

# **Digital Controller**

[1-loop motorized control type]

Type: PXH

# User's Manual

# **BEFORE USE**

Thank you very much for purchasing Fuji's digital controller (1-loop motorized valve controller).

- (1) Be sure to deliver this manual to the end user.
- (2) Be sure to read this manual and grasp the concept before operating the instrument.
- (3) The purpose of this manual is to provide detailed information on the function of the instrument. It does not guarantee that the instrument conforms to the specific purpose of the customer.
- (4) No part or the whole of this manual may be reproduced without Fuji Electric permission.
- (5) The contents of this manual may be changed without prior notice.

#### Note

Sufficient care has been taken to assure the accuracy of this manual. Please note that Fuji Electric is not responsible for any damage, including indirect damage, resulting from an error in writing, missing information, or the use of the information described in the manual.

©Fuji Electric Co., Ltd. 2006

Issued in January, 2006 Rev. 1st edition May, 2008 Rev. 2nd edition April, 2011 Rev. 3rd edition September, 2012

# PLEASE READ FIRST

# SAFETY WARNINGS

Please read the section "Safety Warnings" thoroughly before using.

Please observe the warnings stated here as they contain important safety details. The safety warning items are divided into "WARNING" and "CAUTION" categories.

<b>≜WARNING</b>	Mishandling may lead to death or serious injury.		
⚠CAUTION	Mishandling may cause injury to the user or property damage.		



#### Limitations in use

This product was developed, designed and manufactured on the premise that it would be used for general machinery. In particular, if this product is to be used for applications that require the utmost safety as described below, please take into consideration the safety of the entire system and the machine by adopting such means as a fail-safe design, a redundancy design as well as the conducting of periodical inspections.

- · Safety devices for the purpose of protecting the human body
- · Direct control of transportation equipment
- · Airplanes
- · Space equipment
- · Atomic equipment, etc,

Please do not use this product for applications which directly concern human lives.

#### **Installation and wiring**

· This equipment is intended to be used under the following conditions.

Ambient temperature	−10°C to 50°C			
Ambient humidity	90% RH or below (with no condensation)			
Installation category	II	by IEC1010-1		
Pollution level	2	by 1201010-1		

• Between the temperature sensor and the location where the voltage reaches the values described below, secure clearance space and creepage distance as shown in the table below.

If such space cannot be secured, the EN61010 safety compliance may become invalid.

Voltage used or generated	Clearance Space	Creepage Space	
by any assemblies	[mm]	[mm]	
Up to 50 Vrms or Vdc	0.2	1.2	
Up to 100 Vrms or Vdc	0.2	1.4	
Up to 150 Vrms or Vdc	0.5	1.6	
Up to 300 Vrms or Vdc	1.5	3.0	
Above 300 Vrms or Vdc	Please consult our distributor		

hazardous voltage

• For the above, if voltage exceeds 50Vdc (called danger voltage), grounding and basic insulation for all terminals of the equipment and auxiliary insulation for warning outputs are required.

Note that the insulation class for this equipment is as follows. Before installing, please confirm that the insulation class for equipment meets usage requirements.

Power source	Internal Circuit	
Digital output (Do) 1, 2	PC Loader Interface	
	Measurement value input 1 (PV1)	
Digital output (Do) 3	Measurement value input 2 (PV2)	
Digital output (Do) 4	Auxiliary analog Input 1 (Ai1) /	
Digital output (Do) 11 to 15	Valve opening feedback input (FB)	
	Output 1 (Current / SSR driver)	
Basic insulation (1500VAC)	Output 2 (Current)	
,	Digital input (DI) 1 to 4	
——— Functional insulation (500VAC)	Digital input (DI) 11 to 15	
No insulation	Transmitter power supply	
	RS485	

- · In cases where damage or problems with this equipment may lead to serious accidents, install appropriate external protective circuits.
- · As this equipment does not have a power switch or fuses, install them separately as necessary. (Main power switch: 2point Breaker, fuse rating: 250V 1A)
- · For power supply wiring, use wire equal to 600V vinyl insulation or above.
- · To prevent damage and failure of the equipment, provide the rated power voltage.
- · To prevent shock and equipment failure, do not turn the power ON until all wiring is complete.
- Before feeding power, confirm that clearance space has been secured to prevent shock and fire with the equipment.

- · Do not touch the terminal while the machine is on. Doing so risks shock or equipment errors.
- · Never disassemble, convert, modify or repair this equipment. Doing so carries the risk of abnormal operation, shock and fire.

#### Maintenance

- · When installing and removing the equipment, turn the power OFF. Failing to do so may cause shock operational errors or failures.
- · Periodic maintenance is recommended for continuous and safe use of this equipment. Some components used on this equipment have a limited life and/or may deteriorate over time.
- The warranty period for this unit (including accessories) is one year, if the product is used properly.

### **!** Caution

#### Cautions when installing

Please avoid installing in the following locations.

- · Locations in which the ambient temperature falls outside the range of -10 to 50°C when equipment is in use. (If the power supply is AC200V, the recommended maximum ambient temperature is 45°C.)
- · Locations in which the ambient humidity falls outside the range of 0 to 90% RH when equipment is in use
- · Locations with rapid temperature changes, leading to dew condensation
- · Locations with corrosive gases (especially sulfide gas, ammonia, etc.) or flammable gases
- · Locations in contact with water, oil, chemicals, steam or hot water (If the equipment gets wet, there is a risk of electric shock or fire, so have it inspected by the distributor.)
- · Locations with high concentrations of atmospheric dust, salt or iron particles
- · Locations with large inductive interference, resulting in static electricity, magnetic fields or noise
- · Locations in direct sunlight.
- · Locations that build up heat from radiant heat sources, etc.

#### Cautions when attaching the panels

· Please attach the PXH with the included Fixtures (2 pieces) to the top and bottom, and tighten with a screwdriver.

The clamp torque is approximately 0.15 N·m (1.5 kg·cm)

It is designed such that overtightening will cause left/right cracking to the central area of the Fixtures and hence reduce the torque.

Cracking to the central area will not cause any problems in terms of usability of the equipment as is. (However, do exercise caution in not applying too much torque because the casing is made of plastic.)

#### **Cautions for wire connections**

- · For thermocouple input, use the designated compensation lead; for resistance temperature sensors, use wires with small lead wire resistance and without any resistance difference among the three wires.
- To avoid noise conductor effects, do not use input signal wires in close proximity with electric power lines or load lines.
- · Use input signal lines and output signal lines that are separated from each other and are shielded.
- · If there is a lot of noise from the power source, adding an insulation transducer and using a noise filter is recommended.

(Example: TDK ZMB22R5-11 noise filter)

Always attach a noise filter to a panel that is grounded securely, and keep the wiring between the noise filter output side and the measuring equipment power terminal wiring to a minimum length. Please do not attach fuses and switches, etc. to the noise filter output wiring since doing so will decrease the filter's effectiveness.

- Twisting the measuring instrument wiring is effective when connecting the wires. (The shorter the pitch of the twist, the more effective the connection is against noise.)
- · Operation preparation time is required for the contact output when power is turned on. If using it as a signal to an external interlock circuit, please couple it with a delayed relay.
- · Concerning the output relay, connecting the maximum rated load will shorten the product's life; so please attach an auxiliary relay. If the output operation frequency is high, selecting a SSR/SSC drive output type is recommended.

[Proportionate cycles] Relay output: 30 seconds or more,

SSR/SSC drive output: 1 second or more

· When inductive loads such as magnetic opening/closing equipment, etc. as relay output equipment are connected, use of "Zetrap," manufactured by Fuji Device Technology, Co. Ltd., is recommended in order to protect the connection points against opening/closing surges and to ensure long-term use.

Model names: ENC241D-05A (For 100V power voltage) ENC471D-05A (For 200V power voltage)

#### **Others**

- · Please do not wipe the equipment with organic solvents such as alcohol or benzene, etc. If wiping is necessary, do so with a neutral cleaning agent.
- Do not use mobile phones near the instrument (within 50 cm). Otherwise malfunction may occur.

# **CONTENTS**

BEFORE USE1	1
PLEASE READ FIRST2	2
CONTENTS	3
1 OUTLINE	9 10 11
2 INSTALLATION AND WIRING  2-1 Installation site  2-2 External and panel cut dimensions  2-3 Mounting the PXH to the panel  2-4 Before wiring  2-5 Wiring	13 14 15 16
3 BASIC USAGE 3-1 Setting control template 3-2 Setting input 3-3 Selection of motorized valve type 3-4 Setting the dead band of valve operation 3-5 Calibrating the motorized valve position 3-6 Setting the indication of operation display 3-7 Reset command 3-8 Setting control parameter 3-9 Setting the set value (SV) 3-10 AT (Auto tuning) 3-11 Alarm function 3-12 Re-transmission output 3-13 Setting communications	21 27 36 38 40 43 46 48 50 52 54
4 OPERATION 7 4-1 Auto operation 7 4-2 Manual operation 7 4-3 Remote operation (SV=External set value PV2) 8 4-4 SV selection function (Remote operation) 8 4-5 Standby function 8 4-6 How to use monitoring function	76 78 30 33
5 ADVANCED USAGE 8   5-1 Setting inputs 8   5-2 Setting output 8   5-3 Setting PID 9   5-4 Setting hysteresis 9   5-5 Setting bAL, Arh, and ArL 9   5-6 Palette function 9   5-7 Key lock 9   5-8 Setting output direction at the input error burnout 9   5-9 User adjustment 9   5-10 Digital input (Di) function 9   5-11 Digital output (Do) function 1   5-12 Setting LED allocation 1   5-13 Function key 1	37 39 91 92 93 94 95 96 97 104 1104
5-14 Math function ·······	111

5-15 Remote operation	on prohibition ·····	114
5-16 Remote acknow	ledge (R-ACK) function ·····	115
5-17 Manual operatio	n prohibition ······	116
5-18 Operation mode	at the time of power ON······	117
5-19 SV tracking fund	rtion	118
	(	
5-22 EX-MV function		121
5-23 Setting 2 degree	es of freedom PID ·····	122
5-24 Setting output ty	/pe	123
5-25 Screen display s	selection function ······	124
5-26 Totalizer function	J	125
5-27 Recipe function	on	136
5-28 Linearize function	ough communications	1.44
5-29 Data Change thi	ough communications ·····	141
•		
6 TROUBLESHOOTI	NG	151
7 FREQUENTLY ASK	(ED QUESTIONS ······	
8 SPECIFICATIONS		
Appendix 1 Terminal co	onnection diagram ·····	157
Appendix 2 Parameter	list	158
9 INDEX		176

# 1 OUTLINE

Thank you very much for purchasing Fuji's digital controller (1-loop motorized valve controller). This manual describes the installation, operation, maintenance, etc. of this instrument. Read it carefully before operating the controller.

# 1-1 Code symbols

Before using the controller, check that the controller is of the type you ordered.

			1 2 3 4 5 6 7 8 9 10111213 - Digit
Digit	Description	Notes	
4	<b>Communication Contract H x W&gt;</b> 96 x 96 mm		9
5	<number control="" function="" loops="" of=""> 1-loop motorized valve controller (with valve openings feedback input) 1-loop motorized valve controller (without valve openings feedback input)</number>		D S
6	<measurement input="" value=""> Universal input: 1 point Universal input: 2 points</measurement>	*1	1 2
7	<a href="#">Auxiliary input&gt;</a> Not fitted DC voltage: 1 point		0
8	<version no.=""></version>		1
9	<output> OUT1 OUT2</output>	*2	
	Current Not fitted Current Current Current Transmitter supply		1 2 5
10	<power supply=""> 100 to 240 V AC</power>		v
11	<communication interface=""> Not fitted RS-485</communication>		0 R
12	<digital input="" output=""> Digital input Digital output (Including valve control output)</digital>	*3	
	4 points (Di1 to Di4) 2 points (Do3, Do4) 4 points (Di1 to Di4) 4 points (Do1 to Do4) 9 points (Di1 to Di4, Di11 to Di15) 9 points (Do1 to Do4, Do11 to Do15)	*1	0 A B
13	<additional specifications=""> Not fitted.</additional>		0

<sup>\*1:</sup> Universal input 2 points and "B" for the 12th digit cannot be specified at the same time. Select "universal input 2 points" when external setting input (RSV) is required.

If 2 or 3 Do points are required for event output, specify code A, and if 4 to 8 Do points are required, specify code B.

	Terminal	Do4	OUT1	OL	JT2	
	Output kind	Relay	Current (4 to 20 mA)	Current (4 to 20 mA)	Transmitter	
Code	Function *	Used for valve open/close output.	Re-transmission output	Re-transmission output	Transmitter power supply	
9th	1	0	0	_	_	
digit	2 🔾		0	0	_	
	5	0	0	_	0	

<sup>\*</sup>The selection of "Function" is specified according to the parameter.

: Not fitted: Fitted

<sup>\*2: &</sup>quot;D" for the 5th digit and "1" for the 7th digit cannot be specified at the same time.

<sup>\*3:</sup> Do4 is used as control output.

## 1-2 Checking the delivered items

Confirm that all of the following accessories are included.

Digital Controller 1 unit
Instruction Manual 1 copy
CD-ROM 1 pc.

(Contents)

**Instruction Manual** 

User's Manual

Communication Functions Instruction Manual (Modbus)

Communication Sample Program

Parameter Loader Instruction Manual

Parameter loader software

Mounting fixture 2 pcs.
Waterproof packing 1 pc.
Unit nameplate 1 pc.
Terminating resistance \*1 1 pc.

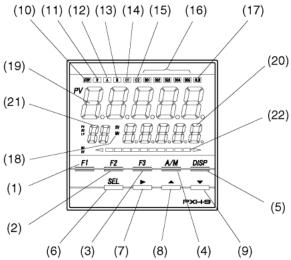
#### Option

Name	Order No.
PC loader communication cable	ZZPPXH*TK4H4563
Terminal covers *2	ZZPPXR1-B230

<sup>\*2)</sup> Two pieces are required per unit.

<sup>\*1)</sup> Supplied only when the communications function (RS485) is selected with this model.

# 1-3 Operating parts and their functions



#### Operation Part

Name	Function
(1) F1 key	Assignable by the user.
(2) F2 key	Assignable by the user.
(3) F3 key	Assignable by the user.
(4) A/M key (AUTO/MANUAL switch key)	Switches between AUTO mode and MANUAL mode
(5) DISP key (switch display key)	Switches the display between set value (SV)/control output (MV) and valve opening feedback (MVRB). Press the key to return from the setting mode to the operation mode (operation screen).
(6) SEL key (Select key)	For parameter block selection, parameter selection, and parameter setting change.
(7) ► key (Digit selection key)	Select a digit of data value for a desired setting change.
(8) ▲ key (Up key)	Increases the data value of a desired setting change. Increases the setting when the set value (SV) is displayed on the operation screen.  Manual valve operation is allowed when the control output value (MV) is displayed on the manual mode operation screen.  (An opening signal is output while the key is pressed.) Used also for channel selection, parameter selection, and parameter setting change.
(9) ▼ key (Down key)	Decreases the data value of a desired setting change. Decreases the setting when the set value (SV) is displayed on the operation screen.  Manual valve operation is allowed when the control output value (MV) is displayed on the manual mode operation screen. (A closing signal is output while the key is pressed.) Used also for channel selection, parameter selection, and parameter setting change.

(6) (4) (8	7)
Display Name	Function
(10) STBY Lamp	Lamp lights when in standby mode.
	, ,
(11) R Lamp	Lamp lights when in REMOTE mode.
(12) A Lamp	Lamp lights when in AUTO mode.
(13) M Lamp	Lamp lights when in MANUAL mode.
(14) C1 Lamp	Kept on while valve open output (OPEN) is ON.
(15) C2 Lamp	Kept on while valve close output (CLOSE) is ON.
(16) DO1 Lamp DO2 Lamp DO3 Lamp DO4 Lamp DO5 Lamp	Lamp lights when digital output 1 to output 4 (DO1 to DO4) is on. The lamp functions are assignable by the user.
(17) ALM Lamp	Lamp lights when alarm is activated.
(18) SV / MV / MVRB Lamp	Display the type of data appearing in the lower 5-digit display section. SV lights: Set value MV lights: Control output (MV) MV lights +*lights: Valve opening feedback (MVRB) MV lights +*blink: Estimated valve opening (estimated MVRB)
(19) Measurement value (PV) display	Displays measured value (PV) on the operation screen. Displays channel name when channel is selected. Displays parameter name while parameter selection/setting is in progress.
(20) Set value (SV) / control output (MV) / valve opening (MVRB) display section	Displays set value (SV), control output (MV), or valve opening feedback (MVRB) on the operation screen. Displays parameter setting while parameter selection/setting is in progress.  Display switching between control output and valve opening can be set with parameter dSPT (Ch9-78). Displays lower 5 digits of the totalized value in totalized value display.
(21) Sub-segment display	During operation:  When TPLT (ch8-92) is set at 30 or 33, the loop number is displayed.  When TPLT (ch8-92) is set at 31 or 34, the SV number is displayed.  Setting parameters:  Parameter number is displayed.  Display higher 2 digits of the totalized value in totalized value display.
(22) Bar graph display	Displays control output (MV) or valve opening feedback (MVRB) with a bar graph during operation.

# 1-4 Digital characters

The following tables provide correspondence between digital characters used for the display of the controller and alphanumerical characters.

Alphabet	Digital character	Alphabet	Digital character	Alphabet	Digital character
A	8	K	Ł	U	IJ
В	ь	L	L	V	Ū
С		M	:	W	R
D	6	N	c	X	H
Е	8	О	0	Y	y
F	٢	P	ρ	Z	کے
G	רי	Q	*		
Н	h	R	۲		
I	, ,	S	5		
J	<u>r</u>	T	١		

Numeric character	Digital character	Numeric character	Digital character
1	1	6	Б
2	5	7	7
3	3	8	8
4	Y	9	9
5	5	0	O

<sup>\*</sup> Not used by PXH.

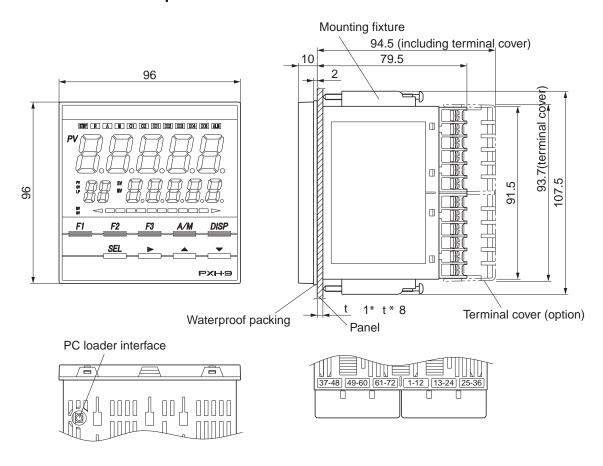
# 2INSTALLATION AND WIRING

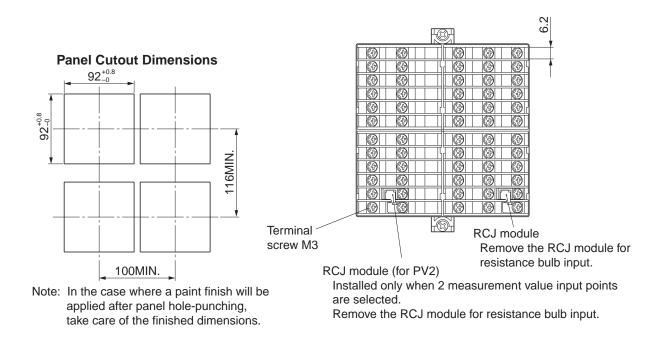
#### 2-1 Installation site

Install the controller in the following places.

- · A place where ambient temperature falls within the range from -10 to 50°C, and temperature change is minimal (We recommend you to use the controller at the ambient temperature of 45°C at the maximum if the power supply is 200V AC.).
- · A place where ambient humidity falls within the range from 0 to 90%RH, and where condensation does not occur.
- · A place where corrosive gases (such as sulfuric gas or ammonia) or inflammable gases are not generated.
- · A place where vibration or impact is not directly transferred to the main unit (The output relay may malfunction because of vibration or impact.).
- · A place not subjected to exposure to water, oil, chemicals, vapor, and steam (If water is splashed onto the controller, electrical leaks or fire may occur. Ask your distributor for maintenance in such cases.).
- · A place where accumulation of heat due to radiant heat does not occur.
- · A place where electromagnetic interference by radios or mobile phones does not occur.
- · A place where dust, salt, or iron content is minimal.
- · A place not subjected to direct sunlight.
- · A place where inductive interference is large and therefore not prone to generation of static electricity, magnetism, and noise.

# 2-2 External and panel cut dimensions

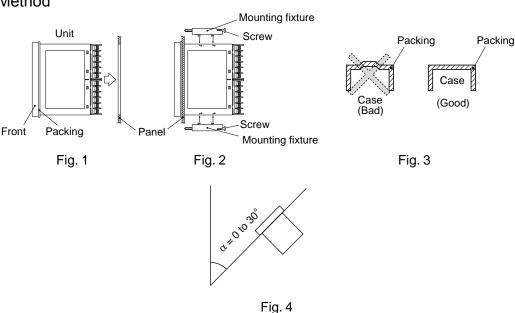




## 2-3 Mounting the PXH to the panel

- · Please attach the PXH with the included Fixtures (2 pieces) to the top and bottom, and tighten with a screwdriver.
  - The clamp torque is approximately 0.15 N·m (1.5 kg·cm)
  - (However, do exercise caution in not applying too much torque because the casing is made of plastic.)
- The front of this equipment is waterproof in compliance with NEMA-4X standards (IP66-equivalent). However, regarding waterproofing between the equipment and the panel, use the included packing to ensure waterproofing and attach it according to the guidelines below. (Incorrect attachment may cause the equipment to lose its waterproof capabilities.)
  - (1) As shown in Fig. 1, insert the panel after attaching the packing to the equipment case.
  - (2) As shown in Fig. 2, tighten the fixture screws so that no gaps can remain between the equipment face, the packing and the panels. Once finished, confirm that there are no changes in shape such as displaced or improperly-fitted packing, etc. as shown in Fig. 3.
- Please exercise caution if the panel strength is weak and gaps develop between the packing and the panel, as this will result in the loss of its waterproofing capabilities.

#### Mounting Method



Standard: vertical panel attachment (horizontal position installing) If attached at an angle, the maximum gradient is a 30° downslope.

#### (Caution)

- · In order not to hamper heat radiation, do not block the sides of the equipment.
- · Do not block the air vents on the upper part of the terminal.
- · For the PXH9, please attach the Fixtures to the attachment holes in the center of the main unit.

# 2-4 Before wiring

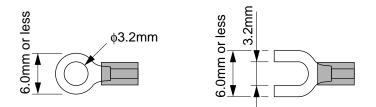
· Use wires and Crimp-style terminals of the size shown below for connection.

#### Wire size

Parts	Size
Thermocouple	1.25mm <sup>2</sup> or smaller
(Compensation wire)	
Wire	1.25mm <sup>2</sup> or smaller

#### Crimp-style terminal

Applicable wire size	Fastening torque
0.25 to 1.25mm <sup>2</sup>	0.8N·m



## 2-5 Wiring

- · For thermocouple input use the appropriate compensating cable, for resistance bulb sensors, use wires with small resistance and without any resistance difference among the three wires.
- · To avoid noise conductor effects, do not use input signal wires in close proximity with electric power lines or load lines.
- · Use input signal lines and output signal lines that are separated from each other and are shielded.
- · If there is a lot of noise from the power source, adding an insulation transducer and using a noise filter is recommended.

(Example: TDK ZMB22R5-11 noise filter)

Always attach a noise filter to a panel that is grounded securely, and keep the wiring between the noise filter output side and the measuring equipment power terminal wiring to a minimum length. Please do not attach fuses and switches, etc. to the noise filter output wiring since doing so will decrease the filter's effectiveness

- Twisting the measuring instrument wiring is effective when connecting the wires. (The shorter the pitch of the twist, the more effective the connection is against noise.)
- It takes preparation time before operation starts for the contact output when power is turned on. If using it as a signal to an external interlock circuit, please couple it with a delayed relay.
- · Concerning the output relay, connecting the maximum rated load will shorten the relay's life; so please attach an auxiliary relay. If the output operation frequency is high, selecting a SSR/SSC drive output type is recommended.

[Proportionale cycles] Relay output: 30 seconds or more,

SSR/SSC drive output: 1 second or more

· When inductive loads such as magnetic opening/closing equipment, etc. as relay output equipment are connected, use of "Zetrap," manufactured by Fuji Device Technology, Co. Ltd., is recommended in order to protect the connection points against opening/closing surges and to ensure long-term use.

Model names: ENC241D-05A (For 100V power voltage)

ENC471D-05A (For 200V power voltage)

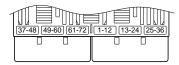
Attachment position : Please connect between the relay control output connection points. (Refer to Fig. 5.)

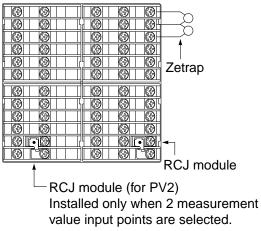
· If using a thermocouple input, make sure that an RCJ module is connected as shown in the Fig. 5. (If an RCJ module is not connected, the temperature measurement cannot function.)

To use resistance bulb input instead of thermocouple input, remove RCJ module.

Keep the removed RCJ module, and do not forget to mount it back again when input is changed.

- · Take wiring resistance into consideration when using a Zener barrier.
- · In applying mV voltage, do not remove the RCJ module.
- · It is dangerous to make an SSR connection when the output is set at 4-20mA, because the output will be kept "ON" even when the MV display shows -5%. Make sure to confirm the setting and the wiring before making the SSR connection.
- · When the transmitter power supply model is selected, the external wiring will be connected as Fig. 6.





value input points are selected.

Fig. 5 Attachement position of Zetrap and Fig. 6 Ext

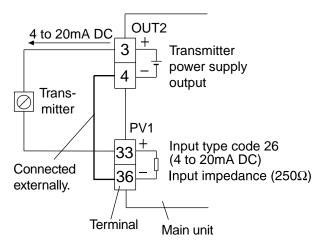
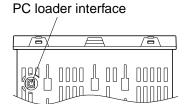


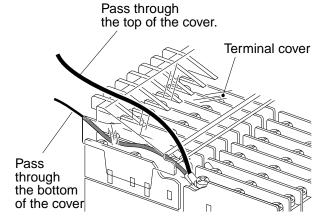
Fig. 6 External wiring for the model with the transmitter power supply.



RCJ module

 To connect the main unit to a PC, connect the optional PC loader communication cable to the PC loader interface and the serial port (RS232C) of the PC.

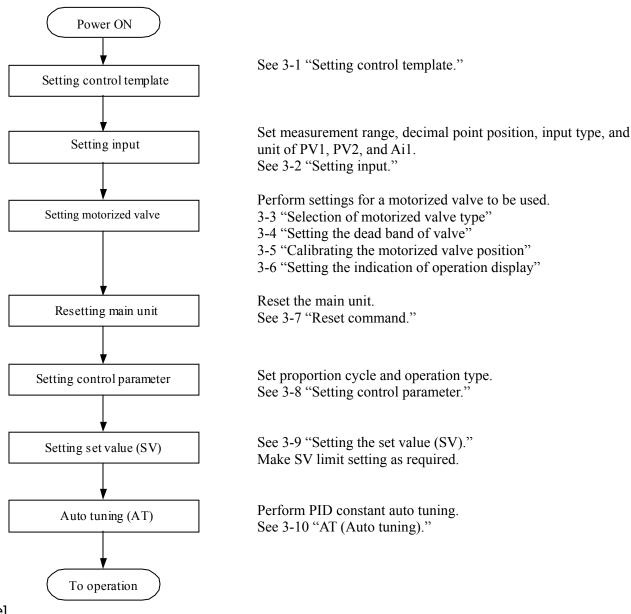
• Connection when terminal cover is used To connect 2 cables to one terminal, use cables of 1.25 mm<sup>2</sup> or smaller in diameter, and make connections as shown by the figure at right.



# $oldsymbol{3}$ BASIC USAGE

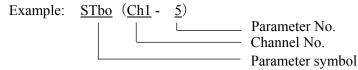
Basic settings required in the flow from power ON to the start of operation are shown below. See the next page for basic key operations.

#### Setting procedure

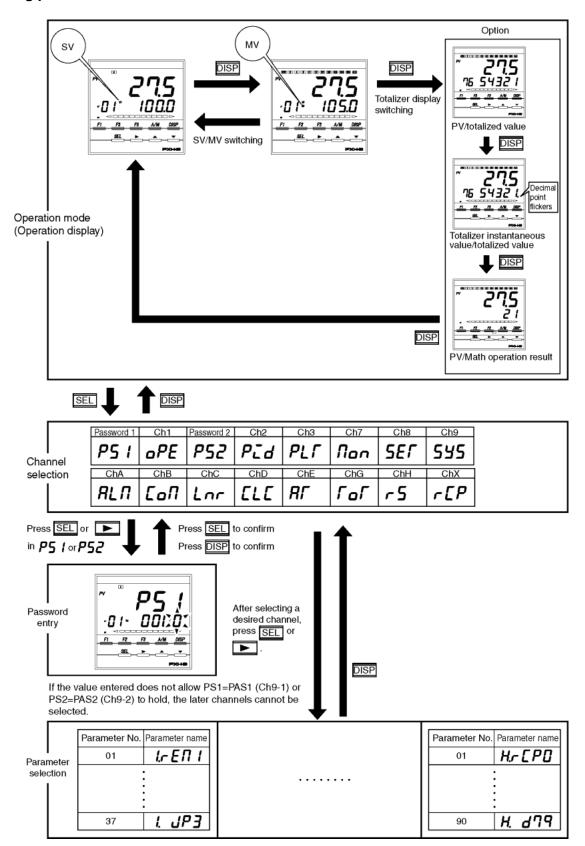


#### [Note]

- \* To enable the setting of [rEv1] of Ch2, Ch9, ChB, and Ch8 that has been registered, reset the controller or turn on the power again.
- \* If key operation is not performed for 10 seconds under the condition where the setting is flickering in setting change mode, the value being changed is canceled.
- \* This instrument is not provided with the function of automatically returning to the operation screen when no operation status is continued. Return to the operation screen manually.
- \* Parameters in the text are expressed as shown below



#### **Switching parameters**



<sup>\*</sup>See appended parameter list.

## 3-1 Setting control template

FPLF Specifying control template (Setting range: 30, 31 33, 34)

#### [Description]

· Specify control templates.

TPLT	Control template	SV selection	Math function	
30	Single-loop motorized valve control (with Math function)	_	0	
31	Single-loop SV selectable motorized valve control (with Math function)	0	0	
33	Single-loop motorized valve control	_	_	<fa< td=""></fa<>
34	Single-loop SV selectable motorized valve control	0	_	

<Factory set>

· Each template is provided with an input conditioner function.

Input conditioner function allows the following four operations.

- (1) User adjustment
- (2) Square root extraction
- (3) Input filter
- (4) Linearize
- · Math function can be selected for templates No.30 and No.31, and SV selection can be selected for templates No.31 and No.34. See the template chart on the next page for details.
- \* See 5-14 "Math function" for Math function.

See 4-4 "SV selection" for SV selection function.

[Setting example] Setting the template to be used to 31. —

# Operation procedure Display 1. Check that the operation display is shown. •**8**1 Operation display 2. Press the SEL key, and the channel selection display appears, displaying P5 1. Channel selection display 3. Press the $\bigcirc$ key to display 8 5 $\varepsilon\Gamma$ . Channel selection display Press the SEL or the key, and 8.P 5 1F appears and the parameter selection display is shown 4000 Parameter selection display 5. Press the key to display 8.5 PL 5. Parameter selection display Press the SEL or the Wey to make the setting flicker, and set the value to 0003 t using the $\bigcirc$ , $\bigcirc$ or the $\bigcirc$ key. Setting change mode 7. Press the SEL key to register the setting. Parameter selection display 8. Press the DISP key once to return to the parameter selection display. Press it again to return to the operation display. Operation display

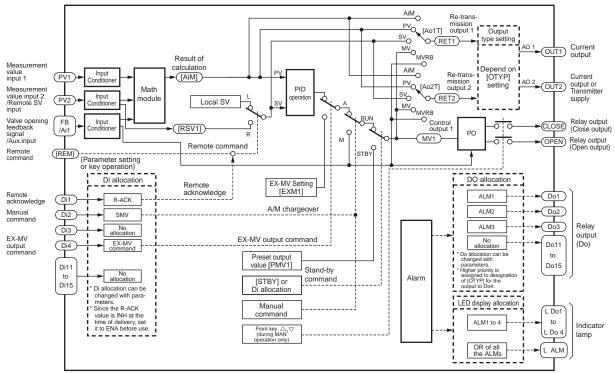
### **FPL** = 30 1-loop motorized valve controller (with Math function)

Contents of input conditioner

- · User adjustment
- · Square root extractions
- · Input filter
- · Linarize
- 1 The value obtained by calculating the input value for PV1, PV2, and Ai1 can be controlled as PV. < Practical operations >
  - · Flow rate/compensation with temperature and Pressure
- · Averaging (Weighting allowed)
- · Maximum/minimum selector
- · Input signal switching
- · Calorie calcuration

(See section 5-14 for details of arithmetic expressions.)

2 The same as Template No.33 except for Math function. Note) A scale setting [UCF1, UCB1, UCD1 (ch8-89 to 91)] must be made in accordance with the range resulting from the Math function.



<sup>\*</sup> Valve opening feedback input is used for the type of 5th digit "D" in CODE SYMBOLS.

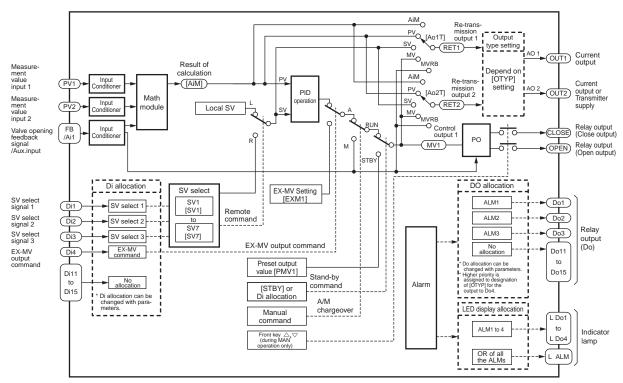
# 1-loop SV selectable motorized valve controller (with Math function)

- 1 The template is used to perform Math function with PV1, PV2, and Ai1 in SV selectable type control. (See item 1 in template No.30 for Math function.)
- The same as template No.34 except for the Math function.

  Note) Scale setting [UCF1, UCB1, UCD1 (ch8-89 to 91)] must be made in accordance with the range resulting from the Math function.

