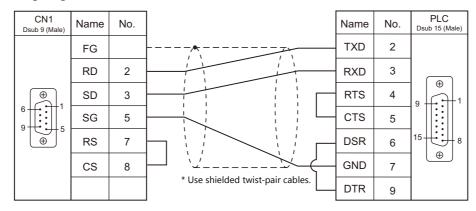
When Connected at CN1:

RS-232C

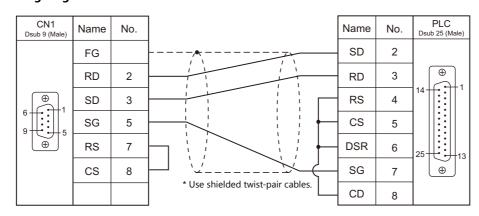
Wiring diagram 1 - C2



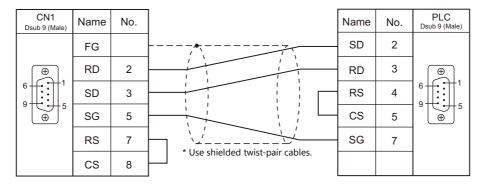
Wiring diagram 2 - C2



Wiring diagram 3 - C2

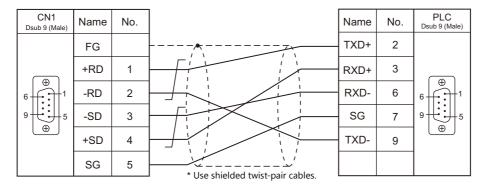


Wiring diagram 4 - C2

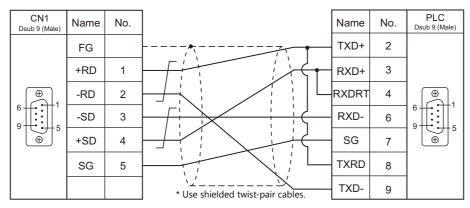


RS-422/RS-485

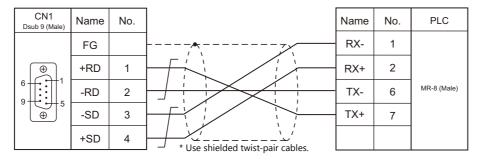
Wiring diagram 1 - C4



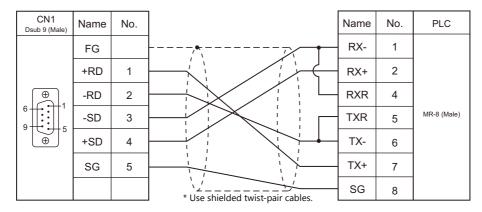
Wiring diagram 2 - C4



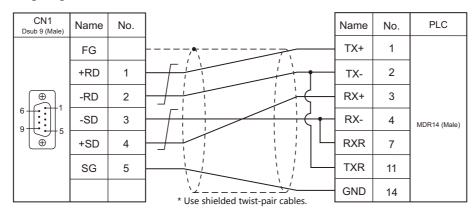
Wiring diagram 3 - C4



Wiring diagram 4 - C4



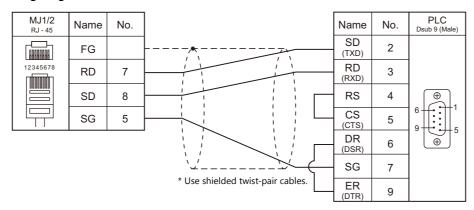
Wiring diagram 5 - C4



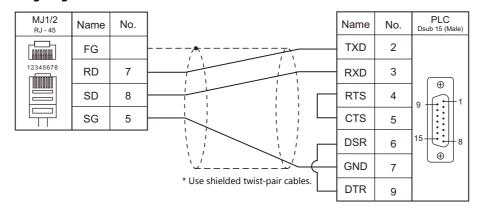
When Connected at MJ1/MJ2:

RS-232C

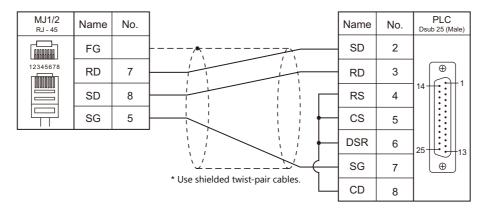
Wiring diagram 1 - M2



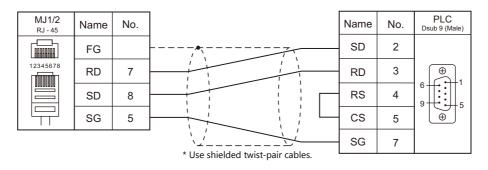
Wiring diagram 2 - M2



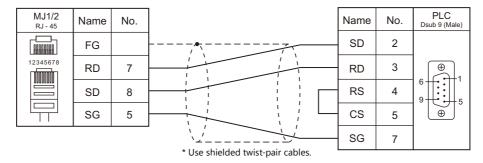
Wiring diagram 3 - M2



Wiring diagram 4 - M2

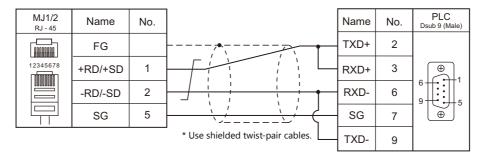


Wiring diagram 5 - M2

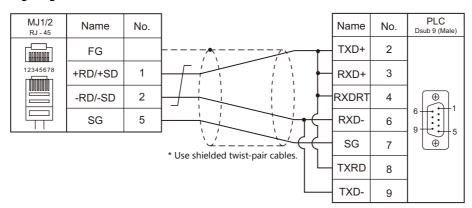


RS-422/RS-485

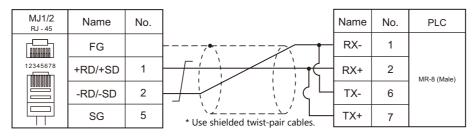
Wiring diagram 1 - M4



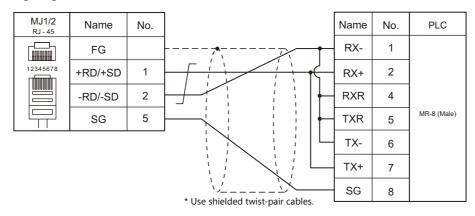
Wiring diagram 2 - M4



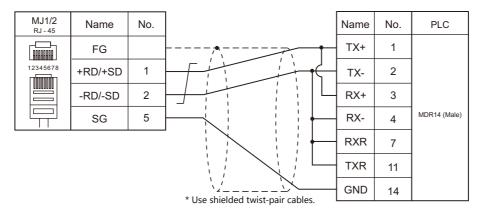
Wiring diagram 3 - M4



Wiring diagram 4 - M4



Wiring diagram 5 - M4



24. Yokogawa Electric

- 24.1 PLC Connection
- 24.2 Temperature Controller/Servo/Inverter Connection

24.1 PLC Connection

Serial Connection

PLC Selection on the	CPU	Unit/Port	Signal Level	Conn	ection	Ladder
Editor	СРО	Unit/Port	Signal Level	CN1	MJ1/MJ2	Transfer *2
	F3SP21-0N F3SP25-2N F3SP35-5N	PROGRAMMER port	RS-232C	Yokogawa's "KM11-xT" + Gender changer *3	Yokogawa's "KM11-xT" + Wiring diagram 2 - M2	0
		F3LC01-1N ^{*1}	RS-232C	Wiring diagram 1 - C2 or	Wising diagram 1 M2	
FA-M3	F3SP20-0N F3SP21-0N	F3LC11-1N	RS-232C	Hakko Electronics' cable "D9-YO2-09"*4	Wiring diagram 1 - M2	×
	F3SP25-2N F3SP35-5N	F3LC11-2N	RS-422	Wiring diagram 1 - C4 or Hakko Electronics' cable "D9-YO4-0T"*5	Wiring diagram 1 - M4	
	F3SP28-3N/3S F3SP38-6N/6S F3SP53-4H/4S F3SP58-6H/6S F3SP59-7S	PROGRAMMER port	RS-232C	Yokogawa's "KM11-xT" + Gender changer *3	Yokogawa's "KM11-xT" + Wiring diagram 2 - M2	0
FA-M3R	F3SP28-3N/3S F3SP38-6N/6S F3SP53-4H/4S F3SP58-6H/6S	F3LC11-1N F3LC11-1F F3LC12-1F	RS-232C	Wiring diagram 1 - C2 or Hakko Electronics' cable "D9-YO2-09"*4	Wiring diagram 1 - M2	
	F3SP59-7S F3SP66-4S F3SP67-6S F3SP71-4N/4S F3SP76-7N/7S	F3LC11-2N F3LC11-2F	RS-422	Wiring diagram 1 - C4 or Hakko Electronics' cable "D9-YO4-0T"*5	Wiring diagram 1 - M4	×
	F3SP66-4S F3SP67-6S	SIO port	RS-232C	Yokogawa's "KM21-2T" + Gender changer *3	Yokogawa's "KM21-2T" + Wiring diagram 2 - M2	×
FA-M3V	F3LC11-1N F3LC11-1F F3LC12-1F		RS-232C	Wiring diagram 1 - C2 or Hakko Electronics' cable "D9-YO2-09"*4	Wiring diagram 1 - M2	
	F3SP76-7N/7S	, -		Wiring diagram 1 - C4 or Hakko Electronics' cable "D9-YO4-0T"*5	Wiring diagram 1 - M4	×

^{*1} When the link unit "F3LC01-1N" is used, the communication setting and available device memory are the same as those for "FA-500". However, "B" (common register) cannot be used.

^{*2} For the ladder transfer function, see the V9 Series Reference Manual.
*3 Use a D-sub gender changer (9-pin, female-to-male) commercially available.

Manufacturer	Model
Black Box	FA440-R2
Misumi	DGC-9PP

^{*4} Cable length: D9-YO2-09- \square M (\square = 2, 3, 5)

^{*5} Cable length: D9-YO4-0T- \square M (\square = 2, 15)

Ethernet Connection

PLC Selection on the Editor	CPU	Unit/Port	TCP/IP	UDP/IP	Port No.	Keep Alive ^{*1}	Ladder Transfer *2
		F3LE01-5T			12289		
FA-M3/FA-M3R	FA-M3/FA-M3R	F3LE11-0T F3LE12-0T					
(Ethernet UDP/IP)	F3SP66-4S F3SP67-6S F3SP71-4N F3SP76-7N	Т/ТХ			12289 12291		
		F3LE01-5T	×	0	12289		
FA-M3/FA-M3R	FA-M3/FA-M3R	F3LE11-0T F3LE12-0T					
(Ethernet UDP/IP ASCII)	F3SP66-4S F3SP67-6S	T/TX			12289 12291		
	F3SP71-4N/4S F3SP76-7N/7S	10BASE-T/ 100BASE-TX					
FA-M3/FA-M3R (Ethernet TCP/IP)		F3LE01-5T			12289 *3		
	FA-M3/FA-M3R	F3LE11-0T F3LE12-0T					N. Control of the con
	F3SP66-4S F3SP67-6S	T/TX			12289 12291 *3		
	F3SP71-4N/4S F3SP76-7N/7S	10BASE-T/ 100BASE-TX	0			0	×
	FA-M3/FA-M3R	F3LE01-5T		×	12289 *3		
FA-M3/FA-M3R		F3LE11-0T F3LE12-0T					
(Ethernet TCP/IP ASCII)	F3SP66-4S F3SP67-6S	T/TX			12289 12291 *3		
	F3SP71-4N/4S F3SP76-7N/7S	10BASE-T/ 100BASE-TX					
		F3LE01-5T			12289 *3		
FA-M3V (Ethernet)	F3SP71-4N/4S F3SP76-7N/7S	F3LE11-0T F3LE12-0T			12289		
	1 331 /0-/11//3	10BASE-T/ 100BASE-TX			12291		
		F3LE01-5T	0	0	12289 *3		
FA-M3V (Ethernet ASCII)	F3SP71-4N/4S F3SP76-7N/7S	F3LE11-0T F3LE12-0T			12289		
, mov (zalemet noch)	133170 714773	10BASE-T/ 100BASE-TX			12291 *3		

^{*1} For KeepAlive functions, see "1.3.2 Ethernet Communication".
*2 For the ladder transfer function, see the V9 Series Reference Manual.
*3 For TCP/IP connection, the number of V9 series units that can be connected to one port is limited.
3LE01-5T/F3LE11-0T/CPU built-in LAN port: Max. 8 units
F3LE12-0T: Max. 9 units

24.1.1 FA-M3/FA-M3R

Communication Setting

Editor

Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1:1/1:n/Multi-link/Multi-link2/Multi-link2 (Ethernet)/ 1:n Multi-link2 (Ethernet)	
Signal Level	<u>RS-232C</u> / RS-422/485	
Baud Rate	4800 / 9600 / 19200 / 38400 /57600 / 76800 / <u>115K</u> bps	
Data Length	7 / <u>8</u> bits	
Stop Bit	<u>1</u> / 2 bits	
Parity	None / Odd / Even	
Target Port No.	0 to 31	
Transmission Mode	With Sum Check / Without Sum Check	

PLC

CPU Programmer Port / SIO Port

(Underlined setting: default)

Item	Programmer port	SIO Port		
Communication Mode	9600 bps, even parity 9600 bps, no parity 19200 bps, no parity 19200 bps, even parity 38400 bps, even parity 38400 bps, no parity 57600 bps, even parity 57600 bps, no parity 115200 bps, even parity	9600 bps, even parity 9600 bps, no parity 19200 bps, even parity 19200 bps, no parity 38400 bps, even parity 38400 bps, no parity 57600 bps, even parity 57600 bps, no parity 115200 bps, no parity 115200 bps, no parity		
PC Link Function	U	se		
Sum check	Provided / <u>N</u>	lot provided		
Terminal Character	None			
Protection Function	None			
Data Length	8	3		

PC Link Module

Station number setting

(Underlined setting: default)

Station Number Setting	Setting	Setting Example
STATION NO.	<u>01</u> to 32	01

Baud rate setting switch

F3LC01-1N / F3LC11-1N / F3LC11-2N

(Underlined setting: default)

Baud Rate Setting Switch	Setting	Baud Rate	Remarks
2 3	4	4800 bps	
	<u>5</u>	9600 bps	
	6	19200 bps	

F3LC11-1F / F3LC12-1F / F3LC11-2F

(Underlined setting: default)

Baud Rate Setting Switch	Setting	Baud Rate	Remarks
	4	4800 bps	
2345	5	9600 bps	
	7	19200 bps	
30384	9	38400 bps	
	A	57.6 kbps	
	В	76.8 kbps	
	<u>C</u>	<u>115.2 kbps</u>	

Data format setting switch

(Underlined setting: default)

Switch	Functions	OFF	ON	Setting Example
1	Data length	7	<u>8</u>	
2	Dority	Not provided	Provided	© <u>■</u> 1
3	Parity	<u>Odd</u>	Even	F
4	Stop bit	<u>1</u>	2	4
5	Sum check	Not provided	Provided	 5
6	Terminal character	Not provided	Provided	6
7	Protection function	Not provided	Provided	
8	-	-	-	

Function setting switch

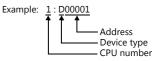
All OFF

Available Device Memory

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

	Device Memory	TYPE	Remarks
D	(data register)	00H	
R	(common register)	01H	
٧	(index register)	02H	
W	(link register)	03H	
Z	(special register)	04H	
TP	(count-down timer/current value)	05H	
TS	(timer/set value)	06H	Read only
СР	(count-down counter/current value)	07H	
CS	(counter/set value)	08H	Read only
Χ	(input relay)	09H	
Υ	(output relay)	0AH	
I	(internal relay)	0BH	
E	(common relay)	0CH	
L	(link relay)	0DH	
М	(special relay)	0EH	
В	(file register)	0FH	
SW	(special module register)	10H	
SL	(special module register)	11H	Double-word
F	(cache register)	12H	Available only with F3SP71-4N/4S and F3SP76-7N/7S CPU.

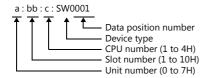
^{*} The CPU number is required in addition to the device type and address. The assigned device memory is expressed as shown on the right when editing the screen.



SW/SL device memory

The SW or SL device memory is used to read/write data from/into the data position number of the specified special module. For more information, refer to the PLC manual issued by the manufacturer.

The address denotation of the SW or SL device memory is shown below.



Indirect Device Memory Designation

• For X/Y device memory

15	5 8	7 0
n + 0	Model	Device type
n + 1	Addre	ss No.
n + 2	Expansion code *	Bit designation
n + 3	00	Station number

* For the expansion code, specify the value obtained by subtracting "1" from the actual CPU number.

Example: When specifying "X935" by indirect device memory designation



Converting "A" into a binary number 9 (DEC) = 1001 (BIN)

09	08	07	06	05	04	03	02	01	00
0	0	0	0	0	0	1	0	0	1
	z					\Box_{x}			

Converting "BB" into a binary number 35 (DEC) = 100011 (BIN)

07	06	05	04	03	02	01	00	
0	0	1	0	0	0	1	1	
		Y			C	it No. Obtaine 1" fron	ed by :	subtracting value.

Arranging the values X, Y and Z in the following order

15	14	13	12	11	10	09	08	07	06	05	04	03	02	01	00
0	0	0	0	1	0	0	1	0	0	0	0	0	0	1	0
				\sqsubseteq_{x}					z		— Fix	red to	0	Ly	

0000100100000010 (BIN) = 902 (HEX): Address No. 0011 (BIN) = 3 (HEX) - 1 = 2 (HEX): Bit No.

Example: When specifying "X76705" by indirect device memory designation



Converting "AAA" into a binary number

767 (DEC) = 1011111111 (BIN)

09	08	07	06	05	04	03	02	01	00
1	0	1	1	1	1	1	1	1	1
	— z					\Box_{X}			

Converting "BB" into a binary number 05 (DEC) = 101 (BIN)

07	06	06	05	04	03	02	01	00	
0	0	0	0	0	0	1	0	1	
			—ү				it No. btaine L" fron	ed by s	subtractin value.

Arranging the values X, Y and Z in the following order

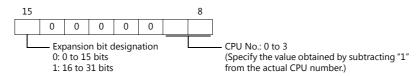
1	1	1	1	1	1	1	1	1	0	0	0	0	0	0	0
15	14	13	12	11	10	09	08	07	06			03	02	01	00

1111111110000000 (BIN) = FF80 (HEX): Address No. 0101 (BIN) = 5 (HEX) - 1 = 4 (HEX): Bit No.

· For SW/SL device memory

15	5 8	7 0
n + 0	Model	Device type
n + 1	Addres	ss No. *1
n + 2	Unit number (0 to 7H)	Slot number (1 to 10H)
n + 3	Expansion code *2	Bit designation
n + 4	00	Station number

- Specify the data position for the address number. The value to specify is obtained by subtracting "1" from the actual data position.
- Specify the expansion bit and the CPU number in the expansion code.



• Other than X/Y/SW/SL device memory

For the device memory address number, specify the value obtained by subtracting "1" from the actual address. For the expansion code, specify the value obtained by subtracting "1" from the actual CPU number.

PLC_CTL

Macro command "PLC_CTL F0 F1 F2"

Contents	F0		F1 (= \$u n)	F2				
User log registration number read	1 - 8 (PLC1 - 8)	n	CPU No. + station No. O001H Station No.: 01 to 1F CPU No. CPU No. 1: 00 CPU No. 2: 01 CPU No. 3: 02 CPU No. 4: 03	2				
		n + 1	Command: FFFFH					
		n + 2	Registration number (Stores the same number as the one stored in special register Z105.)					
		n	CPU No. + station No. 0001H Station No.: 01 to 1F CPU No. CPU No. 1: 00 CPU No. 2: 01 CPU No. 3: 02 CPU No. 4: 03					
		n + 1	Command: 0000H					
Latest user log read	1 - 8 (PLC1 - 8)	n + 2	Header 0: Normal -1: Error (data not exist/communication error)	2				
		n + 3	Year (ASCII)					
		n + 4	Month (ASCII)					
		n + 5	Day (ASCII)					
		n + 6	Hour (ASCII)					
		n + 7	Minute (ASCII)					
		n + 8	Second (ASCII)					
		n + 9	Main code (DEC)					
		n + 10	Sub code (DEC)					
		n	CPU No. + station No. 0001H Station No.: 01 to 1F CPU No. CPU No. 1: 00 CPU No. 2: 01 CPU No. 3: 02 CPU No. 4: 03					
		n + 1	Command: 0001H to 003FH					
"n"th user log read	1 - 8 (PLC1 - 8)	n + 2	Header 0: Normal -1: Error (data not exist/communication error)	2				
		n + 3	Year (ASCII)					
		n + 4	Month (ASCII)					
		n + 5	Day (ASCII)					
		n + 6 Hour (ASCII)						
		n + 7	Minute (ASCII)					
		n + 8	Second (ASCII)					
		n + 9	Main code (DEC)					
		n + 10	Sub code (DEC)					

Contents	F0		F1 (= \$u n)	F2			
			CPU No. + station No.				
		n	0001H Station No.: 01 to 1F CPU No. CPU No. 1: 00 CPU No. 2: 01 CPU No. 3: 02 CPU No. 4: 03				
		n + 1	Command: 0100H				
Latest system log read	1 - 8 (PLC1 - 8)	n + 2	Error type 0: System error 1: Basic error 2: Sequence error 3: I/O error	2			
		n + 3	Error code				
		n + 4	Year (ASCII)				
		n + 5	Month (ASCII)				
		n + 6	Day (ASCII)				
		n + 7	Hour (ASCII)				
		n + 8	Minute (ASCII)				
		n + 9 Second (ASCII)					
		n + 10 -	n + 10 - Additional information (max. 11 words) *1				
	1 - 8 (PLC1 - 8)	n	CPU No. + station No. 0001H Station No.: 01 to 1F CPU No. CPU No. 1: 00 CPU No. 2: 01 CPU No. 3: 02 CPU No. 4: 03				
		n + 1 Command: 0101H to 017FH					
"n"th system log read		n + 2	Error type 0: System error 1: Basic error 2: Sequence error 3: I/O error	2			
		n + 3	Error code				
		n + 4	Year (ASCII)				
		n + 5	Month (ASCII)				
		n + 6	Day (ASCII)				
		n + 7	Hour (ASCII)				
		n + 8	Minute (ASCII)				
		n + 9	Second (ASCII)				
		n + 10 -	Additional information (max. 11 words) *1				
Alarm information clear	1 - 8 (PLC1 - 8)	n	CPU No. + station No. 0001H Station No.: 01 to 1F CPU No. CPU No. 1: 00 CPU No. 2: 01 CPU No. 3: 02 CPU No. 4: 03	2			
		n + 1	Command: FFFEH				

Contents	F0		F	1 (= \$u n)	F2
		n		ation No.: 01 to 1F PU No. CPU No. 1: 00 CPU No. 2: 01 CPU No. 3: 02 CPU No. 4: 03	
		n + 1	Command: FF		
		n + 2	Unit No.: 0 to	7	
Mounted module name readout	1 - 8 (PLC1 - 8)	n + 3 to n + 4		Module name (ASCII)	
		n + 5	Module information of slot 1 *2	I/O type (DEC) 0: Without I/O relay 1: Input relay only 2: Output relay only 3: With both input and output	3
Wounted module name readout		n + 6		Number of I/O relays (DEC)	5
		n + 7 to n + 8		Module name (ASCII)	
		n + 9	Module information of slot 2 *2	I/O type (DEC) 0: Without I/O relay 1: Input relay only 2: Output relay only 3: With both input and output	
		n + 10		Number of I/O relays (DEC)	
		:	:	:	
		n + 63 to n + 64		Module name (ASCII)	
		n + 65	Module information of slot 16 *2	I/O type (DEC) 0: Without I/O relay 1: Input relay only 2: Output relay only 3: With both input and output	
		n + 66		Number of I/O relays (DEC)	

Return data: Data stored from PLC to V series

- *1 Additional information (max. 11 words)
 - For "system error" No additional information
 - For "basic error"

n + 10 to n + 13	Block name (8 bytes)
	Command number: 5-digit string pattern in decimal notation (5 bytes)

• For "sequence error"

n + 10 to n + 13	Program name (8 bytes)
n + 14 to n + 17	Subprogram name (8 bytes)
n + 18 to n + 20	Row number: 5 digits in decimal notation (5 bytes)

• For "I/O error"

n + 10 to n + 11	Slot number (4 bytes)
n + 12 to n + 13	Detailed error (4 bytes)

^{*2} When no module is mounted, "(space)" is assigned for the module name and "0" is assigned for the I/O type and the number of I/O relays.