SV selection signal and SV number to be selected

ev colocion olgitar and ev mamber to be colociou			
Selection SV No.	SV selection Signal 1	SV selection Signal 2	SV selection Signal 3
Local SV	OFF	OFF	OFF
SV1	ON	OFF	OFF
SV2	OFF	ON	OFF
SV3	ON	ON	OFF
SV4	OFF	OFF	ON
SV5	ON	OFF	ON
SV6	OFF	ON	ON
SV7	ON	ON	ON

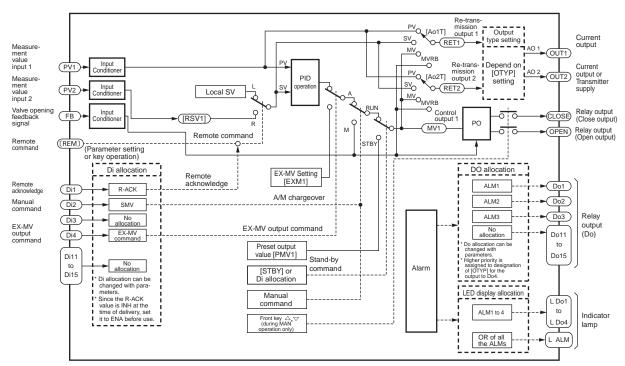


<sup>\*</sup> Valve opening feedback input is used for the type of 5th digit "D" in CODE SYMBOLS.

### Image: Text of t

Contents of input conditioner

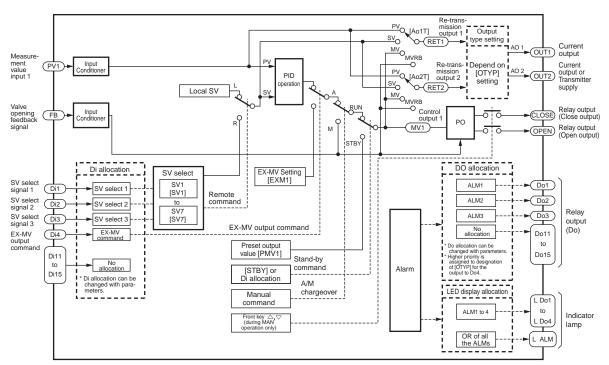
- · User adjustment
- · Square root extractions
- · Input filter
- · Linarize
- 1 This is the most basic control template.
- 2 Control is allowed in an Auto/Manual/Remote operation mode and by digital input.
- 3 Set the re-transmission output with a parameter [Ao1T, Ao2T].
- 4 By changing the digital input (Di) allocations, a standby operation, etc. can be performed. (See section 5-10 for details.)
- 5 Digital ouitput (Do) and LED lamp allocations can be changed. (See section 5-11 for details.)



\* Valve opening feedback input is used for the type of 5th digit "D" in CODE SYMBOLS.

### 「PL「 =34 1-loop SV selectable motorized valve controller

- 1 Setting value (SV) can be selected by digital inputs. The SV can be selected from the local (front panel) setting value and 7 pairs of palette setting values (SV of ch3), 8 points in total.
- 2 PID parameters can be switched according to the SV. (Set parameter [PLTS] (ch9-31) to "SV".) (See section 5-16 for details.)
- 3 Set the transfer output with a parameter [Ao1T, Ao2T].
- 4 By changing the allocation of the digital input (Di), a standby operation, etc. can be performed. (See section 5-10 for details.)
- 5 Digital output (Do) and LED lamp allocations can be changed. (See section 5-11 for details.)
- · SV selection signals and selected SV Numbers are the same as those of template No.31.



<sup>\*</sup> Valve opening feedback input is used for the type of 5th digit "D" in CODE SYMBOLS.

## 3-2 Setting input

Make the setting of each input of PV1, PV2, and Ai1. Parameters you have to make the setting are shown below.

#### <PV1 input>

Parar	neter symbol	Meaning
Pū IF	Pv1F (Ch8-1)	Measurement value input (PV1) full scale setting
PJ 16	Pv1b (Ch8-2)	Measurement value input (PV1) base scale setting
Pឆ Id	Pv1d (Ch8-3)	Measurement value input (PV1) decimal point position setting
ខ្លារ	Pv1T (Ch8-4)	Measurement value input (PV1) input type setting
₽ឆ ប	Pv1U (Ch8-5)	Measurement value input (PV1) unit setting

#### <PV2 input>

Parameter symbol		Meaning
P52F	Pv2F (Ch8-14)	Measurement value input (PV2) full scale setting
P526	Pv2b (Ch8-15)	Measurement value input (PV2) base scale setting
P528	Pv2d (Ch8-16)	Measurement value input (PV2) decimal point position setting
PSZF	Pv2T (Ch8-17)	Measurement value input (PV2) input type setting
Pū≥U	Pv2U (Ch8-18)	Measurement value input (PV2) unit setting

#### <Ail input>

Param	eter symbol	Meaning
AC IF AC Ib	Ai1F (Ch8-40) Ai1b (Ch8-41)	Analog input (Ai1) full scale setting Analog input (Ai1) base scale setting
85 IF	Ai1d (Ch8-42) Ai1T (Ch8-43)	Analog input (Ai1) decimal point position setting Analog input (Ai1) input type setting

· Subsequent descriptions are given with PV1 taken as example. To use PV2 or Ai1, check the above parameter symbols, and make the setting, following the same procedure.

#### Note

- (1) Do not change the setting of Ai1 in the case of "with valve opening input" Type ("D" for the 5th digit in CODE SYMBOLS).

  Analog auxiliary input (Ai1) is used for valve opening feedback.
- (2) To enable the setting, reset the main unit. See 3-7 "Reset command" for resetting procedure. Check whether the setting has been enabled with the display and parameter setting on the operation screen.

PJ IF

Measurement value input (PV1) full scale (Setting range: -19999 to 99999)

Р5 16

Measurement value input (PV1) base scale (Setting range: -19999 to 99999)

#### [Description]

- · Set the upper limit PV1F (Ch8-1) and the lower limit PV1b (Ch8-2) of the measurement range.
- · Select decimal point position with Pv1d (Ch8-3), and input type with Pv1T (Ch8-4).
- · See the following table for details of input range.
- · To use Pv2 and Ai1, set Pv2F (Ch8-14), Pv2b (Ch8-15), Ai1F (Ch8-40), and Ai1b (Ch8-41), following the same procedure.

Input Type		Measurement Range (°C)	Measurement Range (°F)
	Pt100Ω	0 to 150	32 to 302
		0 to 300	32 to 572
Resistance bulb (RTD) IEC		0 to 500	32 to 932
		0 to 600	32 to 1112
		-50 to 100	-58 to 212
		-100 to 200	-148 to 392
		-150 to 600	-238 to 1112
		-150 to 850	-238 to 1562

• To use Zener barrier for RTD input, user adjustment (section 5-9) is required.

Note 1)

R thermocouple 0 to 500°C B thermocouple 0 to 400°C

Proper values may not be displayed within these ranges due to the sensor's characteristics.

Note 2) When using at the settings below the minimum range stated in the table above, the input accuracy is not guaranteed.

Note 3) In the -50%FS to +50%FS display, values under -199.99 will not be displayed.

Input Type		Measurement Range (°C)	Measurement Range (°F)
	J	0 to 400	32 to 752
	J	0 to 1000	32 to 1832
	K	0 to 400	32 to 752
	K	0 to 800	32 to 1472
	K	0 to 1200	32 to 2192
	R	0 to 1600	32 to 2912
	В	0 to 1800	32 to 3272
Thermocouple	S	0 to 1600	32 to 2912
	Т	-200 to 200	-328 to 392
	Т	-200 to 400	-328 to 752
	E	0 to 800	32 to 1472
	E	-200 to 800	-328 to 1472
	PR40/20	0 to 1800	32 to 3272
	N	0 to 1300	32 to 2372
	PL-II	0 to 1300	32 to 2372
	WRe5-26	0 to 2300	32 to 4172
	1 to 5V DC		
	0 to 5V DC		
DC voltage	0 to 10V DC	10000	00000
	0 to 10mV DC	-19999 t	
	0 to 50mV DC	(Scaling is possible)	
DC accomment	4 to 20mA DC		
DC current	0 to 20mA DC		

#### Note

• To enable the setting, reset the main unit. See section 3-7 "Reset command" for resetting procedure.

Check whether the setting has been enabled with the display and parameter setting on the operation screen.

#### [Setting example] Changing scale to "0 to 800" ——

Display	Operation procedure
Pr 27.8 D.D Operation display	1. Check that the operation display is shown.
<b>P5</b> (	2. Press the SEL key, and the channel selection display appears, displaying P5 1.
Channel selection display  F*B**  5EF	3. Press the $\bigcirc$ key to display 8 5EF.
Channel selection display	4. Press the SEL or the key, and 8.Pū IF appears and the parameter selection display is shown.
Parameter selection display	5. Press the SEL or the b key to make the setting flicker, and set the value to \$\mathcal{O}8000\$ using the b, c, or the key.
Setting change mode	6. Press the SEL key to register the setting.
Parameter selection display  Parameter selection display  Parameter selection display	7. Press the DISP key once to return to the parameter selection display. Press it again to return to the operation display.

#### Note

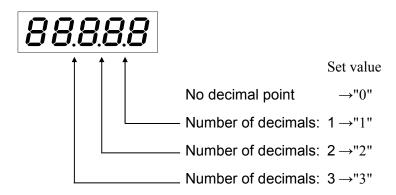
· To enable the setting, reset the main unit. See section 3-7 "Reset command" for resetting procedure. Check whether the setting has been enabled with the display and parameter setting on the operation screen.

الما توع

Measurement value input (PV1) decimal point position (Setting range: 0 to 3)

#### [Description]

· Select the decimal point position of the measurement input value (PV1).



· To use PV2 or Ai1, set Pv2d (Ch8-16) or Ai1d (Ch8-42), following the same procedure.

#### Note

· To enable the setting, reset the main unit. See section 3-7 "Reset command" for resetting procedure. Check whether the setting has been enabled with the display and parameter setting on the operation screen.

#### [Setting example] Selecting 2 decimal places –

# Display Operation procedure 1. Check that the operation display is shown. ·8 ( Operation display 2. Press the SEL key, and the channel selection display appears, displaying P51. Channel selection display 3. Press the $\bigcirc$ key to display 8 5 $\varepsilon\Gamma$ . Channel selection display 4. Press the SEL or the key, and 8.P 5 1F appears and the parameter selection display is shown. Parameter selection display 5. Press the key to display 8.95 ld. Parameter selection display 6. Press the SEL or the key to make the setting flicker, and set the value to 00002 using the $\bigcirc$ , $\bigcirc$ , or the $\bigcirc$ key. Setting change mode Press the SEL key to register the setting. Parameter selection display 8. Press the DISP key once to return to the parameter selection display. Press it again to return to the operation display. Operation display

PJ IF

Setting input type of measurement value input (PV1) (Setting range: 0 to 27)

#### [Description]

- · Specify input type.
- · See the following table for details of input type and setting (input code).

Input Type	Code
Resistance bulb	
• Pt100Ω (IEC)	1
Thermocouple	
• J	2
• K	3
• R	4
•B	5
•S	6
•T	7
•E	8
• PR40/20	9

Input Type	Code
• N • PL-II • WRe5-26	12 13 14
DC voltage	
1 to 5V DC     0 to 5V DC     0 to 10V DC     0 to 10mV DC     0 to 50mV DC	16 17 18 19 20
DC current	
• 4 to 20mA DC • 0 to 20mA DC	26 27
Potentiometer	
Valve opening feedback     (with moving average filter)	23
Valve opening feedback	24

<sup>\*</sup>For Ai1, only DC voltage (code 16 to 18) and Potentiometer (code 23, 24) settings are possible.

· To use PV2 or Ai1, set Pv2T (Ch8-17) and Potentiometer (code 23, 24)or Ai1T (Ch8-43), following the same procedure.

(Ai1T setting range is 16 to 18, 23 and 24.)

- Note 1. For PV1, and PV2, the potentiometer code ("23", "24") can not be selected.
- Note 2. If the model with valve opening feedback (code "D" for the 5th digit in CODE SYMBOLS), Ail can be set to potentiometer code ("22", "24") only.
  - · If the model without valve opening feedback (code "S" for the 5th digit in CODE SYMBOLS), Ail can be set to DC current code ("16 to 18") only.
- Note 3. If, on account of noise, etc., the valve opening feedback input suffers from an abrupt change, select Ai1T = 23 (with moving average filter).

#### [Setting example] Selecting thermocouple J input-

## Display Operation procedure 1. Check that the operation display is shown. •**8**1 Operation display 2. Press the SEL key, and the channel selection display appears, displaying P51. Channel selection display 3. Press the $\bigcirc$ key to display 8 5 $\varepsilon\Gamma$ . Channel selection display 4. Press the SEL or the key, and 8.P is appears and the parameter selection display is shown. Parameter selection display 5. Press the key to display 8.P J If . Parameter selection display 6. Press the SEL or the key to make the setting flicker, and set the value to 00002 using the $\bigcirc$ , $\bigcirc$ , or the $\bigcirc$ key. 03 00002 Setting change mode 7. Press the SEL key to register the setting. Parameter selection display 8. Press the DISP key once to return to the parameter selection display. Press it again to return to the operation display. Operation display

רה ה

Selecting the unit of measurement value input (PV1) (Setting range: non, °F, °C)

### [Description]

· Select a measurement unit from the following.

non: No unit
°F: °F unit
°C: °C unit

· To use PV2, set Pv2U (Ch8-18), following the same procedure.

#### [Setting example] Changing the unit from °C to non —

# Operation procedure Display Check that the operation display is shown. · [] { Operation display 2. Press the SEL key, and the channel selection display appears, displaying P51. Channel selection display 3. Press the $\bigcirc$ key to display 8 5 $\varepsilon\Gamma$ . Channel selection display 4. Press the SEL or the key, and 8.P 5 1F appears and the parameter selection display is shown. Parameter selection display 5. Press the key to display 8.95 IU. Parameter selection display 6. Press the SEL or the key to make the setting flicker, and set the value to $\bigcirc$ using the $\bigcirc$ , $\bigcirc$ , or the $\bigcirc$ key. ροη Setting change mode Press the SEL key to register the setting. ngn Parameter selection display 8. Press the DISP key once to return to the parameter selection display. Press it again to return to the operation display. Operation display

## 3-3 Selection of motorized valve type

JFYP

Selecting the motorized valve control type (Setting range: Fb, Fb-Sr, Sr1, Sr2)

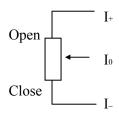
#### [Description]

• The motorized valve control type can be selected from 4 types below.

Setting value	Control type	
Fb	PFB control	
Fb-Sr	PFB + estimation control	
Sr1	Estimation control 1	
Sr2	Estimation control 2 (turning on power closes the all the way)	

- (1) PFB control [Position Feed Back control] (Valve opening input is required)
  - · OPEN or CLOSE signal is output so that the valve opening feedback value (MVRB) will correspond to operation output (MV).
  - · If MVRB input is abnormal, the operation is as given in the following table.

Anomaly	MVRB indication	Operation at error
I- line open-circuited	UUUU	As if MVRB = 105%
I <sub>+</sub> line open-circuited	LLLL	As if MVRB = $-5\%$
I <sub>-</sub> I <sub>0</sub> line short-circuited	UUUU	As if MVRB = 105%
I <sub>+</sub> I <sub>0</sub> line short-circuited	LLLL	As if MVRB = $-5\%$
I <sub>+</sub> I <sub>0</sub> I <sub>-</sub> line short-circuited	LLLL	As if MVRB = $-5\%$



- (2) PFB + estimation control (Valve opening input is required)
  - · The estimation control is automatically posted when the valve opening feedback value (MVRB) has become abnormal.
  - The estimation control refers to valve position control without valve opening feedback value (MVRB) upon estimation of valve position.
  - · If under valve position estimation control, CLOSE or OPEN signal is delivered according to whether operation output  $(MV) \le 0$  or  $\ge 100$ , respectively, for correcting the estimated position.
  - · If under valve position estimation control, the estimated position of valve appears on MVRB display (operation display, monitor).
- (3) Estimation control 1
  - · The valve position is controlled without using valve opening feedback value (MVRB) at all.
  - · If under estimation control, CLOSE or OPEN signal is delivered according to whether operation output  $(MV) \le 0$  or  $\ge 100$ , respectively, for correcting the estimated position.
  - · The valve opening feedback input, even if connected, is not used.
- (4) Estimation control 2
  - The control starts when the valve is completely closed at the time of power on.

    (The time during which CLOSE signal is delivered after turning on power depends on the time required for the valve to complete the full stroke.)
  - The control method is the same as estimation control 1 above.

#### [Note]

- 1) In the case of estimation control, the estimated valve position may be different from the actual valve position. If you use a motorized valve with valve opening feedback, a control by PFB control method (VTYP = FB) is recommended.
- 2) If you use a type with "S" (without valve opening input) for the 5th digit in the CODE SYMBOLS, a selection of "Fb" or "Fb-Sr" will not provide a normal operation.

## 

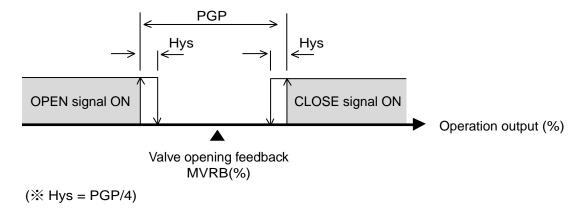
Display	Operation procedure		
PV Z78 -81" B.B  Operation display	1. Check that the operation display is shown.		
P5 (DDDD)  Channel selection display	2. Press the SEL key, and the channel selection display appears, displaying P51.		
FF PFL Channel selection display	3. Press the key to display F PFb.		
FIF 4P  U: Fb  Setting change mode	4. Press the SEL or the key, and Figgs appears, and the parameter selection display is shown.		
FIFE-5.	5. Press the SEL or the key to make the setting flicker, and set the value to Fb-5r using the key.		
FIFE-5. Setting change mode	6. Press the SEL key to register the setting.		
Properation display	7. Press the DISP key once to return to the parameter selection display. Press it again to return to the operation display.		

## 3-4 Setting the dead band of valve operation

Set the dead band of OPEN, and CLOSE signals for valve operation(Setting range: 0.5 to 100.0%)

### [Description]

You can set a dead band where neither OPEN nor CLOSE signal is output.
 A dead band for valve operation prevents the valve from hunting, thereby improving the output stability.



#### [Note]

- · Selecting a smaller dead band will make the valve movement more frequent, thereby making its life shorter. Select an appropriate value according to a control result.
- · The hysteresis (Hys) of OPEN, and CLOSE signal is fixed at 1/4 of dead band of valve operation (PGP).

## [Setting example] Changing the dead band of valve operation from 10.0% to 5.0%—

Display	Operation procedure
· 0 1 " 2 7 8 0.0	1. Check that the operation display is shown.
Operation display	2. Press the SEL key, and the channel selection display appears, displaying P51.
Channel selection display	3. Press the key to display F PFb.
Channel selection display	4. Press the SEL or the key, and F.J. YP appears, and the parameter selection display is shown.
Setting change mode	5. Press the key to display F. PGP.
Setting change mode	6. Press the SEL or the key to make the setting flicker, and set the value to 00050 using the key, or the key.
Setting change mode	7. Press the SEL key to register the setting.
Setting change mode  PV 278 0.0  Operation display	8. Press the DISP key once to return to the parameter selection display. Press it again to return to the operation display.

## 3-5 Calibrating the motorized valve position

רֹבּי Travel time (Setting range: 5.0 to 300.0 sec)

Ratic | Calibration valve at which valve is fully closed (Setting range: 0 to FFFFF)

Raūa Calibration value at which valve is fully open (Setting range: 0 to FFFF)

 LBL b
 Valve calibration command (Setting range: OFF, CLOSE, OPEN, AUTO)

## [Description]

#### Setting the travel time

- TrVL (ChF-2) parameter is used for estimation control (valve position estimation control). Unless TrVL parameter is correctly set, the estimation control will not be correct. Correctly set the full stroke time from fully closing to fully opening of your motorized valve.
- · If automatic calibration of valve is performed, the full stroke time will automatically be set at the end of the calibration.

#### Motorized valve position calibration

• The motorized valve can be calibrated automatically or manually.

The calibration is made upon setting CALb (ChF-8) parameter as shown in the following table.

Setting	Procedure		
OFF	Normal/forced termination of calibration		
CLOSE	Manual calibration of fully closed position		
OPEN	Manual calibration of fully open position		
AUTO	Automatic calibration		

#### (1) Method of automatic calibration

Allowing the valve to operate automatically, acquire the fully closed value (AdVC), fully open value (AdVO), and travel time (TrVL).

#### 1) Operation method

Set CALb (ChF-8) to AUTO.

- · When the automatic calibration terminates properly, CALb = OFF will be resumed automatically.
- · When the automatic calibration terminates abnormally, CALb = Err will appear. (For when the automatic calibration terminates abnormally, see "When calibration error occurs" below.)
- · To quit the automatic calibration, set CALb to OFF.

#### 2) Procedure of automatic calibration

a. This instrument keeps CLOSE signal output until valve closes all the way to acquire completely closed value.



b. This instrument keeps OPEN signal output until valve opens all the way to acquire completely open value.



c. All the calibration values are stored if completely calibration has terminated properly.

#### 3) Precautions

- · If the automatic calibration has terminated abnormally, any values will not be changed. (After normal termination, data will automatically be stored in EEPROM.)
- In the case of estimation control 1 (VTYP = Sr1) or estimation control 2 (VTYP = Sr2), the automatic calibration is impossible (because CALb = OFF).

#### 4) When calibration error occurs

- · Calibration value span (AdVO-AdVC) < 256
- · Calibration value for closing (AdVC) > calibration value for opening (AdVO)
- · PFB burnout occurred
- · 360 seconds elapsed without terminating the automatic calibration
- · TrVL time beyond 5 to 300 seconds
- · PV input burnout occured

#### (2) Method of manual calibration

Manually operate the valve to acquire the completely closed position (AdVC), and completely open control (AdVO).

(For method of manually operating the valve, see section 4-2 "Manual operation".)

#### 1) Operation method

- a. Adjustment of completely closed position
- · Completely close the valve, and set CALb to CLOSE.
- · After the end of calibration, CALb = OFF will be resumed automatically.
- b. Adjustment of completely open position
- · Completely open the valve, and set CALb to OPEN.
- · After the end of calibration, CALb = OFF will be resumed automatically.

#### 2) Precautions

· At a manual calibration, the calibration span error [(AdVO-AdVC) < 256] will not be checked.

After the end of manual calibration, make sure (AdVO-AdVC) < 256 is not the case.

At a manual calibration, the travel time (TrVL) will not be set automatically.
 Accurately set the full stroke time to match a particular valve.
 (Travel time need not be set for PFB control, parameter VTYP = Fb.)

## [Setting example] Performing the automatic calibration of the valve position—

Display	Operation procedure		
· 0 1 * 0.0	1. Check that the operation display is shown.		
Operation display  P5 (	2. Press the SEL key, and the channel selection display appears, displaying P5!.		
Channel selection display	3. Press the  key to display F PFb.		
Channel selection display	4. Press the SEL or the key, and F.J. SP appears, and the parameter selection display is shown.		
Setting change mode	5. Press the \to key to display F.E.RLb.		
Setting change mode	6. Press the SEL or the key to make the setting flicker, and set the value to <code>RUFo</code> using the key.		
Setting change mode	7. Press the SEL key to register the setting.		
Setting change mode  Py 278  Operation display	8. Press the DISP key once to return to the parameter selection display. Press it again to return to the operation display.		

# 3-6 Setting the indication of operation display

**とっこ** Selecting the bar graph indication type (Setting range: NON, MV, MVRB)

Setting the indication type for operation display (Setting range: 0,1)

### [Description]

### Bar graph indication type, brG1 (Ch9-76)

· You can select data to display as bar graph from the following table.

Setting	Bar graph display value		
NON	No display		
MV	Control output (MV)		
MVRB	Valve opening feedback value (MVRB)		

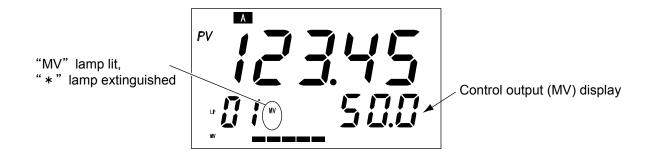
### Operation display indication type, dSPT (Ch9-78)

· You can select data to indicate in the 5th digit on the lower stage (SV/MV display section) of the operation display from the following table.

Setting	Description of MV on the lower stage indication
0	Control output (MV)
1	Valve opening feedback value (MVRB)

#### In the case of dSPT = 0

When SV/MV status lamp "MV" is lit, the operation display indicates PV (measurement value) on the upper stage, and MV (control output) on the lower stage.



#### In the case of dSPT = 1

When SV/MV status lamp "MV" is lit, the operation display indicates PV (measurement value) on the upper stage, and MVRB (valve opening feedback) on the lower stage.

MVRB display is in 2 ways below according to valve control status.

<In the case of PFB input is used for valve control>
[Condition]

- $\cdot VTYP = Fb$
- $\cdot VTYP = Fb-Sr$

#### [Display]

Actual valve opening feedback input is displayed.



<In the case of estimated value is used for valve control>
[Condition]

- $\cdot$  VTYP = Sr1 or Sr2
- · VTYP = Fb–Sr, estimation control being under way

#### [Display]

An estimated opening (calculated value) of valve is displayed.



### [Setting example] Changing the operation display type from 0 (MV) to 1 (MVRB) —

# Display Operation procedure 1. Check that the operation display is shown. Operation display 2. Press the SEL key, and the channel selection display appears, displaying P51. Channel selection display 3. Channel selection display 4. Press the SEL or the key, and 9.P85 t appears, and the parameter selection display is shown. Setting change mode 5. Press the key to display 3.45Pr. Setting change mode 6. Press the SEL or the key to make the setting flicker, and set the value to OOOO using the $\bigcirc$ key. 78 <u>,</u>0000 ( Setting change mode Press the SEL key to register the setting. Setting change mode 8. Press the DISP key once to return to the parameter selection display. Press it again to return to the operation display. Operation display

## 3-7 Reset command

**r £ 5** Resetting the main unit (Setting range: ON, OFF)

## [Description]

- · Selecting ON to reset the main unit.
- · To enable parameters selected for Ch8, Ch9, ChB, and Ch2 (rEv1), reset the main unit or turn on the power again.

### [Setting example] Resetting-

# Display Operation procedure Check that the operation display is shown. Operation display Press the SEL key, and the channel selection display appears, displaying P51. Channel selection display 3. Press the key to display 9 545. Channel selection display Press the SEL or the key, and 9.P85! appears and the 4. parameter selection display is shown. 0000 Parameter selection display 5. Parameter selection display Press the SEL or the key to make the setting flicker, and set the value to $o_0$ using the $\bigcirc$ , $\bigcirc$ , or the $\bigcirc$ key. $\rho \alpha$ Setting change mode Press the SEL key to register the setting. Parameter selection display "WAIT RESET" appears and the bar graph comes on. After resetting is completed, the operation display automatically appears. \* Resetting takes approx. 10 seconds. Operation display

## 3-8 Setting control parameter

ー と こ ! Control action type (Setting range: NRML, REV)

### [Description]

· There are two control action types. One is normal (direct) action, and the other is reverse action.

NRML (Normal (direct) action): If measurement value (PV) becomes larger than the set value (SV),

control output becomes larger.

REV (Reverse action): If measurement value (PV) becomes smaller than the set value (SV),

control output becomes larger.

Control action type	Application
NRML (Normal action)	Cooling control
REV (Reverse action)	Heating control

## [Setting example] Changing control action type from REV to NRML—

# Display Operation procedure Check that the operation display is shown. Operation display Press the SEL key, and the channel selection display appears, displaying P51. Channel selection display 3. Press the key to display 2 PCd. Channel selection display Press the SEL or the key, and 2. P! appears and the 4. parameter selection display is shown. Parameter selection display Press the | key to display 2. Fū!. Parameter selection display Press the SEL or the key to make the setting flicker, and set the value to $\alpha \in \mathbb{N}$ using the $\square$ , $\square$ , or the $\square$ key. Setting change mode Press the SEL key to register the setting. Parameter selection display Press the DISP key once to return to the parameter selection display. Press it again to return to the operation display. Operation display

# 3-9 Setting the set value (SV)

## Setting the set value (SV)

## [Description]

- · Set value (SV) is the target value of the control.
- The upper limit value and the lower limit value of the setting can be set with Sh1 (Ch2-7) and SL1 (Ch2-8).

[Setting example] Changing the set value (SV) from 0.0°C to 60.0°C —

Display	Operation procedure		
Pv Z78 D.D Operation display	<b>1</b> . Check that "SV <b>[]</b> [] " is shown on the operation display.		
<i>" 278 " 1" 11 15 10 10 10 10 10 10 10 10 10 10 10 10 10 </i>	<ul> <li>2. Press the  key to make the SV flicker.</li> <li>3. Set the SV value to  using the , , or the key.</li> </ul>		
Pr 278 200 Soperation display	<ul> <li>4. Press the SEL key to complete the operation.</li> <li>* If the [DISP] key is pressed while the setting is flickering, or no operation status continues for 10 seconds or longer, the value being changed is canceled.</li> <li>* The SV can also be changed without making the value flicker by pressing the key. Just change the value using the or the key.</li> </ul>		

## [Note]

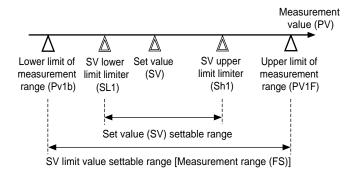
· Setting value (SV) can not be changed during Ramp/soak operation.

**5h** / SV upper limit value (Setting range: –25 to 125%FS)

5L / SV lower limit value (Setting range: –25 to 125%FS)

### [Description]

- · Set the settable range of set value (SV).
- The SV upper and lower limit values, Sh1 (Ch2-7) and SL1 (Ch2-8), can be set within the range of Pv1 scale from Pv1F (Ch8-1) to Pv1b (Ch8-2). (See the following figure.)



### [Note]

- · Be sure to set the following parameters before setting Sh1 (Ch2-7) and SL1 (Ch2-8) parameters.
  - · Measurement range upper limit setting Pv1F (Ch8-1)
  - · Measurement range lower limit setting Pv1b (Ch8-2)
  - · Decimal point position Pv1d (Ch8-3)
  - · After changing Pv1F (Ch8-1), Pv1b (Ch8-2), and Pv1d (Ch8-3) parameters, reset the controller, and then set Sh1 (Ch2-7) and SL1 (Ch2-8) parameters.
  - · Set the limit values so that Sh1 (Ch2-7) becomes equal or larger than SL1 (Ch2-8).

## 3-10 AT (Auto tuning)

Auto tuning function (Setting range: OFF, ON1)

**RFP**: Setting auto tuning method (Setting range:NRML, LPV)

### [Description]

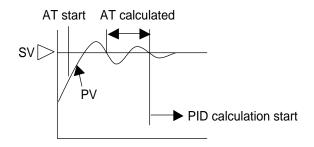
- The controller automatically measures, calculates, and sets PID constant, which is called auto tuning. Perform auto tuning after setting of input range (Pv1F (Ch8-1), Pv1b (Ch8-2), Pv1d (Ch8-3)), set value (SV), and proportion cycle TC1 (Ch2-19) is completed.
- · When auto tuning is normally completed, the automatically set PID parameter value is maintained even if the power is turned off. If the power is turned off during the process of auto tuning, start again from the beginning. (PID value does not change.)
- · Since ON-OFF operation (2-position operation) is performed during auto tuning, PV may fluctuate greatly depending on the process. Do not perform auto tuning for the processes where great fluctuation of PV is not allowed. Do not perform auto tuning, either, for the processes where the response is quick, such as pressure control or flow rate control.
- · If auto tuning is not completed in 4 hours, it may not be performed properly. Check input/output wiring and parameters such as control output (forward, reverse) and input sensor type.
- · If input range (Pv1F (Ch8-1), Pv1b (Ch8-2), and Pv1d (Ch8-3)) is changed or the operation of control target is changed because a great change is made to the SV, perform auto tuning again.

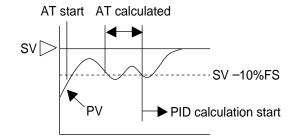
Parameter		Description	
Ch E	RCP I	Auto tuning type	
		MRML: Standard type (with reference to SV)	
		LPV: Low PV type (With reference to SV -10%FS)	
Ch 1	PLIn	Palette No. used for control (Reflect the result of AT.)	
		0: Local PID	
		1 to 7: Palettes No.1 to 7	

(1) Standard type (ATP1=NRML)

(2) Low PV type (ATP1=LPV)

Overshoot at the time of tuning is reduced.





### [Setting example] Performing auto tuning -

## Display Operation procedure Check that the operation display is shown. Operation display Press the SEL key, and the channel selection display appears, displaying P51. Channel selection display 3. Press the $\bigcirc$ key to display $I \circ PE$ . Channel selection display Press the SEL or the key, and LeEn I appears and the 4. parameter selection display is shown. Parameter selection display 5. M oFF Parameter selection display Press the SEL or the key to make the setting flicker, and set the value to oo! using the $\bigcirc$ , $\bigcirc$ , or the $\bigcirc$ key. [] [ on ( Setting change mode Press the SEL key to register the setting. ŊŊ Parameter selection display Press the DISP key once to return to the parameter selection display. Press it again to return to the operation display. ·8 1 \* While auto tuning is in progress, the decimal point of the figure on the right of the lower row is kept flickering. It goes off when auto tuning is Operation display completed.

## 3-11 Alarm function

1*[P* 

to

8FP

Setting alarm type (Setting range: 0 to 38)

### [Description]

- · Set the operation type of alarms 1 to 8.
- · See the following figure for details of alarm type.

	1TP to 8TP	Alarm Type	Operation Diagram
	0	No alarm	<b>→</b> PV
Absolute value Alarm	1	Upper limit absolute	ALn PV
	2	Lower limit absolute	ALn PV
	3	Upper limit absolute (with hold)	ALn PV
	4	Lower limit absolute (with hold)	ALn PV
Deviation Alarm	5	Upper limit deviation	ALn SV PV
	6	Lower limit deviation	ALn PV
	7	Upper/lower limit deviation	ALn ALn PV
	8	Upper limit deviation (with hold)	ALn SV PV
	9	Lower limit deviation (with hold)	ALn PV
	10	Upper/lower limit deviation (with hold)	ALn ALn SV
Range Alarm	11	Range upper/lower limit deviation	ALn ALn PV

#### Caution The Hold Function:

This is an alarm for situations when the alarm does not turn ON immediately, and the value go to outside the range once and then reenters within the range, even when the measured value is within the range of the alarm at the time the power is turned on.

#### Notes)

- After changing the alarm type, confirm the alarm setting values.
- Alarm setting values may change by changing the alarm type, but this is normal.
- Caution: The alarm latch function cannot be used when using the OFF delay timer.
- ALn : Indicates the AL1 (ch1-10) to AL8 (ch1-31) alarm setting values.
- An-H : Indicates the A1-H (ch1-12) to A8-H (ch1-33) alarm setting values.
- An-L : Indicates the A1-L (ch1-11) to A8-L (ch1-32) alarm setting values.
- dLYn: Indicates the 1dLY (chA-4) to 8dLY (chA-39) alarm ON delay setting values.

	1TP to 8TP	Alarm Type	Operation Diagram
Upper/ lower limit Alarm	16	Upper/lower limit absolute	An-L An-H PV
	17	Upper/lower limit deviation	An-L An-H SV
	18	Upper limit absolute Lower limit deviation	An-L SV An-H
	19	Lower limit absolute Upper limit deviation	An-H PV
	20	Upper/lower limit absolute (with hold)	An-L An-H PV
	21	Upper/lower limit deviation (with hold)	An-L An-H PV
	22	Upper limit absolute Lower limit deviation (with hold)	An-L SV An-H PV
	23	Upper limit deviation Lower limit absolute (with hold)	An-H PV
Range Alarm	24	Range upper/lower limit absolute	An-L An-H PV
	25	Range upper limit/lower limit deviation	An-L An-H PV
	26	Range upper limit absolute Lower limit deviation	SV An-H PV
	27	Range upper limit deviation Lower limit absolute	An-H PV
Range Alarm	28	Range upper limit/lower limit absolute (with hold)	An-L An-H PV
	29	Range upper limit/lower limit deviation (with hold)	An-L An-H
	30	Range upper limit absolute Lower limit deviation (with hold)	SV An-H PV
	31	Range upper limit deviation Lower limit absolute(with hold)	An-H PV
Limit	32	SV upper/lower limit	An-L An-H SV
Rate of change	35	PV rate of change Upper/lower limit	0% ALn 100  PV change ratio among 5 cycles of input sampling
Timer	36	ON delay timer	OUT dLYn
	37	OFF delay timer	DI OUT
	38	ON/OFF delay timer	OUT GLYN GLYN

[Setting example] Setting alarm type of Alarm 1 to upper limit deviation (with hold)————

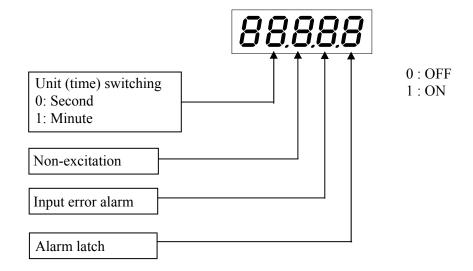
Display	Operation procedure
~ 2 <b>78</b>	1. Check that the operation display is shown.
Operation display	2. Press the SEL key, and the channel selection display appears, displaying P5!.
Channel selection display	3. Press the key to display 8 ALT.
Channel selection display	4. Press the SEL or the key, and R IFP appears and the parameter selection display is shown.
Parameter selection display	5. Press the SEL or the key to make the setting flicker, and set the value to 00008 using the key, or the key.
Setting change mode	6. Press the SEL key to register the setting.
Parameter selection display  Parameter selection display  Parameter selection display  Parameter selection display	7. Press the DISP key once to return to the parameter selection display. Press it again to return to the operation display.



### [Description]

#### Setting alarm options

· Switching of alarm unit (time) and function setting can be made. (See the following figure).

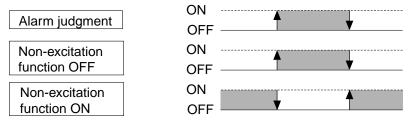


· Unit (time) switching is used for 1dLY (ChA-4) to 8dLY (ChA-39).

#### What is the excitation/non excitation function?

It is a function that makes the alarm output excited or not excited and outputs to the alarm relay. (When the function is set to ON, the alarm is output when not excited.)

#### Excitation/non excitation function



#### [Note]

If power is turned OFF or during standby, alarm is not output (OFF) even if non-excitation function is set to ON.

### What is input error alarm function?

It is a function that turns ON the alarm relay when an error occurs to the main unit.

#### What is alarm latch function?

It is a function that maintains alarm ON status once the alarm is turned ON. Following procedures are available to reset the alarm latch.

- 1) Turn on the power of the controller again.
- 2) Set the alarm latch setting to OFF.
- 3) Reset using the alarm latch reset command LACh (Ch1-8).
- 4) Reset by DI input.
- 5) Reset by communication.

[Setting example] Setting the unit to minute, non-excitation to ON, input error alarm to OFF, and alarm latch to OFF

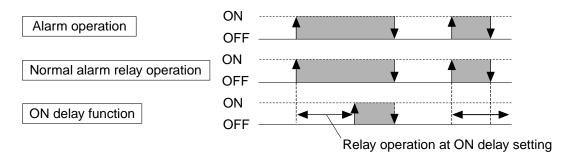
Display		Operation procedure
~ 278 · 0 1 ° 0.0	1.	Check that the operation display is shown.
Operation display		
" <b>P5 !</b>	2.	Press the SEL key, and the channel selection display appears, displaying P5!.
Channel selection display	3.	Press the key to display 8 8L
Channel selection display	4.	Press the $\square$ or the $\square$ key, and $\bowtie$ $\square$ appears and the
		parameter selection display is shown.
Parameter selection display	5.	Press the $\square$ key to display $P_{\alpha} P_{\alpha}$ .
Parameter selection display	6.	Press the SEL or the key to make the setting flicker, and set the value to !!!!! using the , , or the key.
Setting change mode	7.	Press the SEL key to register the setting.
Parameter selection display  ***********************************	8.	Press the DISP key once to return to the parameter selection display. Press it again to return to the operation display.

IGLY	to	84LY	Setting alarm delay time (Setting range: 0 to 9999)
IHY5	to	8h45	Setting alarm hysteresis (Setting range: 0.00 to 50.00%FS)

#### [Description]

## Setting alarm delay time

· When alarm ON conditions are met, the alarm is set to ON after selected ON delay time elapses.



## Setting alarm hysteresis

- · Set the operation dead band (hysteresis).
- · By setting alarm hysteresis, fluctuation of output is prevented and the output is stabilized. Setting can be made according to applications.

## [Setting example ] Setting delay time of Alarm 5 to 50 \_\_\_\_\_

Display	Operation procedure	
· 0 ( * 0.0	1. Check that the operation display is shown.	
Operation display	2. Press the SEL key, and the channel display appears, displaying P5!.	
Channel selection display	3. Press the	
Channel selection display	4. Press the SEL or the key, and R IFP appears and the parameter selection display is shown.	
Parameter selection display	5. Press the 💟 key to display ねらむしら.	
Parameter selection display	6. Press the SEL or the  key to make the setting flicker, and set the value to @@@5@ using the , or the key.	
Setting change mode	7. Press the SEL key to register the setting.	
Parameter selection display  Parameter selection display  Properation display	8. Press the DISP key once to return to the parameter selection display. Press it again to return to the operation display.	

AL I	to	RL8	Alarm setting	
A 1-L	to	A8-L	Alarm lower limit setting	Setting range: 0 to 100%FS for absolute value alarm,  -100 to 100%FS
A 1-h	to	88-h	Alarm upper limit setting	for deviation alarm

## [Description]

- · Set the operation value of alarms from 1 to 8.
- · Display/non display status of AL1 (Ch1-10) to AL8 (Ch1-31), A1-L (Ch1-11) to A8-L (Ch1-32), A1-h (Ch1-12) to A8-h (Ch1-33) changes automatically according to the type of alarms selected. (See the following table for details.)

Setting of 1TP to 8TP	Displayed parameter
1 to 11, 35	AL1 to AL8
16 to 32	A1-h to A8-h
10 (0 32	A1-L to A8-L

### [Setting example] Setting alarm 1 setting to 60.0 ——

# Display Operation procedure Check that the operation display is shown. •**8** 1 Operation display Press the SEL key, and the channel selection display appears, displaying P51. Channel selection display 3. Press the key to display IoPE. Press the SEL or the key, and LeEn! appears and the 4. Channel selection display parameter selection display is shown. 5. Press the | key to display ! AL !. Parameter selection display Press the SEL or the key to make the setting flicker, and set the value to OOSOO using the $\bigcirc$ , $\triangle$ , or the $\bigcirc$ Parameter selection display key. Press the SEL key to register the setting. Setting change mode Press the DISP key once to return to the parameter selection display. Press it again to return to the operation display. Parameter selection display \* When 1TP is set to 16-32, AL1 is not displayed. See the table on the previous page. Operation display

## 3-12 Re-transmission output

Ro II Setting output type of re-transmission output 1 (Setting range: PV, SV, MV, DV,

AiM, MVRB, TV)

### [Description]

· See the following table for details of output type.

Ao1T	Meaning
PV	Measurement value (PV)
SV	Set value (SV)
MV	Operation output value (MV)
DV	Deviation (PV – SV)
AiM	Result of Math function
MVRB	Valve opening feedback (MVRB) Note 1)
TV	Totalizer result value Note 2)

- To use output scaling, make the scaling setting of Ao1H (Ch8-66) and Ao1L (Ch8-67).
- · To use Ao2, make the setting of Ao2T (Ch8-70), Ao2H (Ch8-72), Ao2L (Ch8-73) in the same way.

Note 1: If, in case "MVRB" is selected as output type of re-transmission, the direction of burnout (brd1) is set to PoFF, the re-transmission output at burnout will be -5%.

(For details of brd1, see section 5-8 "Setting output direction at the input error".)

Note 2: If [TV] is selected as re-transmission output type, make rTSC (ChG-21) setting.

## [Setting example] Changing the type of re-transmission output 1 from PV to SV \_\_\_\_\_

Display	Operation procedure	
~ 278	1. Check that the operation display is shown.	
Operation display  P5 i BBBB  Channel selection display	2. Press the SEL key, and the channel selection display appears, displaying P5!.	
Ehannel selection display	3. Press the key to display 8 5EF.	
Parameter selection display	4. Press the SEL or the key, and 8.P. IF appears and the parameter selection display is shown.	
880 15 84 Pü	5. Press the key to display 8.80 IF.	
Parameter selection display  Figure 1.5  Setting change mode	6. Press the $\square$ or the $\square$ key to make the setting flicker, and set the value to $\square$ using the $\square$ , $\square$ , or the $\square$ key.	
BRO II	7. Press the SEL key to register the setting.	
Parameter selection display  Parameter selection display  Parameter selection display	8. Press the DISP key once to return to the parameter selection display. Press it again to return to the operation display.	

Ro Ih

Upper limit value of the scale of re-transmission output 1 (Setting range: -130.0% to 130.0%)

Ro IL

Lower limit value of the scale of re-transmission output 1 (Setting range: -130.0% to 130.0%)

### [Description]

- · Set the upper limit value and lower limit value of the scaling of re-transmission output.
- · The unit of setting is %.

Output type	Meaning of setting value [%]			
Output type	When TPLT=33, 34	When TPLT=30, 31		
PV/SV/DV	Scale set in Pv1F (Ch8-1),	Scale set in UCF1 (Ch8-89),		
r v/Sv/Dv	Pv1b (Ch8-2), Pv1d (Ch8-3)	UCb1 (Ch8-90), UCd1 (Ch8-91)		
AiM		Scale set in UCF1 (Ch8-89),		
Allvi		UCb1 (Ch8-90), UCd1 (Ch8-91)		
MV/MVRB	Fixed to 0.0 to 100.0% (output value)	Fixed to 0.0 to 100.0% (output value)		
TV	Scale of input type selected in	Scale of input type selected in		
1 V	Toin (ChG-3)	Toin (ChG-3)		

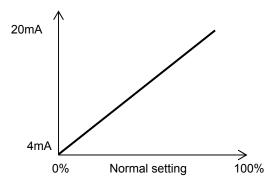
Note: The following is an example where scales used are PV1F, PV1b, and PV1d. Find the setting using the same expression when using other scales. (Refer also to the setting example shown below.)

Setting (%) =  $(A / B) \times 100 (\%)$ 

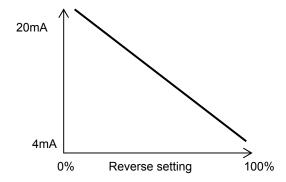
A =The value to be set – Setting of parameter Pv1b (Ch8-2)

B = Setting of parameter Pv1F (Ch8-1) – Setting of Pv1b (Ch8-2)

- · When the value of re-transmission output type (SV for example) becomes equal to the setting of Ao1L (Ch8-67), the re-transmission output becomes 0% (output).
- · When the value of re-transmission output type (PV for example) becomes equal to the setting of Ao1h (Ch8-66), the re-transmission output becomes 100% (output).
- · To use this function for output 2, make the setting of Ao2h (Ch8-72) and Ao2L (Ch8-73) in the same way.
- · If the scaling upper limit values Ao1h, Ao2h and the lower limit values Ao1L, Ao2L are set in reverse, the output is reversed. (See the following figure.)



When Ao1L=0.0%, Ao1H=100.0%



When Ao1L=100.0%, Ao1H=0.0%

[Setting example] Performing scaling to allow 0% output when PV (value of re-transmission output type) is 100°C, and 100% output when it is 300°C, with the input type of K thermocouple of 0 to 400°C

Since measurement range is from 0 to  $400^{\circ}$ C, Pv1b = 0 (lower limit value of the measurement range), and Pv1F = 400 (upper limit value of the measurement range), the values of A and B in the expression on the previous page are calculated as follows.

 $A = (100^{\circ}C - 0)$  or  $(300^{\circ}C - 0)$ , B = 400 - 0 = 400

- 1) Setting of Ao1L: At what % position is 100°C in 0 to 400°C range? = 25% (= 100 0) /  $400 \times 100$  [%])  $\rightarrow$  Ao1L = 25.0%
- 2) Setting of Ao1h: At what % position is 300°C in 0 to 400°C range? = 75% (= 300 0) /  $400 \times 100$  [%])  $\rightarrow$  Ao1h = 75.0%

Display	Operation procedure	
Operation display	1.	Check that the operation display is shown.
" <b>P5 ;</b>	2.	Press the SEL key, and the channel selection display appears, displaying P5 1.
Channel selection display	3.	Press the \times key to display \( 8 \) \( 5\)E\( \Gamma \).
Channel selection display	4.	Press the SEL or the key, and BPJ IF appears and the parameter selection display is shown.
Parameter selection display	5.	Press the \times key to display \( \begin{align*} \begin{align*} \Partial \cong \eta \\ \eta \eta \eta \\ \eta \eta \et
Parameter selection display	6.	Press the SEL or the  key to make the setting flicker, and set the value to 00750 using the , or the key.
Setting change mode	7.	Press the SEL key to complete the setting of 8.70 lh.
<b>55 75.D</b> Parameter selection display		(Continued to the next page.)

Display	Operation procedure
"8"Ro !L	8. Press the key to display 8.80 IL.
Parameter selection display	9. Press the SEL or the  key to make the setting flicker, and set the value to \$\mathbb{B} = 5.0\$ using the , , or the key.
Setting change mode	<b>10.</b> Press the SEL key to complete the setting of 880 IL.
" <b>A"A (L</b> 87 25.0	
Parameter selection display	11. Press the DISP key once to return to the parameter selection
·01° 00	display. Press it again to return to the operation display.
Operation display	

**R ! L h** Upper limit value of re-transmission output (Setting range: −25.0% to 105.0%)

R !L L Lower limit value of re-transmission output (Setting range: –25.0% to 105.0%)

## [Description]

- · Set the limit values of re-transmission output.
- · When setting Ao2, set A2Lh and A2LL in the same way.

[Setting example] Changing lower limit setting of re-transmission 1 output from -5% to 10% —

Display		Operation procedure
~ 2 <b>78</b>	1.	Check that the operation display is shown.
Operation display		
<b>P5!</b>	2.	Press the SEL key, and the channel selection display appears, displaying P5 1.
Channel selection display	3.	Press the $\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \$
Channel selection display	4.	Press the SEL or the key, and 8.P.J. IF appears and the parameter selection display is shown.
Parameter selection display	5.	Press the \times key to display \( \mathbb{B} \mathbb{B} \) ILL.
Parameter selection display	6.	Press the SEL or the  key to make the setting flicker, and set the value to 00 10.0 using the , , or the key.
Setting change mode	7.	Press the SEL key to register the setting.
<b>BA ILL</b>		
Parameter selection display  Parameter selection display  Parameter selection display	8.	Press the DISP key once to return to the parameter selection display. Press it again to return to the operation display.

## 3-13 Setting communications

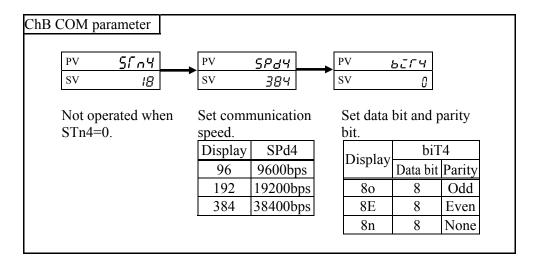
รักฯ RS485 station No. (Setting range: 0 to 255)

5Pd4 RS485 communication speed (Setting range: 96, 192, 384)

Bこ「Y RS485 bit format (Setting range: 8o, 8n, 8E)

### [Description]

- · Reading and writing of internal data are allowed with MODBUS RTU communications.
- · See the following figure for details of parameter setting.



- · Selected parameters are not enabled unless the power is turned on again. Be sure to reset the instrument or turn the power on again.
  - \* See "Instruction Manual for Communication Functions (MODBUS)" for details of reading and writing of internal data and communications.

## [Setting example] Changing communication speed from 38400bps to 19200bps —————

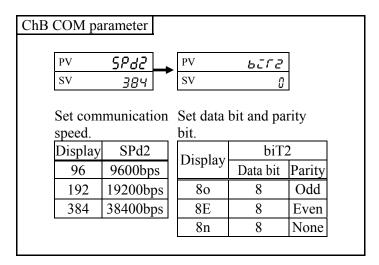
Display	Operation procedure
~0.1° 278	1. Check that the operation display is shown.
Operation display	2. Press the SEL key, and the channel selection display appears, displaying P5!.
Channel selection display	3. Press the key to display b con.
Channel selection display	4. Press the SEL or the key, and b.55774 appears and the parameter selection display is shown.
Parameter selection display	5. Press the key to display 6.5Pd4.
Parameter selection display	6. Press the SEL or the key to make the setting flicker, and set the value to 192 using the key, key, or the key.
Setting change mode	7. Press the SEL key to register the setting.
Parameter selection display  Parameter selection display  Operation display	8. Press the DISP key once to return to the parameter selection display. Press it again to return to the operation display.

PC loader interface (RC232C) communication speed (Setting range: 96, 192, 384)

**Bこ「己** PC loader interface (RS232C) bit format (Setting range: 8o, 8n, 8E)

#### [Description]

· See the following figure for details of parameter setting.



· Selected parameters are not enabled unless the power is turned on again. Be sure to reset the instrument or turn the power on again.

### [Setting example] Setting bit format 80 to 8E \_\_\_\_\_

Display	Operation procedure		
~0.0° 27.8°	1. Check that the operation display is shown.		
Operation display	2. Press the SEL key, and the channel selection display appears, displaying P5!.		
Channel selection display	3. Press the		
Channel selection display	4. Press the SEL or the key, and b.5504 appears and the parameter selection display is shown.		
Parameter selection display	5. Press the key to display bbcre.		
Parameter selection display	6. Press the SEL or the key to make the setting flicker, and set the value to 8E using the , , or the key.		
Setting change mode	<b>7.</b> Press the SEL key to register the setting.		
Parameter selection display	8. Press the DISP key once to return to the parameter selection display. Press it again to return to the operation display.		
Operation display			

# 4OPERATION

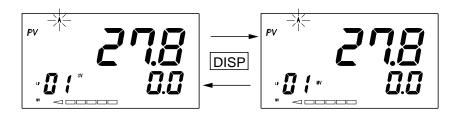
### Operation mode

This instrument can be operated in Auto, Remote, or Manual mode.

The operation method of each mode, operation display, and operation procedures are described below.

### Auto operation

The instrument is automatically operated with the target settings set in the controller. Target settings can be set on the front panel or with communication.



[Mode indicator]

A lights

[PV indicator]

Displays measurement value (PV).

[SV/MV indicator]

Displays set value (SV).

[SV/MV operation]

Settings can be changed on the front panel.

[Mode indicator]

A lights

[PV indicator]

Displays measurement value (PV).

[SV/MV indicator]

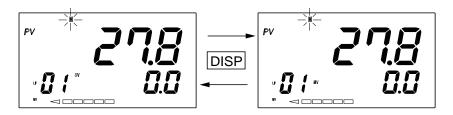
Displays operation output (MV).

[SV/MV operation]

Operation output cannot be changed on the front panel.

#### Manual operation

An operator manually changes operation output (MV) to operate the instrument.



[Mode indicator]

M lights

[PV indicator]

Displays measurement value (PV).

[SV/MV indicator]

Displays set value (SV).

[SV/MV operation]

Settings can be changed in local mode.

[Mode indicator]

M lights

[PV indicator]

Displays measurement value (PV).

[SV/MV indicator]

Displays operation output (MV).

[SV/MV operation]

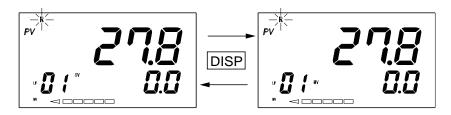
Settings can be changed on the front panel.

<sup>\*</sup> See section 4-1 "Auto operation" for details of auto operation procedures.

<sup>\*</sup> See section 4-2 "Manual operation" for details of manual operation procedures.

#### Remote operation

Operation is performed with auxiliary input Ail or the setting of SV selection (SV selectable PID controller type) used as target setting.



[Mode indicator]

R lights on.

[PV indicator]

Displays measurement value (PV).

[SV/MV indicator]

Displays auxiliary input Ail or target setting of SV selection PID control.

[SV/MV operation]

Target settings cannot be changed.

[Mode indicator]

R lights on.

[PV indicator]

Displays measurement value (PV).

[SV/MV indicator]

Displays operation output (MV) or valve opening feedback (MVRB).

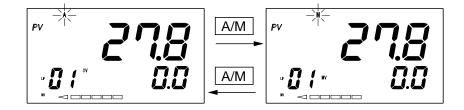
[SV/MV operation]

Displays operation output (MV) or valve opening feedback (MVRB).

### Change between Auto and Manual mode

Changing method: Operation mode can be changed between Auto and Manual using the A/M key on the operation display.

(See section 4-2 "Manual operation" for detailed operation procedures.)



- Related functions: [1] Prohibition of change to manual operation: Change to manual operation can be prohibited with A-M1 (Ch9-15) parameter. (See section 5-17 "Manual operation prohibition" for details.
  - [2] Operation mode can be switched to Manual by manual command signal with Di input.

(See section 5-10 "Digital input (Di) function" for details.)

Note:

Change both from Auto to Manual and Manual to Auto is a balanceless bumpless transfer.

<sup>\*</sup> See section 4-3 "Remote operation" for details of remote operation procedures.

### ■ Changing between Auto and Remote operations

Changing method: [1] Operation mode can be changed between Auto and Remote with rEM1 (Ch1-1). (See section 4-3"Remote operation" for detailed operation procedures.)

[2] Operation mode can be changed between Auto and Remote by operating the dSV key.

(See section 5-13"Function key" for details.)

[3] The operation mode is automatically changed to Remote by performing SV switching at the time of SV selectable PID controller.

Related functions: [1]

- [1] Remote operation prohibition function: Remote operation can be prohibited with rihl (Ch9-7) parameter.
- [2] Changing with R-ACK signal: The operation mode can be changed to Remote with R-ACK signal from digital input with rAC1 (Ch9-11) setting. (See section 5-16 "R-ACK function", and section 5-10 "Digital input (Di) function" for ditails.)

Note: Change from Remote to Local: Provision of trac

Provision of tracking function can be selected with

Trk1 (Ch9-23).

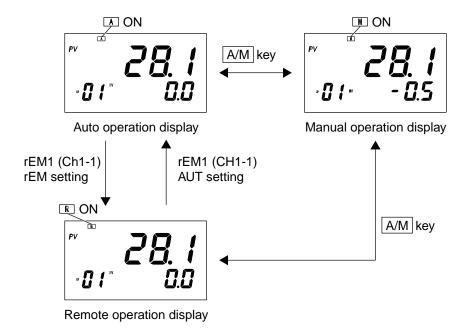
Balanceless bumpless transfer when TrK1 = On Balance bumpless transfer when TrK1 = Off

Change from Local to Remote: Balance bumpless transfer

(Balance remote SV and local SV while watching

dSV display before changing modes.)

### Flow of operation mode change



### 4-1 Auto operation

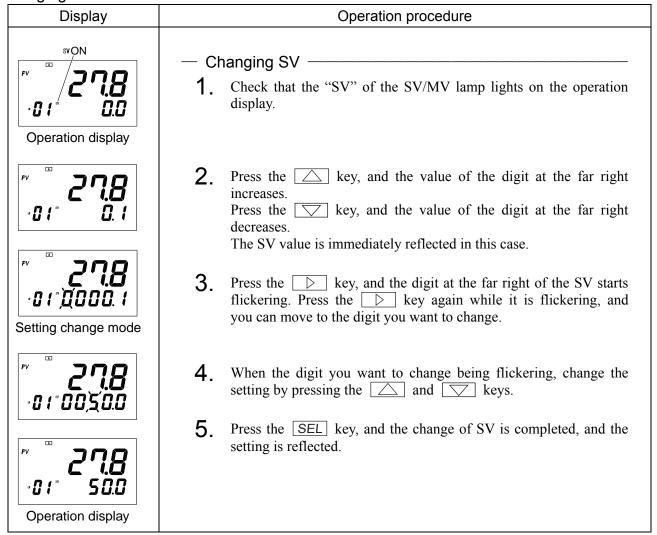
### [Description]

The "Auto operation" refers to an operation where, with a value (SV) selected on the front panel, OPEN, and CLOSE signals are output so that MVRB (valve opening degree feedback or estimated valve position) will coincide with MV (operation output) resulting from Math of PID.

The A lamp is kept on during auto operation.

The SV during auto operation is called "Local SV".

### Changing SV-



Displaying operation output (MV) / Valve opening feedback (MVRB) —

Display	Operation procedure		
SVON  PV  278 0.0  Operation display  NVON	—Displaying MV ———————————————————————————————————		
* Lamp ON or flickering	2. Press the DISP key while the "SV" lamp is on, and the display changes to MV/MVRB display. ("MV" lamp comes on) (Press the DISP key again to return to the SV display operation screen.)		

Changing from Auto (A) operation to Manual (M) operation \_\_\_\_\_

Display	Operation procedure
PON 27.8	1. Check that the A lamp lights on the operation display.
Operation display  PV  PV  PV  - 5.0  * Lamp ON or flickering	2. Press the A/M key while the A lamp is on, and the M lamp comes on, and the operation mode is changed to Manual.  (Press the A/M key to return to Auto operation.)

Note: The operation output (MV) value at a change from Auto to Manual operation is arranged to join the valve opening degree feedback (MVRB).

OPEN, and CLOSE signals are off until " or " " is pressed.

# 4-2 Manual operation

The motorized valve can be directly operated by an operator, which is called "Manual operation."

The M lamp lights is on during manual operation.

The operation output during Manual operation is arranged to join the valve opening degree feedback (MVRB).

Display, and operating the operation output (MV)/valve opening feedback value (MVRB)

Display	Operation procedure		
	—Displaying MV/MVRB— At MV on the bottom stage of the operation screen, the controller car display operation output value (MV) or valve opening degree feedback value (MVRB) as selected by dSPT (Ch9-78) parameter.		
Lamp (lit when MVRB display is selected)	1. When the "MV" lamp is lit at SV/MV lamp on the operation screen, either operation output value (* lamp extinguished) or valve opening degree feedback value (* lamp lit) is displayed at the bottom SV/MV display section.		
	2. When the "SV" lamp is lit at SV/MV lamp, pressing the DISP key selects MV/MVRB display.  (Pressing the DISP key again selects SV display.)		
Operation display  MON MON  PV  DOD  DOD  DOD  DOD  DOD  DOD  DOD	Operating the motorized valve  Check that the "MV" lamp and M lamp light on the operation display.		
Operation display	2. Holding down the  key turns on the OPEN signal. Holding down the  key turns on the CLOSE signal. (The signals stay on while either key is pressed.) Holding down both , and  keys turns off OPEN signal and CLOSE signal.		
	[Note] During estimation control, the operation output value is limited between 0, and 100.0%.  (Even when the operation output value is limited, the  or  key can output the OPEN or CLOSE signal.)		

Changing from Manual (M) to Auto (A) operation —————

Display	Operation procedure		
PV 278	1. Check that the M lamp lights on the operation display.		
Operation display  OPERATION  FV CONTRACTOR OF THE CONTRACTOR OF T	2. Press the A/M key while the M lamp is kept on, and the A lamp starts flickering and the operation mode is changed to Auto.  After change from Manual to Auto operation, the MV output starts at valve opening degree feedback (or estimated valve position).  (Press the A/M key again to return to Manual operation.)		

### 4-3 Remote operation (SV=External set value PV2)

**ren :** Changing Remote/Auto operation (Setting range: REM, AUT)

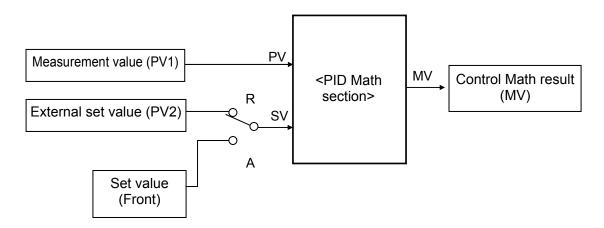
### [Description]

The instrument is operated by "Auto operation" according to set values (SV) by front panel keys, and "Remote operation" by external set values (remote SV) resorting to analog input signal or SV selection type (see section 4-4"SV selection function (Remote operation)")."

The Remote operation can be selected by this parameter operation as well as user allocated key, or Di remote permit signal (R-ACK). besides using this parameter.

This parameter cannot be used for SV selection method.

- \* See section 5-16 for details of R-ACK function.
- \* See section 5-13 for details of Function keys.



### Remote operation by analog input (RSV)

- · PID control is performed with input value of universal input 2 (PV2) as external set value (RSV).
- · In case of motorized valve control type, universal input 2 (PV2) is used as analog input for remote set value (RSV).

### To perform Remote operation (by analog input)

- (1) Universal input 2 (PV2) is necessary for remote operation by external set value on a motorized valve control type.
  - (Check that the 6th digit of type code of your instrument is "2" (universal input of 2 points.)
- (2) Set the control template (TPLT (Ch8-92)) to "30" or "33".
- (3) Set PV2F, PV2B, and PV2D to the same values as PV1F, PV1B, and PV1D. (If PV1 input scale, and PV2 input scale settings are different, the values of PV2 (Ch7-2) monitor, and remote SV (operation screen) are not the same.)
- (4) Set PV2T to match the input type used. (See section 3-2"Setting input.")
- (5) Changing REM1 (ch1-1) from "AUT" to "REM" selects a remote SV operation (that can also be selected by a function assigned to user key or Di).

### [Supplement]

Remote operation by auxiliary analog input (Ai1)

If the 5th digit of type code of motorized valve control type (without PFB) is "S", the auxiliary analog input (Ai1) can be used as an external set value (RSV).

- · Using Ai1 as RSV
- (1) Set Ai1F, Ai1B, and Ai1D (Ch8-40,41,42) to the same values as PV1F, PV1B, and PV1D (Ch8-1,2,3).
- (2) Set Ai1T (Ch8-43) to match the input type used. (See section 3-2 "Setting input.")
- (3) Set the 15th bit of DS25 (Ch9-A5) to "0" to display Cn02 (Ch8-99) parameter. (Normally, Cn02 parameter is not displayed. For parameter mask, see section 5-21 "Parameter mask.")
- (4) Change the setting of Cn02 (Ch8-99) from "1" to "3". (Changing the control template resets Cn02 to 1. Recommence setting.)

### · Precaution

This function can be used only when the 7th digit of type code is "1" (auxiliary input of 1 point).

### [Setting example] Changing operation mode from Auto to Remote ————

Display	Operation procedure		
PV 278	1. Check that the operation display is shown.		
Operation display  PS 1  DDD  Setting change mode	2. Press the SEL key, and the channel selection display appears, displaying P5!.		
Fv J PE Eh Setting change mode	3. Press the key to display ! oPE.		
Parameter selection display	4. Press the SEL or the key, and the parameter selection display appears, displaying Letil.		
Setting change mode	5. Press the SEL or the key to make the setting flicker, and set the value to refl using the or the key.		
Parameter selection display	6. Press the SEL key to register the setting.		
PV 278 -01" 0.0  Operation display	7. Press the DISP key once to return to the parameter selection display. Press it again to return to the operation display.		

### [Note]

For changing operation mode from Remote to Auto.

- · Follow the same procedure to change this parameter from REM to AUT.
- · See section 5-19 "SV tracking function" for the SV when the operation mode is changed from Remote to Auto.

### 4-4 SV selection function (Remote operation)

- · Eight kinds of set values (SV), SV1 to 7 of Ch3 (PLT) and local SV, can be selected and controlled with Di1 to 3, which is called SV selection function.
- · Set TPLT (Ch8-92) to "31" or "34" to use the SV selection function.
- · Select SV, referring to the following table.

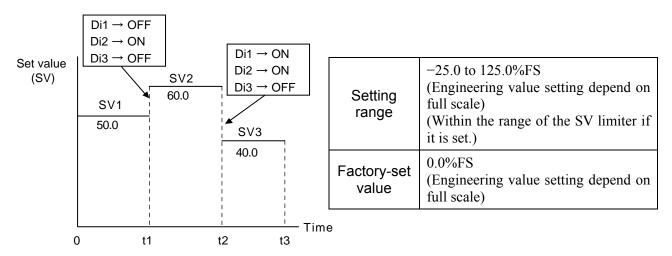
SV No.	Di1	Di2	Di3
SV (Local set value)	OFF	OFF	OFF
SV1 (Remote SV)	ON	OFF	OFF
SV2 (Remote SV)	OFF	ON	OFF
SV3 (Remote SV)	ON	ON	OFF
SV4 (Remote SV)	OFF	OFF	ON
SV5 (Remote SV)	ON	OFF	ON
SV6 (Remote SV)	OFF	ON	ON
SV7 (Remote SV)	ON	ON	ON

#### [Note]

Operation is carried out in Remote mode when SV1 to 7 is selected.

#### [Example]

Set SV1 (Ch3-1) to 50.0, SV2 (Ch3-12) to 60.0, and SV3 (Ch3-23) to 40.0, and the operation can be performed according to the settings of SV1 (for 0 to  $t_1$ ), SV2 (for  $t_1$  to  $t_2$ ) and SV3 (for  $t_2$  to  $t_3$ ).



· See section 5-19 "SV tracking function" for the SV when the operation mode is changed from Remote to Auto.

### 4-5 Standby function

5 たらら Standby setting (Setting range: ON, OFF)

**5** Departion setting for standby function (Setting range: 0, 1)

P∏ I Output setting for standby function (Setting range: –25.0 to 105.0%)

### [Description]

1) Change between RUN/Standby with STby (Ch1-5).

During standby state, all the outputs except for control output (MV) and communication are turned OFF. Control output (MV) becomes designated value.

The STBY lamp is kept on during standby.
 (PV and SV display can be turned off with STbo (Ch9-30).

· See the following table for the status of functions during standby.