24.1.2 FA-M3/FA-M3R (Ethernet UDP/IP)

Communication Setting

Editor

Make the following settings on the editor. For more information, see "1.3.2 Ethernet Communication".

- IP address for the V9 unit
 - When specified on the screen program: [System Setting] \rightarrow [Hardware Setting] \rightarrow [Local Port IP Address]
 - When specified on the V9 unit: Local mode → [LAN Setting]
- Port number for the V9 unit (for communication with PLC) $[\text{System Setting}] \rightarrow [\text{Hardware Setting}] \rightarrow [\text{PLC Properties}] \rightarrow [\text{Communication Setting}]$
- IP address and port number of the PLC $\mathsf{Register} \ on \ the \ [\mathsf{PLC} \ \mathsf{Table}] \ in \ [\mathsf{System} \ \mathsf{Setting}] \ \rightarrow \ [\mathsf{Hardware} \ \mathsf{Setting}] \ \rightarrow \ [\mathsf{Target} \ \mathsf{Setting}].$

PLC

Ethernet Module

Condition setting switch

SW9	BIT	Contents	Setting		
	1		F3LE01-5T		
		Data format setting	Port No.	OFF	ON
1 2 3 4 5 6 7 8			12289	ASCII	Binary
0FF			F3LE11-0T/F3LE12-0T		
			Port No.	OFF	ON
			12289	ASCII	Binary
			12291	Binary	ASCII
					.
	2	Write protection	OFF: not protected		ted
	3		OFF		
	4	System reserved			
	5	System reserved			
	6				
	7	Line handling at TCP time-out ^{*1}	OFF: close		
	8	Operation mode	OFF: normal		

- *1 F3LE01-5T only *2 Port number: 12289

IP address setting switch

(Underlined setting: default)

IP Address Setting Switch	Setting	Remarks
SW1 SW3 SW6 SW7 SW2 SW4 SW6 SW8	<u>0.0.0.0</u> to 255.255.255	Set in hexadecimal notation. Example HEX C0.A8.FA.D2 ↓ DEC 192.168.250.210

T/TX, 10BASE-T/100BASE-TX Ports

CPU properties

Setting	Setting Items	Setting	Remarks	
NETWORK	NETWORK_SELECT 1			
ETHERNET	ETHER_MY_IPADDRESS	0.0.0.0 - 255.255.255.255	IP address	
	ETHER_SUBNET_MASK	0.0.0.0 - 255.255.255.255	Subnet mask	
	HLLINK_PROTOCOL_A	1: UDP/IP	Port 12289	
HIGHER-LEVEL_LINK_SERVICE	HLLINK_DATA_FORMAT_A	1: binary code	POIT 12209	
	INK_SERVICE HLLINK_PROTOCOL_B 1: UDP/IP		Port 12291	
	HLLINK_DATA_FORMAT_B	1: binary code	POIT 12291	
	HLLINK_PROTECT	0: write enabled		

Available Device Memory

The contents of "Available Device Memory" are the same as those described in "24.1.1 FA-M3/FA-M3R".

PLC_CTL

The contents of "PLC_CTL" are the same as those described in "24.1.1 FA-M3/FA-M3R".

* The station number can be specified in the range from 0 to FFH.

For the station number, specify the PLC table number set for [System Setting] → [Hardware Setting] → [PLC Properties] → [Target Settings].

24.1.3 FA-M3/FA-M3R (Ethernet UDP/IP ASCII)

Communication Setting

Editor

Make the following settings on the editor. For more information, see "1.3.2 Ethernet Communication".

- IP address for the V9 unit
 - When specified on the screen program:
 [System Setting] → [Hardware Setting] → [Local Port IP Address]
 - When specified on the V9 unit: Local mode → [LAN Setting]
- Port number for the V9 unit (for communication with PLC)
 [System Setting] → [Hardware Setting] → [PLC Properties] → [Communication Setting]
- IP address and port number of the PLC Register on the [PLC Table] in [System Setting] → [Hardware Setting] → [PLC Properties] → [Target Settings].

PLC

Ethernet Module

Condition setting switch

SW9	BIT	Contents	Setting		
	1		F3LE01-5T		
			Port No.	OFF	ON
			12289	ASCII	Binary
1 2 3 4 5 6 7 8		Data format setting	F3LE11-0T/F3LE12-0T		
			Port No.	OFF	ON
			12289	ASCII	Binary
			12291	Binary	ASCII
	2	Write protection	OFF: not protected		ed
	3		OFF		
	4	System reserved			
	5	System reserved			
	6				
	7	Line handling at TCP time-out*1	OFF: close		
	8	Operation mode	OFF: normal		

^{*1} F3LE01-5T only

IP address setting switch

(Underlined setting: default)

IP Address Setting Switch	Setting	Remarks
SW1 SW3 SW6 SW7 SW2 SW4 SW6 SW6 SW8 SW8	<u>0.0.0.0</u> to 255.255.255.255	Set in hexadecimal notation. Example HEX C0.A8.FA.D2 DEC 192.168.250.210

T/TX, 10BASE-T/100BASE-TX Ports

CPU properties

Setting	Setting Items	Setting	Remarks	
NETWORK	NETWORK_SELECT	1		
ETHERNET	ETHER_MY_IPADDRESS	0.0.0.0 to 255.255.255.255	IP address	
	ETHER_SUBNET_MASK	0.0.0.0 to 255.255.255.255	Subnet mask	
HIGHER-LEVEL_LINK_SERVICE	HLLINK_PROTOCOL_A	1: UDP/IP	Port 12289	
	HLLINK_DATA_FORMAT_A	0: ASCII format	PORT 12289	
	HLLINK_PROTOCOL_B	1: UDP/IP	Port 12291	
	HLLINK_DATA_FORMAT_B	0: ASCII format	POIT 12291	
	HLLINK_PROTECT	0: write enabled		

Available Device Memory

The contents of "Available Device Memory" are the same as those described in "24.1.1 FA-M3/FA-M3R".

PLC_CTL

The contents of "PLC_CTL" are the same as those described in "24.1.1 FA-M3/FA-M3R".

* The station number can be specified in the range from 0 to FFH.

For the station number, specify the PLC table number set for [System Setting] → [Hardware Setting] → [PLC Properties] → [Target Settings].

24.1.4 FA-M3/FA-M3R (Ethernet TCP/IP)

Communication Setting

Editor

Make the following settings on the editor. For more information, see "1.3.2 Ethernet Communication".

- IP address for the V9 unit
 - When specified on the screen program: [System Setting] \rightarrow [Hardware Setting] \rightarrow [Local Port IP Address]
 - When specified on the V9 unit: Local mode → [LAN Setting]
- Port number for the V9 unit (for communication with PLC) $[\text{System Setting}] \rightarrow [\text{Hardware Setting}] \rightarrow [\text{PLC Properties}] \rightarrow [\text{Communication Setting}]$
- IP address and port number of the PLC $\mathsf{Register} \ on \ the \ [\mathsf{PLC} \ \mathsf{Table}] \ in \ [\mathsf{System} \ \mathsf{Setting}] \ \rightarrow \ [\mathsf{Hardware} \ \mathsf{Setting}] \ \rightarrow \ [\mathsf{Target} \ \mathsf{Setting}].$

PLC

Ethernet Module

Condition setting switch

SW9	BIT	Contents	Setting				
			F3LE01-5T	F3LE01-5T			
			Port No.	OFF	ON		
1 2 3 4 5 6 7 8			12289	ASCII	Binary		
OFF OFF	1	Data format setting	F3LE11-0T/F3LE12-0T				
			Port No.	OFF	ON		
			12289	ASCII	Binary		
			12291	Binary	ASCII		
	2	Write protection	(OFF: not protec	ted		
	3						
	4	Customs was an used	OFF				
	5	System reserved					
	6						
	7	Line handling at TCP time-out ^{*1}		OFF: close			
	8	Operation mode	OFF: normal				

- F3LE01-5T only Port number: 12289

IP address setting switch

IP Address Setting Switch	Setting	Remarks
SW1 SW5 SW7 SW1 SW4 SW6 SW8 SW1 SW8 SW8	<u>0.0.0.0</u> to 255.255.255	Set in hexadecimal notation. Example HEX C0.A8.FA.D2 DEC 192.168.250.210

T/TX, 10BASE-T/100BASE-TX Ports

CPU properties

Setting	Setting Items Setting		Remarks
NETWORK	NETWORK_SELECT	1	
ETHERNET	ETHER_MY_IPADDRESS	0.0.0.0 - 255.255.255	IP address
	ETHER_SUBNET_MASK	0.0.0.0 - 255.255.255	Subnet mask
	HLLINK_PROTOCOL_A	0: TCP/IP	Port 12289
	HLLINK_DATA_FORMAT_A	1: binary code	PORT 12289
HIGHER-LEVEL_LINK_SERVICE	HLLINK_PROTOCOL_B	0: TCP/IP	Port 12291
	HLLINK_DATA_FORMAT_B	1: binary code	PUIL 12291
	HLLINK_PROTECT	0: write enabled	

Available Device Memory

The contents of "Available Device Memory" are the same as those described in "24.1.1 FA-M3/FA-M3R".

PLC_CTL

The contents of "PLC_CTL" are the same as those described in "24.1.1 FA-M3/FA-M3R".

* The station number can be specified in the range from 0 to FFH.
For the station number, specify the PLC table number set for [System Setting] → [Hardware Setting] → [PLC Properties] → [Target Settings].

24.1.5 FA-M3/FA-M3R (Ethernet TCP/IP ASCII)

Communication Setting

Editor

Make the following settings on the editor. For more information, see "1.3.2 Ethernet Communication".

- IP address for the V9 unit
 - When specified on the screen program:
 [System Setting] → [Hardware Setting] → [Local Port IP Address]
 - When specified on the V9 unit: Local mode → [LAN Setting]
- Port number for the V9 unit (for communication with PLC)
 [System Setting] → [Hardware Setting] → [PLC Properties] → [Communication Setting]
- IP address and port number of the PLC Register on the [PLC Table] in [System Setting] → [Hardware Setting] → [PLC Properties] → [Target Settings].

PLC

Ethernet Module

Condition setting switch

SW9	BIT	Contents		Setting			
			F3LE01-5T	F3LE01-5T			
			Port No.	OFF	ON		
			12289	ASCII	Binary		
	1	Data format setting	F3LE11-0T/F3LE12-0T				
			Port No.	OFF	ON		
			12289	ASCII	Binary		
			12291	Binary	ASCII		
	2	Write protection	OFF: not protected				
	3		OFF				
	4	System reserved					
	5	System reserved					
	6						
	7	Line handling at TCP time-out*1		OFF: close			
	8	Operation mode	OFF: normal				

^{*1} F3LE01-5T only

IP address setting switch

(Underlined setting: default)

IP Address Setting Switch	Setting	Remarks
SW1 SW3 SW5 SW7 SW2 SW4 SW6 SW6 SW8	<u>0.0.0.0</u> to 255.255.255	Set in hexadecimal notation. Example HEX C0.A8.FA.D2 ↓ DEC 192.168.250.210

T/TX, 10BASE-T/100BASE-TX Ports

CPU properties

Setting	Setting Items	Setting	Remarks	
NETWORK	NETWORK_SELECT	1		
ETHERNET	ETHER_MY_IPADDRESS	0.0.0.0 to 255.255.255.255	IP address	
EIHERNEI	ETHER_SUBNET_MASK	0.0.0.0 to 255.255.255.255	Subnet mask	
	HLLINK_PROTOCOL_A	0: TCP/IP	Port 12289	
	HLLINK_DATA_FORMAT_A	0: ASCII format	FOIT 12269	
HIGHER-LEVEL_LINK_SERVICE	HLLINK_PROTOCOL_B	0: TCP/IP	Port 12291	
	HLLINK_DATA_FORMAT_B	0: ASCII format	FOIT 12291	
	HLLINK_PROTECT	0: write enabled		

Available Device Memory

The contents of "Available Device Memory" are the same as those described in "24.1.1 FA-M3/FA-M3R".

PLC_CTL

The contents of "PLC_CTL" are the same as those described in "24.1.1 FA-M3/FA-M3R".

* The station number can be specified in the range from 0 to FFH.

For the station number, specify the PLC table number set for [System Setting] → [Hardware Setting] → [PLC Properties] → [Target Settings].

24.1.6 FA-M3V

Communication Setting

Editor

Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1:1/1:n/Multi-link/Multi-link2/ Multi-link2 (Ethernet)/1:nMulti-link2 (Ethernet)	
Signal Level	<u>RS-232C</u> / RS-422/485	
Baud Rate	4800 / 9600 / 19200 / 38400 / 57600 / 76800 / <u>115K</u> bps	
Data Length	7 / <u>8</u> bits	
Stop Bit	<u>1</u> / 2 bits	
Parity	None / Odd / Even	
Target Port No.	0 to 31	
Transmission Mode	With Sum Check / Without Sum Check	

PLC

PC Link Module

Station number setting

(Underlined setting: default)

Station No.	Setting	Example	
STATION NO.	<u>01</u> to 32	01	

Baud rate setting switch

F3LC11-1N / F3LC11-2N

(Underlined setting: default)

Baud Rate Setting Switch	Setting	Baud Rate	Remarks
	4	4800 bps	
2 3 y	<u>5</u>	9600 bps	
○	6	19200 bps	

F3LC11-1F / F3LC12-1F / F3LC11-2F

(Underlined setting: default)

Baud Rate Setting Switch	Setting	Baud Rate	Remarks
	4	4800 bps	
\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\	5	9600 bps	
	7	19200 bps	
3038 ⁴	9	38400 bps	
	A	57.6 Kbps	
	В	76.8 Kbps	
	<u>C</u>	<u>115.2 Kbps</u>	

Data format setting switch

(Underlined setting: default)

Switches	Function	OFF	ON	Example
1	Data length	7	<u>8</u>	
2	Parity	Not provided	Provided	0 <u> </u>
3	ranty	<u>Odd</u>	Even	F 2 3
4	Stop bit	<u>1</u>	2	<u> </u>
5	Checksum	Not provided	Provided	5
6	Terminal character	Not provided	Provided	6
7	Protection function	Not provided	Provided	8
8	=	=	=	

Function setting switch

All OFF

Available Device Memory

The contents of "Available Device Memory" are the same as those described in "24.1.1 FA-M3/FA-M3R".

PLC_CTL

The contents of "PLC_CTL" are the same as those described in "24.1.1 FA-M3/FA-M3R".



24.1.7 FA-M3V (Ethernet)

Communication Setting

Editor

Make the following settings on the editor. For more information, see "1.3.2 Ethernet Communication".

- IP address for the V9 unit
 - When specified on the screen program:
 - [System Setting] \rightarrow [Hardware Setting] \rightarrow [Local Port IP Address]
 - When specified on the V9 unit: Local mode → [LAN Setting]
- Connection port on the V9 unit:

The [Target Port No.] for the connected device on the [Hardware Setting] window ([System Setting] → [Hardware Setting])

- When using TCP/IP:
- Select [Built-in LAN (TCP)].
- When using UDP/IP: Select [Built-in LAN (UDP)].
- Port number for the V9 unit (for communication with PLC) $[\text{System Setting}] \rightarrow [\text{Hardware Setting}] \rightarrow [\text{PLC Properties}] \rightarrow [\text{Communication Setting}]$
- IP address and port number of the PLC Register on the [PLC Table] in [System Setting] \rightarrow [Hardware Setting] \rightarrow [PLC Properties] \rightarrow [Target Settings].

PLC

Ethernet Module

Condition setting switch

SW9	BIT	Contents		Setting			
			F3LE01-5T	F3LE01-5T			
			Port No.	OFF	ON		
			12289	ASCII	Binary		
	1	Data format setting	F3LE11-0T/F3L	F3LE11-0T/F3LE12-0T			
			Port No.	OFF	ON		
			12289	ASCII	Binary		
OFF			12291	Binary	ASCII		
	2	Write protection	OFF: not protected				
	3						
	4	Comtons recent					
	5	System reserve					
	6						
	7	Line handling at TCP time-out ^{*1}					
	8	Operation mode		OFF: normal			

^{*1} F3LE01-5T only

IP address setting switch

(Underlined setting: default)

IP Address Setting Switch	Setting	Remarks
SWI SWS SWS SWS SWS SWS SWS SWS SWS SWS	<u>0.0.0.0</u> to 255.255.255.255	Set in hexadecimal notation. Example: HEX C0.A8.FA.D2 DEC 192.168.250.210

10BASE-T/100BASE-TX Ports

CPU properties

Setting	Setting Items	Setting Values	Remarks
NETWORK	NETWORK_SELECT	1	
ETHERNET	ETHER_MY_IPADDRESS	0.0.0.0 to 255.255.255	IP address
ETTENNET	ETHER_SUBNET_MASK	0.0.0.0 to 255.255.255	Subnet mask
	HLLINK_PROTOCOL_A	0: TCP/IP 1: UDP/IP	Port 12289
	HLLINK_DATA_FORMAT_A	1: binary code	
HIGHER-LEVEL_LINK_SERVICE	HLLINK_PROTOCOL_B	0: TCP/IP 1: UDP/IP	Port 12291
	HLLINK_DATA_FORMAT_B	1: binary code	
	HLLINK_PROTECT	0: write enabled	

Available Device Memory

The contents of "Available Device Memory" are the same as those described in "24.1.1 FA-M3/FA-M3R".

PLC_CTL

The contents of "PLC_CTL" are the same as those described in "24.1.1 FA-M3/FA-M3R".

* The station number can be specified in the range from 0 to FFH.

For the station number, specify the PLC table number set for [System Setting] → [Hardware Setting] → [PLC Properties] → [Target Settings].

24.1.8 FA-M3V (Ethernet ASCII)

Communication Setting

Editor

Make the following settings on the editor. For more information, see "1.3.2 Ethernet Communication".

- IP address for the V9 unit
 - When specified on the screen program: [System Setting] → [Hardware Setting] → [Local Port IP Address]
 - When specified on the V9 unit: Local mode → [LAN Setting]
- Connection port on the V9 unit:

The [Target Port No.] for the connected device on the [Hardware Setting] window ([System Setting] → [Hardware Setting])

- When using TCP/IP:
- Select [Built-in LAN (TCP)].
- When using UDP/IP: Select [Built-in LAN (UDP)].
- Port number for the V9 unit (for communication with PLC)
 [System Setting] → [Hardware Setting] → [PLC Properties] → [Communication Setting]
- IP address and port number of the PLC
 Register on the [PLC Table] in [System Setting] → [Hardware Setting] → [PLC Properties] → [Target Settings].

PLC

Ethernet Module

Condition setting switch

SW9	Bits	Contents	Setting				
			F3LE01-5T	F3LE01-5T			
			Port No.	OFF	ON		
			12289	ASCII	Binary		
	1	Data format setting	F3LE11-0T/F3I	F3LE11-0T/F3LE12-0T			
1 2 3 4 5 6 7 8			Port No.	OFF	ON		
			12289	ASCII	Binary		
OFF			12291	Binary	ASCII		
	2	Write protection OFF: not protected			ed		
	3						
	4	Combana manana	OFF				
	5	System reserve					
	6						
	7	Line handling at TCP time-out ^{*1}		OFF: close			
	8	Operation mode		OFF: normal	·		

^{*1} F3LE01-5T only

IP address setting switch

(Underlined setting: default)

IP Address Setting Switch	Setting	Remarks
SWI SWS	<u>0.0.0.0</u> to 255.255.255.255	Set in hexadecimal notation. Example: HEX C0.A8.FA.D2 ↓ DEC 192.168.250.210

10BASE-T/100BASE-TX Ports

CPU properties

Setting	Setting Items	Setting Values	Remarks
NETWORK	NETWORK_SELECT	1	
ETHERNET	ETHER_MY_IPADDRESS	0.0.0.0 to 255.255.255	IP address
ETHERNET	ETHER_SUBNET_MASK	0.0.0.0 to 255.255.255	Subnet mask
	HLLINK_PROTOCOL_A	0: TCP/IP 1: UDP/IP	Port 12289
	HLLINK_DATA_FORMAT_A	0: ASCII format	
HIGHER-LEVEL_LINK_SERVICE	HLLINK_PROTOCOL_B	0: TCP/IP 1: UDP/IP	Port 12291
	HLLINK_DATA_FORMAT_B	0: ASCII format	
	HLLINK_PROTECT	0: write enabled	

Available Device Memory

The contents of "Available Device Memory" are the same as those described in "24.1.1 FA-M3/FA-M3R".

PLC_CTL

The contents of "PLC_CTL" are the same as those described in "24.1.1 FA-M3/FA-M3R".

* The station number can be specified in the range from 0 to FFH.

For the station number, specify the PLC table number set for [System Setting] → [Hardware Setting] → [PLC Properties] → [Target Settings].

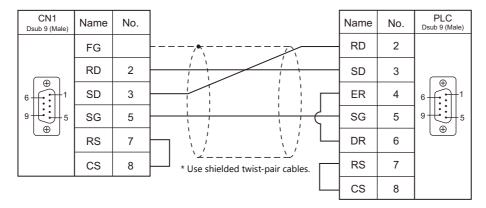
24.1.9 Wiring Diagrams

When Connected at CN1:

RS-232C

Wiring diagram 1 - C2

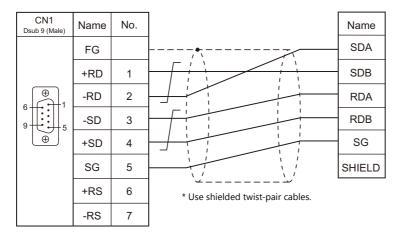
Hakko Electronics' cable "D9-YO2-09- \square M" (\square = 2, 3, 5)



RS-422/RS-485

Wiring diagram 1 - C4

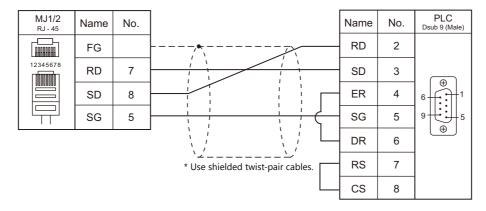
Hakko Electronics' cable "D9-YO4-0T- \square M" (\square = 2, 15)



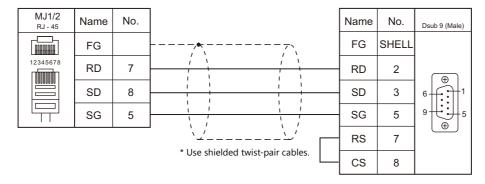
When Connected at MJ1/MJ2:

RS-232C

Wiring diagram 1 - M2

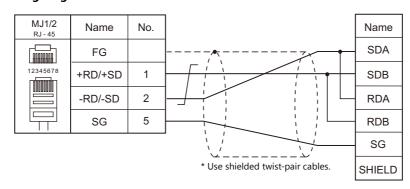


Wiring diagram 2 - M2



RS-422/RS-485

Wiring diagram 1 - M4



24.2 Temperature Controller/Servo/Inverter Connection

The controllers shown below can be connected.