	During standby	Return from standby
Operation output	Outputs value designated by PMv1.	Bumpless restart from PMV1.
	OPEN or CLOSE signal is output so	
	that valve opening degree is equal to	
	PMV1 set value.	
Alarm output	All outputs are OFF.	_
Timer operation	All operations are OFF.	Zero start
Hold operation	-	Initial start
Latch operation	All operations are OFF.	Initial start (released)
Non-excitation output	All outputs are OFF.	Work in non-excitation
operation	(Non-exitation operations are invalid)	operation
Communication	Not affected by standby status.	
Analog	0mA	
re-transmission output		
Digital output (Do)	All outputs are OFF.	_
Digital input (Di)	_	Status detection: Operated
		Edge detection: Not operated.
Control mode	Not affected by standby status.	
Display	Can be selected from ON/OFF	ON

- · Standby setting is maintained even if the power is turned ON/OFF.
- · If the instrument is put into standby while auto tuning is carried out, the auto tuning is canceled. PID constant is not updated.
- 2) Set the operations during standby to STbo.
- · See the following table for the operations during standby.

	Operation during standby			
STBY	STbo setting	MV output	Output other than MV	Display
ON	0	Value of PMV1 (Ch2-22) (-25% to 125%)	OFF or –25%	ON
ON	1	Value of PMV1 (Ch2-22) (-25% to 125%)	OFF or –25%	OFF
OFF		Normal operation	Normal operation	ON

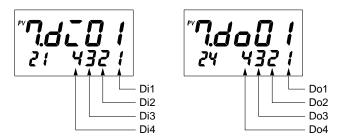
3) Set the output value (MV) during standby to PMV1 (Ch2-22). This value is output during standby. On setting standby to OFF, the operation value (MV) restarts in bumplessly.

Example: When PMv1 (Ch2-22) is set to 100.0

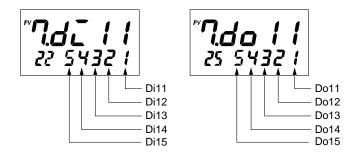


### 4-6 How to use monitoring function

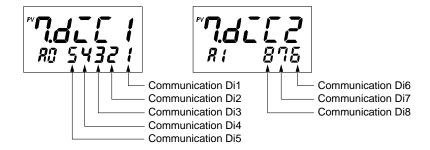
- · Monitoring: Input/output value can be checked with the monitoring function.
- The monitor exists in Ch7 (Mon.) See the appended parameter list.
- (1) Di and Do are displayed as shown below.



When the value is kept on: ON When the value is kept off: OFF



When the value is kept on: ON When the value is kept off: OFF



When display stays on: ON When display stays off: OFF

- (2) Ao1, Ao2, AMv1 and FFv1 are in unit of %.
- (3) The unit for TM1 to 8 is changed between seconds and minutes according to the alarm option setting.
- (4) MVRB monitor (Ch7-50) displays a valve opening degree value.

  During estimation control for valve position, it displays an estimated (calculated value) valve position.

#### [Note]

Contents in monitors cannot be changed.

# 5 ADVANCED USAGE

### 5-1 Setting inputs

P /[] PV1 input square-root extractor cut point (Setting range: OFF, 0.0 to 125.0%)

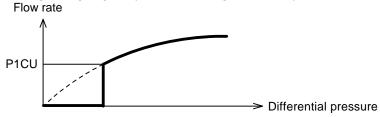
P IFF PV1 input filter time constant (Setting range: 0.0 to 900.0 seconds)

### [Description]

### 1) P1CU(Ch8-11)

Square root extraction

To convert differential pressure to flow rate, use square root extraction. Where differential pressure is small, the flow rate to the set router cut point is handled as "0" to prevent the flow rate from being changed greatly and becoming unstable by noise.



• To use square root extraction for PV2 and Ai1, make the setting for P2CU (Ch8-24) and A1CU (Ch8-49) in the same way.

### 2) P1TF (Ch8-12)

Input filter

Fluctuation of measurement value by noise, etc. can be suppressed by input filter.

When the value of P1 (Ch2-1) (proportional band) is small, even a small change of PV makes the MV value fluctuate greatly. Control can be stabilized by filtering in such cases.

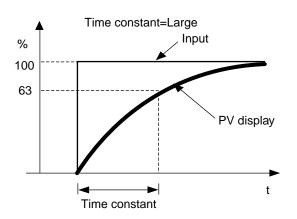
This instrument's filter is a first-order lag filter.

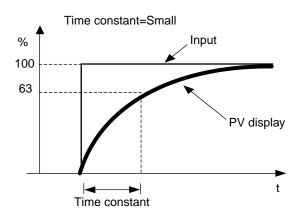
If the input filter time constant P1TF is set to 5.0, the PV display gradually changes when input is suddenly changed from 0 to 100% as shown by the following figure, and it takes 5 seconds for the value to change from 0 to 63.2%.

The larger the value of the filter time constant, the stronger the effect of the filter.

Small←	Time constant→	Large
Fast←	Response→	Slow
Weak←	Effect→	Strong

### 5. ADVANCED USAGE





To use the filter for PV2 and Ai1, make the setting for P2TF (Ch8-25) and A1TF (Ch8-50) in the same way. [Note]

In case the 5th digit of type code of motorized valve control type (with PFB) is "D", selecting A1TF validates filter to valve opening degree feedback value.

### 5-2 Setting output

Ld! Output limiter type setting (Setting range: 0 to 3)

ロット ! Upper limit value of operation output (MV) (Setting range: –25.0 to 125.0%FS))

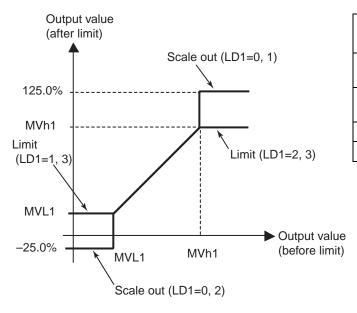
Lower limit value of operation output (MV) (Setting range: –25.0 to 125.0%FS))

בּיּגוֹם Limit value of MV change rate (Setting range: 0.0 to 150.0%)

### [Description]

### 1) Ld1 (Ch2-38)

• It can be set whether the value should be limited at the output limit setting or the limit should be exceeded (scale out) when the operation output (MV) value reaches the output limit setting.



LD1	Output operation		
setting	Upper side	Lower side	
0	Scale out (125.0%)	Scale out (-25%)	
1	Scale out (125.0%)	Limit (MVL1)	
2	Limit (MVh1)	Scale out (-25%)	
3	Limit (MVh1)	Limit (MVL1)	

### 2) Mvh1 (Ch2-9), MvL1 (Ch2-10)

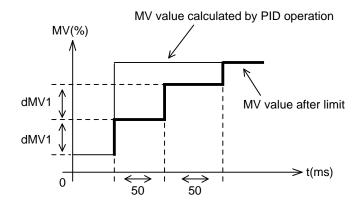
· Set the limit value or scale out point of the operation output (MV).

#### [Note]

- · Neither upper/lower limit nor scale out does not occur in the following cases.
  - 1) During manual operation
  - 2) During standby
  - 3) During EXMV output
  - 4) During burnout
- · Ld1 (Ch2-38), Mvh1 (Ch2-9), MvL1 (Ch2-10) output settings are enabled during auto tuning.
- If MV is limited, P and I operations in the direction in which MV deviates from the limit are cut off.

### 3) dMv1 (Ch2-13)

- · Limit value for the change of MV in 1 control cycle (50msec) can be set.
- · Setting 0.0 provides no limit.
- · Operation output (MV) set manually during manual operation is also limited.



### 5-3 Setting PID

Proportional band (Setting range: 0.0 to 999.9%)

Integral time (Setting range: 0.0 to 3200.0sec)

Derivative time (Setting range: 0.0 to 999.9sec)

| df | PID operation cycle setting (Setting range: 5 to 1000)

### [Description]

### 1) P1 (Ch2-1)

[Setting method]

- · Setting can be made automatically by auto tuning.
- To set manually, select optimum value in the proportional band with this parameter. [ON/OFF control]
- · Set P1 to 0.0 to perform ON/OFF control (2-position control).
- · Hysteresis of ON/OFF control can be set with hS1 (Ch2-15).
- · Generally, if too small a value is set to P (proportional band), the control becomes unstable. If too large a value is set, on the contrary, the reaction becomes slow.
- The instrument is placed under PID control ( $P\neq 0$ ) mode, if auto tuning is performed. If the instrument should be operated with ON/OFF control, do not perform auto tuning.

#### 2) i1 (Ch2-2)

[Setting method]

- · Setting can be made automatically by auto tuning.
- · To set manually, select optimum integral time with this parameter.

#### [Positional P operation]

- · If it is set to 0.0, integral action is not carried out. Positional P operation is performed instead. [Note]
- · If P1 is set to values other than 0, i1 setting is made invalid.

### 3) d1 (Ch2-3)

[Setting method]

- · Setting can be made automatically by auto tuning.
- To set manually, select optimum derivative time with this parameter.

#### [Note]

- · If d1 is set to 0.0, derivative action is not carried out.
- · If P1 is set to 0, d1 setting is made invalid.

### 4) dT1 (Ch2-14)

- · Set the cycle of performing control operation (PID operation). [Note]
- · Setting can be made in the unit of 10ms, but operation cycle is changed in the unit of 50ms.
- · (Setting example)

When dT1=5 to 9, control operation cycle is 50ms.

When dT1=10 to 14, control operation cycle is 100ms.

### 5-4 Setting hysteresis

**h5** / Hysteresis width at the time of 2-position operation (Setting range: 0 to 50%FS)

### [Description]

### 1) hS1 (Ch2-15)

- To perform ON/OFF control (2-position operation control), set P1 (Ch2-1) to 0.0. i1 (Ch2-2) or d1 (ch2-3) need not be set.
- · If the hysteresis width (width of ON/OFF control) is made small, output may be repetitively turned ON/OFF frequently. (In the case of contact output, in particular, the service life of the relay and the operation device may be shortened.)
- The unit of the setting of this parameter is engineering value, but the settable range varies depending on the measurement range of the input.

[Example] Input K Thermocouple: When measurement range is 0 to 400°C,

Settable range is 0 to 200°C.

Resistance bulb: When measurement range is 0 to 150°C,

Settable range is 0 to 75°C.

### Example of parameter setting and operation

#### 1) Reverse action

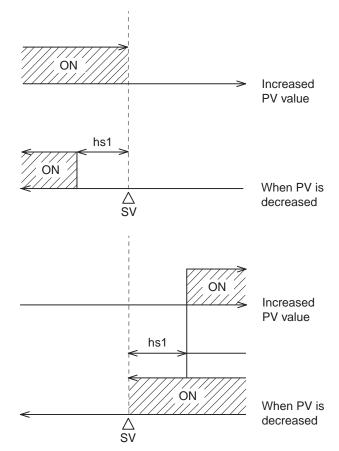
Parameter	Set value
P1 (Ch2-1)	0.0
hS1 (Ch2-15)	Arbitrary
rEv1 (Ch2-20)	REV

Relation between PV and SV	Output
PV > SV	OFF
PV < SV	ON

#### 2) Normal (direct) action

Parameter	Set value
P1 (Ch2-1)	0.0
hS1 (Ch2-15)	Arbitrary
rEv1 (Ch2-20)	NRML

Relation between PV and SV	Output
PV > SV	ON
PV < SV	OFF



### 5-5 Setting bAL, Arh, and ArL

**₽₽** / Output convergence value (Setting range: –100.0 to 100.0%)

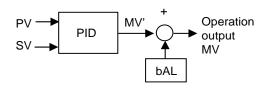
## Integration upper cut point (Setting range: 0 to 100%FS)

RrL I Integration lower cut point (Setting range: 0 to 100%FS)

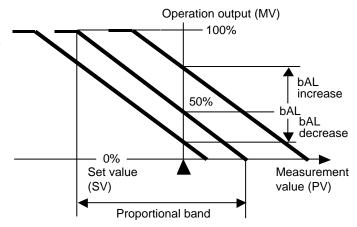
### [Description]

### 1) bAL1 (Ch2-18)

· In the case of I=0 (Positional P operation)
The value of bAL (Ch2-18) is added as offset to the result of PID operation performed with PV and SV, which is regarded as output (MV).

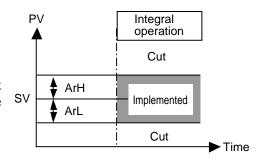


In the case of PID operation (I≠0)
 The value set to bAL becomes the operation output value at the time of power ON.



#### 2) Arh1 (Ch2-5), ArL1 (Ch2-6)

- · The range where integral action is performed is limited.
- · Integration is performed within the range SV-ArL≤PV≤SV+Arh.
- · Integral action is not carried out outside the range.
- · If integral action is included in the control operation, overshoot occurs due to initial excessive integration. To prevent this, the range where integral action is performed is limited.



### [Note]

· Arh1 (Ch2-5), ArL1 (Ch2-6) and bAL (Ch2-18) are not automatically set by auto tuning.

### 5-6 Palette function

PLIn Palette selection (Setting range: 0 to 7)

PL [5] Palette switching method setting (Setting range: PLTn, SV, PV)

### [Description]

This instrument is provided with 7 groups of control palettes (group of control parameters) at Ch3 (PLT), in addition to control parameter at Ch2 (PID). Control can be made while switching these control palettes. Select control palette switching method with PLTS parameter.

### 1) PLTS (Ch9-31)

PLTS setting	Control palette switching method
PLT n	Operation is performed with the control palette set at PLTn (Ch1-9). The SV of the control palette being selected becomes the current target set value.
SV	This is effective when SV selectable type PID control (TPLT=31 or 34) is used. Operation is performed with the control palette of the SV No. selected by Di. See section 3-1 "Setting control template" for details of SV selection type PID control.
PV	Operation is performed while control palettes are automatically switched depending on the measurement value (PV), with the value set for rEF1 to rEF7 (Ch3-78 to 84) regarded as threshold.  The following figure shows the relation between the PV reference point and the control palettes.
	PV Measurement value (PV)
	rEF7Control palette 7
	rEF6
	rEF5
	rEF4 Control palette 3
	rEF3 Control palette 2
	Control palette 1 Control parameter  t

### 2) PLT n (Ch1-9)

- · When PLTS is set to PLTn, set the No. of control palette used for operation.
- · When PLTS is set to SV or PV, No. of control palette currently used for operation is displayed. PLTn parameter cannot be set in this case.

#### [Note]

- 1) Before using the palette function, be sure to set rEF1, and rEF7.
- 2) Set as rEF1 < rEF2, ... < rEF7. (Unless the above is met, settings will be ignored.)

## 5-7 Key lock

Lo[ Key lock setting (Setting range: 0 to 5)

### [Description]

### 1) LoC (Ch1-34)

- · Key lock is the function of preventing parameters and set values (SV) from being changed. Note that if the key lock function is made valid, parameters and set values can be displayed.
- · Set LoC (Ch1-34) to 0 to reset the key lock function.
- · Control operation and alarm operation are performed normally even if the key lock function is made valid.
- · The setting of key lock function can be made in the following 6 stages.

	Key operation		Yia communication	
LoC	All	Set value	All	Set value
	parameters	(SV)	parameters	(SV)
0	0	0	0	0
1	Х	X	0	0
2	Х	0	0	0
3	0	0	Х	Х
4	Х	X	Х	Х
5	Х	0	Х	X

<sup>○:</sup>Setting allowed X:Setting not allowed

## 5-8 Setting output direction at the input error burnout

**brd** Burnout direction setting (Setting range: HOLD, LO, UP, EXMV, POFF)

### [Description]

### 1) brd1(Ch9-35)

· Set the value of operation output (MV) at the time of input error. Output value can be selected from the following 5 types.

brd1	Operation output (MV) at the time of input error
hold	OPEN or CLOSE signal is output so that the valve opening degree input (MVRB) will coincide with operation output value (MV) right after the burnout.
LO	CLOSE signal remains on.
UP	OPEN signal remains on
EX-MV	OPEN or CLOSE signal is output so that the valve opening degree input (MVRB) will coincide with EXM1 (Ch2-97) setting.
POFF	Turns off OPEN, and CLOSE signals, arranging control output (MV) to join the valve opening feedback (MVRB).

\* See section 5-22 "EX-MV function" for details of EXM1 setting.

Error display

Error dispic	ay .
Display	Cause
	1) Burnout of thermocouple sensor
IIIIII	2) Burnout of resistance bulb
UUUU	3) PV reading exceeds upper limit value +5%FS.
	4) RCJ module is not mounted (thermocouple input).
LLLL	1) LLLL display appears for a moment when resistance bulb
LLLL	sensor (line B) breaks.

- · If even one of the inputs related to mathematical expressions (PV1, PV2, Ai1) burns out when Math function (TPLT (Ch8-92)=30 or 31) is performed, the main unit is brought into burnout state.
- \* See section 5-14 for details of Math function.
- \* See section 3-1 for details of control templates.

### 5-9 User adjustment

Zero adjustment value setting of PV1 input (Setting range: –50% to 50%)

P<sub>-</sub> 15 | Span adjustment value setting of PV1 input (Setting range: –50% to 50%)

### [Description]

### PV1Z (Ch8-6), PV1S (Ch8-7)

- · User calibration function is independent of the adjusted value of the controller main unit. If 0 is set to this parameter, factory-set status can be restored.
- 1) Before starting calibration using this parameter, provide the following devices.
  - · Generator

1 to 5V (For voltage input)

0 to 100mV (For thermocouple)

0 to 100mA (For current input)

· Dial resistor

100.0 to  $400.0\Omega$  (For resistance bulb input)

2) Apply input equivalent to 0°C.

If the error is out of permissive range, set PV1Z (Ch8-6).

(See the following example for setting method.)

3) Apply input equivalent to 100°C.

If the error is out of permissive range, set PV1S (Ch8-7).

(See the following example for setting method.)

#### [Example of adjustment for input range of 0 to 400°C]

Before adjustment	Adjusted value	After adjustment
Reading at 0°C input: -1°C	PV1Z: 1	Reading at 0°C input: 0°C
Reading at 400°C input: 402°C	PV1S: -2	Reading at 400°C input: 400°C

If 0 is set both to PV1Z and PV1S parameters, factory-set calibration status is restored.

#### [Note]

· Check the value of each input with monitoring parameters in Ch7 (MON).

To adjust thermocouple input, set parameter rCJ1 to OFF before performing operation in [item 2)] above, and when the operation in [item 3)] above is completed, set it to ON again.

See section 5-21 "Parameter mask" for procedure of displaying parameter rCJ.

$$\left(\frac{\text{rCJ1 display mask=20-6}}{\text{rCJ2 display mask=21-6}}\right)$$

- · To use it as input offset, set the same value to PV1Z and PV1S. The shift is made by the set value.
- To adjust PV2, set PV2Z (Ch8-19) and PV2S (Ch8-20).

  To adjust Ai1, set Ai1Z (Ch8-45) and Ai1S (Ch8-46). (If the 5th digit of code of motorized valve control type (with PFB) is "D", the valve opening degree feedback value is affected by user adjustment.)

# 5-10 Digital input (Di) function

### [Description]

di01 (Ch9-39) to di04 (Ch9-42)

dil1 (Ch9-43) to dil5 (Ch9-47) [only for 9 digital input point model.]

Select each Di function with Di setting parameter, and set Di to ON to operate.

			Operation	Conditions	
Di1 to Di15 setting	Function	Status detection		Edge detection	
		ON	OFF	<b>1</b> ON	OFF
0	None	_	ı	_	-
1	STBY (standby)	Standby	RUN	_	-
30	AT (Auto tuning)	_	-	AT start	AT stop
40	Alarm latch reset (Alarm 1) to (Alarm 8) Release all	-	ı	Release all	Latch hold
50 to 57	Timer operation (Alarm 1) to (Alarm 8)	ON	OFF	_	_
60	R-ACK (Remote acknowledge)	Remote	Local	_	_
70	SMV (Manual command)	Manual mode	Auto mode	_	-
80	PV-TRK command (PV tracking)	ON	OFF	-	-
103	EX-MV (External output value)	EX-MV	MV	-	-
140	Switching of the active expression for Math function	Hi selector expression	Lo selector expression	-	-
160		HOLD	RUN	_	-
161	Totalizer start/stop, reset	LATCH	RUN	_	-
162		Reset	ı	_	_
170	Ramp/soak OFF	_	ı	OFF	_
171	Ramp/soak RUN/HOLD	-	ı	RUN	HOLD
172	Ramp/soak RUN	_	I	RUN	-
173	Ramp/soak HOLD	-	ı	HOLD	-
174	Ramp/soak activation pattern No. +1	+1	ı	_	_
175	Ramp/soak activation pattern No. +2	+2	_	_	-
176	Ramp/soak activation pattern No. +4	+4	_	_	-
177	Ramp/soak activation pattern No. +8	+8	_	_	_
178	Ramp/soak activation pattern No. +16	+16	_	_	_

1) Switching between control RUN and Standby (Di setting=1)

· Switching can be done between control RUN and Standby with Di.

ON: Standby OFF: RUN

- 2) Auto tuning start (AT) (Di setting=30)
  - · Switching can be done between Start and Stop of auto tuning.

Auto tuning type	Di		
Auto turning type	ON	→ OFF	
Normal type (NRML)	AT start	AT stop	
Low PV type (LPV)	Ai stait	AT stop	

- \* Type of auto tuning (NRML, LPV) is selected with ATP1 (ChE-1) beforehand.
- 3) Alarm latch reset (Di setting=40)
  - · The latched alarm can be released with this function.

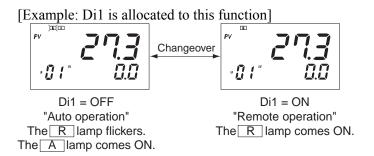
Di setting	Di	
Di setting	ON	OFF
40	Latch release (all alarms)	Latch hold

- 4) Timer operation (Di setting=50 to 57)
  - · When the code is set to 36 to 38 with alarm type setting, timer ON/OFF can be selected. See section 3-11 "Alarm function" for details of timer operation.

ON: Timer operation ON, OFF: Timer operation OFF

Di Setting	Timer operation
50	ALM1
51	ALM2
52	ALM3
53	ALM4
54	ALM5
55	ALM6
56	ALM7
57	ALM8

- 5) R-ACK (Remote acknowledge) (Di setting=60)
  - · Changeover between Auto and Remote can be done with Di.
  - · To use this function, set TPLT (Ch8-92) to 30 or 33, rAC1 (Ch9-11) to EnA, and rEM1 (Ch1-1) to rEM.



- \* After changing TPLT (Ch8-92) setting, be sure to reset the instrument or turn the power on again.
- \* See section 5-16 for details of R-ACK (remote acknowledge).

- 6) SMV (Manual command) (Di setting=70)
  - · Changeover between Auto and Manual operation can be done with Di.
  - · To use this function, set TPLT (Ch8-92) to 30 or 33.

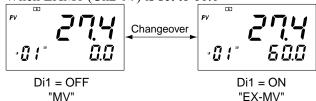
[Example: Di2 is allocated to this function]



- \* After changing TPLT (Ch8-92) setting, be sure to reset the instrument or turn the power on again.
- 7) PV tracking (Di setting=80)
  - · SV value can be tracked to PV value.
  - · Select one Di from Di 1 to 4 or Di 11 to 15, and set it to "80."
  - · Set the selected Di to ON or OFF to perform switching.



- 8) EX-MV (Di setting=103)
  - · Switching between MV (operation output) and EX-MV (external output) can be done with Di.
  - · Set Di to OFF to select MV, and set it to ON to select EX-MV.
  - · When EXM1 (Ch2-97) is set to 60.0



- \* See section 5-22 "EX-MV function" for details.
- 9) Switching the active expression for Math function. (Di setting: 140)
  - · Di input is used as a selector switch between Lo selector/Hi selector expressions in the case of CALC (Ch8-88) is set as follows.

CALC	Name of operation	Di input	
setting	ivalile of operation	OFF	ON
12	H/L selector, 2 points	Lo selector	Hi selector
13	H/L selector, 3 points	Lo selector	Hi selector
32	H/L selector, 2 points (with coefficient)	Lo selector	Hi selector
33	H/L selector, 3 points (with coefficient)	Lo selector	Hi selector

### 10) Totalizer RUN/HOLD and LATCH (Di setting=160, 161)

Di satting		Di
Di setting	OFF	ON
160	RUN	HOLD
161	RUN	LATCH

<sup>\*</sup> See "RUN/HOLD/LATCH" in section 5-26 "Totalizer function" for details.

### 11) Totalizer RESET (Di setting=162)

Di sottino	Di	input
Di setting	OFF	ON
162	=	RESET

<sup>\*</sup> See "Totalize RESET" in section 5-26 "Totalizer function" for details.

### 12) Ramp/soak

Switches the Ramp/soak operation and specify the activation pattern.

DI setting		Di
value	OFF	ON
170	1	Ramp/soak OFF
171	Ramp/soak HOLD	Ramp/soak RUN
172	1	Ramp/soak RUN
173	_	Ramp/soak HOLD
174	_	Ramp/soak activation pattern No. +1
175	_	Ramp/soak activation pattern No. +2
176	_	Ramp/soak activation pattern No. +4
177	_	Ramp/soak activation pattern No. +8
178	-	Ramp/soak activation pattern No. +16

### [Note]

<sup>·</sup> Please refer to "5-30 Ramp/Soak" regarding the Ramp/soak function.

# 5-11 Digital output (Do) function

do l	to	do4	Do allocation setting (Setting range: 0 to 427)
doll	to	do 15	bo anocation setting (Setting range: 0 to 427)

### [Description]

- 1) do1(Ch9-53) to do4(Ch9-56) do11 (Ch9-57) to do15 (Ch9-61) [only for 9 digital output point model]
  - · Select signals to be output to digital output (Do).
  - · Do keeps output even if the input value becomes error (ex. UUUU, LLLL).
  - · If OTYP (Ch8-93) is set to 11 or 13, and MV is allocated, priority is given to MV.

See the following table for the setting.

ne ronowing to	iole for the setting.	
Do Setting	Output signal	
0	No setting	
1	ALM1	
2	ALM2	
3	ALM3	
4	ALM4	
5	ALM5	
6	ALM6	
7	ALM7	
8	ALM8	
17	OR of ALMs	
29	System fault	
41	Totalizer ALM1	
42	Totalizer ALM2	
80	Manual MV (status)	
81	EX-MV command (status)	
82	Remote SV (status)	
83	Local SV (status)	
84	PV tracking (status)	
85	Normal (Direct) action (status)	
86	Auto tuning (AT) (status)	
87	Remote request (status)	
88	Remote acknowledge (R-ACK) (status)	
89	Not-Auto (status)	
90	Mode OR output 1	*1
91	Mode OR output 2	*2
160	Ramp/soak OFF	
161	Ramp/soak RUN	
162	Ramp/soak HOLD	
163	Ramp/soak GS	
164	Ramp/soak END	
•••		
170	Time signal (1st segment)	
171	Time signal (2nd segment)	
	Time signal (3rd to 126th segment)	
		_

1 2

Do Setting	Output signal
296	Time signal (127th segment)
297	Time signal (128th segment)
•••	
300	Relative time signal (1st segment)
301	Relative time signal (2nd segment)
•••	Relative time signal (3rd to 126th segment)
426	Relative time signal (127th segment)
427	Relative time signal (128th segment)

<sup>\*1)</sup> Contents of OR operation: Manual + Auto

<sup>\*2)</sup> Contents of OR operation: Manual + EX-MV

# 5-12 Setting LED allocation

### [Description]

- 1) C1(Ch9-67), C2(Ch9-68) Ldo1(Ch9-69) to Ldo5(Ch9 to 73)
- · Make the setting to change signals to be output to the lamp on the front face.
- · See the following table for the setting.

Ldo1 to Ldo5	C1, C2		
0         No setting           1         ALM1           2         ALM2           3         ALM3           4         ALM4           5         ALM5           6         ALM6           7         ALM7           8         ALM8           17         OR of ALMs           21         Output (MV) 1         *3           22         Output (MV) 2         *3           29         System fault         *4           41         Totalizer ALM1         *42           42         Totalizer ALM2         *3           80         Manual MV (status)           81         EX-MV command (status)           82         Remote SV (status)           83         Local SV (status)           84         PV tracking (status)           85         Normal (Direct) action (status)           86         Auto tuning (AT) (status)           87         Remote request (status)           88         Remote request (status)           89         Not-Auto (status)           90         Mode OR output 1         *1           91         Mode OR output 2         *2	· · · · · · · · · · · · · · · · · · ·	Type	
2		No setting	
3	1		
4         ALM4           5         ALM5           6         ALM6           7         ALM7           8         ALM8           17         OR of ALMs           21         Output (MV) 1         *3           22         Output (MV) 2         *3           29         System fault         *4           41         Totalizer ALM1         *42           80         Manual MV (status)           81         EX-MV command (status)           82         Remote SV (status)           83         Local SV (status)           84         PV tracking (status)           85         Normal (Direct) action (status)           86         Auto tuning (AT) (status)           87         Remote request (status)           88         Remote acknowledge (R-ACK) (Status)           89         Not-Auto (status)           90         Mode OR output 1         *1           91         Mode OR output 2         *2           160         Ramp/soak PUN         *2           161         Ramp/soak HOLD         *2           163         Ramp/soak END         *3           **1         *4 <t< td=""><td>2</td><td>ALM2</td><td></td></t<>	2	ALM2	
5         ALM5           6         ALM6           7         ALM7           8         ALM8           17         OR of ALMs           21         Output (MV) 1         *3           22         Output (MV) 2         *3           29         System fault         *4           41         Totalizer ALM1         *4           42         Totalizer ALM2         *8           80         Manual MV (status)           81         EX-MV command (status)           82         Remote SV (status)           83         Local SV (status)           84         PV tracking (status)           85         Normal (Direct) action (status)           86         Auto tuning (AT) (status)           87         Remote request (status)           88         Remote acknowledge (R-ACK) (Status)           89         Not-Auto (status)           90         Mode OR output 1         *1           91         Mode OR output 2         *2           160         Ramp/soak RUN         *2           161         Ramp/soak HOLD         *3           162         Ramp/soak END         *4           *170	3	ALM3	
6         ALM6           7         ALM7           8         ALM8           17         OR of ALMs           21         Output (MV) 1         *3           22         Output (MV) 2         *3           29         System fault         *4           41         Totalizer ALM1         *42           80         Manual MV (status)           81         EX-MV command (status)           82         Remote SV (status)           83         Local SV (status)           84         PV tracking (status)           85         Normal (Direct) action (status)           86         Auto tuning (AT) (status)           87         Remote request (status)           88         Remote acknowledge (R-ACK) (Status)           89         Not-Auto (status)           90         Mode OR output 1         *1           91         Mode OR output 2         *2           160         Ramp/soak OFF         *1           161         Ramp/soak HOLD         *2           163         Ramp/soak END         *1           **1         *1         *1           170         Time signal (1st segment)         *1 <td>4</td> <td>ALM4</td> <td></td>	4	ALM4	
7         ALM7           8         ALM8           17         OR of ALMs           21         Output (MV) 1         *3           22         Output (MV) 2         *3           29         System fault         *4           41         Totalizer ALM1         *42           80         Manual MV (status)           81         EX-MV command (status)           82         Remote SV (status)           83         Local SV (status)           84         PV tracking (status)           85         Normal (Direct) action (status)           86         Auto tuning (AT) (status)           87         Remote request (status)           88         Remote request (status)           89         Not-Auto (status)           90         Mode OR output 1         *1           91         Mode OR output 2         *2           160         Ramp/soak GF         *1           161         Ramp/soak HOLD         *2           163         Ramp/soak END         *1           **1         *1         *1           170         Time signal (1st segment)         *1           171         Time signal (2nd segment) <td>5</td> <td>ALM5</td> <td></td>	5	ALM5	
S	6	ALM6	
17	7	ALM7	
21	8	ALM8	
22	17	OR of ALMs	
29         System fault           41         Totalizer ALM1           42         Totalizer ALM2           80         Manual MV (status)           81         EX-MV command (status)           82         Remote SV (status)           83         Local SV (status)           84         PV tracking (status)           85         Normal (Direct) action (status)           86         Auto tuning (AT) (status)           87         Remote request (status)           88         Remote acknowledge (R-ACK) (Status)           89         Not-Auto (status)           90         Mode OR output 1         *1           91         Mode OR output 2         *2           160         Ramp/soak OFF         *1           161         Ramp/soak HOLD         *2           162         Ramp/soak GS         *3           164         Ramp/soak END         *1           ***         ***         ***           170         Time signal (1st segment)         *1           171         Time signal (2nd segment)         ***	21		*3
41         Totalizer ALM1           42         Totalizer ALM2           80         Manual MV (status)           81         EX-MV command (status)           82         Remote SV (status)           83         Local SV (status)           84         PV tracking (status)           85         Normal (Direct) action (status)           86         Auto tuning (AT) (status)           87         Remote request (status)           88         Remote acknowledge (R-ACK) (Status)           89         Not-Auto (status)           90         Mode OR output 1         *1           91         Mode OR output 2         *2           160         Ramp/soak OFF         *1           161         Ramp/soak HOLD         *2           163         Ramp/soak GS         *3           164         Ramp/soak END         *3           170         Time signal (1st segment)         *1           171         Time signal (2nd segment)	22		*3
42         Totalizer ALM2           80         Manual MV (status)           81         EX-MV command (status)           82         Remote SV (status)           83         Local SV (status)           84         PV tracking (status)           85         Normal (Direct) action (status)           86         Auto tuning (AT) (status)           87         Remote request (status)           88         Remote acknowledge (R-ACK) (Status)           89         Not-Auto (status)           90         Mode OR output 1         *1           91         Mode OR output 2         *2           160         Ramp/soak OFF         161         Ramp/soak HOLD           163         Ramp/soak HOLD         163         Ramp/soak END            170         Time signal (1st segment)           171         Time signal (2nd segment)	29		
80         Manual MV (status)           81         EX-MV command (status)           82         Remote SV (status)           83         Local SV (status)           84         PV tracking (status)           85         Normal (Direct) action (status)           86         Auto tuning (AT) (status)           87         Remote request (status)           88         Remote acknowledge (R-ACK) (Status)           89         Not-Auto (status)           90         Mode OR output 1         *1           91         Mode OR output 2         *2           160         Ramp/soak OFF         *1           161         Ramp/soak HOLD         *2           163         Ramp/soak GS         *3           164         Ramp/soak END         *1           170         Time signal (1st segment)         *1           171         Time signal (2nd segment)	41	Totalizer ALM1	
81         EX-MV command (status)           82         Remote SV (status)           83         Local SV (status)           84         PV tracking (status)           85         Normal (Direct) action (status)           86         Auto tuning (AT) (status)           87         Remote request (status)           88         Remote acknowledge (R-ACK) (Status)           89         Not-Auto (status)           90         Mode OR output 1         *1           91         Mode OR output 2         *2           160         Ramp/soak OFF         *1           161         Ramp/soak HOLD         *2           163         Ramp/soak GS         *3           164         Ramp/soak END         *1           170         Time signal (1st segment)         *1           171         Time signal (2nd segment)	42	Totalizer ALM2	
82         Remote SV (status)           83         Local SV (status)           84         PV tracking (status)           85         Normal (Direct) action (status)           86         Auto tuning (AT) (status)           87         Remote request (status)           88         Remote acknowledge (R-ACK) (Status)           89         Not-Auto (status)           90         Mode OR output 1         *1           91         Mode OR output 2         *2           160         Ramp/soak OFF         *2           161         Ramp/soak HOLD         *2           162         Ramp/soak GS         *3           164         Ramp/soak END         *3           170         Time signal (1st segment)           171         Time signal (2nd segment)	80	Manual MV (status)	
83         Local SV (status)           84         PV tracking (status)           85         Normal (Direct) action (status)           86         Auto tuning (AT) (status)           87         Remote request (status)           88         Remote acknowledge (R-ACK) (Status)           89         Not-Auto (status)           90         Mode OR output 1         *1           91         Mode OR output 2         *2           160         Ramp/soak OFF           161         Ramp/soak HOLD           162         Ramp/soak GS           164         Ramp/soak END            Time signal (1st segment)           170         Time signal (2nd segment)	81		
84         PV tracking (status)           85         Normal (Direct) action (status)           86         Auto tuning (AT) (status)           87         Remote request (status)           88         Remote acknowledge (R-ACK) (Status)           89         Not-Auto (status)           90         Mode OR output 1         *1           91         Mode OR output 2         *2           160         Ramp/soak OFF           161         Ramp/soak HOLD           162         Ramp/soak GS           164         Ramp/soak END            Time signal (1st segment)           170         Time signal (2nd segment)	82	Remote SV (status)	
85         Normal (Direct) action (status)           86         Auto tuning (AT) (status)           87         Remote request (status)           88         Remote acknowledge (R-ACK) (Status)           89         Not-Auto (status)           90         Mode OR output 1         *1           91         Mode OR output 2         *2           160         Ramp/soak OFF           161         Ramp/soak HOLD           162         Ramp/soak GS           164         Ramp/soak END            Time signal (1st segment)           171         Time signal (2nd segment)	83	Local SV (status)	
86         Auto tuning (AT) (status)           87         Remote request (status)           88         Remote acknowledge (R-ACK) (Status)           89         Not-Auto (status)           90         Mode OR output 1         *1           91         Mode OR output 2         *2           160         Ramp/soak OFF           161         Ramp/soak RUN           162         Ramp/soak HOLD           163         Ramp/soak GS           164         Ramp/soak END            Time signal (1st segment)           171         Time signal (2nd segment)	84	PV tracking (status)	
87         Remote request (status)           88         Remote acknowledge (R-ACK) (Status)           89         Not-Auto (status)           90         Mode OR output 1         *1           91         Mode OR output 2         *2           160         Ramp/soak OFF           161         Ramp/soak RUN           162         Ramp/soak HOLD           163         Ramp/soak GS           164         Ramp/soak END            Time signal (1st segment)           171         Time signal (2nd segment)	85	Normal (Direct) action (status)	
88         Remote acknowledge (R-ACK) (Status)           89         Not-Auto (status)           90         Mode OR output 1         *1           91         Mode OR output 2         *2           160         Ramp/soak OFF         *1           161         Ramp/soak RUN         *1           162         Ramp/soak HOLD         *1           163         Ramp/soak GS         *1           164         Ramp/soak END         **1           ***         ***         ***           170         Time signal (1st segment)         ***           171         Time signal (2nd segment)		• 7	
89         Not-Auto (status)           90         Mode OR output 1         *1           91         Mode OR output 2         *2           160         Ramp/soak OFF         *1           161         Ramp/soak RUN         *1           162         Ramp/soak HOLD         *1           163         Ramp/soak GS         *1           164         Ramp/soak END         **1           170         Time signal (1st segment)         *1           171         Time signal (2nd segment)			
90         Mode OR output 1         *1           91         Mode OR output 2         *2           160         Ramp/soak OFF         *1           161         Ramp/soak RUN         *1           162         Ramp/soak HOLD         *1           163         Ramp/soak GS         *1           164         Ramp/soak END         **1           **1         Time signal (1st segment)         **1           171         Time signal (2nd segment)		Remote acknowledge (R-ACK) (Status)	
91         Mode OR output 2         *2           160         Ramp/soak OFF         *1           161         Ramp/soak RUN         *1           162         Ramp/soak HOLD         *2           163         Ramp/soak GS         *3           164         Ramp/soak END         **2           170         Time signal (1st segment)         **2           171         Time signal (2nd segment)			
160         Ramp/soak OFF           161         Ramp/soak RUN           162         Ramp/soak HOLD           163         Ramp/soak GS           164         Ramp/soak END            Time signal (1st segment)           171         Time signal (2nd segment)			*1
161 Ramp/soak RUN 162 Ramp/soak HOLD 163 Ramp/soak GS 164 Ramp/soak END 170 Time signal (1st segment) 171 Time signal (2nd segment)			*2
162 Ramp/soak HOLD 163 Ramp/soak GS 164 Ramp/soak END 170 Time signal (1st segment) 171 Time signal (2nd segment)	160		
163 Ramp/soak GS 164 Ramp/soak END  170 Time signal (1st segment) 171 Time signal (2nd segment)	161	Ramp/soak RUN	
164 Ramp/soak END  170 Time signal (1st segment) 171 Time signal (2nd segment)	162	Ramp/soak HOLD	
170 Time signal (1st segment) 171 Time signal (2nd segment)	163	Ramp/soak GS	
170 Time signal (1st segment) 171 Time signal (2nd segment)	164	Ramp/soak END	
171 Time signal (2nd segment)			
8 8	170	Time signal (1st segment)	
··· Time signal (3rd to 126th segment)	171	Time signal (2nd segment)	
		Time signal (3rd to 126th segment)	