Temperature Controller

PLC Selection	Model	Port Signal Level	Port Signal Level Conn		ection	Lst File
on the Editor	Wiodei	rort	Signal Level	CN1	MJ1/MJ2	LSCTILE
UT100	UT130-xx/RS UT150-xx/RS UT152-xx/RS UT155-xx/RS	RS-485 port	RS-485	Wiring diagram 2 - C4	Wiring diagram 2 - M4	UT100.Lst

Digital Indicating Controller

PLC Selection	Model	Port	Signal Level	Conn	ection	Lst File
on the Editor	Model	FOIL	Signal Level	CN1	MJ1/MJ2	LSCFIIE
	UT750-01	RS-485 port	RS-485	Wiring diagram 1 - C4	Wiring diagram 1 - M4	
UT750	UT750-11 UT750-51	High-speed RS-485 port	RS-485	Wiring diagram 2 - C4	Wiring diagram 2 - M4	UT750.Lst
UT550	UT550-01, 02 UT550-11, 12 UT550-21, 22 UT550-31, 32 UT550-41, 42	RS-485 port	RS-485			UT550.Lst
UT520	UT520-07	RS-485 port	RS-485			
UT350	UT350-01 UT350-21 UT350-31	RS-485 port	RS-485		Wiring diagram 1 - M4	UT350.Lst
UT320	UT320-01 UT320-21 UT320-31	RS-485 port	RS-485		01330.LSt	
UT450	UT450-01, 02 UT450-11, 12 UT450-21, 22 UT450-31, 32 UT450-41, 42	RS-485 port	RS-485			UT450.Lst

Multi-point Temperature Controller

PLC Selection	Model	Port	Signal Level	Conn	Lst File	
on the Editor	Model	FOIL	Signal Level	CN1	MJ1/MJ2	LSCFIIE
UT2400/2800	UT2400-1, 1/HB UT2400-2, 2/HB UT2400-3, 3/HB UT2400-4, 4/HB UT2800-1, 1/HB UT2800-2, 2/HB UT2800-3, 3/HB UT2800-4, 4/HB	RS-485 port	RS-422	Wiring diagram 3 - C4	×	UT2000.Lst

24.2.1 UT100

Communication Setting

Editor

Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1:1/ <u>1:n</u> /Multi-link/Multi-link2/ Multi-link2 (Ethernet)/ 1:n Multi-link2 (Ethernet)	
Signal Level	<u>RS-422/485</u>	
Baud Rate	4800 / <u>9600</u> bps	
Data Length	7 / <u>8</u> bits	
Stop Bit	<u>1</u> / 2 bits	
Parity	None / Odd / <u>Even</u>	
Target Port No.	1 to 31	
Sum Check	Provided / <u>Not provided</u>	Make the same setting as PSL (communication protocol selection) of the temperature controller.

^{*} Select "Without Sum Check" for the transmission mode on the editor when "1: PC link communication (with checksum)" is specified for P.SL (Protocol selection) on the controller.

Temperature Controller

The communication parameters can be set using keys attached to the temperature controller. Be sure to match the settings to those made under [Communication Setting] of the editor.

(Underlined setting: default)

Parameter	Display	Item	Setting	Example
	PSL	Protocol selection	0: PC link communication 1: PC link communication (with checksum)	0
	ADR	Communication address	<u>1</u> to 31	1
Communication	BPS	Baud rate	4.8: 4800 bps 9.6: 9600 bps	9.6
	PRI	Parity	NON: None EVN: Even ODD: Odd	EVN
	STP	Stop bit	1 / 2 bits	1
	DLN	Data length	7 / <u>8</u> bits	8

Available Device Memory

The available setting range of device memory varies depending on the model. Be sure to set within the range available for the model to be used. Use [TYPE] when assigning indirect device memory for macro programs.

	Device Memory	TYPE	Remarks
D	(data register)	00H	
I	(input relay)	01H	

Indirect Device Memory Designation

For the device memory address number, specify the value obtained by subtracting "1" from the actual address.

24.2.2 UT750

Communication Setting

Editor

Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1:1/1:n/Multi-link2/Multi-link2(Ethernet)/ 1:n Multi-link2(Ethernet)	
Signal Level	RS-422/485	
Baud Rate	4800 / <u>9600</u> / 19200 / 38400 bps	
Data Length	7 / <u>8</u> bits	
Stop Bit	<u>1</u> / 2 bits	
Parity	None / Odd / <u>Even</u>	
Target Port No.	<u>1</u> to 31	
Sum Check	Provided / <u>Not provided</u>	Make the same setting as PSL (communication protocol selection) of the temperature controller.

Digital Indicating Controller

The communication parameters can be set using keys attached to the digital indicating controller. Be sure to match the settings to those made under [Communication Setting] of the editor.

(Underlined setting: default)

Parameter	Port	Indication	Item	Setting	Example
		PSL1	Protocol selection 1	0: Personal computer link communication 1: Personal computer link communication (with sum check)	0
		BPS1	Baud rate 1	3: 4800 bps 4: 9600 bps	4
	RS-485 port	PRI1	Parity 1	0: None 1: Even 2: Odd	1
		STP1	Stop bit 1	<u>1</u> / 2 bits	1
		DLN1	Data length 1	7 / <u>8</u> bits	8
		ADR1	Address 1	<u>1</u> to 31	1
Communication	High-speed RS-485 port	PSL2	Protocol selection 2	0: Personal computer link communication 1: Personal computer link communication (with sum check)	0
		BPS2	Baud rate 2	3: 4800 bps 4: 9600 bps 5: 19200 bps 6: 38400 bps	4
		PRI2	Parity 2	0: None 1: Even 2: Odd	1
		STP2	Stop bit 2	1 / 2 bits	1
		DLN2	Data length 2	7 / <u>8</u> bits	8
		ADR2	Address 2	<u>1</u> to 31	1

Available Device Memory

The available setting range of device memory varies depending on the model. Be sure to set within the range available for the model to be used. Use [TYPE] when assigning indirect device memory for macro programs.

	Device Memory	TYPE	Remarks
D	(data register)	00H	
I	(input relay)	01H	

Indirect Device Memory Designation

For the device memory address number, specify the value obtained by subtracting "1" from the actual address.

24.2.3 UT550

Settings are the same as those described in "24.2.1 UT100".

24.2.4 UT520

Settings are the same as those described in "24.2.1 UT100".

24.2.5 UT350

Settings are the same as those described in "24.2.1 UT100".

24.2.6 UT320

Settings are the same as those described in "24.2.1 UT100".

24.2.7 UT450

Settings are the same as those described in "24.2.1 UT100".

24.2.8 UT2400/2800

Communication Setting

Editor

Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1:1/ <u>1:n</u> /Multi-link2/Multi-link2(Ethernet)/ 1:n Multi-link2(Ethernet)	
Signal Level	RS-422/485	
Baud Rate	4800 / <u>9600</u> bps	
Data Length	7 / <u>8</u> bits	
Stop Bit	<u>1</u> / 2 bits	
Parity	None / Odd / <u>Even</u>	
Target Port No.	<u>1</u> to 16	
CR	<u>Checked</u> / Unchecked	
CPU No. *	01 / 02	01: 1 to 4CH 02: 5 to 8CH (available only with UT2800)

Set the CPU number on the [Device Input] dialog. "CPU No. 2" is not provided for UT2400. It can be specified only when UT2800 is used.

Multi-point Temperature Controller

Be sure to match the settings to those made under [Communication Setting] of the editor.

Communication mode selector switch

(Underlined setting: default)

Communication Mode Selector Switch	OFF	ON	Remarks
OFF OFF	Ladder communication mode	Personal computer link communication mode	

Communication condition setting switch

Communication Condition Setting Switch	Setting	Baud Rate	Parity	Data Length	Stop Bit	Setting Example
	0		None			
B C O C	1	9600 bps	Odd			9600 bps
[-](\(\sum_{-1} \) \(\sum_{-1} \)	2		Even	8	1	₂ . Even
0 5 + E 1	3		None	8	1	2. 8 bits 1 bit
	4	4800 bps	Odd			1 DIL
	5		Even			

Unit No. selector switch

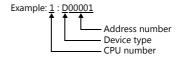
Unit No. Selector Switch	Setting	Station Number	Setting Example
	0 to F	1 to 16	0: Station number 1

Available Device Memory

The available setting range of device memory varies depending on the model. Be sure to set within the range available for the model to be used. Use [TYPE] when assigning indirect device memory for macro programs.

	Device Memory	TYPE	Remarks
D	(data register)	00H	
I	(input relay)	01H	

* The CPU number is required in addition to the device type and address. The assigned device memory is expressed as shown on the right when editing the screen.



Indirect Device Memory Designation

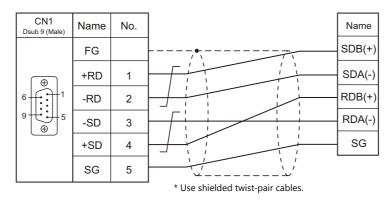
For the device memory address number, specify the value obtained by subtracting "1" from the actual address. Specify the CPU number in the expansion code.

24.2.9 Wiring Diagrams

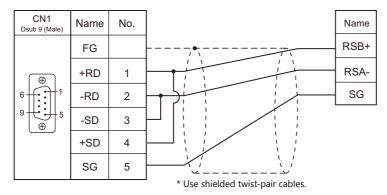
When Connected at CN1:

RS-422/RS-485

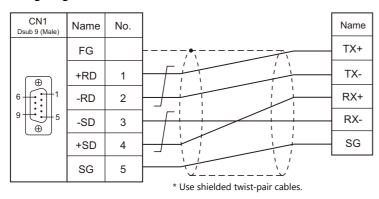
Wiring diagram 1 - C4



Wiring diagram 2 - C4



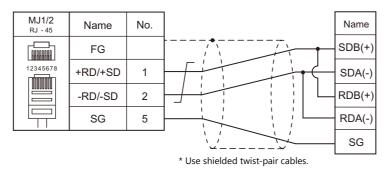
Wiring diagram 3 - C4



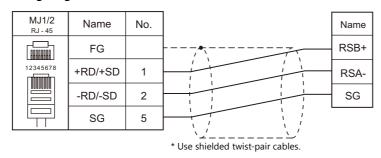
When Connected at MJ1/MJ2:

RS-422/RS-485

Wiring diagram 1 - M4



Wiring diagram 2 - M4



MEMO
Please use this page freely.

25. MODBUS

25.1 PLC Connection

25.1 PLC Connection

Serial Connection

The V9 series works as the Modbus RTU master station. It can be connected with devices that support Modbus RTU communication.

PLC Selection on the Editor	Applicable Device	Signal Level	Connection		
FLC Selection on the Editor	Applicable Device	Signal Level	CN1	MJ1/MJ2	
		RS-232C	Wiring diagram 1 - C2	Wiring diagram 1 - M2	
MODBUS RTU	Modbus RTU slave device	RS-422	Wiring diagram 1 - C4	×	
		RS-485	Wiring diagram 2 - C4	Wiring diagram 1 - M4	
		RS-232C	Wiring diagram 1 - C2	Wiring diagram 1 - M2	
MODBUS RTU EXT Format	Modbus RTU slave device	RS-422	Wiring diagram 1 - C4	×	
		RS-485	Wiring diagram 2 - C4	Wiring diagram 1 - M4	
		RS-232C	Wiring diagram 1 - C2	Wiring diagram 1 - M2	
MODBUS ASCII	MODBUS ASCII slave device	RS-422	Wiring diagram 1 - C4	×	
		RS-485	Wiring diagram 2 - C4	Wiring diagram 1 - M4	

Ethernet Connection

The V9 series works as the Modbus TCP/IP master station. It can be connected with devices that support Modbus TCP/IP slave communication.

PLC Selection on the Editor	Applicable Device	TCP/IP	UDP/IP	Port No.
MODBUS TCP/IP (Ethernet)	Modbus TCP/IP slave device			
MODBUS TCP/IP (Ethernet) Sub Station	Modbus TCP/IP slave device	0	×	502 *
MODBUS TCP/IP (Ethernet) EXT Format	Modbus TCP/IP slave device			

^{*} Depending on the device specification, an arbitrary port number can be specified.

25.1.1 MODBUS RTU

Communication Setting

Editor

Communication setting

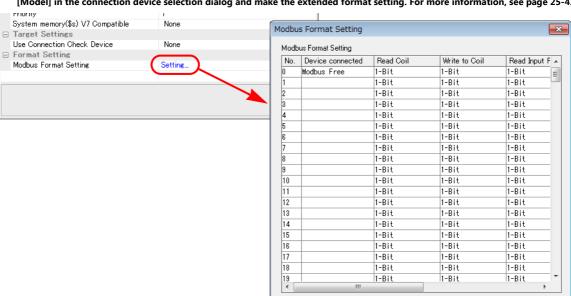
(Underlined setting: default)

Item	Setting	Remarks
$ \begin{array}{c} 1:1/\underline{1:n} \ / \ Multi-link2 \ / \\ \ \ \ \ \ \ \ \ \ \ \ \ $		
Signal Level	RS-232C / RS-422/485	
Baud Rate	4800 / <u>9600</u> / 19200 / 38400 / 57600 / 115K bps	
Data Length	8 bits	
Stop Bit	<u>1</u> / 2 bits	
Parity	None / <u>Odd</u> / Even	
Target Port No.	0 to 255	0: Broadcast

Modbus format setting

Make communication format settings for each connected device.

* If the maximum number of words to be read or written varies among the address ranges, select [MODBUS RTU EXT Format] for [Model] in the connection device selection dialog and make the extended format setting. For more information, see page 25-4.



No. 1 to 255	Port number of the connected device		
Read Coil	Format setting		
Write to Coil	Set the number of words to be read or written at one time of communication for each device. For details on		
Read Input Relay	the maximum value that can be set on V-SFT, see the table shown below.*1		
Read Holding Register	The format setting also serves as the function code ^{*1} setting used for Modbus communication. The		
Write Holding Register	available function codes vary depending on the device. Refer to the instruction manual of the connected device as well as the table shown below *1, and set the options on the dialog correctly.		
Read Input Register	device as well as the table shown below , and set the options on the dialog correctly.		

*1 Format setting on V-SFT and function code for the Modbus communication

	V-SFT Format Se	Modbus Communication		
Operat	ion	Maximum Setting	Function Code	
Read Coil		992 bits	01H	
Write to Coil	1 bit	1 word	05H	
Write to Coll	16 bits or more	992 bits	0FH	
Read Input Relay		992 bits	02H	
Read Holding Register		62 words	03H	
Write Holding	1 word	1 word	06H	
Register	2 words or more	62 words	10H	
Read Input Register		62 words	04H	

PLC

Make communication settings of the connected device according to the settings made for the V9 series. For more information on settings, refer to the instruction manual issued by the manufacturer.

Available Device Memory

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

	Device Memory		Remarks
0	(output coil)	00H	
1	(input relay)	01H	
4	(holding register)	02H	
3	(input register)	03H	

Notes on Creating Screen Programs

On the editor, the device memory address is specified in decimal notation. Thus, when the address of a connected device is expressed in hexadecimal notation, convert the address into decimal one and add "1".

Setting example

- When specifying the PV (current value) RAM address "3814H" for Modbus RTU connection with Yamatake's "SDC35":
 - 1) Convert the hexadecimal address into the decimal one. $3814 \text{HEX} \rightarrow 14356 \text{DEC}$
 - 2) Add "1" to the decimal address. 14356 + 1 = 14357DEC
 - 3) On the editor, specify "14357" for the holding register (4).

25.1.2 MODBUS RTU EXT Format

In the case with some Modbus RTU devices, the function code to be used or the maximum value to be read or written at one time varies depending on the address range even in the same device memory.

When [MODBUS RTU EXT Format] is selected, the address range as well as the communication format can be set as desired according to the specifications of the connected device. With [MODBUS RTU EXT Format] selected, since access will not be made to any address other than those specified in the format setting, communication can be performed effectively.

Communication Setting

Editor

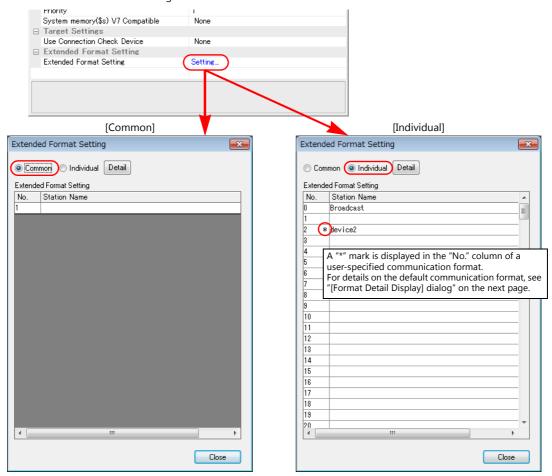
Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1 : 1 / <u>1 : n</u> / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet)	
Signal Level	RS-232C / <u>RS-422/485</u>	
Baud Rate	4800 / <u>9600</u> / 19200 / 38400 / 57600 / 115K bps	
Data Length	8 bits	
Stop Bit	1 / 2 bits	
Parity	None / <u>Odd</u> / Even	
Target Port No.	0 to 255	0: Broadcast

Extended format setting

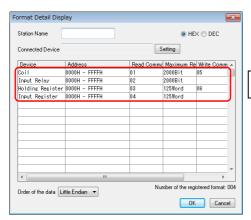
Make communication format settings for the connected device.



Common	Used to set the communication format commonly to all station numbers.		
Discrete	Used to set a communication format for respective station numbers.		
Detail	Displays the [Format Detail Display] dialog.		
No.	Displays the station number of the connected device.		
Station Name	Sets and displays the station name of the connected device.		

[Format Detail Display] dialog

Register the communication format for each of the specified address range. Make the setting according to the device specification.



Four types of communication formats shown to the left have been registered by default.

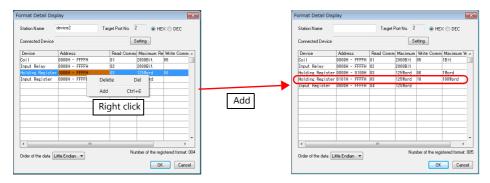
Station Name	Register a desired station name.			
Target Port No.	When [Discrete] is selected, the number of the selected station is automatically displayed.			
HEX/DEC	Select the address notation. HEX / DEC			
Device	Displays the currently registered device memory name. Coil / Input Relay / Holding Register / Input Register (default settings: one each, deletion impossible)			
Address	Specify the address range for each device memory. HEX: 0000 to FFFF DEC: 1 to 65536 * The address range must not be duplicated.			
Read Command	Set the communication format used for reading from or writing into the specified address range.			
Maximum Read Value	 [Read Command] / [Write Command] Specify the function code^{*1} to use for Modbus communication. The available function codes vary depending on the device. Refer to the instruction manual of the connect device as well as the table shown below^{*1}, and set the options on the dialog correctly. 			
Write Command				
Maximum Write Value	[Maximum Read Value] / [Maximum Write Value] Set the maximum value to be read or written at one time. Make the setting according to the device specification. For details on the maximum value that can be set for each device memory by using V-SFT, see the table shown below.*1			
Order of the data	Specify the ordering of data. Little Endian / Big Endian			
Number of the registered format	Displays the number of currently registered formats. Default: 4 (deletion impossible) Max.: 255			

*1 Device memory setting on V-SFT and function code for the Modbus communication

	Modbus Communication			
0	peration		Max. Read/Write Value	Function Code
	Read		2000 bits	01H
Coil	Write	1 bit	1 bit	05H
	vviite	2 bits or more	800 bits	0FH
Input Relay	Read		2000 bits	02H
	Read		125 words	03H
Holding Register	Write 1 word	1 word	1 word	06H
	2 words or more		100 words	10H
Input Register	out Register Read		125 words	04H

Adding a format

To add a format, select a device memory, right-click on the selected device memory and select [Add].



Setting example

When connecting a device which has the following specifications to station number 1:

Function Code	Operation	Max. Communication Points	Available Address		Example
01H	Read coil	4000	HEX: 0000 to 00FF	DEC: 1 to 256	(1)
OIH	Read COII	4000	HEX: 2EE0 to 4E1F	DEC: 12001 to 20000	(2)
05H	Write single coil	1	HEX: 0000 to 00FF	DEC: 1 to 256	(1)
0FH	Write multiple coils	1000	HEX: 2EE0 to 4E1F	DEC: 12001 to 20000	(2)
03H	Read holding register	200	HEX: 0000 to 103F	DEC: 1 to 8000	(3)
USH			HEX: 2EE0 to 2FDF	DEC: 12001 to 12256	(4)
06H	Write single holding register	1	HEX: 2EE0 to 2FDF	DEC: 12001 to 12256	(4)
10H	Write multiple holding registers	50	HEX: 0000 to 1F3F	DEC: 1 to 8000	(3)

• Read/write coil

(1) 0000 to 00FF (HEX)

- Register "01H" (function code for reading) to [Read Command] or "05H" (function code for writing) to [Write Command].
- The maximum number of communication points to be read is 4000. Accordingly, register "2000 bits" for [Maximum Read Value] on V-SFT.
- The maximum number of communication points to be written is 1. Accordingly, register "1 bit" for [Maximum Write Value] on V-SFT.

(2) 2EE0 to 4E1F (HEX)

- Register "01H" (function code for reading) to [Read Command] or "0FH" (function code for writing) to [Write Command].
- The maximum number of communication points to be read is 4000. Accordingly, register "2000 bits" for [Maximum Read Value] on V-SFT.
- The maximum number of communication points to be written is 1000. Accordingly, register "800 bits" for [Maximum Write Value] on V-SFT.

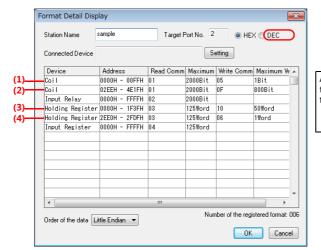
• Read/write holding register

(3) 0000 to 1F3F (HEX)

- Register "03H" (function code for reading) to [Read Command] or "10H" (function code for writing) to [Write Command].
- The maximum number of communication points to be read is 200. Accordingly, register "125 words" for [Maximum Read Value] on V-SFT.
- The maximum number of communication points to be written is 50. Accordingly, register "50 words" for [Maximum Write Value] on V-SFT.

(4) 2EE0 to 2FDF (HEX)

- Register "03H" (function code for reading) to [Read Command] or "06H" (function code for writing) to [Write Command].
- The maximum number of communication points to be read is 200. Accordingly, register "125 words" for [Maximum Read Value] on V-SFT.
- The maximum number of communication points to be written is 1. Accordingly, register "1 word" for [Maximum Write Value] on V-SFT.



Access will not be made to any addresses other than those not registered on the dialog shown on the left.

- Coil: 0100 to 2EDF, 4E20 to FFFF
- Holding register: 1040 to 2EDF, 2FE0 to FFFF

PLC

Make communication settings of the connected device according to the settings made for the V9 series. For more information on settings, refer to the instruction manual issued by the manufacturer.

Available Device Memory

The contents of "Available Device Memory" are the same as those described in "25.1.1 MODBUS RTU".

25.1.3 MODBUS ASCII

Communication Setting

Editor

Communication setting

(Underlined setting: default)

Item	Setting	Remarks
Connection Mode	1 : 1 / <u>1 : n</u> / Multi-link2 / Multi-link2 (Ethernet) / 1 : n Multi-link2 (Ethernet)	
Signal Level	RS-232C / <u>RS-422/485</u>	
Baud Rate	4800 / 9600 / 19200 / 38400 / 57600 / 115K bps	
Data Length	7 / <u>8</u> bits	
Stop Bit	<u>1</u> / 2 bits	
Parity	None / <u>Odd</u> / Even	
Target Port No.	0 to 255	0: Broadcast

Format setting

Make communication format settings for each connected device. (See page 25-2.)

PLC

Make communication settings of the connected device according to the settings made for the V9 series. For more information on settings, refer to the instruction manual issued by the manufacturer.

Available Device Memory

The contents of "Available Device Memory" are the same as those described in "25.1.1 MODBUS RTU".

25.1.4 MODBUS TCP/IP (Ethernet)

Communication Setting

Editor

Make the following settings on the editor. For more information, see "1.3.2 Ethernet Communication".

- IP address for the V9 unit
- Port number for the V9 unit at [Communication Setting] in the [PLC Properties] window ([Hardware Setting])
- PLC's IP address and port number for [PLC Table] under [Target Settings] in the [PLC Properties] window ([Hardware Setting])
- [Format Setting] in the [PLC Properties] window ([Hardware Setting])

Format setting

Make communication format settings for each connected device. (See page 25-2.)

* If the maximum number of words to be read or written varies among the address ranges, select [MODBUS TCP/IP (Ethernet) EXT Format] for [Series] in the [Connection Device Selection] dialog and make extended format settings. For more information, see page 25-10.

PLC

Make communication settings of the connected device according to the settings made for the V9 series. For more information on settings, refer to the instruction manual issued by the manufacturer.

Available Device Memory

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

	Device Memory		Remarks
0	(output coil)	00H	
1	(input relay)	01H	
4	(holding register)	02H	
3	(input register)	03H	

Notes on Creating Screen Program

On the editor, the device memory address is specified in decimal notation. Thus, when the address of a connected device is expressed in hexadecimal notation, convert the address into decimal one and add "1". (See page 25-3.)

25.1.5 MODBUS TCP/IP (Ethernet) EXT Format

In the case with some Modbus TCP/IP (Ethernet) devices, the function code to be used or the maximum value to be read or written at one time varies depending on the address range even in the same device memory.

When [MODBUS TCP/IP (Ethernet) EXT Format] is selected, the address range as well as the communication format can be set as desired according to the specifications of the connected device. With [MODBUS TCP/IP (Ethernet) EXT Format] selected, since access will not be made to any address other than those specified in the format setting, communication can be performed effectively.

Communication Setting

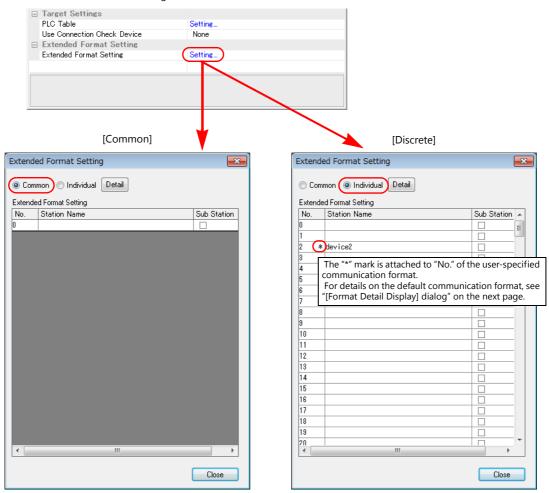
Editor

Make the following settings on the editor. For more information, see "1.3.2 Ethernet Communication".

- IP address for the V9 unit
- Port number for the V9 unit at [Communication Setting] in the [PLC Properties] window ([Hardware Setting])
- PLC's IP address and port number for [PLC Table] under [Target Settings] in the [PLC Properties] window ([Hardware Setting])
- [Extended Format Setting] in the [PLC Properties] window ([Hardware Setting])

Extended format setting

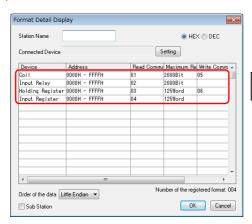
Make communication format settings for the connected device.



Common	Used to set the communication format commonly to all station numbers.		
Discrete	Used to set a communication format for respective station numbers.		
Detail	Displays the [Format Detail Display] dialog.		
No.	Displays the station number of the connected device.		
Station Name	Sets and displays the station name of the connected device.		
Sub Station	Check the box when Modbus TCP/IP communication is to be performed with a device requiring a unit ID specification. When this box is checked, the unit ID can be specified when setting the device memory address. (Without check: The unit ID is fixed to "FFH".)		

[Format Detail Display] dialog

Register the communication format for each of the specified address range. Make the setting according to the device specification.



Four types of communication formats shown to the left have been registered by default.

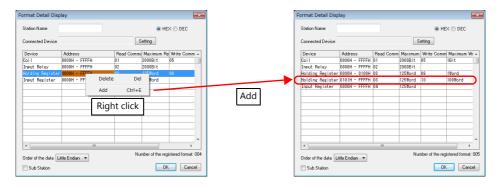
Station Name	Register a desired station name.			
Target Port No.	When [Discrete] is selected, the number of the selected station is automatically displayed.			
HEX/DEC	Select the address notation. HEX / DEC			
Device	Displays the currently registered device memory name. Coil / Input Relay / Holding Register / Input Register (default settings: one each, deletion impossible)			
Address	Specify the address range for each device memory. HEX: 0000 to FFFF DEC: 1 to 65536 * The address range must not be duplicated.			
Read Command	Set the communication format used for reading from or writing into the specified address range.			
Maximum Read Value	 [Read Command] / [Write Command] Specify the function code^{*1} to use for Modbus communication. The available function codes vary depending on the device. Refer to the instruction manual of the connect device as well as the table shown below^{*1}, and set the options on the dialog correctly. 			
Write Command	[Maximum Read Value] / [Maximum Write Value]			
Maximum Write Value	Set the maximum value to be read or written at one time. Make the setting according to the device specification. For details on the maximum value that can be set for each device memory by using V-SFT, see the table shown below.*1			
Order of the data	Specify the ordering of data. Little Endian / Big Endian			
☐ Sub Station	Check this box when using the sub station function.			
Number of the registered format	Displays the number of currently registered formats. Default: 4 (deletion impossible) Max.: 255			

*1 Device memory setting on V-SFT and function code for the Modbus communication

	Modbus Communication			
Operation			Max. Read/Write Value	Function Code
	Read		2000 bits	01H
Coil	Write	1 bit	1 bit	05H
	vviite	2 bits or more	800 bits	0FH
Input Relay	Read		2000 bits	02H
	Read		125 words	03H
Holding Register	Write 1	1 word	1 word	06H
	vvrite	2 words or more	100 words	10H
Input Register	Read		125 words	04H

Adding a format

To add a format, select a device memory, right-click on the selected device memory and select [Add].



Example

When connecting a device which has the following specifications to station number 1:

Function Code	Operation	Max. Communication Points	Availa	ble Address	Example
01H	Read coil	4000	HEX: 0000 to 00FF	DEC: 1 to 256	(1)
			HEX: 2EE0 to 4E1F	DEC: 12001 to 20000	(2)
05H	Write single coil	1	HEX: 0000 to 00FF	DEC: 1 to 256	(1)
0FH	Write multiple coils	1000	HEX: 2EE0 to 4E1F	DEC: 12001 to 20000	(2)
03H	Read holding register	200	HEX: 0000 to 103F	DEC: 1 to 8000	(3)
			HEX: 2EE0 to 2FDF	DEC: 12001 to 12256	(4)
06H	Write single holding register	1	HEX: 2EE0 to 2FDF	DEC: 12001 to 12256	(4)
10H	Write multiple holding registers	50	HEX: 0000 to 1F3F	DEC: 1 to 8000	(3)

• Read/write coil

(1) 0000 to 00FF (HEX)

- Register "01H" (function code for reading) to [Read Command] or "05H" (function code for writing) to [Write Command].
- The maximum number of communication points to be read is 4000. Accordingly, register "2000 bits" for [Maximum Read Value] on V-SFT.
- The maximum number of communication points to be written is 1. Accordingly, register "1 bit" for [Maximum Write Value] on V-SFT.

(2) 2EE0 to 4E1F (HEX)

- Register "01H" (function code for reading) to [Read Command] or "0FH" (function code for writing) to [Write Command].
- The maximum number of communication points to be read is 4000. Accordingly, register "2000 bits" for [Maximum Read Value] on V-SFT.
- The maximum number of communication points to be written is 1000. Accordingly, register "800 bits" for [Maximum Write Value] on V-SFT.

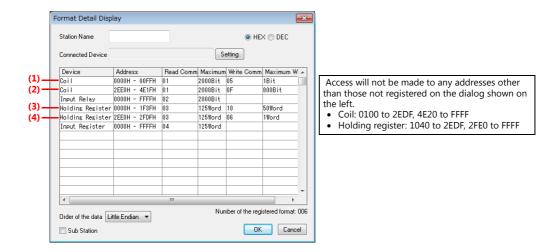
• Read/write holding register

(3) 0000 to 1F3F (HEX)

- Register "03H" (function code for reading) to [Read Command] or "10H" (function code for writing) to [Write Command].
- The maximum number of communication points to be read is 200. Accordingly, register "125 words" for [Maximum Read Value] on V-SFT.
- The maximum number of communication points to be written is 50. Accordingly, register "50 words" for [Maximum Write Value] on V-SFT.

(4) 2EE0 to 2FDF (HEX)

- Register "03H" (function code for reading) to [Read Command] or "06H" (function code for writing) to [Write Command].
- The maximum number of communication points to be read is 200. Accordingly, register "125 words" for [Maximum Read Value] on V-SFT.
- The maximum number of communication points to be written is 1. Accordingly, register "1 word" for [Maximum Write Value] on V-SFT.



PLC

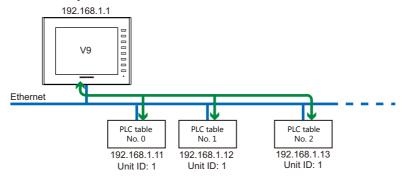
Make communication settings of the connected device according to the settings made for the V9 series. For more information on settings, refer to the instruction manual issued by the manufacturer.

Available Device Memory

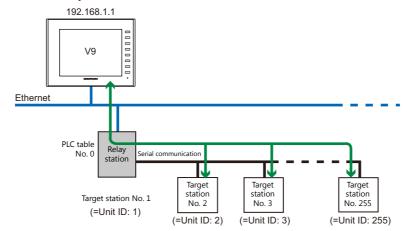
The contents of "Available Device Memory" are the same as those described in "25.1.4 MODBUS TCP/IP (Ethernet)".

25.1.6 MODBUS TCP/IP (Ethernet) Sub Station

- Modbus TCP/IP (Ethernet) communication with devices which require unit ID specifications
 - [Connection Mode]: "1: n"



- Serial communication with Modbus devices via relay station
 - [Connection Mode]: "1:1"



Communication Setting

Editor

Make the following settings on the editor. For more information, see "1.3.2 Ethernet Communication".

- IP address for the V9 unit
- Port number for the V9 unit at [Communication Setting] in the [PLC Properties] window ([Hardware Setting])
- PLC's IP address and port number for [PLC Table] under [Target Settings] in the [PLC Properties] window ([Hardware Setting])
- [Format Setting] in the [PLC Properties] window ([Hardware Setting])

Modbus format setting

Make communication format settings for each connected device. (See page 25-2.)

PLC

Make communication settings of the connected device according to the settings made for the V8 series. For more information on settings, refer to the instruction manual issued by the manufacturer.

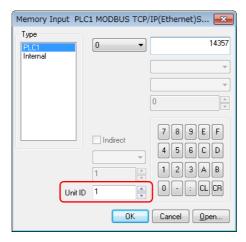
Available Device Memory

The available setting range of device memory varies depending on the PLC model. Be sure to set within the range available for the PLC to be used. Use [TYPE] when assigning indirect device memory for macro programs.

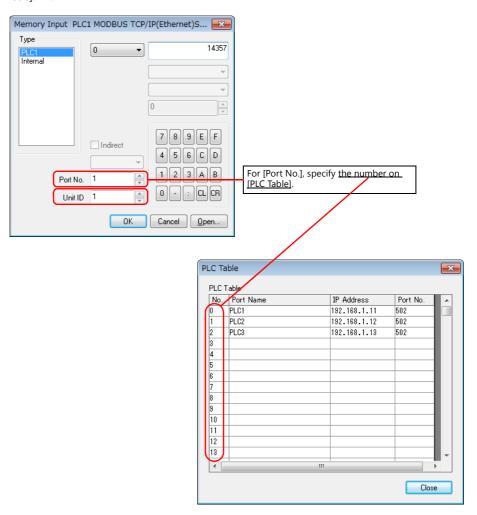
Device Memory		TYPE	Remarks
0	(output coil)	00H	
1	(input relay)	01H	
4	(holding register)	02H	
3	(input register)	03H	

Notes on Creating Screen Programs

- On the editor, the device memory address is specified in decimal notation. Thus, when the address of a connected device is expressed in hexadecimal notation, convert the address into decimal one and add "1". (See page 25-3.)
- Set the unit ID when specifying the device memory address.
 - [Connection Mode]: "1:1"



- [Connection Mode]: "1: n"

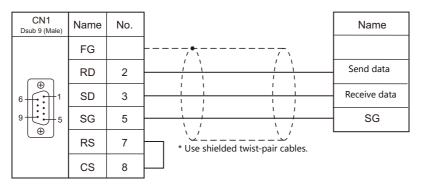


25.1.7 Wiring Diagrams

When Connected at CN1:

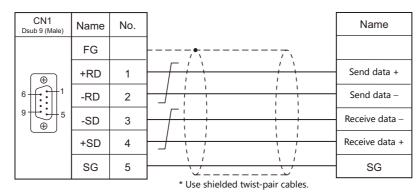
RS-232C

Wiring diagram 1 - C2

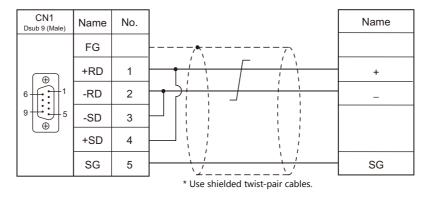


RS-422/RS-485

Wiring diagram 1 - C4



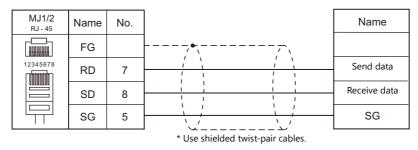
Wiring diagram 2 - C4



When Connected at MJ1/MJ2:

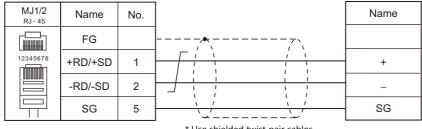
RS-232C

Wiring diagram 1 - M2



RS-422/RS-485

Wiring diagram 1 - M4



* Use shielded twist-pair cables.

MEMO
Please use this page freely.

26. Barcode Reader

26.1 Barcode Reader Connection

26.1 Barcode Reader Connection

Barcode readers can be connected to the serial port or USB-A port at the V9 series. The controller models shown below can be connected.

Serial Connection

Manufacturer	Model Signal Lovel	anufacturer Model Signal Level Connection		ection
Manufacturer	Model	Signal Level	CN1	MJ1/MJ2
Tohken	THIR-6000 THIR-3000N-RF TFIR3102 THLS-6800 TLMS-3500RV THLS6912			
OMRON	V500-R521b V520-RH series		Wiring diagram 1 - C2 Wiring o	
KEYENCE	BL-210R BL-600 series BL-N60R BL-80R	RS-232C		Wiring diagram 1 - M2
Cognex	In-Sight 5100 In-Sight 5400			
Nichiei Intec	FFTA10ARS			
Unitech	MS210-1			
SICK	LD9000E			
OLYMPUS-symbol	LSH3502			
symbol	LS2104			
WelchAllyn	IT3800			

Match communication settings of the barcode reader to those made on the V9 series. For more information on settings, refer to the specifications issued by the manufacturer.

USB Connection

Use a barcode reader which is compatible with USB-HID.

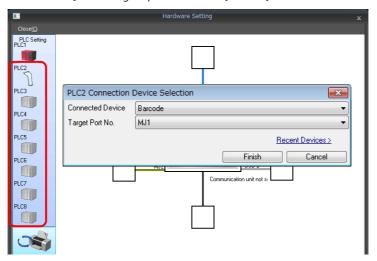
Manufacturer	Model	Remarks
Tohken	THLS-6922USB THLS-6800 THIR-6000U	HID mode
KEYENCE	BL-N60UB	
Cognex	Dataman710	
DENSO	AT10Q-SM	USB keyboard interface
AIMEX	BW-880UB	

26.1.1 Communication Setting

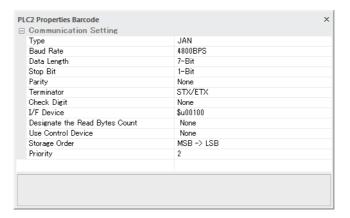
Editor

Device selection

Select [Barcode] at [Connected Device] for the logical ports PLC2 to 8. [Barcode] cannot be selected for PLC1.



Communication setting



(Underlined setting: default)

Item	Setting	Remarks	
Туре	JAN/ITF/CODABAR/CODE39/ANY/CODE128*1		
Baud Rate	4800/9600/19200 bps		
Data Length	<u>7</u> / 8 bits		
Stop Bit	<u>1</u> / 2 bits	Valid for serial connection	
Parity	None / Odd / Even		
Terminator	STX/ETX/CR/LF/CR		
Check Digit	None / Do Not Delete / Delete		
I/F Device	Refer to "26.1.2 I/F Device Memory" (page 26-3).		
Designate the Read Bytes Count	Neier to 20.1.21/1 Device Memory (page 20-3).		
Use Control Device	Refer to "26.1.3 Control Device Memory" (page 26-4).		
Use Start/End Code	 Yes Data is saved with "*" attached. None Data is saved without "*". 	Enabled when [CODABAR] or [CODE39] is selected for [Type].	
Storage Order	LSB→MSB/MSB→LSB	Data is stored into the I/F device in order according to the setting specified here.	

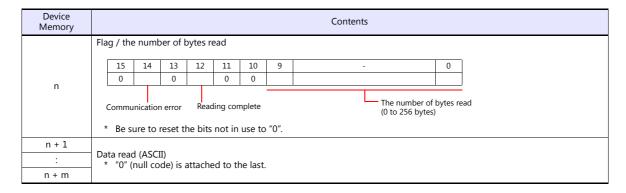
^{*1} When [CODE128] is selected, 128 characters of ASCII code (numbers, alphabet, symbols, control characters) can be used; however, control characters cannot be read on a USB barcode reader. When using control characters, connect the barcode reader via serial connection.

26.1.2 I/F Device Memory

I/F device memory stores barcode information. The number of words used varies depending on the setting.

I/F Device Memory

Type: JAN / ITF / CORDABAR / CODE39



Type: ANY

Device Memory	Contents			
	Flag			
	15 14 13 12 11 10 9 - 0			
n	0 0 0 0 0 - 0			
	Communication error Reading complete * Be sure to reset the bits not in use to "0".			
n + 1	The number of bytes read (0 to 2048 bytes)			
n + 2				
:	Data read (ASCII) * "0" (null code) is attached to the last.			
n + m	o (num code) is acadered to the last.			

Details of flag

Communication error	When an error occurs in communication between the barcode reader and the V9 series, "1" is set. Check the communication settings and wiring.
Reading complete	When data received from the barcode reader has been written into the I/F device memory, "1" is set. When this bit is set, reset it to "0" before reading the next data.
The number of bytes read	Stores the number of bytes read from the barcode reader.

Read Bytes Setting

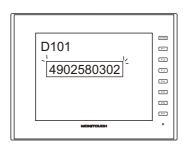
The number of bytes that can be read is determined according to the settings at [Type] and [Read Bytes Setting].

Туре	Read Bytes Setting	Allowable Number of Bytes
JAN ITF	Not specified	Variable according to the code to be read Max. 254 bytes
CORDERBAR CODE39 CODE128	Specified	Fixed to the specified number of words (2 to 254 bytes)
ANY	Not specified	Variable according to the code to be read Max. 2046 bytes
AINT	Specified	Fixed to the specified number of words (2 to 2046 bytes)

• Example

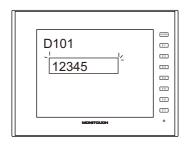
I/F Device Memory:D100Read Bytes Setting:SpecifiedBytes:10 bytesText Process:LSB \rightarrow MSB

- If data greater than 10 bytes ("4902580302474") is read: 10 bytes of data are stored and the remaining data is discarded.



I/F Device Memory	Value		
D100	Flag Number of read data		
D101	3934HEX	•]
D102	3230HEX	Ī	
D103	3835HEX	Ī	10 bytes
D104	3330HEX	Ī	
D105	3230HEX		
D106	Not used	_	•

- If data of 10 bytes or smaller ("12345") is read: "HEX 0" is assigned to the address where no data is stored.

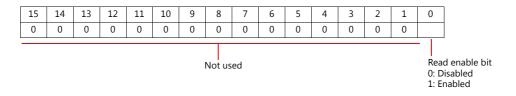


I/F Device Memory	Value		
D100	Flag Number of read data		
D101	3231HEX	Ī	
D102	3433HEX	Ī	
D103	0035HEX	Ī	10 bytes
D104	0000HEX	Ī	
D105	0000HEX	_	
D106	Not used		

26.1.3 Control Device Memory

Reading operation of the barcode reader can be controlled by using read enable bit of the control device memory.

Control Device Memory



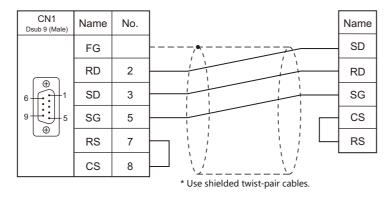
- Bit 0: Read enable bit Data is stored into I/F device memory when bit 0 is set.
- * A bit array of the PLC control device memory may be different from the one shown above depending on the PLC model. Set the bit according to the PLC specification.

26.1.4 Wiring Diagrams

When Connected at CN1:

RS-232C

Wiring diagram 1 - C2



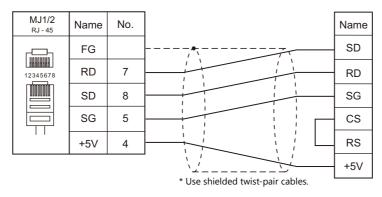
When Connected at MJ1/MJ2:



- For barcode readers with CS/RS control, it may be necessary to install a jumper between the CS and RS to maintain proper operation.
- Allowable current for the external power supply +5V at MJ1/MJ2 is 150 mA in total. There are restrictions
 on the total current value when an extension unit, communication unit or USB device is used. For details,
 refer to the V9 Series Hardware Specifications manual.