C1, C2 Ldo1 to Ldo5	Туре
296	Time signal (127th segment)
297	Time signal (128th segment)
300	Relative time signal (1st segment)
301	Relative time signal (2nd segment)
	Relative time signal (3rd to 126th segment)
426	Relative time signal (127th segment)
427	Relative time signal (128th segment)

<sup>\*1)</sup> Contents of OR operation: Manual + Auto

<sup>\*2)</sup> Contents of OR operation: Manual + EX-MV

<sup>\*3)</sup> The lamp does not come ON for current (4 to 20mA) output type.

# 5-13 Function key

FI	to <b>F3</b>	Function key allocation setting (Setting range: 0 to 72)
----	--------------	--

### [Description]

F1(Ch9-32) to F3(Ch9-34)

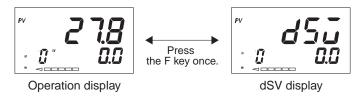
• Functions listed in the following table can be allocated to the F1, F2, and the F3 keys. The F1, F2, and the F3 keys are collectively called referred to as F key.

	F3 keys are collectively called referred to as F key.
F key setting (Function key code)	Key operation
0	No function
1	dSV display Changeover between Remote and Auto (Press for 2 seconds.) Note 1
2	Standby/RUN changeover
3	Alarm latch reset
10	AT (Auto tuning) START/STOP
20	Timer operation start/stop (ALM 1)
21	Timer operation start/stop (ALM 2)
22	Timer operation start/stop (ALM 3)
23	Timer operation start/stop (ALM 4)
24	Timer operation start/stop (ALM 5)
25	Timer operation start/stop (ALM 6)
26	Timer operation start/stop (ALM 7)
27	Timer operation start/stop (ALM 8)
30	Totalizer RUN/HOLD
31	Totalizer RUN/LATCH
32	Totalizer RESET
41	Transfer of SV1 to local SV
42	Transfer of SV2 to local SV
43	Transfer of SV3 to local SV
44	Transfer of SV4 to local SV
45	Transfer of SV5 to local SV
46	Transfer of SV6 to local SV
47	Transfer of SV7 to local SV
50	Selection of palette 0
51	Selection of palette 1
52	Selection of palette 2
53	Selection of palette 3
54	Selection of palette 4
55	Selection of palette 5
56	Selection of palette 6
57	Selection of palette 7
60	Parameter jump 1
61	Parameter jump 2
62	Parameter jump 3
70	Change over the "RUN/OFF" of Ramp/soak
71	Change over the "RUN/HOLD" of Ramp/soak
72	Send pattern No.+1

Note 1: Do not use this setting when TPLT (Ch8-92) is set to 11 or 14.

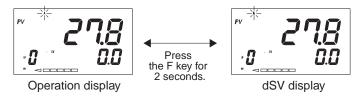
1) dSV display Remote/Auto changeover (Function key code=1)

Press the F key once. : By pressing the F key once on the operation display, the dSV display and the PV/SV operation display (or PV/MV operation display) can be displayed alternately.



Note: Switching between the operation display and the dSV display can be done both in Auto and Remote operation modes.

• Press the F key for 2 seconds. : By pressing the F key for 2 seconds on the operation display, changeover between Remote and Auto operations is executed.



· How to use the dSV display

Use the dSV display to balance the Remote SV and the Local SV when switching operation mode from Auto to Remote.

(When operation is switched from Remote to Auto, the set value (SV) is automatically balanced, which is SV tracking function.)

 $dSV = Local \ SV - Remote \ SV$  [Example of use] Operation mode = Auto Local  $SV = 50.0^{\circ}C$  Remote  $SV = 200.0^{\circ}C$  dSV =  $-150.0^{\circ}C$  (  $=50.0^{\circ}C - 200.0^{\circ}C$ ) is displayed.

Procedure 1: Press the F key once to show the dSV display.

Procedure 2:Using the ▶, ▲, and the ▼ key, change the value of dSV from −150.0 to 0.0. (When dSV is set 0.0, the Local SV becomes equal to the Remote SV.)

Procedure 3: Press the F key for 2 seconds to switch operation from Auto to Remote.

(The controller is operated with the Remote SV (externally set signal) regarded as target set value.)

#### [Note]

- · If the operation cannot be switched from Auto to Remote by the procedures shown above, check rAC (Ch9-11) parameter. See section 5-16 "Remote acknowledge (R-ACK) function" for details of rAC parameter.
- · If the set value (SV) cannot be automatically balanced when operation is switched from Remote to Auto, check Trk1 (Ch9-23) parameter.

See section 5-19 "SV tracking function" for details of Trk1 parameter.

- 2) Standby/RUN changeover (Function key code=2)
  - · Control can be switched between RUN and Standby with the F key.
  - · Press the F key for 1 second to switch.

Press the F key for 1 second.

RUN Standby

- \* See section 4-5 for details of function.
- 3) Alarm latch reset (Function key code=3)
  - · The latched alarm can be released with this function.
- 4) Auto tuning (AT) (Function key code=10)

· Auto tuning start and stop can be switched.

Type of auto tuning	F key	F key
Standard Low PV	AT start	AT stop

- \* See section 3-10 "AT (Auto tuning)" for details.
- 5) Timer operation (Function key code=20 to 27)
  - · When alarm type code is set to 36 to 38 with alarm function, timer ON/OFF can be selected. See section 3-11 "Alarm function" for details of timer operation.
- 6) Totalizer START/HOLD/LATCH and RESET operation (Function key code = 30 to 32)

Use this function to perform totalizer operation control.

The following functions can be allocated to function keys.

<u> </u>		-9
Function key	Function	Note
30	RUN / HOLD	Every time the function key is pressed
31	RUN / LATCH	Every time the function key is pressed
32	RESET	Press the function key for 1 second

- 7) Local SV switching (Function key code = 41 to 47)
  - · The settings for palettes 1 to 7, SV1 to SV7, can be used as Local SV.
  - · Press the F key for 1 second to make.
  - · Switching can be made only when PV/SV is displayed on the operation screen.
    - \* This function is available even when operation is performed in SV selectable controller.
    - \* This function is available even when Remote operation is performed.
    - (1) Operation is performed with switched SV at the time of  $R \rightarrow A$ , if SV tracking function is OFF.
    - (2) Operation is performed with Remote SV at the time of  $R \rightarrow A$ , if SV tracking function is ON.
- 8) Palette number selection (Function key code = 50 to 57)
  - · Use this function to switch palette numbers (PLTn parameter).
  - · Palette number 0 means Local PID control parameters. (Ch2 Pid)
  - · Palette numbers 1 to 7 mean control palettes. (Ch3 PLT)
  - · Press the F key for 1 second to make.
  - · Switching can be made only when PV/SV is displayed on the operation screen.

- 9) Parameter jump (Function key code = 60 to 62)
  - · Use the function to jump to set parameters specified beforehand.
  - The destination of the jump is the parameter set in "JP parameter setting."
  - · Press the key once to jump to the specified parameter.
  - · Jump can also be made on the operation, parameter display, and monitor screens.

Function key	Function	Parameter for setting destination of jump
60	Parameter jump 1	JP1 (Ch1 - 35)
61	Parameter jump 2	JP2 (Ch1 - 36)
62	Parameter jump 3	JP3 (Ch1 - 37)

See "JP parameter setting" on the next page for details of jump destination parameter setting.

- \* "PAS1" is displayed if a masked parameter or channel is specified and the F key is pressed.
- \* Even if the F key is pressed while parameter setting is performed, jump to a parameter does not occur.

#### 10) Ramp/soak

- · When Ramp/soak operation setting is set, following can be used.
- · Following functions can be allocated to the function key.

Function key	Function	Note
70	RUN/OFF	Everytime press the function key, Ramp/soak RUN/OFF will be changed over.
71	RUN/HOLD	Everytime press the function key, Ramp/soak RUN/HOLD will be changed over.
72	Current Ramp/soak activation pattern +1	Sends the Ramp/soak pattern №+ 1

Note: Ramp/soak activation pattern chaged over by function key "72" will be changed over by pattern selection Max. and Min. setting (PTnM,PMin)

Please refer to "5-30 Ramp/Soak" concerning pattern selection Max. and Min. setting.

# **リア** to **リア** JP parameter setting (Setting range: 1-01 to z-z9)

### [Description]

### JP1 (Ch1-35), JP2 (Ch1-36), JP3 (Ch1-37)

Enabled when parameter jump function is allocated to function keys

The parameter to which the jump is to be made can be set.

See the following table for the function key setting and parameters to which, jump is to be made.

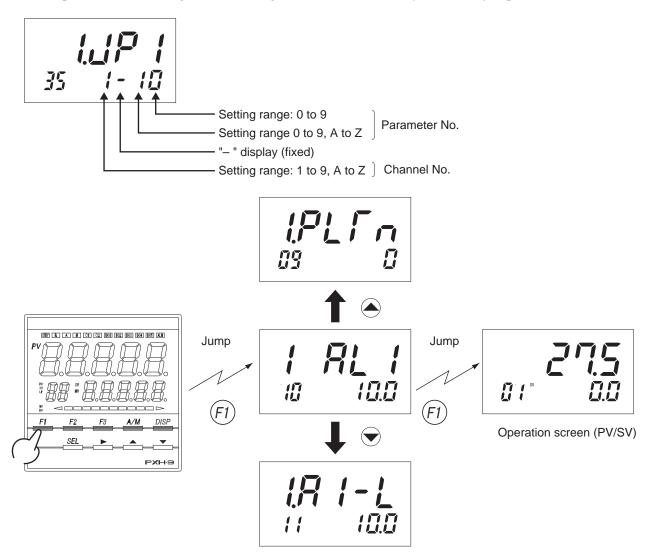
JP parameter	Function key setting
JP1 (Ch1-35)	60
JP2 (Ch1-36)	61
JP3 (Ch1-37)	62

#### 1) JP parameter setting method

Parameters can be allocated as JP parameters as follows.

Use channels and parameter numbers to make parameter setting.

[Example] When allocating alarm 1 setting AL1 (ch1-10) to F1 key to make a jump



\* After a jump is made, transfer between parameters and setting can be made as usual.

## 5-14 Math function

[RL[ Math function type setting (Setting range: 0 to 40)

☐ ☐ F I | Scale of Math function on the full side

Setting range: –19999 to 99999)

じにも ! Scale of Math function on the base side

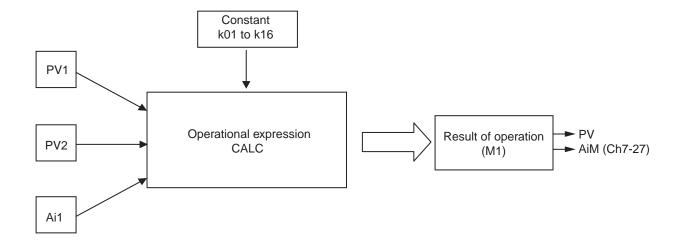
ロロ Decimal point position of Math function (Setting range: 0 to 3)

**EDI** to **EIB** The constant for expression (Setting range: –9999 to 99999)

### [Description]

What is Math function?

By substituting arbitrary values into input value (PV1, PV2, Ai1) and constant (k01 (ChD-1) to k16 (ChD-16)), the result of operation M1 can be used as PV, which is called Math function. (See the following figure.)



Set the control template TPLT (Ch8-92) to 30 or 31 to use Math function.

#### [IMPORTANT]

In the case of using the result of operation (M1) as PV, the scale of PID operation (i.e. Full Scale) is defined with UCF1, UCb1, and UCd1.

## 1) CALC (Ch8-88)

Select the type of arithmetic expressions.
 There are 24 types of arithmetic expressions.

P	e are 24 types of arith	metic expressions. (See the following table.)
CALC setting	Name of operation	Arithmetic expression
0	No math operation	M1 = PV1 input
1	Mathematical expression 1 (Flow rate compensation with temperature and pressure)	M1 = k01 X $\sqrt[*1]{\text{PV1}}$ X $\sqrt[*2]{\frac{\text{Ai1} + \text{k02}}{\text{k03}}}$ X $\frac{\text{k04}}{\text{PV2} + \text{k05}}$ PV1: Flow rate (differential pressure), PV2: Temperature, Ai1: Pressure
2	Mathematical expression 2 (Flow rate compensation with temperature and pressure)	M1 = k01 X PV1 X $\sqrt[*1]{\frac{\text{Ai1} + \text{k02}}{\text{k03}}}$ X $\frac{\text{k04}}{\text{PV2} + \text{k05}}$ PV1: Flow rate (differential pressure), PV2: Temperature, Ai1: Pressure
3	Mathematical expression 3 (Flow rate compensation with temperature and pressure)	M1 = k01 x PV1 x $\frac{\text{Ai1+k02}}{\text{k03}}$ x $\frac{\text{k04}}{\text{PV2+k05}}$ PV1: Flow rate (differential pressure), PV2: Temperature, Ai1: Pressure
4	Mathematical expression 4	$M1 = \frac{(k01 \ X \ (k02 \ X \ PV1 + k03 \ X \ PV2 + k04 \ X \ Ai1) + k05)}{(k06 \ X \ (k07 \ X \ PV1 + k08 \ X \ PV2 + k09 \ X \ Ai1) + k10)}$
5	Mathematical expression 5	$M1 = \frac{(k01 \text{ X} ((k02 \text{ X} \text{ PV1} + k03) \text{ X} (k04 \text{ X} \text{ PV2} + k05) \text{ X} (k06 \text{ X} \text{ Ai1} + k07)) + k08)}{(k09 \text{ X} ((k10 \text{ X} \text{ PV1} + k11) \text{ X} (k12 \text{ X} \text{ PV2} + k13) \text{ X} (k14 \text{ X} \text{ Ai1} + k15)) + k16)}$
6	Mathematical expression 6	M1 = k01 X PV1 X (k02 X PV2 + k03 X Ai1) + k04 X Ai1 + k05
7	H selector (2 points)	M1 = Max (PV1, PV2) PV1 or PV2, whichever is larger, is selected.
8	L selector (2 points)	M1 = Min (PV1, PV2) PV1 or PV2, whichever is smaller, is selected.
9	H selector (3 points)	M1 = Max (PV1, PV2, Ai1)
10	L selector (3 points)	PV1, PV2, or Ai1, whichever is largest, is selected.  M1 = Min (PV1, PV2, Ai1) PV1, PV2, or Ai1, whichever is smallest, is selected.
11	Input switching (2 points)	M1 = PV1 when PV1 ≦k01, M1 = PV2 when PV1 > k01
12	H/L selector (2 points) (with Di switching function)	Expression 7 or 8 is used by Di switching. (Specify "140" for Di function for switching.)
13	H/L selector (3 points) (with Di switching function)	Expression 9 or 10 is used by Di switching. (Specify "140" for Di function for switching.)
20	Flow rate compensation with temperature and pressure [% value operation]	M1 = √PV1
21	Flow rate compensation with temperature and pressure [% value operation] (without square-root extraction)	M1 = PV1 (Ai1 X k01) + k02 (PV2 X k03) + k04  All the inputs and constants are of the same specifications as mathematical expression 20.
27	H selector (2 points) (with coefficient)	M1 = max ((PV1 X k01 + k02), (PV2 X k03 + k04))
28	L selector (2 points) (with coefficient)	M1 = min ((PV1 X k01 + k02), (PV2 X k03 + k04))
29	H selector (3 points) (with coefficient)	M1 = max ((PV1 X k01 + k02), (PV2 X k03 + k04), (Ai X k05 + k06))
30	L selector (3 points) (with coefficient)	M1 = min ((PV1 X k01 + k02), (PV2 X k03 + k04), (Ai X k05 + k06))
31	Input switching (2 points) (with coefficient)	$ M1 = (PV1 \ X \ k02 + k03) \ when \ k01 > (PV1 \ X \ k02 + k03) $ $ M1 = (PV2 \ X \ k04 + k05) \ when \ k01 \leqq (PV1 \ X \ k02 + k03) $
32	H/L selector (2 points) (with Di switching function)	Expression 27 or 28 is used by Di switching. (Specify "140" for Di function for switching.)
33	H/L selector (3 points) (with Di switching function)	Expression 29 or 30 is used by Di switching. (Specify "140" for Di function for switching.)
34	Input switching (2 points) (with coefficient and interpolation function)	When PV1 ≤ k05 : M1 = (PV1 X k01) + k02 When PV2 ≤ k06 : M1 = (PV2 X k03) + k04 When PV1 > k05 and PV2 < k06 : Interpolation shown below, is executed. M1 = $\left(1 - \frac{(PV1 X k01 + k02) - k05}{k06 - k05}\right)$ X (PV1 X k01 + k02) - k05 - $\left(\frac{(PV1 X k01 + k02) - k05}{k06 - k05}\right)$ X (PV2 X k03 + k04) * note) k05 : Input switching upper value k06 : Input switching lower value
40	Calorie calculation	M1 = ((PV1 X k01 + k02) - (PV2 X k03 + k04)) X (Ai1 X k05 + k06))
	l .	

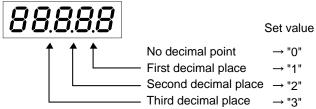
<sup>\*1:</sup> Square-root extraction cut point can be set with k06.
\*2: Square-root extraction cut point can be set with k07.

### 2) UCF1 (Ch8-89) UCb1 (Ch8-90)

• The scale of the full side (upper limit) and the base side (lower limit) of the result of operation used for control operation can be set. This scale becomes the scale of PID operation.

#### 3) UCd1 (Ch8-91)

· Select the decimal point position of the result of Math operation.



If CALC (CH8-88) is set to 0 (no operation) when TPLT is set to 10, 11 or 16, PV1 becomes the result of operation, and the scale used for PID operation becomes UCF1 (Ch8-89), UCB1 (Ch8-90) and UCD1 (Ch8-91).

### 4) k01 (Chd-1) to k16 (Chd-16)

· Substitute proper values into constant k01 (Chd-1) to k16 (Chd-16). [Setting method]

Setting method of constant is different from the method of setting other parameters.

Press the key, and digit selection is changed in the order from the 1st, 5th, decimal point, 4th, 3rd, 2nd, and back to the 1st.

Press the key to move the decimal point to the left, and press the key to move it to the right. When it is moved to the end, it is then moved to the other end.





# 5-15 Remote operation prohibition

 right
 Remote operation prohibition setting (Setting range: ON, OFF)

## [Description]

- 1) rih1 (Ch9-7)
  - · Remote operation can be prohibited. (See the following table.)
  - · Use this function when remote operation function is not required.

rīh!	Remote operation
OFF	Allowed
ON	Prohibited

When rih1 is set to ON, R-ACK of Di function, SV selection of Di function, remote operation function with REM1 parameter, and remote operation function at the time of power ON cannot be used.

# 5-16 Remote acknowledge (R-ACK) function

## [Description]

## 1) rAC1(Ch9-11)

- · Setting of permission of switching to Remote/Auto operation can be made with Di.
- To use this function, set TPLT (Ch8-92) to 30 or 33, rAC1 (Ch9-11) to EnA, rEM (Ch1-1) to rEM, and 60 (Remote acknowledge) to either of Di01 to Di15 (Ch9-39 to 47).

Setting	Explanation
EnA (Enable)	"Remote mode" allowed with Di
Inh (inhblt)	"Remote mode" prohibited with Di

Operation mode	Di (R-Ack)	Indication lamp status		
Remote	ON	R ON,		
Auto	OFF	R flickers, A ON		
Manual	ON	M ON, R flickers		
Manual	OFF	M ON, A flickers		

# 5-17 Manual operation prohibition

**R-71** Setting manual operation prohibition (Setting range: A-M, A)

## [Description]

### 1) A-M1(Ch9-15)

- · Manual operation can be prohibited. (See the following table.)
- · Use this function when manual operation function is not required.

Setting	Manual operation
A-M	Allowed
A	Prohibited

When manual operation is prohibited, forced manual operation (SMV) and manual power ON by Di function cannot be performed.

# 5-18 Operation mode at the time of power ON

[nd | Operation mode setting at the time of power ON (Setting range: A, R, M)

### [Description]

## 1) Cnd1(Ch9-19)

- · Operation mode at the time of power ON can be set.
- · Operation mode can be selected from the following three options below.
  - A: Auto operation
  - R: Remote operation
  - M: Manual operation
- Setting Cnd1 to R (Remote operation)
   Under Remote operation prohibition setting, the instrument is started by Manual operation when SMV of Di function is set to ON, and in other cases, it is started by Auto operation.
- · Setting Cnd1 to M (Manual operation)
  Under Manual switching prohibition setting, the instrument is started by Remote operation when R-Ack of Di function is set to ON and rEM1 (Ch1-1) is set to rEM in SV selection, and in other cases, it is started by Auto operation.
- \* See section 4-1 "Auto operation," section 4-2 "Manual operation," and section 4-3 "Remote operation" for details of each operation.

# 5-19 SV tracking function

「「」」 SV tracking function ON/OFF setting (Setting range: ON, OFF)

## [Description]

### 1) TRK1(Ch9-23)

· Tracking of RSV (remote SV) to LSV (local SV) is allowed when operation is switched from Remote to Auto, which is called SV tracking function.

ON: Tracking is performed. (Local SV = Remote SV)

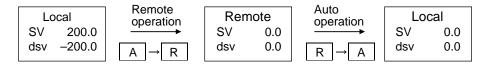
OFF: Tracking is not performed. (Local SV ≠ Remote SV)

Local value at the time of switching to remote operation is restored.

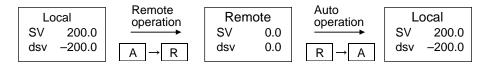
### [Example]

When TPLT (Ch8-92) is set to 30 or 33, Local SV is set to 200.0, and Remote SV is set to 0.0

#### When Trk1 = ON



#### When Trk1 = OFF



\* See section 3-1 "Setting control template" for details of TPLT (Ch8-92).

### [Note]

- · If setting is changed from Remote SV to Local SV during Manual operation, the instrument operates as shown above.
- · During Remote operation, SV tracking setting is used when setting is changed from Remote SV to Local SV both in auxiliary input Ai1 and SV selection methods.
- When operation is switched to remote SV operation during Ramp/soak and then switched to local SV operation again, SV value will be switched to Ramp/soak SV value even though SV tracking function is set to ON.

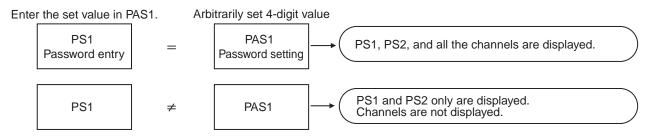
## 5-20 Password

P5 | P52 Password entry (Setting range: 0000 to FFFF)

PR5 | PR52 PR53 Password setting (Setting range: 0000 to FFFF)

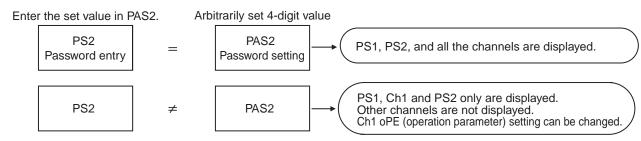
### [Description]

1) PS1-PAS1 (The function prevents people other than the administrator from changing the setting of this instrument.)



<sup>\*</sup> Please be sure to note the registered password.

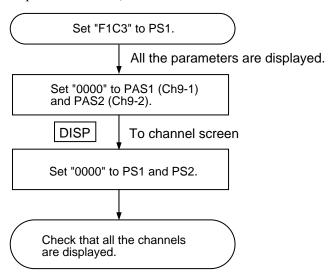
# 2) PS2-PAS2 (The function prevents people other than the administrator from changing the settings except for Ch1 oPE (operation parameter).)



<sup>\*</sup> Please be sure to note the registered password.

#### [Note]

· If the password is lost,



- \* If "F1C3" is selected, parameters not displayed in normal times are displayed.

  Never change the parameters that are not displayed in normal times. Otherwise a failure may occur.
- \* PAS3 is for maintenance work. Never change the setting. Otherwise a failure may occur.

## 5-21 Parameter mask

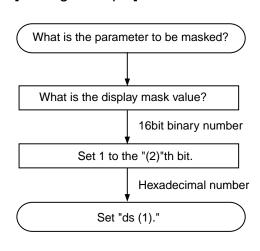
d500 to d543 Parameter mask setting (Setting range: 0000 to FFFF)

## [Description]

### 1) ds00(Ch9-80) to ds43(Ch9-C3)

- · Unnecessary (unused) parameters can be masked (non-display).
- · This function can be used to prevent settings from being changed by mistake.
- · See "Display mask" in the parameter list for correspondence between ds00 (Ch9-80) to ds43 (Ch9-C3) setting and parameters to be masked (non-display).
- · See the following setting example for setting method.

## [Setting example]



## [Example] TC1

Parameter mask definition is below (See Appendix 2 Parameter List).

$$\frac{03}{(1)} - \frac{13}{(2)}$$

4th digit	3rd digit	2nd digit	1st digit	Digit of hexadecimal number
13	9	5	1	No. of digits of binary number
0 0 0 1	0000	0000	0000	Binary number
1	0	0	0	Hexadecimal number
	1000( I	16)		
	Ţ			

Set 1000 to ds03 to mask TC1.

#### Note:

· When the setting of the parameter (dsxx) whose setting is to be changed is other than 0, add current set value to the value calculated as shown above.

Factory-set value of ds00 to ds44

1 400	0.9 000 10	aiao o	1 4000 10	4011					
ds	Set value	ds	Set value	ds	Set value	ds	Set value	ds	Set value
00	8000	10	0002	20	0038	30	00EE	40	00FC
01	002E	11	0002	21	0038	31	0404	41	01FF
02	0000	12	0002	22	01FF	32	1D00	42	01FF
03	4622	13	0002	23	001A	33	0000	43	01FF
04	FFFF	14	0002	24	01dF	34	FF00	44	0018
05	FFFF	15	0000	25	80FC	35	0003		
06	FFFF	16	003E	26	0018	36	0C31		
07	0002	17	0E24	27	0EEE	37	0314		
08	0002	18	000E	28	0E0E	38	0010		
09	0002	19	0002	29	0007	39	0076		

· Do not display parameters masked at the time of delivery and change the setting. Otherwise a failure may occur.

## 5-22 EX-MV function

**EHII!** External manipulated value setting (Setting range: –25 to 125%)

### [Description]

### 1) EXM1(Ch2-97)

- · OPEN or CLOSE signal is output so that the valve opening degree feedback (or estimated valve position) will be the value of external manipulated value (EXM1).
- · During EX-MV operation, ordinary MV follows EX-MV.
- · To set the control mode to EX-MV, set the EX-MV value and then set Di to ON.

Di input	Output signal
OFF	MV (PID result)
ON	EX-MV

- \* During Manual operation, even if Di allocated with EX-MV is set to ON, EX-MV will not output.
- \* Allocation is made to Di4 of each template at the time of delivery. If EX-MV value is not output when Di4 is set to ON, check if EX-MV (103) is allocated to Di (Ch9-39 to 47).

# 5-23 Setting 2 degrees of freedom PID

**FLP** 1 2 degrees of freedom coefficient  $\alpha$  setting (Setting range: -300.0 to 300.0%))

**b***E* $\Gamma$  / 2 degrees of freedom coefficient  $\beta$  setting (Setting range: 0.0 to 900.0%)

### [Description]

The function is used to suppress overshoot generated in PID control.

The 2 degrees of freedom PID system of this instrument adopts set value (SV) filter method, which is effective at suppressing overshoot at the time of setting change or power ON.

If ALP1 ( $\alpha$ ) is set to 100.0%, and bET1 ( $\beta$ ) to 0.0%), ordinary PID control (1 degree of freedom PID) is performed.

Adjust ALP1 ( $\alpha$ ) and bET1 ( $\beta$ ) as follows.

- 1) Set ALP1 ( $\alpha$ ) to 40.0%, and bET1 ( $\beta$ ) to 100.0%.
- 2) Perform control and check responsibility (overshoot volume).

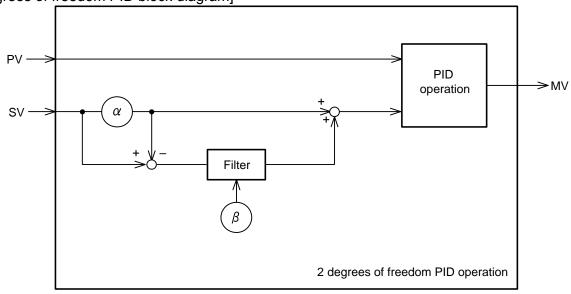
If overshoot cannot be improved in this stage, adjust ALP1 ( $\alpha$ ) and bET1 ( $\beta$ ), following the definition listed in the following table.

If ALP1 ( $\alpha$ ) is generally not required adjusting.

Therefore, it is recommend that you use the instrument with ALP1 ( $\alpha$ ) set to 40.0%.

Result of control	bET1	ALP1
Large overshoot	Increase BET1 (β) by 20%	Decrease ALP1 (α) by 10%
Small overshoot	Decrease BET1 (β) by 20%	Increase ALP1 (α) by 10%

[2 degrees of freedom PID block diagram]



#### [Note]

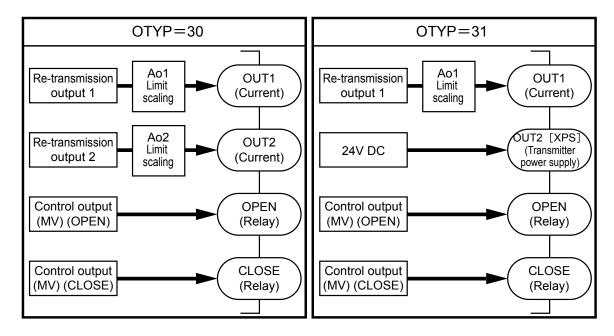
- \* Change the setting of ALP1 (α) in manual mode. Before changing ALP1 (α) setting, set bET1 (β) to 0.0%. Change ALP1 (α) setting, and then set desired value to bET1 (β) again. Improper procedure may cause output (target value) to increase temporarily, thus posing danger.
- \* The purpose of this function is to suppress overshoot generated in ordinary PID control. Overshoot may not always be eliminated.