RS-232C

Wiring diagram 1 - M2



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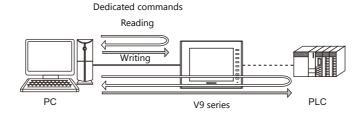
27. Slave Communication Function

- 27.1 V-Link
- 27.2 Modbus RTU Slave Communication
- 27.3 Modbus TCP/IP Slave Communication

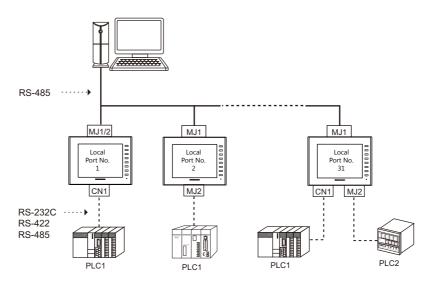
27.1 V-Link

27.1.1 Overview

• "V-Link" is the network where the computer reads from and writes to the internal device memory of the V9 series, memory card device memory, or PLC1 to 8 device memory using a dedicated protocol.



- Use CN1, MJ1 or MJ2 for connection with a general-purpose computer.
- Data of the connected devices can be collected through communications with the V9 series. Data collection is available even between devices of different manufacturers.
- Either signal level RS-232C or RS-485 can be selected.
 With RS-232C, one V9 series unit can be connected; with RS-485, a maximum of 31 V9 series units can be connected.
 - RS-485 connection

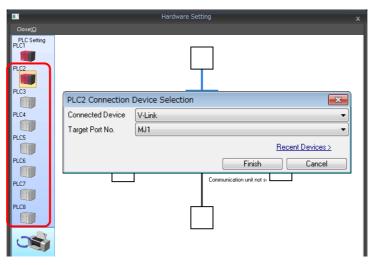


27.1.2 Communication Setting

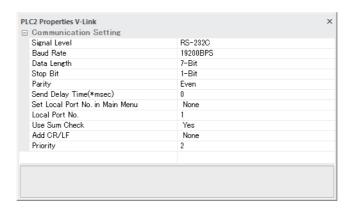
Editor

Device selection

Select [V-Link] at [Connected Device] for the logical ports PLC2 to 8. [V-Link] cannot be selected for PLC1.



Communication setting



(Underlined setting: default)

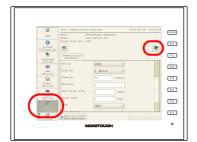
Item	Setting
Signal Level	<u>RS-232C</u> / RS-485
Baud Rate	4800 / 9600 / <u>19200</u> / 38400 / 57600 / 115 Kbps
Data Length	7 / 8 bits
Stop Bit	1/2 bits
Parity	None / Odd / Even
Send Delay Time	<u>0</u> to 255 msec
Local Port No.	1 to 254 (Maximum connectable units: 31)
Use Sum Check	Yes / None
Add CR/LF	Yes / None

MONITOUCH

Local port setting (Local mode)

The local port can be set on the V9 series unit in Local mode.

- 1. Transfer the screen program.
- 2. Switch to Local mode on MONITOUCH.
- 3. Press [Communication Setting] to display the Communication Setting screen, and then select the communication setting for "V-Link".







4. Configure [Local Port No.] and press the [Apply] switch.

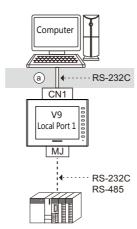


27.1.3 Wiring Diagrams

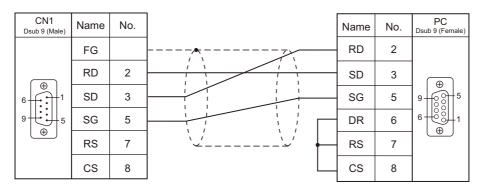
When Connected at CN1:

RS-232C

Connect the CN1 port at the V9 to the computer via RS-232C.

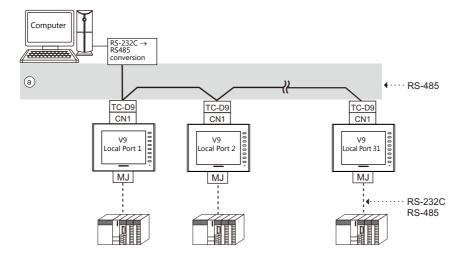


• Wiring example of above (a)

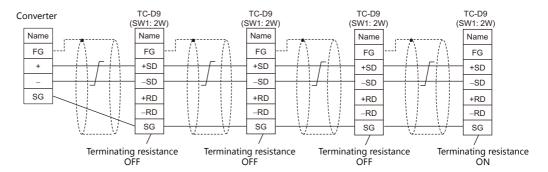


RS-485

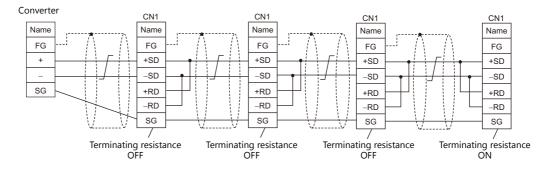
Connect the CN1 port at the V9 to the computer via RS-485. A maximum of 31 units of the V9 series can be connected.



- Wiring example of above (a)
 - When a TC-D9 is used:

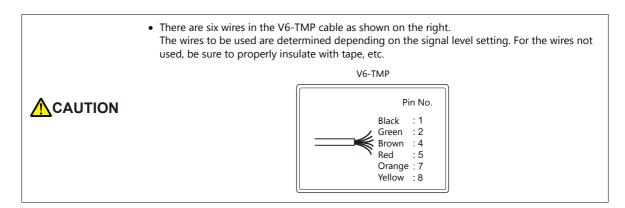


- When no TC-D9 is used

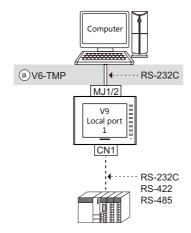


When Connected at MJ1/MJ2:

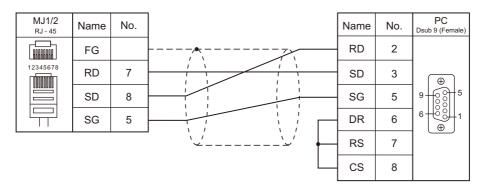
Use Hakko Electronics' cable "V6-TMP" (3, 5, or 10 m) for connection with a computer.



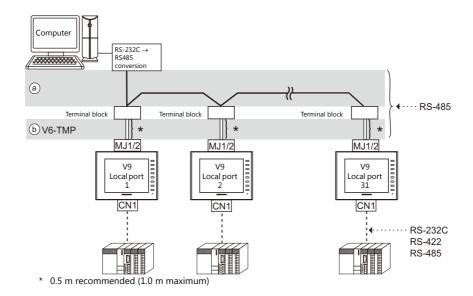
RS-232C



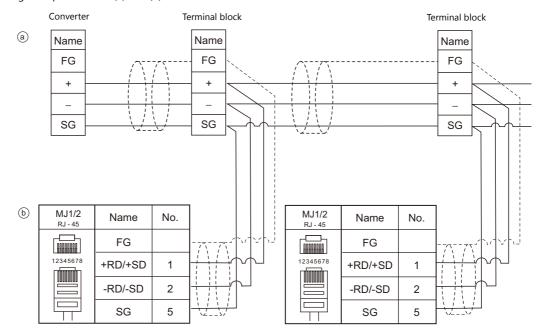
• Wiring example of above (a)



RS-485 (V9 Series: Max. 31 Units)

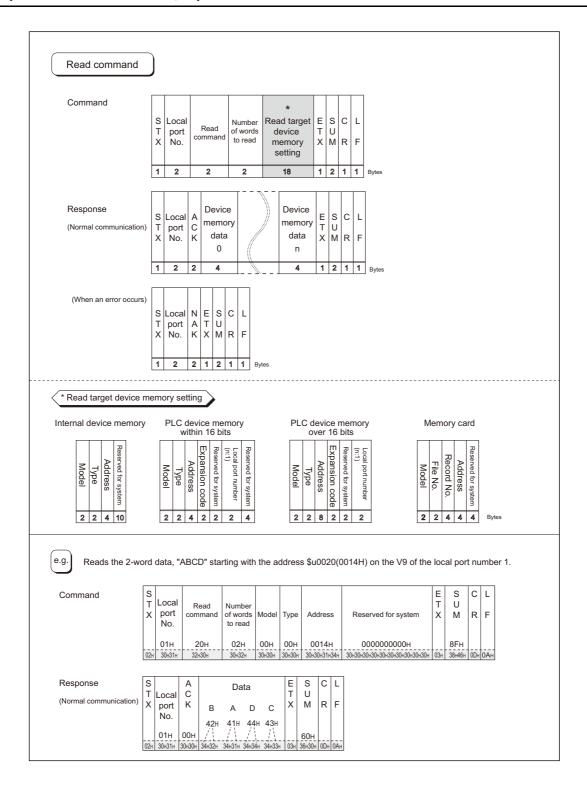


• Wiring example of above (a) and (b)

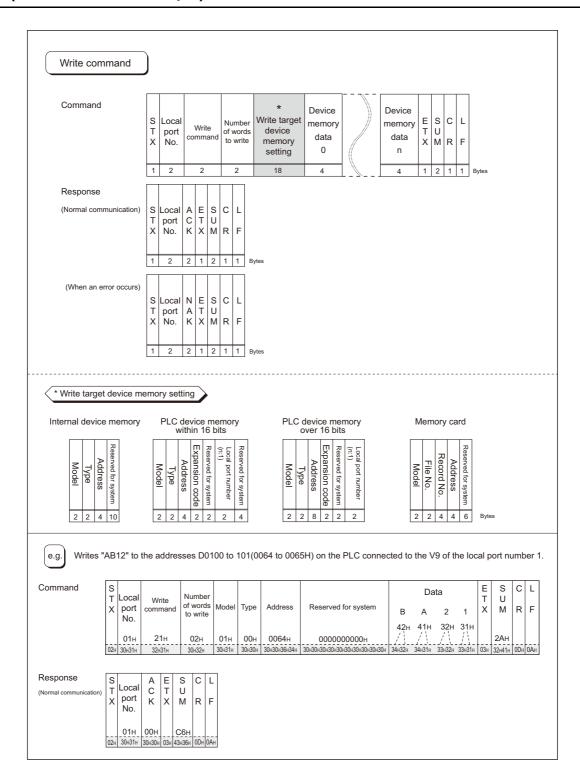


27.1.4 Protocol

Read (with Sum Check and CR/LF)



Write (with Sum Check and CR/LF)





Items for Protocols

Transmission control code: 1 byte

Signal Name	Code (Hexadecimal)	Content
STX	02H	Start of transmission block
ETX	03H	End of transmission block
CR	0DH	Carriage return
LF	0AH	Line feed

Local port number: 2 bytes

Local port numbers are used so that the host computer can identify each V9 series for access. The data range is from 01H to 1FH (1 to 31) and is converted into the ASCII code before use. Set the V9 series' local port number for [Local Port No.] on the editor. See page 27-2.

Command: 2 bytes

Available commands are shown below.

Name	Code (Hexadecimal)	ASCII	Content
Read	20H	32 30	Read from device memory
Write	21H	32 31	Write to device memory

The number of words to be read or written: 2 bytes

Set the number of words to be read or written by one command.

The data range is from 01H to FFH (1 to 255) and is converted into the ASCII code before use.

Device Memory address to be read or written: 18 bytes

Specify the device memory address to be accessed.

Set the following code in the format as shown for "Read target device memory setting" on page 27-8 and "Write target device memory setting" on page 27-9.

Model

	Word A	Address	Double-word Address		
Device Memory	Code (Hexadecimal) ASCII		Code (Hexadecimal)	ASCII	
Internal device memory	00H	3030	80H	3830	
PLC1 device memory	11H	3131	91H	3931	
PLC2 device memory	12H	3132	92H	3932	
PLC3 device memory	13H	3133	93H	3933	
PLC4 device memory	14H	3134	94H	3934	
PLC5 device memory	15H	3135	95H	3935	
PLC6 device memory	16H	3136	96H	3936	
PLC7 device memory	17H	3137	97H	3937	
PLC8 device memory	18H	3138	98H	3938	
Memory card	02H	3032		-	

Type

	Туре	Code (Hexadecimal)	ASCII
	\$u (user device memory)	00H	3030
	\$s (system device memory)	01H	3031
Internal device memory	\$L (non-volatile word device memory)	02H	3032
Internal device memory	\$LD (non-volatile double-word device memory)	03H	3033
	\$T (temporary user device memory)	04H	3034
	\$P (device memory for 8-way communication)	05H	3035
PLC1-to-8 device memory Depends on the PLC to be used. Set [TYPE No.] of the device memory used for ea device memory.			

Address
 Specify the device memory address to be accessed.

• Expansion code

When accessing to the device memory shown below, set the expansion code in addition to the type and address.

Model	Expansion Code
\$P	PLC 1 to 8
Fuji Electric PLC	File No. of the MICREX-F series, CPU No. of MICREX-SX series
JTEKT PLC	PRG No.
MITSUBISHI ELECTRIC PLC	Unit No. of SPU device memory
OMRON PLC	Bank No.
SHARP PLC	File No. of Fn device memory
Yokogawa Electric PLC	CPU No.

^{*} If there is no need to set the expansion code, set "00" (= 3030 in the ASCII code).

Set the port number used for 1: n connection (multi-drop)

For 1:1 connection or n:1 connection (multi-link), the port number setting is not used. Alternatively, set "00" (= 3030 in the ASCII code).

• File number

Specify the file number set in the [Memory Card Setting] dialog of the V-SFT editor.

Specify the record number set in the [Memory Card Setting] dialog of the V-SFT editor.

• System reserved

Enter "0" (= 30 in the ASCII code) for the number of bytes.

10

The number of bytes for "system reserved" varies depending on the model. Example:

Model Bytes Code (Hexadecimal) ASCII V9 internal device

000000000H

Sum Check Code (SUM): 2 Bytes

memory

Data is added up (SUM), and the lower one byte (8 bits) of the sum is converted into a two-digit ASCII code (hexadecimal). A sum check code is shown below.

30303030303030303030

Example: Transmission mode: without CR/LF, with sum check

Command: 20 (data read)

Address: 10 words from \$u1000 (03E8H)

When reading, a sum check will be performed as shown below.

STX	Port No.	Command	Read words	Device model	Device type	Address	System reserved	ETX	SUM
	01H	20H	0AH	00H	00H	03E8H	0 0 0 0 0 0 0 0 0 H		В9Н
02H	30H31H	32H30H	30H41H	30H30H	30H30H	30H 33H 45H 38H	30H 30H 30H 30H 30H 30H 30H 30H 30H	03H	42H39H
									1
1									
02H	+ 30H +	31H + 32	H + 30H +	30H + 41H +	30H + 30H	+ 30H + 30H + 3	30H + 33H + 45H + 38H		
	+ 30H + 03H = 4B9H								
	T I								

Response Code: 2 Bytes

"ACK" code is received at normal termination, and "NAK" code at abnormal termination. The following table shows the details of each code

C	ode	Contents				
ACK	00H	Normal termination				
	02H	Overrun/Framing error An overrun or framing error is detected in the received data. Send the command again.				
	03H	Parity error A parity error is detected in the received data. Send the command again.				
	04H	Sum check error A sum error occurs with the received data.				
	06H	Count error The device memory read/write count is "0".				
NAK	0FH	ETX error No ETX code is found.				
	11H	Character error A character not used in the received data is found (other than 0 to F). Check the character and send the command again.				
	12H	Command error An invalid command is given.				
	13H	Device Memory setting error The address or device memory number is invalid.				

27.1.5 1-byte Character Code List

Upper

	0	1	2	3	4	5	6	7	8	9	Α	В	С	D	Е	F
0			SP	0	@	Р	,	р								
1			!	1	Α	Q	а	q								
2			"	2	В	R	b	r								
3			#	3	С	S	С	s								
4			\$	4	D	Т	d	t								
5			%	5	Е	U	Φ	u								
6			&	6	F	٧	f	٧								
7			,	7	G	W	g	W								
8			(8	Н	Х	h	х								
9)	9	I	Υ	i	у								
Α			*		J	Z	j	z								
В			+	;	K	[k	{								
С			,	<	L	¥	I	1								
D			_	=	М]	m	}								
E				>	N	۸	n	~								
F			/	?	0	_	0									

Lower

27.2 Modbus RTU Slave Communication

For details on Modbus RTU slave communication, refer to the Modbus Slave Communication Specifications manual provided separately.

27.3 Modbus TCP/IP Slave Communication

For details on Modbus TCP/IP slave communication, refer to the Modbus Slave Communication Specifications manual provided separately.

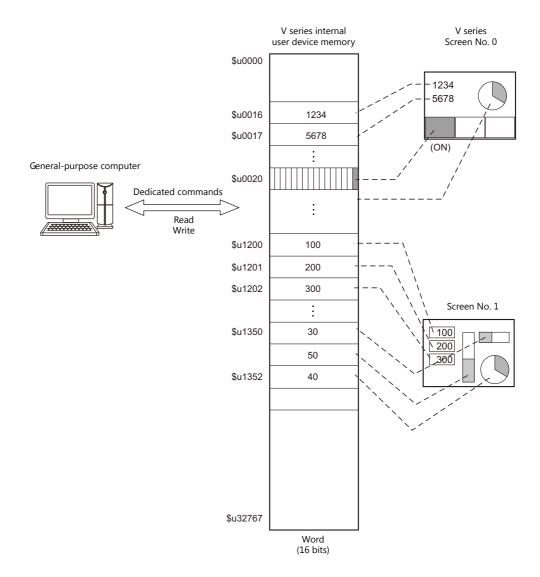
28. Universal Serial Communication

- 28.1 Overview
- 28.2 Wiring Diagrams
- 28.3 Hardware Settings
- 28.4 Standard Type Protocol
- 28.5 Device Memory Map

28.1 Overview

Overview of Communication

- As shown in the diagram below, when a general-purpose computer communicates with the V series, the general-purpose computer acts as the host and the V series acts as the slave.
- Switch, lamp, data display, etc., are allocated within the internal user device memory (\$u0 to 32767). Assign device memory addresses for system, lamp, data display, and mode within this range.
- When a screen number is specified from the host, a write action takes place to the internal device memory address specified for the screen. When a screen is changed internally by a switch, etc., the changed screen number is read, and written in the internal device memory address specified for the screen.



Differences between Connecting to General-purpose Computer and Connecting to PLC

Input format (code)
 The input format used for screen number, block number, message number, etc, is fixed in [DEC].

· Write area

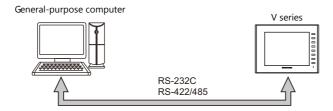
When connecting to the PLC, only the three words shaded in the diagram below are used, but when connecting to a general-purpose computer, all 16 words shown below are used.

Address	Name	Contents
n + 0	CFMDAT	Sub command/data
n + 1	SCRN_COM	Screen status
n + 2	SCRN_No	Displayed screen
n + 3	SW0	No. 0 switch data
n + 4	SW1	No. 1 switch data
n + 5	ENT0	Entry information 0
n + 6	ENT1	Entry information 1
n + 7	ENT2	Entry information 2
n + 8	GREPNS	Global response
n + 9		
•		Reserved (7 words)
n + 15		

System Configuration

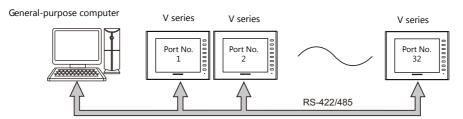
1:1 connection

- The transmission distance available via RS-232C is 15 m and RS-422/485 is 500 m at the maximum.
- It is possible to use an interrupt* when connecting a computer to a V series in a 1:1 connection.
 - * For RS-485 (2-wire connection), interrupts cannot be used. For details on interrupts, see page 28-32.



1: n connection

- 1: n connection is available via RS-422/485. A maximum of 32 V series units can be connected.
- The transmission distance available is 500 m at the maximum.
- For 1: n connection, interrupts cannot be used.

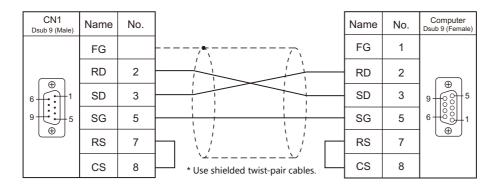


28.2 Wiring Diagrams

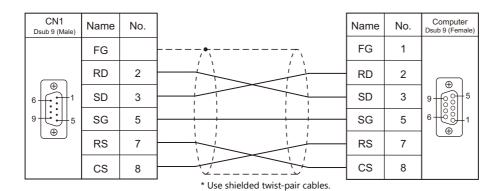
When Connected at CN1:

RS-232C

Without flow control

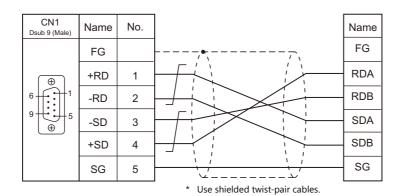


With flow control



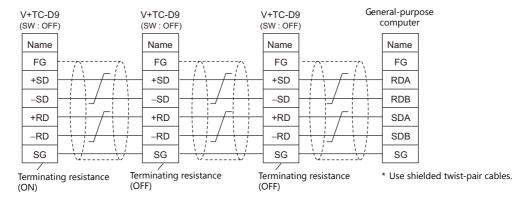
RS-422

1:1 connection



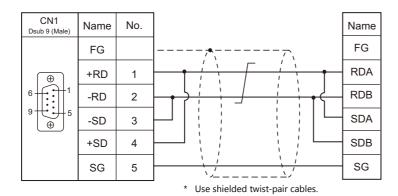
1: n connection

* It is convenient to use the optional terminal converter "TC-D9".



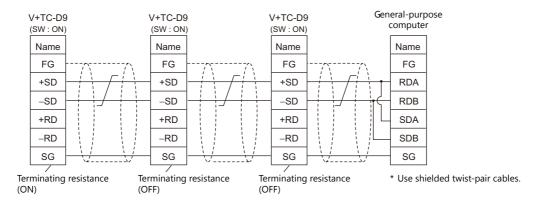
RS-485

1:1 connection

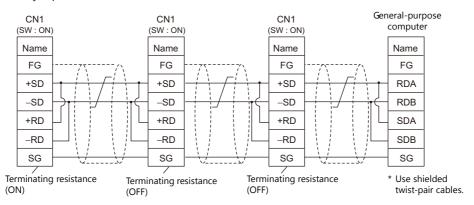


1: n connection

• With TC-D9

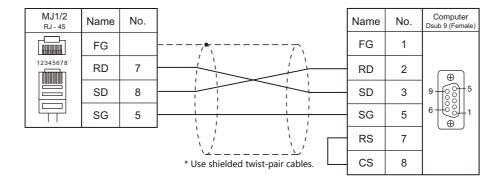


Without TC-D9
 Install jumpers between +RD/+SD and -RD/-SD.