# 5-24 Setting output type

Output type selection (Setting range: 30, 31)

### [Description]

- · Select a control output type according to applications.
- · See the following figure for each output type.

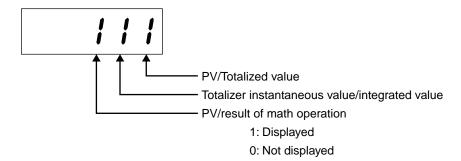


# 5-25 Screen display selection function

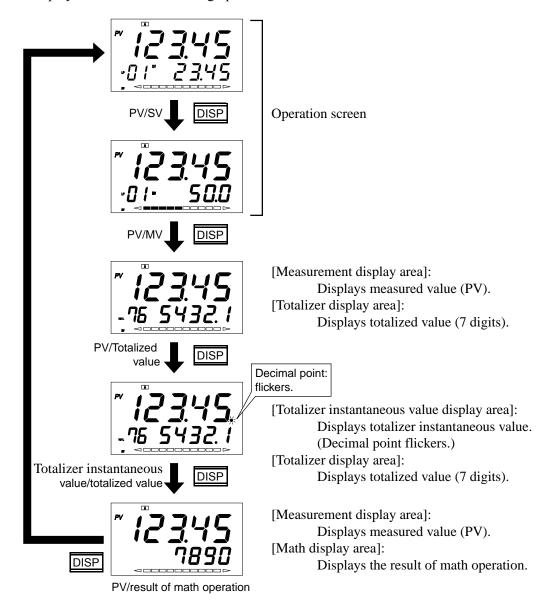
Operation display setting (Setting range: 000 to 111)

### [Description]

Items to be displayed on the operation screen can be selected with parameters. Make the following parameter setting for operation display setting odSP (Ch9-79).



The display shifts as follows during operation.



## 5-26 Totalizer function

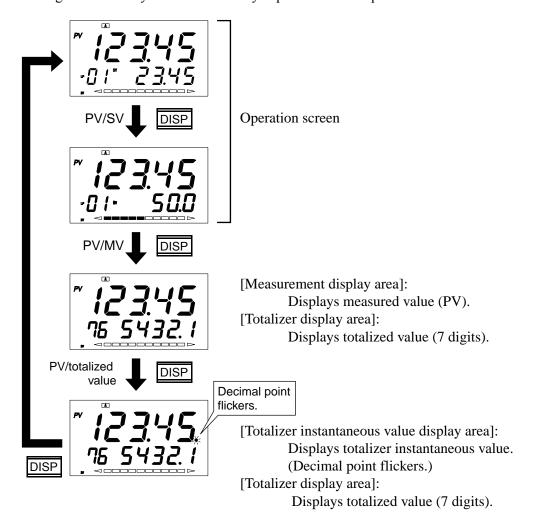
### [Description]

### Description of totalizer function

The totalizer function can be used to select one point from PV1, PV2, Ai1, and AiM, and totalize the input values. The totalized value can be displayed on the screen.

### totalized value display

PV/ totalized value display and totalizer instantaneaus/totalized value display can be displayed on the operation screen using the screen display selection function odSP (Ch9-79). Switching is made every time the DISP key is pressed on the operation screen.



# rnod

Totalizer mode setting (Setting range: 0, 1)

### [Description]

The totalizer function is available in 2 modes, Japanese mode and English mode.

Mode selection is allowed by parameter setting.

Description of each mode and setting method are described below.

### 1) Japanese mode

Calculation is carried out using totalizing factor.

Totalizing factor TCF (ChG-17): Sets the totalized value display when 100% input is continued for 1 hour. (Setting range: 20 to 9999999)

#### 2) English mode

Totalized value display by totalizer reference time, totalizer divisor, and totalizer multiplier Totalizer reference time Tb (ChG-14): Sets the reference time of input signals. Totalized value per reference time is displayed.

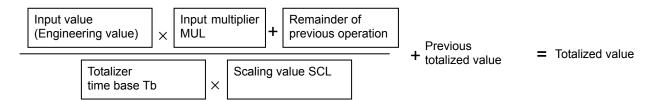
(Setting range: sec/min/hour/day)

Scaling value SCL (ChG-15): Divisor for totalized value scale conversion. The value divided by the divisor is used as totalized value.

(Setting range: 0 to  $\pm 1000000$ )

Input multiplier MUL (ChG-16): Multiplier for totalized value scale conversion. The value multiplied by the multiplier is used as totalized value.

(Setting range: 0 to  $\pm 1000000$ ))



### TMod(ChG-12)

Setting	Setting contents
JPn	Japanese mode
EnG	English mode

## [run

### Totalizer RUN/HOLD and LATCH (Setting range: HoLd/rUn/LATcH)

### [Description]

### 1) TrUn (ChG-1)

Totalizer is started/stopped and latched as follows.

- · When power is turned on: Selection can be made from RUN and HOLD.
- · During standby: Totalizer is not performed during standby. RESET operation is allowed. Since totalizer alarm is set to OFF during standby, alarm judgment is not made.
- · Totalizer operation is continued in other modes.

Parameter	Operation
RUN	Starts totalizer, makes totalizer alarm judgment.
HOLD	Stops totalizer, continues instantaneous value display, holds totalizer alarm output.
LATCH	Stops totalizer display, continues totalizer, stops instantaneous value display, continues totalizer alarm operation.

### 2) Allocation to Di function

- · Operation can be allocated to Di.
- The following totalizer operations can be allocated to parameters Di01 (Ch9-39) to Di04 (Ch9-42) and Di11 (Ch9-43) to Di15 (Ch9-47).

Di setting	Di input	
Di1 to Di15	OFF	ON
160	RUN	HOLD
161	RUN	LATCH

#### [Note]

- · If RUN/HOLD and RUN/LATCH functions are allocated to Di at the same time, the one with larger Di number takes precedence in operation over the other.
- · If RUN/HOLD and RUN/LATCH functions are allocated to Di, parameter setting or allocation to function keys cannot be performed.

#### 3) Allocation to function keys

- · Totalizer operation can be allocated to function keys.
- The following totalizer operations can be allocated to parameters F1 (Ch9-32) to F3 (Ch9-34).]

Function key code, F1 to F3	Function
30	RUN / HOLD
31	RUN / LATCH

# 「「F5 Totalizer reset (Setting range: ON, OFF)

### [Description]

4) TrES (ChG-2)

Totalizer can be reset.

ON: Clears totalized value, totalizer alarm OFF

Automatically returns to OFF state after the reset.

- 5) Allocation to Di function
  - · Reset function can be allocated to Di.
  - The following Di settings can be allocated to parameters Di01 (Ch9-39) to Di04 (Ch9-42) and Di11 (Ch9-43) to Di15 (Ch9-47).

Di setting	Di input	
Di1 to Di15	OFF	ON
162	_	Reset

- 6) Allocation to function keys
  - · Totalizer operation reset function can be allocated to function keys.
  - · Totalizer reset function can be allocated to parameters F1 (Ch9-32) to F3 (Ch9-34).

Function key code, F1 to F3	Function
32	Totalizer reset

# Totalizer input source setting (Setting range: PV1, PV2, Ai1, AiM)

### [Description]

### Toin (ChG-3)

- · Input source used for totalizer can be selected.
- · Select one from PV1, PV2, Ai1, and AiM as totalizer input.

Parameter	Input source
PV1	Measurement input 1
PV2	Measurement input 2
Ai1	Auxiliary analog input
AiM	Result of Math operation

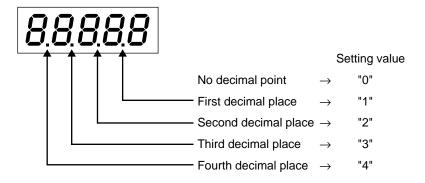
*[ 46 ]* 

Totalizer decimal point position setting (Setting range: 0 to 4)

### [Description]

#### TdP (ChG-4)

Decimal point position in totalized value display can be set.



### [Note]

- · Once the decimal point position is changed, the decimal point position of totalizer conversion factor (TCF (ChG-17)), totalizer initial value (TihT (ChG-18)), totalizer alarm 1 setting (A1SP (ChG-19)), totalizer alarm 2 setting (A2SP (ChG-20)), and re-transmission output source scale (rTSc (ChG-21)) is also changed. Check the decimal point position of each parameter.
- · In the case of English operation mode, once the decimal point position is changed during totalize operation, the digit of totalizer is changed. Be sure to reset the totalized value before changing the decimal point position.

*「[U[*] T

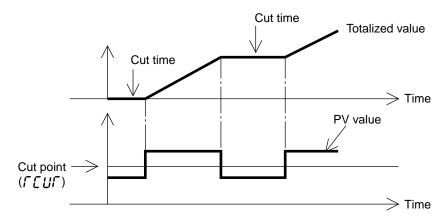
Totalizer cut point setting (Setting range: 0 to 100%FS)

### [Description]

#### TCUT (ChG-5)

Totalizer cut point for totalizer input can be set.

Input lower than the totalizer cut point is not added to totalized value.



#### [Note]

- In the case of English operation mode, if minus value is selected, the totalizer cut point becomes 0.
- The decimal point appears according to the decimal point position setting of measurement input.

8 15 8

Totalizer alarm 1 alarm type setting (Setting range: 0 to 3)

R2FP

Totalizer alarm 2 alarm type setting (Setting range: 0 to 3)

## [Description]

## A1TP (ChG-6), A2TP (ChG-9)

· Alarm type of totalizer alarms 1 and 2 can be set.

The alarm type can be selected from the three types listed in the following table.

A1TP A2TP	Alarm type
0	No alarm
1	Totalized value alarm
2	Batch control output
3	Batch control output (with auto reset)

#### 1) Totalized value alarm output

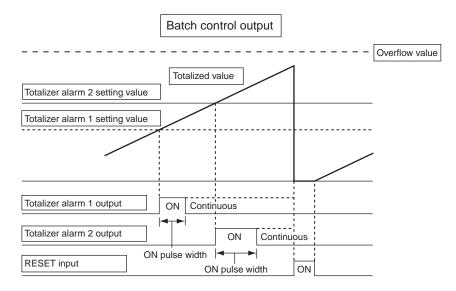
- · Plus alarm setting: Alarm comes ON when totalized value > alarm setting.
- · Minus alarm setting: Alarm comes ON when totalized value < alarm setting. Totalized alarm is set to OFF by reset input TrES (ChG-2).

Or, it is also set to OFF by auto reset, display overflow reset, or setting the totalizer initial value at which alarm comes OFF.

### 2) Batch control output

- · Plus alarm setting: Alarm comes ON when totalized value > alarm setting.
- · Minus alarm setting: Alarm comes ON when totalized value < alarm setting. Select pulse width from parameters A1on (ChG-7) and A2on (ChG-10). (100ms/200ms/500ms/1s/Continuous)

If continuous output is set to pulse width, alarm output is set to OFF by performing totalizer reset TrES (ChG-2).



Note: The pulse width error falls within 0 to 50msec.

- 3) Batch control output (with auto reset)
  - · Plus alarm setting: Alarm is set to ON when totalized value > alarm setting.
  - · Minus alarm setting: Alarm is set to ON when totalized value < alarm setting.

Select pulse width from parameters A1on (ChG-7) and A2on (ChG-10).

(100ms/200ms/500ms/continuous)

If the pulse width is set to continuous, alarm output is set to OFF by performing totalizer reset TrES (ChG-2).

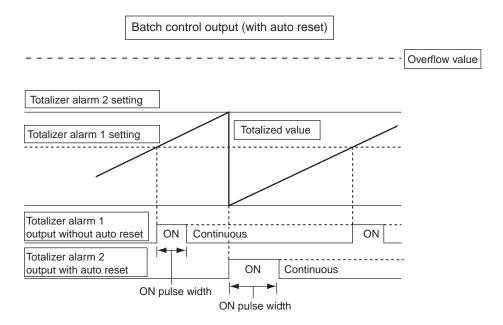
Auto reset function: Resets the totalizer when the alarm output comes ON.

If the pulse width is set to continuous, totalizer alarm is not set to OFF at the time of auto reset.

OFF action of the batch control output

Alarm ON pulse width	by Auto reset	by Reset input
Continuous output	Not set to OFF.	OFF
Others	Set to OFF after the output of O input.	N pulse width irrespective of reset

When the totalizer initial value is the same or larger than the alarm setting, resetting is made immediately and the totalizer starts is started from 0.



Note: The error of pulse width falls within 0 to 50msec.

8 lon

Totalizer alarm 1 ON pulse width setting (Setting range: 0 to 4)

8200

Totalizer alarm 2 ON pulse width setting (Setting range: 0 to 4)

## [Description]

### A1on (ChG-7), A2on (ChG-10)

• The ON pulse width can be set for batch control output of totalizer alarms 1 and 2. The pulse width can be selected from the 5 types listed in the following table.

A1on A2on	ON pulse width
0	Continuous
1	100ms
2	200ms
3	500ms
4	1sec

A lop

Totalizer alarm 1 excitation, non-excitation setting (Setting range: 0, 1)

8208

Totalizer alarm 2 excitation, non-excitation setting (Setting range: 0, 1)

### [Description]

### A1oP (ChG-8), A2oP (ChG-11)

· Excitation or non-excitation output for totalizer alarms 1 and 2 can be set.

Setting	Setting contents
0	Excitation
1	Non-excitation

When excitation is selected for totalizer alarm

When non-excitation is selected for totalizer alarm



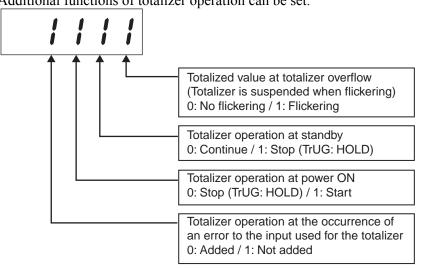
## ropr

Totalizer option setting (Setting range: 0000 to 1111)

## [Description]

### ToPT (ChG-13)

Additional functions of totalizer operation can be set.



\* If "No flickering" is selected, totalizer is reset and restarted beginning from 0. If "Flickering" is selected, the display starts flickering after the reset.

Totalizer time base setting (Setting range: SEC, Min, hour, dAY) (only for English mode)

### [Description]

### Tb (ChG-14)

The unit of totalizer reference time can be set.

Time base	
SEC	
Min	
hour	
dAy	

SEL

Totalizer scaling value setting (Setting range: 0 to ±1000000) (only for English mode)

## [Description]

### **SCL (ChG-15)**

• The unit of totalized value can be transformed from the unit of input value.. Example:

Unit of totalizer input	Unit of totalized value	SCL
cm <sup>3</sup>	$m^3$	1000000
g	kg	1000

Note: Do not select 0. If 0 is selected, the value is not added to totalized value.

NUL

Input multiplier setting (Setting range: 0 to ±1000000) (only for English mode)

### [Description]

### MUL (ChG-16)

· The unit of totalized value can be transformed from the unit of input value.

r [ F

Totalizer conversion factor setting (Setting range: 20 to 9999999) (only for Japanese

mode)

## [Description]

### **TCF (ChG-17)**

Totalized value display, when 100% input is continued for 1 hour.

Note: The decimal point position is determined according to the totalizer decimal point position setting TdP (ChG-4).

Totalizer initial value setting (Setting range: -1999999 to 9999999)

### [Description]

### TinT (ChG-18)

When totalizer initial value is changed, the current totalized value is changed to changed value.

Note: The decimal point position is determined according to the totalizer decimal point position setting TdP (ChG-4).

A 15P

Totalizer alarm 1 set value setting (Setting range: -1999999 to 9999999)

8258

Totalizer alarm 2 set value setting (Setting range: -1999999 to 9999999)

## [Description]

4) A1SP (ChG-19), A2SP (ChG-20)

The operation value for totalizer alarms 1 and 2 can be set.

Note: The decimal point position is determined according to the totalizer decimal point position setting TdP (ChG-4).

# -155

Re-transmission output scale setting (Setting range: -1999999 to 9999999)

## [Description]

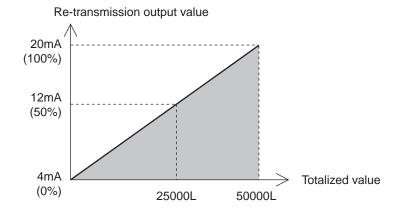
## rTSC (ChG-21)

The totalized value can be set so that re-transmission output becomes 100%.

Note: This setting is enabled only when "TV" is selected for re-transmission output type.

Example: When rTSC = 50000L

Output becomes 50% (12mA) when totalized value is 25000L.



# 5-27 Recipe function

## Description of the recipe function

The recipe function is used to switch the values of the parameters registered as recipe parameters, synchronized with the switching of control palettes.

Select the setting for each control palette for parameters d00 to d79. (Refer to the description on the next page for details.)

## [Description]

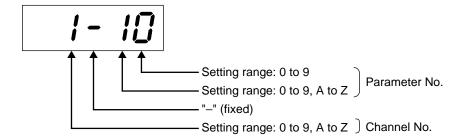
1) rCP0 to rCP9 (ChX-1 to 10)

Parameters to be allocated to recipe parameters can be set.

Symbol	Name	Description
rCP0	Recipe allocation 1	Select parameter to be allocated as recipe 1
rCP1	Recipe allocation 2	Select parameter to be allocated as recipe 2
rCP2	Recipe allocation 3	Select parameter to be allocated as recipe 3
rCP3	Recipe allocation 4	Select parameter to be allocated as recipe 4
rCP4	Recipe allocation 5	Select parameter to be allocated as recipe 5
rCP5	Recipe allocation 6	Select parameter to be allocated as recipe 6
rCP6	Recipe allocation 7	Select parameter to be allocated as recipe 7
rCP7	Recipe allocation 8	Select parameter to be allocated as recipe 8
rCP8	Recipe allocation 9	Select parameter to be allocated as recipe 9
rCP9	Recipe allocation 10	Select parameter to be allocated as recipe 10

Make parameter setting using channel parameter numbers.

[Example] When setting the alarm setting 1 AL1 (Ch1-10) for recipe allocation 1 rCP0



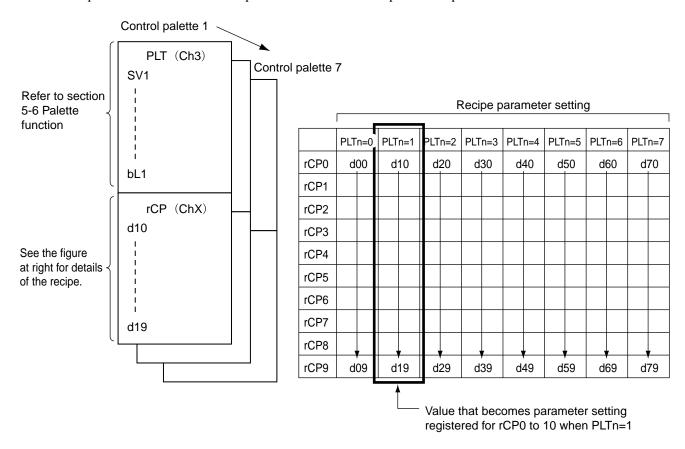
dana to dana Recipe set value setting (Setting range: Depends on the setting range

of parameter set in recipe allocation.)

### [Description]

Set the value that corresponds to each control palette of parameters allocated to recipe allocation 1 to 10. (The setting range is the same as that of parameters to which recipes are allocated.)

The correspondence between control palette numbers and recipe-related parameters is shown below.



d00 to d79 (ChX-11 to 90)

- 1) d00 to d09 (ChX-11 to 20): Setting that corresponds to the situation where none of control palettes for recipe allocation 1 to 10 are selected
  - d10 to d19 (ChX-21 to 30): Setting that corresponds to control palette 1 of recipe allocation 1 to 10
  - d20 to d29 (ChX-31 to 40): Setting that corresponds to control palette 2 of recipe allocation 1 to 10
  - d30 to d39 (ChX-41 to 50): Setting that corresponds to control palette 3 of recipe allocation 1 to 10
  - d40 to d49 (ChX-51 to 60): Setting that corresponds to control palette 4 of recipe allocation 1 to 10
  - d50 to d59 (ChX-61 to 70): Setting that corresponds to control palette 5 of recipe allocation 1 to 10
  - d60 to d69 (ChX-71 to 80): Setting that corresponds to control palette 6 of recipe allocation 1 to 10
  - d70 to d79 (ChX-81 to 90): Setting that corresponds to control palette 7 of recipe allocation 1 to 10

### [Note]

- · Masked parameters cannot be registered as recipes.
- · Recipe allocation setting is enabled after the main unit is reset or power ON again.
- The following parameters cannot be used as recipe parameters. Do not select them for recipe allocation (rCP0 to 9).

### [Parameters that cannot be registered]

Ch3 (PLT channel)	Ch7 (MON channel)	Ch8 (SET channel)
Ch9 (SYS channel)	ChA (ALM channel)	ChB (Com channel)
ChT (TLK channel)	ChX (RCP channel)	

ChT (TLK channel)

STBY (Ch1-5) AT (Ch1-7) PLTN (Ch1-9) LACH (ch1-8) RES (Ch9-E3) TrUn (ChG-1) TrES (ChG-2) TinT (ChG-18) CALB (ChF-8)

### [Example]

To change the alarm setting (AL1) to 100.0°C when control palette is not used (PLTn=0), the alarm setting (AL1) to 200.0°C when control palette 1 is selected (PLTn=1), and the alarm setting (AL1) to 300.0°C when control palettes 2 to 7 are selected (PLTn=2 to 7), select recipe-related parameters as follows.

Parameter	Setting
rCP0 (Recipe allocation 1)	1-10
d00 (Value when PLTn=0 holds)	100.0
d10 (Value when PLTn=1 holds)	200.0
d20 (Value when PLTn=2 holds)	
	300.0
d70 (Value when PLTn=7 holds)	

## 5-28 Linearize function

PILn PV1 input linearize setting

P2Ln PV2 input linearize setting (Setting range: OFF, nrML, hi-C, Lo-C)

RILn Ai1 input linearize setting

## [Description]

- · Linear conversion is performed by 16 straight-line table specific to each input (PV1, PV2, Ai1).
- · Select linearize output from the following 3 types.

P1Ln (Ch8-13, P2Ln (Ch8-26), A1Ln (Ch8-51)

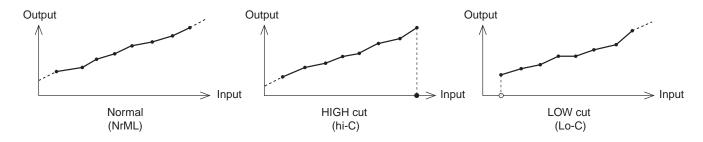
Select enable/disable of linearize function of each input.

OFF: Linearize disabled

NrML: Values outside the table range is output without making conversions.

hi-C: Values higher outside the table is limited.

Lo-C: Values lower outsides the table is limited.



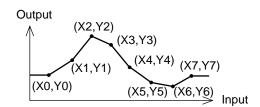
P IHD to R ISF Linearizer table setting (Setting range: –25 to 125%FS)

## [Description]

### P1X0 to A1YF (ChC-1 to 128)

- 1) The settings of the X-axis and the Y-axis of the linearize table for PV1 input (P1X0 to P1YF), for PV2 input (P2X0 to P2YF), and for Ai1 input (A1X0 to A1YF) are set as follows.
- 2) Sixteen straight-line setting can be made for each table.
- 3) The following table shows the broken-line table.

Input	Output
X0	Y0
X1	Y1
X2	Y2
X3	Y3
X4	Y4
X5	Y5
X6	Y6
X7	Y7
X8	Y8
X9	Y9
XA	YA
XB	YB
XC	YC
XD	YD
XE	YE
XF	YF



# 5-29 Data change through communications

## (1) MV value setting in manual mode (Setting range: -250 to 1250)

### [Description]

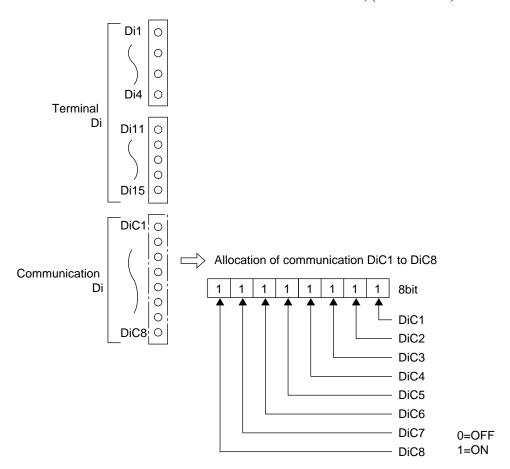
If data is written into the manual MV exclusive for communications, the MV value can be changed in manual mode.

- \* The data is tracked to calculated value MV in modes other than manual mode.
- \* The data is limited within the range from -25% to 125% if values that do not fall within that range are specified.

## (2) Di function through communications

### [Description]

In addition to terminals 1 to 4 and Di11 to 15, communication-Di can be used. Communication-Di functions can be allocated to Ci01 to Ci08, (chb-51 to 58).



\* See the communication manual for MODBUS communication address of communication Di.

[[] to [[] Communication Di function setting (Setting range: 0 to 255)

## [Description]

1) Ci01 to Ci08 (Chb-51 to 58)

Function setting is the same as Di function setting. (See 5-10 "Digital input (Di) function".)

## (3) RSV change through communications (for Template 16)

### [Description]

Change of RSV setting is allowed through communication.

· Select communication RSV using the RSV signal selector switch.

<Setting method>

Set CN02 (ch8-99) = 5.

This allows values to be set through communications.

See the communication manual for the MODBUS communication address of communication RSV.

# 5-30 Ramp/Soak

**P-** Ramp/Soak activation Command (Setting range: oFF, rUn, hLd)

Pro Ramp/Soak activation Pattern (Setting range: 0 to 30,di)

ิ Ramp/soak time units (Setting range: hh.MM.MM.SS)

ร\_- เ to ร\_รู Y setting value (setting range: 0 to 100%FS)

 Image: 1.0 | Imag

Ramp/soak mode (setting range: 0 to 15)

Guaranty soak ON/OFF (setting range: oFF, on)

**□ □ □ □** Guaranty soak band (upper) (setting range: 0 to 50%FS)

**□5-** Guaranty soak band (lower) (setting range: 0 to 50%FS)

Pustart (setting range: oFF, on)

Continue mode (setting range: rES, Con, ini)

**PF \_\_\_\_\_\_** Sets the max pattern (setting range: 0 to 30, di)

Pnin | Sets the min pattern (setting range: 0 to 30, di)

#### [Explanation]

What is Ramp/Soak?

This function automatically runs after setting SV and the times for the SV changes.

SV setting can be set to maximum 64 steps and Ramp/soak activation pattern can be selected from 31 patterns or by specified Di.

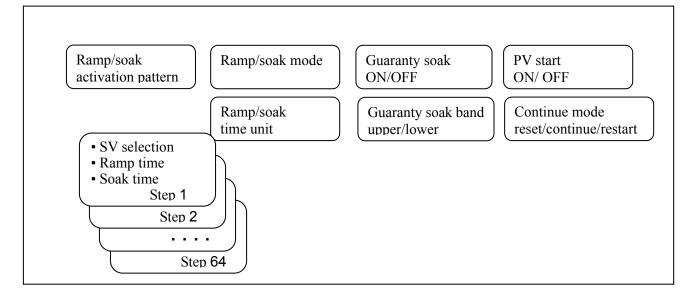
(Please refer to "5-10 Digital input (Di) function" regarding Di function)

Additionally, Ramp/soak status can be output from Do.

(Please refer to "5-11 Digital output (Do) function" regarding Do function)

- Ramp: Changing SV tends to reach a target SV
- Soak: Maintains a set SV

The ramp/soak menu (ch8) consists of the following function blocks.



#### Note

- · Even if operation is switched to remote SV operation or manual MV operation during Ramp/soak, Ramp/soak operation will not be stopped.
  - Even Ramp/soak operation is continued and SV is kept changing, remote SV operation or manual MV operation is given first priority to.
- · When operation is switched to remote SV operation during Ramp/soak and then switched to local SV operation again, SV value will be switched to Ramp/soak SV value even though SV tracking function is set to ON.

#### 1) PrG (Ch1-6)

Switch between Ramp/soak states.

Ramp/soak can switch the following three conditions.

PrG	Operation status	
oFF	Stop: Ramp/soak is stopped.	
rUn	Run: Ramp/soak starts.	
hLd	Hold: Ramp/soak hold. To release the hold, select "rUn" again.	

- Parameter will be switched automatically based on Ramp/soak status.

PrG	Status
GS	Guaranty soak ON: Guaranty soak is activated and PV is out of guaranty soak setting range.
End	End: Ramp/soak ends

- "RS" ramp lights up as following during Ramp/soak

Ramp/soak status	Operation screen	others
oFF (Stop)	OFF	
r Un (Run)	blinking	
hLd (Hold)	blinking	OFF
GS (out of GS range)	blinking	
End (End)	ON	



#### Note

Local SV value can not be changed during Ramp/soak operation.

When you change the local SV to given value, make sure to set PrG to "oFF" before change.

#### 2) PTn (Ch8-1)

- Selects the Ramp/soak activation pattern.

Ramp/soak of following steps will be carried out based on Ramp/soak activation pattern setting.

PTn	Activation step
0	1 ~ 4
1	5 ~ 8
2	9 ~ 12
3	13 ~ 16
4	$17 \sim 20$
5	21 ~ 24
6	25 ~ 28
7	29 ~ 32
8	33 ~ 36
9	$37 \sim 40$
10	41 ~ 44
11	45 ~ 48
12	49 ~ 52
13	53 ~ 56
14	57 ~ 60
15	61 ~ 64

PTn	Activation step
16	1 ~ 8
17	9 ~ 16
18	17 ~ 24
19	25 ~ 32
20	$33 \sim 40$
21	41 ~ 48
22	49 ~ 56
23	57 ~ 64
24	1 ~ 16
25	17 ~ 32
26	33 ~ 48
27	49 ~ 64
28	1 ~ 32
29	33 ~ 64
30	1 ~ 64
di	specified by Di

#### Note

- When Di is selected, make sure to set to "pattern №+1 to 16" by " 5-10 digital input (Di) function" and specify the activation pattern by Di
  - Additionally, during Ramp/soak operation do not change the Di input status which specify Rmp/soak activation pattern.
- · Do not change the PTn setting during Ramp/soak operation. When you change the setting, make sure to set the PrG to "oFF".

#### 3) TiMU (Ch8-2 to 2)

- Sets the time units when Ramp/soak is activated.

Max. settable time of Ramp/soak is as follows related to setting value.

TiMU	Time unit	Max. settable time
hh.MM	hour: min	99hours 59minutes
MM.SS	min: sec	99minutes 59seconds

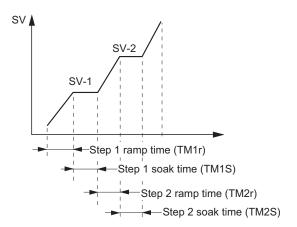
#### Note

· Time units can not be set separately for each step. All steps use the same unit of time.

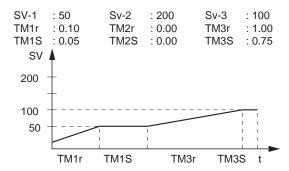
- 4) Sv-1 to Sv64 TM1r to T64r TM1S to T64S (Ch8-3 toJ4)
- Sets the target value (SV value), ramp time and soak time.
   Target value (SV value), Ramp time and soak time can be set up to 64 steps.

Ramp time is a changing time of SV to reach target SV. Soak time is a duration time to maintain the setting SV.

Parameter	Setting value
Sv-1 to Sv64	"SV lower limit (S v L) to SV upper limit (S v h)"
TM1r to T64r	"00:00-99:59 (hour:min/min: sec)"
TM1S to T64S	"00:00-99:59 (hour:min/min: sec)"

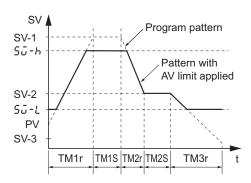


– Both ramp time (TM1r to T64r) and soak time (TM1S∼T64S) skip segment 00:00 and proceed the next step.



#### [Note]

- The SV limit function (SV-h, SV-L) is still on while ramp/soak is running.
The set value (SV-n) does not change, but the value is limited during ramp/soak. For that reason, the value may not change at the set times for the following patterns."



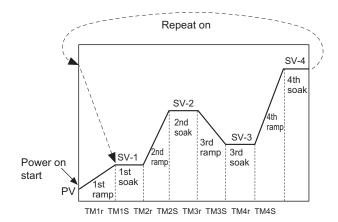
#### 5) Mod (Ch8-J5)

– Sets the method of ramp/soak operation.

Function	Description
Power-on start	Starts ramp/soak from the current PV value when the main unit is turned on.
END time output	Maintains the same state as at the end of ramp/soak when ramp/soak is
_	complete. (It is invalid when repeat operation is activated)
oFF time output	Switches to the OFF state when ramp/soak is complete.
Repeat operation	Repeats ramp/soak from step 1 when the last step finishes.

There are 16 types of operation modes according to the combination of function as shown blow.

MOD	Power On Start	Engine Output	OFF Output	Repeat Behavior
0	none	Maintain control	Maintain control	none
1	none	Maintain control	Maintain control	on
2	none	Maintain control	Standby Mode	none
3	none	Maintain control	Standby Mode	on
4	none	Standby Mode	Maintain control	none
5	none	Standby Mode	Maintain control	on
6	none	Standby Mode	Standby Mode	none
7	none	Standby Mode	Standby Mode	on
8	on	Maintain control	Maintain control	none
9	on	Maintain control	Maintain control	on
10	on	Maintain control	Standby Mode	none
11	on	Maintain control	Standby Mode	on
12	on	Standby Mode	Maintain control	none
13	on	Standby Mode	Maintain control	on
14	on	Standby Mode	Standby Mode	none
15	on	Standby Mode	Standby Mode	on



#### 6) Gsok (Ch8-J6) GS-h (Ch8-J7) GS-L (Ch8-J8)

- Sets the Guaranty soak ON/OFF.

Guaranty soak is the function to guarantee soak time.

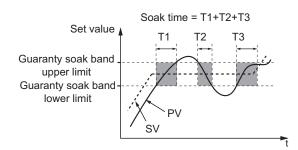
Soak time is counted down only when PV is in the proper temperature range of SV setting.

In the diagram below, the total of the shaded regions are counted as soak time.

When this total is equal to the specified soak time, the cycle proceeds to the next step.

Gsok	Function
oFF	Disable guaranty soak.
on	Enable guaranty soak.

Parameter	Setting range
GS-h	0 to 50%FS
GS-L	0 to 50%FS



#### Note

- · In guaranty soak, soak time is counted using by SV and PV value where are set at Sv-1 to S v 64.
- · For this reason, when you set SV value lower than setting value of Sv-1to Sv64 with SV limit function, please note that soak time may not be counted.