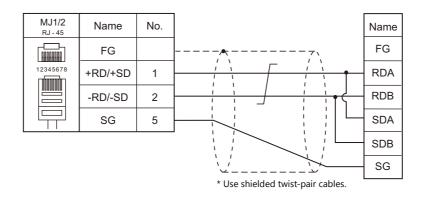
When Connected at MJ1/MJ2:

RS-232C

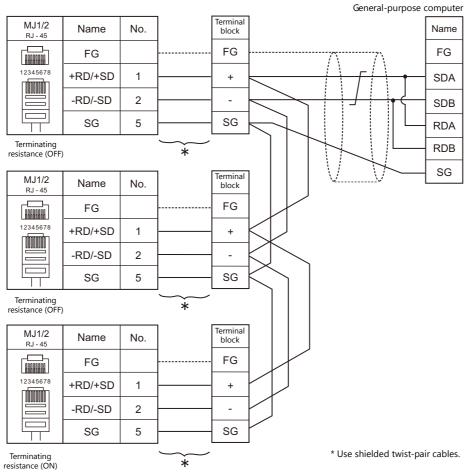


RS-485

1:1 connection



1: n connection

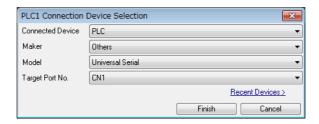


0.5 m recommended (1.0 m maximum)

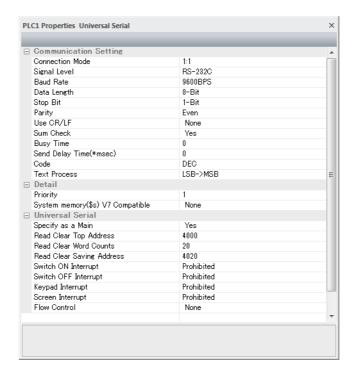
28.3 Hardware Settings

PLC Settings

Connecting Device Selection



PLC Properties

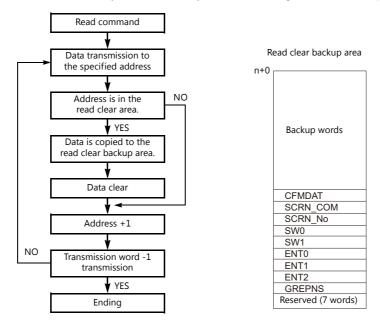


	Item	Contents				
	Connection Mode	Set the connection method for the V series and host. 1:1 Select when connecting one V series unit to one host. 1:n Select when connecting multiple V series units to one host.				
	Signal Level	Set the signal level used for communication between the host and the V series. RS-232C/RS-422/485				
	Baud Rate	Set the communication speed between the host and the V series. 4800/9600/19200/38400/57600/76800/115K bps				
	Data Length	8 bits (fixed)				
Communication	Stop Bit	Select a stop bit. 1 bit / 2 bits				
Setting	Parity	Select an option for parity bit. None / Odd / Even				
	Local Port No.	This option is valid when 1: n connection is used. Set the port number of the V series.				
	Use CR/LF	Set whether or not to use a CR/LF code at the end of transmission data.				
	Sum Check	Set whether or not to add a sum check code at the end of transmission data.				
	Busy Time	Refer to page 28-24.				
	Send Delay Time	Set the time for V series to send a response to a host after receiving a command from a host.				
	Code	DEC (fixed)				

	Item	Contents					
		When using text process, choose either [LSB \rightarrow MSB] or [MSB \rightarrow LSB] in order to make arrangements for the order of the first and the second bytes in one word.					
Communication Setting	Text Process	[LSB \rightarrow MSB] 15 0 MSB LSB 2nd byte 1st byte					
		[MSB \rightarrow LSB] 15 0 MSB LSB 1st byte 2nd byte					
	Specify as a Main	Specify which connection to use as the main connection when multiple universal serial connections are made at PLCs 1 to 8. This is set to [Yes] when there is only one universal serial connection. * When [None] is selected, the following limitations apply. • The following interruption communications occur simultaneously when the connection specified as the main interrupts. - Interruption function of a switch - Interruption function of a "Write" switch on the keypad or on the keyboard - Interruption function of screen internal switching • Responses to commands for global stations cannot be output. • The read clear functions are not available. • \$s111 cannot be used. The contents of the connection specified as the main are displayed.					
	Read Clear Top Address ^{*2}	This setting is available when [Specify as a Main] is set to [Yes]. Set the top address number of the read clear area. The read clear area is the starting area from which the V series clears data that wa previously read. Due to the fact that it is cleared to "0", once this area is read, the d remains at "0" even if you attempt to read again when a read response error occur					
	Read Clear Word Counts*2	This setting is available when [Specify as a Main] is set to [Yes]. Set the number of words that will be used for clearing the read area.					
Universal Serial	Read Clear Saving Address*2	This setting is available when [Specify as a Main] is set to [Yes]. Set the top address for the read clear backup area. The area size will be the same as the previously described read clear area. The number of words written in the read clear backup area is the same as the number specified for the read clear area.					
	Switch ON Interrupt*1	Select whether or not to enable or disable an interrupt when the switch changes from OFF to ON.					
	Switch OFF Interrupt*1	Select whether or not to enable or disable an interrupt when the switch changes from ON to OFF.					
	Keypad Interrupt*1	Select whether or not to enable or disable an interrupt when the "Write" switch on t keypad or on the keyboard is pressed and it changes from OFF to ON.					
	Screen Interrupt*1	Select whether or not to enable or disable an interrupt when the screen change switch is pressed.					
	Flow Control	This option is valid only for 1:1 communication via RS-232C using CN1. Select [Yes] when disabling an interrupt from the V series (e.g. when the host cannot receive interrupt data). This following actions take place. Interrupt enabled when CS (pin 8) on the V series side is ON Interrupt disabled when CS (pin 8) on the V series side is OFF When CS is ON, interruption information stored by then is output in succession. (Interruption information for 3 times can be stored at the most.)					
	Output OFF	This option is valid only for 1:1 communication via RS-422 using 4-wire connection. Normally, V series uses the same cables to send or receive data regardless of 4-wire of 2-wire connections. For this reason, send output remains OFF (High impedance) except for sending signals from V series. However, depending on the host specifications, send output OFF operation from the V series is not required. In this case, specify [None].					
	2-Wire System	Select [Yes] for 1 : 1 communication via RS-422/485 using 2-wire connection. Interruptions are disabled.					

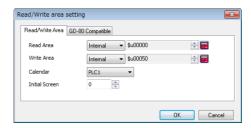
^{*1} Interruption settings can be changed from the host using the [WI] command during communication. For details on interruption, refer to "28.4.4 Interrupt (ENQ)".

*2 Read clear and read clear backup action
The action that occurs when a read command from the host tries to access to the read clear area is shown in the following diagram.
Backup data of the write area in the system device memory is allocated following the read clear backup area.



Control Device Memory

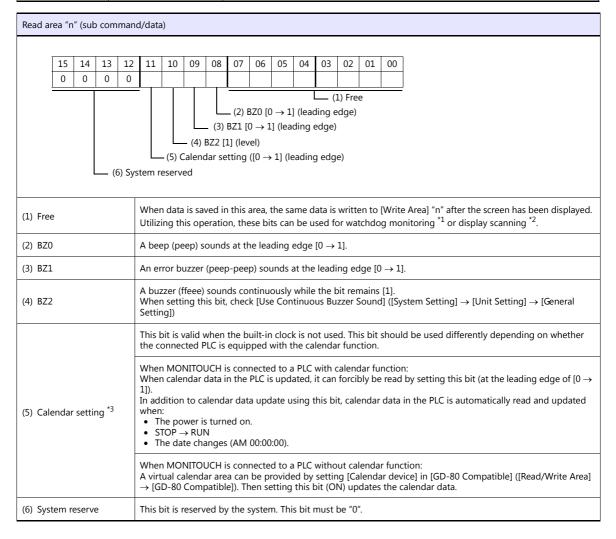
Read/Write Area



Read Area

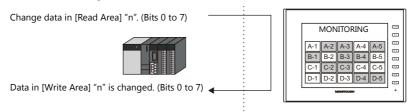
This device memory area is necessary to change the screen display status by giving a command from the host. Be sure to set the \$u device memory. Address allocation is shown in the table below. For more information, see "1.4.2 MONITOUCH Settings" (page 1-46).

Address	Name	Contents
n + 0	RCVDAT	Sub command/data
n + 1	SCRN_COM	Screen status command
n + 2	SCRN_No	External screen command



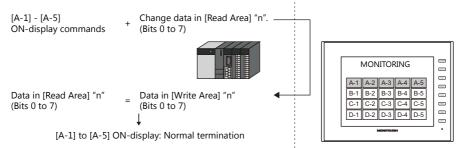
Watchdog
When the PLC is communicating with MONITOUCH, there is no means for the PLC to know whether or not MONITOUCH is doing operations correctly.

To solve this one-way communication, forcibly change data in bits 0 to 7 in [Read Area] "n" and check that the same data is saved in bits 0 to 7 in [Write Area] "n". This proves that the V series is correctly doing operations through communications with the PLC. This verification is called "watchdog".

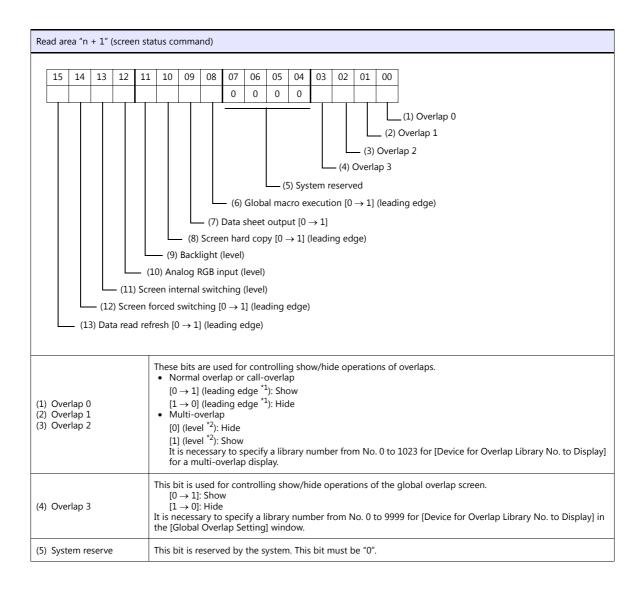


Display scanning

This operation can be utilized for display scanning. Change data in bits 0 to 7 in [Read Area] "n" when giving a graphic change command and check that the same data is saved in bits 0 to 7 in [Write Area] "n". This can prove that the graphic change command is received and executed correctly.



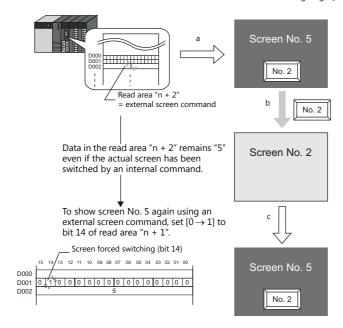
*3 If this bit is used during constant sampling, data sampling timing may be shifted. If this bit is set during constant sampling, we recommend you to reset the sampling as well.



(6) Global macro execution	The macro set for [Macro Block] is executed once at $[0 \to 1]$ (leading edge). The macro block number should be specified for [Global Macro Device] in the window that is displayed by selecting [System Setting] \to [Macro Setting]. For more information, refer to the Macro Reference manual provided separately.
(7) Data sheet output	The data sheet is printed out at $[0 \to 1]$ (leading edge). This bit becomes valid when the data sheet function is set.
(8) Screen data output	The V series screen image is printed out at $[0 \to 1]$ (leading edge). This bit becomes valid when a printer is connected. It is also possible to make a screen hard copy using an internal switch [Function: Hard Copy].
(9) Backlight	This bit becomes valid when an option other than [Always ON] is selected in the [Backlight] tab window that is displayed by selecting [System Setting] → [Unit Setting]. [0] (level): OFF when the conditions are satisfied [1] (level): ON
(10)Analog RGB input	These bits are used for controlling show/hide operations of the analog RGB input screen. [0] (level): RGB input screen not displayed (in RUN mode) [1] (level): RGB input screen displayed
(11)Screen internal switching	This bit controls screen switching by internal switches. [0]: Screen switching by internal switches is enabled. [1]: Screen switching by internal switches is disabled. * An "internal switch" means a switch you can create for internal processing within MONITOUCH by selecting [Screen] or [Return] for [Function:] of the switch.
(12)Screen forced switching	This bit is used for switching the screen using the read area "n + 2" when the required screen number has already been specified in "n + 2 ". *3
(13)Data read refresh	All the data display items on the screen are refreshed at $[0 \rightarrow 1]$ (leading edge). This is applied to every data display item regardless of the setting for [Process Cycle].

- It is possible to make this function work with the bit in the level. For more information, refer to the V9 Series Reference Manual.
- *2 As an exception, a multi-overlap may appear/disappear at the edge. For more information, refer to the V9 Series Reference Manual.
- *3 Usage Example
 - Step a: Screen change according to read area "n + 2"
 Step b: Screen change with an internal switch

Step c: Screen change to the same screen number as step a according to read area "n + 2" In this case, however, the same value is stored in read area "n + 2" so the command is not valid. In such a case, it is possible to forcibly switch the screen to the screen number contained in read area "n + 2" at the leading edge $[0 \rightarrow 1]$ of bit 14.



Reset this bit (OFF) after checking that bit 14 of write area "n + 1" is ON, or the value stored in write area "n + 2" is the same as the value in read area "n + 2".

ad aı	rea	n "n +	+ 2" (screer	num	nber c	omm	and)																				
15	5	14	13	12	11	10	09	08	07	06	05	04	03	02	01	00												
									(1) S	creen	num	ber																
		n nur nand	mber *1		T V E	Vhen ven if	bits a a scre the s	en nu creen	umbe i has l	r is sp been	ecifie switcl	ed in t ned u	hese sing a	bits, i an int	he sc ernal :	rnal co reen is switch, ave pr	dis it i	spl s p	os	sib				ree	en u	sing	j an	

*1 Screen No. Error When MONITOUCH has started communications with the PLC, the screen of the screen number specified in read area "n + 2" is displayed. If the screen number specified in read area "n + 2" does not exist in the screen data, "Screen No. Error" is displayed on MONITOUCH.



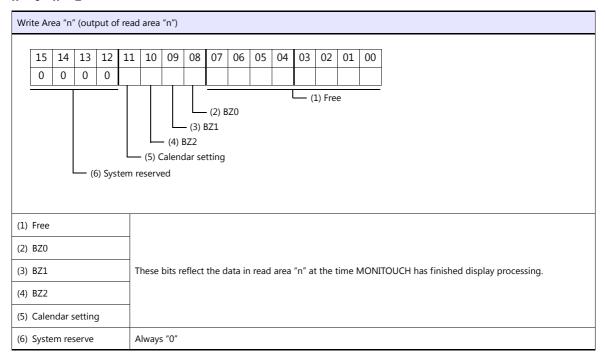
Before starting communications with the PLC, check the data in [Read Area] "n + 2" and confirm that the screen number to be displayed initially is specified.

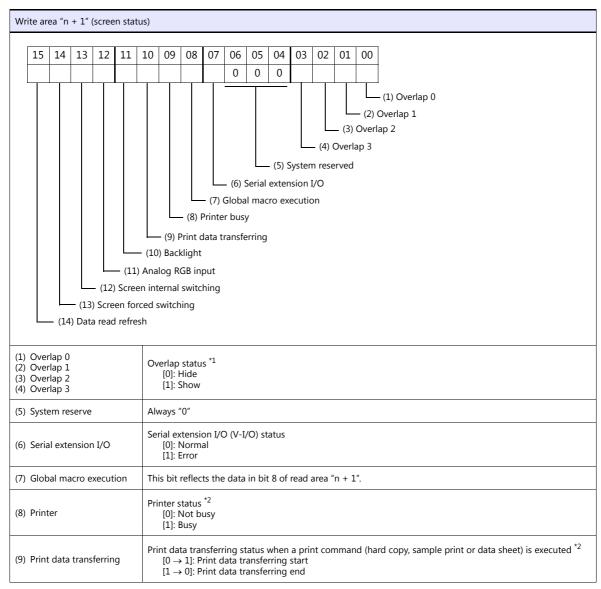
Write Area

This device memory area is used to store information regarding screen number, overlap display, and entry mode when the screen display status is changed by a command received from the host. Be sure to set the \$u device memory. Address allocation is shown in the table below.

Address	Name	Contents			
n + 0	CFMDAT	Sub command/data			
n + 1	SCRN_COM	Screen status			
n + 2	SCRN_No	Displayed screen			
n + 3	SW0	No. 0 switch data			
n + 4	SW1	No. 1 switch data			
n + 5	ENT0	Entry information 0			
n + 6	ENT1	Entry information 1			
n + 7	ENT2	Entry information 2			
n + 8	GREPNS	Global response			
n + 9					
: n + 15		Reserved (7 words)			

n + 0 - n + 2

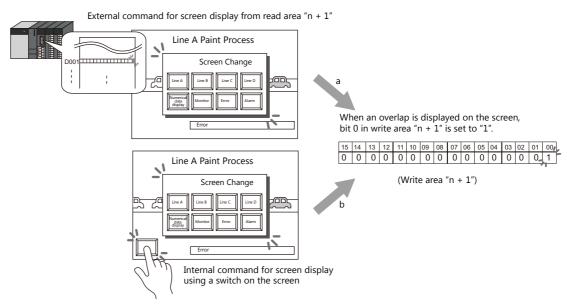




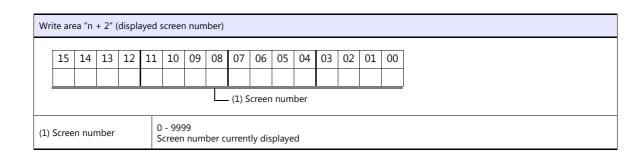
(10)Backlight	Backlight ON/OFF status *3 [0]: OFF [1]: ON * Even if bit 11 (backlight) in read area "n + 1" is reset (0: OFF), this bit shows "1" if the backlight is on.
(11)Analog RGB input	Analog RGB input screen status [0]: RGB input screen not displayed (in RUN mode) [1]: RGB input screen displayed
(12)Screen internal switching	This bit reflects the data in bit 13 of read area "n + 1".
(13)Screen forced switching	This bit reflects the data in bit 14 of read area "n + 1".
(14)Data read refresh	This bit reflects the data in bit 15 of read area "n + 1".

*1 Example:

- Display overlap No. 0 from read area (n + 1) using an external command.
- b. Display overlap No. 0 internally using the [Function: Overlap = ON] switch. In either case (a or b), bit 0 of write area "n + 1" is set (ON). In the case of b, the bit in read area "n + 1" remains "0".



- *2 Data of bits 9 and 10 is output to internal device memory address \$s16. For more information on the internal device memory (\$s), refer to the V9 Series Reference Manual.
- Data of bit 11 is output to internal device memory address \$s17. For more information on the internal device memory (\$s), refer to the V9 Series Reference Manual.



n + 3 (SW0) switch data No. 0, n + 4 (SW1) switch data No. 1

When a switch, for which [Output Action] is set to [Momentary/Momentary W] and [Output Device] is set in location from \$s0080 to 0095, is pressed, the status and the number of the switch is stored.

	15	14	13	12	11	10	09	80	07	06	05	04	03	02	01	00
1		0	0	0	0	0	0	0								
		(ch sta): OFF L: ON										s	Switch	num	ber

For the relationship between the switch output device memory and the switch number, see page 28-36.

n + 5 (ENT0) entry information 0, n + 6 (ENT1) entry information 1

The same contents as n + 0 and n + 1 of the [Info. Output Device] that is set in the entry mode are written. Write operation occurs when the key whose function is set to "Write" is pressed in the entry mode.

When the entry selection has changed, write operation will not occur.

When (n + 5) entry information 0 is read by the host, the writing completed bit (bit 15) is reset.

Data is written in the backup (escape) area before it is read (see page 28-9).

n + 7 (ENT2) entry information 2

The entry mode window number where a write operation was executed is written.

The relationship between the window number and base and the window number and overlap is shown in the following table

Window No.	Contents
0	Base entry mode
1	Overlap 0 entry mode
2	Overlap 1 entry mode
3	Overlap 2 entry mode

- In case of using the entry mode for the table data display When the bit No. 12 of "Command Device" in the [Entry] dialog is ON [1], the line number and the column number will be output to the address n + 1 and the block number to the address n + 2 of the "Info. Output Device". Note that therefore, in only this case the window number cannot be referred because the block number is output to the address n + 7 (ENT2) of the write area.

n + 8 (GREPNS) global response

A response is written when a global port number is used in 1: n communication. The contents of a response are shown in the following table.

For details on the global port number, see page 28-22.

Device Contents	Description					
0000	Global command not received					
0100	ACK					
Others	Others Identical to NAK code (see page 28-23).					

n + 9 to n + 15

System reserved

Calendar

Select a device memory from which the calendar data is read without using the V9 series' built-in clock. For more information on the built-in clock, refer to the V9 Series Reference Manual.

PLC1 to 8

Calendar data is read from the selected device memory.

The calendar data will be updated when:

- The power is turned on.
- STOP→RUN
- The date changes.
- At the leading edge of a bit (0 \rightarrow 1) in the calendar device memory in the reading area

Initial Screen

Set the number of the screen to be displayed when power to the V series is turned on.

GD-80 Compatible

This setting is not valid because the GD-80 series cannot be used for universal serial communication.

28.4 Standard Type Protocol

28.4.1 Standard Type Protocol

The connection mode and transmission mode are set under [System Setting] \rightarrow [Communication Setting]. The mode contents are as follows.

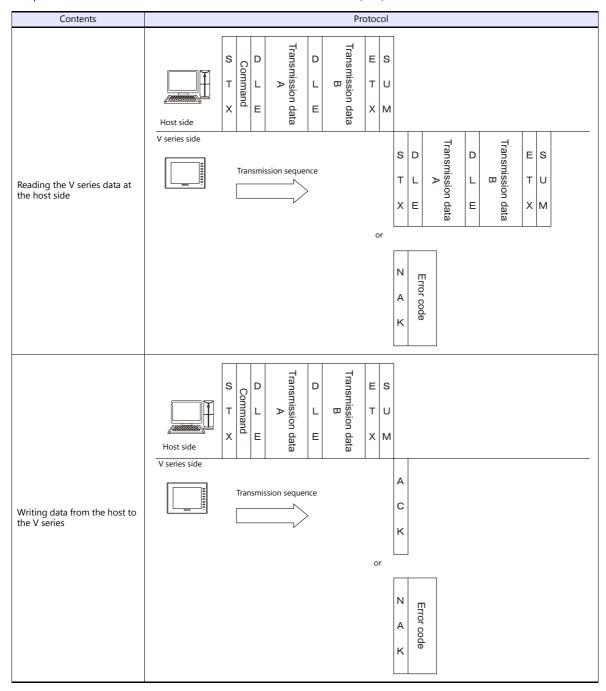
- Connection mode
 - 1:1: Select it when connecting one V series unit to one host.
 - 1 : n: Select it when connecting multiple V series units to one host. A maximum of 32 units can be connected. (Multi-drop specifications)
- Transmission mode

There are four transmission modes, depending on whether or not a sum check or CR/LF code is attached to the end of transmission and received data, as shown below.