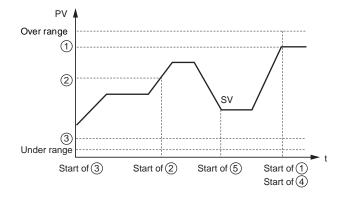
#### 7) PvST (Ch8-J9)

- When the ramp soak starts (RUN), this function searches the first point where the measurement value (PV) and the program pattern match, and starts operation at that point.

PvST	Function
oFF	Disables PV start function
on	Enables PV start function

Difference of starting position according to PV value

- 1) When PV is matching SV setting value in the program, it will start from Soak period of matching SV.
- 2) When PV is in a range of the SV setting value of the Ramp period, the Ramp is started on the way in the Ramp period.
- 3) When PV does not match SV in the program within the PV input range (PV is lower than SV), Ramp is started from PV value towarding to the first target SV.
- 4) When the PV value does not match SV in the program within the PV input range (PV is higher than SV) or PV is an over range, it is started from the Soak period of program SV setting value MAX value.
- 5) When the PV value is under range, it is started from the Soak period of program SV setting value MIN value.



Note

· When ConT(Ch8-K0) is set to "Con", PV start is disabled.

#### 8) ConT (Ch8-KO)

When the power turns off during operation due to power outage or other reasons, continue mode can specify the ramp soak operation when the power turns on.
 Restore the status up to 5 minutes before.

Setting value	Operation of continue mode
rES	Ramp/Soak is not be operated.
Con	Continues the operation from the status of the time which power is turned off
ini	Starts the Ramp/Soak from the first step again.

#### Note

- · Do not change the "ConT "during Ramp/soak operation. Make sure to change while "PrG" is set to "oFF".
- When "ConT" setting is set to "Con", PV start is disabled.
- · "ConT" is set to "Con"and when outage occur, restore the status up to 5 minutes before where outage occurred.
- · When "ConT" is set to "Con", do not set the Ramp/Soak command (Ch1-6) to "hoLd"frequently more than 10times/per hour.

#### 9) PTnM (Ch8-K1) Pmin (Ch8-K2)

- Sets the max./min. pattern to proceed the Ramp/soak activation pattern with function keys.

Parameter	Setting range
PTnM	0 to 30,di
PMin	0 to 30,di

When you change this setting, make sure to set that "PTnM" (Max.value) is more than "PMin" (Min.value).

Please refer to the "5-13 Function key" regarding user key setting.

#### Note

· When "di" is selected by PTnM and PMin, Ramp/soak activation pattern specified by Di will be conducted after Ramp/soak activation pattern "30". Tus, when Ramp/soak activation pattern is not specified by Di, do not set the setting value to "di".

# 6TROUBLESHOOTING

Symptom	Possible cause	Remedy	See (page)
Reading appears     as UUUU or     LLLL.	(1) Input signal of the sensor and settings of parameter PV1T, PV2T, or AI1T do not coincide.	Make the setting of PV1T, PV2T, and AI1T again.	27
	(2) Polarity of input signal is reversed.	Check the polarity and connect properly.	157
	(3) Short circuit occurred to the input of B or R thermocouple (PV1T, PV2T = 4, 5).	Set parameters PV1T and PV2T to 3, and check that temperature around normal temperature is displayed. (The error of B and R thermocouples is extremely large near normal temperature. It is not a failure.)	27
	(4) Input signal of the sensor and the type do not match.	Ask your distributor for modification, or replace it with a proper type unit.	_
	(5) Input connection is loose.	Fasten securely.	_
	(6) The sensor is broken or short-circuited.	Replace the sensor, or remove the short-circuited part.	157
	(7) A device connected to the sensor or the input of the main unit is defective.	Replace the sensor or input devices.	_
	(8) Parameter PV1B, PV2B, AI1B or UCB1 is set to the value larger than PV1F, PV2F, AI1F, or UCF1 respectively.	Make the setting again to assure PV1B <pv1f, <ai1f,="" <pv2f,="" ai1b="" and="" pv2b="" td="" ucb1<ucf1.<=""><td>27</td></pv1f,>	27
	(9) Measurement value is too large or too small.	Extend the setting value for parameters PV1B, PV2B, AI1B, UCB1, PV1F, PV2F, AI1F, and UCF1.	27
2. Fractional portion of the reading is not displayed.	Parameter, PV1d, PV2D, AI1D, or UCD1 is set to 0.	Set them in the range from 1 to 3.	27
3. SV and set value of some of the parameters change spontaneously.	Parameter PV1b, PV1F, or Pv1d has been changed (when TPTL=33, 34). Parameter UCB1, UCF1, or UCD1 has been changed (when TPLT=30, 31).	Make the setting of all the parameters again.	158 to 169
4. ON/OFF control (2-position control) cannot be started.	Parameter P1 is not set to 0.0.	Set P1 to 0.0.	91
5. ON/OFF control does not function.	(1) Setting of parameter hS1 is not correct.	Adjust the setting of hS1 according to the control target.	92
6. Control does not function	(1) Setting of parameter P1, i1, or d1 is not correct.	Do auto tuning.	52
properly.	(2) Output limit is posed.	Make the setting of parameters MVh1 and MVL1 to the value appropriate for the process.	89
7. Reaction is slow. (Measurement value changes very slowly.)	Input filter is too large.	Decrease the setting of parameter P1TF. When PV2 or AI1 is used, decrease the setting of P2TF or A1TF.	87

Symptom	Possible cause	Remedy	See (page)
8. Reading does not change	(1) Input is short-circuited.	Remove the short-circuited part.	_
although output is turned ON/OFF.	(2) Connection with operation terminal is off.	Connect properly.	157
	(3) Power for the operation terminal is OFF.	Set the power to ON.	_
	(4) Output signal and input signal of the operation unit do not coincide.	Provide a thermoregulator appropriate for the operation terminal, or provide operation terminal appropriate for the signals from the thermoregulator.	_
9. Key operation cannot be performed. Parameter value cannot be changed.	Parameter LOC is set to 1, 2, 4, or 5.	Set LOC to 0 or 3. (If LOC is set to 3, setting cannot be made by communication.)	95
10. SV cannot be	(1) Parameter LOC is set to 1 or 4.	Set LOC to 0, 2, 3, or 5.	95
changed.	(2) Setting of values outside the measurement range (parameters Sh1 to SL1) was attempted.	Extend the range of Sh1 and SL1. (Do not extend the range exceeding the values listed in input range table.)	51
11. Parameter to be checked or changed does not appear.	Setting has been made to skip the parameters in question with parameters ds00 to ds43.	Change the setting of the parameter in question in ds00 to ds43.	120
12. Auto tuning cannot be done properly.	(3) After auto tuning was started, input was set to UUUU.	Expand the range of parameters PV1d, PV1F, and PV1B when TPLT =33, 34, and expand the range of parameters UCD1, UCF1, and UCB1 when TPLT = 30, 31 and then do auto tuning again.	27
	(4) After auto tuning was done, SV was changed.	Restore the SV value to be controlled and then do auto tuning again.	52
	(5) Peripheral devices or connections with those devices are faulty.	Make connections with peripheral devices properly.	_
	(6) Forward/reverse operation of thermoregulator and the system of control target do not coincide.	Set parameter rEV1 properly.	48
	(7) Control target runs out of time in a very slow process (about 17 hours or longer).	Do tuning manually. (Set P1 to 0, and perform ON/OFF control.)	91
13. Overshoot is too large in auto	_	(1) Do auto tuning at ATP1 = LPV (low PV type AT).	52
tuning.	_	(2) Do tuning manually.	_
14. Decimal point cannot be changed.	TPLT has been set to 30, 31.	Set TPLT to 33 or 34, or change the decimal point of UCd1.	21 or 27
15. MVRB value is UUUU or LLLL.	(1) Valve control type is under PFB control, and valve opening degree feedback input is open or short-circuited.	Check the valve opening degree feedback input line.	120
	(2) Valve is not correctly positioned.	Perform the valve adjustment automatically or manually.	37

#### **Error indications**

This Controller has a display function to notify when the equipment is not functioning properly. When a problem occurs, remove the cause immediately.

Once the cause has been removed, turn the power OFF then ON again.

Display	Cause	Control output
טטטט	<ol> <li>Thermocouple sensor wire broken</li> <li>RTD wiring broken</li> <li>PV value above upper limit +5%FS or more</li> <li>RCJ sensor not attached (thermocouple input)</li> </ol>	OPEN, and CLOSE are output in terms of the value of brd1 (ch9-35).
LLL	<ul> <li>(1) Short circuit of resistance bulb sensor (between A and B)</li> <li>(2) When PV value without fractional portion is under –19999.</li> <li>Note) In case of the resistance bulb, LLLL is not displayed even if under –150°C.</li> </ul>	Control continues.  Note) Control continues until below  -5%FS.  Burnout occurs at below -5%FS.
PV not displaying	Standby mode STBO (Ch9-30)=1(PV display set to off)	OPEN or CLOSE is output so that valve opening degree feedback (MVRB) or estimated valve position will be the setting value of PMv1 (ch2-22).
-19999 or 99999	Display limit is smaller than over range or under range value.	Control continues.  Note) Control continues until under  -5%FS or 105%FS.
Correct PV not displayed	The main unit was not reset or the power was not turned on after scale setting was changed.	

Valve opening degree feedback display (MVRB)	Cause	Control output (OPEN, CLOSE)
טטטט	<ul><li>(1) G line open-circuited</li><li>(2) T-G line short-circuited</li></ul>	Based on 105% assumed for MVRB.
LLLL	<ul><li>(1) Y line open-circuited</li><li>(2) T-Y line short-circuited</li><li>(3) T-Y-G line short-circuited</li></ul>	Based on –5% assumed for MVRB.

## 7 FREQUENTLY ASKED QUESTIONS

- Q1 Decimal point of the measurement value (PV) started flickering while parameter setting was being changed. What does the decimal point at the far right mean?
- A The decimal point at the far right is kept flickering while auto tuning is being performed. Set AT (Ch1-7) to OFF.
- Q2 How is temperature displayed?
- A The value rounded off from the lower place value is displayed.
- Q3 Can 105°C be expressed as 60°C?
- A It is possible by adjustment by the user. Display can be made in the range of  $\pm 50\%$  of the full scale range.
- Q4 What kind of cables should we use for RS485?
- A Use twisted pair cables with a shield. Recommended cable: KPEV-SB (By FURUKAWA)
- Q5 PV value has been stably displayed for about a week. Then it increased suddenly for 2 to 3 minutes, and returned back to the original value.
- A Effect of noise is considered. Replace the cable with the one provided with a shield.
- Q6 P is set to 0.0, but ON/OFF display does not appear.
- A There is no ON/OFF display. Either of the two output status of MV, 0% (OFF) or 100% (ON) is displayed.
- Q7 Key operation cannot be made.
- A The instrument is provided with key lock function, but if the display does not change even if the SEL key is pressed, key failure is considered. Check the type and ask the manufacturer for repair.
- Q8 Reading error of 7 to 8°C is observed.
- A The error can be adjusted by user adjustment.
- Q9 What does 50%FS (full scale) of user adjustment mean?
- A Setting can be made within the range of 50% of the measurement range. Up to 200°C can be set if the measurement range is 0 to 400°C.

### 8 SPECIFICATIONS

#### **General specifications**

#### **General specifications**

(1) Power supply voltage:

100V (-15%) to 240V (+10%) AC, 50/60 Hz

(2) Power consumption:

15 VA or less (100 V AC)

20 VA or less (220 V AC)

(3) Insulation resistance:

20 MΩ or more (500 V DC)

(4) Withstand voltage:

Power supply ↔ All terminals;

1500 V AC for 1 minute

Relay output ↔ All terminals;

1500 V AC for 1 minute

Others; 500 V AC for 1 minute

#### Input section

#### Measurement value input

(1) Number of inputs: 1 or 2 (Option)

(2) Input signal type:

Thermocouple: J, K, R, B, S, T, E, PR40/20, N, PL-II,

WRe5-26

Resistance bulb : Pt100Ω (3-wire)

Voltage: 0 to 10 mV DC, 0 to 50 mV DC,

1 to 5 V DC, 0 to 5 V DC, 0 to 10 V DC

Current: 4 to 20 mA DC, 0 to 20 mA DC

(3) Measurement range:

Refer to the measurement range table.

(4) Input indication accuracy (Ambient temperature: 23°C):

·Thermocouple:  $(\pm 0.1\%FS \pm 1 digit \pm 1^{\circ}C)$  or  $\pm 1.5^{\circ}C$ ,

whichever is larger

Thermocouple B: 0 to 400°C range;

±5%FS±1digit±1°C

Thermocouple R: 0 to 500°C range;

±1%FS ±1digit ±1°C

·Resistance bulb input: (±0.1%FS ±1digit) or ±0.25°C, whichever is larger

WillChevel is larger

· Voltage input, current input: ±0.1%FS±1digit

- (5) Input sampling cycle: 50 ms
- (6) Input impedance
  - Thermocouple, voltage input (mV): 1  $\mbox{M}\Omega$  or more
  - Voltage input (V): 1MΩ
  - Current input: 250Ω
- (7) Influence of source resistance / Permissible wiring resistance
  - $\cdot\,$  Thermocouple, voltage input (mV): 0.1%FS per 100 $\Omega$
  - · Voltage input (V): 0.1%FS per 500Ω
  - · Resistance bulb input:  $10\Omega$  or less (per cable)
- (8) Permissible input voltage
  - · Voltage (V) input: +35 V / −10 V DC
  - · Current input: ±25 mA DC
  - · Thermocouple/Resistance bulb/Voltage (mV) input:

±5 V DC

- (9) Noise reduction ratio
  - · Normal mode: 40 dB (50/60 Hz) or more
  - · Common mode: 120 dB (50/60 Hz) or more
- (10) Input value correction function (Input conditioner)
  - · User adjustment:

±50%FS both for zero point and span point

· Square-root extractor:

OFF or cut point from 0.0 to 125.0%

· Input filter: 0.0 to 900.0 sec for time constant.

### Auxiliary analog input (Option) <With PFB input/"D" at 5th digit of PILC>

- (1) Number of inputs: 1
- (2) Input signal

DC voltage: Valve opening degree feedback signal [Potentiometer]

- (3) Input accuracy: ±1.0%FS
- (4) Resistance range: 100  $\Omega$  to 10 k $\Omega$ , 3 wire system
- (5) Resolution: 0.1%FS

#### <Without PFB input/"S" at 5th digit of PILC>

- (1) Number of inputs: 1
- (2) Input signal
  - DC voltage: 1 to 5 V DC / 0 to 5 V DC / 0 to 10 V DC
- (3) Input accuracy: ±0.2%FS
- (4) Sampling cycle: 100 ms
- (5) Input impedance: 1 MΩ
- (6) Influence of source resistance: 0.2%FS per 500Ω
- (7) Permissible input voltage: +35 V / -10 V DC
- (8) Noise reduction ratio
  - · Normal mode: 40 dB (50/60 Hz)
  - · Common mode: 120 dB (50/60 Hz)
- (9) Input value correction function
  - · User adjustment:
  - ±50%FS both for zero point and span point
  - Square-root extractor:
  - OFF or cut point from 0.0 to 125.0%
  - · Input filter: 0.0 to 900.0 sec. for time constant.

#### Digital input (DI)

(1) Number of points: 9 points max

Standard with 4 points (Di1 to 4)

Extended with 5 points (9 points max. totally)

- (2) Specifications: Contact or transistor input
- (3) Contact capacity:

12 V DC, Approx. 2 mA (per point)

- (4) Detection pulse width: 200 ms or more
- (5) Function: Control mode changeover, EX-MV selection, SV

changeover, Control run/standby, Auto-tuning start, Built-in timer start,

Alarm latch cancel.

#### Math function

(1) Kind of formula:

Select by the parameter setting.

(flow compensation, Average, Hi/Lo selector, input selector)

(2) Operation parameter:

Analog input (PV1, PV2, Ai1),

Constant (K01 - K16)

(3) Data type: Engineering unit (with floating point)

#### **Output section**

#### **Control output**

- (1) Number of points: 2 (OPEN, CLOSE)
- (2) Type: Motor-operated valve control pulse output.

Contact structure : 1a (SPST) contact ×2

[with interlock circuit]

Contact capacity : 220 V AC/30 V DC, 1 A (Resistive load) 220 V AC/30 V DC, 0.3 A (Inductive load)

Contact durability: 100,000 operations min. (Rated load)

#### Digital output

(1) Number of points:

Basic: 2 (Do3, 4)

Expansion: Maximum 7 (9 points in total at max.) 1 point (Do4) is used for control output

(2) Specifications:

·Contact structure:

SPST contact (except for Do4)

SPDT contact (Do4)

·Contact capacity:

220 V AC / 30 V DC, 1A (Resistive load)

·Life: 100,000 operations (rated load)

(3) Function: Alarm output, timer output, control output (Do4)

(4) Limitation: Up to four Do's in case of 2 measurement inputs

#### Analog re-transmission output

(1) Number of points: 2 at max.

(2) Type: Current output (4 to 20 mA DC)

Accuracy: ±0.2%FS Linearity: ±0.2%FS

Load resistance:  $600\Omega$  or less

(3) Output contents: PV, SV, MV, DV, AiM, MVRB

#### Transmitter power supply output

(1) Number of points: 1 at max.

(2) Rating:

24 V DC (17 to 30 V DC), Maximum current; 23 mA (with short circuit protection)

#### Alarm function

#### Number of alarm points

8 points for setting

#### Type of alarm

- PV value (upper/lower limit, absolute/deviation, band), PV variation ratio, SV upper/lower limit, main unit error <Optional operation>
  - · Hold (standby) function
  - · Alarm latching
  - · Excitation/non-excitation
  - · Operation delay: 0 to 9999 sec, 0 to 9999 min

#### Alarm output

Allocated to DO1 to DO4 and DO11 to DO15 (Allocation change available.)

#### Communication function

#### PC Loader interface

- (1) Number of points: 1
- (2) Physical specifications: EIA RS232C
- (3) Protocol: Modbus-RTU
- (4) Communication method:

3-wire, half-duplex, bit serial asynchro-nous communication

(5) Data type, Data length:

8 bits, Parity; Odd/Even/None

(6) Communication speed:

9600 bps, 19200 bps, 38400 bps

(7) Connector: 3-pole, 2.5 mm dia. Sub-miniature jack

\* Special cable is prepared as option.

#### **RS-485** interface

- (1) Number of points: 1
- (2) Physical specifications: EIA RS485
- (3) Protocol: Modbus-RTU
- (4) Communication method:

2-wire, half-duplex, bit serial asynchro-nous

communication

(5) Data type, Data length:

8 bits, Parity; Odd/Even/None

(6) Communication speed:

9600 bps, 19200 bps, 38400 bps

(7) Connection topology:

Multi-drop, Up to 31 units can be connected including

master device

(8) Communication distance:

500 m max. (Total length of connection)

#### **Display**

- (1) Type: LED
- (2) Display contents

Measurement value display:

7 segments, 5 digits (red), Character height: 20 mm

Setting display: 7 segments, 5 digits (orange),

Character height; 13 mm

Auxiliary display:
7 segments, 2 digits (orange),

Character height; 12 mm

Bar graph: 12 segments (orange)

Status display indicator lamp:

Standby, control mode (R/A/M), output, alarm

#### Operation and storage conditions

- (1) Ambient operating temperature: -10 to 50°C
- (2) Storage temperature: -20 to 60°C
- (3) Ambient humidity for use/storage:

90% RH or less (non-condensing)

(4) Warm-up time: 15 min. or longer

#### Structure

- (1) Mounting method: Panel flush mounting
- (2) External terminal: M3 screw terminal
- (3) Case

Material: Plastic (Flame-resistant, UL94V-0)

Color:

(4) Protection

Faceplate: IEC IP66, NEMA-4X-equivalent (When mounted on panel with our genuine packing. Waterproof

feature unavailable in side-by-side mounting.) · Body: IEC IP20 (Provided with slits on top and bottom

faces)

· Terminal section: IEC IP00. Terminal cover can be mounted (option).

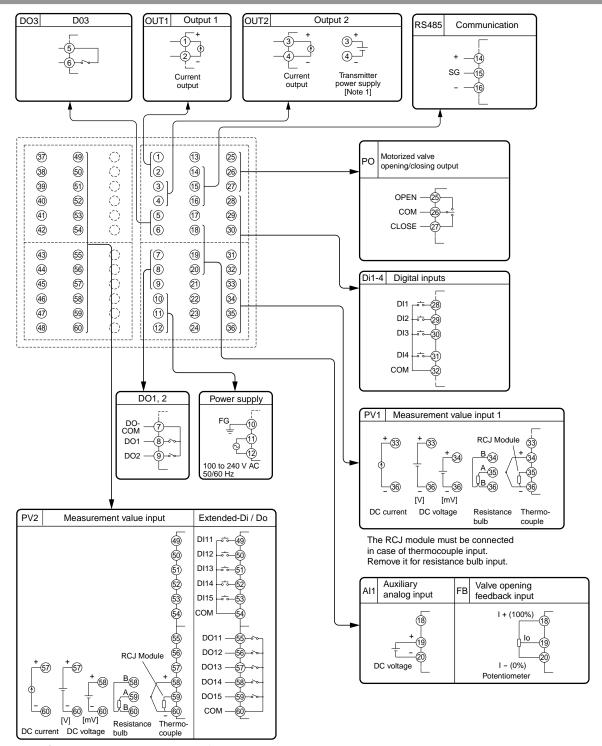
(5) External dimension:

96 (W) x 96 (H) x 81.5 (D) mm

"D" is the depth from the front face of the panel (not including terminal cover).

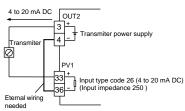
(6) Mass: Approx. 500 q

## Appendix 1 Terminal connection diagram



The RCJ module must be connected in case of thermocouple input. Remove it for resistance bulb input.

[Note1] Connection to the transmitter power supply



## Appendix 2 Parameter list

Cł	1 o F	РΕ (0	peration pa	rameter)			
		Parameter		Content Explanation	Factory	Parameter	Notes
No. 1	r EN I	rEM1	Name Remote mode	Switches setting between remote/auto mode operation. REM: Remote mode AUT: Auto mode	default AUT	mask 01-1	See 4-3.
5	SLPA	STbY	Standby command	Switches controller to RUN/Standby. ON: Control standby (output OFF, alarm OFF) OFF: Control RUN	OFF	01-5	See 4-5.
6	PrG	PrG	Ramp/soak activation command	Switches between ramp/soak operation states oFF: Stop rUn: Run hLd: Hold	OFF	01-6	See 5-30.
7	Ar	AT	Auto-tuning command	Sets auto-tuning. OFF: non-action ON1: start auto-tuning.	OFF	01-7	See 3-10.
8	LACH	LACh	Alarm latch clear command	Disables alarm 1 - 8 latch. OFF: non-action CLR: Latch clear	OFF	01-8	See 3-11.
9	PLIN	PLTn	Palette selection	Selects a PID palette to be used to control. (Setting range: 0 to 7)	0	01-10	See 5-6.
10	ALI	AL1	Alarm settings 1	Alarm 1 operation value setting. Setting possible within the input range	10%FS	02-1	Displayed when alarm operation type 1TP (chA-1) is set to 1 to 11. (See 3-11.)
11	A I-L	A1-L	Alarm lower limit settings 1	Alarm 1 lower limit operation value setting. Setting possible within the input range	10%FS	02-1	Displayed when alarm operation type 1TP (chA-1) is set to 16 to 31. (See 3-11.)
12	A 1-h	A1-h	Alarm upper limit settings 1	Alarm 1 upper limit operation value setting. Setting possible within the input range	10%FS	02-1	Displayed when alarm operation type 1TP (chA-1) is set to 16 to 31. (See 3-11.)
S							B: 1 1 1
31	AL8	AL8	Alarm settings 8	Alarm 8 operation value setting. Setting possible within the input range	10%FS	02-8	Displayed when alarm operation type 8TP (chA-36) is set to 1 to 11. (See 3-11.)
32	A8-L	A8-L	Alarm lower limit settings 8	Alarm 8 lower limit operation value setting. Setting possible within the input range	10%FS	02-8	Displayed when alarm operation type 8TP (chA-36) is set to 16 to 31. (See 3-11.)
33	A8-h	A8-h	Alarm upper limit settings 8	Alarm 8 upper limit operation value setting. Setting possible within the input range	10%FS	02-8	Displayed when alarm operation type 8TP (chA-36) is set to 16 to 31. (See 3-11.)
34	LoC	LoC	Keylock	Selects parameter lock type (Setting range: 0 to 5)	0	01-11	See 5-7.
35	JP I	JP1	Parameter jump setting 1	Press the function key (when 60 is selected), and the display jumps to the specified parameter. (Setting range: I-01 to Z-Z9)	2-01	01-12	See 5-13.
36	JP2	JP2	Parameter jump setting 2	Press the function key (when 61 is selected), and the display jumps to the specified parameter. (Setting range: I-01 to Z-Z9)	2-02	01-12	
37	JP3	JP3	Parameter jump setting 3	Press the function key (when 62 is selected), and the display jumps to the specified parameter. (Setting range: I-01 to Z-Z9)	2-03	01-12	

Ch	2 2	d (Co	ontrol paraı	meter)			
		Parameter			Factory	Parameter	Notes
No.	Display	Symbol	Name	Content Explanation	default	mask	Notes
1	ρ;	P1	Proportional band	Setting range: 0.0 to 999.9% ON/OFF control at setting = 0.	5.0	03-1	See 5-3.
2	<u> </u>	i1	Integral time	Setting range: 0.0 to 3200.0 seconds Integral control OFF at setting = 0.	240.0	03-1	
3	d !	d1	Derivative time	Setting range: 0.0 to 999.9 seconds Derivative control OFF at setting = 0.	60.0	03-1	
5	Arh I	Arh1	Anti - reset windup Upper limit setting value	Integration cut point upper limit setting value (Setting range: 0 to 100%FS)	100%FS	03-3	Sets by deviation from SV. (See 5-5.)
6	Arl I	ArL1	Anti - reset windup Lower limit setting value	Integration cut point lower limit setting value (Setting range: 0 to 100%FS)	100%FS	03-3	
7	Sh I	Sh1	SV value upper limit	Sets upper limit SV (Setting range: -25 to 125%FS)	100%FS	03-4	See 3-9.
8	SL I	SL1	SV value lower limit	Sets lower limit SV (Setting range: -25 to 125%FS)	0%FS	03-4	
9	Nāh I	Mvh1	MV value upper limit	Sets upper limit MV (Setting range: –25.0 to 125.0%FS)	105.0	03-5	See 5-2.
10	NGL I	MvL1	MV value lower limit	Sets lower limit MV (Setting range: -25.0 to 125.0%FS)	-5.0	03-5	
13	anā i	dMv1	MV change ratio limit	Sets the limit value of deviation of MV (DMV) in one control cycle (50ms.) (Setting range: 0.0 to 150.0%) 0.0: No limit	0.0%	03-7	Limit is not applied to the deviation of MV by EX-MV operation. (See 5-2.)
14	ar i	dT1	Sampling cycle	Sets sampling cycle for PID operation. (Setting range: 5 to 1000)	5	03-8	The actual cycle is (dT1 × 10) ms. (See 5-3.)
15	h5 I	hS1	Hysteresis setting	Hysteresis value during ON/OFF control time. (Setting range: 0 to 50%FS)	0.3%FS	03-9	See 5-4.
18	BAL I	bAL1	Operation output convergence value	Sets output convergence value (Setting range: -100.0 to 100.0%)	0.0%	03-12	See 5-5.
19	ΓEΙ	TC1	Cycle time of Control output (MV1)	Sets proportional cycle for control output. (Setting range: 1 to 150 sec)	By designation at the time of ordering	03-13	Effective only for RY output and SSR drive output.
20	rEū!	rEv1	Control action setting	Sets a control action. NRML:Normal (Direct) action REV:Reverse action	REV	03-14	See 3-8.
22	PNJ I	PMv1	Preset value for control output	Sets MV for stanby mode. (Setting range: -25.0 to 125.0%)	0.0	03-16	See 4-5.
23	ALP I	ALP1	Alpha	Sets 2 degrees of freedom coefficient α. (Setting range: –300.0 to 300.0%)	40.0	40-1	See 5-23.
24	BET I	bET1	Beta	Sets 2 degrees of freedom coefficient β. (Setting range: 0.0 to 999.9%)	100.0	40-1	
38	Ld I	Ld1	Output limiter type setting	Sets whether the value should be limited at the output limit setting or the limit should be exceeded (125%, $-25\%$ ) when the output reaches the output limit setting. $\begin{array}{ c c c c c c }\hline LD1 & Output operation \\\hline Upper side & Lower side \\\hline 0 & 125.0\% & -25.0\% \\\hline 1 & 125.0\% & Limit \\\hline 2 & Limit & -25.0\% \\\hline 3 & Limit & Limit \\\hline \end{array}$	3	40-9	See 5-2.
97	EHNI	EXM1	External manipulated value	Sets external output value. (Setting range: -25.0 to 125.0%)	0.0	07-1	See 5-22.
99	ŁF I	kF1	FF gain	Sets Feed Forward gain and bias 1,	0.0	40-2	
A0	ЫFI	b1F1	FF bias1	bias 2. [FF = KF1 × (Input - B1F) + B2F]	0.0	40-2	
A1	62F I	b2F1	FF bias2	(Setting range: -1000.0 to 1000.0)	0.0	40-2	

		_			1		
Vo.	Display	Parameter Symbol	Name	Content Explanation	Factory default	Parameter mask	Notes
1	5ū I	Sv1	Setting value 1	Palette 1 SV (Setting range: SV lower limit value to SV upper limit value)	0%FS	08-1	See 5-6.
2	P-!	P-1	Proportional band 1	Palette 1 proportional band (Setting range: 0.0 to 999.9%) ON/OFF control at setting = 0.	5.0	08-1	
3	<u> </u>	i-1	Integral time 1	Palette 1 integral time (Setting range: 0.0 to 3200.0 sec) Integral control OFF at setting = 0.	240.0	08-1	
4	d-1	d-1	Derivative time 1	Palette 1 derivative time (Setting range: 0.0 to 999.9 sec) Derivative control OFF at setting = 0.	60.0	08-1	
6	Arh!	Arh1	Anti - reset windup upper limit value 1	Palette 1 Anti - reset windup upper limit value setting. (Setting range: 0 to 100%FS)	100%FS	08-1	
7	Arl!	ArL1	Anti - reset windup lower limit value 1	Palette 1 Anti - reset windup lower limit value setting. (Setting range: 0 to 100%FS)	100%FS	08-1	
8	h95 I	hYS1	Hysteresis setting 1	Palette 1 hysteresis setting (Setting range: 0 to 50%FS)	0.3%FS	08-1	
11	bL - 1	bL-1	Output convergence value 1	Palette 1 Output convergence value (Setting range: -100.0 to 100.0%)	0.0%	08-1	
67	557	Sv7	Setting value 7	Palette 7 SV (Setting range: SV lower limit value to SV upper limit value)	0%FS	14-1	See 5-6.
68	P-7	P-7	Proportional band 7	Palette 7 proportional band (Setting range: 0.0 to 999.9%) ON/OFF control at setting = 0.	5.0	14-1	
69	<u>-</u> 7	i-7	Integral time 7	Palette 7 integral time (Setting range: 0.0 to 3200.0 sec) Integral control OFF at setting = 0.	240.0	14-1	
70	d-7	d-7	Derivative time 7	Palette 7 derivative time (Setting range: 0.0 to 999.9 sec) Derivative control OFF at setting = 0.	60.0	14-1	
72	Arhl	Arh7	Anti - reset windup upper limit value 7	Palette 7 Anti - reset windup upper limit value setting. (Setting range: 0 to 100%FS)	100%FS	14-1	
73	Arll	ArL7	Anti - reset windup lower limit value 7	Palette 7 Anti - reset windup lower limit value setting. (Setting range: 0 to 100%FS)	100%FS	14-1	
74	hYS7	hYS7	Hysteresis setting 7	Palette 7 hysteresis setting (Setting range: 0 to 50%FS)	0.3%FS	14-1	
77	bL - 7	bL-7	Output convergence value 7	Palette 7 Output convergence value (Setting range: -100.0 to 100.0%)	0.0%	14-1	
78	rEF I	rEF1	PID switch point 1	Palette 1 PID switch point (Setting range: -25 to 125%FS)	0%FS	08-1	See 5-6.
84	rEF7	rEF7	PID switch	Palette 7 PID switch point	0%FS	14-1	See 5-6.