Transmission Mode	Sum Check	CR/LF
1	Not provided	Not provided
2	Provided	Not provided
3	Not provided	Provided
4	Provided	Provided

Connection (1:1), Transmission Mode (with Sum Check)

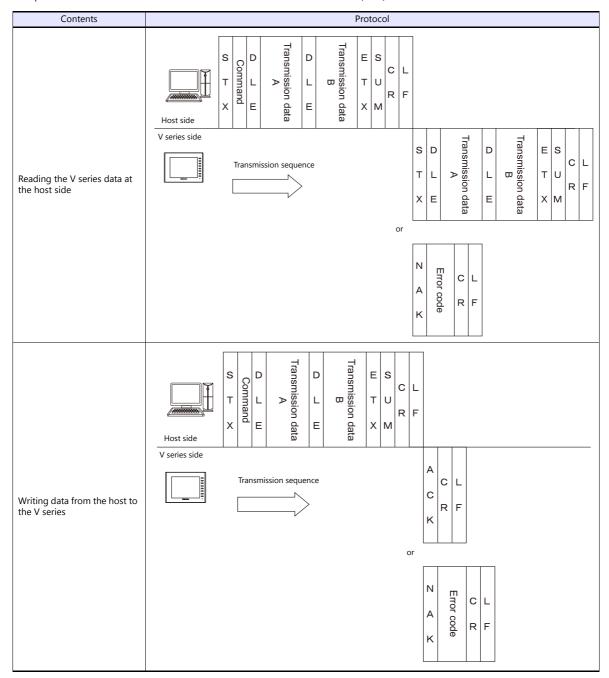
This protocol is used when one host communicates with one V series unit (1:1).



• When 1:1 connection is used, an interrupt can be used. For more information, see page 28-32.

Connection (1:1), Transmission Mode (with Sum Check and CR/LF)

This protocol is used when one host communicates with one V series unit (1:1).



• When 1:1 connection is used, an interrupt can be used. For more information, see page 28-32.

Connection (1:n), Transmission Mode (with Sum Check)

It is possible to connect as many as 32 V series units to one host. (For information on the global command, see page 28-25.)

Contents	Protocol
Reading the V series data at the host side	Transmission data V series side Transmission sequence Transmission sequence Transmission sequence Transmission data
	data Error code Port No. R A K
Writing data from the host to the V series	Transmission data S T X M Host side V series side Transmission sequence Transmission sequence Transmission sequence Or Transmission sequence Transmission sequence Or Transmission sequence

Connection (1: n), Transmission Mode (with Sum Check and CR/LF)

It is possible to connect as many as 32 V series units to one host. (For information on the global command, see page 28-25.)

Contents	Protocol
Reading the V series data at the host side	Transmission data Solution Solution Transmission data B Transmission data Fort No. Solution Fort N
Writing data from the host to the V series	Transmission data V series side Transmission sequence

28.4.2 Protocol Contents

Transmission Control Code

The transmission control codes are shown in the table below.

Signal Name	Code (Hexadecimal)	Contents
STX	02H	Start of transmission block
ETX	03H	End of transmission block
ENQ	05H	Interrupt
ACK	06H	Positive acknowledge
CR	0DH	Carriage return
DLE	10H	Change contents within a block
NAK	15H	Negative acknowledge
LF	0AH	Line feed

Port Number

Port numbers can be set for connection mode "1: n".

They are used so that the host computer can identify each V series for access.

The data range is from 00H to 1FH (0 to 31) and is converted into a two-digit ASCII code (HEX) before use. Set port numbers of the V series at [Local Port No.] under [Communication Setting].

Global port number (FFH)

When the global port number [FFH] is set, commands are send to all V series units at one time.

Commands for which global port numbers are active are shown below. If commands other than these are used, a command error will occur.

Signal Name	Name	Contents
WM	Write	Write data device memory
WC	Write CHR	Write data device memory as characters

Responses to global port numbers are not transmitted to the host. However, responses are written in write area n + 8.

Device Contents	Description
0000H	Global command not received
0100H	ACK
Others	Identical to NAK code (see page 28-23.)

Command

Available commands are shown below. The details on commands are described on pages shown at "Refer to:".

Signal Name	Name	Contents	Refer to:
RM	Read	Read data device memory	page 28-26
WM	Write	Write data device memory (512 words maximum)	page 28-28
TR	Retry	Retry when NAK [01] is BUSY	page 28-29
WI	Interrupt Setting	Allow interrupt (Connection mode 1:1)	page 28-30
RI	Read interrupt status	Read interrupt setting status (Connection mode 1 : 1)	page 28-31
RC	Read CHR	Read data device memory as characters	page 28-25
WC	Write CHR	Write data device memory as characters (1024 bytes maximum)	page 28-27

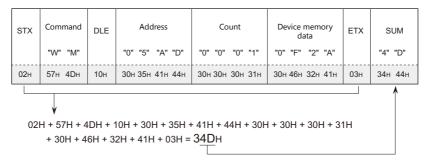
Sum Check Code (SUM)

Data is added up (SUM), and the lower one byte (8 bits) of the sum is converted into a two-digit ASCII code (HEX).

Example:

Transmission mode: without CR/LF, with sum check

The sum check code is added as shown below when data "3882" (OF2AH) is transmitted to the address "\$u1453" (05ADH) using the command [WM] (data writing).



 $^{^{\}ast}\;$ In the case of an interrupt, data from ENQ to ETX is subject to a sum check.

Error Codes

An error code is sent along with an NAK response as a two-digit ASCII code (HEX).

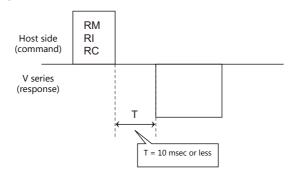
Error Codes	Contents
01H	The V series is currently engaged in display processing. The received command is on standby due to display processing. Wait a few moments and re-transmit the command.
02H	Overrun/Framing error An overrun or framing error is detected in the received data. Send the command again.
03H	Parity error A parity error is detected in the received data. Send the command again.
04H	Sum check error A sum error occurs with the received data.
05H	Address error The address specified by the device memory read/write command is incorrect. Check the address or counter and re-transmit the command.
06H	Count error The device memory read/write count is "0".
07H	Screen error The data to be written in read area n + 2 (screen status command), as specified by a write command, is not registered on the screen. Check the screen number and re-transmit the data.
08H	Format error The number of DLEs is 0 or greater than 6.
09Н	Received data over The number of write command data received from the host exceeded that of data shown below. • Write memory command = 512 words • Write CHR command = 1024 bytes
ОВН	Retry command error When a retry command is received, there is no BUSY status (NAK [01]) command.
0FH	ETX error No ETX code is found.
10H	DLE error No DLE code is found.
11H	Character error A character not used in the received data is found (other than 0 to F). Check the character and send the command again.
12H	Command error An invalid command is given.

Response Time and BUSY

Response time varies depending on the type of command.

RM / RI / RC

These commands immediately send a response once receipt of data is complete. No NAK [01] (BUSY) signal is given.



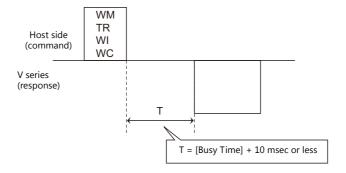
WM / TR / WI / WC

Once receipt of data is complete, these commands first check the display status. If the display status is found to be complete, a response is sent and a command is executed.

If the status is BUSY and the display is completed within the time set in [Busy Time], a response is sent.

If the display is not completed within the specified time, an NAK [01] (BUSY) signal is sent. In this case, it is necessary to retransmit the command.

When [Busy Time] is set as [0], the machine waits until the display is complete, and then a response is transmitted after a command is executed.



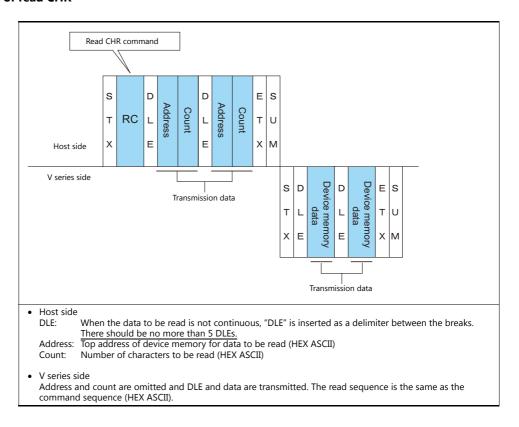
28.4.3 Command

RC: Read CHR

This command is used to read data in device memory as characters.

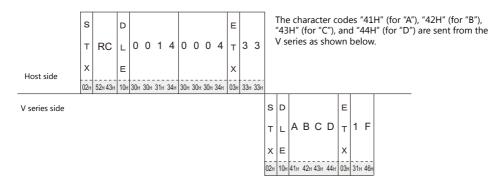
* When character data is sent, 1 character (1 byte) is converted into a two-byte ASCII code and transmitted by the read memory command. When the read CHR command is given, character data is not converted into the ASCII code before transmission, and thus, the transmission time is decreased by approximately 1/2.

Details of read CHR



Example:

Call up 4 characters that are written at the top of the address \$u0020 (0014H).

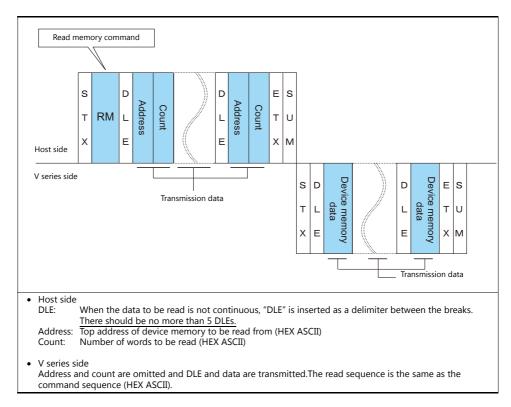


RM: Read Memory

This command is used to read data in device memory.

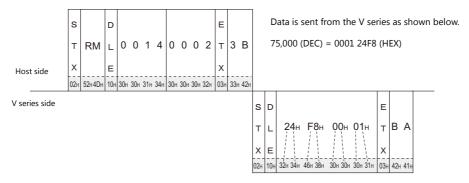
* Communication speed is increased when you use the read CHR command to read characters.

Details of read memory



Example:

Read the double-word data "75,000" (DEC) contained in the address \$u0020 (0014H).

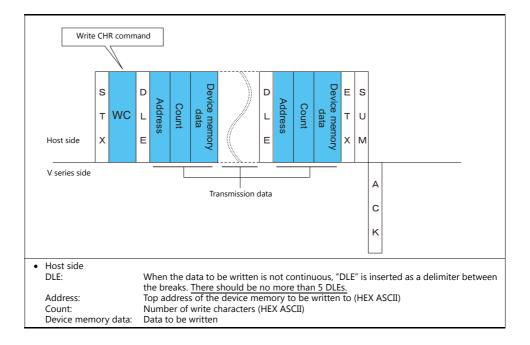


WC: Write CHR

This command is used to write data to device memory as characters.

* When character data is sent, 1 character (1 byte) is converted into a two-byte ASCII code and transmitted by the write memory command. When the write CHR command is given, character data is not converted into the ASCII code before transmission, and thus, the transmission time is decreased by approximately 1/2. (Character codes from 00 to 1F cannot be used.)

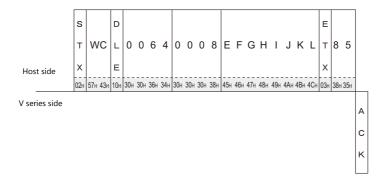
Details of write CHR



Example:

Send data to display the following characters on the V series.

\$u0100 (0064H), EF \$u0101 (0065H), GH \$u0102 (0066H), IJ \$u0103 (0067H), KL

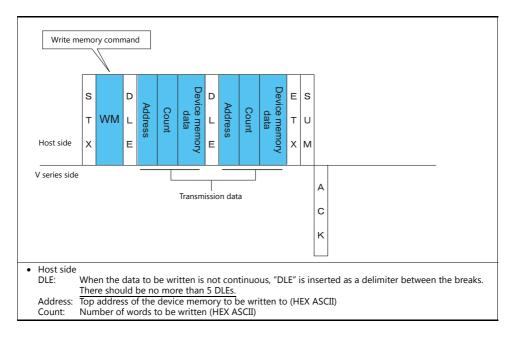


WM: Write Memory

This command is used to write data to device memory.

* Communication speed is increased when you use the write CHR command to write characters.

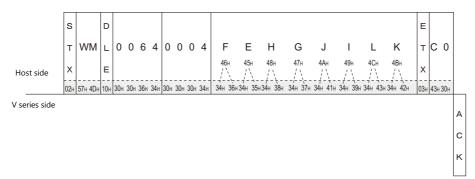
Details of write memory



Example:

Send data to display the following characters on the V series.

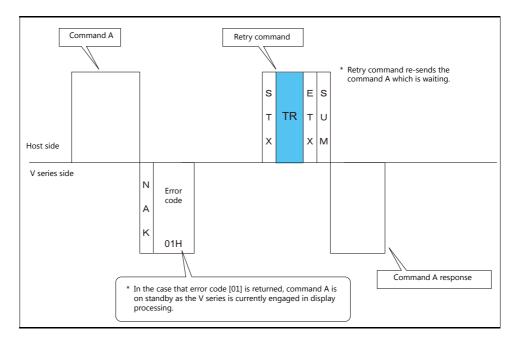
\$u0100 (0064H), EF (= 4645 H) \$u0101 (0065H), GH (= 4847 H) \$u0102 (0066H), IJ (= 4A49 H) \$u0103 (0067H), KL (= 4C4B H)



TR: Retry Command

This command is used to re-send a write command/write CHR command when an NAK error code [01] is returned.

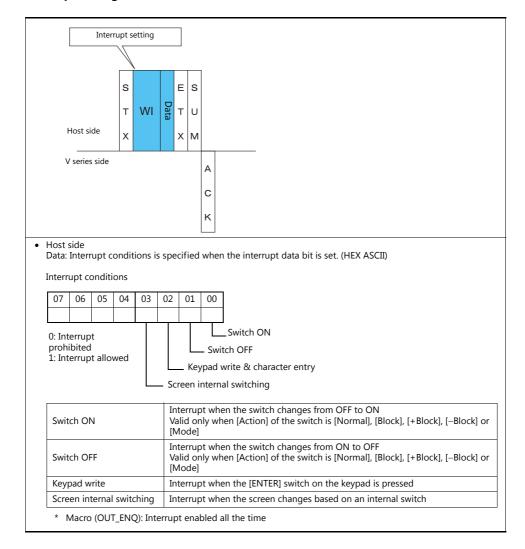
Details of retry



WI: Interrupt Setting Command

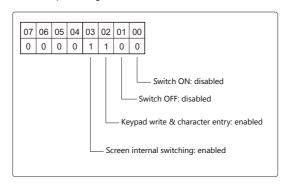
This command is used to send interrupt conditions. It can be used for 1:1 connection.

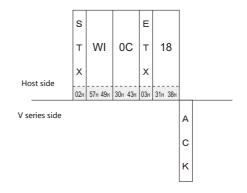
Details of interrupt setting command



Example:

Interrupt settings are as shown below.

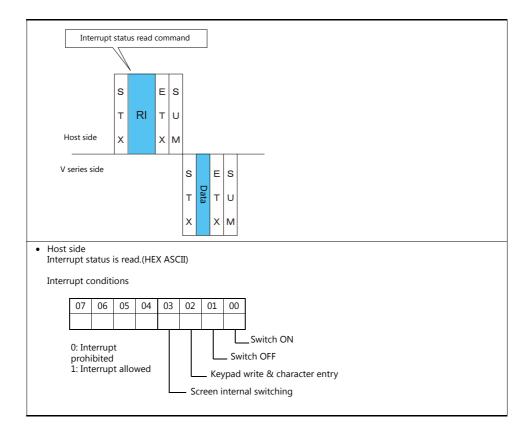




RI: Interrupt Status Read Command

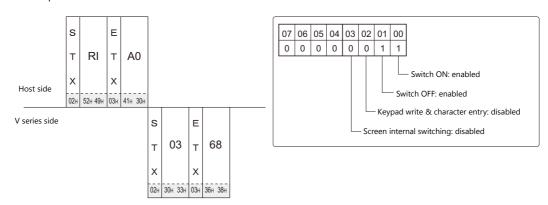
This command is used to read interrupt setting status. It can be used for 1:1 connection.

Details of interrupt status read command



Example:

Interrupt status is read.



28.4.4 Interrupt (ENQ)

The interrupt command can be used for 1:1 connection.* Interrupt data becomes the contents of write areas n+2 to n+7. (See page 28-13.)

* For RS-485 (2-wire connection), interrupts cannot be used.

Interrupt codes and conditions

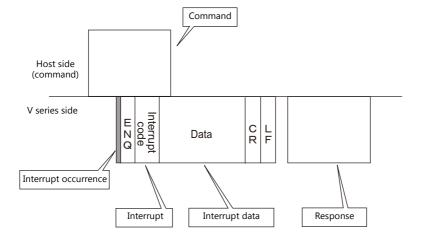
An interrupt code is sent to the host for the following actions.

Interrupt Codes	Interrupt Conditions						
00Н	The regular switch is changed from ON to OFF or OFF to ON when it is pressed.						
	* When universal serial connection is made at multiple ports, all ports are interrupted at the same time.						
	The "Write" switch on the keypad or on the keyboard is changed from OFF to ON when it is pressed.						
01H	 * If [Control Prohibition/Enabled of Write Key] is checked, the write enable bit must be set in order to send an interrupt code. * When universal serial connection is made at multiple ports, all ports are interrupted at the same time. 						
	The screen is switched by an internal switch.						
02H	* When universal serial connection is made at multiple ports, all ports are interrupted at the same time.						
10H to 2FH	The macro command [OUT_ENQ] is executed (for PLC1). The macro command [OUT_ENQ_EX] is executed (PLC1 to 8 selected by user).						
30H to 3FH	The macro command [OUT_ENQ] is executed (for PLC2).						
40H to 4FH	The macro command [OUT_ENQ] is executed (for PLC3).						
50H to 5FH	The macro command [OUT_ENQ] is executed (for PLC4).						
60H to 6FH	The macro command [OUT_ENQ] is executed (for PLC5).						
70H to 7FH	The macro command [OUT_ENQ] is executed (for PLC6).						
80H to 8FH	The macro command [OUT_ENQ] is executed (for PLC7).						
90H to 9FH	The macro command [OUT_ENQ] is executed (for PLC8).						

Interrupt timing

When an interrupt condition occurs while the host is transmitting a command or before the V series transmits a response, the interrupt code will be transmitted before the response is transmitted.

To use an interrupt, it is necessary to enable interrupt code detection when a response is received on the host program.



Interrupt Data

When a regular switch is pressed



E	00	Screen No.	SW0	SW1	ENTO	CNIT4	ENTO	Е	s
N	00	Screen No.	5000	5001	ENT0	ENT1	ENT2	Т	U
Q		WORD	WORD	WORD	WORD	WORD	WORD	Х	М

A "regular switch" means a switch for which [Momentary] is selected for [Output Action] and \$s0080 to 0095 is set for [Output Device]. When this switch is pressed, the following actions take place.

Output device memory is set $(0 \to 1)$ while the switch is held down, and is reset $(1 \to 0)$ when the switch is released. At the same time, the switch number that corresponds to the output device memory is written in write areas n + 3 and n + 4

For details on the output device memory and the switch number, see page 28-37.

Normally, [1-Output] is set for the switch. Thus, the switch number and switch information is written in write area n + 3. However, when the switch as well as a function switch is pressed simultaneously (2-Output), the switch number and switch information is written in write areas n + 3 and n + 4.

When the "Write" switch on the keypad is pressed:

When the [ENT] switch on the keypad is pressed



E								Е	S
N	01	Screen No.	SW0	SW1	ENT0	ENT1	ENT2	Т	U
Q		WORD	WORD	WORD	WORD	WORD	WORD	х	М
		WORD	WOILD	WOILD	WOILD	WOILD	WOILD		

ENT0/1/2 is the same as the write area in system device memory (n + 5, n + 6, n + 7).

When the screen is internally changed:

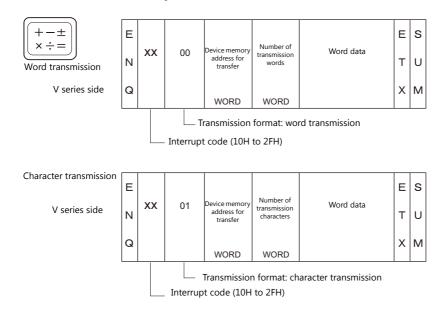


V series side

E		Caraca Na						E	s
N	02	Screen No.	SW0	SW1	ENT0	ENT1	ENT2	т	U
Q		WORD	WORD	WORD	WORD	WORD	WORD	x	М

When a macro command (OUT_ENQ) is executed:

With an OUT_ENQ command, you can either convert the data into HEX code and transmit it (word transmission), or you can transmit the data just as it is without converting it (character transmission). For more information on "OUT_ENQ", refer to the Macro Reference manual.



1-byte Character Code List

Lower

U	р	р	e

	0	1	2	3	4	5	6	7	8	9	Α	В	С	D	Е	F
0			SP	0	@	Р	,	р								
1			!	1	Α	Q	а	q								
2			"	2	В	R	b	r								
3			#	3	С	S	С	s								
4			\$	4	D	Т	d	t								
5			%	5	Е	U	е	u								
6			&	6	F	٧	f	٧								
7			,	7	G	W	g	w								
8			(8	Н	Х	h	х								
9)	9	I	Υ	i	у								
Α			*	:	J	Z	j	z								
В			+	;	K	[k	{								
С			,	<	L	¥	I									
D			-	=	М]	m	}								
Е				>	N	٨	n	~								
F			/	?	0	_	0									

28.5 Device Memory Map

Device Memory

Inside the V series, there is internal device memory necessary for screen display called "user device memory (\$u)", as well as device memory that the V series uses for the system called "system device memory (\$s)".

User Device Memory (\$u)

32768 words are available for user device memory. This area is usable as desired for screen programs. Also the host computer can write to and read from the area.

The device memory map is as shown below.

	\$u0000
	\$u0001
	\$u0002
	\$u0003
	\$u0004
	\$u0005
	\$u0006
User device memory (32768 words)	
	\$u32761
	\$u32761 \$u32762
	·
	\$u32762
	\$u32762 \$u32763
	\$u32762 \$u32763 \$u32764
	\$u32762 \$u32763 \$u32764 \$u32765

System Device Memory (\$s)

2048 words are available for system device memory. System device memory is device memory that writes V series action status when the V Series is currently displaying something. With this written information, it is possible to check overlap status, buffer area, printer, backlight, and slave station status in multi-drop connection mode. In the table below, a small part (\$s80 to 95) of system device memory is extracted. For other device memory addresses, refer to the Reference Manual.

* System device memory cannot be read or written from the host computer.

Address \$s0080 to 95

Set [Output Device] in location (\$s0080 to 95) of system device memory, and select [Momentary] for [Output Action] of a switch. When the switch is pressed, output device memory is set $(0 \to 1)$ and the corresponding switch number is written in system setting areas n + 3 and n + 4. (See page 28-15.)

The relationship between the output device memory and the switch number is shown in the following diagram. For details about the output of a switch, see page 28-34.

Address								Con	tents								
:																	
	Universal s	erial sw	itch o	utput () Switc	h No.	0 to 15	i									
# 00		MSB															LSB
\$s80		15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
	No.	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
	Universal s	erial sw	itch o	utput 1	Switc	h No.	16 to 3	1									
	MSB LSB															LSB	
\$s81		15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
	No.	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
	Universal serial switch output 2 Switch No. 32 to 47																
															LSB		
\$s82		15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
	No.	47	46	45	44	43	42	41	40	39	38	37	36	35	34	33	32
	Universal s	orial cu	itch o	utput 3	Cwitc	h No	10 to 6	:2									
	Universal s		nich o	utput s	SWILC	II INO.	40 10 0	13									
\$s83		MSB			40		10	0		_		-		-	-		LSB
	No.	15 63	14 62	13 61	12 60	11 59	10 58	9 57	8 56	7 55	6 54	5 53	4 52	3 51	2 50	1 49	0 48
									30	33	31	33	32	31	30	13	10
	Universal serial switch output 4 Switch No. 64 to 79																
\$s84		MSB															LSB
4301		15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
	No.	79	78	77	76	75	74	73	72	71	70	69	68	67	66	65	64
	Universal s	erial sw	itch o	utput 5	Switc	h No.	80 to 9	5									
		MSB															LSB
\$s85		15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
	No.	95	94	93	92	91	90	89	88	87	86	85	84	83	82	81	80
	Universal s	erial sw	itch o	utput 6	Switc	h No.	96 to 1	.11									
		MSB															LSB
\$s86		15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
	No.	111	110	109	108	107	106	105	104	103	102	101	100	99	98	97	96
	Universal s	erial sw	itch o	utput 7	7 Switc	h No.	112 to	127									
		MSB															LSB
\$s87		15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
	No.	127	126	125	124	123	122	121	120	119	118	117	116	115	114	113	112
	Universal s	orial cu	itch o	itnii+ C	S Swite	h Na	128 +	1/12									
	Offiversal S		nteri O	atput č	SWILC	II INO.	120 lÜ	T43									
\$s88		MSB	14	12	12	11	10	0	0	7	_	-	4	2	2	1	LSB
	No.	15 143	14 142	13 141	12 140	11 139	10 138	9	8 136	7 135	6 134	5 133	4 132	3 131	2 130	1 129	128
	. 10.	_ 13	- 12	'-	-10	233	-50	23,	-50	-55	-51	200	-52	101	-50	1	

Address		Contents															
	Universal s	erial sw	itch o	utput 9	9 Swite	h No.	144 to	159									
¢ 00		MSB															LSB
\$s89		15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
	No.	159	158	157	156	155	154	153	152	151	150	149	148	147	146	145	144
	Universal s	erial sw	itch o	utput 1	L0Swite	h No.	160 to	175									
		MSB															LSB
\$s90		15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
	No.	175	174	173	172	171	170	169	168	167	166	165	164	163	162	161	160
	Universal s	orial cu	itch o	itnut 1	1 Cwi+	h No	176 to	101		I		I					
	Offiversals		nich of	atput 1	LISWILL	JII INO.	170 10	191									
\$s91		MSB		4.2	4.0		10			_		_		_	_		LSB
	No.	15 191	14 190	13 189	12 188	11 187	10 186	9 185	8 184	7 183	6 182	5 181	4 180	3 179	2 178	1 177	0 176
									104	103	102	101	100	1/9	176	1//	170
	Universal s	erial sw	itch o	utput 1	L2 Sw	itch No	. 192 1	to 207									
\$s92		MSB															LSB
\$592		15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
	No.	207	206	205	204	203	202	201	200	199	198	197	196	195	194	193	192
	Universal s	erial sw	itch o	utput 1	L3 Sw	itch No	o. 208 t	to 223									
		MSB															LSB
\$s93		15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
	No.	223	222	221	220	219	217	218	216	215	214	213	212	211	210	209	208
	Universal s	erial sw	itch o	utput 1	L4 Sw	itch No	o. 224 t	to 239									
\$s94		MSB					1	1	1	,	1	,					LSB
Ψ33 1		15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
	No.	239	238	237	236	235	234	233	232	231	230	229	228	227	226	225	224
	Universal s	erial sw	itch o	utput 1	L5 Sw	itch No	o. 240 t	to 255									
\$s95		MSB															LSB
\$595		15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
	No.	255	254	253	252	251	250	249	248	247	246	245	244	243	242	241	240
:																	

Address \$s0111

This address stores the local port number.

 $^{\star}\,$ The local port number specified for [Specify as a Main] in the [PLC Properties] window is stored.

MEMO
Please use this page freely.

Connection Compatibility List

April, 2014

Manufacturer	Models	1:1	1 : n Multi-drop	n : 1 Multi-link2	Multi-link2 Ethernet	1 : n Multi-link2 Ethernet	n : 1 Multi-link
	PLC-5	0	0	0	0	0	0
	PLC-5 (Ethernet)	0	0				
	Control Logix / Compact Logix	0		0	0		
	Control Logix (Ethernet)	0	0				
Mon Bradley	SLC500	0	0	0	0	0	
Allen-Bradley	SLC500 (Ethernet TCP/IP)	0	0				
	NET-ENI (SLC500 Ethernet TCP/IP)	0	0				
	NET-ENI (MicroLogix Ethernet TCP/IP)	0	0				
	Micro Logix	0	0	0	0	0	
	Micro Logix (Ethernet TCP/IP)	0	0				
	Direct LOGIC (K-Sequence)	0		0	0		
Automationdirect	Direct LOGIC (Ethernet UDP/IP)	0	0	Ŭ			
	Direct LOGIC (MODBUS RTU)	0	0	0	0	0	
	MX series	0	0	0	0	0	
	SDC10	0	0	0	0	0	
	SDC20						
		0	0	0	0	0	
	SDC21	0	0	0	0	0	
	SDC30/31	0	0	0	0	0	
	SDC35/36	0	0	0	0	0	
	SDC40A	0	0	0	0	0	
Azbil	SDC40G	0	0	0	0	0	
	DMC10	0	0	0	0	0	
	DMC50(COM)	0	0	0	0	0	
	AHC2001	0	0	0	0	0	
	AHC2001+DCP31/32	0	0	0	0	0	
	DCP31/32	0	0	0	0	0	
	NX(CPL)	0	0	0	0	0	
	NX(MODBUS RTU)	0	0	0	0	0	
	NX(MODBUS TCP/IP)	0	0				
Baumuller	BMx-x-PLC	0		0	0		
BECKHOFF	ADS protocol (Ethernet)	0	0				
	LT400 Series (MODBUS RTU)	0	0	0	0	0	
	DP1000	0	0	0	0	0	
	DB100B (MODBUS RTU)	0	0	0	0	0	
CHINO	KR2000 (MODBUS RTU)	0	0	0	0	0	
	LT230 (MODBUS RTU)	0	0	0	0	0	
	LT300 (MODBUS RTU)	0	0	0	0	0	
	LT830 (MODBUS RTU)						
	BP series	0	0	0	0	0	
CIMON		0		0	0		
DELTA	CP series	0		0	0		
DELTA	DVP series	0	0	0	0	0	
DELTA TAU DATA SYSTEMS	PMAC	0	_	0	0		
ELTON C. I	PMAC(Ethernet TCP/IP)	0	0	_	_	_	
EATON Cutler-Hammer	ELC	0	0	0	0	0	
EMERSON	EC10/20/20H (MODBUS RTU)	0	0	0	0	0	
FANUC	Power Mate	0		0	0		
Fatek Automation	FACON FB Series	0	0	0	0	0	
FUFENG	APC Series Controller	0	0	0	0	0	
	MICREX-F series	0	0	0	0	0	0
	MICREX-F series V4-compatible	0	0	0	0	0	
	SPB (N mode) & FLEX-PC series	0	0	0	0	0	
	SPB (N mode) and FLEX-PC CPU	0		0	0	0	
	MICREX-SX SPH/SPB series	0		0	0		
	MICREX-SX SPH/SPB CPU	0		0	0		
	MICREX-SX (Ethernet)	0	0				
Fuji Electric	PYX (MODBUS RTU)	0	0	0	0	0	
	PXR (MODBUS RTU)	0	0	0	0	0	
	PXG (MODBUS RTU)	0	0	0	0	0	
					0		
	PXH (MODRUS PTII)						
	PXH (MODBUS RTU)	0	0	0		0	
	PXH (MODBUS RTU) PUM (MODBUS RTU) F-MPC04P (loader)	0	0	0	0	0	

Manufacturer	Models	1:1	1 : n Multi-drop	n : 1 Multi-link2	Multi-link2 Ethernet	1 : n Multi-link2 Ethernet	n : 1 Multi-link
	FVR-E11S	0	0	0	0	0	
	FVR-E11S (MODBUS RTU)	0	0	0	0	0	
	FVR-C11S (MODBUS RTU)	0	0	0	0	0	
	FRENIC5000 G11S/P11S	0	0	0	0	0	
	FRENIC5000 G11S/P11S (MODBUS RTU)	0	0	0	0	0	
	FRENIC5000 VG7S (MODBUS RTU)	0	0	0	0	0	
	FRENIC-HVAC/AQUA (MODBUS RTU) FRENIC-Mini (MODBUS RTU)	0	0	0	0	0	
	FRENIC-IVINI (MODBUS RTU)	0	0	0	0	0	
	FRENIC-Multi (MODBUS RTU)	0	0	0	0	0	
	FRENIC-MEGA (MODBUS RTU)	0	0	0	0	0	
	FRENIC-MEGA (MODBOS RTU)	0	0	0	0	0	
	HFR-C9K	0	0	0	0	0	
Fuji Electric	HFR-C11K	0	0	0	0	0	
	PPMC (MODBUS RTU)	0	0	0	0	0	
	FALDIC-α series	0	0	0	0	0	
	FALDIC-W series	0	0	0	0	0	
	PH series	0	0	0	0	0	
	PHR (MODBUS RTU)	0	0	0	0	0	
	WA5000	0	0	0	0	0	
	APR-N (MODBUS RTU)	0	0	0	0	0	
	ALPHA5 (MODBUS RTU)	0	0	0	0	0	
	ALPHA5 Smart (MODBUS RTU)	0	0	0	0	0	
	WE1MA (Ver. A)(MODBUS RTU)	0	0	0	0	0	
	WE1MA (Ver. B)(MODBUS RTU)	0	0	0	0	0	
	WSZ series	0	0	0	0	0	
Gammaflux	TTC2100	0	0	0	0	0	
	90 series	0	0	0	0	0	
	90 series (SNP-X)	0		0	0		
GE Fanuc	90 series (SNP)	0	0	0	0	0	
	90 series (Ethernet TCP/IP)	0	0				
	RX3i (Ethernet TCP/IP)	0	0	_	_		
	HIDIC-S10/2α, S10mini	0	_	0	0		
	HIDIC-S10/2α, S10mini (Ethernet)	0	0				
Hitachi	HIDIC-S10/4α	0		0	0		
	HIDIC-S10V	0	0	0	0		
	HIDIC-S10V (Ethernet) HIDIC-H	0	0				
	HIDIC-H (Ethernet)	0	0	0	0	0	0
	HIDIC-FHV	0	0	0			0
Hitachi Industrial Equipment Systems	HIDIC-EHV (Ethernet)	0	0	0	0	0	0
	SJ300 series	0	0	0	0	0	
	SJ700 series	0	0	0	0	0	
	X-SEL controller	0	0	0	0	0	
	ROBO CYLINDER (RCP2/ERC)	0	0	0	0	0	
IAI	ROBO CYLINDER (RCS/E-CON)	0	0	0	0	0	
	PCON/ACON/SCON (MODBUS RTU)	0	0	0	0	0	
	MICRO 3	0	0	0	0	0	
IDEC	MICRO Smart	0	0	0	0	0	
	MICRO Smart pentra	0	0	0	0	0	
	TOYOPUC	0	0	0	0	0	0
JTEKT	TOYOPUC (Ethernet)	0	0				
	TOYOPUC (Ethernet PC10 mode)	0	0				
KEYENCE	KZ Series Link	0	0	0	0	0	0
	KZ-A500 CPU	0		0	0		
	KV10/24 CPU	0		0	0		
	KV-700	0		0	0		
	KV-700 (Ethernet TCP/IP)	0	0				
	KV-1000	0		0	0		
	KV-1000 (Ethernet TCP/IP)	0	0				
	KV-3000/5000	0		0	0		
	KV-3000/5000 (Ethernet TCP/IP)	0	0				
KOGANEI	IBFL-TC	0	0	0	0	0	
	SU/SG	0	0	0	0	0	
KOYO ELECTRONICS	SR-T (K protocol)	0		0	0		
	SU/SG (K-Sequence)	0	_	0	0	_	
	SU/SG (Modbus RTU)	0	0	0	0	0	

Manufacturer	Models	1:1	1 : n Multi-drop	n : 1 Multi-link2	Multi-link2 Ethernet	1 : n Multi-link2 Ethernet	n : 1 Multi-link
	MASTER-KxxxS	0		0	0		
	MASTER-KxxxS CNET	0	0	0	0	0	
	GLOFA CNET	0	0	0	0	0	0
	GLOFA GM7 CNET	0	0	0	0	0	
	GLOFA GM series CPU	0		0	0		
LS	XGT/XGK series CNET	0	0	0	0	0	
	XGT/XGK series CPU	0		0	0		
	XGT/XGK series (Ethernet)	0	0				
	XGT/XGI series CNET	0	0	0	0	0	
	XGT/XGI series CPU	0		0	0		
	XGT/XGI series (Ethernet)	0	0				
	A series link	0	0	0	0	0	0
	A series CPU	0		0	0		
	QnA series link	0	0	0	0	0	
	QnA series CPU	0	-	0	0		
	QnA series (Ethernet)	0	0	-	-		
	QnH (Q) series link	0	0	0	0	0	
	QnH (Q) series CPU	0		0	0		
	QnU series CPU	0		0	0		
	Q00J/00/01CPU	0		0	0		
	QnH (Q) series (Ethernet)	0	0)		
	QnH (Q) series link (multi CPU)	0	0	0	0	0	
	QnH (Q) series (multi CPU) (Ethernet)	0	0	0		Ü	
	QnH (Q) series CPU (multi CPU)	0	Ü	0	0		
	QnH (Q) series (Ethernet ASCII)	0	0	0	0		
	QnH (Q) series (multi CPU) (Ethernet ASCII)	0	0				
	QnU series (built-in Ethernet)	0	0				
	L series link	0	0	0	0	0	
MITSUBISHI ELECTRIC	L series (built-in Ethernet)	0	0				
	FX series CPU	0		0	0		
	FX2N/1N series CPU	0		0	0		
	FX1S series CPU	0		0	0		
	FX series link (A protocol)	0	0	0	0	0	0
	FX-3U/3UC/3G series CPU	0		0	0		
	FX-3U series (Ethernet)	0	0				
	FX3U/3UC/3UG series link (A protocol)	0	0	0	0	0	0
	A-Link + Net10		0				
	Q170MCPU (multi CPU)	0		0	0		
	Q170 series (multi CPU) (Ethernet)	0	0				
	FR-*500	0	0	0	0	0	
	FR-V500	0	0	0	0	0	
	MR-J2S-*A	0	0	0	0	0	
	MR-J3-*A	0	0	0	0	0	
	MR-J3-*T	0	0	0	0	0	
	FR-E700	0	0	0	0	0	
MODICON	Modbus RTU	0		0	0		
MOELLER	PS4	0		0	0		
M-SYSTEM	R1M series (MODBUS RTU)	0	0	0	0	0	

Manufacturer	Models	1:1	1 : n Multi-drop	n : 1 Multi-link2	Multi-link2 Ethernet	1 : n Multi-link2 Ethernet	n : 1 Multi-link
	SYSMAC C	0	0	0	0	0	0
	SYSMAC CV	0	0	0	0	0	0
	SYSMAC CS1/CJ1	0	0	0	0	0	
	SYSMAC CS1/CJ1 DNA	0	0				
	SYSMAC CS1/CJ1 (Ethernet)	0	0				
	SYSMAC CS1/CJ1 (Ethernet Auto)	0	0				
	SYSMAC CS1/CJ1 DNA (Ethernet)	0	0				
	E5AK	0	0	0	0	0	
	E5AK-T	0	0	0	0	0	
	E5AN/E5EN/E5CN/E5GN	0	0	0	0	0	
OMRON	E5AR/E5ER	0	0	0	0	0	
	ESCK	0	0	0	0	0	
	E5CK-T	0	0	0	0	0	
	E5CN-HT	0	0	0	0	0	
	E5EK	0	0	0	0	0	
	E5ZD	0	0	0	0	0	
	E5ZE	0	0	0	0	0	
	E5ZN	0	0	0	0	0	
	V600/620/680	0	0	0	0	0	
	KM20	0	0	0	0	0	
	KM100						
	High-efficiency AR series (MODBUS RTU)	0	0	0	0	0	
Oriental Motor	-	0	0	0	0	0	
	CRK series (MODBUS RTU)	0	0	0	0	0	
	FP Series (RS232C/422)	0	0	0	0	0	0
	FP Series (TCP/IP)	0	0				
	FP Series (UDP/IP)	0	0				
	FP-X (TCP/IP)	0	0				
Panasonic	FP7 Series (RS232C/422)	0	0	0	0	0	
	FP7 Series (Ethernet)	0	0				
	LP-400	0		0	0		
	KW Series	0	0	0	0	0	
	MINAS A4 series	0	0	0	0	0	
	SR-Mini (MODBUS RTU)	0	0	0	0	0	
	CB100/CB400/CB500/CB700/CB900 (MODBUS RTU)	0	0	0	0	0	
	SR-Mini (Standard Protocol)	0	0	0	0	0	
DIKE	REX-F400/F700/F900(Standard Protocol)	0	0	0	0	0	
RKC	SRV (MODBUS RTU)	0	0	0	0	0	
	MA900/MA901 (MODBUS RTU)	0	0	0	0	0	
	SRZ (MODBUS RTU)	0	0	0	0	0	
	FB100/FB400/FB900 (MODBUS RTU)	0	0	0	0	0	
	NX7/NX Plus Series (70P/700P/CCU+)	0	0	0	0	0	0
	N7/NX Series (70/700/750/CCU)		0	0	0	0	0
RS Automation	NX700 Series (Ethernet)	0	0				
	X8 Series	0	0		0		
				0	0	0	
	X8 Series (Ethernet) PCD	0	0				
SAIA	PCD S-BUS (Ethernet)	0	0	0	0	0	
	` '	0	0	_	_	_	_
SAMSUNG	N_plus	0	0	0	0	0	0
	SECNET	0	0	0	0	0	0
SANMEI	Cuty Axis	0	0	0	0	0	
SanRex	DC AUTO (HKD type)	0	0	0	0	0	
	JW series	0	0	0	0	0	0
	JW100/70H COM port	0	0	0	0	0	0
	JW20 COM port	0	0	0	0	0	0
SHARP	JW series (Ethernet)	0	0				
	JW300 series	0	0	0	0	0	0
	JW311/312/321/322 series (Ethernet)	0	0				
	JW331/332/341/342/352/362 series (Ethernet)	0	0				
SHIMADEN	SHIMADEN standard protocol	0	0	0	0	0	

Manufacturer	Models	1:1	1 : n Multi-drop	n : 1 Multi-link2	Multi-link2 Ethernet	1 : n Multi-link2 Ethernet	n : 1 Multi-link
	C Series	0	0	0	0	0	
	FC Series	0	0	0	0	0	
	GC Series	0	0	0	0	0	
	DCL-33A	0	0	0	0	0	
SHINKO TECHNOS	JCx-300 Series	0	0	0	0	0	
SHINKO LECHINOS	PC-900	0	0	0	0	0	
	PCD-33A	0	0	0	0	0	
	ACS-13A	0	0	0	0	0	
	ACD/ACR Series	0	0	0	0	0	
	WCL-13A	0	0	0	0	0	
	S5 PG port	0	0	0	0	0	
	S7	0		0	0		
	S7-200 PPI	0	0				0
	S7-200 (Ethernet ISOTCP)	0	0				
Siemens	S7-300/400 MPI	0	0				
	S7-300/400 (Ethernet ISOTCP)	0	0				
	S7-300/400 (Ethernet TCP/IP PG protocol)	0	0				
	S7-1200 (Ethernet ISOTCP)	0	0				
	TI500/505	0	0	0	0	0	
SINFONIA TECHNOLOGY	SELMART	0	0	0	0	0	0
TECO	TP-03 (MODBUS RTU)	0	0	0	0	0	-
Telemecanique	TSX Micro						0
	TTM-000	0	0	0	0	0	
ТОНО	TTM-00BT	0	0	0	0	0	
	TTM-200	0	0	0	0	0	
	T series / V series (T compatible)	0	0	0	0	0	0
	EX series	0	0	0	0	0	
	VF-S7	0	0	0	0	0	
	VF-S9	0	0	0	0	0	
	VF-S11	0	0	0	0	0	
TOSHIBA	VF-A7	0	0	0	0	0	
	VF-AS1	0	0	0	0	0	
	VF-P7	0	0	0	0	0	
	VF-PS1	0	0	0	0	0	
	VF-FS1	0	0	0	0	0	
	VF-nC1	0	0	0	0	0	
	TC200	0	0	0	0	0	
TOSHIBA MACHINE	VELCONIC series		0		0		
TURCK	BL Series Distributed I/O (MODBUS TCP/IP)	0	0				
	F340A	0	0	0	0	0	
	F371	0	0	0	0	0	
UNIPULSE	F800	0	0	0	0	0	
	F805A	0	0	0	0	0	
	F720A	0	0	0	0	0	
LINUTRONICC	M90/M91/Vision Series (ASCII)	0	0	0	0	0	
UNITRONICS	Vision Series (ASCII Ethernet TCP/IP)	0	0				
VIGOR	M series	0	0	0	0	0	
	750 series (MODBUS RTU)	0	0	0	0	0	
WAGO	750 series (MODBUS ETHERNET)	0	0				
XINJE	XC Series (MODBUS RTU)	0	0	0	0	0	
YAMAHA	RCX142	0		0	0		
	Memobus	0	0	0	0	0	
	CP9200SH/MP900	0	0	0	0	0	
	MP2000 series	0	0	0	0	0	
Yaskawa Electric	MP2300 (MODBUS TCP/IP)	0	0		<u> </u>		
	CP MP expansion memobus (UDP/IP)	0	0				
	- p			1	i i	1	I .

Manufacturer	Models	1:1	1 : n Multi-drop	n : 1 Multi-link2	Multi-link2 Ethernet	1 : n Multi-link2 Ethernet	n : 1 Multi-link
	FA-M3	0	0	0	0	0	0
	FA-M3R	0	0	0	0	0	0
	FA-M3/FA-M3R (Ethernet UDP/IP)	0	0				
	FA-M3/FA-M3R (Ethernet UDP/IP ASCII)	0	0				
	FA-M3/FA-M3R (Ethernet TCP/IP)	0	0				
	FA-M3/FA-M3R (Ethernet TCP/IP ASCII)	0	0				
	FA-M3V	0	0	0	0	0	0
	FA-M3V (Ethernet)	0	0				
Yokogawa Electric	FA-M3V(Ethernet ASCII)	0	0				
	UT100	0	0	0	0	0	
	UT750	0	0	0	0	0	
	UT550	0	0	0	0	0	
	UT520	0	0	0	0	0	
	UT350	0	0	0	0	0	
	UT320	0	0	0	0	0	
	UT2400/2800	0	0	0	0	0	
	UT450	0	0	0	0	0	
	Universal Serial	0	0				
	MODBUS RTU	0	0	0	0	0	
	MODBUS RTU EXT Format	0	0	0	0	0	
None	MODBUS TCP/IP (Ethernet)	0	0				
	MODBUS TCP/IP (Ethernet) Sub Station	0	0				
	MODBUS TCP/IP (Ethernet) EXT Format	0	0				
	MODBUS ASCII	0	0	0	0	0	

Slave Communication

Manufacturer	Models	Setting	Remarks
	Universal serial	0	
None	V-Link	0	
	Modbus slave (RTU)	0	
	Modbus slave (TCP/IP)	0	

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