C	hz 🛭 c	-	lonitor)				
C			ioriitor)		ı		
No.	Display	Parameter Symbol	Name	Content Explanation	Factory default	Parameter mask	Notes
1	ا ت ۲	Pv1	PV1 monitor	Displays Process value 1 input.	-	17-1	See 4-6
2	P52	Pv2	PV2 monitor	Displays Process value 2 input.	-	17-2	
4	8 <u>.</u> ;	Ai1	Al1 monitor	Displays Analog input 1 input.	-	17-5	
6	rSū!	rSv1	RSV1 monitor	Displays Remote set value 1	-	17-9	
10	LSūl	LSV1	Local SV1 monitor	Display Local set value 1	-	17-9	
14	r[]1	RCJ1	RCJ1 monitor	Displays RCJ1 input.	-	17-1	
15	r E J2	RCJ2	RCJ2 monitor	Displays RCJ2 input.	-	17-2	
17	Ro I	Ao1	AO1 monitor	Displays Analog output 1 output value.	-	18-1	
18	802	Ao2	AO2 monitor	Displays Analog output 2 output value.	_	18-1	
21	9 <u>50</u> 1	Di01	DI monitor 1	Displays Nitalog Guiput 2 Guiput Value:  Displays DI1 to 4 status.  DI4  DI3  DI2  DI1  OFF: Blank ON: Di No.	-	19-1	
22	∂ī II	Di11	DI monitor 2	DI15	-	19-1	
24	do0 1	DO01	DO monitor 1	Displays DO1 to 4 status.  DO4 DO3 DO2 DO1 DO1 DO1 DO2 DO1 DO3 DO2 DO1 DO3 DO2 DO1 DO3 DO3 DO3 DO3 DO3 DO4 DO3 DO5	-	19-1	
25	do II	DO11	DO monitor 2	Displays DO11 to 15 status.  DO15 DO14 DO13 DO12 DO11	-	19-1	
27	8EN	AiM	Math result monitor	Displays result of math operation.	_	19-3	
28	רח ו	TM1				34-1	
29	rns	TM2				34-2	
30	rn3	TM3	<b>.</b>			34-3	
31	רחץ	TM4	Alarm delay	Displays the remaining time for the alarm	-	34-4	
32	กกร	TM5	remaining time monitor	delay of ALM1 to ALM8.		34-5	
33	rns	TM6				34-6	
34	רחז	TM7				34-7	
35	rne	TM8				34-8	
36	805 (	AMV1	EXMV monitor	Displays the value to be output as EXMV.	-	17-9	
40	FF J I	FFV1	Feed Forward value	Displays the value of Feed Forward element.	-	17-9	
50	Погь	MVrb	Valve monitor	Displays the valve opening degree	-	17-5	
				feedback value.	l		

С	h7 <i>11 c</i>	on (N	lonitor)				
		Parameter			Factory	Parameter	
No.	Display	Symbol	Name	Content Explanation	default	mask	Notes
100	9∑E 1	DiC1	Communication Di monitor (1-5)	Displays the status of communication Di1-5.  Communication Di5  Communication Di4  Communication Di3  Communication Di2  Communication Di1	-	19-4	See 5-28
101	4565	DiC2	Communication Di monitor (6-8)	Displays the status of communication Di6-8.  Communication Di8  Communication Di7  Communication Di6	1	19-4	
A2	SCAC	STAT	Display of Ramp/soak activation	Displays the Ramp/soak running status oFF: Ramp/soak is stopped 1-rP: Step1 during ramp 1-Sk: Step1 during soak 64rP: Step64 during ramp 64Sk: Step64 during soak End: Ramp/soak end	-	15-1	See 5-30
<b>A</b> 3	רפרח	rSTM	Ramp/soak elapsed time	Displays the elapsed time of segment during Ramp/soak 00:00 to 99:59 (hour : min / min : sec)	-	15-2	
A4	Prno	PTno	Current pattern No.	Displays the pattern No. of the ramp soak currently selected. 0 to 30	-	15-3	
<b>A</b> 5	PEPF	DiPT	Current pattern No. selected by DI	Displays the pattern No. of the ramp soak currently selected 0 to 30	-	15-4	
A6	r5ū	rSV	Display the SV value which is result from Ramp/soak calculation	Displays the SV value which is result from Ramp/soak calculation. 0 to 100%FS	-	15-5	

Ch	n8 5E	Γ (In	put/output	definition)			
<u> </u>		Parameter	paroarpar		Factory	Parameter	
No.	Display	Symbol	Name	Content Explanation	default	mask	Notes
1	Pā IF	Pv1F	PV1 full-scale	Sets the full-side scale of PV1 input. (Setting range: -19999 to 99999)	As ordered	20-1	See 3-2.
2	PJ 16	Pv1b	PV1 base scale	Sets the base-side scale of PV1 input. (Setting range: –19999 to 99999)	As ordered	20-1	
3	Pā Ia	Pv1d	PV1 decimal point position	Specifies the decimal point position of PV1 input. (Setting range: 0 to 3)  3: 2: 1: 0: No decimal point	As ordered	20-1	
4	רה ור	Pv1T	PV1 input type	Sets the type of PV1 input. (Setting range: 0 to 27)	As ordered	20-1	
5	P	Pv1U	PV1 unit	Sets the measurement unit.  non : No unit  °F : °F unit  °C : °C unit	As ordered	20-2	
6	ان اد	Pv1Z	PV1 input zero point adjustment	Sets the correction value of a zero point for PV1 input. (Setting range: -50 to 50%FS)	0%FS	20-3	See 5-9.
7	Pū 15	Pv1S	PV1 input span point adjustment	Sets the correction value of a span point for PV1 input. (Setting range: -50 to 50%FS)	0%FS	20-3	
11	P ICU 	P1CU	PV1 input cut point	Sets the cut point of square-root extraction calculation for PV1 input. In case of OFF, the square-root extraction is not calculated. (Setting range: OFF, 0.0 to 125.0%)	OFF	20-7	See 5-1.
12	PIFF	P1TF	PV1 input filter	Sets the time constant for PV1 input filter. (Setting range: 0.0 to 900.0 sec)	0.0	20-8	
13	PILA	P1Ln	PV1 linearize setting	PV1 input linearize enable/disable setting (Setting range: OFF, nrML, hi-C, Lo-C)	OFF	20-9	See 5-28.
14	PJ2F	Pv2F	PV2 full-scale	Sets the full-side scale of PV2 input. (Setting range: –19999 to 99999)	As ordered	20-1	See 3-2.
15	Pü26	Pv2b	PV2 base scale	Sets the base-side scale of PV2 input. (Setting range: –19999 to 99999)	As ordered	20-1	
16	Pū2d	Pv2d	PV2 decimal point position	Specifies the decimal point position of PV2 input. (Setting range: 0 to 3)  3: 2: 1: 0: No decimal point	1	20-1	
17	P525	Pv2T	PV2 input type	Sets the type of PV2 input. (Setting range: 0 to 27)	3	20-1	
18	P52U	Pv2U	PV2 unit	Sets the measurement unit for PV2 input.  non : No unit  °F : °F unit  °C : °C unit	°C	20-2	
19	Pū22	Pv2Z	PV2 input zero point adjustment	Sets the correction value of a zero point for PV2 input. (Setting range: -50 to 50%FS)	0%FS	20-3	See 5-9.
20	P525	Pv2S	PV2 input span point adjustment	Sets the correction value of a span point for PV2 input. (Setting range: -50 to 50%FS)	0%FS	20-3	
24	P2CU	P2CU	PV2 input cut point	Sets the cut point of square-root extraction calculation for PV2 input. In case of OFF, the square-root extraction is not calculated. (Setting range: OFF, 0.0 to 125.0%)	OFF	20-7	See 5-1.
25	PZTF	P2TF	PV2 input filter	Sets the time constant for PV2 input filter. (Setting range: 0.0 to 900.0 sec)	0.0	20-8	

	18 <i>5E</i>	, (111	putoutput	definition)			
No.	Display	Parameter Symbol	Name	Content Explanation	Factory default	Parameter mask	Notes
26	P2Ln	P2Ln	PV2 linearize setting	PV2 input linearize enable/disable setting (Setting range: OFF, nrML, hi-C, Lo-C)	OFF	21-9	See 5-28.
40	AC IF	Ai1F	Ai1 full scale	Sets the full-side scale of analog (Ai1) input. (Setting range: –19999 to 99999)	As ordered	23-1	See 3-2.
41	AC 16	Ai1b	Ai1 base scale	Sets the scale of base-side analog (Ai1) input. (Setting range: –19999 to 99999)	As ordered	23-1	
42	₩. IA	Ai1d	Ai1 decimal point position	Specifies the decimal point position for analog (Ai1) input. (Setting range: 0 to 3)  3: 2: 1: 0: No decimal point	1	23-1	
43	AC IF	Ai1T	Ai1 input type	Sets the type of Ai1 input. (Setting range: 16 to 18, 23, 24)	As ordered	23-1	
45	AC 15	Ai1Z	Ai1 input zero point adjustment	Sets the correction value of a zero point for Ai1 input. (Setting range: -50 to 50%FS)	0%FS	23-3	See 5-9.
46	AC IS	Ai1S	Ai1 input span point adjustment	Sets the correction value of a span point for Ai1 input. (Setting range: -50 to 50%FS)	0%FS	23-3	
49	A ICU	A1CU	Ai1 input cut point	Sets the cut point of the square-root extraction calculation for Ai1 input. In case of OFF, the square-root extraction is not calculated.  (Setting range: OFF, 0.0 to 125.0%)	OFF	23-7	See 5-1.
50	A ICF	A1TF	Ai1 input filter	Sets the time constant for Ai1 input filter. (Setting range: 0.0 to 900.0sec)	0.0	23-8	
51	A ILn	A1Ln	Ai1 linearize setting	Ai1 input linearize enable/disable setting (Setting range: OFF, nrML, hi-C. Lo-C)	OFF	23-9	See 5-28.
64	Ao If	Ao1T	AO1 output type	Switches the AO1 (re-transmission output) signal. Setting range: PV, SV, MV, DV, AiM, MVRB, TV	PV	25-1	See 3-12.
66	Ro Ih	Ao1h	AO1 output scale upper limit	Sets the scale upper limit value of the AO1 output. (Setting range: -130.0 to 130.0%)	100.0%	25-1	
67	Ro IL	Ao1L	AO1 output scale lower limit	Sets the scale lower limit value of the AO1 output. (Setting range: -130.0 to 130.0%)	0.0%	25-1	
68	A ILh	A1Lh	AO1 output limit upper limit	Sets the upper limt value of the AO1 output limit. (Setting range: -25.0 to 105.0%)	105.0%	25-1	
69	A ILL	A1LL	AO1 output limit lower limit	Sets the lower limt value of the AO1 output limit. (Setting range: -25.0 to 105.0%)	-5.0%	25-1	
70	A-21	Ao2T	AO2 output type	Switches the AO2 (re-transmission output) signal. Setting range: PV, SV, MV, DV, AiM, MVRB, TV	PV	25-2	
72	Ro2h	Ao2h	AO2 output scale upper limit	Sets the scale upper limit value of the AO2 output. (Setting range: -130.0 to 130.0%)	100.0%	25-2	
73	Ro2L	Ao2L	AO2 output scale lower limit	Sets the scale lower limit value of the AO2 output. (Setting range: -130.0 to 130.0%)	0.0%	25-2	
74	82Lh	A2Lh	AO2 output limit upper limit	Sets the upper limt value of the AO2 output limit. (Setting range: -25.0 to 105.0%)	105.0%	25-2	
75	85LL	A2LL	AO2 output limit lower limit	Sets the lower limt value of the AO2 output limit. (Setting range: -25.0 to 105.0%)	-5.0%	25-2	

Cł	18 <i>5E</i>	່ 「 (In	put/output	definition)			
No.	Display	Parameter Symbol	Name	Content Explanation	Factory default	Parameter mask	Notes
88	ERLÉ	CALC	Calculation setting	Math function type setting. (Setting range: 0 to 40)	0	25-9	See 5-14.
89	UCF I	UCF1	Math function full scale	Sets the scale on the full side which is utilized for mathematical calculations. (Setting range: –19999 to 99999)	As ordered	25-9	
90	ИСЬ І	UCb1	Math function base scale	Sets the scale on the base side which is utilized for mathematical calculations. (Setting range: –19999 to 99999)	As ordered	25-9	
91	UC4 I	UCd1	Math function decimal point position	Sets the decimal point position for mathematical calculations. (Setting range: 0 to 3)	1	25-9	
92	r PL r	TPLT	Template	Specifies the template. The range of effective setting. 30 : 1-loop motor-operated valve controller (with input Math) 31 : 1-loop SV selection type motor-operated valve controller (with input Math) 33 : 1-loop motor-operated valve controller 34 : 1-loop SV selection type motor-operated valve controller	13	25-10	See 3-1.
93	oryp	oTYP	Output type	Selects the control output selector type. (Setting range: 30 to 31)	As ordered	25-11	See 5-24.
98 \$ b3	Cn0 I S Cn 16	CN01	System constant 1 \$ System constan 16	Sets a constant value used for templates. The meaning of the value varies depending on template. Make the setting after checking the description of each template. (Setting range: -19999 to 99999)	As ordered	25-15	

			stem defin	,			
No.	Display	Parameter Symbol	Name	Content Explanation	Factory default	Parameter mask	Notes
1	PAS I	PAS1	Password 1	Sets security (passwords). (Setting range: 0000 to FFFF)	0000	26-1	See 5-20.
2	PRS2	PAS2	Password 2	Sets security (password). (Setting range: 0000 to FFFF)	0000	26-2	
3	PRS3	PAS3	Password 3	Sets security (password). (Setting range: 0000 to FFFF)	0000	26-3	
7	rīh!	rih1	Remote mode inhibiting	Prevents switching to the REMOTE mode. (Setting range: ON/OFF)	OFF	27-1	See 5-15.
11	rRC I	rAC1	R_ACK use selection	Selects use or non-use of R_ACK. (Setting range: INH, ENA)	INH	27-5	See 5-16.
15	A-U I	A-M1	A/M mode	Selects the A/M mode. (Setting range: A-M, A)	A-M	27-9	See 5-17.
19	[nd	Cnd1	Mode settings when the power turns ON.	Sets the mode when the power turns ON. (Setting range: A, R, M)	А	28-1	See 5-18.
23	L-F1	Trk1	Tracking method selection (SV)	Selects ON or OFF for tracking the local set value (SV)	ON	28-9	See 5-19.
30	Srbo	STBo	Operation settings when in standby mode	Sets the front display operation in the standby mode. (Setting range: 0: lighting, 1: extinction)	0	29-4	See 4-5.
31	PLT5	PLTS	Palette switching method selection	Selects a palette switching factor. (Setting range: PLTn, SV, PV)	PLTn	29-6	See 5-6.
32	FI	F1	User designation key-1 (F1)	Sets user assignments for function keys.	0	29-7	See 5-13.
33	F2	F2	User designation key-2 (F2)	[F1] - [F3]. (Setting range: 0 - 72)	0	29-8	
34	F3	F3	User designation key-3 (F3)		0	29-9	
35	brd!	brd1	Designates output at burnout	Designates control output at input error or valve opening degree feedback anomaly.  HOLD: Outputs to follow MV  Lo : Turns on CLOSE signal  UP : Turns on OPEN signal  EXMV: Controls to join EXMV setting  Poff : Turns off OPEN, and CLOSE  signals, MV is tracked to MVRB.	Lo	30-1	See 5-8.
39	9 <u>50</u> 1	di01	Assignment for digital input 1		di01 : 60 di02 : 70	31-1	See 5-10.
<b>\$</b> 42	9 <u>5</u> 04	S di04	Assignment for digital input 4	Sets assignments for DI1-DI4, DI11-DI15.	di03 : 0 di04 : 103		
43	dī 11	di11	Assignment for digital input 11	(Setting range: 0 - 178)	0	31-2	
<b>\$</b> 47	9 <u>5</u> 12	<b>\$</b> di15	Assignment for digital input 15				
53	do l	do1	Assignment for digital output 1		do1 : 1 do2 : 2	31-9	See 5-11.
<b>\$</b> 56	√ do4	<b>\$</b> do4	\$ Assignment for digital output 4	Sets assignments for DO1-DO4, DO11-DO15.	do3 : 3 do4 : 4		
57	do 11	do11	Assignment for digital output 11	(Setting range: 0 - 427)	0	31-10	
<b>\$</b> 61	s do 15	<b>\$</b> do15	Sassignment for digital output 15				

Cł	<sub>19</sub> 55	5 (S)	stem defir	nition)			
		Parameter		Content Explanation	Factory	Parameter	Notes
No.	Display	Symbol	Name	Someth Explanation	default	mask	110100
67	E 1	C1	LED C1 assignment		19	32-1	See 5-12.
68	[5	C2	LED C2 assignment		20	32-2	
69	Ldo I	Ldo1	LED DO1 assignment	Allocates indicator LEDs. (Setting range: 0 to 427)	Ldo1 : 1 Ldo2 : 2	32-3 32-4	
\$	\$	S	\$ LED DO5		Ldo3 : 3 Ldo4 : 4	32-5 32-6	
73	Ldo5	Ldo5	assignment		Ldo5 : 0	32-7	
74	LALN	LALM	LED ALM assignment		17	32-8	
76	6-6 I	brG1	Bar graph display type	Select value to display on bar graph.  MON : No display  MV : Control output  MVRB : Valve opening degree feedback  value (MVRB)	MV	32-10	See 3-6.
78	aspr	dSPT	Operation screen display type	Select value to indicate at 5-digit display on bottom of operation screen.  0 : Control output (MV)  1 : Valve opening degree feedback value (MVRB)	0	32-14	See 3-6.
79	ad5P	odSP	Operation display setting	Sets display items during operation. (Setting range: 000 to 111)  PV/totalized value Totalizer instantaneous value/ totalized value PV/Math calculation result	000	32-15	See 5-24.
80 \$ C3	4500 4544	dS00 <b>\$</b> dS44	Parameter mask setting	Skips (not display) unnecessary parameters.	-	0-1 \$ 0-14	See 5-21.
E3	rES	rES	Reset command	Resets the main unit. ON : Reset OFF : RUN	OFF	33-1	See 3-7.

		Parameter		Content Evalenation	Factory	Parameter	
No.	Display	Symbol	Name	Content Explanation	default	mask	Notes
1	IFP	1TP	Alarm 1 type setting	Sets the alarm type for alarm 1. (Setting range: 0 to 38)	0	34-1	See 3-11.
2	loP	10P	Alarm 1 option setting	Sets alarm options for alarm 1. (Setting range: 0000 to 1111)  Switching unit time 0: Seconds 1:minutes non-excitation output Unit abnormal Latch	0000	34-1	
3	IHYS	1hYS	Alarm 1 hysteresis setting	Sets alarm hysteresis for alarm 1. (Setting range: 0.00 to 50.00%FS)	0.3%FS	34-1	
4	IALY	1dLY	Alarm 1 delay time setting	Sets delay time for alarm 1. (Setting range: 0 to 9999)  * Sets alarm options for time units. The unit of time is selected by alarm options.	0	34-1	
S							
36	8rP	8TP	Alarm 8 type setting	Sets the alarm type for alarm 8. (Setting range: 0 to 38)	0	34-8	See 3-11.
37	8 <sub>0</sub> P	80P	Alarm 8 option setting	Sets alarm options for alarm 8. (Setting range: 0000 to 1111)  Switching time unit 0: OFF 1: ON non-excitation output Abnormal input Latch	0000	34-8	
38	8h45	8hYS	Alarm 8 hysteresis setting	Sets alarm hysteresis for alarm 8. (Setting range: 0.00 to 50.00%FS)	0.3%FS	34-8	
39	84LY	8dLY	Alarm 8 delay time setting	Sets delay time for alarm 8. (Setting range: 0 to 9999)  * Sets alarm options for time units. The unit of time is selected by alarm options.	0	34-8	

Ch	в Га		ommunicati	ion)						
		Parameter				1 2		Factory	Parameter	N. c
No.	Display	Symbol	Name	Conter	nt Ex	planation		default	mask	Notes
2	SFAY	STn4	RS485 station No.	Specifies RS485 communication station No. (Setting range: 0 to 255)  * does not operate with STn4=0.			1	36-2	See 3-13.	
3	SPd4	SPd4	RS485 communication speed	Selects communication. (Setting range) 96:9600 b 192:19200 384:38400	ps bps	n speed fo	or RS485	384	36-3	
4	BITY	biT4	RS485 bit format	8	for R 8n 8o 8E	S485 comi Data length 8 8 8		80	36-4	
7	SPd2	SPd2	PC Loader communication speed	Selects the comm Loader communic 96: 9600 bps 192: 19200 bps 384: 38400 bps				384	36-9	
8	PILS	biT2	PC Loader bit format			for PC Loa Data length 8 8 8	Parity None Odd Even	80	36-10	
51	E E O 1	Ci01	Communication Di1 function setting	Sets the function	of co	ommunicat	tion Di1.	0	36-16	See 5-29.
52	E E O 2	Ci02	Communication Di2 function setting	Sets the function	of co	ommunicat	tion Di2.	0	36-16	
53	E E O 3	Ci03	Communication Di3 function setting	Sets the function	of co	ommunicat	tion Di3.	0	36-16	
54	E E O Y	Ci04	Communication Di4 function setting	Sets the function	of co	ommunicat	tion Di4.	0	36-16	
55	<i>E E O S</i>	Ci05	Communication Di5 function setting	Sets the function	of co	ommunicat	tion Di5.	0	36-16	
56	E E 08	Ci06	Communication Di6 function setting	Sets the function	of co	ommunicat	tion Di6.	0	36-16	
57	בבטח	Ci07	Communication Di7 function setting	Sets the function	of co	ommunicat	tion Di7.	0	36-16	
58	E E 08	Ci08	Communication Di8 function setting	Sets the function	of co	ommunicat	tion Di8.	0	36-16	

Cł	nc Ln	ر (Li	nearize)				
	1	Parameter		Content Explanation	Factory	Parameter	Notes
No.	Display	Symbol	Name	Comem Explanation	default	mask	
1	P 1H0	P1X0	Linearize table P1X0	Linearize table X0 for PV1 input (Setting range: –25% to 125%FS)	-25%FS	37-1	See 5-28.
S							
32	P IYF	P1YF	Linearize table P1YF	Linearize table YF for PV1 input (Setting range: –25% to 125%FS)	125%FS	37-1	
33	P2H0	P2X0	Linearize table P2X0	Linearize table X0 for PV2 input (Setting range: –25% to 125%FS)	-25%FS	37-2	
5							
64	P2YF	P2YF	Linearize table P2YF	Linearize table YF for PV2 input (Setting range: -25% to 125%FS)	125%FS	37-2	
97	8 IHO	A1X0	Linearize table A1X0	Linearize table X0 for Ai1 input (Setting range: –25% to 125%FS)	-25%FS	37-4	
5							
128	A IYF	A1YF	Linearize table A1YF	Linearize table YF for Ai1 input (Setting range: –25% to 125%FS)	125%FS	37-4	

Ch	ChD £££ (Calculation constant)										
Na	Parameter  O. Display Symbol Name  Content Explanation  Factory Parameter default mask Notes										
No.	Display	Symbol	Name	•	delault	mask					
1 \$ 16	£01 €15	k01 { k16	Constant for math function	Sets the constant used for mathematical expressions	0.0000	38-1 \$ 38-4	See 5-14.				

Ch	1E <i>81</i>	(Tu	ıning)				
No.	Display	Parameter Symbol	Name	Content Explanation	Factory default	Parameter mask	Notes
1	ACP I	ATP1	Auto tuning type	Specifies the auto-tuning method. (Setting range) NRML: Standard type AT LPV: Low PV type AT	NRML	39-1	See 3-10.

Ch	of <i>PF</i>	<i>ხ</i> (m	otorized va	lve definition)			
No.		Parameter	Name	Content Explanation	Factory default	Parameter mask	Notes
1	Display JF 4P	Symbol VTYP	Valve type	Sets control type of motorized valve.  Fb : PFB control  Fb-Sr : PFB + estimation control  Sr1 : Estimation control 1  Sr2 : Estimation control 2  (Turning on power closes valve all the way)	Fb	44-1	See 3-3.
2	rūL	TrVL	Travel time	Sets time required for valve to move over full stroke. Automatically set in case of automatic adjust of valve. (Setting range: 5.0 to 300.0 sec)	30.0S	44-2	See 3-5.
3	PGP	PGP	Dead band of valve operation	Sets dead band of OPEN/CLOSE signals. (Setting range: 0.5 to 100.0%)	10.0%	44-3	See 3-4.
6	84PE	AdPC	Calibration value at which valve is fully closed	Value at which valve is closed all the way. (Setting range: 0 to FFFFF)	-	44-6	See 3-5.
7	RdPo	AdPO	Calibration value at which valve is fully open	Value at which valve is open all the way. (Setting range: 0 to FFFFF)	-	44-7	See 3-5.
8	CALЬ	CALb	Valve calibration command	Allows to adjust the valve.  OFF : Termination of calibration  CLOSE: Manual calibration of fully closed position  OPEN: Manual calibration of fully open position  AUTO: Automatic calibration	OFF	44-8	See 3-5.

Cł	ng <i>[ a</i>	Γ (To	otalizer)				
		Parameter		Content Explanation	Factory	Parameter	Notes
No.	Display	Symbol TrUn	Name Totalizer	Control the totalizer.	default HOLD	mask 45-1	See 5-26.
	[run	11011	command/status	(Setting range: HoLd/rUn/LATcH)	HOLD	43-1	066 J-20.
2	r-85	TrES	Totalizer reset command	Resets totalizer. (on/oFF)	oFF	45-1	
3	Foin	Toin	Totalizer input selection	Selects input used for totalizer. (Setting range: Pv1, Pv2, Ai1, AiM) * Math function scale (Ch8-89, 90, 91) is adopted when "(3) AiM" is selected.	Pv1	45-2	
4	1.9b	TdP	Totalizer decimal point position	Sets decimal point position of totalized value. (Setting range: 0 to 4)	0	45-3	
5	רנטר	TCUT	Totalizer input cut point	Sets the cut point for totalizer input. The input lower than the cut point is not added. (Setting range: 0% to 100%FS)	0%FS	45-4	
6	A IFP	A1TP	Totalizer alarm 1 type	Sets alarm type of totalizer alarm 1. Setting range: 0: No alarm 1: Totalize value alarm 2: Batch control output 3: Batch control output (with auto reset)	0	45-5	
7	A lon	A1on	Totalizer alarm 1 ON pulse width	Sets ON pulse width for batch control output for totalizer alarm 1. Setting range: 0: Continue 1: 100ms 2: 200ms 3: 500ms 4: 1 sec.	0	45-5	
8	A 10P	A1oP	Totalizer alarm 1 option setting	Sets excitation/non-excitation option for totalizer alarm 1 (Setting range: 0: Excitation, 1; Non-excitation)	0	45-3	
9	ASCP	A2TP	Totalizer alarm 2 type	Sets alarm type of totalizer alarm 2. Setting range: 0: No alarm 1: Totalize value alarm 2: Batch control output 3: Batch control output (with auto reset)	0	45-6	
10	A2on	A2on	Totalizer alarm 2 ON pulse width	Sets ON pulse width for batch control output for totalizer alarm 2. Setting range: 0: Continue 1: 100ms 2: 200ms 3: 500ms 4: 1 sec.	0	45-6	
11	R20P	A2oP	Totalizer alarm 2 option setting	Sets excitation/non-excitation option of totalizer alarm 2. (Setting range: 0; Excitation, 1; Non-excitation)	0	45-6	
12	LUOA	TMod	Operation mode	Selects operation mode from Japanese and English modes. [Japanese mode] Calculation is made using totalizer conversion factor. [English mode] Calculation is made based on time base time and scaling value. Setting range: (0) JPn: Japanese mode (1) EnG: English mode	EnG	45-7	

Cł	ng Fa	ر (To	otalizer)				
No.	Display	Parameter Symbol	Name	Content Explanation	Factory default	Parameter mask	Notes
13	ropr	ToPT	Totalizer option setting	(bit setting: 0000 to 1111) Obit: Sets flickering of the totalized value at the occurrence of totalized value over. (Totalize is suspended while the display flickers.) 1bit: Totalizer operation at standby 0: Continue, 1: Stop 2bit: Command at power ON 0: Stop, 1: Start 3bit: Totalizer operation at the occurrence of erroneous input 0: Add, 1: Not add	0011	45-8	See 5-26.
14	ГЬ	Tb	Totalizer time base	Sets reference unit time for totalize. (Setting range: SEC, Min, hour, dAY)	hoUr	45-9	
15	SCL	SCL	Totalizer scaling value	Divisor for totalizer input value scale conversion  Note: Addition is not performed when 0 is selected. (Setting range: 0 to ±1000000)	1	45-9	
16	NUL	MUL	Input multiplier	Multiplier for input value scale conversion (Setting range 0 to ±1000000)	1	45-9	
17	ΓEF	TCF	Totalizer conversion factor	Totalized value display when 100% input is continued for 1 hour (Setting range: 20 to 9999999. The decimal point appears according to TdP setting.)	10000	45-10	
18	Līn	TinT	Totalizer initial value	The following relation holds when the value different from the current setting is selected as the initial value of totalizer.  Totalized value = Initial value of totalizer (Setting range: 1999999 to 9999999. The decimal point appears according to TdP setting.)	0	45-11	
19	A ISP	A1SP	Totalizer alarm 1 setting	Sets the operation value of totalizer alarm 1. (Setting range: 1999999 to 9999999. The decimal point appears according to TdP setting.)	10000	45-5	
20	R2SP	A2SP	Totalizer alarm 2 setting	Sets the operation value of totalizer alarm 2. (Setting range: 1999999 to 9999999. The decimal point appears according to TdP setting.)	10000	45-6	
21	-F5E	rTSc	Re-transmission output scale	Sets the totalized value that allows re-transmission output to be 100%. (Setting range:1999999 to 9999999. The decimal point appears according to TdP setting.)	10000	45-12	

Cł	nH ~ 5	(Ra	amp/soak)				
No.	Parameter			Content Explanation	Factory default	Parameter mask	Notes
1	PFn	PTn	Name Ramp/soak activation pattern	Sets up which step will be used for Ramp/soak.  0: 1-4	0	15-6	See5-30.
2	רבחט	TiMU	Ramp/soak time units	Sets the units used when setting the ramp/soak time hh.MM (hour : min) MM.SS (min : sec)	hh.MM (0)	15-7	
3	5ū- I	Sv-1	(STEP1) Ramp/soak SV setting value	Sets the SV 0 to100%FS	0%FS	6-1	
4	רח ור	TM1r	(STEP1) Ramp time	Sets the ramp time 00:00 to 99:59 (hour : min / min : sec)	OO:OO (hour : min)	16-1	
5	רח וב	TM1S	(STEP1) Soak time	Set the soak time 00:00 to 99:59 (hour : min / min : sec)	00:00 (hour : min)	16-1	
<b>\</b> J2	5564	Sv64	(STEP64)	Set the SV	0%FS	16-1 16-1	
J3	ГБ4r	T64r	SV setting value (STEP64) Ramp time	0 to 100%FS  Set the ramp time 00:00 to 99:59 (hour : min / min : sec)	00:00 (hour : min)	16-1	
J4	<i>Г</i> Б45	T64S	(STEP64) Soak time	Set the soak time 00:00 to 99:59 (hour : min / min : sec)	00:00 (hour : min)	16-1	
J5	Nod	Mod	Ramp/soak mode	Set the program operation method 0 to 15	0	15-8	
J6	€5o£	GSok	Guaranty soak ON/OFF	Sets the guaranty soak ON/OFF oFF : Guaranty soak OFF on : Guaranty soak ON	oFF (0)	15-9	
J7	65-h	GS-h	Guaranty soak band (upper)	Sets the upper limit for the guaranty soak band. 0 to 50%FS	1.25%FS	15-9	
J8	65-L	GS-L	Guaranty soak band (lower)	Sets the lower limit for the guaranty soak band 0 to 50%FS	1.25%FS	15-9	
J9	PüSC	PvST	PV start	Sets whether or not to start ramp soak with PV  oFF: P V start OFF  on: P V start ON	oFF (0)	15-10	
Ко	Conf	ConT	Continue mode	Sets how to restart when the controller is restored after a power loss during ramp soak.  rES: Reset (hold)  Con: Continue ini: Restart	rES ( 0)	15-11	
K1	₽Γ₼በ	PTnM	Set the Max. pattern	Sets the selectable Max. number to select the pattern with the function key 0 to 30, di	30	15-12	
K2	PNIn	Pmin	Set tne Min. pattern	Sets the selectable Min. number to select the pattern with the function key 0 to 30, di	0	15-12	

Cł	nx σ£	<i>P</i> (Re	ecipe)				
	Parameter			Content Explanation	Factory default	Parameter mask	Notes
No. 1	Display	Symbol rCP0	Name Recipe	Sets parameter to be allocated as	0-00	46-1	See 5-27.
S			allocation 1	recipe 1 (Setting range 0-00 to W-Z9)			
10	r[P9	rCP9	Recipe allocation 10	Sets parameter to be allocated as recipe 10 (Setting range: 0-00 to W-Z9)	0-00	46-10	
11	400	d00	Recipe setting 0	Recipe parameter 1 setting for palette 0 (when palette is not used) (Setting range: According to rCP0 setting)	0	46-15	
20	409	d09	Recipe setting 9	Recipe parameter 10 setting for palette 0 (when palette is not used) (Setting range: According to rCP9 setting)	0	46-15	
21	d 10	d10	Recipe setting 10	Recipe parameter 1 setting for palette 1 (Setting range: According to rCP0 setting)	0	46-1	
30	d 19	d19	Recipe	Recipe parameter 10 setting for palette 1	0	46-10	
31	420	d20	Recipe setting 20	(Setting range: According to rCP9 setting)  Recipe parameter 1 setting for palette 2 (Setting range: According to rCP0 setting)	0	46-1	
S			Scurig 20	(Cetting range. According to roll of Setting)			
40	829	d29	Recipe setting 29	Recipe parameter 10 setting for palette 2 (Setting range: According to rCP9 setting)	0	46-10	
41	430	d30	Recipe setting 30	Recipe parameter 1 setting for palette 3 (Setting range: According to rCP0 setting)	0	46-1	
S							
50	839	d39	Recipe setting 39	Recipe parameter 10 setting for palette 3 (Setting range: According to rCP9 setting)	0	46-10	
51	<i>8</i> 40	d40	Recipe setting 40	Recipe parameter 1 setting for palette 4 (Setting range: According to rCP0 setting)	0	46-1	
S							
60	849	d49	Recipe setting 49	Recipe parameter 10 setting for palette 4 (Setting range: According to rCP9 setting)	0	46-10	
61	<i>a</i> 50	d50	Recipe setting 50	Recipe parameter 1 setting for palette 5 (Setting range: According to rCP0 setting)	0	46-1	
5							
70	d59 	d59	Recipe setting 59	Recipe parameter 10 setting for palette 5 (Setting range: According to rCP9 setting)	0	46-10	
71	d80	d60	Recipe setting 60	Recipe parameter 1 setting for palette 6 (Setting range: According to rCP0 setting)	0	46-1	
S							
80	889	d69	Recipe setting 69	Recipe parameter 10 setting for palette 6 (Setting range: According to rCP9 setting)	0	46-10	
81	470	d70	Recipe setting 70	Recipe parameter 1 setting for palette 7 (Setting range: According to rCP0 setting)	0	46-1	
S							
90	879	d79	Recipe setting 79	Recipe parameter 10 setting for palette 7 (Setting range: According to rCP9 setting)	0	46-10	

# 9<sub>INDEX</sub>

<b>2</b>		${f L}$	
2 degrees of freedom PID	122	LED allocation	104
		Limit value of MV	89
A		Limit value of MV change rate	89
Λ		Limit value of re-transmission output	67
Alarm delay time	58	Linearize function	
Alarm hysteresis		Local SV	8
Alarm option			
Alarm setting		<b>7.</b> //	
Alarm type		${f M}$	
Alarm upper/lower limit setting		Manual operation	75
AT		Manual operation prohibition	
Auto operation		Math function	
Auto tuning function		Monitor	
Auto tuning method		Wollitor	
Auto tuning method	52	•	
_		0	
В		0 1 1 1 1	0
7		Operation during standby	
Burnout function	96	Operation mode	
		Operation mode at the time of power ON	
$\mathbf{C}$		Output convergence value	
· ·		Output during standby	
Communication Di function	142	Output limiter type setting	
Control action type	48	Output type	123
Control templates	21		
		P	
D		-	
D		Palette switching method setting	94
Derivative action time	91	Parameter jump	106, 109
Digital characters		Parameter mask	120
Digital input (Di) function		Password	119
Digital output (Do) function		PFB control	36
Direction of burnout		PID	91
		PID operation cycle	91
TD.		Proportional band	
${f E}$		•	
EX-MV function	191	R	
LIX W V Tuneston	121	$\mathbf{n}$	
T.		Ramp/Soak	14:
${f F}$		Recipe function	
E	100	Remote acknowledge (R-ACK) function	11.5
Function key	106	Remote operation	
		Remote operation prohibition	
H		Reset command	
		Resetting alarm latch	
Hysteresis	92	Re-transmission	
		RS485	
I		10400	06
-		~	
Input decimal point position	30	${f S}$	
Input filter time constant	87	0 1 4:	24
Input scale	28	Scale of input	
input square-root extractor cut point		Scale of transfer output	
Input type		Screen display selection function	
Integral time		Selection of motorized valve type	
Integration upper/lower cut point		Set value (SV)	
<u> </u>	-	Setting communications	
<b>T</b> /		Standby function	
K		SV tracking	
Key lock function	95	SV upper/lower limit value	51

### 9 INDEX

1	
Terminal connection diagram  Totalizer function	
U	
Unit of input	34
Unper/lower limit value of MV	80

User adjustment	97
Z	
Zero/span adjustment value of input	97

